

LGADs-based TOF for ECCE

- status of simulations in Fun4All

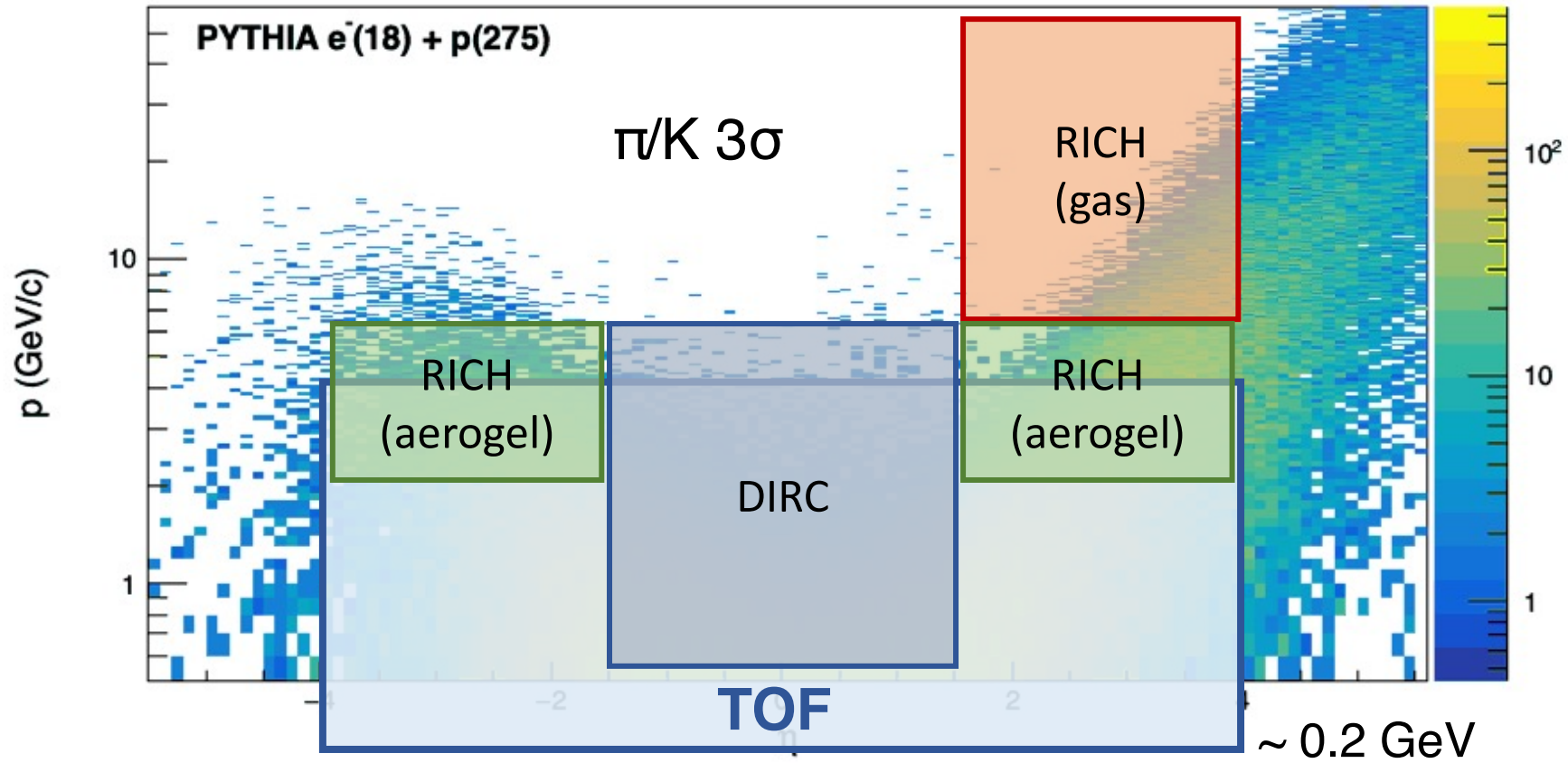
Wei Li (Rice University)



RICE

ECCE PID WG meeting
May 20, 2021

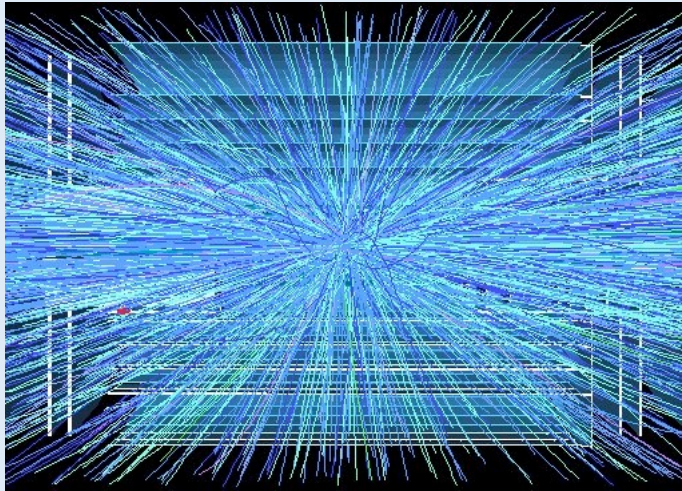
My view on PID@ECCE



η	$\pi/K/p$ PID	
	p-Range (GeV/c)	Separation
-3.5 — -3.0	≤ 7 GeV/c	$\geq 3\sigma$
-3.0 — -2.5		
-2.5 — -2.0		
-2.0 — -1.5		
-1.5 — -1.0		
-1.0 — -0.5	≤ 10 GeV/c	
-0.5 — 0.0		
0.0 — 0.5		
0.5 — 1.0	≤ 15 GeV/c	
1.0 — 1.5	≤ 30 GeV/c	
1.5 — 2.0	≤ 50 GeV/c	
2.0 — 2.5		
2.5 — 3.0		
3.0 — 3.5	≤ 45 GeV/c	

