

Phase space Monte Carlo for DIS

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Outline

- Numerical integration
- Monte Carlo integration
- Random variable generation
- Phase space generation
- Phase space generation for DIS
- KaTie

Numerical integration

Let \mathbf{M} be a space on which a Lebesgue measure is defined.

Let f be a Lebesgue integrable function.

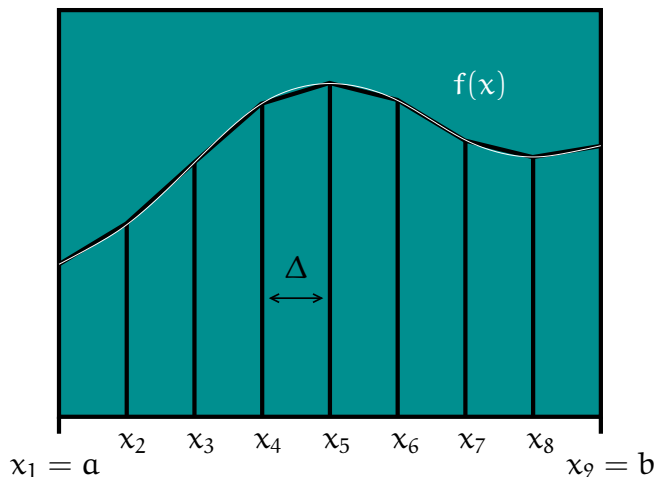
Numerical integration is the attempt to obtain the integral of f by the evaluation of $f(x)$ for several $x \in \mathbf{M}$. More specifically

$$\int_{\mathbf{M}} d^w x f(x) \stackrel{?}{=} \sum_{i=1}^N w(x_i) f(x_i)$$

- various methods exist for choosing the *integration points* x_i and the *weights* $w(x_i)$
- several aspects have to be considered to determine if a method is *good*
 - do you need precision or/and speed?
 - does the method give an error estimate?
 - does the method allow for increasing the precision (by increasing N)?
 - how does the cost of generating the x_i and evaluating the $w(x_i)$ compare to the cost of evaluating $f(x_i)$?
- example for $\mathbf{M} = [a, b]$: define $\Delta = (b - a)/(N - 1)$ and

$$x_i = a + \Delta(i - 1) \quad , \quad w(x_1) = w(x_N) = \frac{\Delta}{2} \quad , \quad w(x_i) = \Delta \quad \text{for } 1 < i < N$$

Numerical integration for a 1-dim example

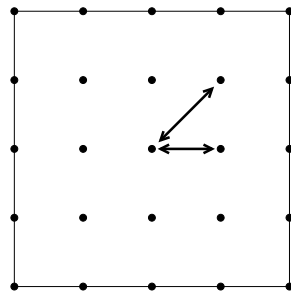


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Curse of dimensionality

- If there is no *a priori* knowledge about f , it seems most reasonable to take the points $\{x_i\}$ distributed over M as uniformly as possible.
- In the 1-dim case, this means the regular grid of the example before.
- Finding uniformly distributed point sets in more dimensions is a highly non-trivial problem.



For a hypercubic grid in n dimensions

$$\sum_{i_1=1}^N \sum_{i_2=1}^N \cdots \sum_{i_n=1}^N w_{i_1, i_2, \dots, i_n} f(a_1 + \Delta_1(i_1 - 1), a_2 + \Delta_2(i_2 - 1), \dots, a_n + \Delta_n(i_n - 1))$$

you need $\mathcal{O}(N^n)$ points to reach a similar precision as the 1-dim case with $\mathcal{O}(N)$ points.

So if the integration error decreases as $N_{\text{eval}}^{-\alpha}$ in the 1-dim case, it decreases as $N_{\text{eval}}^{-\alpha/n}$ in the n -dim case.

So no matter how good your 1-dim method is, no matter how large α is, in high dimension you always lose.

