Boosting Loop Amplitudes and Event Generation with Precision Networks

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Anja Butter, LPNHE/ITP







From Theory to Data and Back



Goal

- \bullet



• Understand full dataset from 1st principles Precision measurements of the SM • Find signs of new physics (eg dark matter) • **Huge** dataset ~1Pb/s before trigger selection



- Facing **25 times** the amount of data
- What do we need to understand the data? (*read:* find new physics)



- Unfolding
- MEM
- Anomaly detection •
- Uncertainty treatment for ML methods

How can ML help?

Monte carlo event generation

1. Generate phase space points

 \rightarrow set of four-momenta p_i

2. Calculate event weight



3. Unweighting

keep events with $\frac{W_i}{\dots} > r \in [0,1]$ *w*max

Phase space mapping

Bottlenecks

- Slow matrix element calculation Complexity grows exponentially with
 - # final state particles
 - Precision (LO, NLO, NNLO, ...)

Low **unweighting** efficiency 2.

• Discard most events if $w_i \ll w_{max}$ • Optimize phase space mapping

$$\Rightarrow J(p_i(r)) = (f \times \mathscr{M})^{-1}$$



Reducing variance in exact calculations

ML for Amplitudes

Multi-loop calculations with NNs

Precision predictions based on loop diagrams



Analytic expression for loop amplitude

$$G = \int_{-\infty}^{\infty} \left(\prod_{l=1}^{L} \frac{\mathrm{d}^{D} k_{l}}{i\pi^{\frac{D}{2}}} \right) \prod_{j=1}^{N} \frac{1}{(q_{j}^{2} - m_{j}^{2} + i\delta)^{\nu_{j}}}$$
$$= \int_{0}^{1} \prod_{j=1}^{N-1} \mathrm{d} x_{j} x_{j}^{\nu_{j}-1} \frac{U^{\nu - (L+1)D/2}}{F^{\nu - LD/2}} = \int_{0}^{1} \prod_{j=1}^{N-1} \mathrm{d} x_{j} I(\vec{x})$$
Rewrite with

Feynman parameters

Still contains singularities

Multi-loop calculations with NNs

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Feynman parameters

Still contains singularities

Solved by contour deformation due to Cauchy's theorem

$$\int_{0}^{1} \prod_{j=1}^{N} \mathrm{d}x_{j} I(\vec{x}) = \int_{0}^{1} \prod_{j=1}^{N} \mathrm{d}x_{j} \det\left(\frac{\partial \vec{z}(\vec{x})}{\partial \vec{x}}\right) I(\vec{z}(\vec{x}))$$



Optimal parametrization = minimal variance





Integration with normalizing flows



$$\frac{\partial \vec{z}(\vec{x}_{(i)})}{\partial \vec{x}_{(i)}} \right) I(\vec{z}(\vec{x}_{(i)})) - \langle I \rangle$$

Multi-loop calculations with INNs Profiting from the Jacobian

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Precision predictions based on loop diagrams



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Optimal parametrization = minimal variance



R. Winterhalder, et al. [2112.09145]

Approximation with Regression

ML for Amplitudes

Limitations of a standard network

Example

 $gg \rightarrow \gamma \gamma g(g) @LO$

90k training amplitudes 870k test amplitudes

Standard approach

Training data

T = (phase space points x, Amplitudes A'(x))

Loss

$$\mathscr{L} = (A'(x) - NN(x))^2$$

PROBLEM: For limited data there is **no unique solution**

 \rightarrow Need better formulation of the problem

 \rightarrow Find p(A | x, T) (from now on x is implicit)

Capturing probabilities with Bayesian networks

$$p(A) = \int dw \ p(A \mid w) p(w \mid T) \approx \int dw \ p(A \mid w) q(w)$$

Bayesian network

Building the loss function

Approximate q(w) by minimizing KL divergence

 $\mathscr{L}_{BNN} = \mathrm{KL}[q(w), p(w \mid T)]$ $= \left[dw \ q(w) \ \log \frac{q(w)}{p(w \mid T)} \right]$ $= \int dw \ q(w) \ \log \frac{q(w)p(T)}{p(w)p(T|w)}$ $= \operatorname{KL}[q(w), p(w)] - \int dw \ q(w) \ \log p(T|w)$ 2 Gaussian prior Gaussian uncertainty $\frac{\sigma_q^2 - \sigma_p^2 + (\mu_q - \mu_p)^2}{2\gamma} + \log \frac{\sigma_p}{\sigma_q}$ $\frac{\left|\bar{A}_{j}(\omega) - A_{j}^{(\text{truth})}\right|^{2}}{2\sigma_{\text{model},j}(\omega)^{2}} + \log\sigma_{\text{model},j}(\omega)$

Results - out of the box

+ Deviations at 1 percent level

Performance worse for rare points with large amplitudes (collinear)

Roughly Gaussian but enhanced tails

Enforce training on samples with $\Delta A > 2\sigma$ \rightarrow include them 5 times in each epoch \rightarrow Repeat 4 times

No change in performance

Loss boosting

Tails reproduced for training data Improvement for test data

Performance boosting

Enforce training on 200 samples with largest uncertainty σ_{tot} \rightarrow include them +3 times in each epoch \rightarrow Repeat 20 times

largest 100% A_{NN} 140 $gg \rightarrow \gamma \gamma g$ largest 1% A_{NN} 120 process-boosted largest 0.1% A_{NN} BNN training normalized 8 ______8 40 20 0 -0.04-0.020.02 0.04 0.00 $\Delta^{(train)}$ + overflow bin

