

Constant-Tune Cyclotrons

FFA Workshop 2023

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Introduction – Isochronous condition

Isochronous condition:

$$\mathcal{R} = \beta \mathcal{R}_\infty$$

where \mathcal{R} is the circumference of the closed orbit divided by 2π , and \mathcal{R}_∞ is a constant.

The integral of the relative error can never exceed the ratio between a quarter of the rf period and the total time of flight from injection: on the order of 10^{-4} or less, for most cyclotrons. Stray away from this strict condition, and no more beam will come out of the machine.

Introduction – Isochronous field distribution

There is no analytical solution* for an isochronous $B(r, \theta)$. Producing an isochronous field distributions is the job of the magnet designer: iterative process that takes many iterations, and on the order of days.

*Except for the case $B(r)$, which is out of question: unstable vertical motion.

Introduction – Isochronous field distribution

For lack of an analytical formula, there is a way to generate a perfectly isochronous (and Maxwellian) field distribution in a split second using a trick I presented at the cyclotron conference in 2019 [[Planche, 2019](#)].

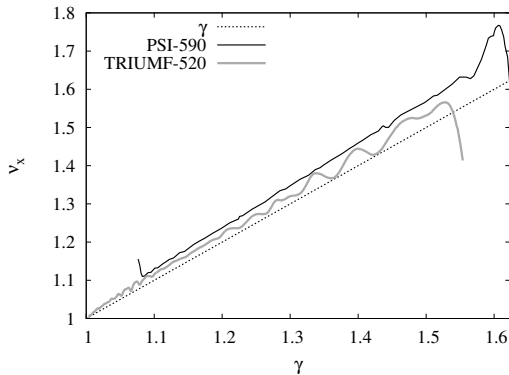
The trick, in a nutshell, is to start from the geometry of a set of **closed orbits** to derive the **tunes** and the **field** distribution.

closed orbits → **tunes** → **field**

which is circular permutation of the more conventional order in which things are normally done. The work I am presenting here is depends heavily on this trick.

Introduction – $\nu_x \approx \gamma$?

The two “most-relivistic” cyclotrons ever built:

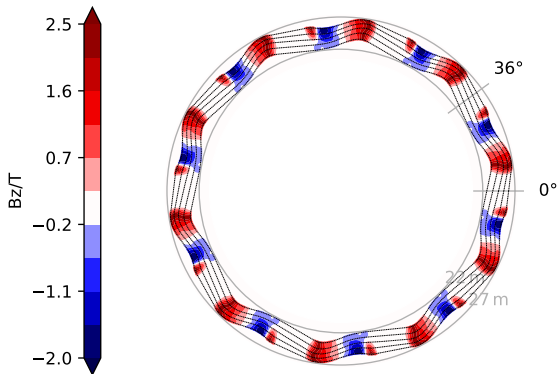


In a cyclotron, does ν_x necessarily follows γ ?

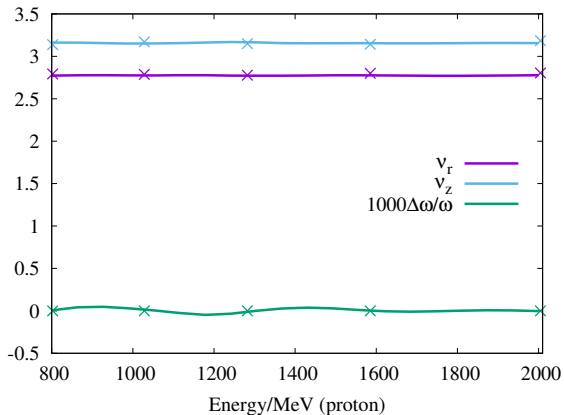
Are higher-energy cyclotrons doomed to cross many resonances?

