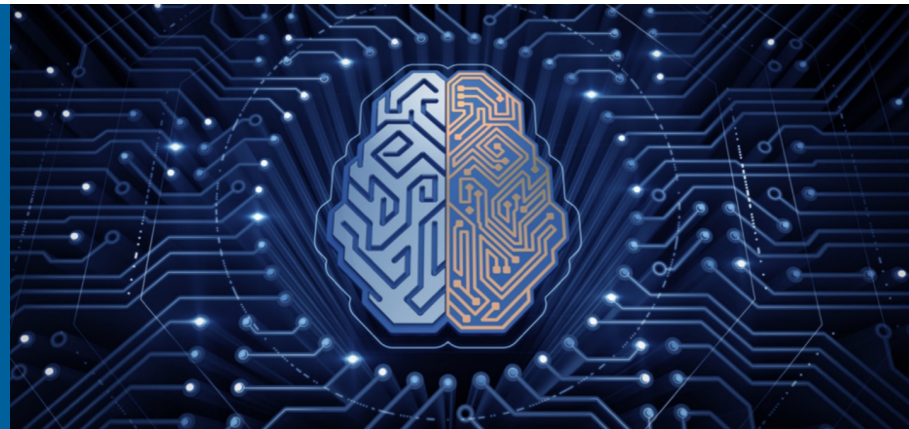


3RD ICFA BEAM DYNAMICS MINI-WORKSHOP ON  
MACHINE LEARNING APPLICATIONS FOR PARTICLE ACCELERATORS

# MACHINE LEARNING TOOLS TO SUPPORT THE ATLAS ION LINAC OPERATIONS AT ARGONNE



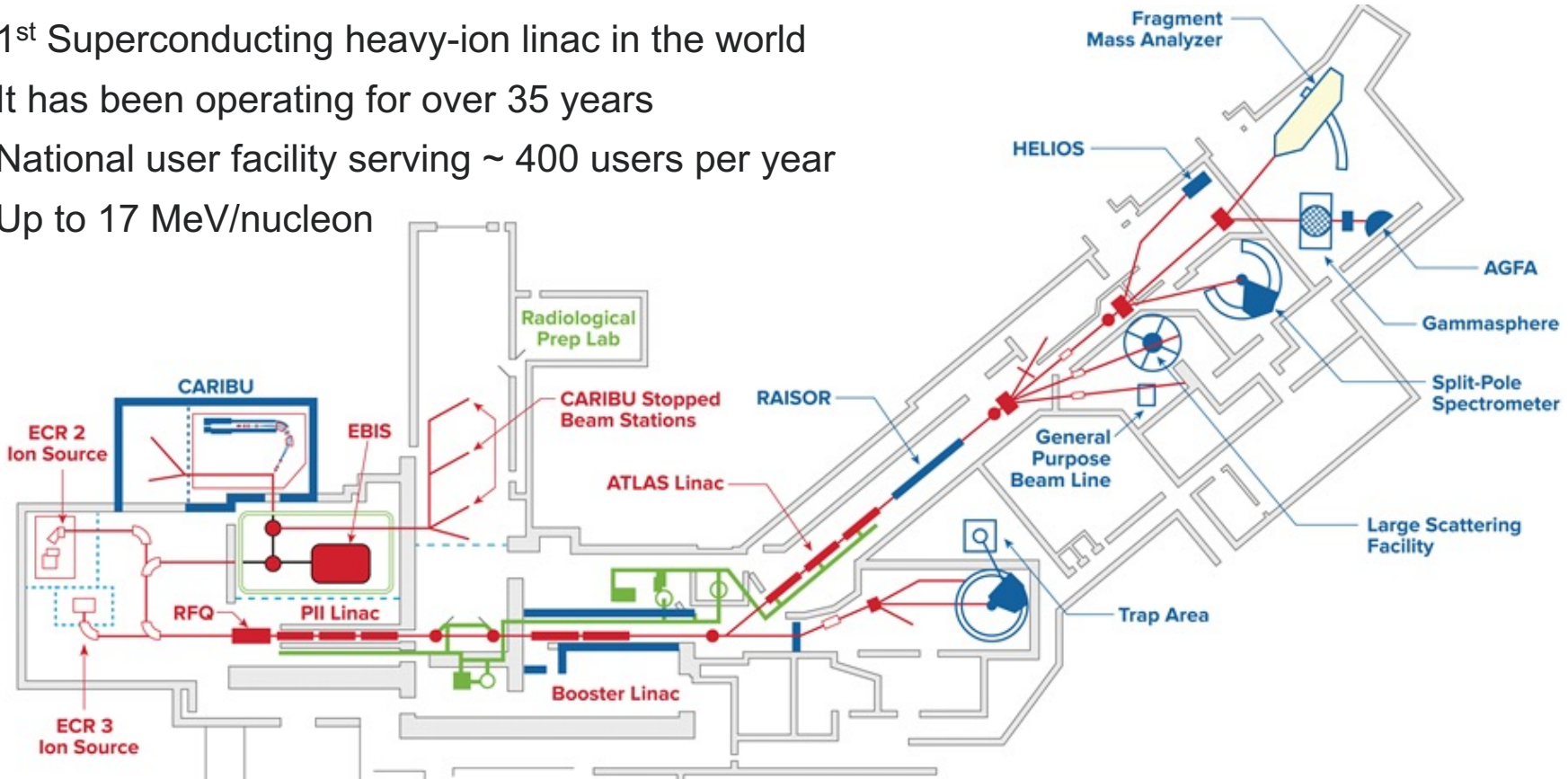
**JOSE L. MARTINEZ-MARIN**  
Physics Division  
Argonne National Laboratory

# OUTLINE

- ❑ Progress on the ATLAS AI/ML Project.
- ❑ Automated data collection established.
- ❑ Bayesian Optimization used for online beam tuning.
- ❑ AI / ML supporting the commissioning of the new AMIS beamline.
- ❑ BO from one beam to another.
- ❑ BO with Deep Kernel Learning.
- ❑ Reinforcement Learning for online beam tuning.

