

# Data Acquisition, Management, and Real-Time Analysis at the EMBL PETRA III Beamlines

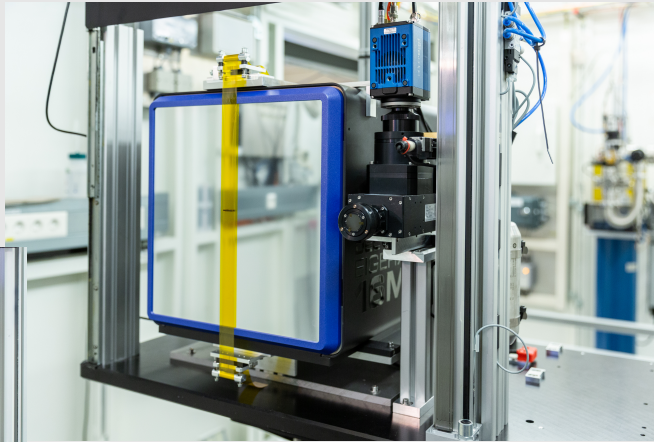
or of Daemons and Data

*Marina Nikolova*

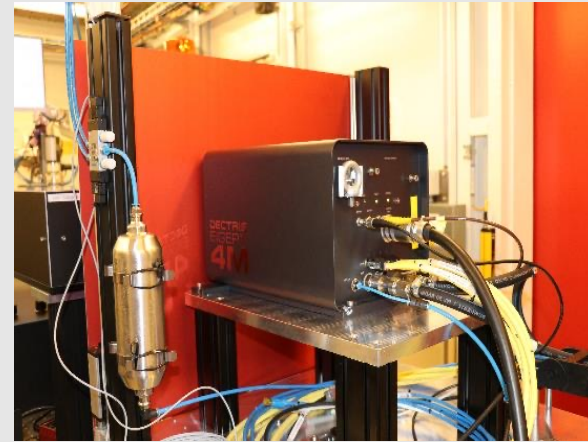


# High-Frame-Rate Detectors and Cameras

- Eiger 16M, DECTRIS
- 16 Megapixel frames @133Hz or 4 Megapixel frames @750Hz
- Currently integrated at P14



- PCO Edge Imaging Camera
- 4 Megapixel frames @100Hz
- Integrated at P14



- Eiger 4M, DECTRIS
- 4 Megapixel frames @750Hz
- Moving between TREXX and P12












- Eiger X 16M CdTe, DECTRIS
- 16 Megapixel frames @130Hz or 4 Megapixels @750Hz
- Delivery expected May, 2021
- To be integrated at P14

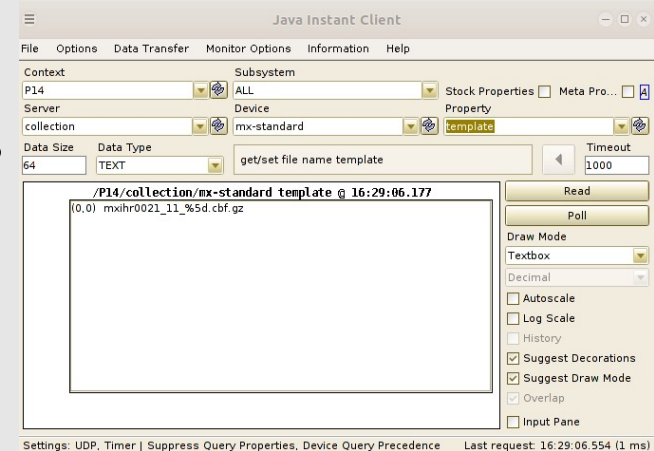
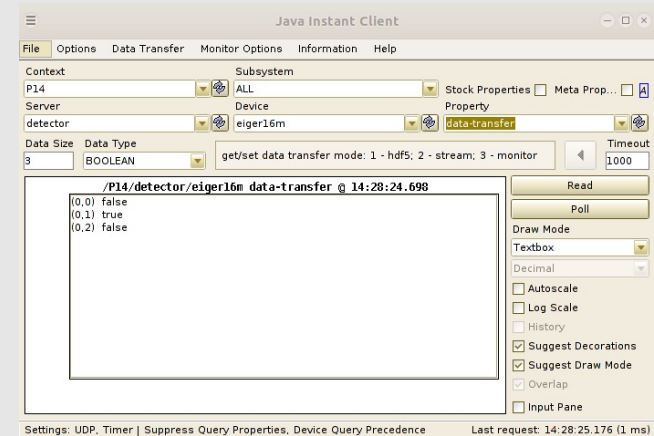
# Tsunami Data Waves