Significant improvement in performance

Precision networks for loop amplitudes

1. Normalizing flows can reduce variance of integration in exact loop calculations

2. Aproximating amplitudes: Bayesian networks provide **uncertainty estimates Boost** network performance for precision or calibration

Monte carlo event generation

1. Generate phase space points

2. Calculate event weight

$$w_{\text{event}} = f(x_1, Q^2) f(x_1, Q^2) \times \mathcal{M}(x_1, x_2, p_1, \dots, p_n) \times J(p_i(r))$$

$$\int \\ \text{PDF} \qquad \text{Matrix element} \qquad \text{Phase space mapping}$$

keep events wi

 \rightarrow set of four-momenta p_i

3. Unweighting

$$\operatorname{ith} \frac{w_i}{w_{\max}} > r \in [0,1]$$

ML for phase space generation

Normalizing flows Invertible networks for complex transformations

- + Bijective mapping
- + Tractable Jacobian $\rightarrow p_x(x) = p_z(z) \cdot J_{NN}$
- + Fast evaluation in both direction

Training on density t(x) \rightarrow Minimize difference

$$\mathcal{L} = \log p_x(x)/t(x)$$
$$= \log p_z(z(x)) J_{NN}/t(x)$$

 $\mathcal{L} = \log p(\theta | x)$ $= \log p(z | \theta) + \log J_{NN} + p(\theta)$

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Training on density t(x) \rightarrow Minimize difference

> $\mathscr{L} = \log p_x(x) / t(x)$ $= \log p_z(z(x)) J_{NN} / t(x)$

Training on samples *x* \rightarrow Maximize the log-likelihood

$$\mathcal{L} = \log p(\theta | x)$$
$$= \log p(z | \theta) + \log J_{NN} + p(\theta)$$

- + Bijective mapping
- + Tractable Jacobian $\rightarrow p_x(x) = p_z(z) \cdot J_{NN}$
- + Fast evaluation in both direction

Evaluation

Training on samples *x* \rightarrow Maximize the log-likelihood

 $\mathcal{L} = \log p(\theta \mid x)$ $= \log p(z | \theta) + \log J_{NN} + p(\theta)$

Putting flows to work **Event generation**

• Train normalizing flow on 4-momenta • Include symmetries in feature representation • Excellent performance for direct output

• Extend setup vor variable jet multiplicity

Challenges for normalizing flows

- Narrow features
- Topological holes (eg ΔR cuts)
 - no bijective mapping possible
 - can only be approximated

Reweighting for Precision

Classifier loss

$$\mathscr{L} = -\sum_{x \sim p_{data}} \log(D(x)) - \sum_{x \sim p_{INN}} \log(1 - D(x))$$
$$= -\int dx \, p_{data}(x) \, \log(D(x)) + p_{INN}(x) \, \log(1 - D(x))$$

• Upon convergence obtain **reweighting factor**

$$\Rightarrow \frac{p_{data}(x)}{p_{INN}(x)} = \frac{D(x)}{1 - D(x)} = w_D$$

• Use classifier feedback to enhance gradients $\left(\frac{\psi(x;c)^2}{2} - \log J(x)\right)$ $\mathscr{L}_{\text{DiscFlow}} \approx \begin{bmatrix} dx & w_D(x)^{\alpha} P(x) \end{bmatrix}$ reweighted truth

 \Rightarrow Reduces range of reweighting factors

Putting flows to work Event generation

- Basis: INN
 - Phase space symmetries in architecture
- Control via classifier D $\frac{p_{\text{truth}}(x)}{p_{\text{INN}}(x)} = \frac{D(x)}{1 - D(x)}$
- Precision via reweighting
 - Correct deviations of p_{INN}
- ➡ Uncertainty estimation via Bayesian NN
- ➡ Uncertainty propagation via conditioning

- Highdimensional
- Bin independent
- $\Box Statistically well defined 26$

cINN unfolding

Given a reconstructed event: What is the probability distribution at particle level?

Inverting inclusive distributions

$pp > WZ > q\bar{q}l^+l^- + ISR \rightarrow 2/3/4$ jet events

Evaluate exclusive 2/3/4 jet events

Migh-dimensional

M. Bellagente et al. [2006.06685]

M Bin-independent

☐ Statistically well defined ?

Event-wise unfolding

Statistically well defined

No deterministic mapping! Check calibration of probability density for individual event unfolding

Migh-dimensional

M. Bellagente et al. [2006.06685]

M Bin-independent

Beyond unfolding: Enabling the MEM 2210.00019

Matrix element method is based on untractable likelihood

$$p(x_{\text{reco}}|\alpha) = \int dx_{\text{hard}} \underbrace{p(x_{\text{hard}}|\alpha)}_{\text{diff. CS}} \underbrace{p(x_{\text{reco}}|x_{\text{hard}},\alpha)}_{\text{estimate with network}}$$

Problem: integration over full phase space of the hard scattering Solution: Use unfolding cINN to sample *x*_{hard}

$$p(x_{\text{reco}}|\alpha) = \left\langle \frac{1}{q(x_{\text{hard}})} \ p(x_{\text{hard}}|\alpha) \ p(x_{\text{reco}}|x_{\text{hard}}, \alpha) \right\rangle$$

Single Higgs production

ML4LHC Event generation

New data are currently on their way...