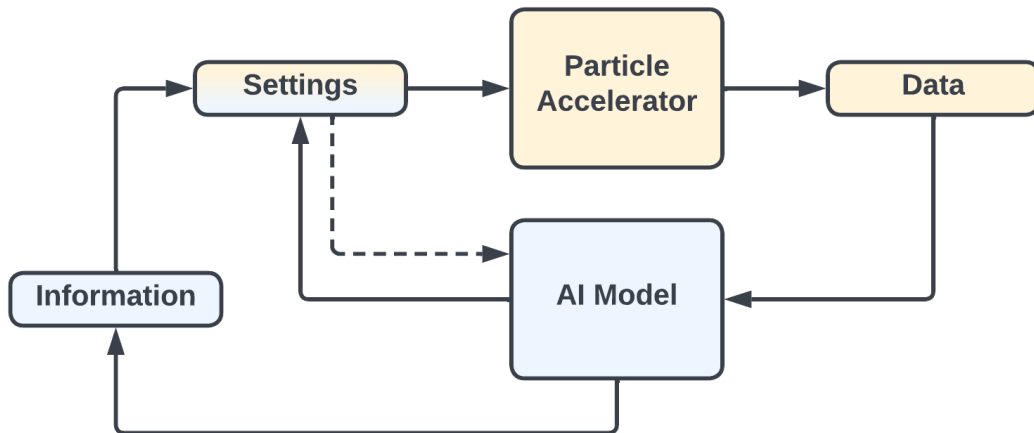
# ARGONNE TANDEM LINEAR ACCELERATOR SYSTEM

- ✓ 1<sup>st</sup> Superconducting heavy-ion linac in the world
- ✓ It has been operating for over 35 years
- ✓ National user facility serving ~ 400 users per year
- ✓ Up to 17 MeV/nucleon



# THE ATLAS AI / ML PROJECT

Use of artificial intelligence to optimize accelerator operations and improve machine performance



- ✓ Surrogate Models
- ✓ Virtual Diagnostics
- ✓ Tuning Control Model
- ✓ ...

# PROGRESS ON THE ATLAS AI / ML PROJECT

## Use of artificial intelligence to optimize accelerator operations and improve machine performance

- ❑ At ATLAS, we switch ion beam species every 3-4 days ... → Using AI could streamline beam tuning & help improve machine performance

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... making progress
  - Virtual model to enhance our understanding of the machine behavior in order to improve performance and optimize particular and new operating modes



# ATLAS – FIRST STEPS IN DATA COLLECTION

**~80% time of a Data Scientist is Collecting Data, Cleaning and Organizing Data**

- ✓ Kind of data?
- ✓ How much data?
- ✓ Accessible?
- ✓ Automated?

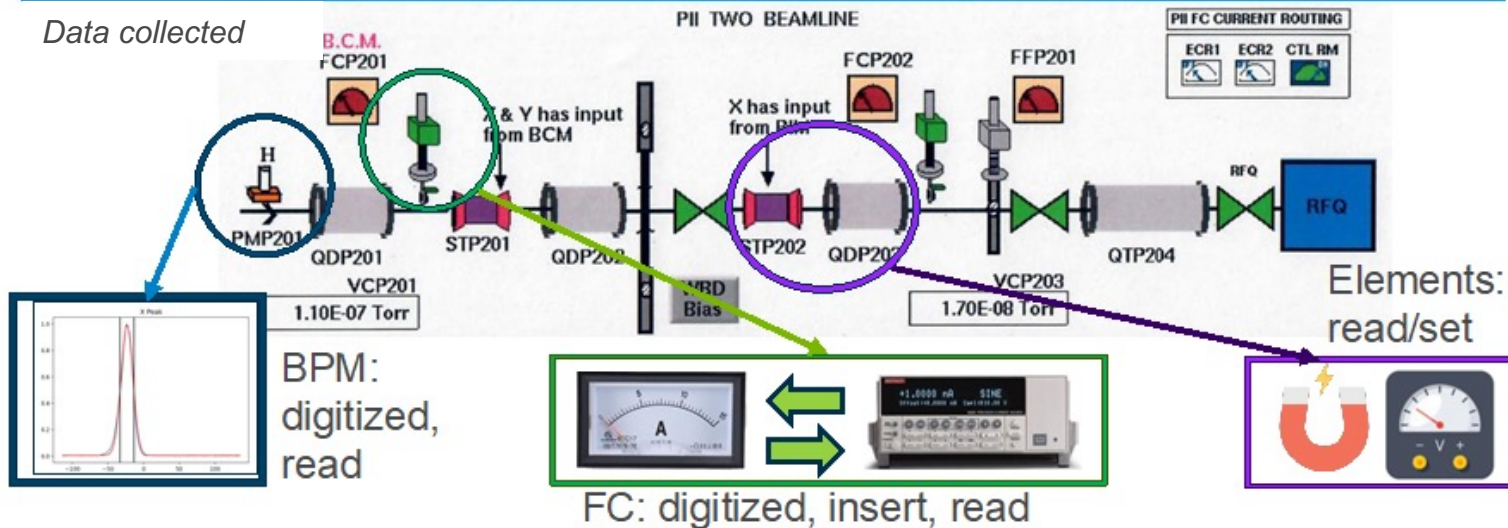
# AUTOMATED DATA COLLECTION ESTABLISHED

- ✓ Beam currents and beam profiles digitized
- ✓ A python interface developed to collect the data automatically