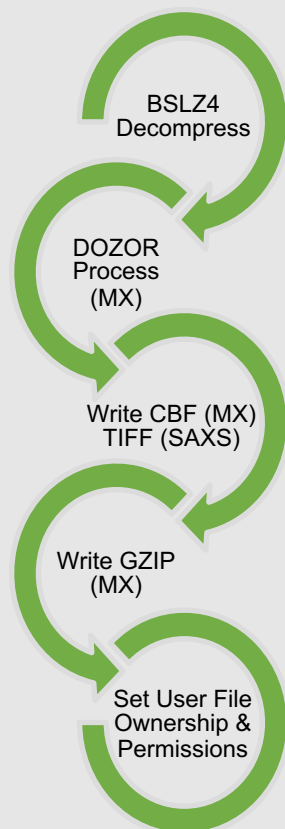
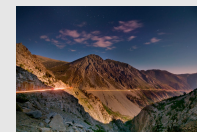
# Acquisition Control Detector/Data Collection Server

-  Unified interface to all X-Ray area detectors
-  Presents the experiment as a service
-  User Interface point of contact
-  Manages the collection sequence
-  Creates metadata
-  Ensures metadata consistency
-  Enables scripting non-standard experiments
-  C++; TINE server
-  Integrated at P14, TREXX, P13, P12



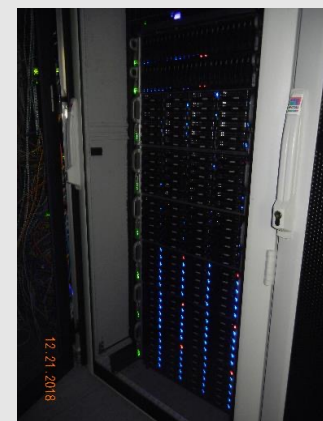


# Data Transfer and Real-Time Analysis: TIOGA



- 🐝 TIOGA: “where it forks”/“swift current”, ZMQ
- 🐝 2 88-core and a 36-core DELL servers, 1 machine each for P14, TREXX, P12
- 🐝 Configurable count of
  - 🐝 Stream receiving and processing threads, and disk writing threads: 176/44
  - 🐝 Frame buffers – limited by 256GB RAM
- 🐝 Connections – 1 InfiniBand + 2 10 Gbit DCU to processing server
- 🐝 Fully integrated in the TINE Control System
- 🐝 DOZOR processing via library routines

```
extern "C" {
void dozor_set_defaults(DATACOL_t*);
void pre_dozor(DETECTOR_t*, DATACOL_t*, LOCAL_t*, char*, char*, int*);
void dozor_bin_image(DETECTOR_t*, int*, int*, short*);
void dozor_bin_image(short*, DETECTOR_t*, DATACOL_t*, DATACOL_PICKLE_t*, LOCAL_t*, char*, char*);
void dozor_get_spot_list(DETECTOR_t*, DATACOL_t*, DATACOL_PICKLE_t*, reflection_t*);
}
```
- 🐝 DOZOR results exported every 300ms via TINE
  - 🐝 Spot Count
  - 🐝 DOZOR Score
  - 🐝 Resolution Limit
  - 🐝 Average Intensity
- 🐝 No intermediate DOZOR and CBF files – all in memory
- 🐝 Max count of frames per scan: 2,560,000 – TREXX
- 🐝 Max frame rate – over 500 DOZOR processed and written fps
- 🐝 Writing over a 40Gbit InfiniBand
- 🐝 Data to Parallel Cluster File System Storage
  - 🐝 1 PB, 7GB/s BeeGFS



