

BPM measurement prediction based on HOM signals using Machine Learning*

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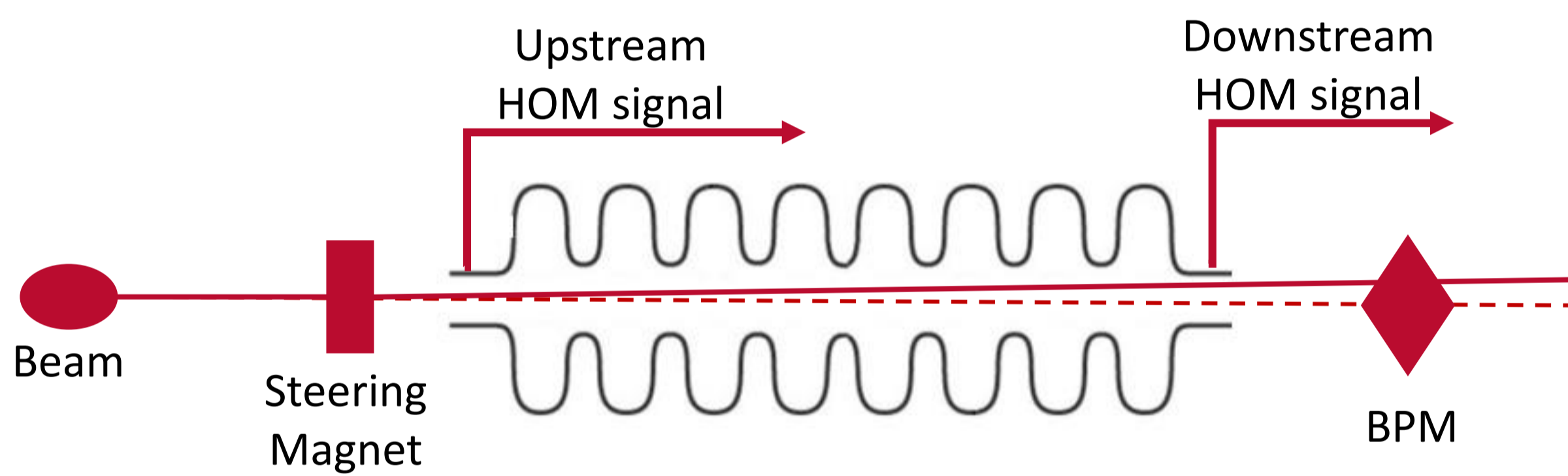


ABSTRACT

Emittance dilution effects due to off-axis beam transport affect the beam quality at facilities like the Linac Coherent Light Source II (LCLS-II) at SLAC, where a low emittance electron beam is desired at the first cryomodule (CM). Transverse offset of the beam as measured by Beam Position Monitors (BPMs) downstream a CM has shown correlation with the beam-induced higher-order modes (HOMs) signals of superconducting RF cavities. Experiments performed at the Fermilab Accelerator Science and Technology (FAST) facility collected HOM signals and BPM measurements for various beam offsets, using a set of vertical and horizontal corrector magnets to change the transverse position of the beam. Here, we present the collected data, and a couple of Neural Networks for bunch-by-bunch mean and standard deviation prediction for BPMs based on HOM measurements.