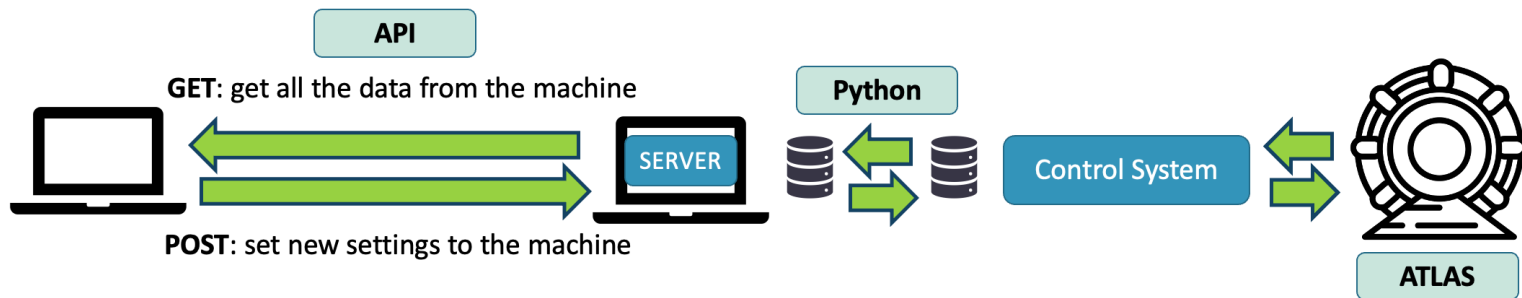
Schematic of data collection interface

Data collected

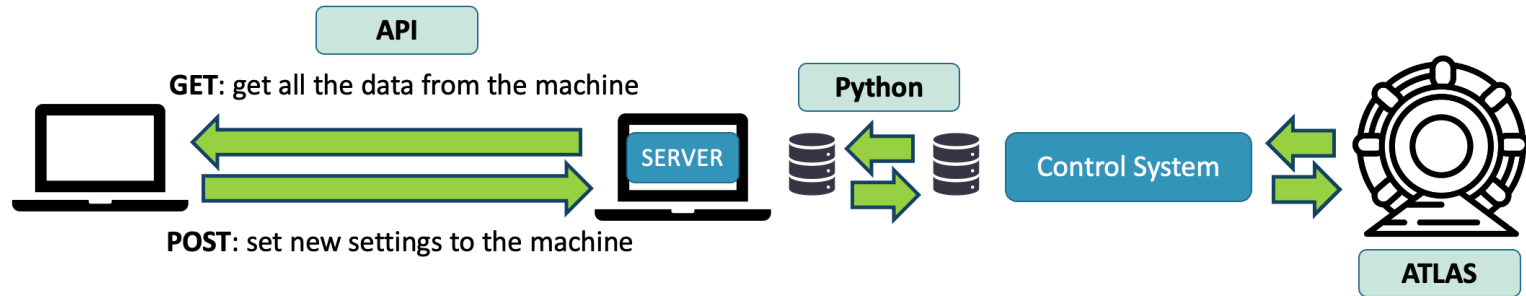


Now focused on reducing reading times...

# ATLAS - DATA COLLECTION



# ATLAS - DATA COLLECTION

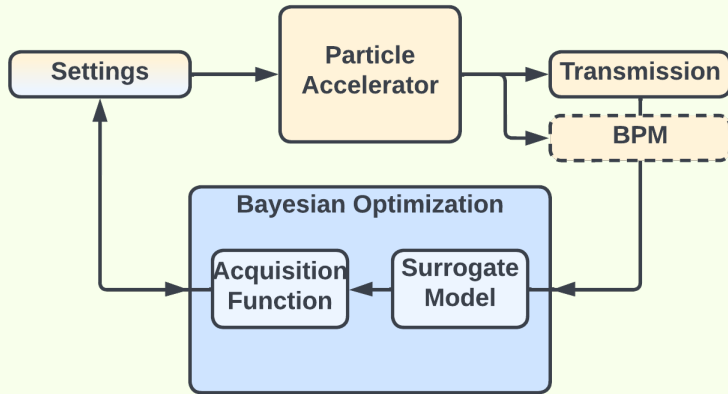


# SIMULATION - DATA COLLECTION

- ✓ Python wrapper for TRACK (Simulation Code)
- ✓ Generation of simulation data
- ✓ Different conditions and inputs
- ✓ Integration with modeling

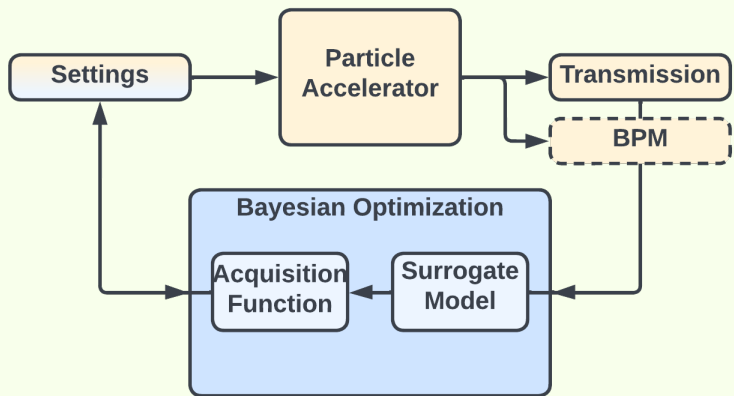


# BAYESIAN OPTIMIZATION USED FOR BEAM TUNING

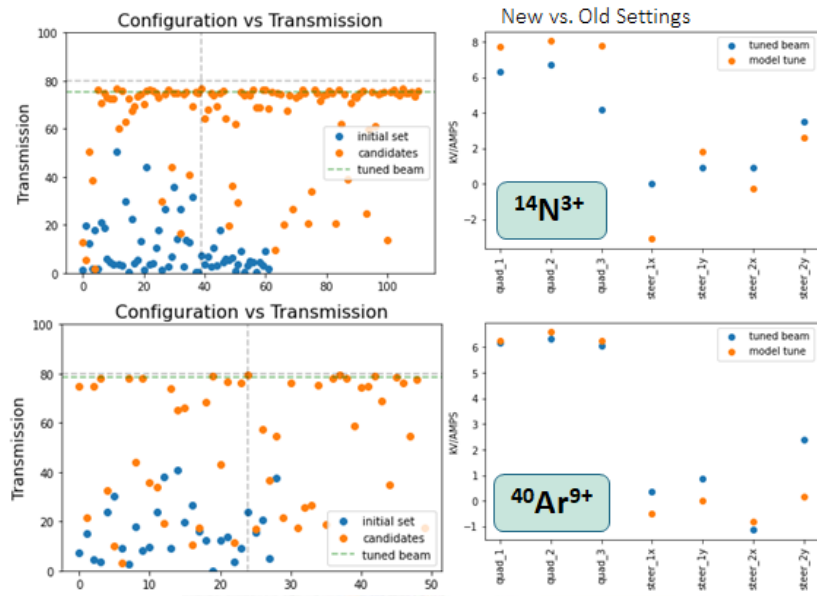


- **Surrogate Model:** A probabilistic model approximating the objective function [Gaussian Process with RBF Kernel and Gaussian likelihood]
- **Acquisition Function** tells the model where to query the system next for more likely improvement [EI]
- **Bayesian Optimization with Gaussian Processes** gives a reliable estimate of uncertainty and guides the model

# BAYESIAN OPTIMIZATION USED FOR BEAM TUNING



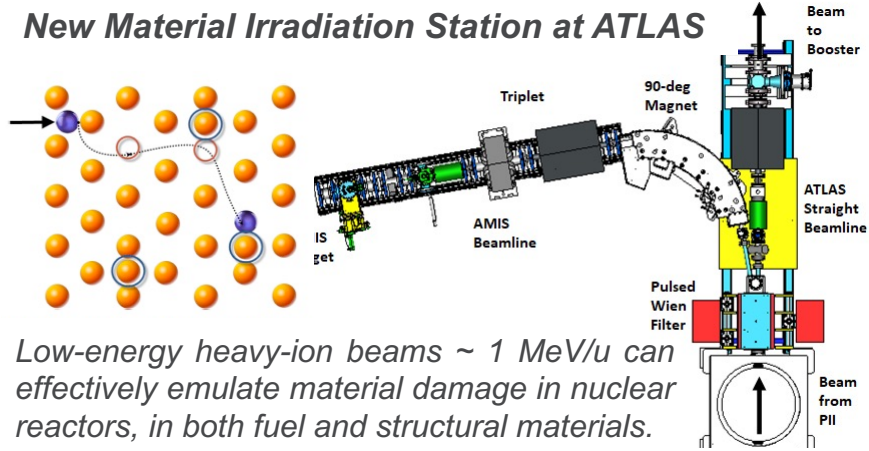
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- 7 varied parameters (3 quads + 2 steerers)
- Optimization of beam transmission
- Case of  $^{14}\text{N}^{3+}$  : 29 historical + 33 random tunes
- Case of  $^{40}\text{Ar}^{9+}$  : 29 historical tunes