The Baddest Daemon




# Data

## Images

 CBF/GZ-compressed CBF – P14, TREXX

 Compressed TIFF – P12

## Spot Files

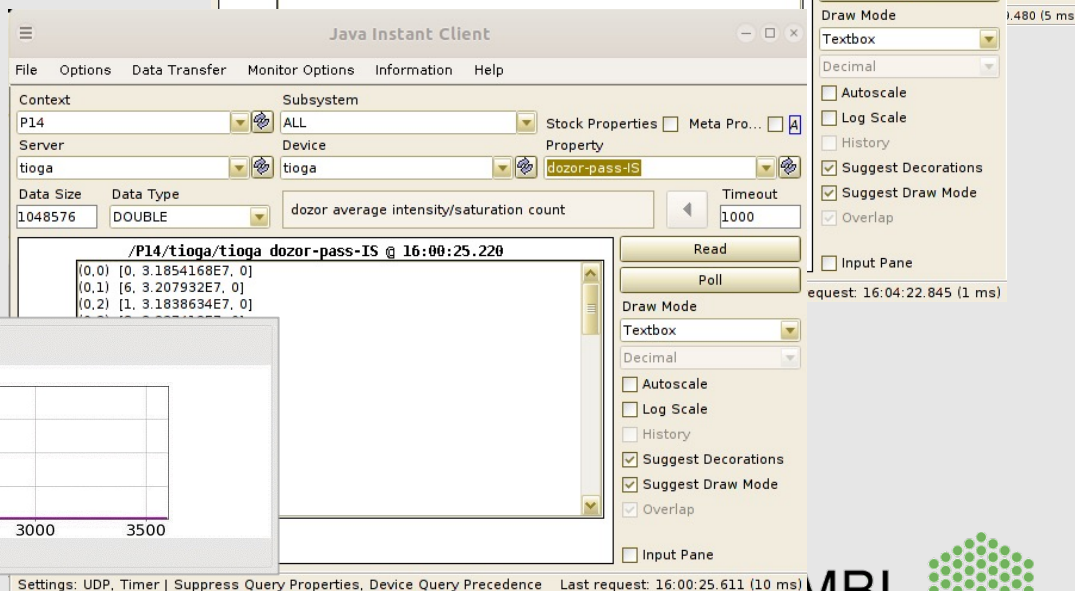
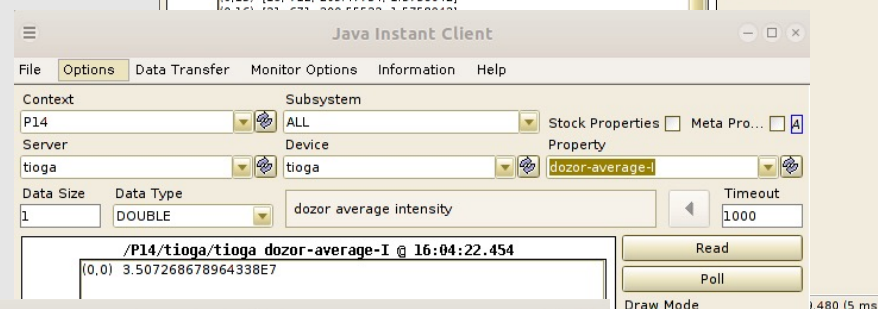
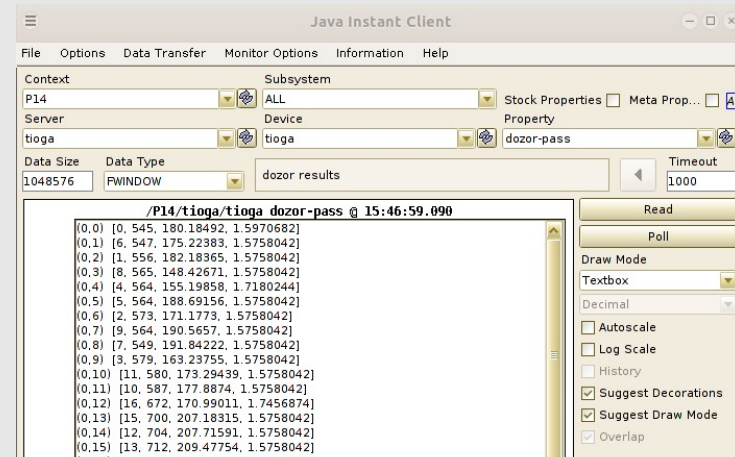
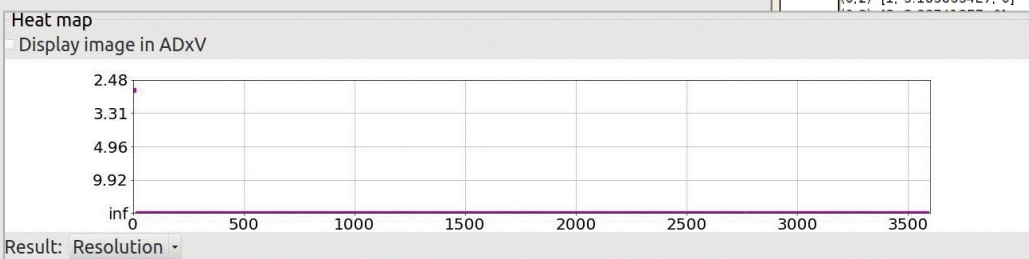
 file\_name.adx.gz

2303.87 1975.71 1 6153.75

1866.46 2055.64 1 1695.58

2328.09 2061.97 1 118.11

...