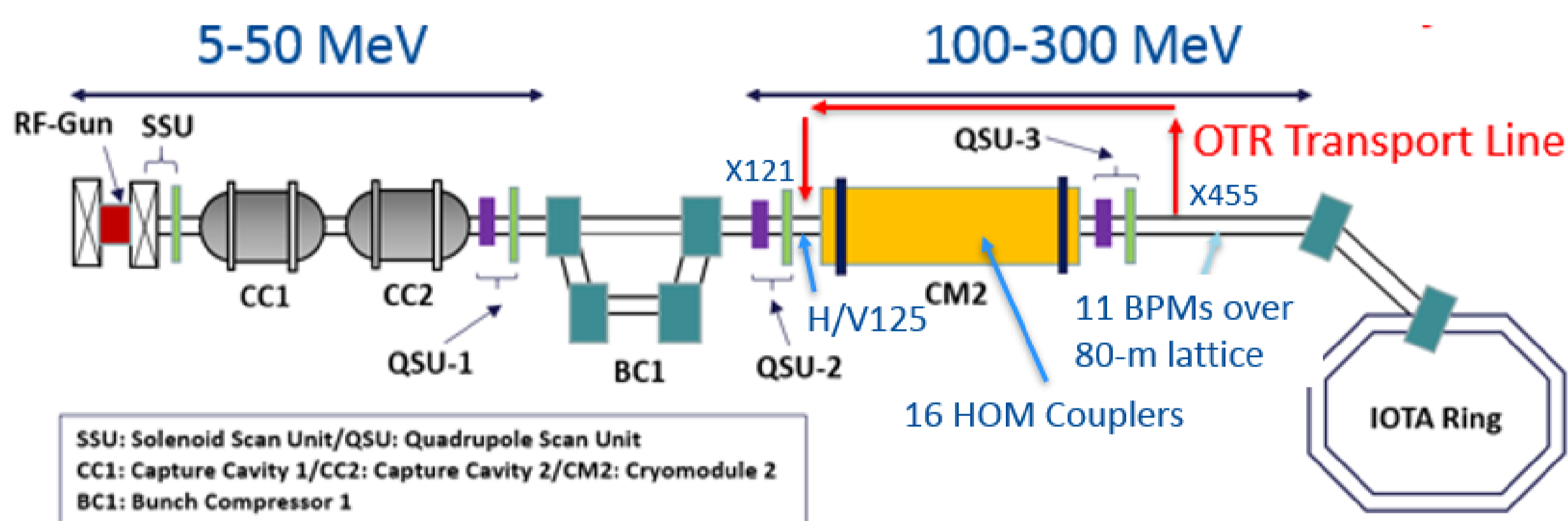
BACKGROUND AND MOTIVATION

- Off-axis beam transport may result in emittance dilution due to transverse long-range (LRW) and short-range wakefields (SRW).
- A set of LRWs known as High Order Modes (HOMs) are proportional to beam offset in SRF cavities.
- Reducing HOMs may help to mitigate emittance dilution effects.
- Low emittance electron beams are of high importance in accelerating structures at large facilities like the LCLS-II at SLAC.