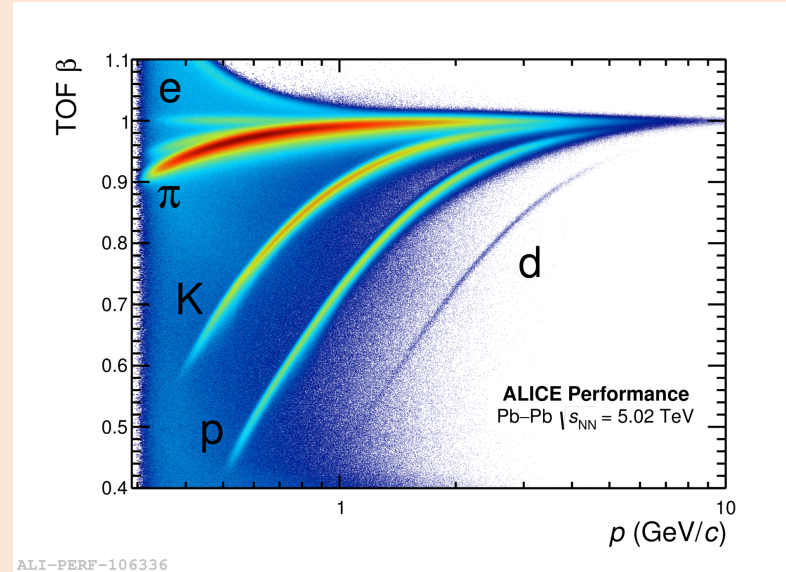
Concept of LGADs sensors

Precision position detectors:



e.g., silicon:
Thin & Light
Segmented
B tolerant
Rad-hard

Precision timing detector:



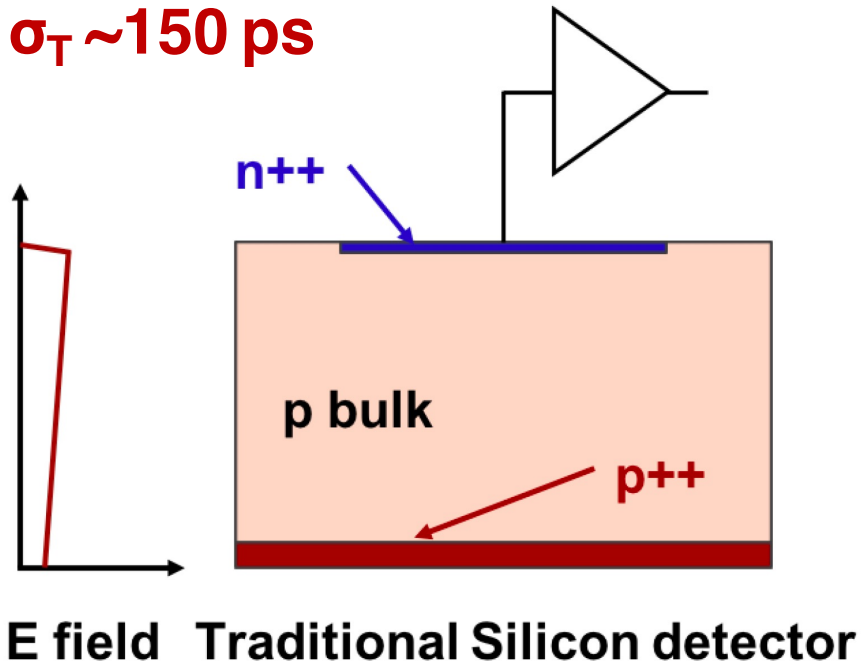
Scintillation
Ionization
+
High gain

LGADs sensors:
precision **position** and **timing**

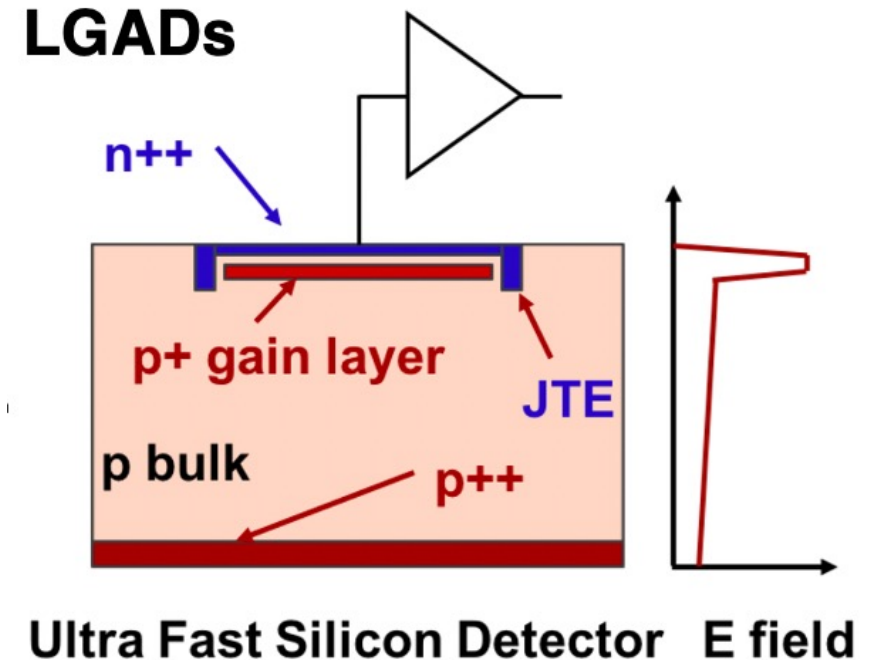
Low Gain Avalanche Diodes (LGADs)

High E field → larger, faster signal → better timing resolution

$\sigma_T \sim 150$ ps



VS.