# AI/ML SUPPORTING AMIS LINE COMMISSIONING

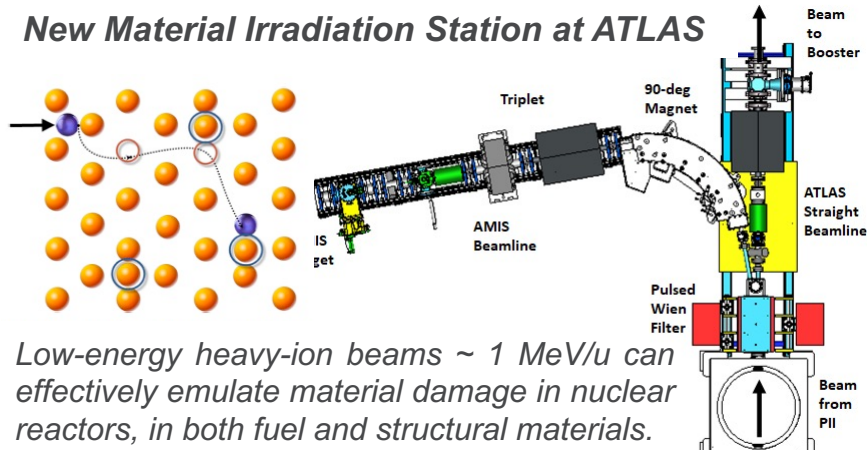
## New Material Irradiation Station at ATLAS



*Low-energy heavy-ion beams  $\sim 1$  MeV/u can effectively emulate material damage in nuclear reactors, in both fuel and structural materials.*

# AI/ML SUPPORTING AMIS LINE COMMISSIONING

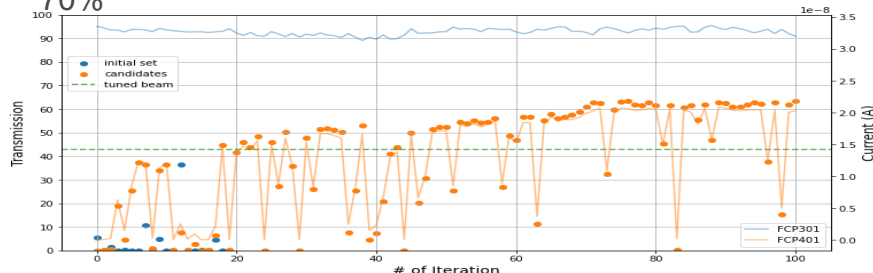
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Low-energy heavy-ion beams  $\sim 1$  MeV/u can effectively emulate material damage in nuclear reactors, in both fuel and structural materials.

## Improving Beam Transmission

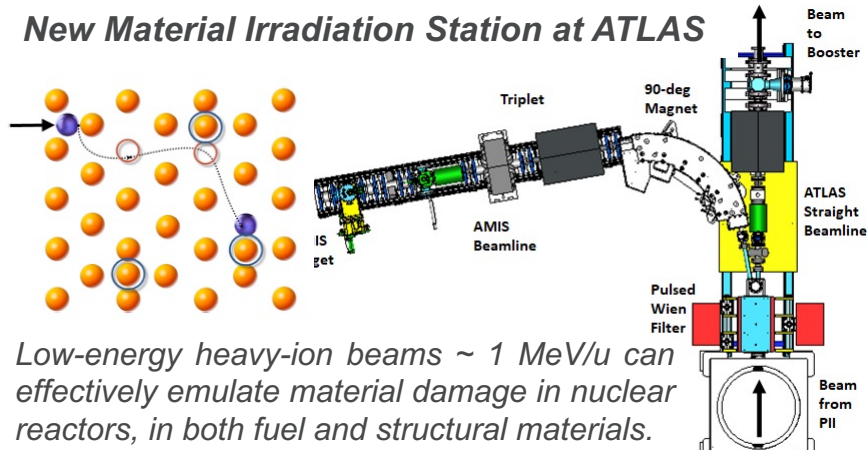
**Problem:** Maximize beam transmission by varying a triplet, two dipoles and two steerers [BO]; **Results:** 40  $\rightarrow$  70%





# AI/ML SUPPORTING AMIS LINE COMMISSIONING

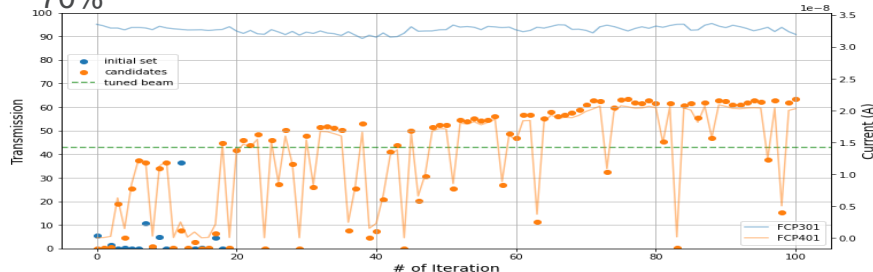
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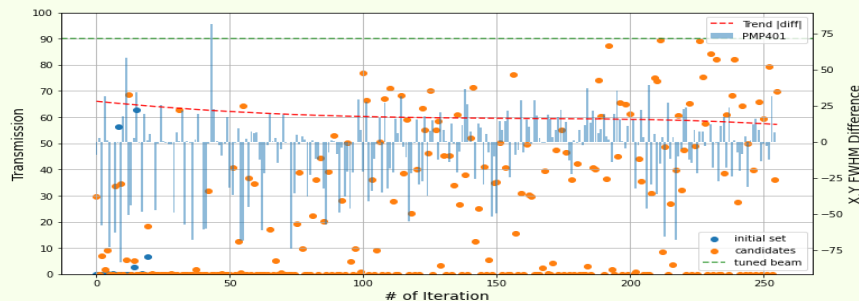
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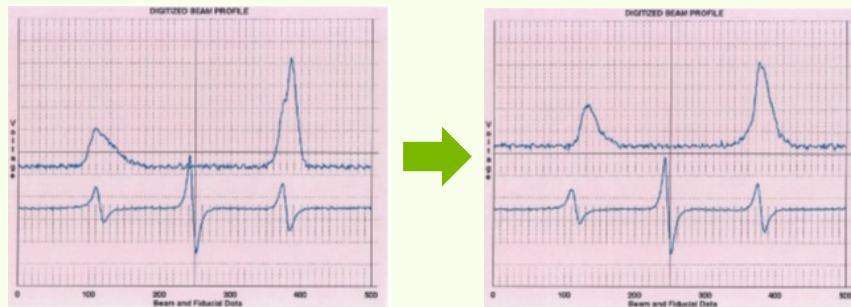


## Improving Beam Profiles

**Problem:** Produce symmetric beam profiles by varying a triplet and a steerer [BO]



Training online, slow convergence but steady progress. Competition between nice profiles and beam transmission!

