TOWARDS A FRAMEWORK-INDEPENDENT ALGORITHM LIBRARY FOR EIC AND BEYOND

algorithms

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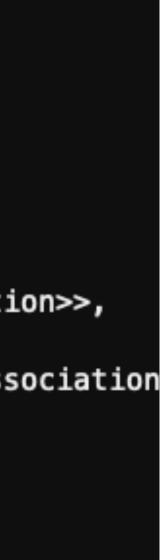
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using ClusteringAlgorithm = Algorithm<</pre> Input<edm4eic::ProtoClusterCollection, std::optional<edm4hep::SimCalorimeterHitCollection>>, Output<edm4eic::ClusterCollection, std::optional<edm4eic::MCRecoClusterParticleAssociation</pre>

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DESIGN GOALS AND CHALLENGES Towards a first prototype for algorithms

DESIGN GOALS

- Enable algorithm sharing across experiments and even communities
- Framework agnostic algorithms
- Main dependencies: EDM4hep/ EDM4eic and DD4hep
- Showcase independence through both Gaudi and JANA2 integration
- Minimal boilerplate for integration Avoid duplication of definitions



CHALLENGES

- Service integration
- Data store interactions
- Properties
- Some definition duplication and manual glue code unavoidable
- Automatic testing in a no-framework context





CHALLENGE 1: SERVICE INTEGRATION Towards a first prototype for algorithms

Thread-safe lazy-evaluated minimal service system CRTP base class to add the instance method This could have been part of DEFINE_SERVICE macro, but I think it is better to keep the macro magic to a minimum to maximize transparency plate <class SvcType> class Service : public PropertyMixin, public NameMixin { olic: static SvcType& instance() { // This is guaranteed to be thread-safe from C++11 onwards. static SvcType svc; return svc; // constructor for the service base class registers the service, except // for the ServiceSvc which is its own thing (avoid circularity) Service(std::string_view name) : NameMixin{name} { ServiceSvc::instance().add(name, this); } namespace algorithms

```
action is responsible for dealing with concurrent calls
       the default LogAction is a thread-safe example
    LogSvc : public Service<LogSvc> {
      LogAction = std::function<void(LogLevel, std::string_view, std::string_view)>;
void defaultLevel(const LogLevel l) { m_level.set(l); }
LogLevel defaultLevel() co
                                       m_level; }
void action(LogAction a) { m_action = a; }
void report(const LogLevel l, std::string_view caller, std::string_view msg) const {
 m_action(l, caller, msg);
Property<LogLevel> m_level{this, "defaultLevel", LogLevel::kInfo};
                                                         iew caller, std::string_view msg) {
    ction m_action = [](<mark>const</mark> LogLevel l, std::strin
  static std::mutex m;
 std::lock_guard<std::mutex> lock(m);
 fmt::print("{} [{}] {}\n", logLevelName(l), caller, msg);
 LGORITHMS_DEFINE_SERVICE(LogSvc)
```



- Services as lazy-evaluated singletons
- Support standalone minimal interface
- Interface has usable defaults for standalone operation
- Standalone defaults are meant to be overridden by the framework
- Prototype currently implements LogSvc and GeoSvc
- Special ServiceSvc provides framework with all required services, so it can handle the bindings





EXAMPLE SERVICE INTEGRATION (JUGGLER) Towards a first prototype for algorithms

```
auto& serviceSvc = algorithms::ServiceSvc::instance();
info() << "ServiceSvc declared " << serviceSvc.services().size() << " services" << endmsg;</pre>
// loop over all services and handle each properly
// Note: this code is kind of dangerous, as getting the types wrong will lead to
// undefined runtime behavior.
   (auto [name, svc] : serviceSvc.services()) {
  if (name == algorithms::LogSvc::kName) {
    auto* logger = static_cast<algorithms::LogSvc*>(svc);
    const algorithms::LogLevel level{
        static_cast<algorithms::LogLevel>(msgLevel() > 0 ? msgLevel() - 1 : 0)};
    info() << "Setting up algorithms::LogSvc with default level "</pre>
           << algorithms::logLevelName(level) << endmsg;</pre>
    logger->defaultLevel(level);
    logger->action(
         const std::string text = fmt::format("[{}] {}", caller, msg);
          if (l == algorithms::LogLevel::kCritical) {
            this->fatal() << text << endmsg;</pre>
          } else if (l == algorithms::LogLevel::kError) {
           this->error() << text << endmsg;</pre>
          } else if (l == algorithms::LogLevel::kWarning) {
           this->warning() << text << endmsg;</pre>
          } else if (l == algorithms::LogLevel::kInfo) {
           this->info() << text << endmsg;</pre>
          } else if (l == algorithms::LogLevel::kDebug) {
            this->debug() << text << endmsg;</pre>
          } else if (l == algorithms::LogLevel::kTrace) {
            this->verbose() << text << endmsg;</pre>
        });
    // set own log level to verbose so we actually display everything that is requested
    // (this overrides what was initally set through the OutputLevel property)
     pdateMsgStreamOutputLevel(MSG::VERBOSE);
  } else if (name == algorithms::GeoSvc::kName) {
    // Setup geometry service
    m_geoSvc = service("GeoSvc");
     if (!m_geoSvc) {
      error() << "Unable to locate Geometry Service. "</pre>
              << "Make sure you have GeoSvc in the right order in the configuration." << endmsg;</pre>
      return StatusCode::FAILURE;
    info() << "Setting up algorithms::GeoSvc" << endmsg;</pre>
    auto* geo = static_cast<algorithms::GeoSvc*>(svc);
                                         Juggler integration
    geo->init(m_geoSvc->detector());
```