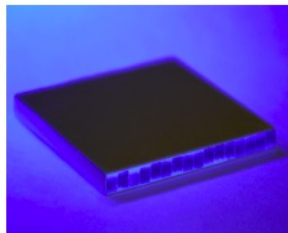
Adding an extra doping layer

- E ~ 300 kV/cm, close to breakdown

LGADs at the HL-LHC (2028)

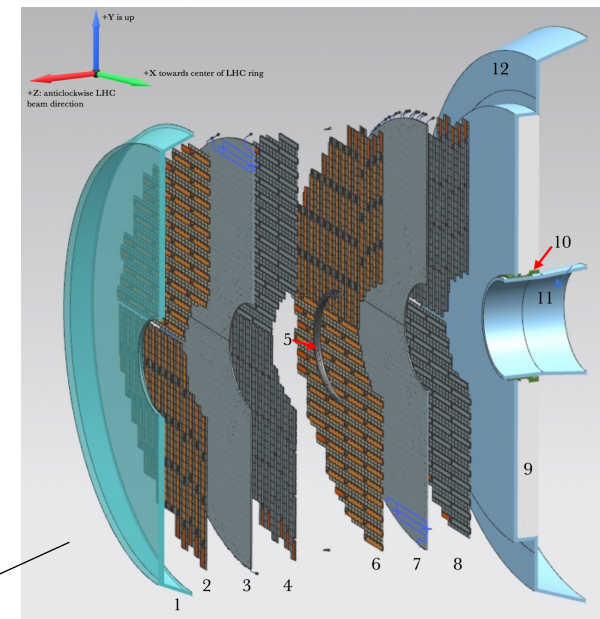
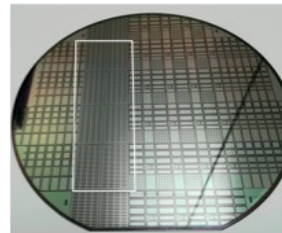
BTL: LYSO bars + SiPM readout:

- TK / ECAL interface: $|\eta| < 1.45$
- Inner radius: 1148 mm (40 mm thick)
- Length: ± 2.6 m along z
- Surface ~ 38 m²; 332k channels
- Fluence at 4 ab^{-1} : $2 \times 10^{14} n_{\text{eq}}/\text{cm}^2$



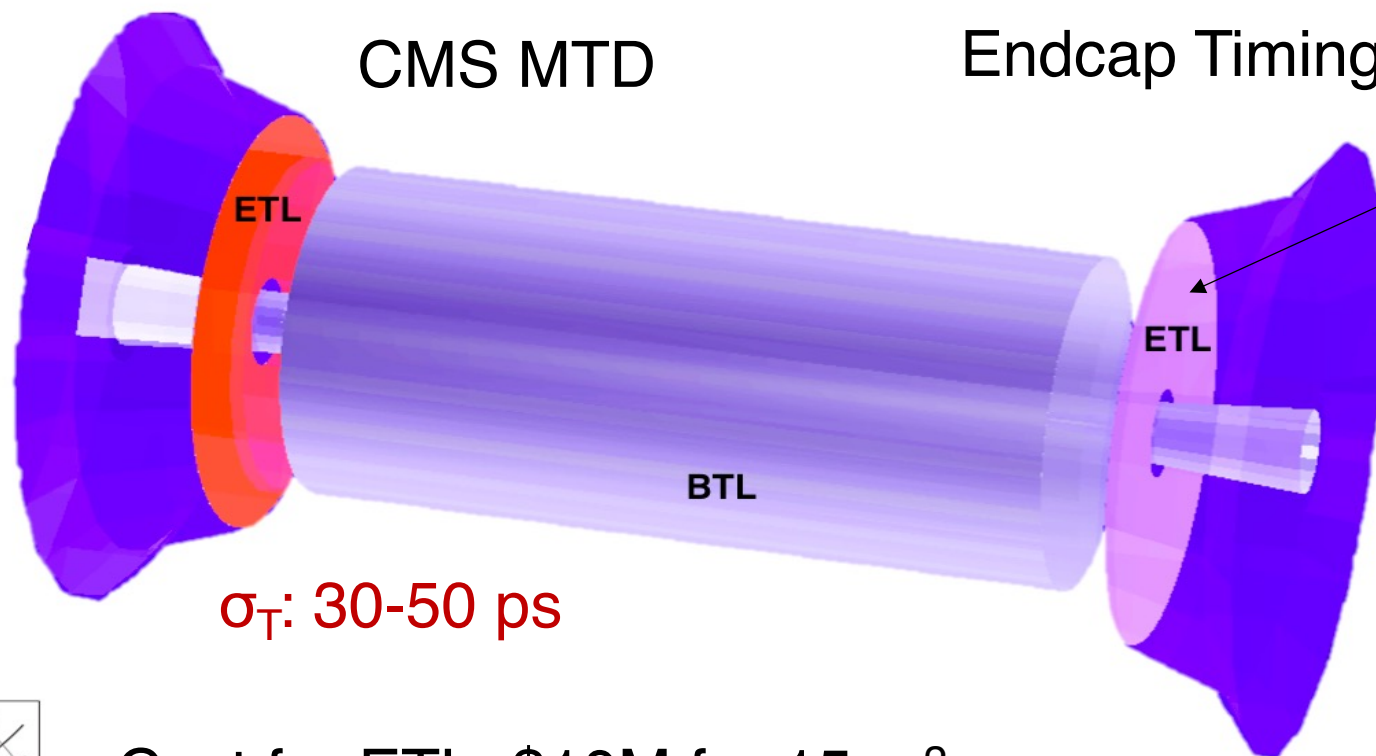
ETL: Si with internal gain (LGAD):

