

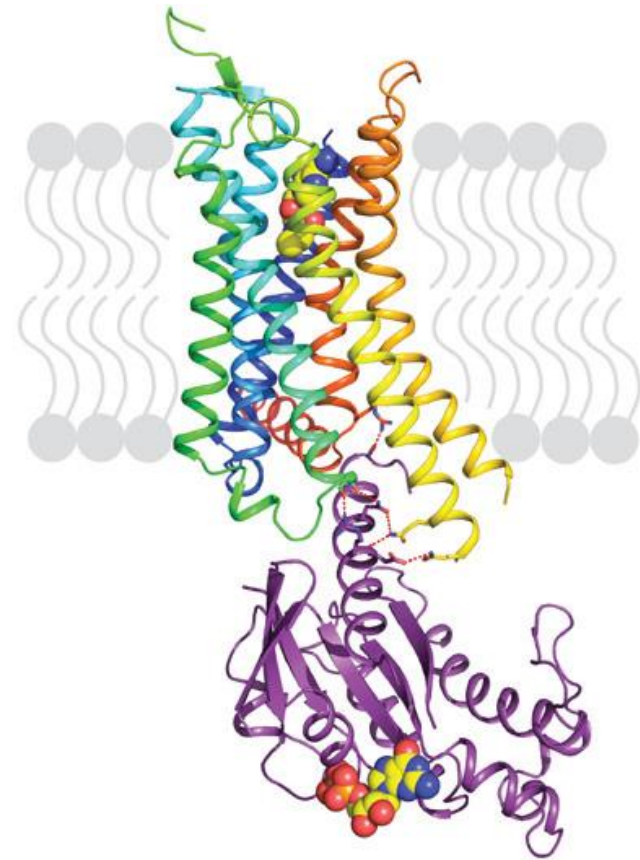
MX3 Beamline – Automation

March 2021

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Overview of High performance Macromolecular Crystallography (MX3)



- High Flux Microfocus MX line – first users July 2023.
- Endstation optimised for ***single crystal and serial crystallography***
- Will complement the existing MX1/MX2 beamlines.
MX3 will be able to measure smaller and more weakly diffracting crystals.
- MX3 will also be capable of ***in-tray screening***, breaking the current bottleneck in crystal production to understand disease pathologies and drug development.
- ***Highly automated (crystal location, data collection and merging).***

Existing MX beamlines at the AS:

MX1:

BM source

180x150 micron beam, 3.4×10^{11} ph/s flux.

MAD capable (6-18 keV energy range)

Eiger2 9M

MX2:

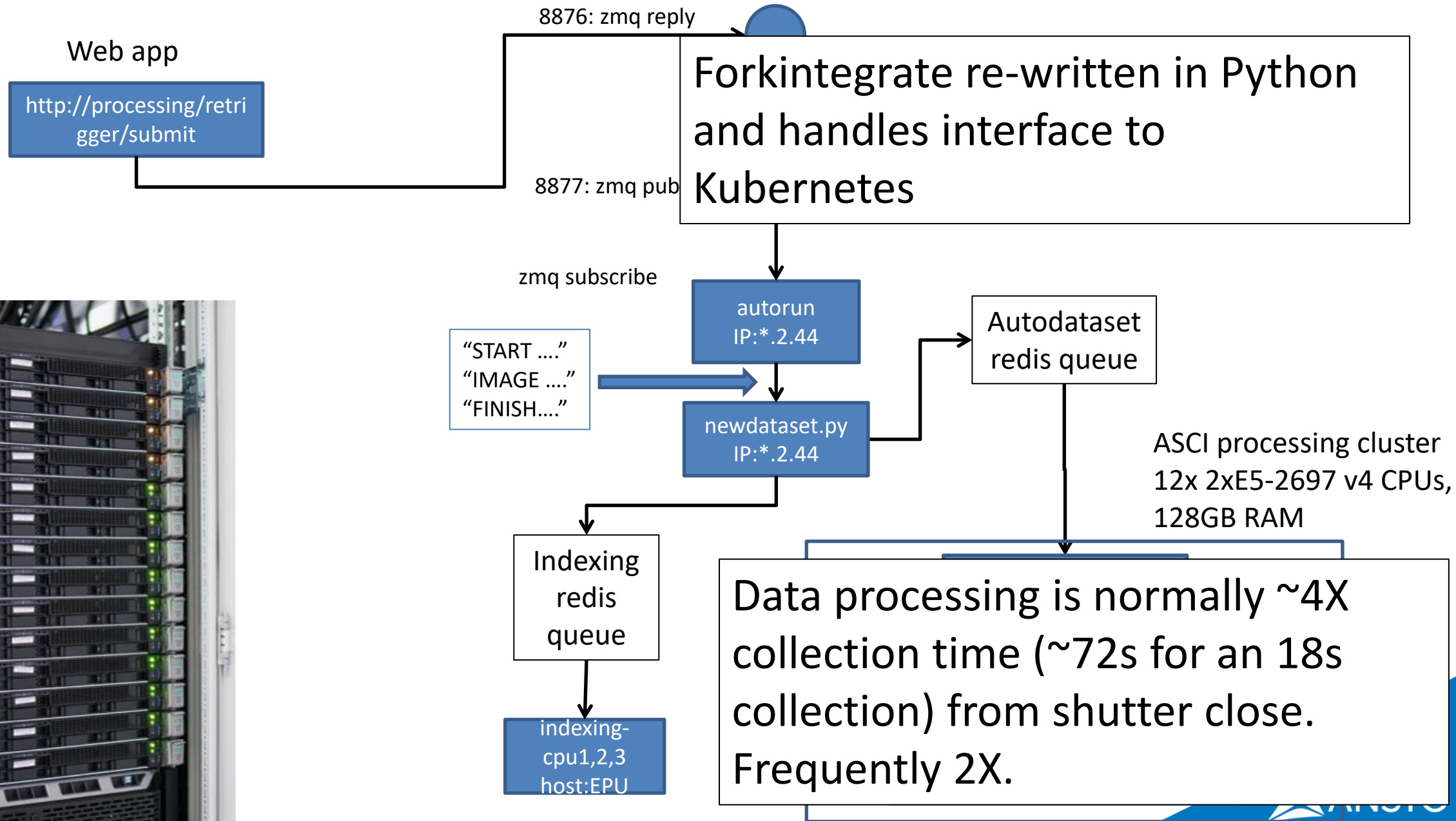
3m u22 IVU source

22x12 micron beam, 2.4×10^{12} ph/s flux

MAD capable (5-21 keV energy range)