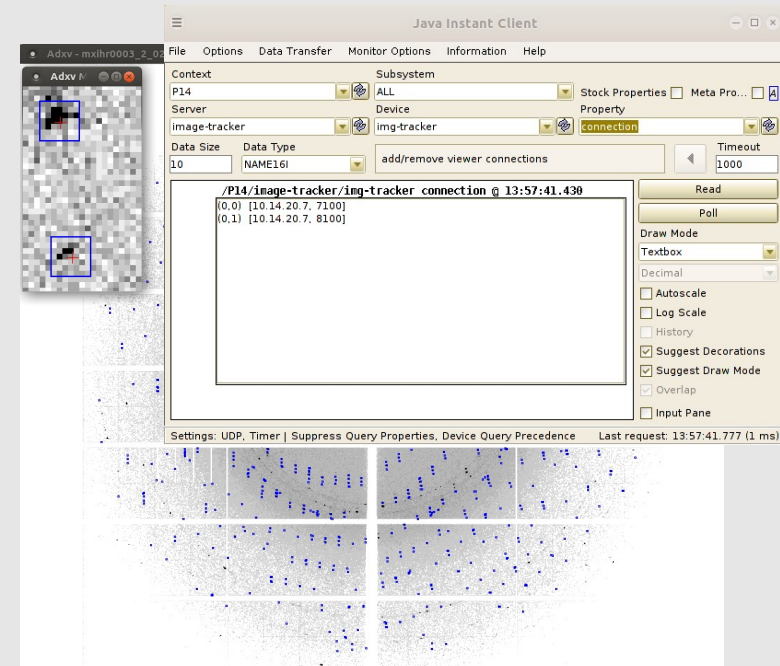
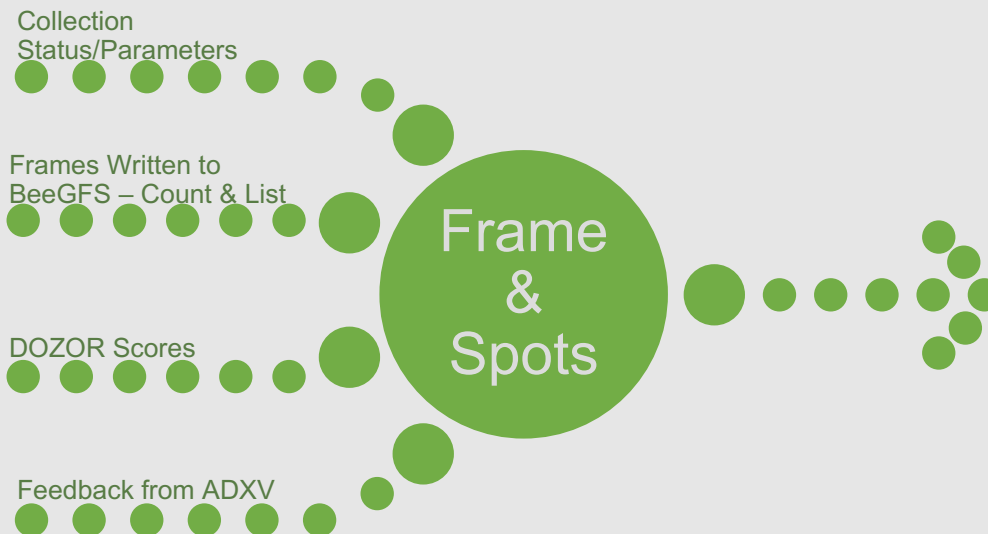


# Live Frame Display

The Smart Daemon



- ☐ ADXV – data read from BeeGFS on the fly during scan
- ☐ Image Tracking Server
  - ☐ Talks to Detector/Data Collection Server, and TIOGA via TINE, and to ADXV via socket and NCAT
  - ☐ Selects preferentially frames with highest DOZOR score
  - ☐ Send Requests to ADXV to display
    - ☐ frames
    - ☐ spot highlights
  - ☐ Heat Map Hovering in GUI: bitmap of frames with diffraction for 32 data collections
  - ☐ Can feed multiple ADXV instances
- ☐ Advantages for Serial Crystallography Experiments
  - ☐ Few(er) empty frames to look at
  - ☐ Quick and Easy Spotting of Diffraction