- On the CE nose: $1.6 < |\eta| < 3.0$
- Radius: $315 < R < 1200$ mm
- Position in z: ± 3.0 m (45 mm thick)
- Surface ~ 14 m²; ~ 8.5 M channels
- Fluence at 4 ab^{-1} : up to $2 \times 10^{15} n_{\text{eq}}/\text{cm}^2$



CMS MTD

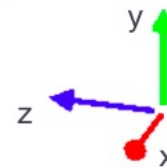
Endcap Timing Layer



σ_T : 30-50 ps

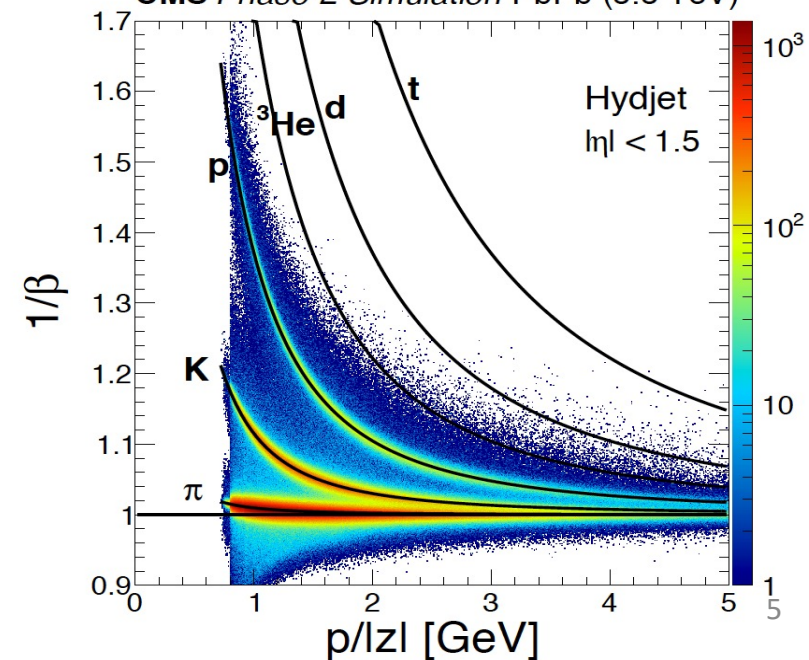


Cost for ETL: \$10M for 15 m²
(possible to optimize for low radiation)

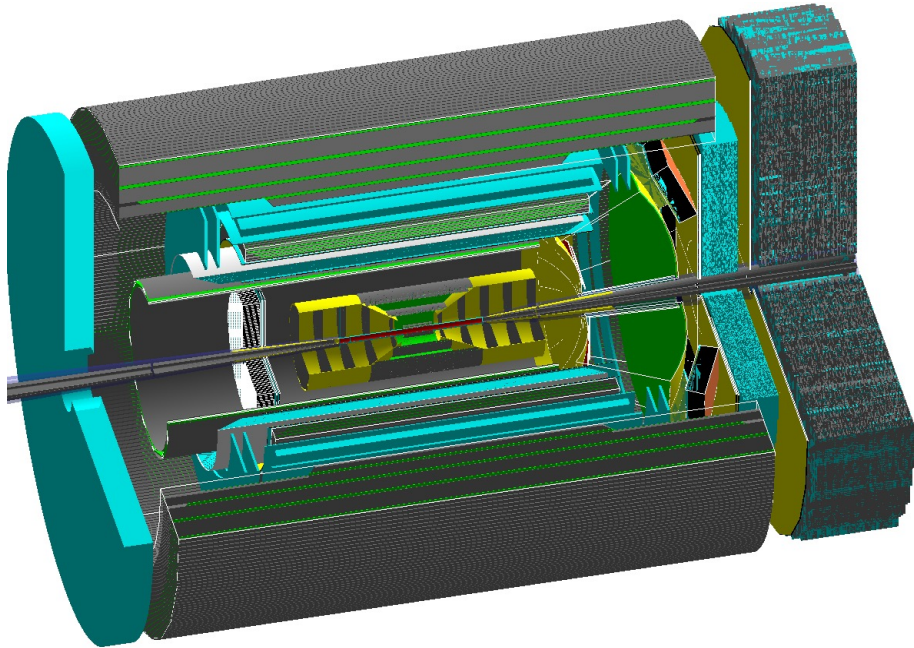


Particle ID in HI

CMS Phase-2 Simulation PbPb (5.5 TeV)



