



# Front-End Evaluation for Pixelated Liquid-Argon Particle Detectors

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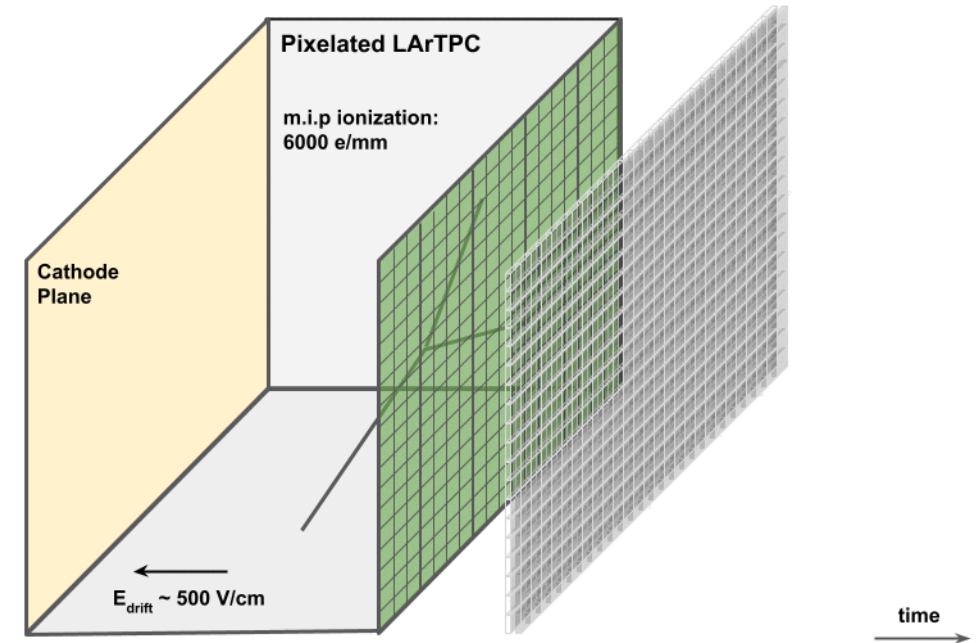
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# Introduction

- Time projection chambers detect spatial and temporal data of an event in order to reconstruct a 3-dimensional particle trajectory or interaction
- Modern TPC's utilize multi-wire planes held at a high voltage relative to the cathode
- The volume of the detector is filled with a charge sensitive bath (Liquid Argon for example)
- Q-Pix Collaboration aims to develop a pixelated self-triggering ASIC
- Front-end Investigation at Fermilab
  - Dynamic Vision Sensing
  - Charge Replenishment



# Q-Pix and 65nm

- Custom CMOS models at LAr temperatures
- Custom standard cell library
- IP extensively tested and validated at LAr temperatures
  - SLVDS Rx/Tx
  - PLL
  - Bandgap Reference
  - POR
  - 1.28Gbps line driver
  - Serializer
- Long-term availability and investment towards models and libraries
- Process for LHC upgrades
- Aligns with other experiments (MIDNA – CCD readout)

