

Xopt: Flexible Black Box Optimization of Simulations and Experiments

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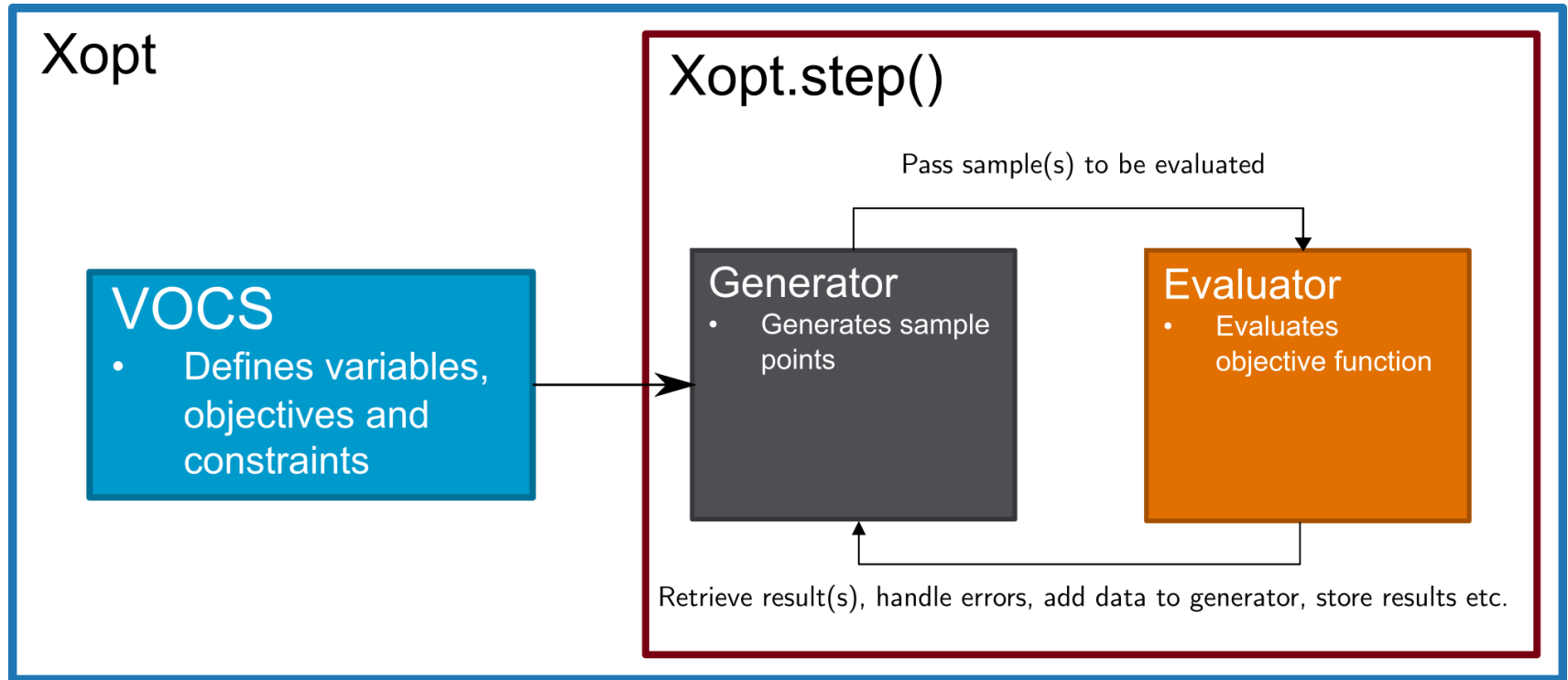