EXPERIMENT & DATA

The FAST Facility at Fermilab

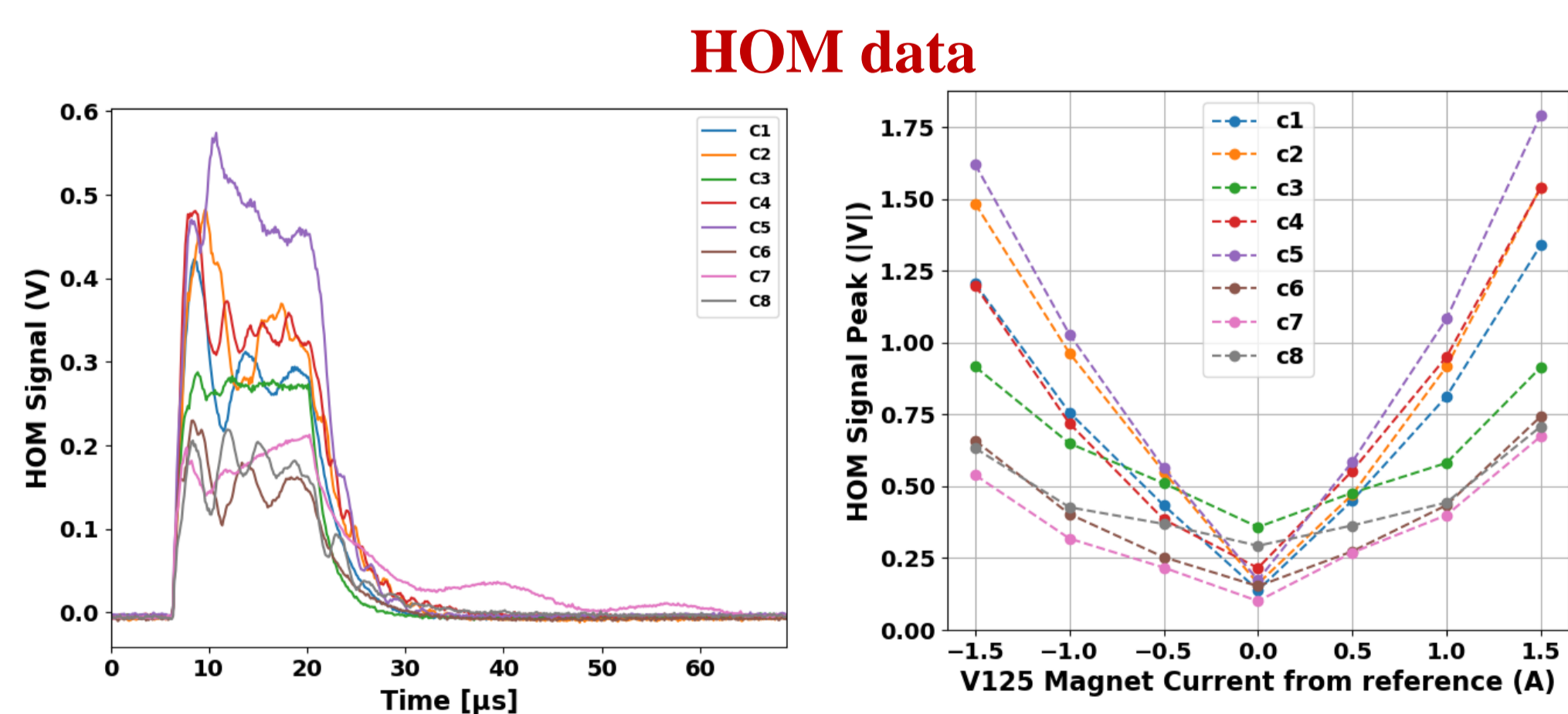


The Beam: electron beam of 50 bunches and 3 MHz bunch repetition rate. Bunch pattern repeats at 1 Hz. Each repetition is called a "shot"

- A "reference" trajectory was found by minimizing as many US HOM signals as possible by steering the beam.
- We captured HOM and BPM data for this reference trajectory and for charges of 125, 250, 400 and 600 pC/b.
- We then repeat the measurements for values of the corrector currents from -1.5 A to 1.5 A from the reference current, with 0.5 A steps.