Introduction – constant-tune cyclotrons

I have shown last year that there exists isochronous fixed field distributions (consistent with Maxwell's equations) that produce constant vertical and horizontal tunes. I had for instance shown the example of a 2 GeV proton cyclotron:



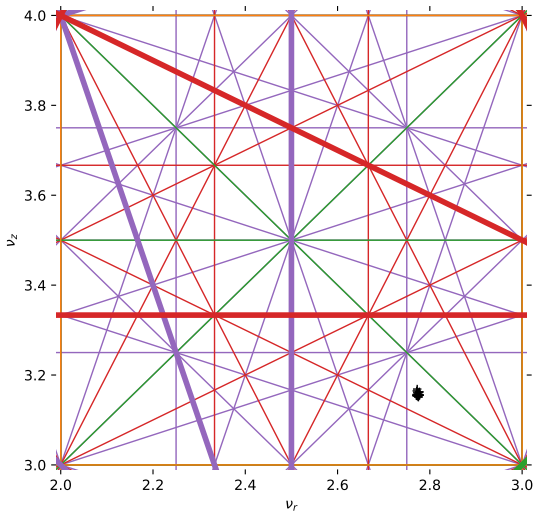
Introduction – constant-tune 2 GeV cyclotron



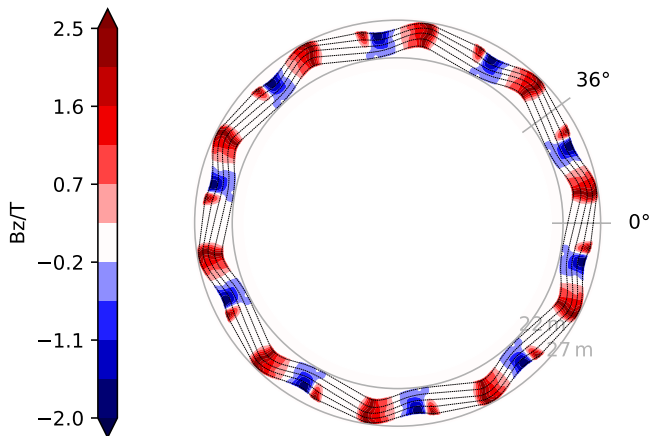
Solid lines: tracking result using CYCLOPS [[Gordon, 1984](#)].

Crosses: from the geometry of the closed orbits using `from_orbit`.

Introduction – constant-tune 2 GeV cyclotron

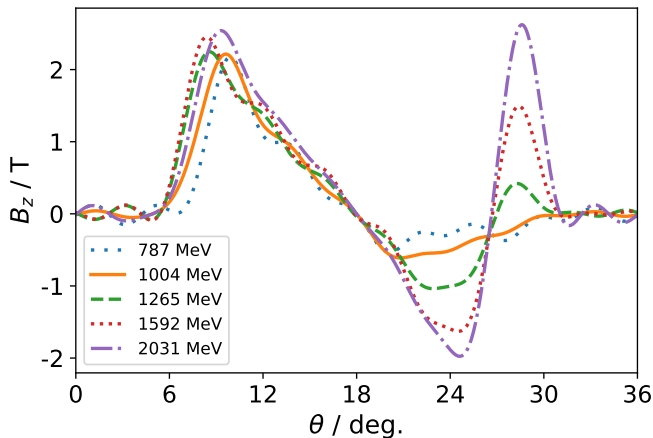


Introduction – constant-tune 2 GeV cyclotron



$r(a, \theta)$ is parametrized so as to have drift sections between sectors.

Introduction – constant-tune 2 GeV cyclotron



Magnetic field plotted along 5 closed orbits.

Introduction. . . finally getting to the point

All this work has been written up in an article that is part of a recent ICFA special issue on cyclotrons [[Planche, 2023](#)], if you are interested.

The question that remains is: **how can one use this technique in practice to design accelerator magnets?**

How to couple `from_orbit` with OPERA-3D

I needed to start from less arbitrary, more practical orbits.

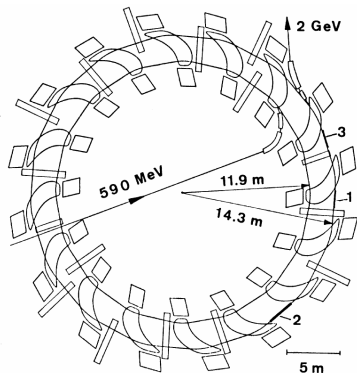
Process:

- 1 Get a field map from some initial 3-D magnet model (OPERA-3D).
- 2 Track particles to find the corresponding closed orbits (CYCLOPS).
- 3 Use `from_orbit` to figure out what transformation (shift, scale) need to be applied to these orbits to achieve the desired tunes.
- 4 Applying the same transformations to the magnet geometry.
- 5 Iterate.

I went on a bit of wild-goose chase to automate fully the construction and post-processing of OPERA-3D model. The result is a python library developed in collaboration with Shinji's group (ISIS Neutron and Muon Source) and my post-doc Huiwen, **see Ta-Jen's talk on Thursday**.