LGADs TOF simulation in Fun4All

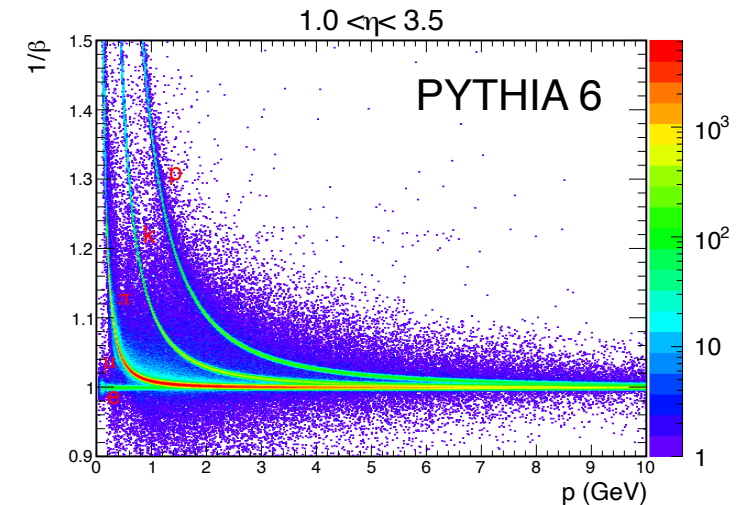


- Silicon layers with timing and position smeared to expected resolution
- Timing and path length of each track stored for calculating the velocity
- Material budget is dummy for now. Expect $< 0.2\% X_0$ per two layers based on CMS ETL

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https://github.com/eic/fun4all_eicmacros/blob/master/common/G4_TTL_EIC.C

	Default	R_{barrel}	Length	z location	$R_{\text{endcap,in}}$	$R_{\text{endcap,out}}$	η coverage	Area (m ²)
Backward	ETTL ₀			-1.555	0.077	0.632	[-3.7,-1.6]	1.23
	ETTL ₁			-1.585	0.078	0.62	[-3.7,-1.6]	1.19
Central	CTTL ₀	0.92	3.6				[-1.34,1.34]	20.8
	CTTL ₁	1.147	3.6				[-1.11,1.11]	25.9
Forward	FTTL ₀			2.87	0.116	1.527	[1.3,3.9]	7.28
	FTTL ₁			2.89	0.117	1.538	[1.3,3.9]	7.39
	FTTL ₂			3.4	0.138	2.185	[1.1,3.9]	14.94



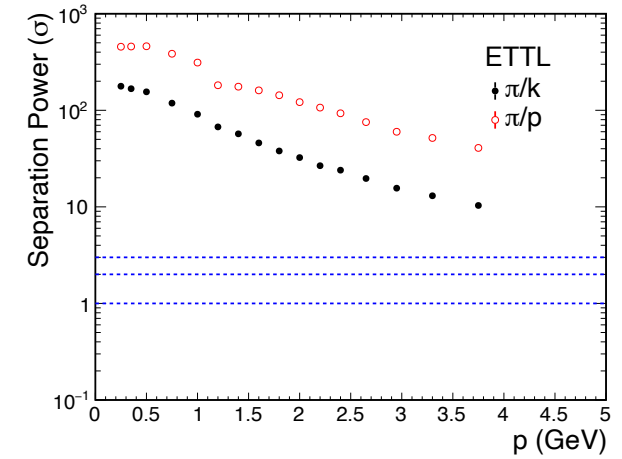
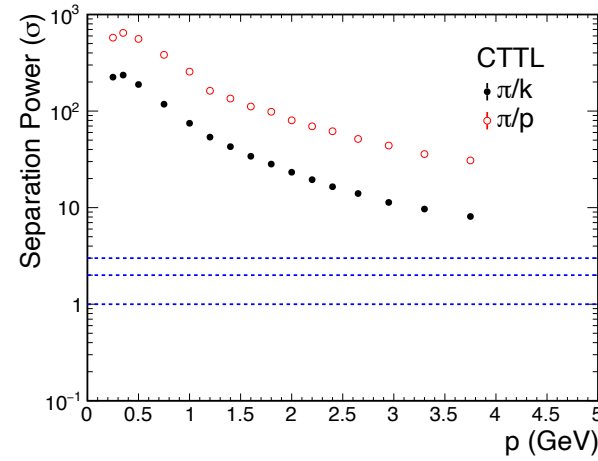
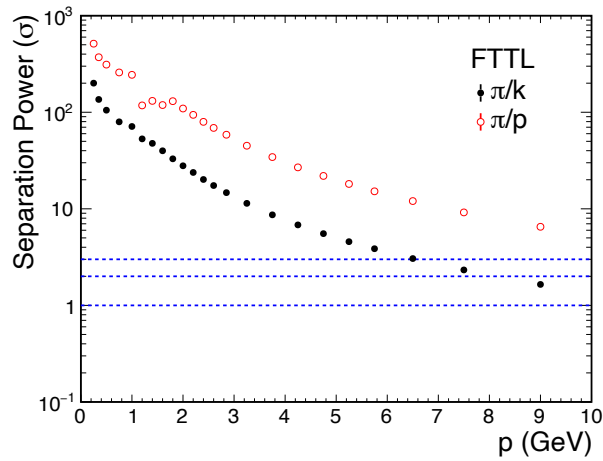
PID performance

Forward ($1 < \eta < 3.5$):

