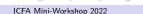
The CERN ML Frameworks

How to get ML into the Control Room

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3rd ICFA Beam Dynamics Mini-Workshop, on Machine Learning Applications for Particle Accelerators, 3 November 2022

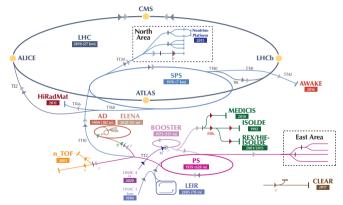




CERN

- many accelerators, extremely diverse
- lots of low-level problems already well automated
- but: many high-level problems still solved manually
- better turnaround time and beam quality necessary to reach target integrated luminosity

The CERN accelerator complex Complexe des accélérateurs du CERN





CERN

Lots of infrastructure already in place!

JAPC: uniform communication protocol with physical and virtual devices

LSA: access to the settings database and history

UCAP: Function as a Service development framework (Link)

WRAP: web app to create browser-based monitoring dashboards (Link)

Acc-Py: Python development and deployment framework

Two projects are more specialized on optimization and ML:

MLP: platform for ML model versioning, storage and deployment

GeOFF: Framework for operational use of RL and numerical optimization



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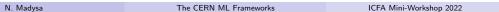
Volatile world of ML:

- code needs to run once
- bleeding-edge technology
- cloud services and custom tools
- maintainability not the first concern

Reliable world of accelerator controls:

- need to run reliably 24/7/365: reproducibility, robustness, traceability
- highly reliable, battle-tested tools
- constraints of the technical network: no internet access, restricted tooling, security precautions
- minimize maintenance effort through standardization and unification





Objectives:

- common approach to storage, versioning, deployment and usage of models
- remove infrastructural concerns from model lifecycle
- fulfill needs specific to accelerator controls:
 - reliability
 - traceability
 - security
 - standardization
- stay out of the user's way:
 - minimize constraints on model developer's workflow
 - don't restrict choice of tools



Concepts:

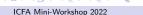
Model Type

- contains the model code
- fully fledged Python package
- lives as a Git repository on our servers
- different versions are different development snapshots

Model Parameters

- contains only the training results
- depends on the ML framework
- often an opaque binary file
- different versions are different training snapshots





Developing a model:

Set up your package

```
tree
my-model-package/
my_model_package/
my_model_package/
mlp-models.toml
mlp-models.toml
pyproject.toml
setup.cfg
```

Made easy with acc-py init and acc-py init-ci!



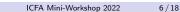


- Set up your package
- Declare your model

```
# mlp-models.toml
```

- 2 [[model]]
- name = "my_model_package:MyModel"
- 4 standalone = false





- Set up vour package
- Oeclare vour model
- Implement a wrapper class

```
# init .pv
   from mlp model api import INPUTS, OUTPUTS
   from mlp tensorflow model \
       import TensorflowModel
   class MvModel(TensorflowModel):
5
       def init (self):
6
           model = tf.keras.Model(...)
7
           super(). init (model)
8
       def predict(self, inputs):
q
           outputs = self.model(\
10
                inputs[INPUTS])
11
           return {OUTPUTS: outputs}
12
```





- Set up your package
- Oeclare your model
- Implement a wrapper class
- optional: other frameworks

```
# __init__.py
   class MyModel(TensorflowModel):
        def export parameters(
            self. parameters target: Path
5
          -> None:
6
7
        def load parameters(
8
            self, parameters src Path
Q
          -> None:
10
11
```



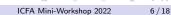


- Set up your package
- ② Declare your model
- Implement a wrapper class
- optional: other frameworks
- O Push a Git tag to Cl

```
$ git commit --all -m "New version."
```

- \$ git push origin main
- 3 **\$** git tag v1.0.0
- 4 \$ git push --tags origin

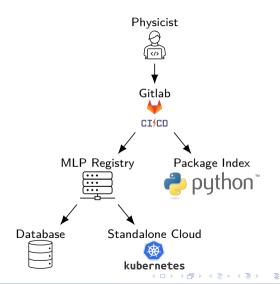




Developing a model:

- Set up your package
- ② Declare your model
- Implement a wrapper class
- optional: other frameworks
- Output Push a Git tag to CI

... and CI takes care of the rest!





Publishing training results to the MLP:

```
# train my model.py
   from my_model_package import MyModel
   from mlp_client import AUTO, Client, Profile
4
   mlp_model = MyModel()
   train(mlp_model.model)
   client = Client(Profile.PRO)
   client publish model parameters version(
       mlp model, name="mv model.default", version=AUTO
10
```





Embedding an MLP model in a Python application:

```
# operational application.py
   from my_model_package import MyModel
   from mlp_client import AUTO, Client, Profile
   from mlp_model_api import INPUTS, OUTPUTS
5
   client = Client(Profile.PRO)
   model = client.create model(
       MvModel. name="mv model.default". version=AUTO
8
9
   response = model.predict({INPUTS: get inputs()})
10
   show_results(response[OUTPUTS])
11
```





Connecting a Python application to a stand-alone model in the cloud:

```
# operational application.py
   from mlp client import AUTO, Client, Profile
   from mlp_model_api import INPUTS, OUTPUTS
4
   client = Client(Profile.PRO)
   model = client.create_standalone_model(
       "my model package:MyModel",
       name="mv model.default".
8
       version=AUTO.
10
   # Communicates via HTTP!
11
   response = model.predict({INPUTS: get inputs()})
12
   show_results(response[OUTPUTS])
13
```