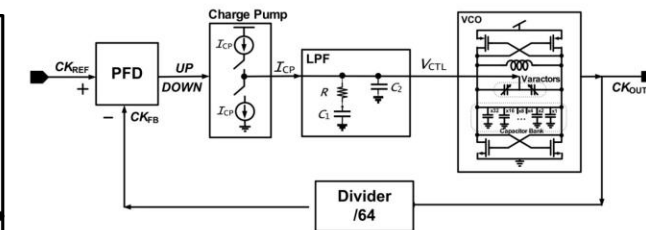
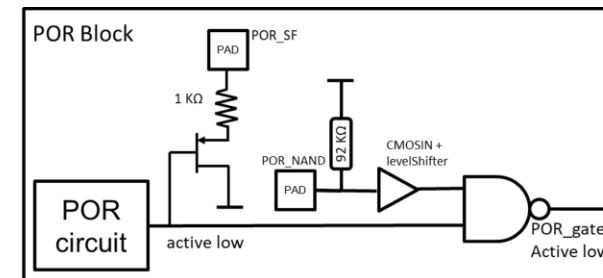
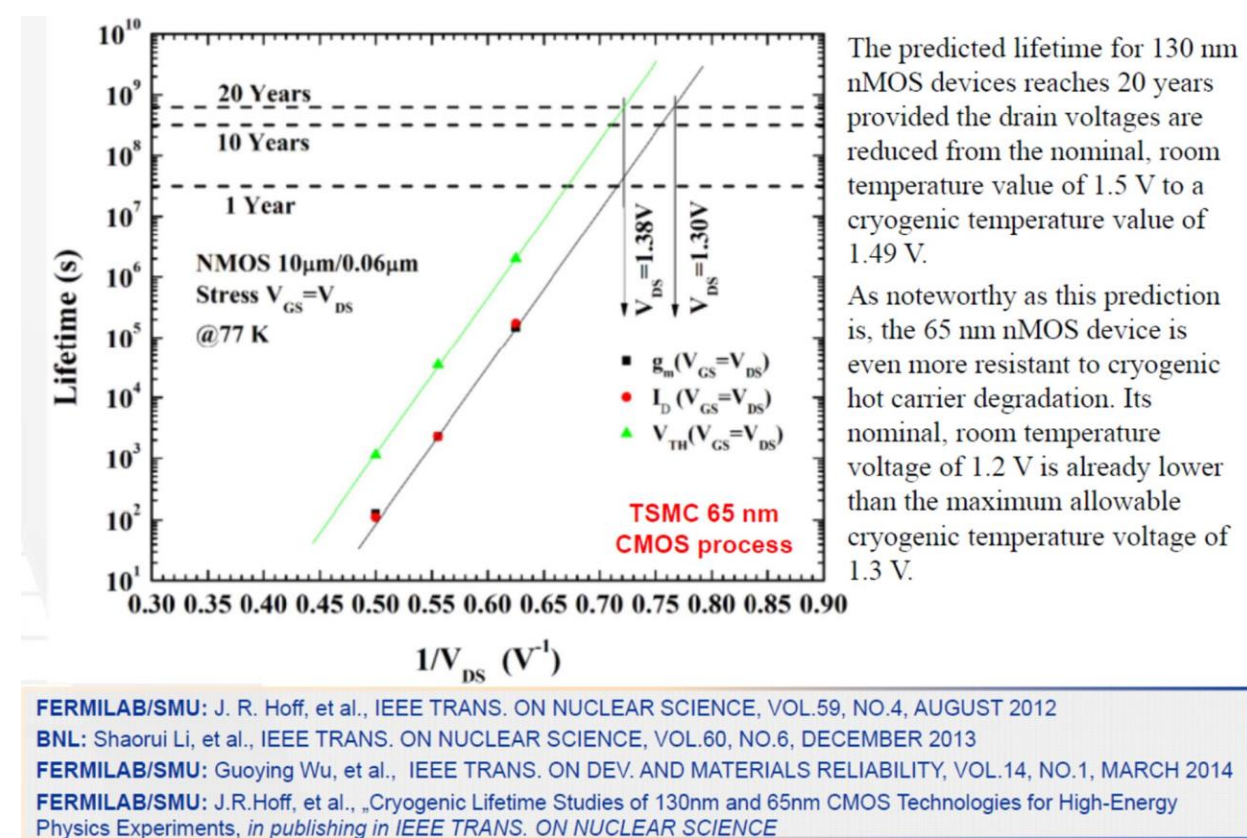
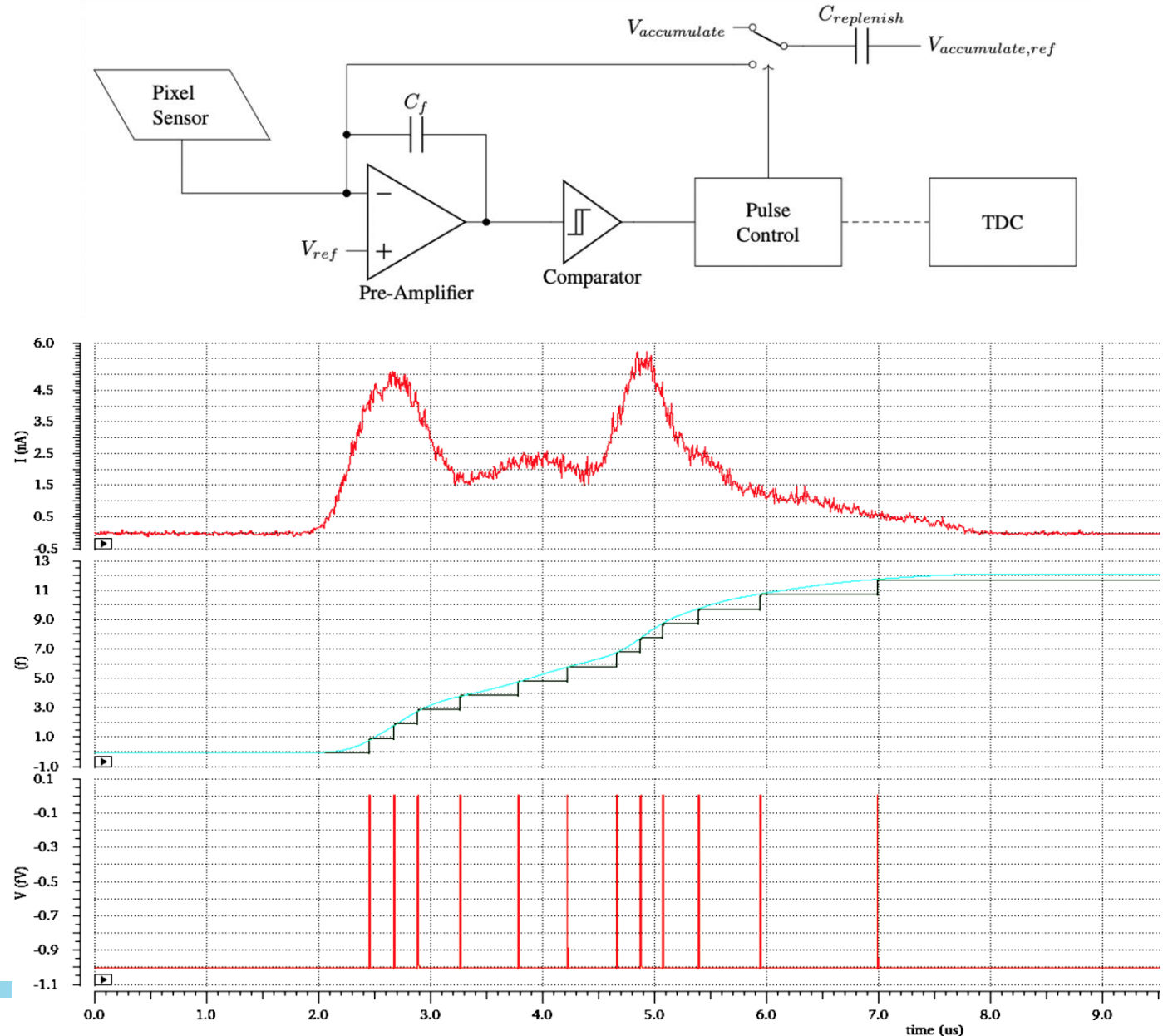