What services does algorithms need?

er->action([this](const algorithms::LogLevel l, std::string_view caller, std::string_view msg) (b Link the logger to the Gaudi logger to the facult logger

Link the DD4hep GeoSvc to the Juggler GeoSvc



CHALLENGE 2: DATA STORE INTERACTIONS Towards a first prototype for algorithms

```
ClusteringAlgorithm = Algorithm<
  Input<edm4eic::ProtoClusterCollection,</pre>
        std::optional<edm4hep::SimCalorimeterHitCollection>>,
  Output<edm4eic::ClusterCollection,
         std::optional<edm4eic::MCRecoClusterParticleAssociationCollection>>>;
   ClusterRecoCoG : public ClusteringAlgorithm {
blic:
                 = ClusteringAlgorithm::Input;
using Input
                = ClusteringAlgorithm::Output;
using Output
using WeightFunc = std::function<double(double, double, double)>;
ClusterRecoCoG(std::string_view name)
   : ClusteringAlgorithm{name,
```

```
{"inputProtoClusterCollection", "mcHits"},
{"outputClusterCollection", "outputAssociations"}} {}
```

```
void ClusterRecoCoG::process(const ClusterRecoCoG::Input& input,
                             const ClusterRecoCoG::Output& output) {
  const auto [proto, opt_simhits] = input;
  auto [clusters, opt_assoc]
                                  = output;
  for (const auto& pcl : *proto) {
   auto cl = reconstruct(pcl);
    if (aboveDebugThreshold()) {
     debug() << cl.getNhits() << " hits: " << cl.getEnergy() / dd4hep::GeV <<</pre>
              << cl.getPosition().x / dd4hep::mm << ", " << cl.getPosition().y
              << cl.getPosition().z / dd4hep::mm << ")" << endmsg;
   clusters->push_back(cl);
```



- Needed to choose between (1) providing algorithms with a framework allocator, (2) going with a purely functional approach, or (3) passing pointers to already existing objects
- Chose (3) (tuple of pointers) as it significantly simplifies interactions with the frameworks
- Algorithm definition takes an Input and an Output type to define the signature of the :: process function
- Special cases for std::vector<T> (to handle multiple objects of the same type) and std::optional<T> (to handle optional data, e.g. MC truth info in reconstruction algorithms)







CHALLENGE 3: PROPERTIES Towards a first prototype for algorithms

edm4eic::MutableCluster reconstruct(const edm4eic::ProtoCluster&)

Property<double> m_sampFrac{this, "samplingFraction", 1.0}; Property<double> m_logWeightBase{this, "logWeightBase", 3.6}; Property<std::string> m_energyWeight{this, "energyWeight", "log"}; Property<std::string> m_moduleDimZName{this, "moduleDimZName", ""}; Property<bool> m_enableEtaBounds{this, "enableEtaBounds", true};

WeightFunc m_weightFunc;

const GeoSvc& m_geo = GeoSvc::instance();

ublic:

ClusterRecoCoG(const std::string& name, ISvcLocator* svcLoc) : A

virtual StatusCode configure() { setAlgoProp("samplingFraction", m_sampFrac.value()); setAlgoProp("logWeightBase", m_logWeightBase.value()); setAlgoProp("energyWeight", m_energyWeight.value()); setAlgoProp("moduleDimZName", m_moduleDimZName.value()); setAlgoProp("enableEtaBounds", m_enableEtaBounds.value()); return StatusCode::SUCCESS; Juggler integration