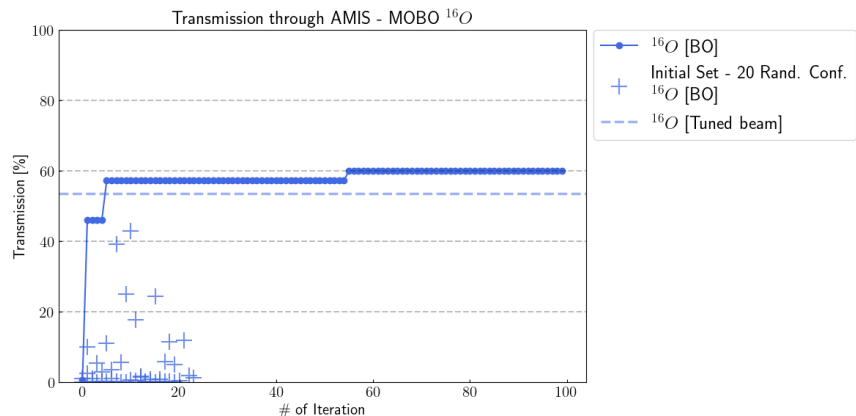
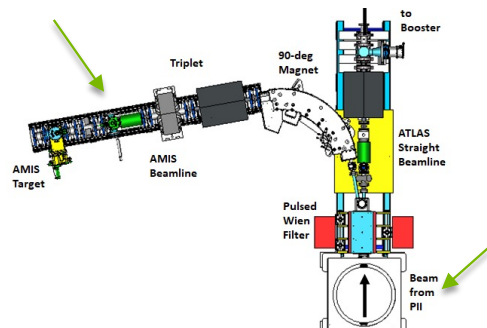


Very encouraging first results!

# MULTI-OBJECTIVE BAYESIAN OPTIMIZATION

## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet, and a doublet [MOBO]; **Results:** 53 → 60%



# MULTI-OBJECTIVE BAYESIAN OPTIMIZATION

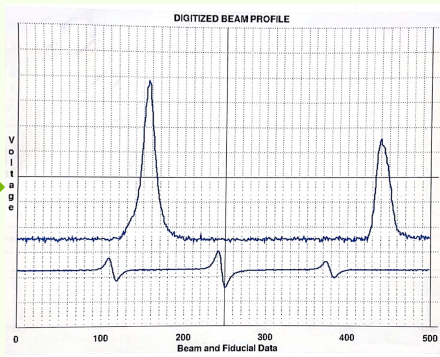
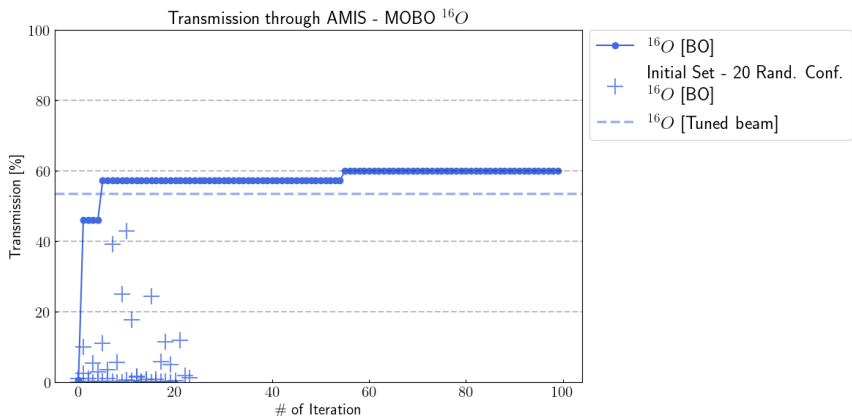
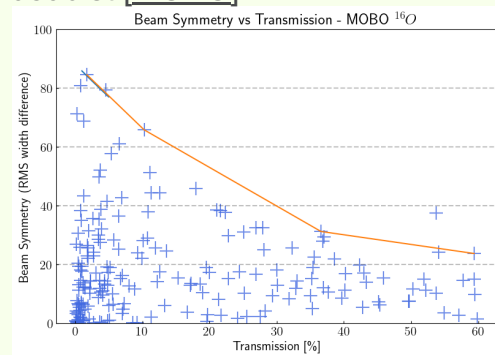
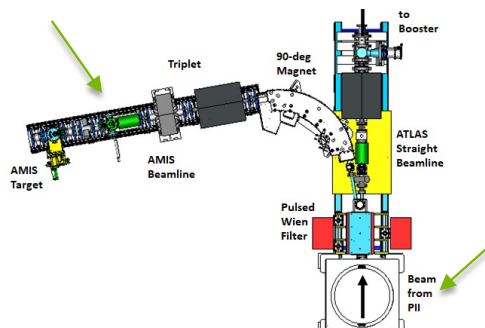
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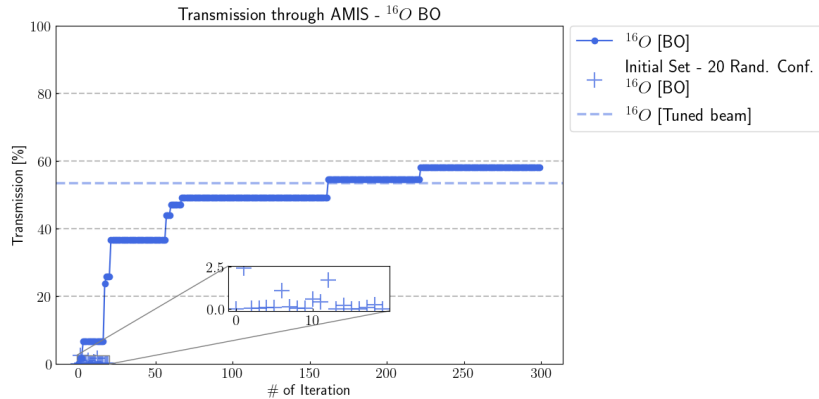
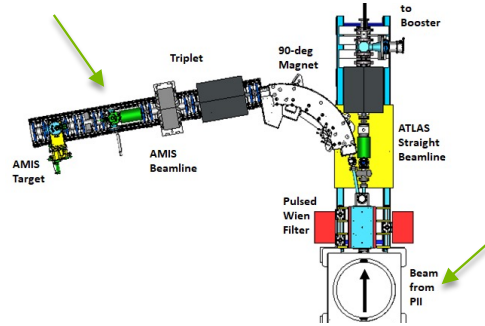
**Problem:** Produce symmetric beam profiles by varying a triplet, and a doublet [MOBO]



