

Consortia, Geometry and Detector-1 Integration

DETECTOR-1 COLLABORATION MEETING 26 July 2022

Silvia dalla Torre, Or Hen, <u>Tanja Horn</u>, John Lajoie, Bernd Surrow

EIC Detector Consortia

- ☐ Background: there are several EIC Detector Consortia that were formed around one or several subsystems and/or detector technologies
 - Expertise and knowledge
 - International
 - Background in EIC Detector R&D
- ☐ Detector-1 study: Reached out to Consortia with the following major questions:
 - Is anything missing in the overall approach for Detector-1?
 - Plans for the next year including the transition from R&D to design and construction
 - Relation with working groups and collaboration formation
- □ Note Consortia of institutions within a specific country and any agreements fall under the auspices of the EIC Project and are not included in this study

Meetings with the EIC Detector Consortia

- ☐ Meetings with the EIC Detector Consortia (so far)
 - 13 May 2022: hpDIRC
 - 16 May 2022: dRICH
 - 19 May 2022: EEEMCAL
 - 9 June 2022: EICSC
 - 23 June 2022: AC-LGAD
- ☐ Note that the Consortia have different characteristics and needs
 - very different nature and size of the consortia with some exclusively dedicated to EIC and others opened to wider communities
 - different perspectives regarding future workforce and financial support
 - Synergies with other subsystems
 - Documentation of technical specifications

Meetings with the Detector Consortia

- □ Overall the Consortia approaches are well formulated and can play a positive role in the process of Detector-1 consolidation and baseline definition
- ☐ Plans for the next year
 - Work with the WGs to understand the geometry constraints of detector-1 and evaluate the impact of the different constraints on the performance
 - Generate technical specifications document in phase with the guidelines on the EIC project timeline
 - Reach out to possible new collaborators to further enlarge the consortium and base for design and construction
 - Identify and take advantage of synergies between subsystems
- ☐ Relation to the Working Groups and Collaboration formation
 - very active in detector-1 working groups
 - o activities in the consortium envisioned to always be fully linked with the Detector-1 WGs
 - added value: consortium internal expertise benefits the entire community

Examples of Detector Consortia Action Items

npDIRC
1pDIR0

☐ Continue the transition from R&D towards identify resources and funding resources for the planned tasks towards design and construction

dRICH

- ☐ Clarify the agreements for engineering help with the national labs
- Reach out to possible new collaborators to further enlarge the consortium and base for design and construction. This includes connections overall and specific connections for, e.g., the mirrors
- ☐ Work on the technical specifications document within the EIC project timeline
- ☐ Identify and take advantage of synergies between forward and backward RICH detectors

EEEMCAL

- ☐ Work closely with EIC PM to secure off-project funding
- ☐ Reach out to possible new collaborators to further enlarge the consortium and base for design and construction.
- ☐ Work on the technical specifications within the EIC project timeline
- ☐ Identify and take advantage of synergies between EEEMCAL and other subsystems using homogeneous radiator materials, e.g., far forward/backward detectors

EIC Global Geometry Database

Adapted from 20 May Detector-1 WG Convener meeting

to provide consistency of detector envelopes between:

- Sketchup: Integration and assembly, installation, and maintenance.
- CAD: Detailed engineering information for construction.
- Simulation: Physics and detector studies using detailed GEANT-based detector simulations.
- Analysis: Reconstruction in simulation and physics analysis