Eiger 16M

Current MX Eiger processing system outline



Processing GUI

- Retriggering – automatic processing is run on all data, with best estimates for parameters
 - Retriggering allows the user to feed information back into the system to get a better dataset

testcrystal_1 - dataset ×

Processing summary

Started At	2016-01-25 14:39:48 AEDT
Status	Success
Sample	testcrystal_1
Directory	/data/10123g/frames/calibration/test_crystal
Resolution	1.79 Å
Space Group	I23
Unit Cell	78.58Å 78.58Å 78.58Å 90.0° 90.0° 90.0°
Processing Dir	/data/10123g/home/aragaod/auto/dataset /xds_process_testcrystal_1_180_56a599049117a620cc614433
Average Mosaicity	0.13 °

Collection parameters

Epn	10123g
Exposure Time	1 s
Start Angle	0.0 °
Oscillation	1.0 °
No Frames	180
Last Frame	/data/10123g/frames/calibration/test_crystal/testcrystal_1_180.img
Attenuation	94.01 %
Energy	12.9999163028 KeV
Distance	264.0375 mm

Retrigger parameters

Processing results

Setup retriggering Close

Retrigger testcrystal_1 - dataset ×

	Old	New
Spacegroup:	I23	<input type="text" value="I23"/>
Unitcell:	78.14Å 78.14Å 78.14Å 90.0° 90.0° 90.0°	<input type="text" value="[78.14, 78.14, 78.14, 90.0, 90.0, 90.0]"/>
Start Frame:	0	<input type="text" value="0"/>
End Frame:	180	<input type="text" value="180"/>
Low Res (cut off):		<input type="text" value="50"/>
High Res (cut-off):	1.8 Å	<input type="text" value="0"/>

☐ Ice
☒ Weak
☐ Slow
☐ Brute

Retrigger Close

MX3 Scientific computing

- A database to manage sample/experiment data (ISpyB)
- User GUI (MXCubev3)
- Tray screening GUI (SynchWeb)
- Python logic code (similar to ZOO¹, some in-house)
- Ophyd+Bluesky
- Autoprocessing code
- Cluster management
- Data management

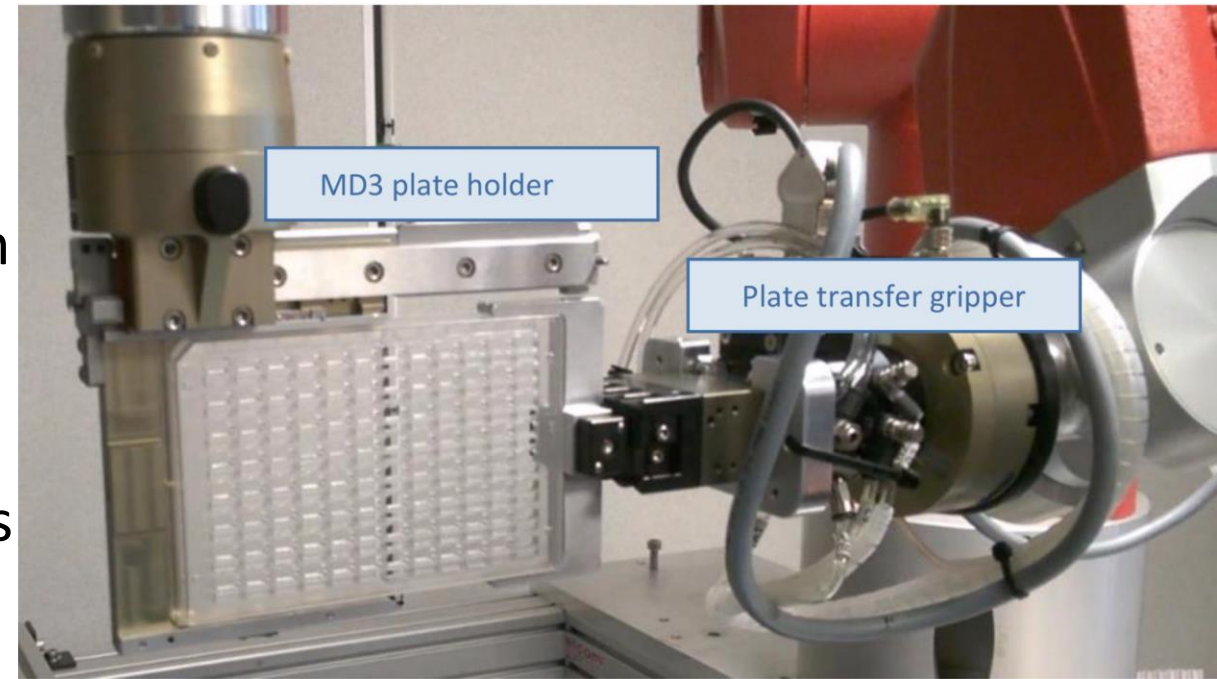
1: Hirata *et al*, (2018) "ZOO: an automatic data-collection system for high-throughput structure analysis in protein microcrystallography", *Acta Cryst D* 75, 138-150.

Scientific Capabilities that MX3 will add:

1. In-tray screening
2. High flux micro crystallography (GPCRs)
3. Serial Crystallography
4. Automated crystal location and collection

1. In-tray

- ISARA robot will load trays from a 20-tray hotel in the hutch onto the MX3.
- “Tray Tuesdays”
- Tray shipping trial Q1 2012. Trays shipped from users to and from the AS
- Seeking volunteers to take part
- Goal is to develop and test shipper, procedures and tracking software
- Goal is to have a “blanket” proposal for the program = no paperwork for users.