# BO – TRANSFER FROM $^{16}\text{O}$ BEAM TO $^{22}\text{Ne}$ BEAM

## Improving Beam Transmission

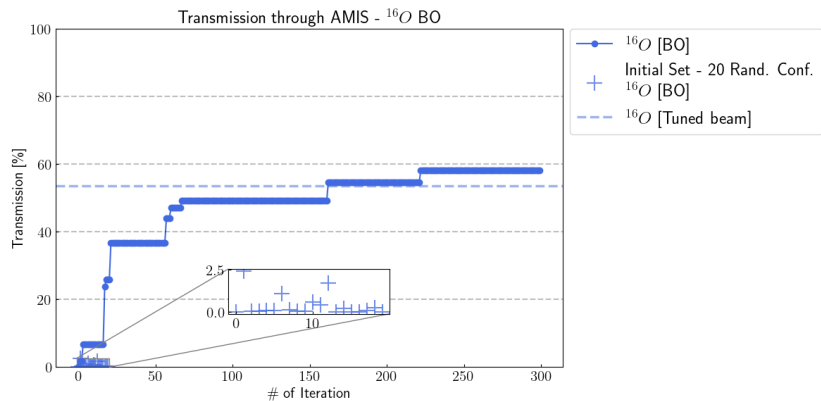
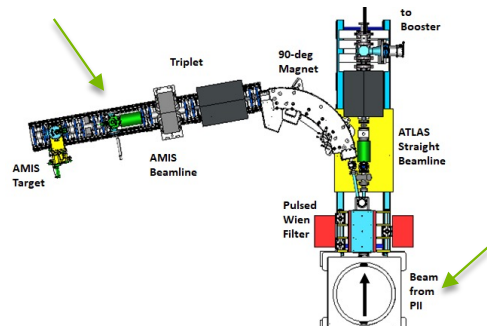
**Problem:** Maximize beam transmission by varying a triplet, and a doublet [BO]; **Results:** 53 → 58%



# BO – TRANSFER FROM 16O BEAM TO 22NE BEAM

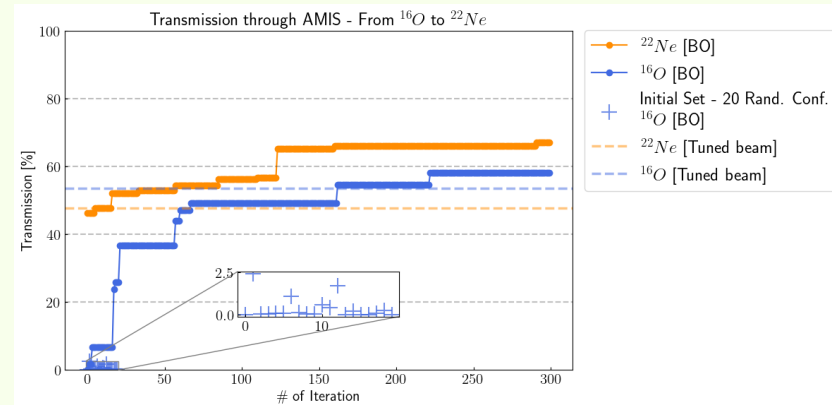
## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet, and a doublet [BO]; **Results:** 53 → 60%



## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet, and a doublet [BO]; **Results:** 48 → 67%

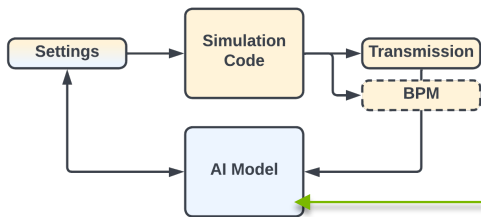
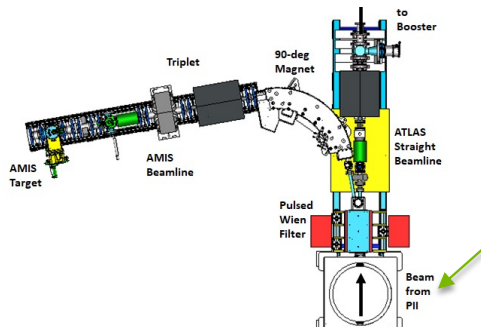


# BO WITH DEEP KERNEL LEARNING AT AMIS

- Deep kernel learning (DKL) aim to combine the representational power of neural networks with the reliable uncertainty estimates of Gaussian processes.

## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet [BO+DKL]; **Results:** 53 → 60%



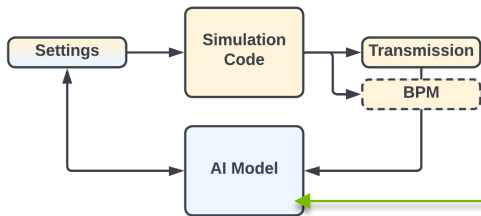
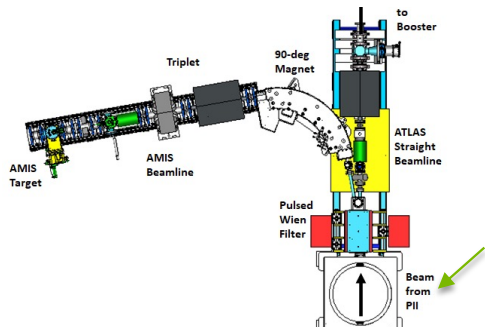
NN trained offline  
with TRACK [4k  
simulations train  
set /1k simulations  
for val set]

# BO WITH DEEP KERNEL LEARNING AT AMIS

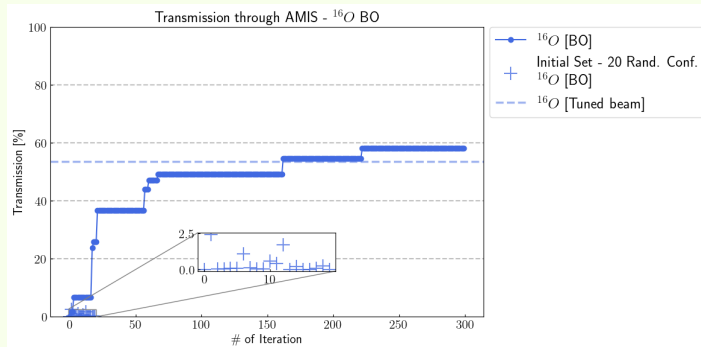
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## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet [BO+DKL]; **Results:** 53 → 60%