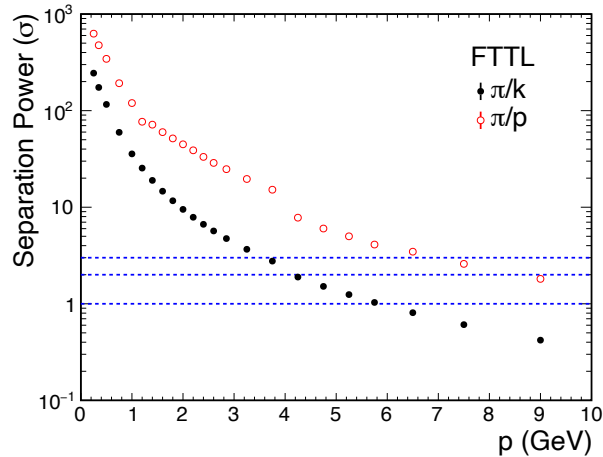
Central ($|\eta| < 1$):

Backward ($-3.5 < \eta < -1$):

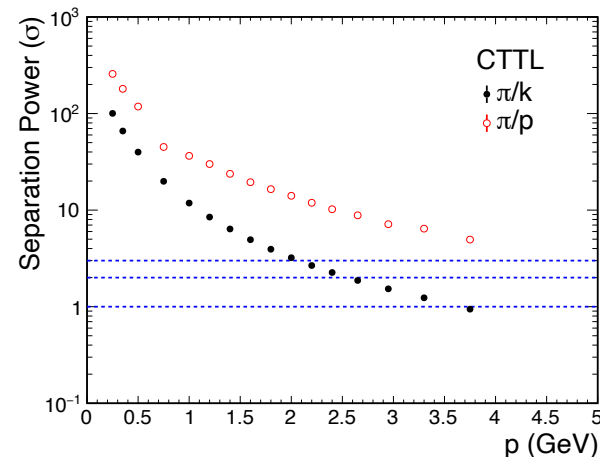
$\sigma_t = 0$ ps



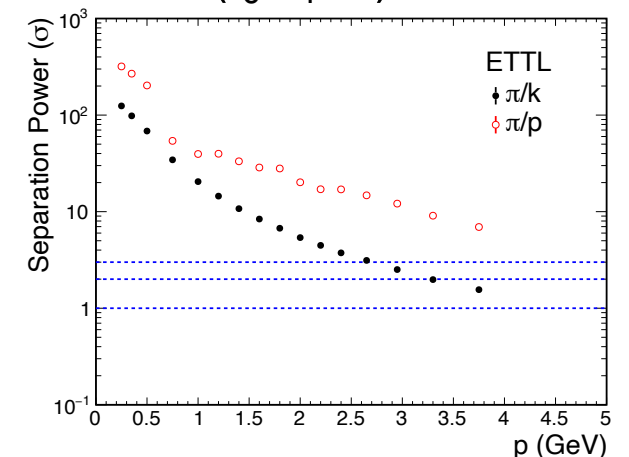
$\sigma_t = 20$ ps



0.2-4 GeV