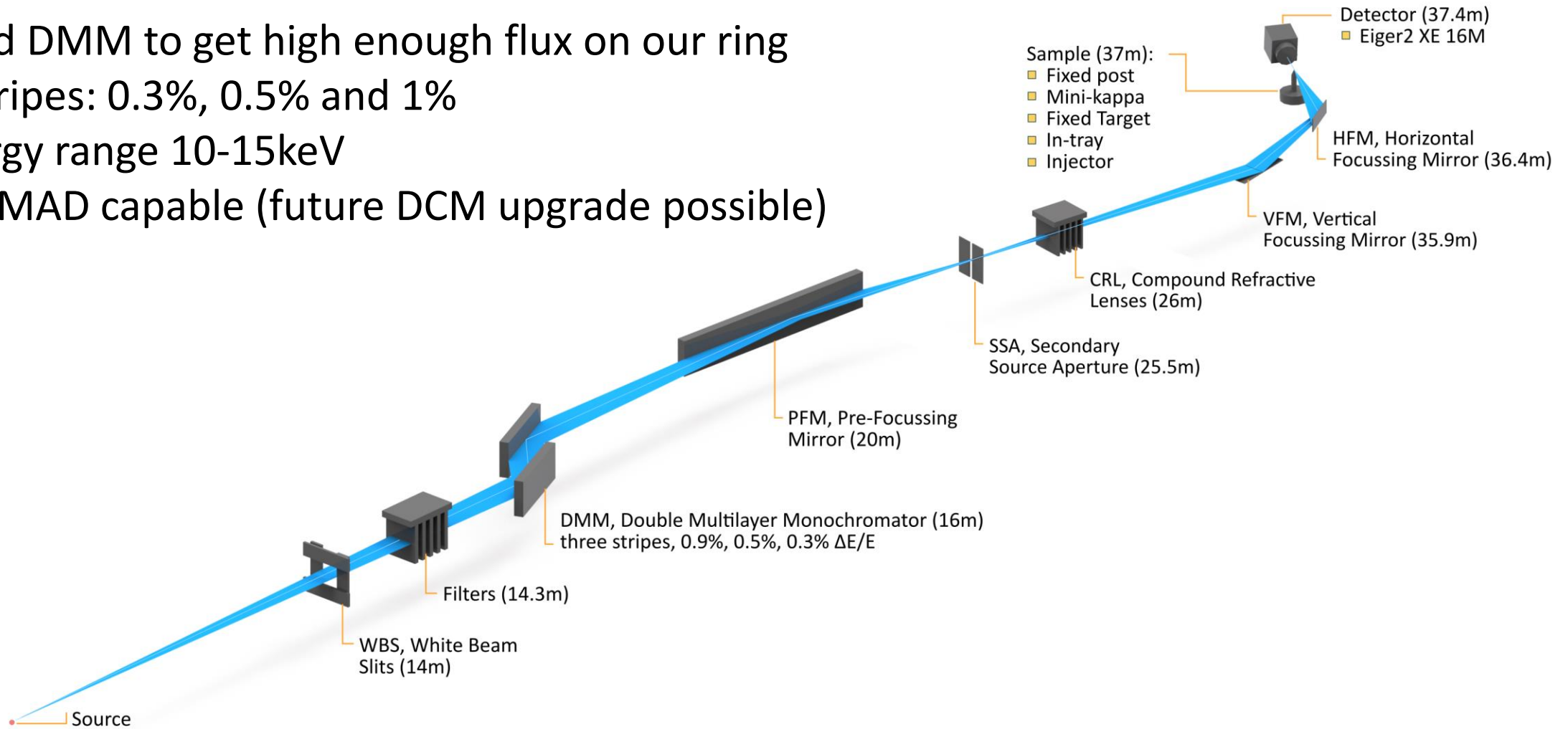
2. High flux micro crystallography

Need DMM to get high enough flux on our ring

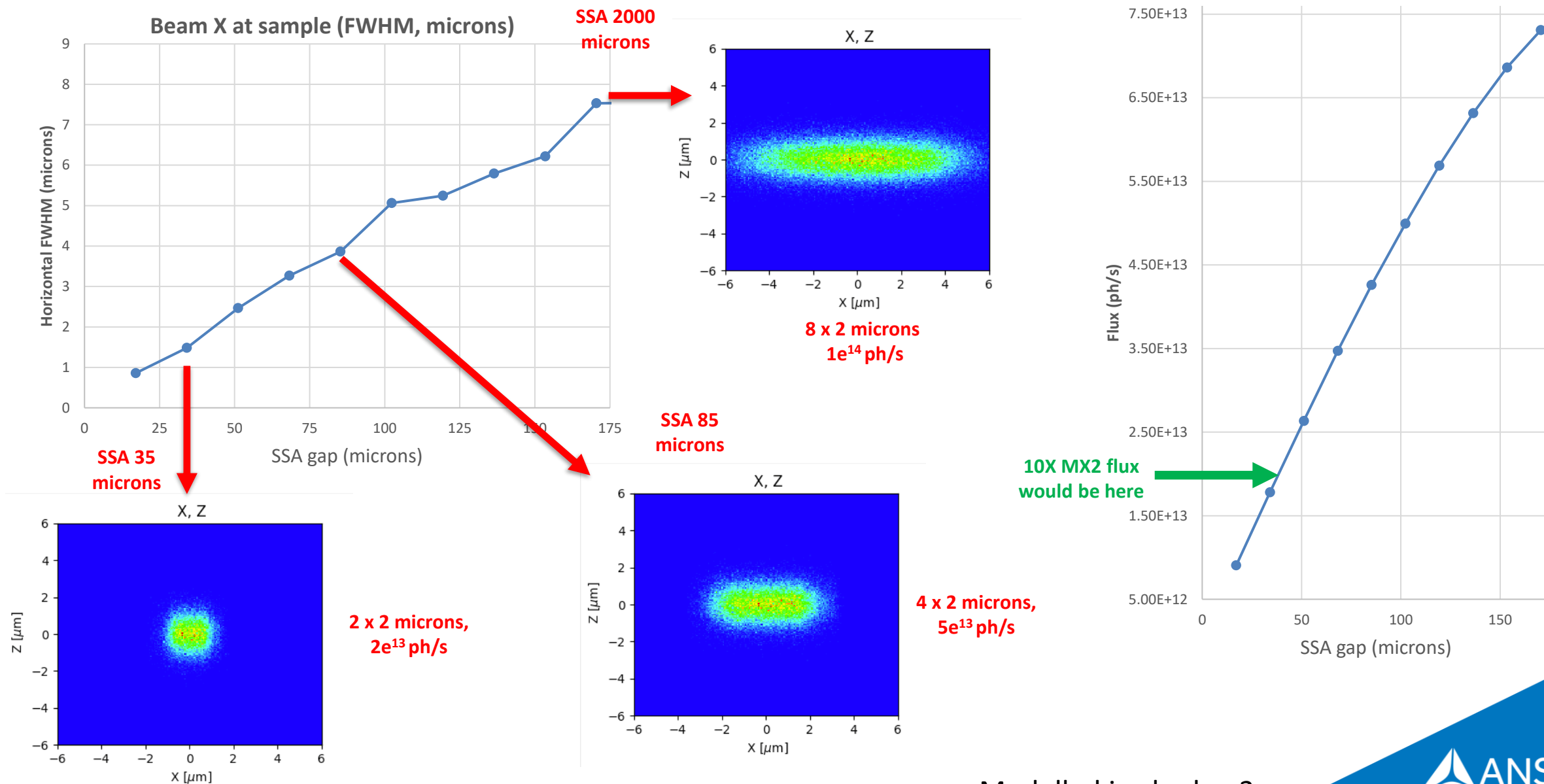
3 stripes: 0.3%, 0.5% and 1%

Energy range 10-15keV

Not MAD capable (future DCM upgrade possible)