Monte Carlo integration

Let g be a *probability density* on \mathbf{M} such that if $f(x) \neq 0$ then $g(x) \neq 0$.
Let $\{x_i\}$ be a sequence of points in \mathbf{M} independently drawn at random from g .
Then, for $N \rightarrow \infty$, the probability distribution of the random variable

$$X_N = \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{g(x_i)}$$

becomes Gaussian, with expectation value and variance

$$E(X_N) = \int_{\mathbf{M}} d^{\omega} x f(x) \quad , \quad V(X_N) = \frac{1}{N} \left[\int_{\mathbf{M}} d^{\omega} x \frac{f(x)^2}{g(x)} - \left(\int_{\mathbf{M}} d^{\omega} x f(x) \right)^2 \right]$$

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$$\begin{aligned} E(X_N) &= \int_{\mathbf{M}} d^{\omega} x_1 g(x_1) \int_{\mathbf{M}} d^{\omega} x_2 g(x_2) \cdots \int_{\mathbf{M}} d^{\omega} x_N g(x_N) \left(\frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{g(x_i)} \right) \\ &= \frac{1}{N} \sum_{i=1}^N \int_{\mathbf{M}} d^{\omega} x_i f(x_i) \prod_{j \neq i} \int_{\mathbf{M}} d^{\omega} x_j g(x_j) = \frac{1}{N} N \int_{\mathbf{M}} d^{\omega} x f(x) \times 1 \end{aligned}$$

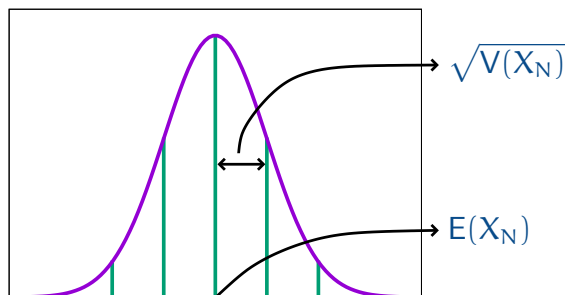
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X_N is an estimate of the integral of f
with error estimate $\sqrt{V(X_N)}$

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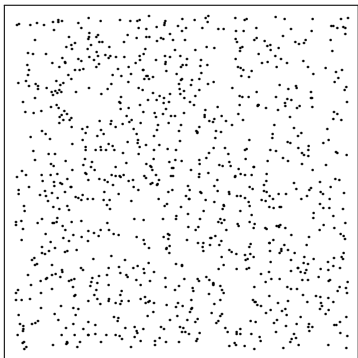
- X_N is an estimate of the integral of f with error estimate $\sqrt{V(X_N)}$
- $V(X_N)$ can be estimated itself with $[N^{-1} \sum_{i=1}^N f(x_i)^2 / g(x_i)^2 - X_N^2] / (N - 1)$
- the error decreases as $N^{-1/2}$, independently of \mathbf{M}
- *importance sampling*: convergence can be improved by choosing g such that it has the same shape as f . If you can construct $g(x) = f(x) / \int_{\mathbf{M}} d^{\omega}y f(y)$, then you actually solved the integration problem without the need of Monte Carlo.

Random number generation

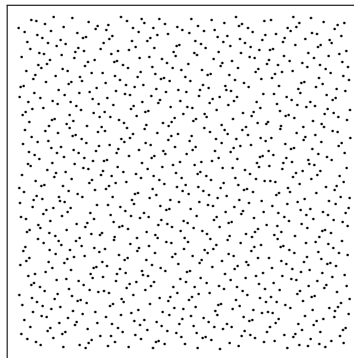
We will always assume there is a generator of uniformly distributed random numbers $p \in [0, 1]$ available.

In practice, this is a *pseudo random number* generator, based on a deterministic algorithm (which is actually usefull for reproducibility).

In higher dimension, so called *quasi random numbers* can be applied to achieve better uniformity:



(pseudo) random



quasi random

Error decreases as $(\log N)^p / N$, but accurate error estimation is much more difficult for Quasi Monte Carlo.

Random variable generation

Several methods exist to generate random variables with non-trivial distribution g on non-trivial space \mathbf{M} :

Inversion: find mapping $\varphi : [0, 1]^\omega \rightarrow \mathbf{M}$ such that

$$|\mathbf{J}_{\varphi^{-1}}(\mathbf{x})| = \int_0^1 d^\omega \rho \delta^\omega(\mathbf{x} - \varphi(\rho)) = g(\mathbf{x})$$

- Is practically only possible for 1-dim cases, for which it can be formulated as solving

$$\int_{-\infty}^x dy g(y) = \rho \int_{-\infty}^{\infty} dy g(y) \quad \Rightarrow \quad \varphi : \rho \rightarrow x$$