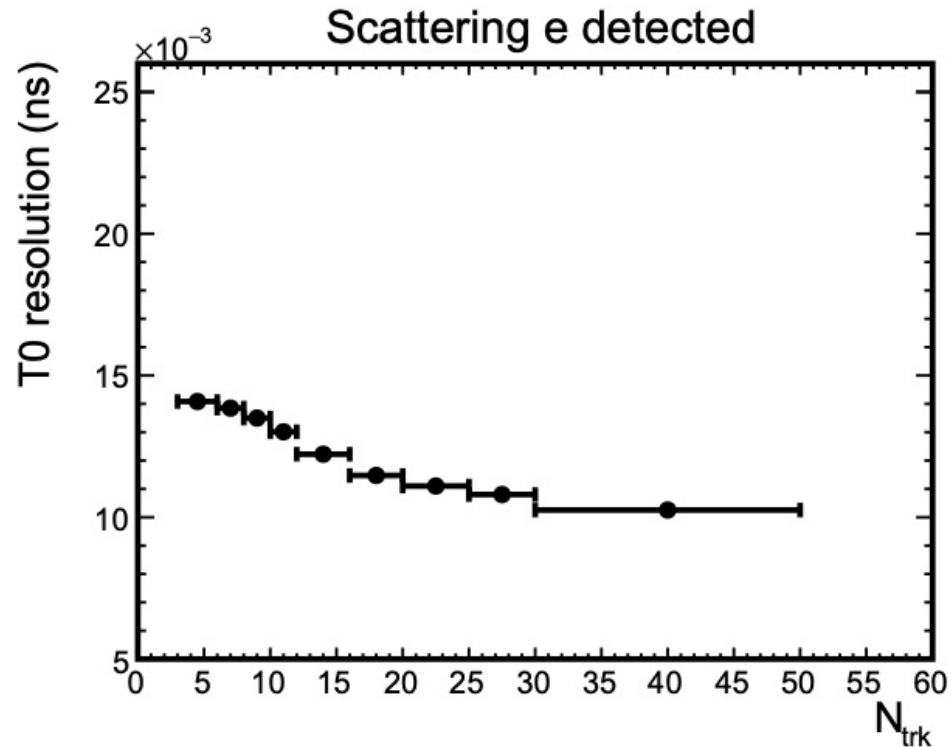
0.2-2.5 GeV



0.2-3 GeV

all uncertainties (t_0 , t_f , L) included

PID performance



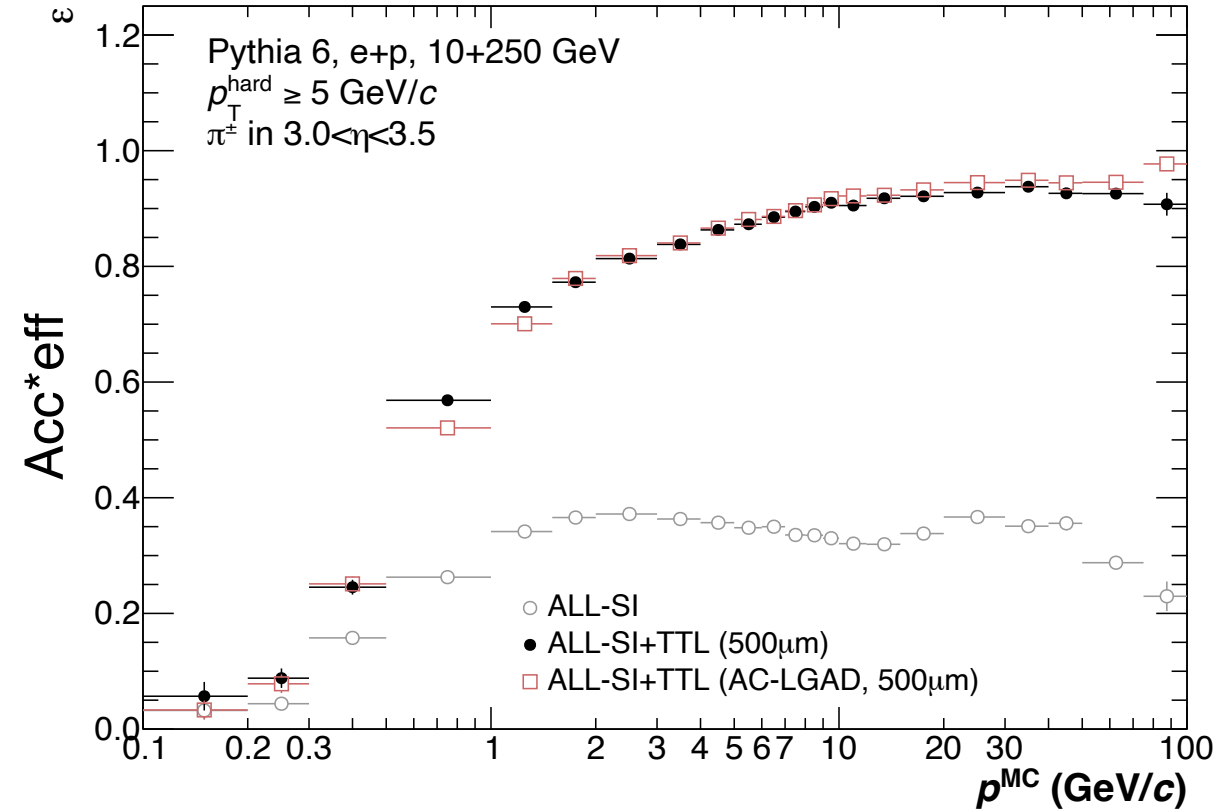
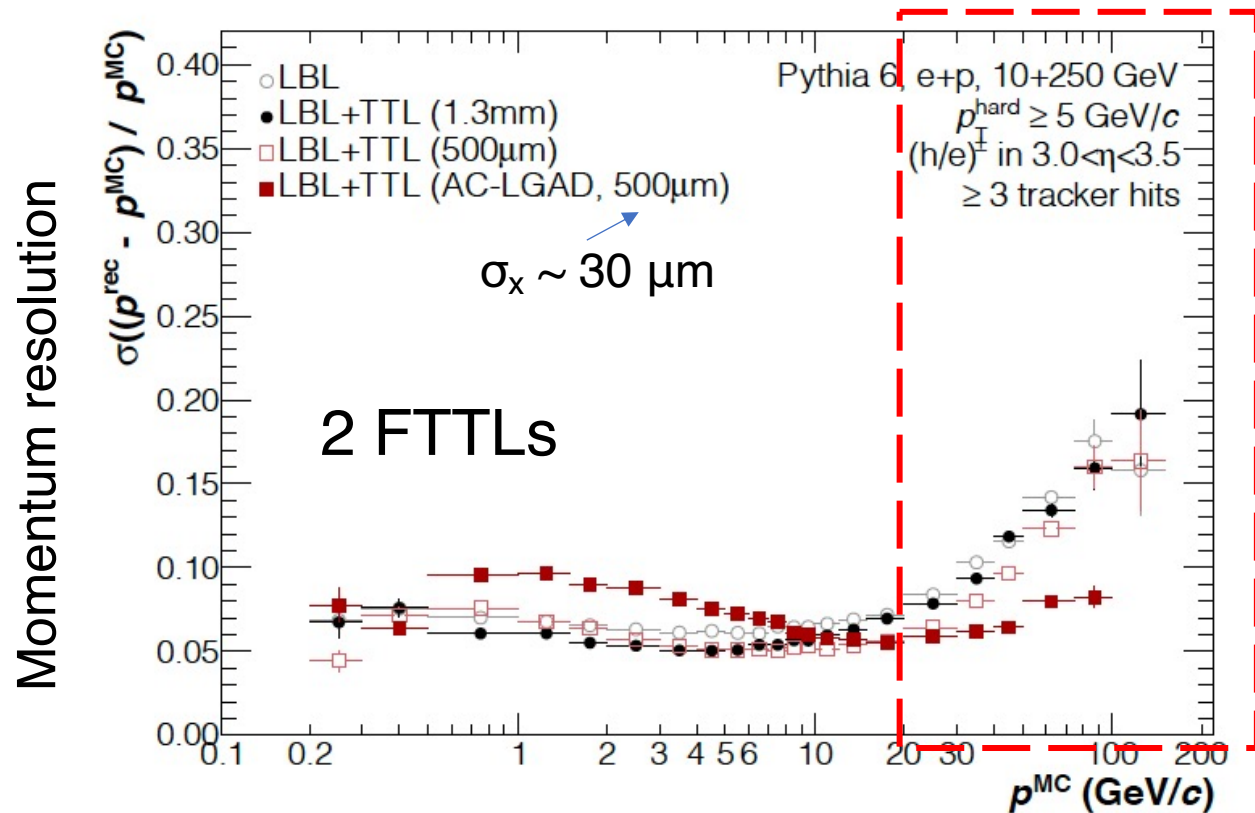
Iterative procedure to determine T_0 :