2. MX3 Beam performance (1% stripe)



2. Making the beam BIGGER

Will use beryllium compound
refractive lenses (1D)

Fast

User selectable

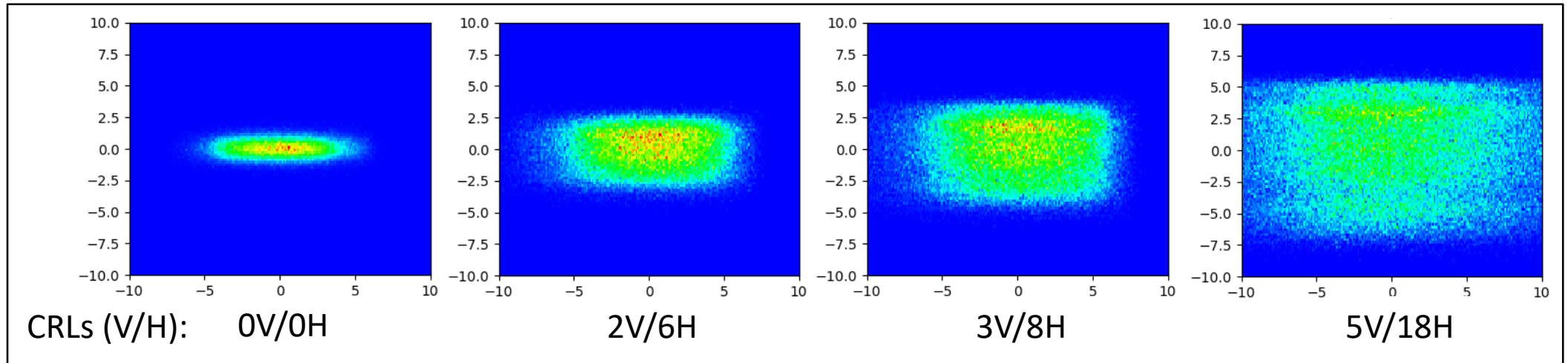
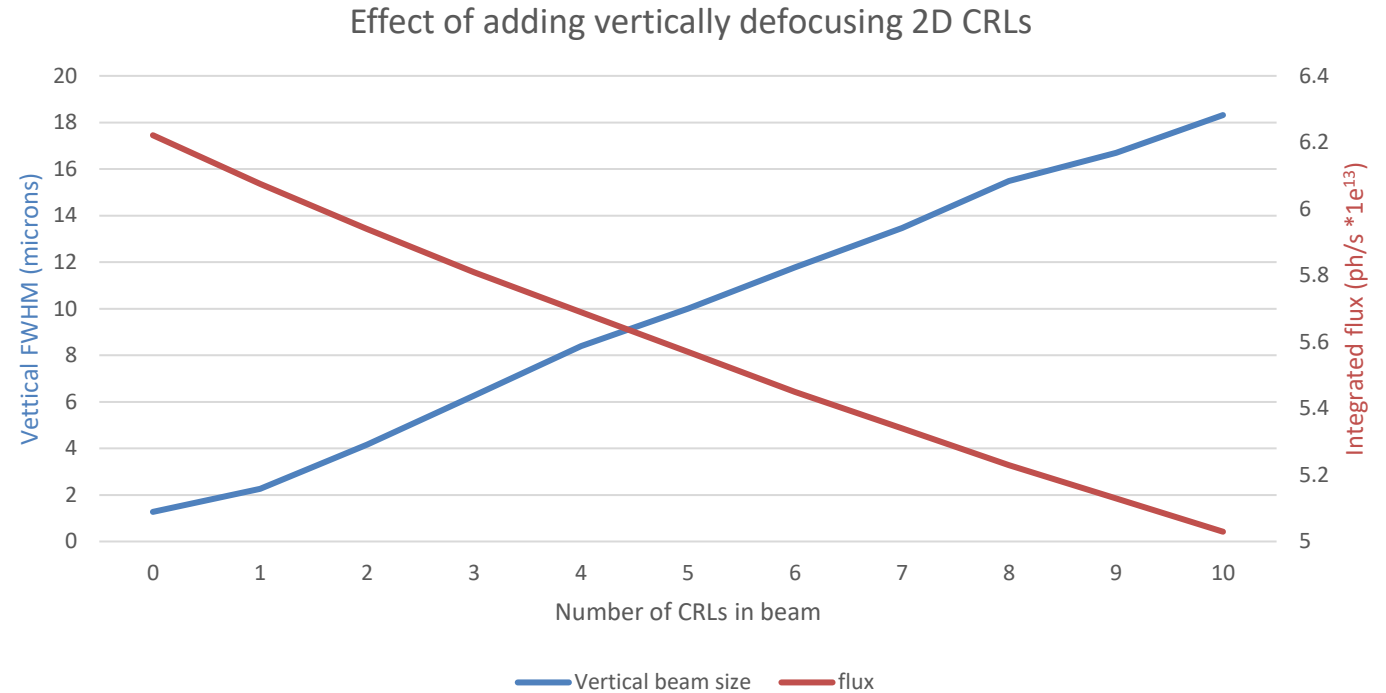
Max beam size now 15x15
microns

Separate H and V defocus

Vertical defocus costs flux

(20%
size)

Horiz
flux (-



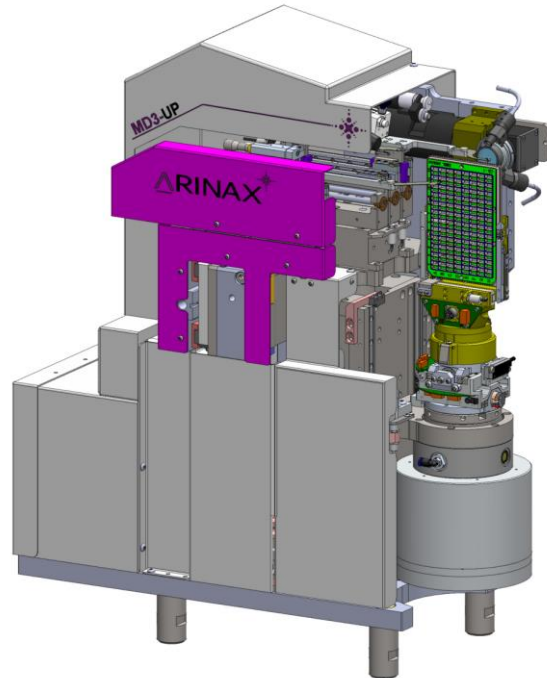
2. Goniometer

High performance goniometer

- MD3 ordered Jan 2021.
- Single axis, kappa and tray-holder heads

Static target systems

- In tray screening using MD3
- Tray hotel in cabin (20 trays)
- Robot can transfer trays from hotel to goniometer.