NN trained offline with TRACK [4k simulations train set /1k simulations for val set]

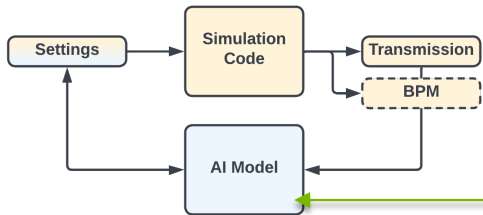
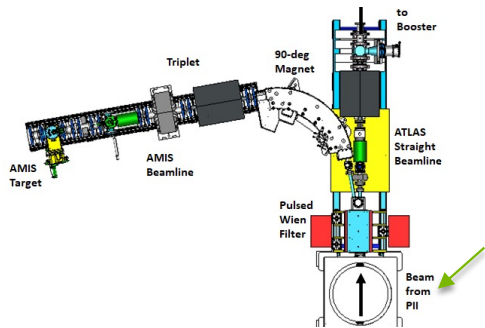


# BO WITH DEEP KERNEL LEARNING AT AMIS

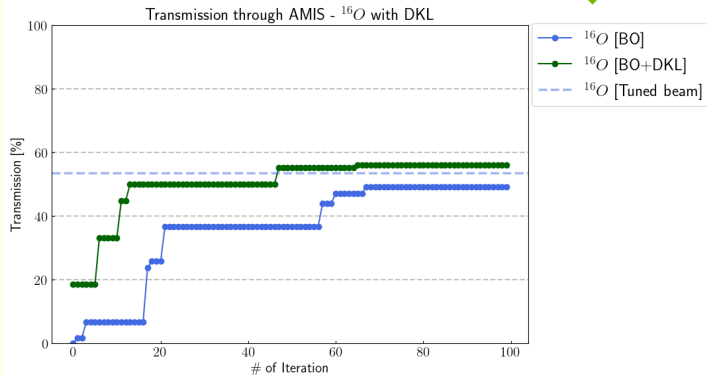
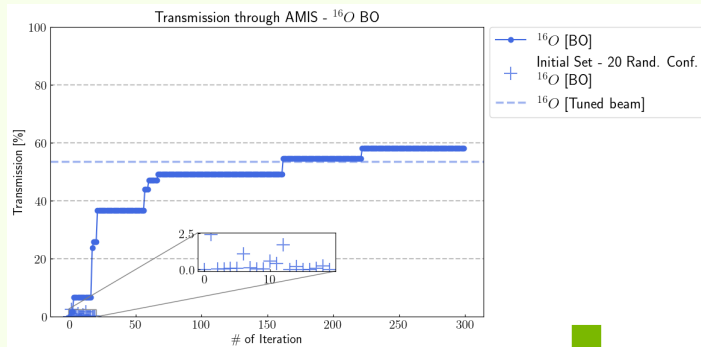
- Deep kernel learning (DKL) aim to combine the representational power of neural networks with the reliable uncertainty estimates of Gaussian processes.

## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet [BO+DKL]; **Results:** 53 → 56%



NN trained offline with TRACK [4k simulations train set /1k simulations for val set]

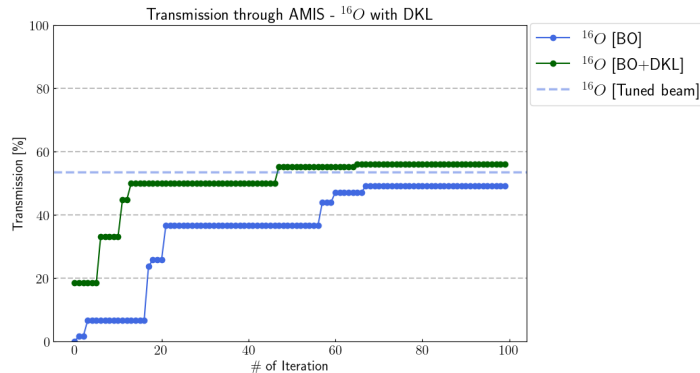
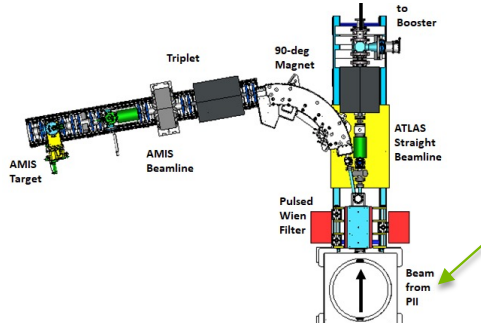




# BO+DKL – TRANSFER FROM 16O TO 22NE BEAM

## Improving Beam Transmission

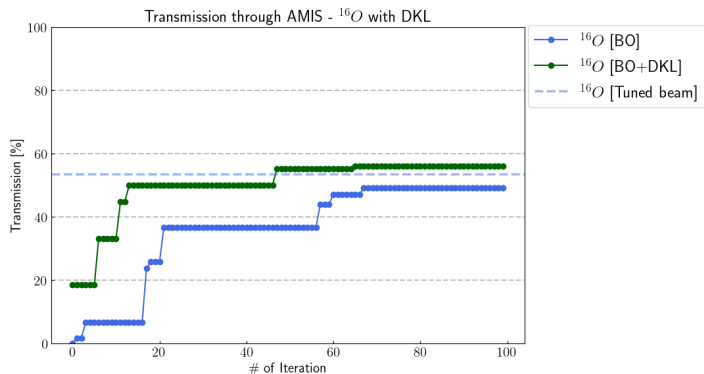
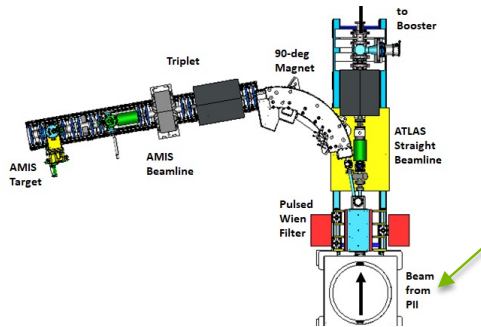
**Problem:** Maximize beam transmission by varying a triplet [BO+DKL]; **Results:** 53 → 56%