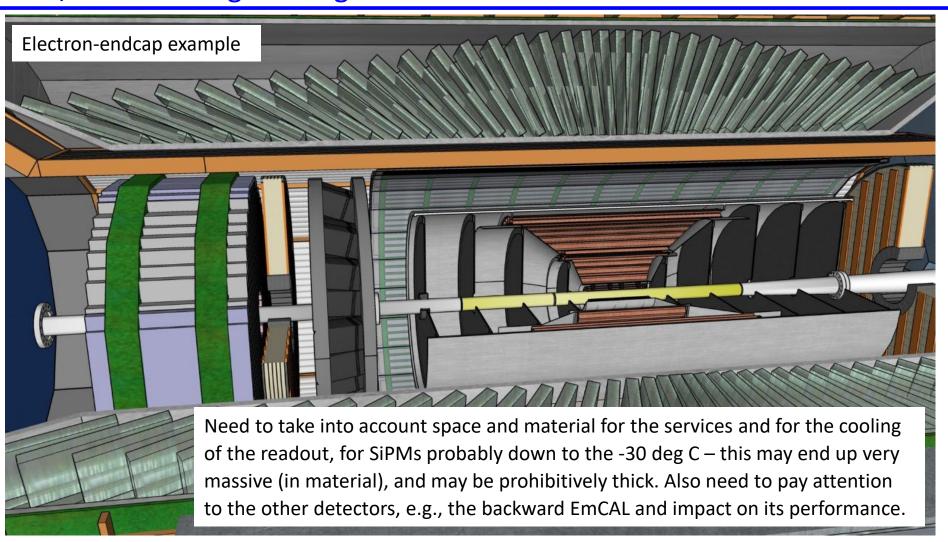
(From discussion with EIC PM on 17 May 2022)

- Gatekeeper: Tanja Horn (for Detecfor-1 contacts; work together with system engineer Walt Akers for global changes and improvements)
 - > Keep some info on changes and why
- Legs of input:
 - Global Detector/Integration Group:
 - Collects all information from working groups
 - Balances detector technology needs versus each other
 - Detector-1 Sim/QA Working Group:
 - Collects all trade-offs of material budget versus science performance
 - Implements version control for simulations
 - ➤ EIC Project Detector Leads:
 - Collect input from E&D process (Space needs for frames and supports, Space needs for service/cooling, Requirements of accelerator and vacuum integration)
 - Fold keep-in volumes into requirements/interface control document

Geometry Database -

https://eic.jlab.org/Geometry/Detector/

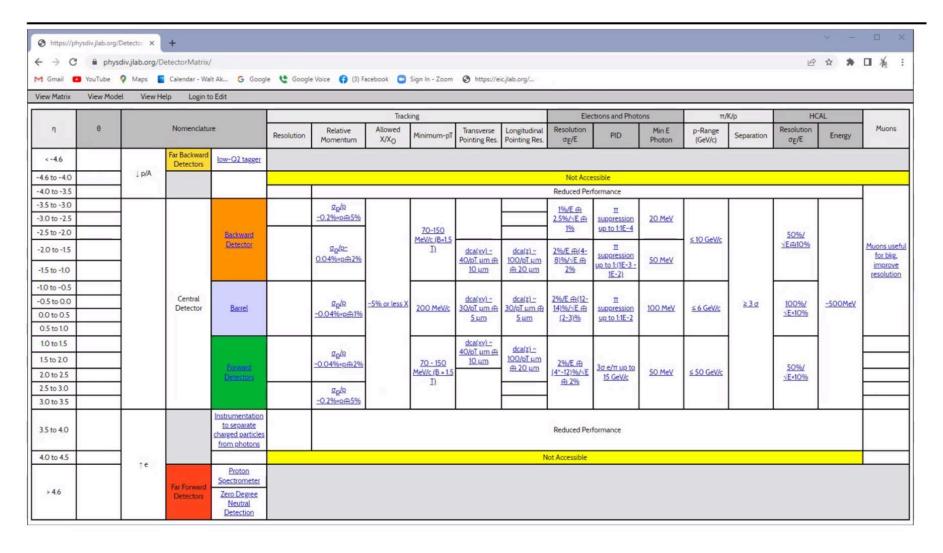
- ☐ The geometry database should capture space and material of detector <u>and</u> service needs.
- Also crucial to take a fully system-integrated approach and detector developers work with electronics/DAQ and engineering teams.