Arinax


2. MX3 Robot

ISARA robot from Irelec ordered Jan 2021.

Dewar capacity is 29 pucks (pin-up).

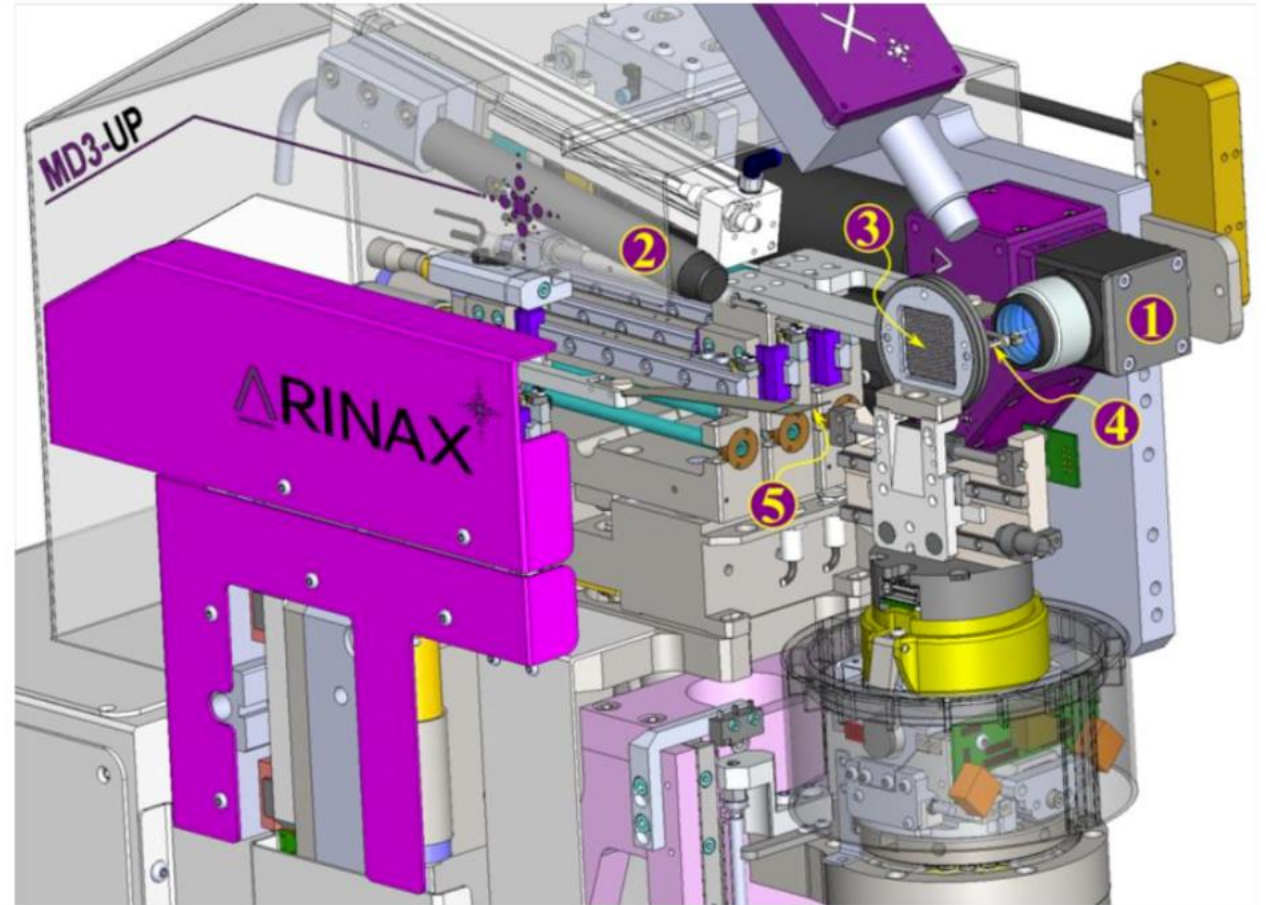
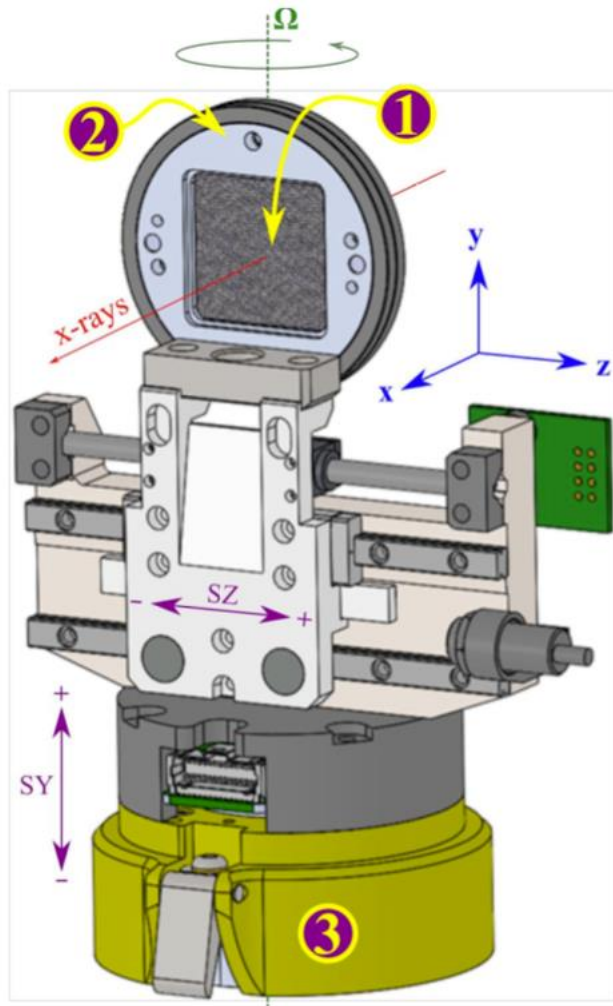
Integration with MD3 and ISARA is well established.