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$$g(x) \stackrel{?}{\sim} \frac{\theta(1 < x < 2))}{x} \quad \Rightarrow \quad \int_1^x \frac{dy}{y} = \rho \int_1^2 \frac{dy}{y} \quad \Leftrightarrow \quad \log(x) = \rho \log(2) \quad \Leftrightarrow \quad x = 2^\rho$$

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Rejection: given an approximate \tilde{g} and a number c such that $c\tilde{g}(x) > g(x) \forall x \in \mathbf{M}$

1. generate x from \tilde{g} and $\rho \in [0, 1]$
2. if $\rho c \tilde{g}(x) \leq g(x)$, then accept x , else reject x and try again

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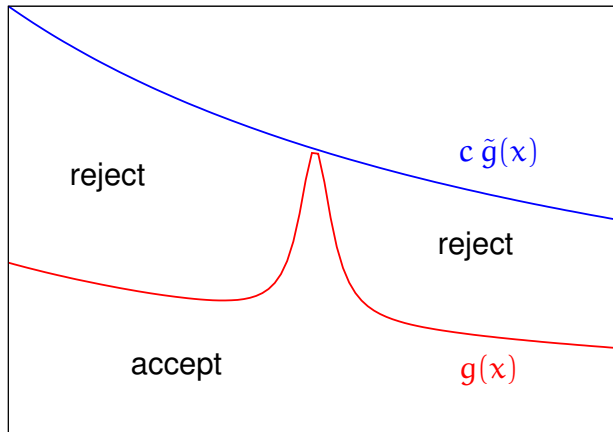
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$$\begin{aligned} f(\mathbf{x}) &= \int_{\mathbf{M}} d^\omega \mathbf{y} \tilde{g}(\mathbf{y}) \int_0^1 d\rho [\theta(\rho c \tilde{g}(\mathbf{y}) \leq g(\mathbf{y})) \delta(\mathbf{x} - \mathbf{y}) + \theta(\rho c \tilde{g}(\mathbf{y}) > g(\mathbf{y})) f(\mathbf{x})] \\ &\Rightarrow f(\mathbf{x}) = g(\mathbf{x}) \left(\int_{\mathbf{M}} d^\omega \mathbf{y} g(\mathbf{y}) \right)^{-1} \end{aligned}$$

Random variable generation



Rejection: given an approximate \tilde{g} and a number c such that $c\tilde{g}(x) > g(x) \forall x \in M$

1. generate x from \tilde{g} and $p \in [0, 1]$
 2. if $p c \tilde{g}(x) \leq g(x)$, then accept x , else reject x and try again
- The larger c , the less efficient the rejection, i.e. the more trials are needed.
 - Interpreting $g(x)/\tilde{g}(x)$ as the *weight* of x , rejection produces a sequence of x -es with constant weight, i.e. they are *unweighed*.

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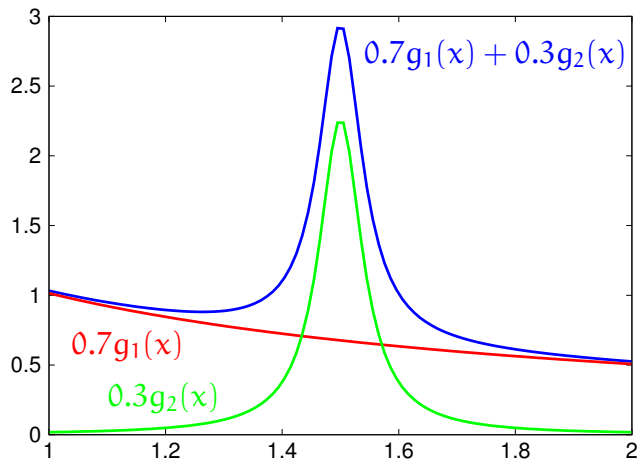
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Many very efficient 1-dim algorithms are based on combining inversion and rejection.