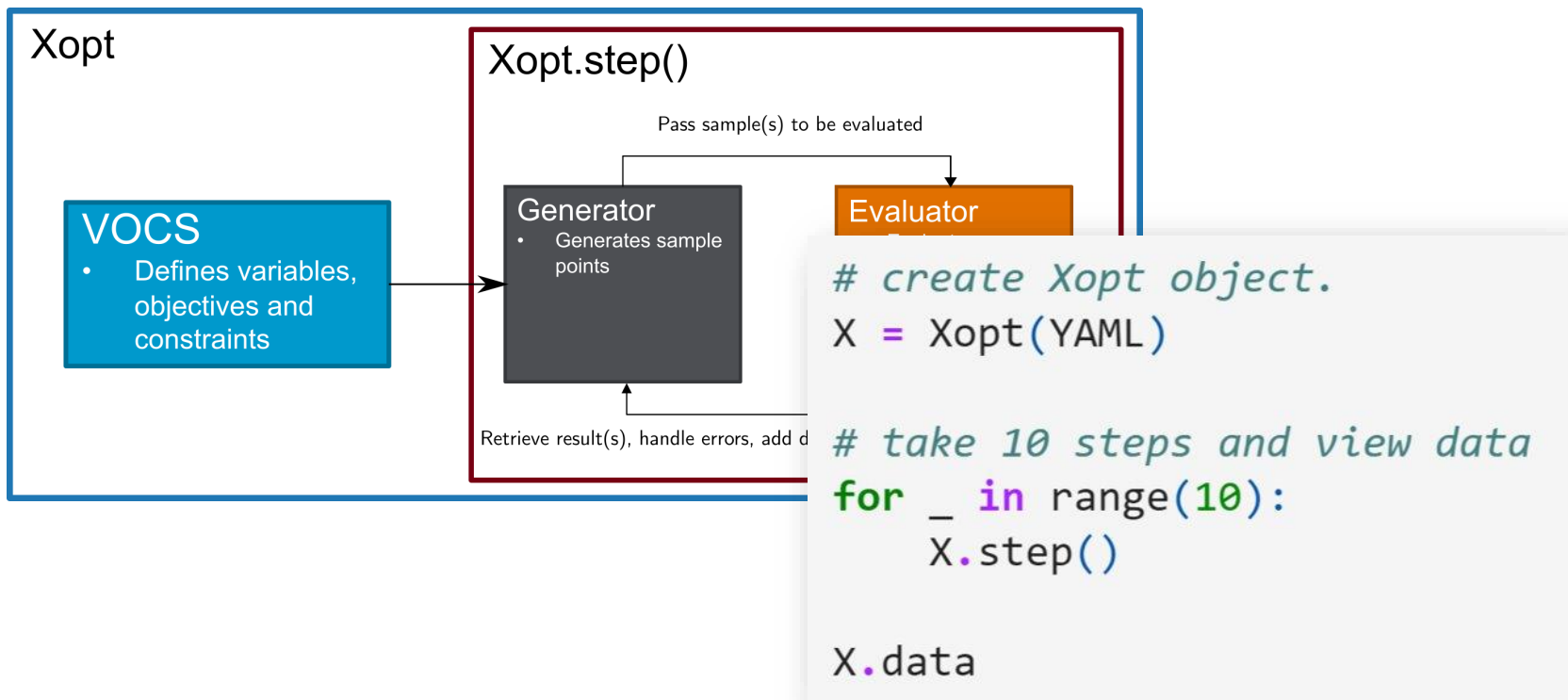
NATIONAL
ACCELERATOR
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What is Xopt?

- Flexible **framework** for optimization of arbitrary problems using python
- **Independent** of problem type (simulation or experiment)
- **Independent** of optimization algorithm + easy to incorporate custom algorithms
- **Easy to use** text interface and/or advanced customized use for professionals







Via YAML file (validated by pydantic):

```
xopt:
  max_evaluations: 6400

generator:
  name: cnsiga
  population_size: 64
  population_file: test.csv
  output_path: .

evaluator:
  function: xopt.resources.test_functions.tnk.evaluate_TNK
  function_kwargs:
    raise_probability: 0.1

vocs:
  variables:
    x1: [0, 3.14159]
    x2: [0, 3.14159]
  objectives: {y1: MINIMIZE, y2: MINIMIZE}
  constraints:
    c1: [GREATER_THAN, 0]
    c2: [LESS_THAN, 0.5]
  linked_variables: {x9: x1}
  constants: {a: dummy_constant}
```

Via python code:

```
evaluator = Evaluator(...)
generator = CNSGAGenerator(...)
vocs = MyVOCS(...)
```

```
X = Xopt(
    evaluator=evaluator,
    generator=generator,
    vocs=VOCS
)
```

Evaluator specification

- Python function must accept/return dicts
- Input dict must have **at least** the keys specified in vocs variables/constants (see next slide)
 - You can include extra keyword args if needed!
- Output dict must have **at least** the keys specified in objectives/constraints (see next slide)
 - The function can output extra keys to be tracked!
- Evaluators inherit directly from python concurrent.futures so you can use this for parallel evaluation (see /xopt/docs/examples/basic/xopt_parallel)

```
xopt:
  max_evaluations: 6400

generator:
  name: gen500
  pop: 500
  pop_size: 500
  output_path: .

evaluator:
  function: xopt.resources.test_functions.tnk.evaluate_TNK
  function_kwargs:
    raise_probability: 0.1

vocs:
  variables:
    x1: [0, 3.14159]
    x2: [0, 3.14159]
  objectives: {y1: MINIMIZE, y2: MINIMIZE}
  constraints:
    c1: [GREATER_THAN, 0]
    c2: [LESS_THAN, 0.5]
  linked_variables: {x9: x1}
  constants: {a: dummy_constant}
```

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```
evaluate(inputs: dict) -> dict
```

```
from epics import caget, caput, cainfo
import time

outputs = ["XRMS", "YRMS"]
def make_epics_measurement(input_dict):
    # set inputs
    for name, val in input_dict.items():
        caput(name, val)

    # wait for inputs to settle
    time.sleep(1)

    # get output values, current time
    output_dict = caget_many(outputs)
    output_dict["time"] = time.time()

    # compute geometric avg of beamsizes
    output_dict["RMS"] = (
        output_dict["XRMS"]*\
        output_dict["YRMS"]
    )**0.5

    return output_dict
```

- Variables: input domain limits and names
- Objectives: objective names and goals (minimize/maximize)
- Constraints: constraint names and conditions (greater than/less than)
- Constants: constant values