Fig. 4. The block diagram of a single path Phase Locked Loop (PLL)

# Charge Replenishment Front-End

- Accumulation
- Replenishment
- Holes and Electron calibration
- Output of front-end is a time-stamp of each packet of detected charge
- Reset time delays allow reconstruction of event



# Performance & Future Work

- Simulation shows
  - ENC(@ 27 C):  $\sim 385\text{ e}^-$
  - ENC(@ -189 C):  $\sim 50\text{ e}^-$  @ 3pF pixel capacitance
  - Front-end readout limited to 10uW per channel
- 65nm 16 Channel Prototype
- Scale to full-chip with periphery and digital readout

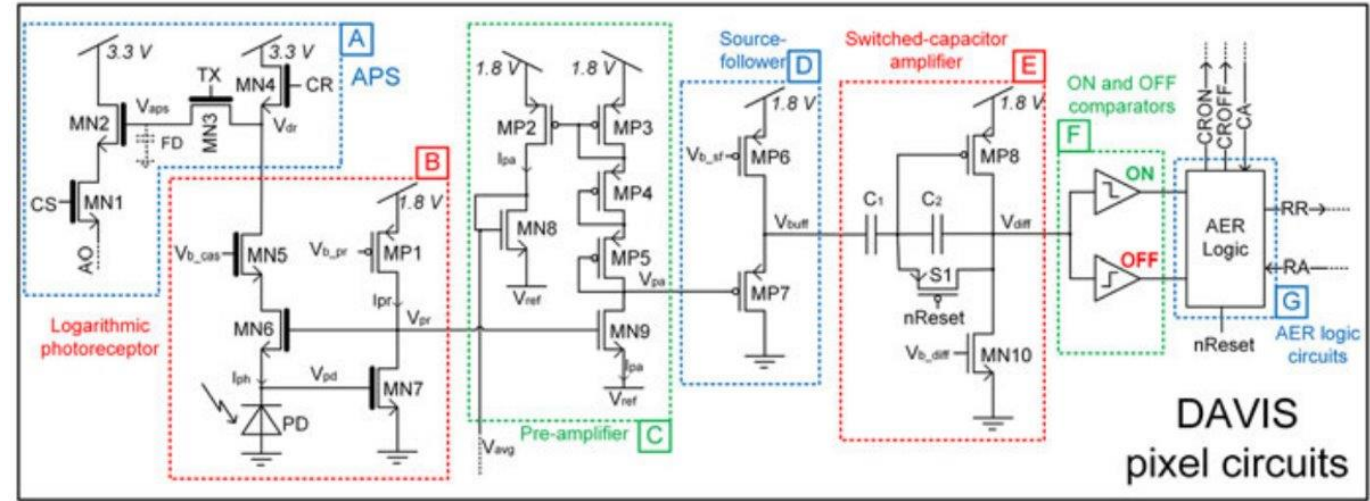
Front-end Block	Power (@ 1.2V)
Integrator + Leakage Compensator	<9.0 uW
Comparator	0.5 uW
Replenishment Control	<100 pW
<b>Total</b> (per pixel)	<10 uW