Adaptive random variable generation

Multi-channel(mixture distribution): given n densities g_i and positive weights w_i with $\sum_{i=1}^n w_i = 1$, we can define the density $g(x) = \sum_{i=1}^n w_i g_i(x)$. To generate x following g

1. generate $\rho \in [0, 1]$ and find i such that $\sum_{j=1}^{i-1} w_j < \rho \leq \sum_{j=1}^i w_j$
2. generate $x \in \mathbf{M}$ following g_i



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Adaptive multi-channel for overlapping densities g_i (Kleiss, Pittau 1994):

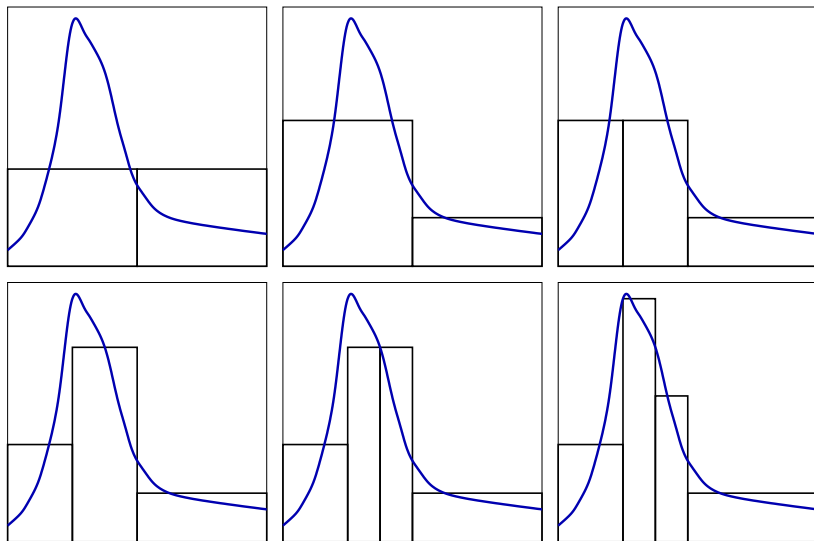
3. collect batches of N integration points x_j and update the weights following

$$w_i \leftarrow w_i \sqrt[p]{\frac{1}{N} \sum_{j=1}^N \frac{g_i(x_j)}{g(x_j)} \left(\frac{f(x_j)}{g(x_j)} \right)^p} \quad \text{and normalize} \quad \sum_{i=1}^n w_i = 1$$

- Originally formulated for $p = 2$ to achieve variance minimalization.
- Works for up to many channels ($\mathcal{O}(1000)$), but the evaluation of $g(x)$ becomes expensive.
- The channels are typically imagined to correspond to Feynman graphs, defining kinematical channels.

Adaptive random variable generation

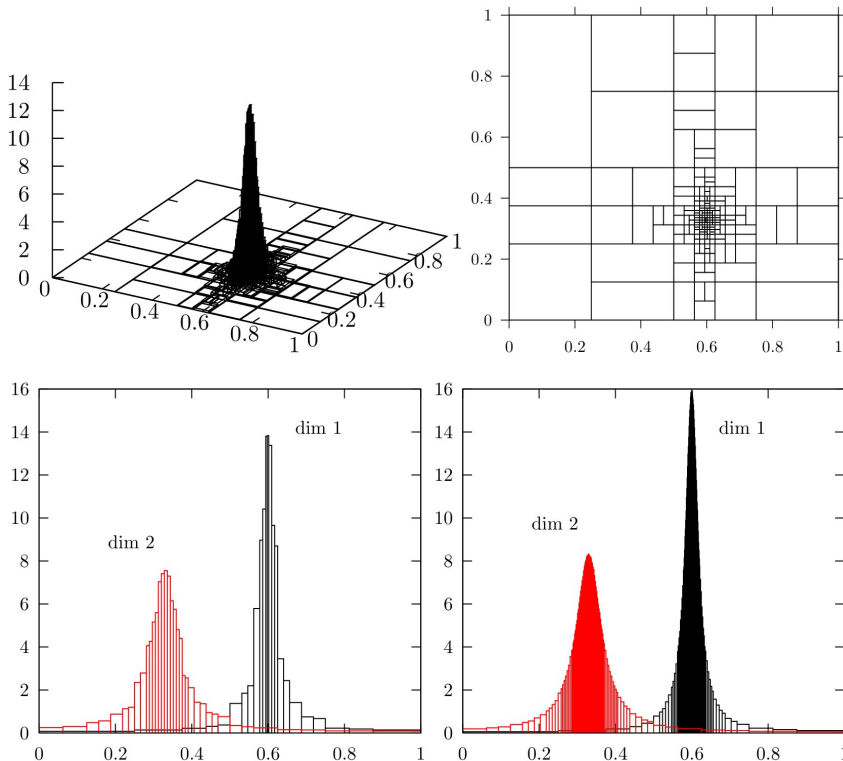
Besides the weights w_i in $g(x) = \sum_{i=1}^n w_i g_i(x)$, we can also try to adapt the densities g_i themselves. In particular when the densities g_i are uniform non-overlapping partition of the integration space, various strategies are thinkable.