Left: Upstream HOM waveforms for 8 cavities. Peak value as representative number

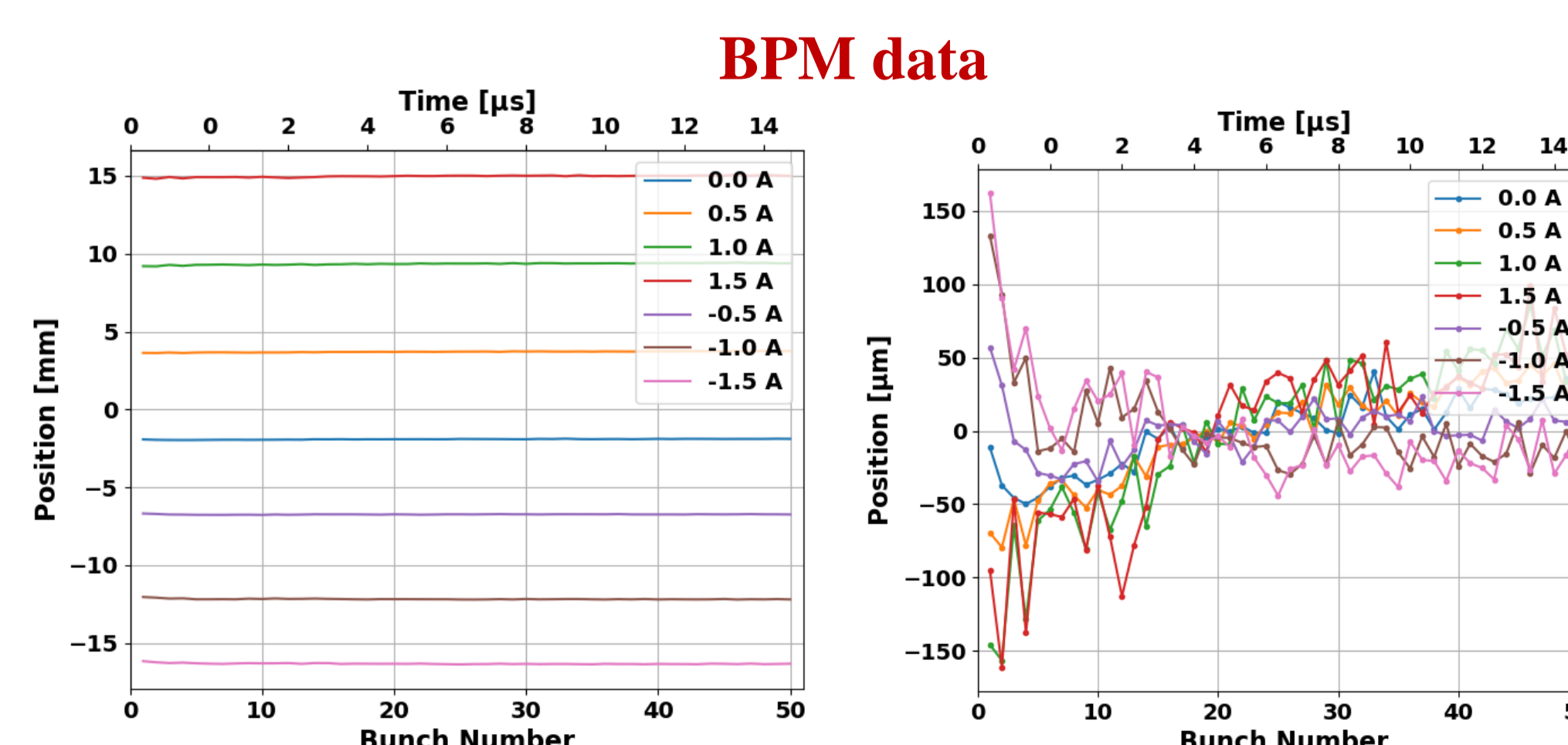
Right: Average US HOM peak value over 300 shots vs V125 corrector current offset at 400pC/b



Vertical scan using V125

Left: BPM mean values over 300 shoots

Right: Evolution of relative beam centroid position. Mean and standard deviation proportional to beam offset