```
xopt:  
  max_evaluations: 6400  
  
generator:  
  name: cnsqa  
  population_size: 64  
  population_file: test.csv  
  output_path: .  
  
evaluator:  
  function: xopt.resources.test_functions.tnk.evaluate_TNK  
  function_kwargs:  
    raise_probability: 0.1
```

```
vocs:  
  variables:  
    x1: [0, 3.14159]  
    x2: [0, 3.14159]  
  objectives: {y1: MINIMIZE, y2: MINIMIZE}  
  constraints:  
    c1: [GREATER_THAN, 0]  
    c2: [LESS_THAN, 0.5]  
  linked_variables: {x9: x1}  
  constants: {a: dummy_constant}
```


Generator specification

- Use built-in generators by name

- optimization algorithms:
 - `cmsga` Continuous NSGA-II with constraints.
 - `bayesian_optimization` Single objective Bayesian optimization (w/ or w/o constraints, serial or parallel).
 - `mobo` Multi-objective Bayesian optimization (w/ or w/o constraints, serial or parallel).
 - `bayesian_exploration` Bayesian exploration.
- sampling algorithms:
 - `random_sampler`

- Each generator has its own specific options

- Locate the default options in the docs or via

```
from xopt.utils import get_generator_and_defaults
gen, options = get_generator_and_defaults("upper_confidence_bound")
print(yaml.dump(options.dict()))
```

```
acq:
  beta: 2.0
  monte_carlo_samples: 512
  proximal_lengthscales: null
model:
  use_conservative_prior_lengthscales: false
  use_conservative_prior_mean: false
  use_low_noise_prior: false
n_initial: 3
optim:
  num_restarts: 5
  raw_samples: 20
  sequential: true
```

```
xopt:
  max_evaluations: 6400

generator:
  name: cmsga
  population_size: 64
  population_file: test.csv
  output_path: .

evaluator:
  function: xopt.resources.test_functions.tnk.evaluate_TNK
  function_kwargs:
    raise_probability: 0.1

vocs:
  variables:
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  constants: {a: dummy_constant}
```

- Data is stored by xopt in the `data` attribute
- Set `dump_file` in xopt options to dump data and xopt config to yaml file after every evaluation step
- Dump file can be used to restart xopt

```
# view the data
X.data
```

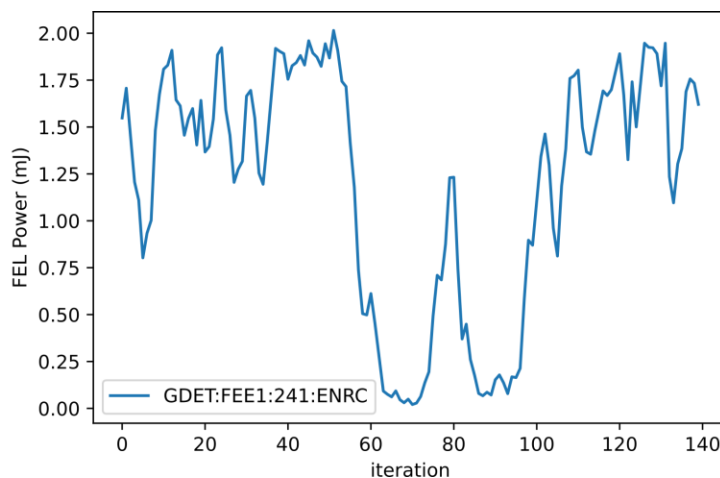
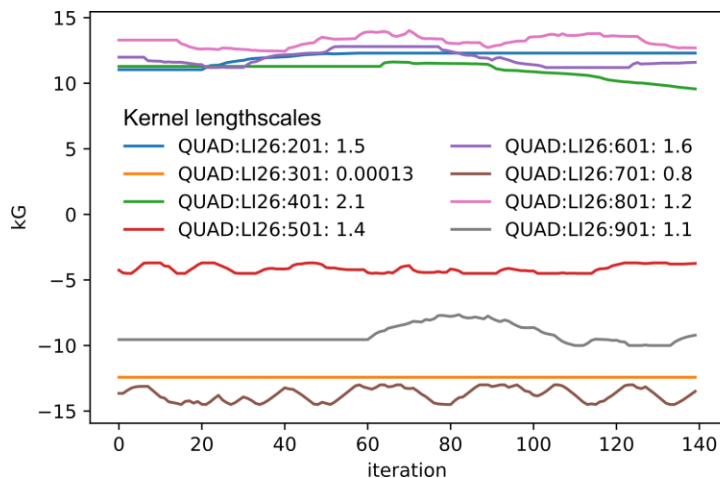
	x1	x2	y1	y2	c1	c2	some_array	xopt_error	xopt_error_str	a
1	1.000000	0.750000	1.000000	0.750000	0.626888	0.312500	[1, 2, 3]	False		NaN
2	0.750000	1.000000	0.750000	1.000000	0.626888	0.312500	[1, 2, 3]	False		NaN
3	0.796389	0.807321	0.796389	0.807321	0.186596	0.182292	[1, 2, 3]	False		dummy_constant
4	0.871085	0.943368	0.871085	0.943368	0.568348	0.334279	[1, 2, 3]	False		dummy_constant
5	1.067732	0.797750	1.067732	0.797750	0.843056	0.410974	[1, 2, 3]	False		dummy_constant
6	0.995019	0.879029	0.995019	0.879029	0.707805	0.388707	[1, 2, 3]	False		dummy_constant
7	0.803822	1.022336	0.803822	1.022336	0.724145	0.365142	[1, 2, 3]	False		dummy_constant
8	0.656282	0.952071	0.656282	0.952071	0.434474	0.228792	[1, 2, 3]	False		dummy_constant
9	0.566763	0.935263	0.566763	0.935263	0.271920	0.193911	[1, 2, 3]	False		dummy_constant
10	0.547152	1.008562	0.547152	1.008562	0.326474	0.260859	[1, 2, 3]	False		dummy_constant
11	0.617813	1.081140	0.617813	1.081140	0.594283	0.351603	[1, 2, 3]	False		dummy_constant
12	0.491363	1.027666	0.491363	1.027666	0.231751	0.278506	[1, 2, 3]	False		dummy_constant