Standard	Gripper	
<i>Unipuck</i> 	<i>Simple Unipuck gripper</i> 	<i>Double Unipuck grippers</i>  <i>designed for MD3-Down</i>
<i>MiniSpine / Newpin</i>  <i>same Dewar interface as for the Unipuck</i>	<i>MiniSpine gripper</i> 	<i>Double MiniSpine gripper</i> 
<i>Crystallization Plates (SBS standard)</i> 	<i>Plate Gripper</i> 	<i>Gripper for transferring plates onto the goniometer</i>  <i>adapted to EMBL plate holder to be mounted on MD3</i>

3. Serial Crystallography – Large Fixed Target

Now run on MD3 (same system as new ID29 at ESRF)



¹Sherrel D. A. et al. "A modular and compact portable mini-endstation for high-precision, high-speed fixed target serial crystallography at FEL and synchrotron sources". Journal of Synchrotron Radiation. Volume 22 | Part 6 | November 2015 | Pages 1372-1378

4. Automation, the core problem

At modern data rates humans can't keep up:

What sample is this?

Typing info into a GUI

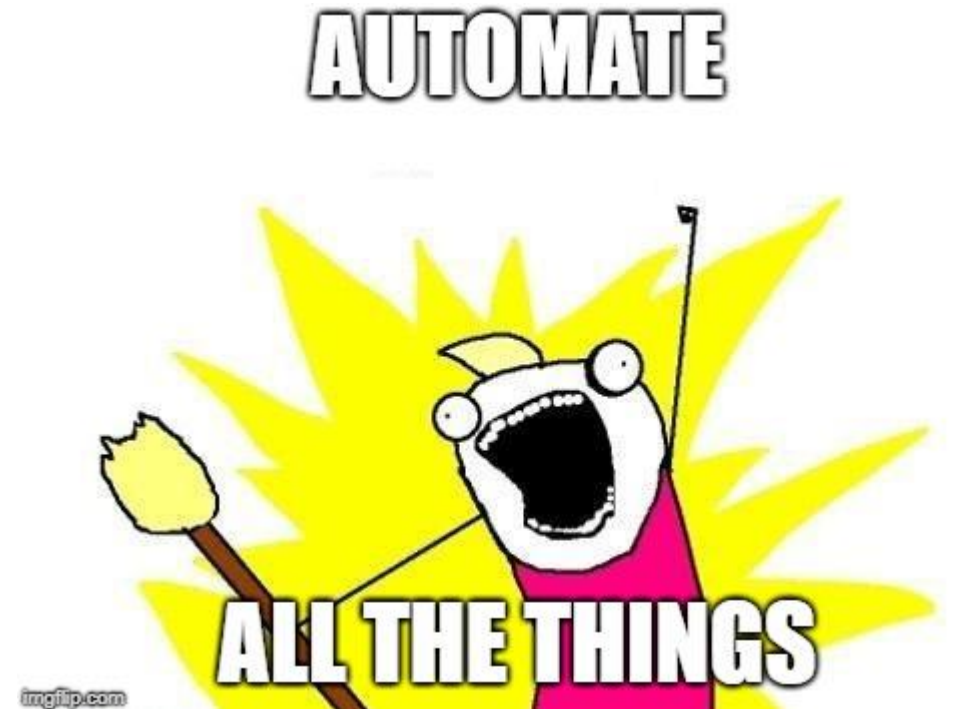
Writing notes

Assessing data quality

Making good collection decisions

Automated crystal location

Automated collection plans

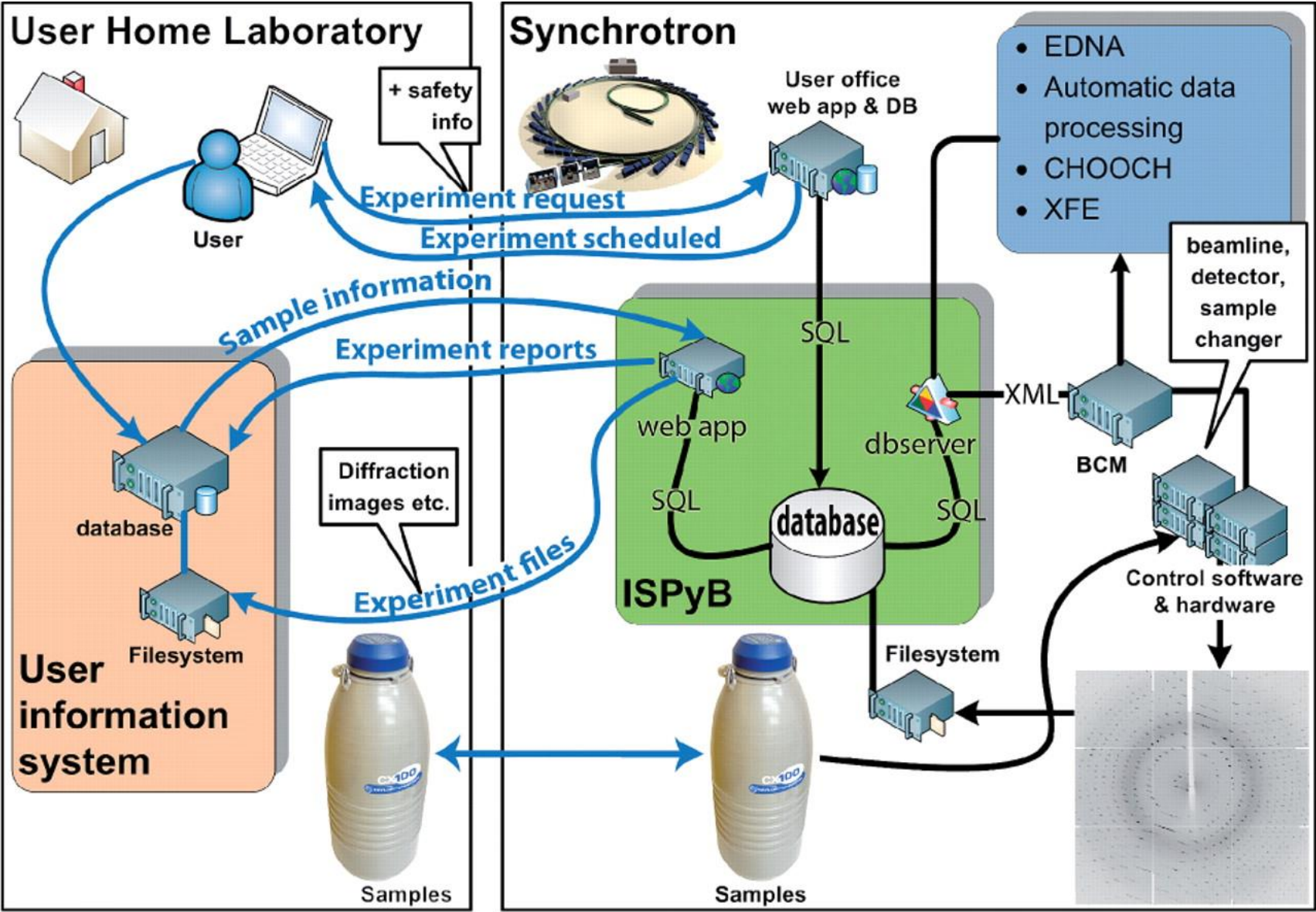


ISPyB

Interest in Python re-write of IspyB backend

Has possible use across more new beamlines at AS (we are building 8)