Overview – Geometry Database

- ☐ Roots of the Project
 - The Detector Matrix and the detector conceptual design
- ☐ Current Interface
 - MS Excel based data collection
 - Web-based upload tool
 - Web-based information matrix with integrated version control
- Demonstration
 - Version-controlled matrices of configuration information
 - Embedded links to references and diagrams
 - Dated commentary on changes that have been introduced over time
 - Automatic notification of registered users whenever a change occurs

Roots of the Project



- I The detector matrix was an interactive tool that was originally developed to collect design data during preconceptual design
- The matrix had a fixed structure which could only be altered by a system administrator
- ☐ The tool provided an internal interface what allowed authorized users to make update to its content
- ☐ This tool did not provide any version control
- Once a proto-detector design was selected, a similar solution was developed for tracking design parameters

Current Interface – Input Spreadsheet

EIC DETE	CTOR GEOMET	TRY FRI, 24 JUN 2022 10:25:07										
Region	Compon											
HADRON DIRECTION		6.10.06 171 30 267 328 499 328 33.61 215,210 FeSc, WSc last segment Tower size: 5cm x 5cm x 140cm, 20cm readout Offset measured from face nearest to interaction point Volume: calculated as cylindrical volume minus the volume of the embedded ECAL										
END CAP		☐ The Geometry Matrix is produced from a configuration file that is generated by MS Excel using VB										
	☐ The structure of the matrix is unrestricted and it can have any number of columns or rows											
		lacktriangle Each cell can have a user-defined link that points to references or supporting documents										
		☐ The data in the workbook is organized using Named Ranges that include										
	Solend EMCal O EMCal C EMCal	 Matrix Table: list of matrix names contained in the workbook 										
CENTRAL	Barr EMCal II	 Comment Table: a list of dated comments 										
DETECTOR	DIRC	 Reference Table: contains a table of references with links and descriptive text 										
	Integrated DIR	o Contact Table: contains the list of contacts associated with the matrix										
	Barrel Time	 CSS Table: contains special cascading style sheet info for the web page 										
	HD Time o Silico Modi	 Field Table: contains list of application specific fields 										
	LD Time o	 Notification Table: contains a list of individuals that will be contacted when a matrix changes 										
LEPTON	Service (Gap 10 -320 -320 -330 0.00 Offset: measured from location nearest to interaction point 610.06 20.32 -330 -350 -350 5.18 40,649 Iron Offset: measured from face nearest to interaction point Weight: calculated as 100% iron. Weight: calculated as 100% iron.										

leight: specified in outer radius

Current Interface – Configuration File

- ☐ The output configuration file is generated by running the Write Geometry macro from the Excel Workbook
- ☐ The text based data structure is uploaded to the server and contains all of the details needed for the web page to be generated
- Any embedded scripting commands are removed when the configuration file is produced to prevent script or html injection
- ☐ The script check is repeated on the server side to ensure that no additional scripting, links, or improper material has been added to the text file
- ☐ The server side application validates the configuration file upon receipt and immediately reports any errors that were found
- ☐ Finally, the server side application allows the caller to preview the web page before it is posted

```
Geometry Matrix for Detector
       name=Detector
       date=07/20/2022 09:40:41
      cols=14
       rows=34
       comment=First release of the geometry and master parameter table
       5=CENTRAL<br/>br>DETECTOR
       32=LEPTON<br>DIRECTION<br>ENDCAP
       [col001.class]
      2=R1A
       5=R2A
      31=R0A
       32=R3A
       [col001.rowspans]
      2=2
      10=0
      11=0
      12=0
      13=0
      14=0
      15=0
      16=0
      17=0
      18=0
      19=0
      20=0
length: 19,070 lines: 1,18 Ln: 1 Col: 1 Sel: 0 | 0
                                                              Windows (CR LF)
```