# BO+DKL – TRANSFER FROM 16O TO 22NE BEAM

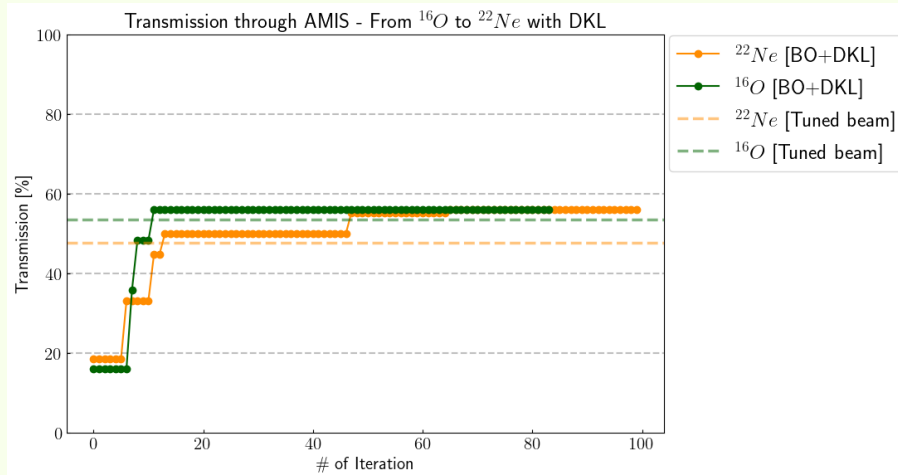
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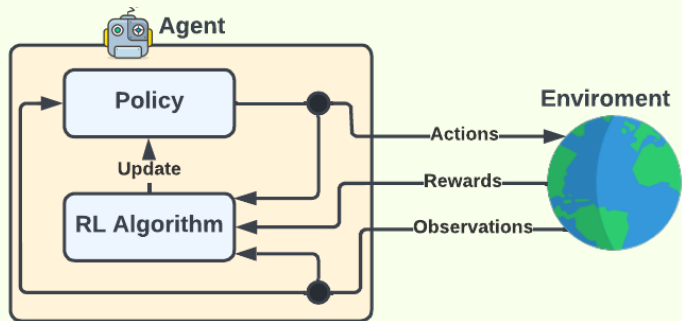


## Improving Beam Transmission

**Problem:** Maximize beam transmission by varying a triplet [BO+DKL]; **Results:** 48 → 56%

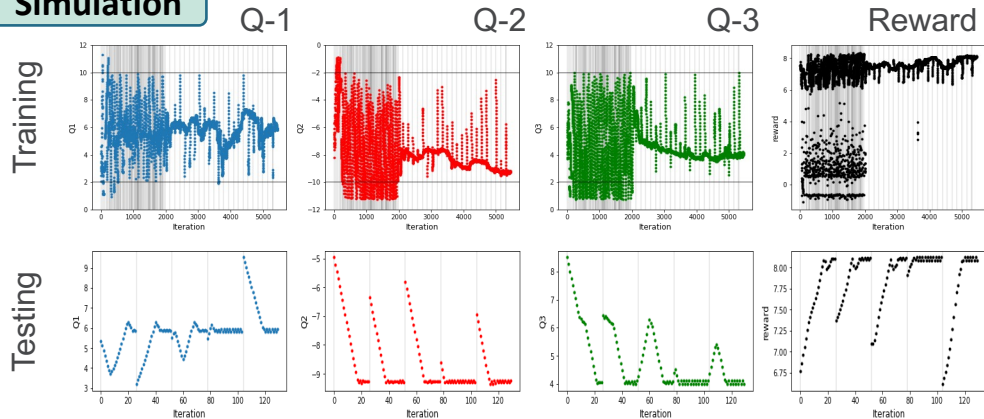


# REINFORCEMENT LEARNING FOR FINE TUNING

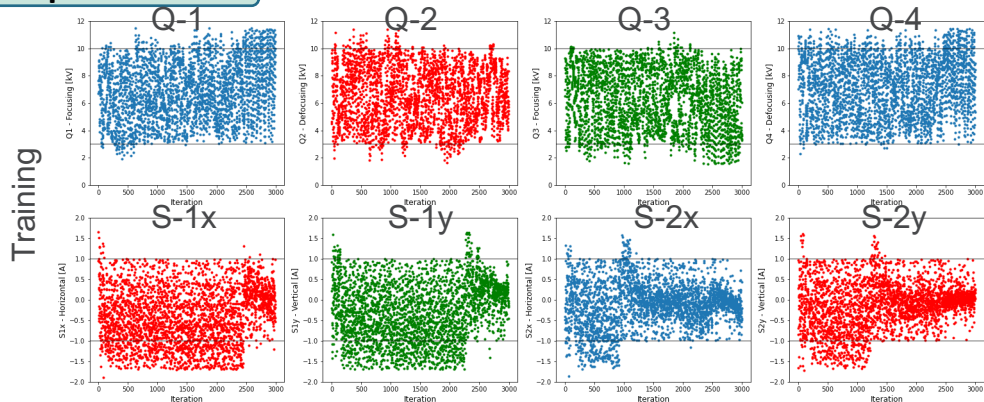


- ✓ **Method:** Deep Deterministic Policy Gradient (DDPG); Actor-Critic Approach
- ✓ **Simulation Case:** Focusing beam on target using a triplet (3 Quadrupoles)
- ✓ **Experimental Case:** Maximizing beam transmission using 4 quads and 2 steerers
- ✓ Electrostatic Quadrupoles :
  - 2 kV to 10 kV
  - Max action +/- 0.25 kV
- ✓ Steering Magnets:
  - -1 A to 1 A
  - Max action +/- 0.25 A

## Simulation



## Experimental\*



# CONCLUSIONS AND NEXT STEPS

- ✓ **Automated data collection** and testing the integration of new devices as the pepper pot and functionalities such as automated quad scan procedure.
- ✓ **Successfully trained and deploy a BO with GP on real machine for a subsection of ATLAS.**
- ✓ **Transfer model from one beam to another beam.**
- ✓ **Integration of RL model with the real machine.**
- ✓ Misalignments and Steerers added into TRACK code.
- ✓ Next Steps:
  - Improve existing models (ex. acquisition function).
  - Better offline training (misalignments and steerers added), online tuning.
- ✓ Current Challenges:
  - Possible damage to devices when beam is lost during model training.

# ACKNOWLEDGMENTS

*Brahim Mustapha, Ben Ryan Blomberg, Eric Letcher, Daniel Stanton,  
Clayton Dickerson, Kenneth Bunnell, Daniel Santiago, Megan McIntyre,  
Alexander F Grabenhofer, Gavin Matthew Dunn, Henry Brito,  
Samantha Burtwistle, Tony Krupa, Leland Luecke, etc.*





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NATIONAL LABORATORY

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