```
xopt:
  dump_file: dump.yaml
```

```
In 3 1 config = yaml.safe_load(open("dump.yaml"))
      2 X2 = Xopt(config)
      3 print(X2.options)
      4 print(X2.generator)
      5 print(X2.evaluator)
```

Example Application: LCLS FEL Power Characterization

- **Proximal biasing** to reduce exploration step size and **constraints** to prevent charge loss.
- **Custom evaluate function** captures 80th percentile FEL power over 100 shots.
- Data stored in Pandas DataFrame objects, exported to text file with Xopt configuration
- FEL sensitivity is captured in the GP model lengthscales inside the generator object.
- Entirely executed from an **interactive Jupyter notebook**.



Badger: Missing Optimizer in the Accelerator Control Room

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What is Badger?

- **Optimization interface** between users and machine, the spiritual successor to Ocelot-optimizer, powered by Xopt
- **Easy to use** one click/cmd to re-run an optimization task
- **Fast to extend** plugin-based, create your own custom environment in minutes
- **Multiple modes** use Badger as a python library, a command line tool, or a GUI application

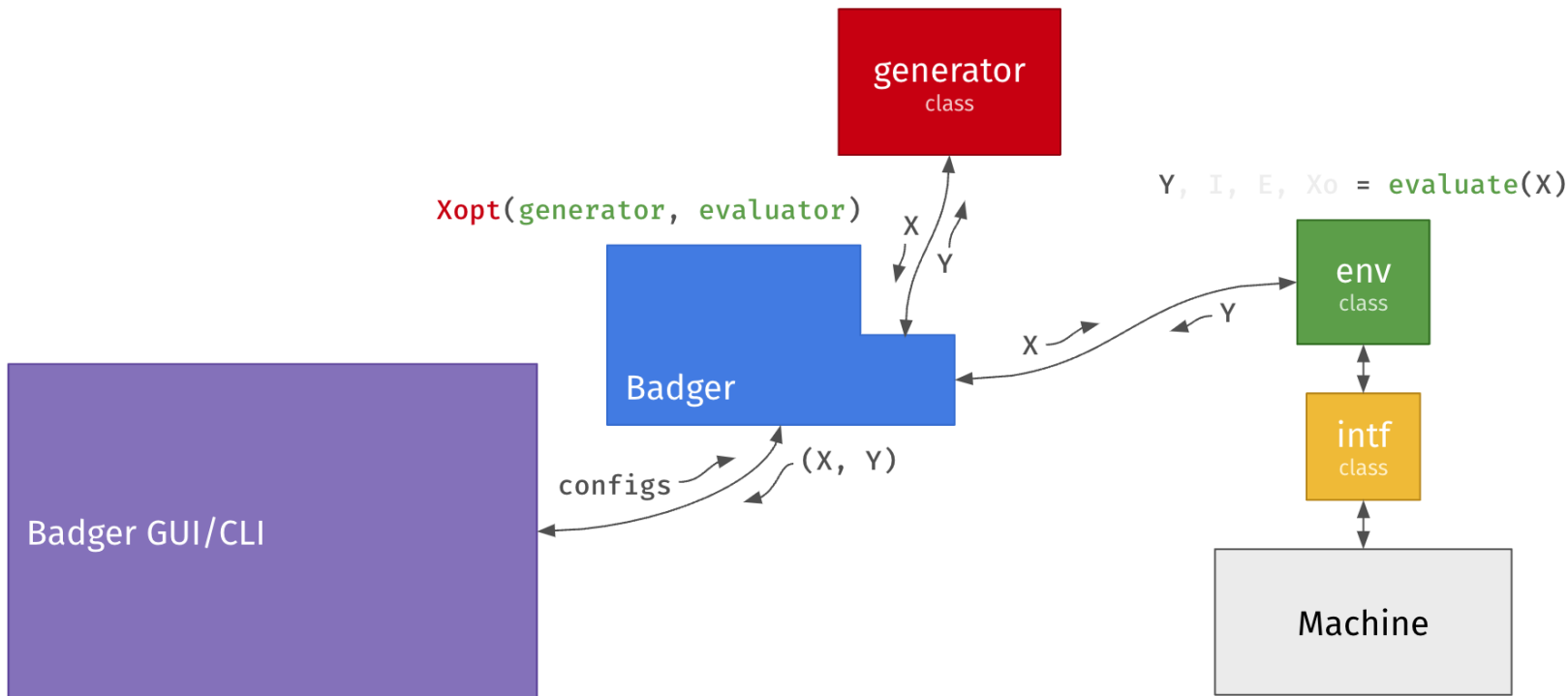


What can Badger do?

- **General features**
 - Control the optimization flow (pause/resume/terminate)
 - Monitor/browse the runs
 - Archive/explore the data
- **Accelerator control room (ACR) oriented features**
 - Send run summary to the logbook
 - Jump/set to optimal solution
 - Recover machine state after run
 - Support soft/hard constraints & tracked states
 - Preserve all raw data
 - *Continue/rollback a run (planned)

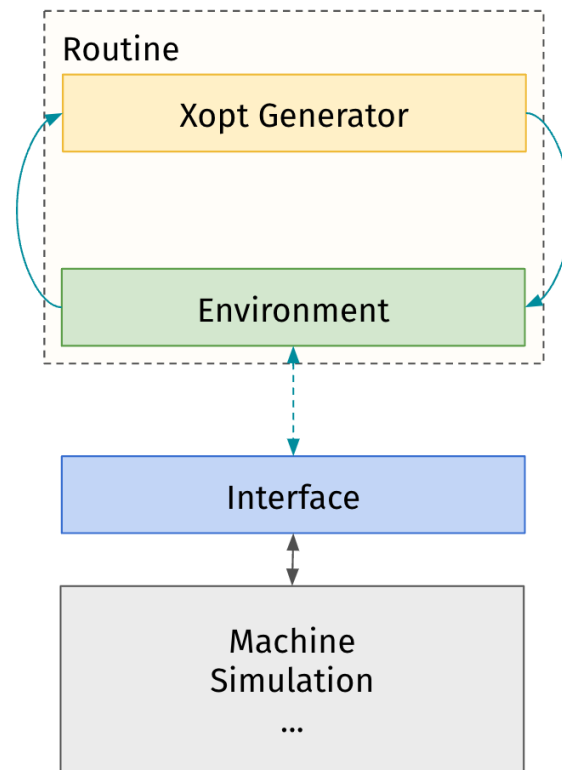


Badger architecture



Badger architecture

- **Generator** algorithms provided by Xopt
- **Environment** defines the observations and the variables
- **Interface** layer between the environment and the machine, all data in a run would flow through the interface