Current Interface – Detector Matrix

ENDCAP

EIC DETECTOR GEOMETRY FRI, 24 JUN 2022 10:25:07 Outer from Physical Physical Weight Length Radius Radius Center Start End Sub-Component WBS (cm) (cm) (cm) (cm) (cm) (m^3) (kg) Technology Region Component (cm) 5.10.06 328 328 33.61 215,210 FeSc, WSc last segment 267 499 Tower size: 5cm x 5cm x 140cm, 20cm readou Offset: measured from face nearest to interaction point Hadron Calorimeter Volume: calculated as cylindrical volume minus the volume of the embedded ECAL HADRON Weight: estimated as 79% iron and 21% plastic DIRECTION END CAP 6.10.05 30 190 328 366 328 4.20 27,165 Tower size: 1cm (1.65cm) x 1cm(1.65cm) x 37.5cm, 5cm readout Electromagnetic Calorimeter The resulting web page contains the complete matrix along Service Gap 320 320 -320 6.10.06 with all comments, references, and contact information **Barrel Hadron Calorimeter** D Section entral Section -150 36.65 D Section -320 Offset: measured from face nearest to interaction poin. 6.10.04 180 280 180 10.29 Aerogel/Gas Offset: measured from face pearest to interaction point Volume: calculated as sum of the sub-sections Weight: based on parametric estimate from CLAS LTCC **Dual RICH** Comments, References and Contact Information The information provided on this page is generated directly from the originating spreadsheet. The data in this section should provide insights into the design choices that have been made over time, along with references to documentation regarding the changes. To request clarification or changes to this information (or to information in the geometry matrix), please reach out to the individuals listed in the Contacts section F Comments Comment Author Date Tanja Horn April 13, 2022 Initial Detector-1 DB posted CENTRAL DETECTOR Tanja Horn Fixed inconsistencies in DIRC frame, hpDIRC and MPGD: Iterated hpDIRC position as balance between phi-coverage and frame engineering strength need; added 2-cm space for May 19, 2022 MPGD tracker (muRWell or MM) on top of DIRC bar boxes --> now 5cm slot for both together; added slots for service needs in frame Walt Ake References lune 20, 2022 Finalizing the design of the detector portion of the EIC Geometry Management System. ☐ References Title Date Description Detector Menagerie A complete collection of Sketchup models that can be used to construct detector systems from parts. Each of the sub-components is independently configurable. Experimental Equipment Sharepoint Repository This is the BNL Sharepoint root directory for Experimental Equipment documents. Key sub-directories are listed in the expanded list below. These links require authenticated access. Contact information Tanja Horn, Walt Akers Primary contact for information that is stored in the Geometry Matrix. Tanja Horn Walt Akers akers@ilab.org Technical contact for online data, features and accessibility. Service Gap -320 -320 -330 0.00 Offset: measured from location nearest to interaction point 20.32 -330 -330 -350.32 40,649 Offset: measured from face pearest to interaction point Weight: calculated as 100% iron. LEPTON DIRECTION Backward Field Return turn Cylinde -350.3

Height: specified in outer radius

EIC DETECTOR GEOMETRY





EIC DETECTOR GEOMETRY INTERACTION POINT 6

An overview page is also generated that shows all the iterations of the matrix on a single page, along with their release comments



Detector Geometry Matrices - IP 6

The following is a date-oriented table of matrices that contain the configuration parameters for the EIC detector at interaction point 6. The current matrix provides a description of the volumetric envelope for all of the sub-detectors, a description of their technology, their estimated weights, and additional configuration notes. Requests for revisions or updates to these matrices should be sent to Tanja Horn.

Name	Author	Date	Description
Detector-20220624102507	Tanja Horn	06/24/2022 10:25:07	Fixed inconsistencies in DIRC frame, hpDIRC and MPGD: Iterated hpDIRC position as balance between phi-coverage and frame engineering strength need; added 2-cm space for MPGD tracker (muRWell or MM) on top of DIRC bar boxes> now 5cm slot for both together; added slots for service needs in frame.
Detector-20220623172941	Tanja Horn	06/23/2022 17:29:41	Initial Detector-1 database posted in the EIC geometry management system.