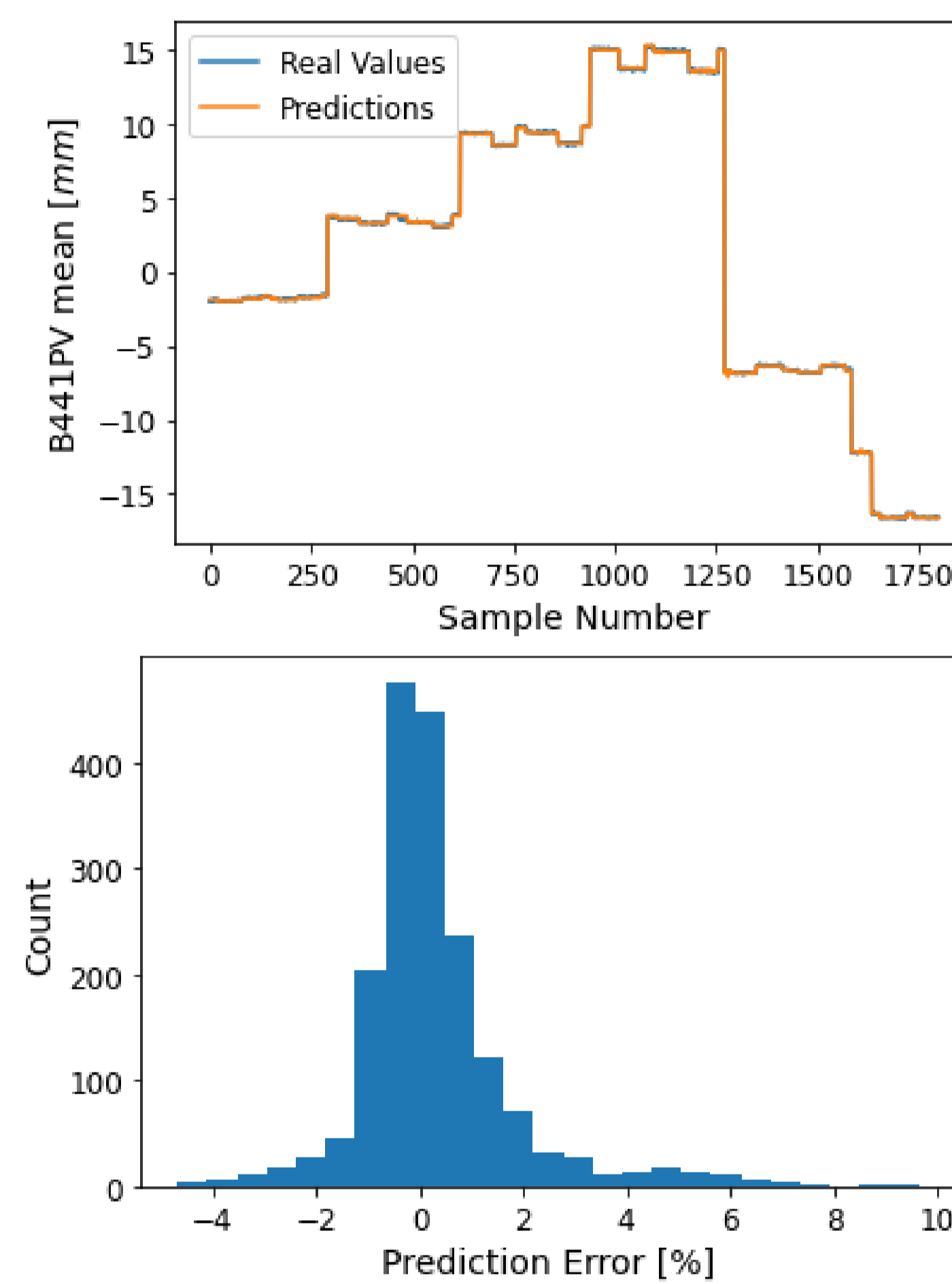


NN MODEL AND RESULTS

GOAL: Train a couple of NNs to predict BPM mean measurements and centroid motion's standard deviation using HOM signal peaks only

NN for mean prediction

- Normalization layer
- 2 hidden layers each one with 32 nodes
- Hyperbolic tangent activation function
- 80-20 split for the training and test datasets.
- From the training dataset, 20% was used for validation.
- Early stop was implemented