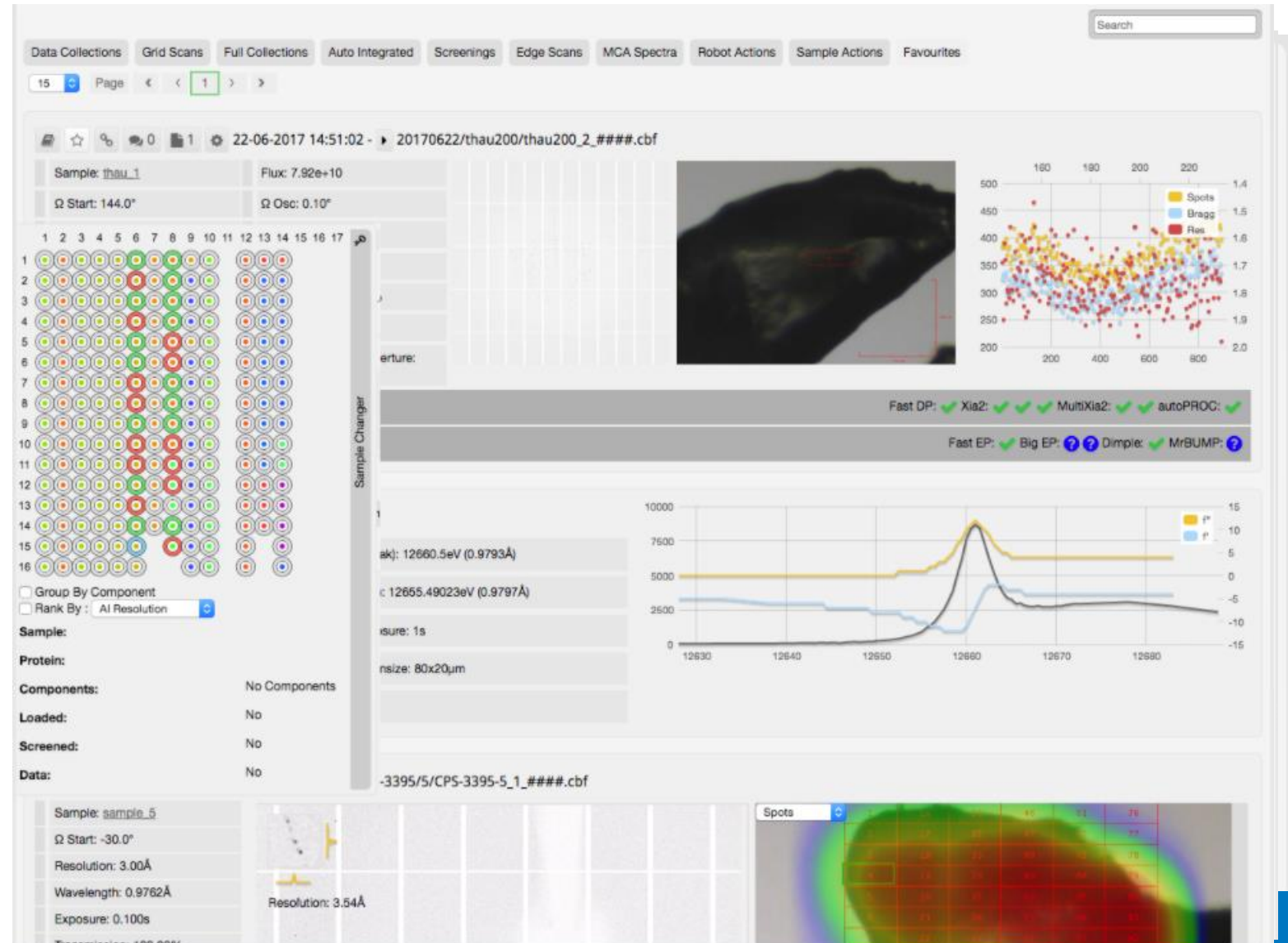
Ideally deployed to MX1/2 as well.



GUIs – ISPyB, SyncWEB etc etc

SyncWEB – WebAPP
(PHP).