Adaptive random variable generation

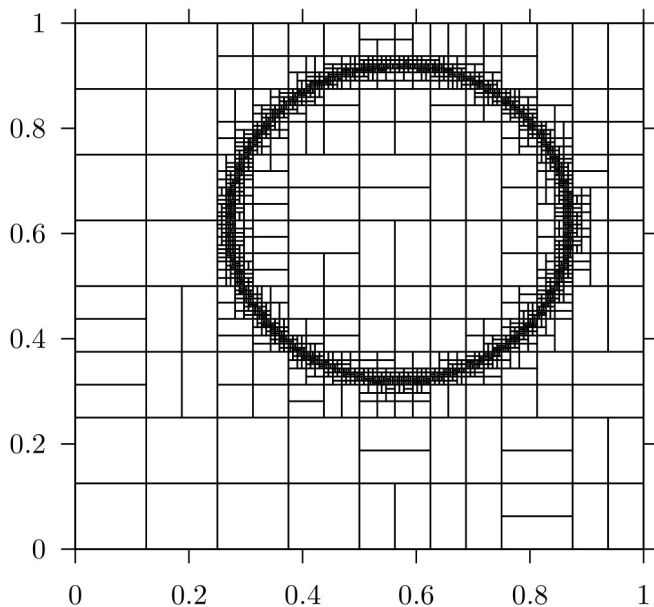
VEGAS approach

In case of multi-dimensional integration problems, it works best for factorizable integrands. Then, one-dimensional partitions are best used.



Adaptive random variable generation

For non-factorizable integrands, truly multi-dimensional partitions can be applied (eg. FOAM [Jadach 2000](#) and PARNI [AvH 2009](#)), but the curse of dimensionality returns.



k_T -dependent factorization

Hadron-scattering process Y with partonic processes y contributing to multi-jet final state

$$d\sigma_Y(p_1, p_2; k_3, \dots, k_{2+n}) = \sum_{y \in Y} \int d^4k_1 \mathcal{P}_{y_1}(k_1) \int d^4k_2 \mathcal{P}_{y_2}(k_2) d\hat{\sigma}_y(k_1, k_2; k_3, \dots, k_{2+n})$$

Collinear factorization:

$$\mathcal{P}_{y_i}(k_i) = \int \frac{dx_i}{x_i} f_{y_i}(x_i, \mu) \delta^4(k_i - x_i p_i)$$

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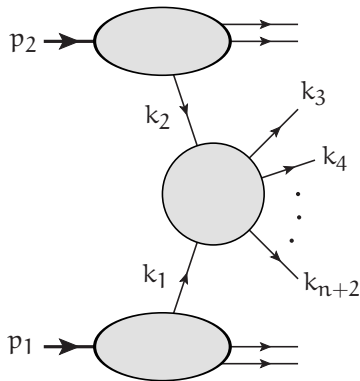
$$\mathcal{P}_{y_i}(k_i) = \int \frac{d^2\mathbf{k}_{iT}}{\pi} \int \frac{dx_i}{x_i} \mathcal{F}_{y_i}(x_i, |\mathbf{k}_{iT}|, \mu) \delta^4(k_i - x_i p_i - \mathbf{k}_{iT})$$

Differential partonic cross section:

$$d\hat{\sigma}_y(k_1, k_2; k_3, \dots, k_{2+n}) = d\Phi_Y(k_1, k_2; k_3, \dots, k_{2+n}) \Theta_Y(k_3, \dots, k_{2+n}) \\ \times \text{flux}(k_1, k_2) \times \mathcal{S}_y |\mathcal{M}_y(k_1, \dots, k_{2+n})|^2$$

Parton-level phase space:

$$d\Phi_Y(k_1, k_2; k_3, \dots, k_{3+n}) = \left(\prod_{i=3}^{n+3} d^4k_i \delta_+(k_i^2 - m_i^2) \right) \delta^4(k_1 + k_2 - k_3 - \dots - k_{n+3})$$