- **Routine** contains complete information about one optimization task



GUI mode (browse/run a routine)

Search bar

Routine filters

Routine list

The screenshot shows the Badger v0.9.1 interface. On the left, there is a search bar and filter section with dropdowns for Objective, Region, and Gain. Below these is a list of routines, including 'simplex-vanilla-test', 'satisfied-silkworm', 'intf-log-re', 'tags-3', 'tags-2', 'tags-1', 'simplex-sara-random-exact', 'intf-log', 'simplex-acr-low-gain-exact', 'simplex-sara-no-adaptive-exact', 'simplex-vanilla-exact', 'simplex-acr-high-gain-exact', 'simplex-acr-exact', and 'simplex-sara-exact'. The main panel displays the 'Run Monitor' for 'BadgerOpt-2022-09-23-112646.yaml'. It features two plots: 'Evaluation History (Y)' showing 'norm_emit' vs 'Iterations' and 'Evaluation History (X)' showing 'variables' vs 'Iterations'. Below the plots is a control bar with buttons for 'Delete Run', 'Logbook', 'Optimal', 'Reset', 'Set', 'Pause', and 'Run'. At the bottom is a data browser table.

	norm_emit	SOL1:solenoid_field_scale	CQ01:b1_gradient	SQ01:b1_gradient
0	0.560924	0.478	-0.0015	-0.0007
1	0.562774	0.4789	-0.0015	-0.0007
2	0.55958	0.478	-0.000575	-0.0007
3	0.559716	0.478	-0.0015	0.000265
4	0.561253	0.4771	-0.000883333	-5.66667e-05

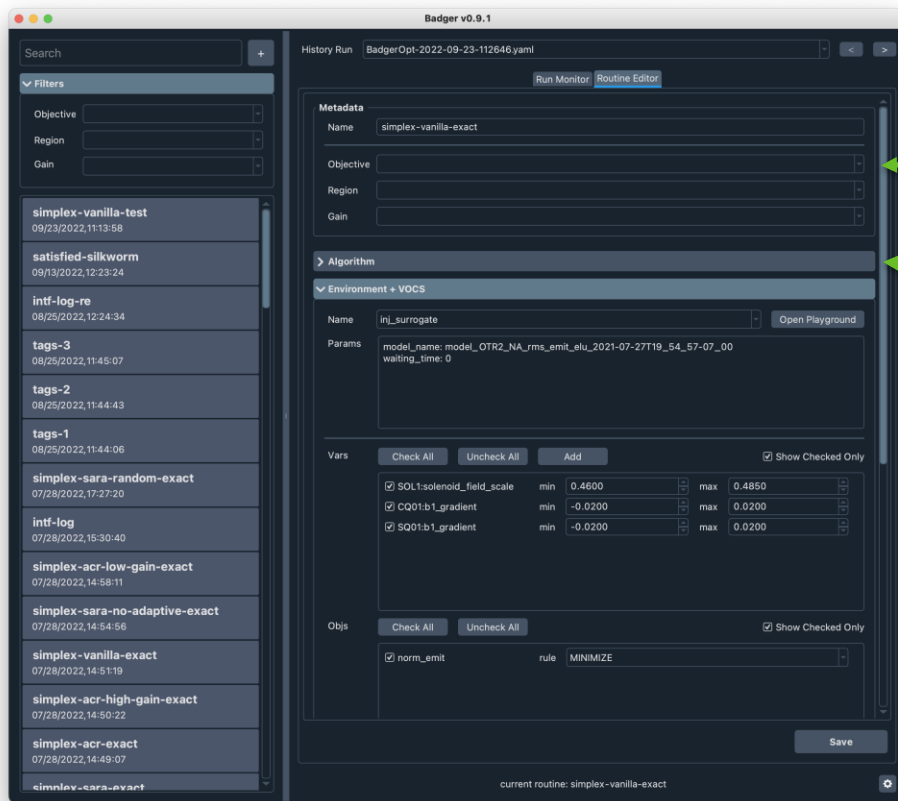
Historical run navigator

Run monitor

Control bar

Data browser

GUI mode (create/edit/view a routine)



Routine configs

Algorithm configs

Environment/VOCS configs

CLI mode

- `badger` to get general information
- `badger algo/env/intf` to list all the algorithms/environments/interfaces
- `badger algo/env/intf NAME` to investigate a specific plugin
- `badger routine` to list all saved routines
- `badger routine NAME` to review the routine
- `badger routine NAME -r` to run the routine
- `badger run` to create and run a routine
- `badger install env/intf` to list/install the environment/interface plugins