Connecting a Java application to a stand-alone model in the cloud:

```
// OperationalApplication.java
   public static void main() {
       StandaloneModel<MyRequest, MyResponse> model =
3
            new MlpClient(Environment.PRO)
            .standaloneModelBuilder(MyRequest.class, MyResponse.class)
5
            .modelType("my_model_package:MyModel")
6
            .modelParameters("my_model.default")
            .build():
8
       MvRequest request = new MvRequest(getInputs()):
9
       MvResponse response = model.predict(request):
10
       showResults(response.getOutput());
11
12
```

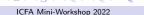


Conclusion:

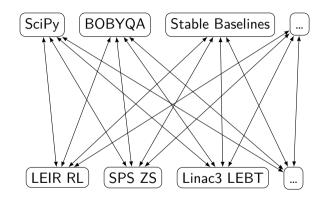
- MLP is ready for production*
- we separate model R&D from its operational use
- model developers can ignore infrastructural concerns
- we follow software engineering best practices
 - ⇒ reliable and maintainable

*standalone model deployment in beta





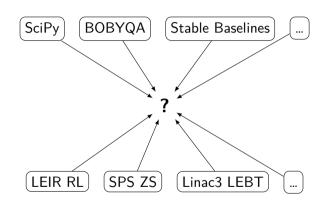
- many different optimizers/APIs
- many different optimization problems
- each problem involves complex machine communication
- operators don't want to juggle Python scripts!







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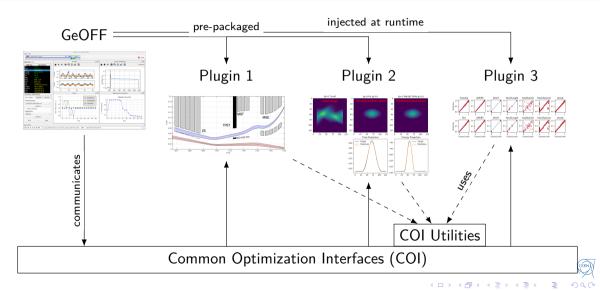
Goals:

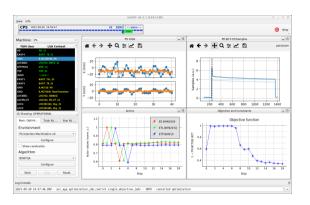
- provide ecosystem for accelerator optimization and control
- provide compatibility with as many algorithms as possible
- facilitate the progression manual tuning o numerical optimization o machine learning

Guiding principles:

- be agnostic over machine, communication protocol or devices
- minimize boilerplate code that does not solve the problem
- don't make people pay for features they don't use
- always leave an escape hatch open







- lists, configures and runs optimization problems
- built-in list of optimizers (will be made user-extensible)
- optimization problems are loaded as plugins pre-packaged or at runtime



GeOFF Use Cases

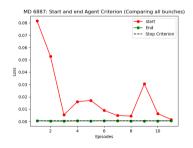
- Linac3: steering of beam transfer line
- Linac4: 2 expert tools
- PSB: operations (WIP) & commissioning
 - bunch recombination at PSB ejection
 - resonance compensation
 - RF optimization
 - injection to PS
- PS: used during commissioning
 - resonance compensation
 - transition gamma jump circuits
 - septa alignment for slow extraction
- LEIR: used during commissioning
 - transfer lines (from Linac3, to PS)
 - injection bumps
 - ▶ phase adjustment of RF cavities

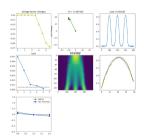
- SPS: expert tool & operations
 - tune adjustments
 - septa alignment for slow extraction
 - spill noise reduction
 - splitter optimization
 - injection kicker optimization
 - crystal shadowing
- used at almost all accelerators
 - ► ISOLDE: lots of homogeneous devices ⇒ CPS Optimizer
 - ► LHC: fast acquisition, high safety req.
 - \Rightarrow bespoke algorithms
- most often used as expert tool

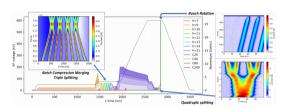


Use Case: PS RF Manipulations via RL

- LHC beam production requires quadruple splitting at $26 \, {\rm GeV}/c$ in PS
- RF phase errors introduce spread in bunch-by-bunch intensity and emittance
- ⇒ RL agent corrects phases for uniform bunches







- faster than classical optimization due to reuse of experience
- trained on simulation, evaluated on real machine
- \bullet episode length $n \in [2,18]$, $\bar{n} = 8.46$

presented yesterday by J. Wulff



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Conclusion

- CERN fosters an ecosystem of independent efforts to improve operational ML usage
- solutions complement and integrate with each other
- but: still plenty to do!
- efforts to open-source MLP and GeOFF are underway
 - upcoming EURO-LABS project will drive this effort further

Links:

- https://gitlab.cern.ch/nmadysa/icfa-tutorial
- https://cernml-coi.docs.cern.ch/
- https://gitlab.cern.ch/be-op-ml-optimization
- https://indico.cern.ch/event/1175862/ (seminar on MLP and GeOFF)