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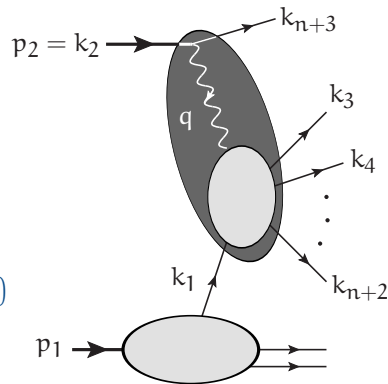
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Parton-level event generation

- choose partonic subprocess $y = y_1, y_2 \rightarrow y_3, \dots, y_{n+2}$ with probability $P(y)$
- generate initial-state variables x_1, x_2, k_{T1}, k_{T2} with probability $P(y; x_1, x_2, k_{T1}, k_{T2})$
- generate final-state momenta k_3, \dots, k_{n+2} with differential probability

$$dF(y, k_1, k_2; k_3, \dots, k_{2+n}) = d\Phi_Y(k_1, k_2; k_3, \dots, k_{2+n}) P(y, k_1, k_2; k_3, \dots, k_{2+n})$$

- assign weight = 0 to phase space point if it does not satisfy the inclusive cuts...
- ... else evaluate PDFs and matrix element and assign weight

$$\mathcal{W}_y(k_1, \dots, k_{2+n}) = \frac{\mathcal{F}_{y_1}(x_1, k_{T1}) \mathcal{F}_{y_2}(x_2, k_{T2}) |\mathcal{M}_y(k_1, \dots, k_{2+n})|^2 \mathcal{S}_y \text{flux}(k_1, k_2)}{P(y) P(y; x_1, x_2, k_{T1}, k_{T2}) P(y, k_1, k_2; k_3, \dots, k_{2+n})}$$

- choose/create probabilities P wisely/adaptively in order to let $\mathcal{W}_y(k_1, \dots, k_{2+n})$ fluctuate as little as possible from event to event ...
- ... this requires an **optimization stage** for each subprocess y during which crude estimates of partonic cross sections are made
- there is a lot of engineering/parameters in P , but there is only QFT in \mathcal{M}_y

Phase Space

The differential volume of n -particle phase space is given by

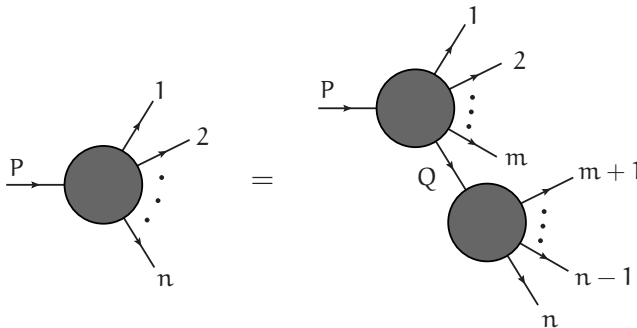
$$d\Phi_n(p_1, s_1, p_2, s_2 \dots p_n, s_n; P) = \\ d^4p_1 \delta(p_1^2 - s_1) d^4p_2 \delta(p_2^2 - s_2) \dots d^4p_n \delta(p_n^2 - s_n) \delta^4(P - p_1 - p_2 - \dots - p_n)$$

and satisfies the recursive relation

$$d\Phi_n(p_1, s_1, p_2, s_2 \dots p_n, s_n; P) = \\ dS d\Phi_{m+1}(p_1, s_1, p_2, s_2 \dots p_m, s_m, Q, S; P) \\ \times d\Phi_{n-m}(p_{m+1}, s_{m+1}, p_{m+2}, s_{m+2} \dots p_n, s_n; Q)$$

with integration over S and Q .

So phase space can be completely decomposed into 2-particle phase spaces, and can be written in terms of invariants and angles.



2-particle phase space

We want to generate $\mathbf{p}_a, \mathbf{p}_b$ in a 2-particle phase space $\Phi(\mathbf{p}_a, s_a, \mathbf{p}_b, s_b; \mathbf{P})$. This implies that \mathbf{P} and also s_a, s_b are given (generated or squared external masses) and we can define

$$|\vec{q}| = \sqrt{\frac{\lambda(P^2, s_a, s_b)}{4P^2}} \quad \text{with} \quad \lambda(x, y, z) = x^2 + y^2 + z^2 - 2xy - 2yz - 2zx$$