- Assume scattered e is detected by TOF
- Start with pion assuming for all other particles to fit T_0
- Update mass assumption for outliers in next iterations

Details described in https://wiki.bnl.gov/conferences/images/0/01/ERD29_progress_report_March2021.pdf
(still optimizing)

Forward tracking with LGADs

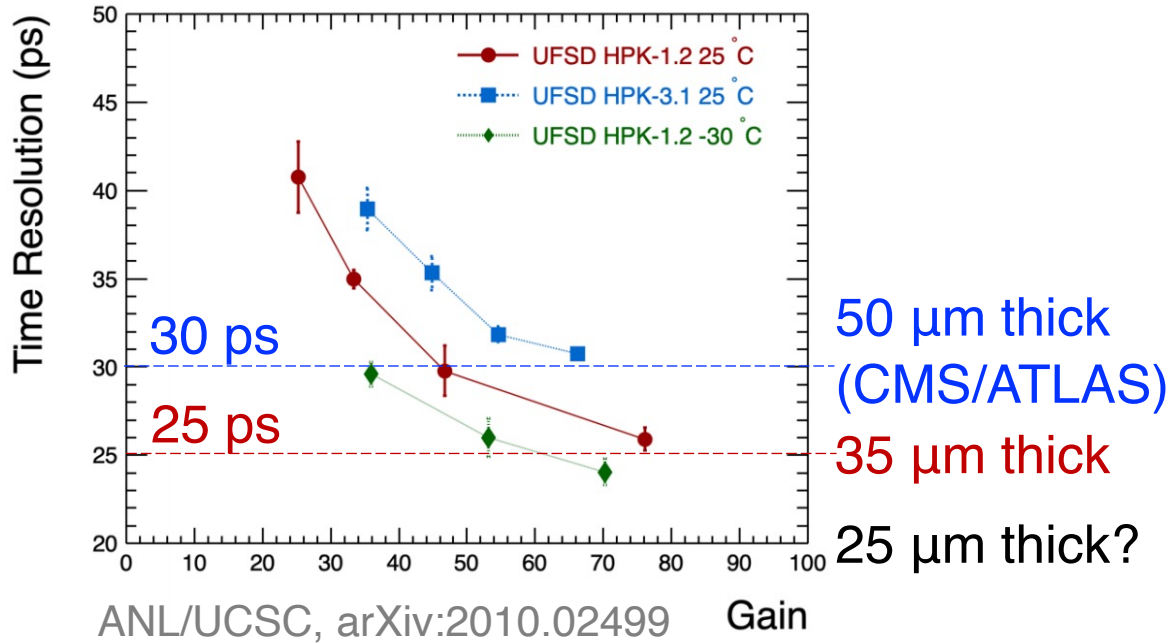
Tracking w/o vs. w/ LGADs layers



LGADs layers will serve as outer tracker to improve p resolution by up to 50% at 100 GeV/c and efficiency at forward y

Status of various R&Ds

LGADs sensor timing performance

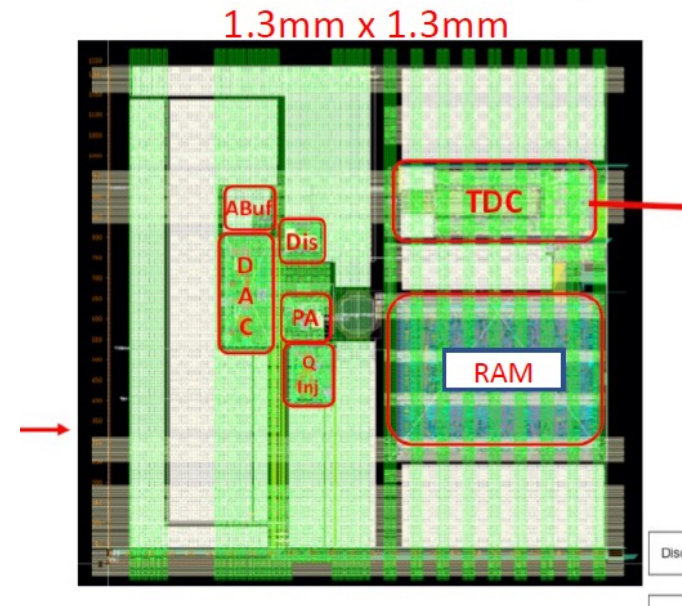


$\sigma_T \sim 20$ ps with 20-25 μm sensors well within the reach

LGADs consortium meeting on electronics:
<https://indico.bnl.gov/event/11717/>

Pitch size: 1.3 mm – 700 (500) μm
 (mainly limited by ASICs)

ETROC1 Single Pixel Layout



Small pitch \rightarrow more channels \rightarrow more power consumption
 (~ 2 mW/ch)

What is the realistic cool capability?

Backups