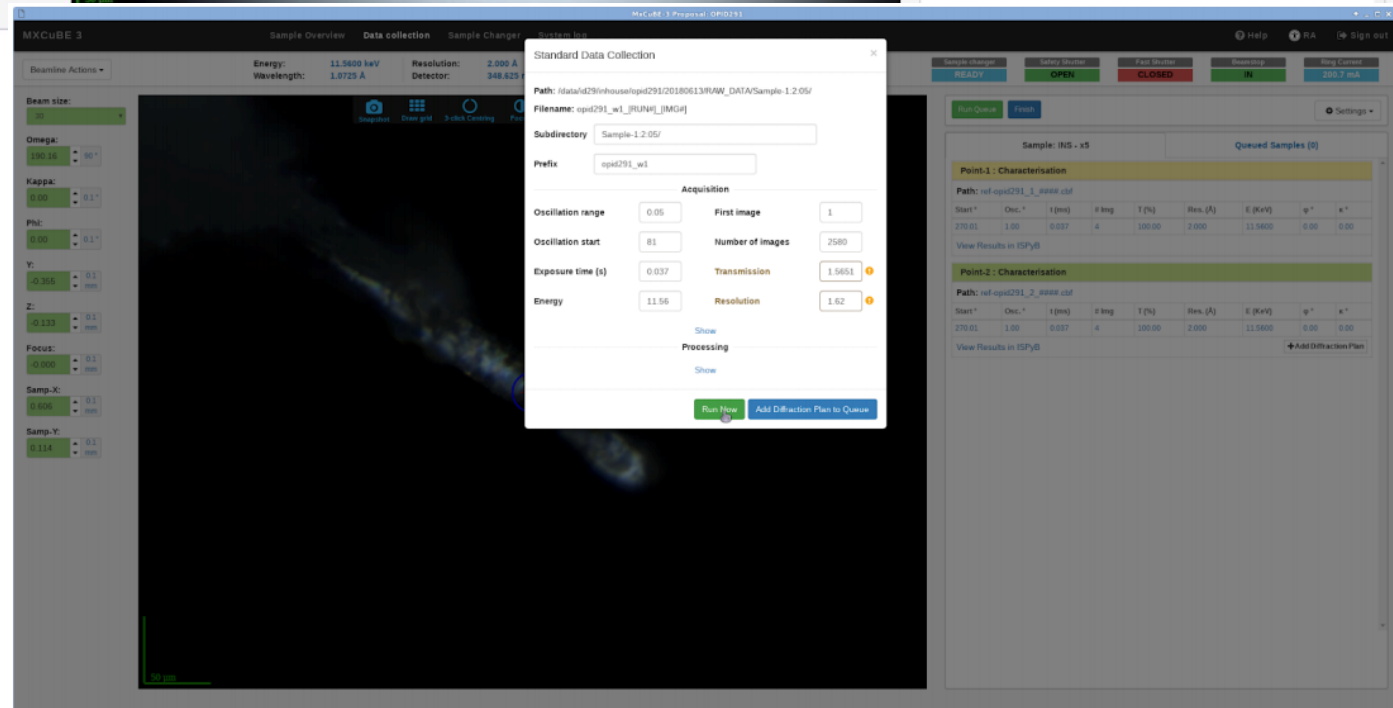
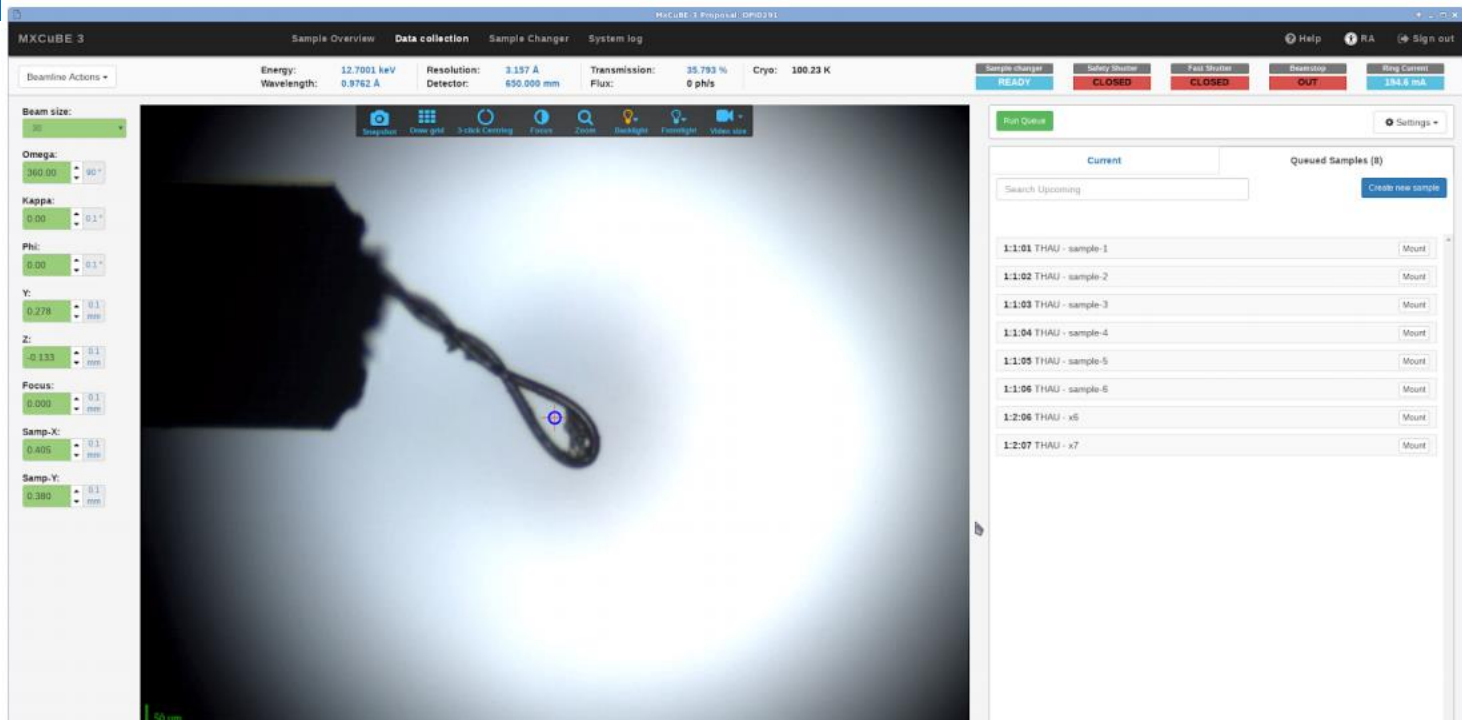
(<https://github.com/ispyb/ispyb-js-api>)



<https://diamondlightsource.github.io/SynchWeb/>

MXCuBEv3

1. WebAPP
2. Backend: Python-flask , SocketIO, REST API
3. Aligns with new code architecture for BRIGHT beamlines.
4. Deployed on ESRF MX lines now



<http://esrf.eu/files/live/sites/www/files/UsersAndScience/Experiments/MX/Software0/MXCuBE3/MXCuBE3%20manual%20v0.1.1.pdf>

We need automation!

1. MX3 will be the most highly automated beamline at the AS
2. Scientific computing will drive the useability and throughput of the beamline
3. Plan is to join ISpyB and MXCUBE consortiums
4. Automated (no-user) queued collection.



WE NEED
AUTOMATION
FOR MX3

The Team

MX

Alan Riboldi-Tunnicliffe

Rachel Williamson

Jun Aishima (now at NSLS II)

David Aragao (now at Diamond)

Kate Smith (now at PSI)

Daniel Eriksson

Mark Clift

Santosh Panjikar

Jason Price

Not pictured:

Stephen Harrop

Eleanor Campbell

Stephanie Boer

Nathan Mudie

Sofia Macedo

Engineering

Vesna Samardzic-Boban

Mark Clift

Robbie Rostan

Robert Grubb

Mark Colclough

IT Group

Uli Felzmann (now at UniMelb)

Robbie Clarken (now at BOSCH)

Ron Bosworth

Scientific Computing

Andreas Moll

John Marcou

Dectris – Andreas Forster, Diego Gaemperle

SLS – Simon Ebner, Zac Panepucci, Meitian Wang

HDRMX – <http://hdrmx.medsbio.org>

NSLS2 – Bruno Martins for AD Eiger



Thank you!

Questions?