# Raster Scan

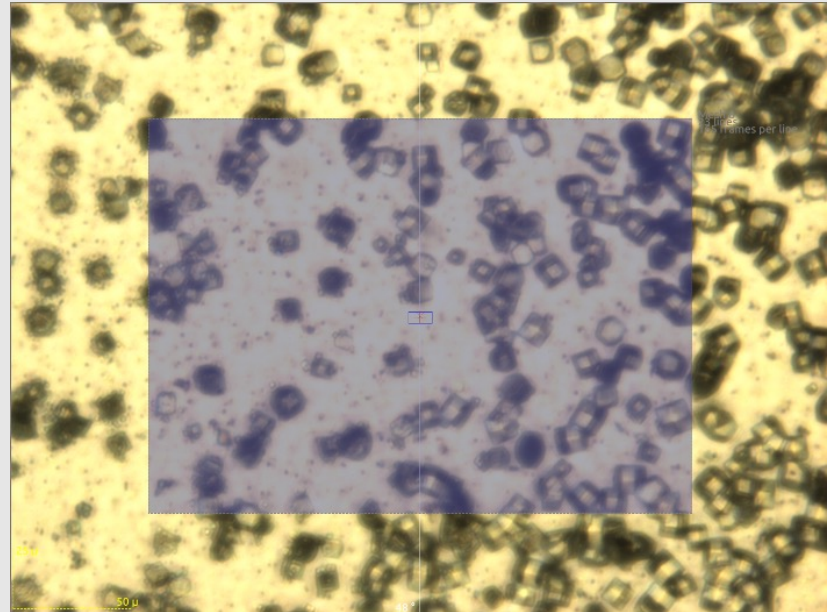
Exposure Time: 0.001343s

ROI Mode: 4M

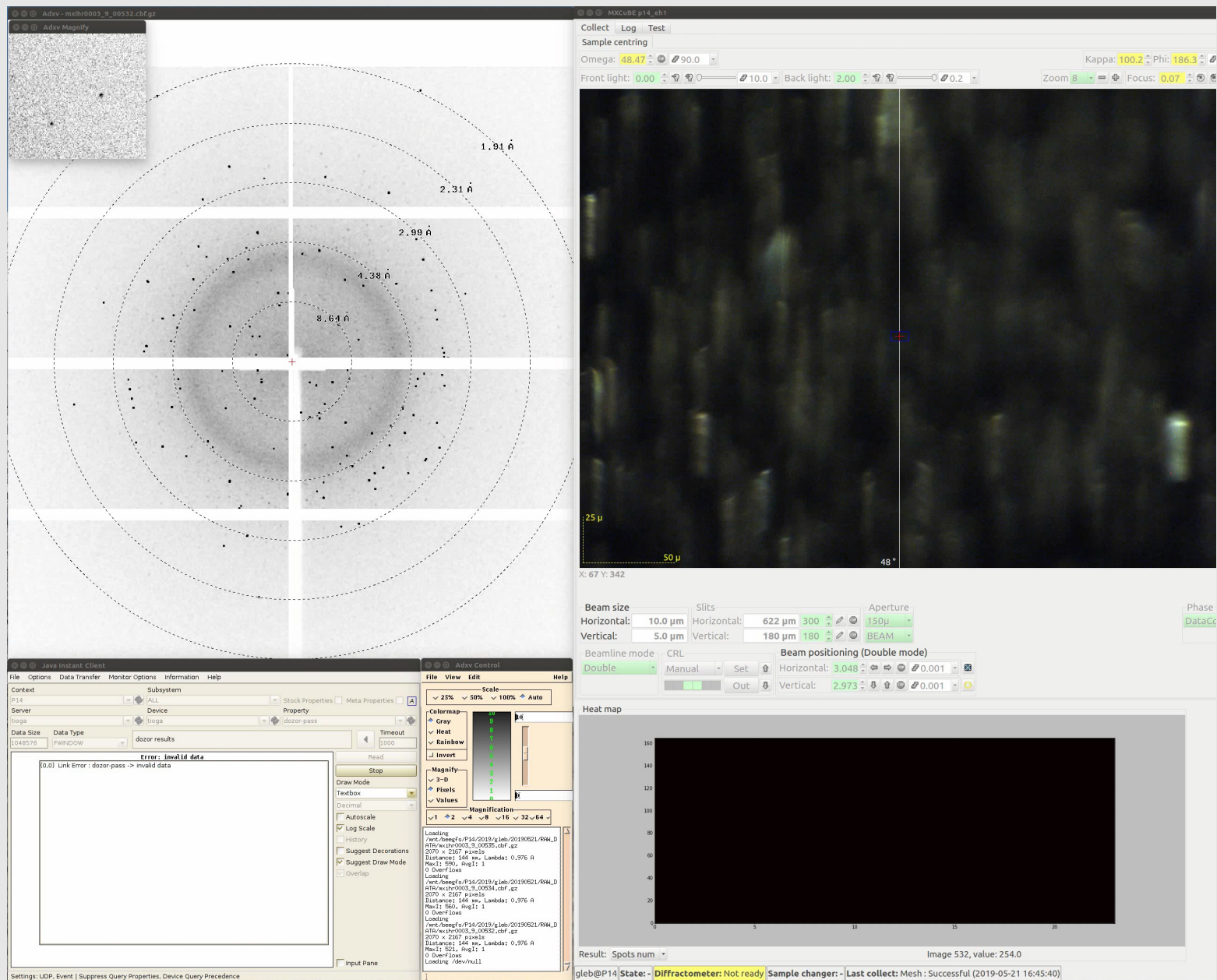
Lines: 23

Frames per Line: 165

Total Frames: 3795







# Wedges



## Multi-trigger Experiments



## Multiple Wedge Data Collections as required by GPhL workflows



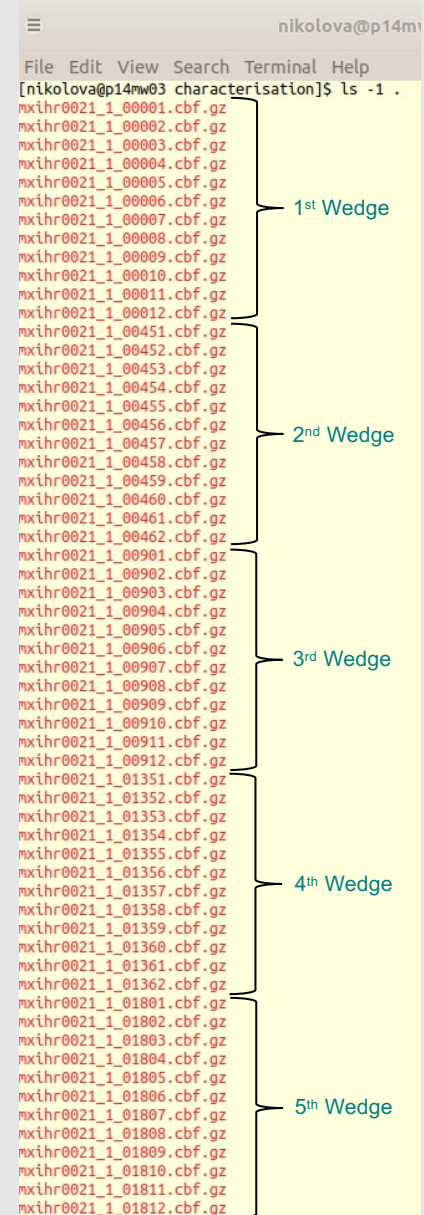
## Detector/Data Collection Server prepares EIGER

# detector triggers = # wedges

# images = # images per