Proof-of-principle 3D magnet design

I chose to design a magnet for W. Joho 2 GeV cyclotron proposal:
ASTOR [Joho, 1983].



and to start with designing so that only ν_y is constant at first.

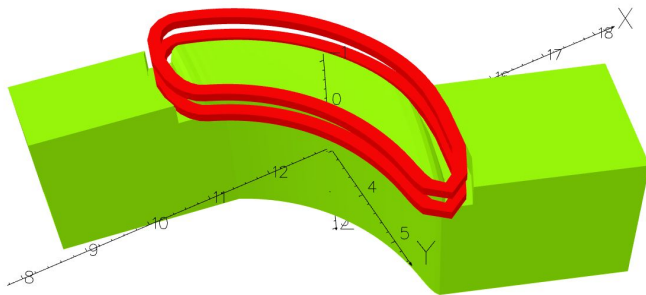
Proof-of-principle 3D magnet design

For each iteration:

- I run OPERA-3D, and get a field map.
- With this field, I run CYCLOPS [[Gordon, 1984](#)] to get a set of closed orbits.
- With these orbits, I run `from_orbit` and shift every orbit azimuthally until I get a constant vertical tune.
- I extract a new magnetic field profile, and a new spiral angle profile, and adjust the magnet gap height and spiral shape accordingly.

Proof-of-principle 3D magnet design

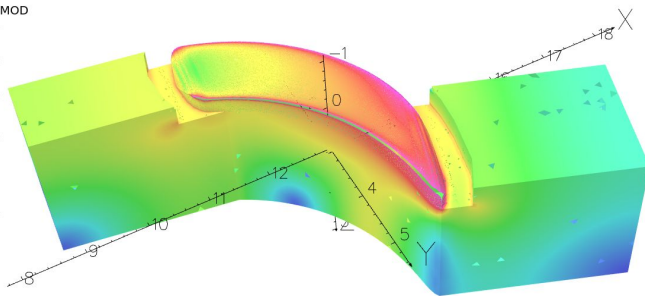
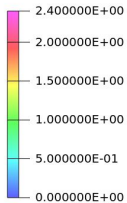
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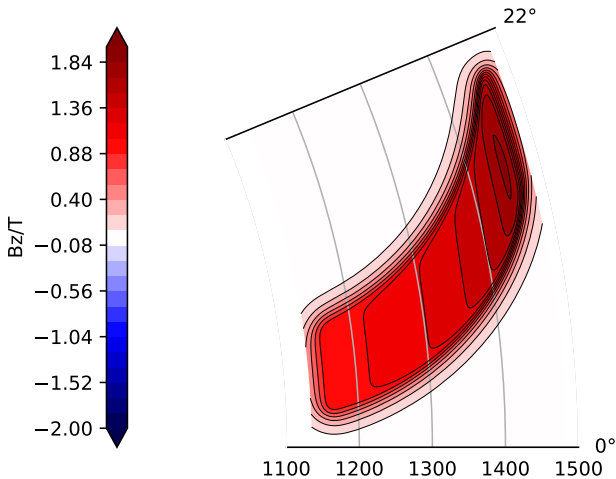
Proof-of-principle 3D magnet design

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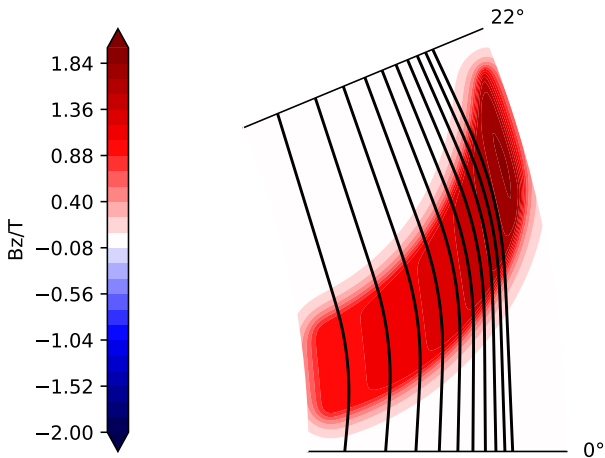
Surface contours: BMOD