- Need a way to define properties for algorithms
- Ideally they should provide for a programatic way to deal with automatic initialization at the framework end (non-trivial)
- Currently choose a Gaudi-like Property<T> class that has run-time performance of a bare T, while providing an avenue for the framework to set the property
- Automatic handling may be possible in the future but outside the scope of this prototype implementation







EXAMPLE ALGORITHM INTEGRATION (JUGGLER) Towards a first prototype for algorithms

```
#include <JugAlgo/Algorithm.h>
#include <algorithms/calorimetry/ClusterRecoCoG.h>
#include "Gaudi/Property.h"
         Jug::Reco {
       AlgoBase = Jug::Algo::Algorithm<algorithms::calorimetry::ClusterRecoCoG>;
     ClusterRecoCoG : public AlgoBase {
 ublic:
  ClusterRecoCoG(const std::string& name, ISvcLocator* svcLoc) : AlgoBase(name, svcLoc) {}
  virtual StatusCode configure() {
    setAlgoProp("samplingFraction", m_sampFrac.value());
    setAlgoProp("logWeightBase", m_logWeightBase.value());
    setAlgoProp("energyWeight", m_energyWeight.value());
    setAlgoProp("moduleDimZName", m_moduleDimZName.value());
    setAlgoProp("enableEtaBounds", m_enableEtaBounds.value());
    return StatusCode::SUCCESS;
  Gaudi::Property<double> m_sampFrac{this, "samplingFraction", 1.0};
  Gaudi::Property<double> m_logWeightBase{this, "logWeightBase", 3.6
  Gaudi::Property<std::string> m_energyWeight{this, "energyWeight", "log"};
  Gaudi::Property<std::string> m_moduleDimZName{thi
                                                     "moduleDimZName"
  Gaudi::Property<bool> m_enableEtaBounds{this, "enableEtaBounds", false};
};
// NOLINTNEXTLINE(cppcoreguidelines-avoid-non-const-global-variables)
DECLARE_COMPONENT(ClusterRecoCoG)
                                             Juggler integration
```

Include the Juggler algorithms bindings and the actual algorithm implementation

Instantiate a Juggler algorithm based on the algorithms algorithm

Minimal Gaudi boilerplate

Only real code: handle properties





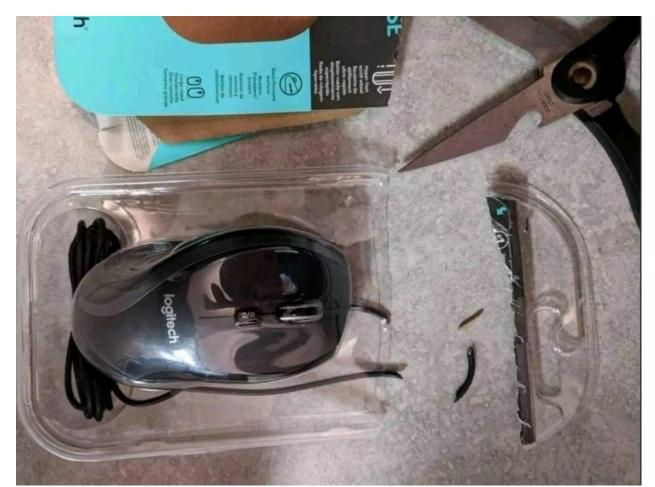


CHALLENGE 4&5: DUPLICATION, AND TESTING Towards a first prototype for algorithms

- Avoided duplication for:
 - Data store interaction without duplication (handled automagically by JugAlgo::Algorithm in prototype)
 - Service interactions without duplication (handled by JugAlgo::AlgoServiceSvc)
- So far did not avoid duplication in Property handling (possible source of errors, should be addressed in future)
- Need to define testing strategy. While integration tests with frameworks are useful, stand-alone unit tests of the library algorithms would be valuable







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OUTLOOK Towards a first prototype for algorithms

- Library infrastructure code ready
- Gaudi bindings being tested
- Once prototype testing complete (soon), will move to finish proof-of-concept by providing JANA2/EICRecon bindings (together with Dmitry Romanov)
- Then can start migrating ongoing development work (e.g. on tracking with ACTS) into algorithms
- Anticipate a first pre-release version on GitHub soon (~week)
- Explore collaboration with Key4hep