Now, we can

1. generate $\varphi \in [0, 2\pi]$ and $z \in [-1, 1]$
2. construct $q^0 = \sqrt{s_a + |\vec{q}|^2}$ and $\vec{q} = |\vec{q}| \left(\sqrt{1 - z^2} \cos \varphi, \sqrt{1 - z^2} \sin \varphi, z \right)$
3. \mathbf{q} is \mathbf{p}_a in the center-of-mass frame of \mathbf{P} , and needs to be boosted:

$$\mathbf{p}_a^\mu = (E, \vec{q} + V\vec{P}) \quad \text{with} \quad E = \frac{\mathbf{q} \cdot \mathbf{P}}{\sqrt{P^2}} \quad \text{and} \quad V = \frac{q^0 + E}{P^0 + \sqrt{P^2}}$$

4. and finally $\mathbf{p}_b = \mathbf{P} - \mathbf{p}_a$

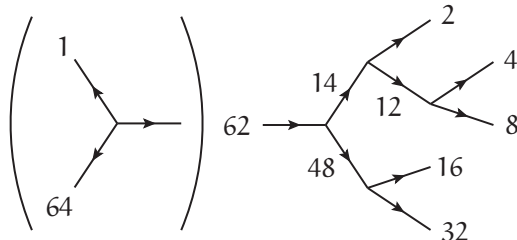
This construction gives a Jacobian $\frac{\sqrt{P^2}}{\pi |\vec{q}|} = \frac{2P^2}{\pi \sqrt{\lambda(P^2, s_a, s_b)}}$

n-particle phase space

To generate, for example, 5-particle phase space, choose a decomposition into 2-particle phase spaces.

External momenta labelled by a power of 2 and $\mathbf{p}_i + \mathbf{p}_j = \mathbf{p}_{i+j}$ and $\mathbf{p}_{2^{n+3}-1} = 0$, so for $n = 5$: $\mathbf{p}_{127} = 0$ and $\mathbf{p}_i = -\mathbf{p}_{127-i}$

The density factor of the example graph is



$$g(\{p\}) = g_{48}(s_{48}) g_{14}(s_{14}) \frac{2s_{62}}{\pi\sqrt{\lambda(s_{64}, s_{48}, s_{14})}} g_{12}(s_{12}) \frac{2s_{14}}{\pi\sqrt{\lambda(s_{14}, s_{12}, s_2)}} \\ \times \frac{2s_{12}}{\pi\sqrt{\lambda(s_{12}, s_8, s_4)}} \frac{2s_{48}}{\pi\sqrt{\lambda(s_{48}, s_{32}, s_{16})}}$$

The virtual invariants (s_{48}, s_{14}, s_{12}) need to be generated, and one can use densities anticipating the behavior of the integrand

$$\text{e.g. } g_{12}(s) \propto \frac{1}{(s - M_Z^2)^2 + \Gamma_Z^2 M_Z^2}$$

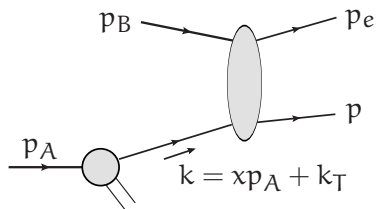
More graphs can be included via the multi-channel method. This way, the squared graphs in a squared amplitude can be matched, while interferences cannot.

Electron-proton scattering

Electron-proton scattering

$$\frac{d^2\sigma_{e^-p \rightarrow e^-X}^{u\text{-quark}}}{dx_{Bj} dQ^2} = \int dx \int \frac{d^2k_T}{\pi} \mathcal{F}_u(x, |\vec{k}_T|, Q) \int d\Phi(p_B + k \rightarrow \{p_e, p\}) \frac{1}{2\chi s} |\overline{\mathcal{M}}(e^- u^* \rightarrow e^- u)|^2$$

$$\times \delta(Q^2 + (p_B - p_e)^2) \delta\left(x_{Bj} - \frac{Q^2}{2p_A \cdot (p_B - p_e)}\right)$$



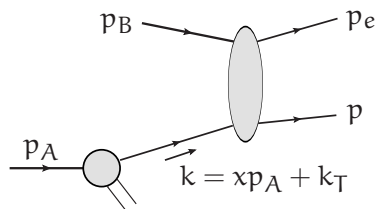
$$p_A^2 = p_B^2 = p_e^2 = p^2 = 0 \quad s = 2p_A \cdot p_B \quad y = \frac{Q^2}{x_{Bj} s}$$

collinear factorization: $\mathcal{F}_u(x, |\vec{k}_T|, Q) \rightarrow f_u(x, Q) \delta(|\vec{k}_T|^2)$