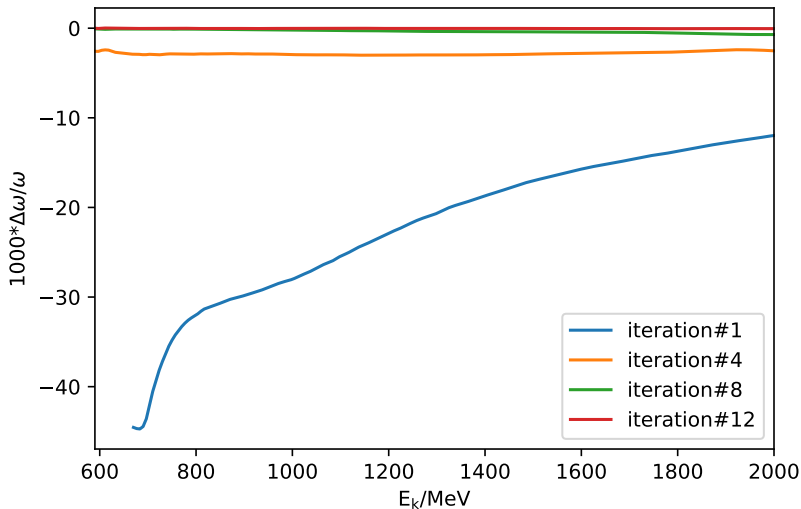
Proof-of-principle 3D magnet design



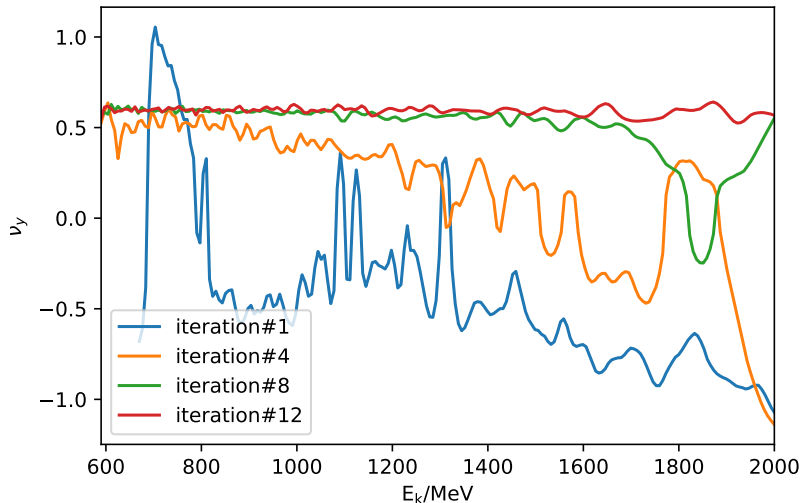
Proof-of-principle 3D magnet design



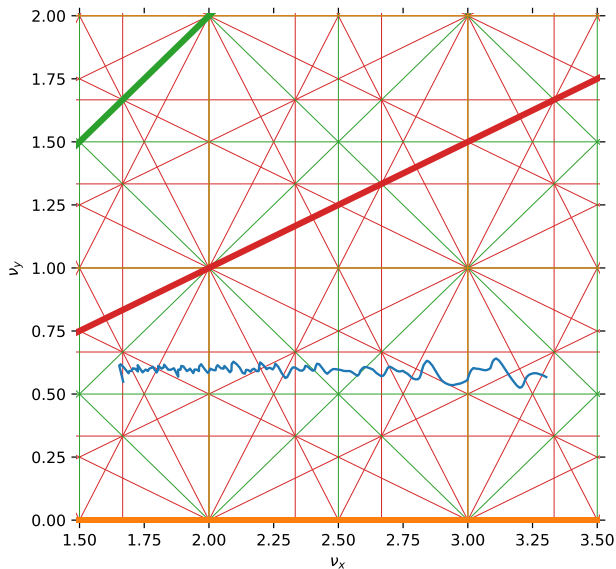
Proof-of-principle 3D magnet design



Proof-of-principle 3D magnet design



Proof-of-principle 3D magnet design



Future work

Next step is to design for both ν_x and ν_y constant at the same time. This will require a reversed bend.

Conclusion

`from_orbit` can be coupled with a 3-dimensional finite element code like OPERA-3D to design fixed-field accelerator magnets.

It allows the design to converge extremely rapidly. I am using it to design cyclotron magnets, but the technique can be applied to design any FFA magnet (not VFFA though).

Thank you

Thank you for your attention

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