wedge



## TIOGA figures out correct headers and file name numbering



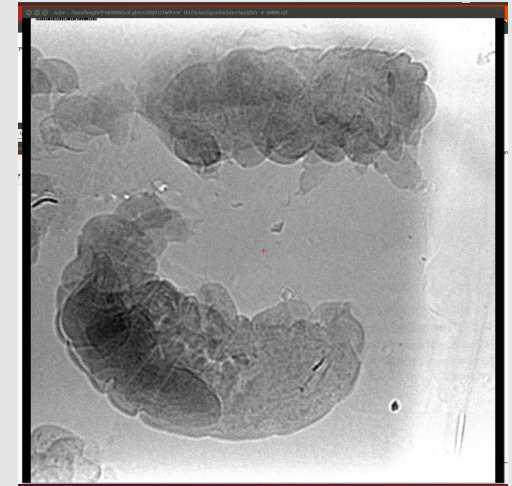
# Imaging for MX

## The Down-To-Earth Daemon



## PCO-SERVER

Receives settings/commands from detector server  
Talks directly to PCO camera  
Sends acquired frames to Arapaho  
ZMQ over 40Gbit InfiniBand  
Keeps a buffer for 360 frames of depth 2 bytes  
Reports progress to clients  
Runs on a 20-core/40-hyperthread machine with 96GB RAM