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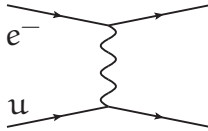
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$$\int d\Phi(p_B + k \rightarrow \{p_e, p\}) \delta(Q^2 + (p_B - p_e)^2) \delta\left(x_{Bj} - \frac{Q^2}{2p_A \cdot (p_B - p_e)}\right)$$

$$= \left\{ \text{collinear} : \frac{\delta(x - x_{Bj})}{8\pi x_{Bj} s}, \quad k_T\text{-factorization} : \frac{1}{16\pi^2 x_{Bj}^2 s \sqrt{\Delta(x, k_T)}} \right\}$$

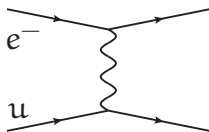
$$\Delta(x, |\vec{k}_T|) = -\prod_{i=1}^4 \left(\frac{|\vec{k}_T|}{Q} \pm \sqrt{x/x_{Bj} - y} \pm \sqrt{1 - y} \right)$$

Electron-proton scattering

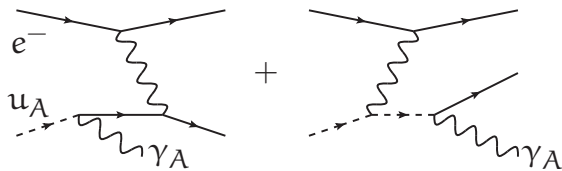


$$\frac{|\overline{\mathcal{M}}(e^-u \rightarrow e^-u)|^2}{(4\pi\alpha C_u)^2} = \frac{2xs}{Q^2} \frac{1 + (1 - \tilde{y})^2}{\tilde{y}} \quad , \quad \tilde{y} = \frac{x_{Bj}}{x} y$$

Electron-proton scattering

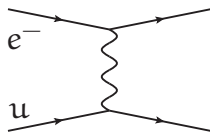


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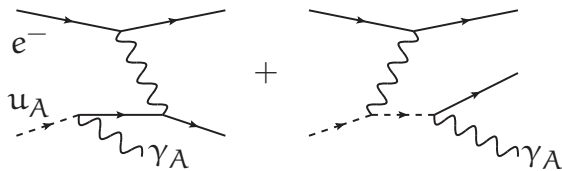


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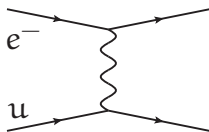
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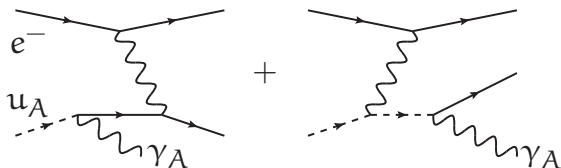
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Electron-proton scattering



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$$\left[\kappa = 1 + \frac{x}{x_{Bj}} - 2y - 2\cos(\pi\rho) \sqrt{(1 - y) \left(\frac{x}{x_{Bj}} - y \right)} \right] = C_u^2 Q^2 \int_{Q^2/s}^1 dx \int_0^1 d\rho \mathcal{F}_u(x, Q^2 \kappa(\rho, x), Q)$$

$$\left[\xi = 1 + \frac{k_T^2}{Q^2} - 2\cos(\pi\rho) \sqrt{1 - y} \frac{k_T}{Q} \right] = C_u^2 x_{Bj} \int_0^{Q^2 \kappa_+(1)} dk_T^2 \int_0^1 d\rho \mathcal{F}_u(x_{Bj} \xi(\rho, k_T), k_T^2, Q)$$

- parton level event generator, like ALPGEN, HELAC, MADGRAPH, etc.
- arbitrary hadron-hadron or hadron-lepton processes within the standard model (including effective Higgs-gluon coupling) with several final-state particles.
- 0, 1, or 2 off-shell initial states.
- produces (partially un)weighted event files, for example in the LHEF format.
- requires LHAPDF. TMD PDFs can be provided as files containing rectangular grids, or with TMDlib (Hautmann, Jung, Krämer, Mulders, Nocera, Rogers, Signori 2014).
- a calculation is steered by a single input file.
- employs an optimization stage in which the pre-samplers for all channels are optimized.
- during the generation stage several event files can be created in parallel.
- event files can be processed further by parton-shower program like CASCADE.
- (evaluation of) matrix elements separately available, including C++ interface.