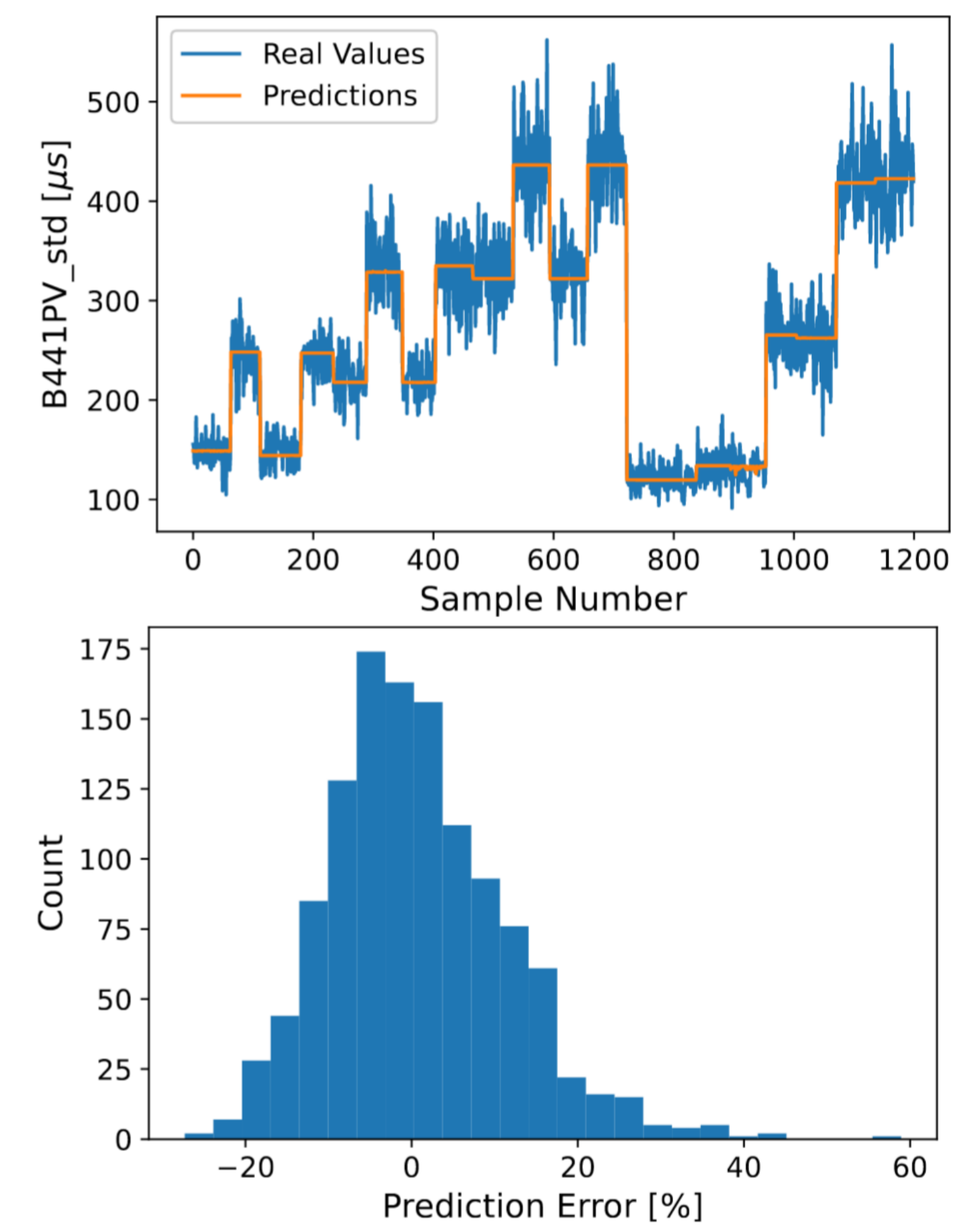


NN results for BPM mean prediction

| BPM | Train MAE [μ m] | Val MAE [μ m] | Test MAE [μ m] | Test MAPE [%] |
|--------|----------------------|--------------------|---------------------|---------------|
| B418PV | 41.05 | 40.75 | 41.03 | 0.61 |
| B441PV | 44.25 | 42.94 | 46.69 | 0.91 |

NN for std prediction

- Normalization layer
- 6 hidden layers (four layers of 100 nodes followed by two layers of 64 nodes)
- Hyperbolic tangent activation function
- 80-20 split for the training and test datasets.
- From the training dataset, 20% was used for validation.
- Early stop was implemented



NN results for BPM std prediction

| BPM | Train MAE [μ m] | Val MAE [μ m] | Test MAE [μ m] | Test MAPE [%] |
|--------|----------------------|--------------------|---------------------|---------------|
| B440PV | 41.42 | 41.98 | 42.82 | 9.76 |
| B440PH | 29.82 | 30.46 | 30.54 | 8.20 |
| B441PV | 18.98 | 19.26 | 19.50 | 8.40 |
| B441PH | 20.89 | 21.43 | 21.62 | 8.44 |

Conclusions and Future Work

- Data with the correlation between beam steering, HOM signals and BPM measurements has been used to train a NN model.
- A NN model is capable of predicting BPM mean value over a train of bunches with less than 1% error.
- A NN model is capable of predicting the centroid slew's standard deviation with less than 10% error.
- These are encouraging results towards developing a ML-based controller for HOM reduction and emittance preservation for the LCLS-II project at SLAC.
- Our next steps include the development of the controller using an inverse model of the NN developed in this research, i.e. a NN that can predict HOM signals for a given beam offset.
- We also plan to explore adaptive learning, Gaussian Processes (GP) and GP optimizers.

References

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