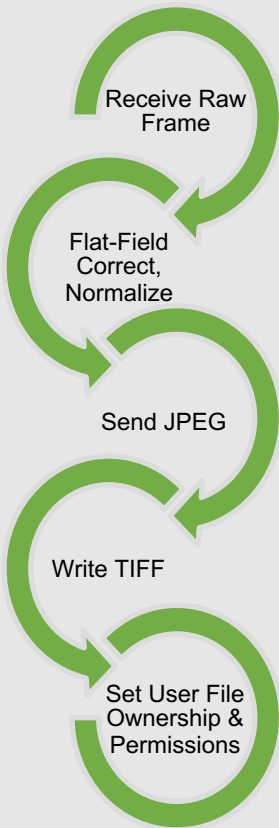
## The Copycat Daemon

## ARAPAHO

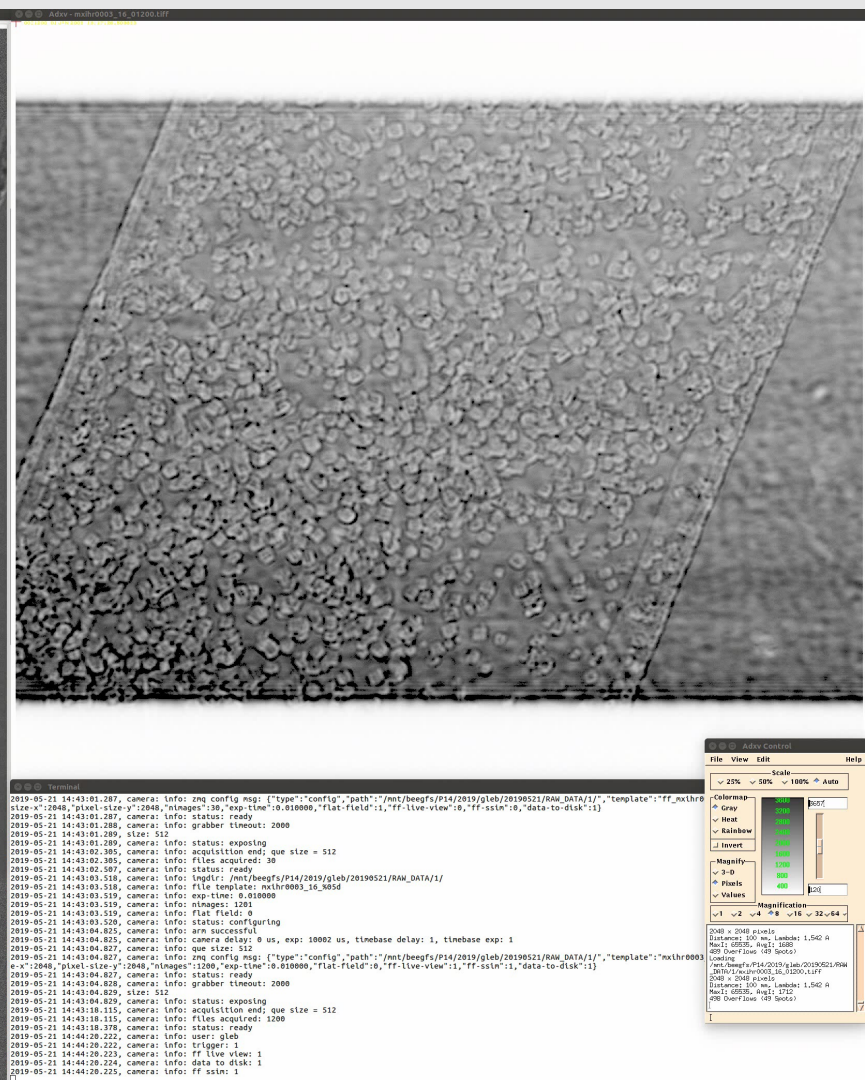
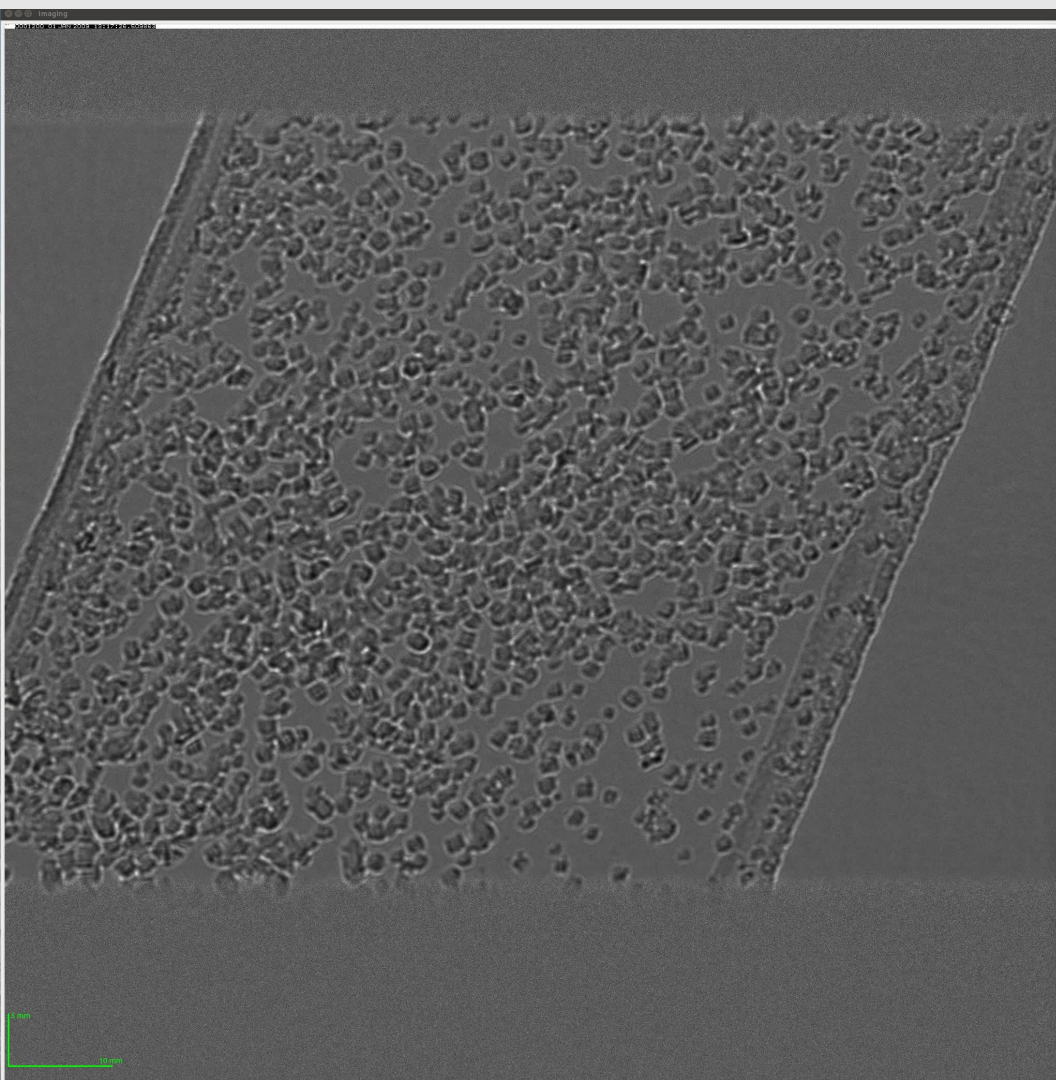