Region	Component	Sub-Component	WBS	Length (cm)	Inner Radius (cm)	Outer Radius (cm)	Offset from Center (cm)	Physical Start (cm)	Physical End (cm)	Volume (m ³)	Weight (kg)	Technology	Notes
HADRON DIRECTION	Hadron Calorimeter		6.10.06	171	30	267	328	499	328	33.61	215,210	FeSc, WSc last segment	Tower size: 5cm x 5cm x 140cm, 20cm readout Offset: measured from face nearest to interaction point Volume: calculated as cylindrical volume minus the volume of the embedded ECAL Weight: estimated as 79% iron and 21% plastic
END CAP	Electromagnetic Calorimeter		6.10.05	38	30	190	328	366	328	4.20	27,165	Pb/Sc	Tower size: 1cm (1.65cm) x 1cm(1.65cm) x 37.5cm, 5cm readout Offset: measured from face nearest to interaction point Weight: estimated as 85% lead glass and 15% steel
	Service Gap			8			320	328	320				
			6.10.06	640		267	0	320	-320	72.60	464,834		Embedded links to references and diagra
	Barrel Hadron Calorimeter	HD Section		170	194	267	150	320	150	17.97			Offset: measured from face nearest to interaction point
		Central Section		300	180	267	0	150	-150	36.65			Offset: measured from center of detector
		LD Section		90 64 4 700 74 1 4 1 10 7	nerwornsen							Flange of th	t measured from face nearest to interaction point
	Dual RICH			l structi ooling	ure &							beam pipe	
	Dual RICH	Detector Section				-							t measured from face nearest to interaction point
		Aerogel Section				1110	1000 conc		*******			/	t measured from face nearest to interaction point
	Solenoid Magnet					1111							nt: based on parametric estimate from CLEO II
	EMCal Outer Support					1111							nt: calculated as 20% of total volume as steel (balance is air)
	EMCal Outer Surface		,	C-1-1		111							nt: calculated as 100% Aluminum
	EMCal Electronics		,	Cables nt. calculated as 25% silicon (balance is air)							nt: calculated as 25% silicon (balance is air)		
	Barrel EMCal			_		mi.							nt: based on parametric estimate from CMS EMCal
	EMCal Inner Surface					-	11111						nt: calculated as 100% Aluminum
CENTRAL DETECTOR	DIRC Support	Bar Support				1	Time.				K		t: measured from point where DIRC bar connects to the readout ne: calculated as sum of sub-sections nt: estimated as 5% of total volume as steel (balance is air & detector)
		Readout Support	ŀ	oeam pi	pe /		111111	Access					out support is triangular frame, therefore volume is halved. tor is totally enclosed by DIRC Support.
		MPGD Tracker											tt claculated as sum of sub-components it based on parametric estimate from SBS Gem
	Integrated DIRC/MPGD Detector	DIRC Bar Box	Interr	nal struc			414						nt. calculated as 30% quartz (balance is air & support system)
		DIRC Readout		cooling	3								out is triangular, therefore volume is halved. it: Calculated as 30% silicon(balance is air & support system)
	Barrel Time of Flight/Tracker					100							nt: based on parametric estimate from SBS Gem
	HD Time of Flight/Tracker		read-c	out boar	rds								t measured from face nearest to interaction point t: based on parametric estimate from SBS Gem
	Silicon Tracker		read c	ead-out boards									nt: calculated as 3% aluminum and 3% silicon (balance is air)
	Modular RICH		in	PbW ternal s	O ₄ crys	tal & / structur	e n	IDC sup	nort fr	2000		1	t: measured from face nearest to interaction point t: based on parametric estimate from CLAS LTCC
	LD Time of Flight/Tracker				3307			IRC sup	5.2		DIRC b		t measured from face nearest to interaction point nt: based on parametric estimate from SBS Gem
	LD EMCal		6.10.05	60	9	63	-175	-175	-235	0.73	4,738	PbWO4	Offset: measured from face nearest to interaction point Weight: estimated as 85% lead glass and 15% steel
	Service Gap			10			-320	-320	-330	0.00			Offset: measured from location nearest to interaction point
LEPTON			6.10.06	20.32			-330	-330		5.18	40,649	Iron	Offset: measured from face nearest to interaction point Weight: calculated as 100% iron.
DIRECTION	Backward Field Return	Return Cylinder		20.32	20	270	-330	-330	-350.32	4.63			
ENDCAP		Support Panel		7.62	454	664	-336.35	-336.35	-343.97	0.55			Height: specified in outer radius

Ongoing Work

- ☐ Continued Integration of Data
 - Populated initial versions of the Detector Matrix and the Far Forward and Far Backward Interaction Region
 - Plan to add tables containing system parameters and other critical information that will be required by scientists and engineers
- ☐ Requirements and Interface Documents
 - May use this platform to make requirements documents and interfaces available to users. This will allow them to see a documented trail of how the design develops over time, along with descriptive text that tellw why decisions were made