```
fish /  
~ - badger routine intf-log -r  
Please review the routine to be run:  
  
=== Optimization Routine ===  
name: intf-log  
algo: silly  
env: silly  
algo_params:  
  start_from_current: true  
  max_iter: 42  
env_params: null  
config:  
  variables:  
    - q1: 0.0 -> 1.0  
    - q2: 0.0 -> 1.0  
    - q3: 0.0 -> 1.0  
    - q4: 0.0 -> 1.0  
  objectives:  
    - l2: MINIMIZE  
  constraints: null  
  states: null  
  domain_scaling: null  
  
Proceed ([y]/n)?  
-----  
| iter | l2 | q1 | q2 | q3 | q4 |  
-----  
| 1 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 |  
| 2 | 1.372 | 0.8838 | 0.6329 | 0.07155 | 0.8343 |  
| 3 | 0.864 | 0.2203 | 0.7632 | 0.07581 | 0.3312 |  
| 4 | 1.384 | 0.06517 | 0.4959 | 0.9432 | 0.8809 |  
| 5 | 1.043 | 0.1173 | 0.2418 | 0.6492 | 0.7702 |  
| 6 | 1.172 | 0.05347 | 0.6336 | 0.9677 | 0.182 |  
| 7 | 1.606 | 0.9123 | 0.7953 | 0.6401 | 0.839 |  
| 8 | 0.6882 | 0.3282 | 0.2254 | 0.05388 | 0.5587 |  
| 9 | 0.5209 | 0.128 | 0.04482 | 0.4601 | 0.203 |  
| 10 | 1.385 | 0.7387 | 0.9853 | 0.006447 | 0.4321 |  
| 11 | 1.378 | 0.5078 | 0.2893 | 0.7706 | 0.9816 |  
| 12 | 1.206 | 0.1058 | 0.5512 | 0.8809 | 0.6024 |  
| 13 | 1.272 | 0.8485 | 0.1888 | 0.2865 | 0.8837 |  
| 14 | 1.287 | 0.8688 | 0.8435 | 0.3678 | 0.2327 |  
| 15 | 1.579 | 0.7412 | 0.5197 | 0.8937 | 0.9358 |  
| 16 | 1.295 | 0.6825 | 0.1887 | 0.5444 | 0.9381 |  
| 17 | 1.318 | 0.6172 | 0.1534 | 0.7868 | 0.8455 |  
| 18 | 0.42 | 0.3756 | 0.04849 | 0.1375 | 0.1187 |  
| 19 | 1.467 | 0.3577 | 0.2782 | 0.9826 | 0.9911 |  
| 20 | 1.461 | 0.8778 | 0.6194 | 0.9771 | 0.1608 |  
| 21 | 0.7706 | 0.6571 | 0.01575 | 0.06577 | 0.3969 |  
| 22 | 0.7706 | 0.2097 | 0.2199 | 0.6972 | 0.1239 |  
-----  
^C Optimization paused. Press Enter to resume or Ctrl/Cmd + C to terminate: ^C
```

- Use **get_algo** to get an algorithm
- Unified user interface/consistent user experience
- No need to deal with algorithm setup
- Use **get_env** to load an environment
- Set variables to the environment and get observations from it
- Embed the env in the workflow
- No need to setup the simulation/experiment configs again and again