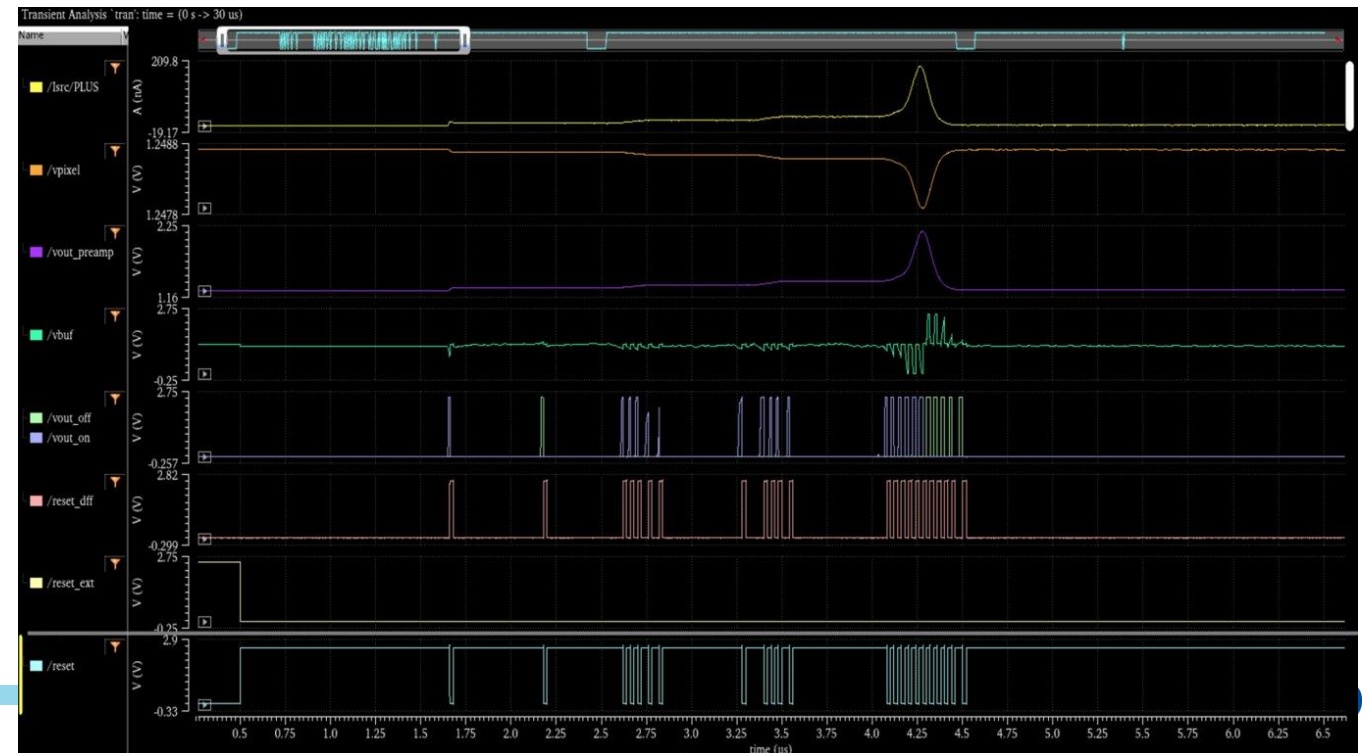
# Dynamic Vision Front-End

- Dynamic Vision Sensor (DVS)
- Used for detecting changes in light intensity
- Potential candidate for photon detection front-end

$$\Delta V_{integ} = \left(-\frac{C_i}{C_f}\right)(\Delta i_{pix} R_f) = \left(-\frac{C_i}{C_f}\right)\left(\frac{dq_{pix}}{dt} R_f\right)$$



<https://ieeexplore.ieee.org/document/8094907>



# Summary

- Investigated a charge sensitive front-end for a 65nm process
- Investigated dynamic vision for a 65nm process
- Looking for collaborators for partnering on chip submissions



# Thank You