- 🐝 A TINE, ZMQ server
- 🐝 Transfers PCO camera frames from pco server to BeeGFS
- 🐝 Flat field processing based on
  - 🐝 Structural Similarity Index (SSIM)\*
  - 🐝 MPFR big number library
- 🐝 Exports flat field SSIM and saturation count to clients
- 🐝 Sends flat-field-corrected frames to GUI via TINE for display

\* Image Quality Assessment: From Error Visibility to Structural Similarity, Wang, Z.  
<http://www.cns.nyu.edu/pub/eero/wang03-reprint.pdf>









# Automatic Data Processing



## Beamline Cluster



13 88-core DELL R840 servers



Data read from BeeGFS over 56 Gbit InfiniBand



## XDS-ZCBF



An XDS and DOZOR plugin for fast in-memory  
decompression of GZIPped CBFs



No intermediate files on disk



Deployed for automatic data processing on beamline cluster



Usage via line in XDS.INP much like HDF5s NEGGIA and DURIN plugins



LIB=/mx-beta/lib/xds-zcbf.so



<https://git.embl.de/nikolova/xds-zcbf>



# Outlook

- Upcoming Software Updates

- DOZOR Saturated Spot Count
- Multiple Energies and Inverse Beam via Multi-trigger
- TIOGA Features also for Pilatus

- New Detector and Camera Integration

- 16M Eiger CdTe, DECTRIS, @ P14
- 4M Jungfrau, PSI, @ TREXX
- 3M Visual Light Motion Camera XStream Mini, Imaging Solutions, @ TREXX



# Summary

- Instantaneous Availability of Frames for Display and Processing
- Immediate Delivery of Processing Results
- Full Integration of MX Analysis in the Control System
- Streamlined Path for Data
- Data Wave Tamed



# Acknowledgements



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für Bildung  
und Forschung

## Thank You!