```
↳ [1]: from badger.factory import get_env, get_algo

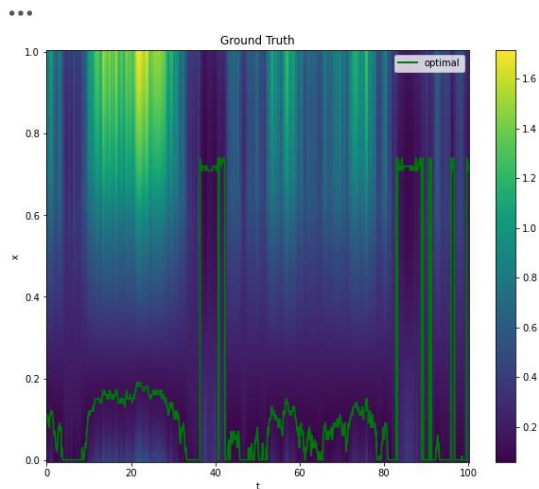
Environment, configs = get_env('inj_surrogate')
env = Environment(configs['params'], None)
env.load_model()

def target(x, t):
    # x is normalized

    _X = denorm(torch.hstack((drift(t), mapping_x(x))))
    ref_point = torch.from_numpy(env.ref_point[0]).to(dtype)
    X_in = ref_point.repeat(len(t), 1)
    indices = [env.model.loc_in[var] for var in list_vars]
    X_in[:, indices] = _X
    Y_out = torch.from_numpy(env.model.pred_machine_units(X_in))

    y_1 = Y_out[:, env.model.loc_out['sigma_x']] * 1e3
    y_2 = Y_out[:, env.model.loc_out['sigma_y']] * 1e3
    y = y_1

    return y.reshape(-1, 1)
```



Create a custom environment

- Think about a list of **variables/observations** that could be involved in your optimization problem
 - **Variables** are the tuning knobs
 - **Observations** are the measurements – including objectives, constraints, or system states to be tracked
- Inherit the base **Environment** class and implements:
 - **name** name of the environment
 - **list_vars** return a list of all the variables
 - **list_obses** return a list of all the observations
 - **_get_var** get the current value of the variable
 - **_set_var** set the variable to the given value
 - **_get_obs** get the current value of the observation

```
class Environment(ABC):  
  
    @property  
    @abstractmethod  
    def name(self) -> str:  
        pass  
  
    @abstractmethod  
    def __init__(self, interface: Interface, params=None):  
        self.interface = interface  
        self.params = merge_params(self.get_default_params(), params)  
  
    # List all available variables  
    @staticmethod  
    @abstractmethod  
    def list_vars() -> List[str]:  
        pass  
  
    # List all available observations  
    @staticmethod  
    @abstractmethod  
    def list_obses() -> List[str]:  
        pass  
  
    # Get the default params of the environment  
    @staticmethod  
    def get_default_params() -> dict:  
        return None  
  
    # Get current variable  
    # Unsafe version (var won't be checked beforehand)  
    @abstractmethod  
    def _get_var(self, var: str):  
        pass  
  
    # Set variable  
    # Unsafe version  
    @abstractmethod  
    def _set_var(self, var: str, x):  
        pass
```

```
pip install badger-opt  
or  
conda install badger-opt  
then  
badger -ga
```

for more information, please check out
<https://slac-ml.github.io/Badger/docs/getting-started/installation>

Run and save an optimization

Create a yaml file under your `pwd` (where you would run an optimization with Badger) with the following content:

```
config.yaml

variables:
- x2
objectives:
- c1
```

To run and save an optimization, run:

```
badger run -a silly -e TNK -c config.yaml -s helloworld
```

Badger will ask you to review the optimization routine:

```
output

Please review the routine to be run:

=== Optimization Routine ===
name: mottled-sloth
algo: silly
env: TNK
algo_params:
  dimension: 1
  max_iter: 42
env_params: null
config:
  variables:
    - x2: 0 -> 3.14159
  objectives:
    - c1: MINIMIZE
  constraints: null

Proceed (y|n)?
```

Hit return to confirm. Badger will print out a table of all the evaluated solutions along the run:

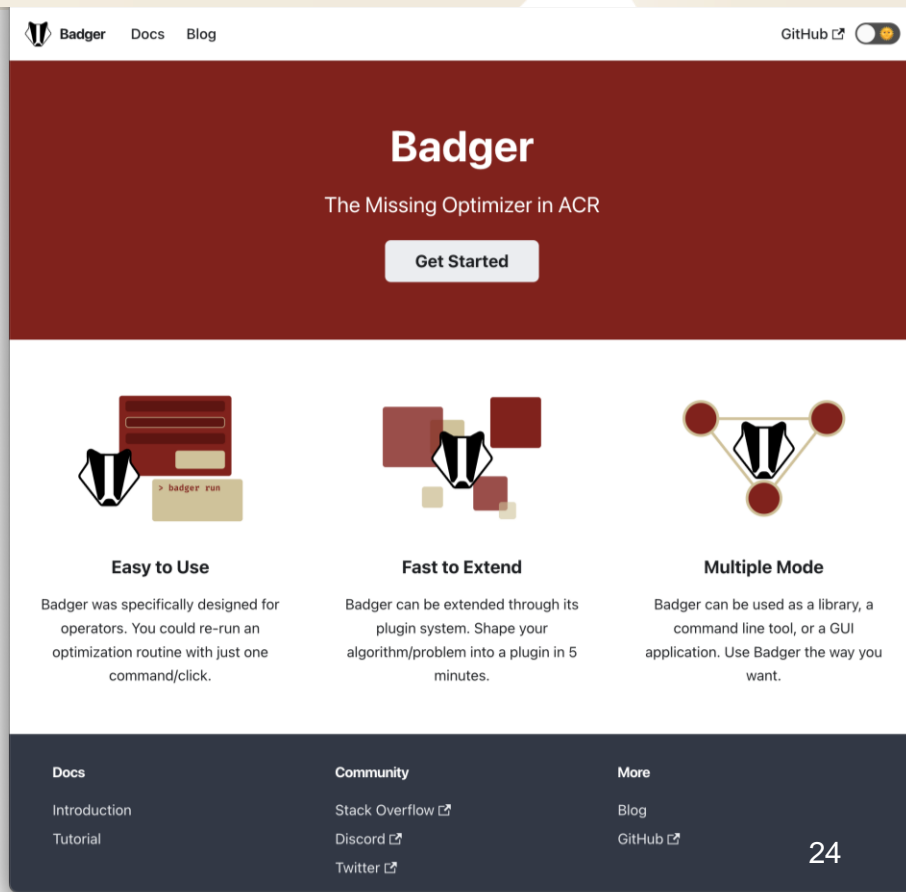
```
output

| iter | c1 | x2 |
|-----|---|---|
| 1 | -1.094 | 0.07432 |
| 2 | 3.563 | 2.159 |
| 3 | 8.749 | 3.138 |
| 4 | 5.351 | 2.54 |
| 5 | 8.17 | 3.045 |
| 6 | 6.536 | 2.763 |
| 7 | 3.007 | 2.0 |
| 8 | -1.089 | 0.1 |
| 9 | 4.127 | 2.2 |
| 10 | 3.519 | 2.1 |
| 11 | 6.647 | 2.7 |
| 12 | 1.074 | 1.4 |
| 13 | -0.8621 | 0.4 |
| 14 | 3.821 | 2.2 |
| 15 | -0.9228 | 0.4 |
| 16 | 6.205 | 2.7 |
| 17 | -1.1 | 0.0 |
| 18 | 8.224 | 3.0 |
| 19 | 7.584 | 2.9 |
| 20 | -0.8961 | 0.4 |
| 21 | -1.093 | 0.0 |
| 22 | 1.293 | 1.5 |
| 23 | 2.593 | 1.9 |
| 24 | 5.563 | 2.5 |
| 25 | 2.046 | 1.7 |
| 26 | 2.501 | 1.8 |
| 27 | -0.8853 | 0.4 |
| 28 | -0.5459 | 0.7444 |
```

for more information, please check out
<https://slac-ml.github.io/Badger/docs/getting-started/tutorial>

Badger resources

- **Badger homepage**
<https://slac-ml.github.io/Badger/>
- **Badger core**
<https://github.com/SLAC-ML/Badger>
- **Badger plugins**
<https://github.com/SLAC-ML/Badger-Plugins>
- **Badger hands-on**
<https://github.com/SLAC-ML/Badger-Handson>
- **Badger on PyPI**
<https://pypi.org/project/badger-opt/>
- **Badger on conda**
<https://anaconda.org/conda-forge/badger-opt>
- **Badger on Slack**
[#badger](#)
[#badger-handsome](#)



The screenshot shows the Badger website homepage. At the top, there is a navigation bar with the Badger logo, 'Docs', and 'Blog' links, and a GitHub link with a toggle switch. The main header features the title 'Badger' and the subtitle 'The Missing Optimizer in ACR', with a 'Get Started' button. Below this, three columns highlight key features: 'Easy to Use' (with a terminal icon), 'Fast to Extend' (with a plugin icon), and 'Multiple Mode' (with a network icon). A footer contains links for 'Docs', 'Community', and 'More'.

Badger Docs Blog GitHub

Badger

The Missing Optimizer in ACR

Get Started

Easy to Use

Badger was specifically designed for operators. You could re-run an optimization routine with just one command/click.

Fast to Extend

Badger can be extended through its plugin system. Shape your algorithm/problem into a plugin in 5 minutes.

Multiple Mode

Badger can be used as a library, a command line tool, or a GUI application. Use Badger the way you want.

Docs Introduction Tutorial

Community Stack Overflow Discord Twitter

More Blog GitHub