Vertex EDM

Joe Osborn, BNL June 8, 2023 Current Vertex Object

```
## Vertexing
edm4eic::Vertex:
 Description: "EIC vertex"
 Author: "W. Armstrong, S. Joosten, based off EDM4hep"
  Members:
                                       // Boolean flag, if vertex is the primary vertex of the event
   - int32_t
                         primary
                                       // Chi-squared of the vertex fit
                         chi2
    float
                         probability // Probability of the vertex fit
    float
                         position
                                       // [mm] position of the vertex.
   - edm4hep::Vector3f
   ## this is named "covMatrix" in EDM4hep, renamed for consistency with the rest of edm4eic
                         positionError // Covariance matrix of the position
   - edm4eic::Cov3f
                         algorithmType // Type code for the algorithm that has been used to create the vertex - check/set the colle
   - int32_t
   ## Additional parameter not in EDM4hep: vertex time
   float
                                       // Vertex time
                         time
  VectorMembers:
                                       // Additional parameters related to this vertex - check/set the collection parameter "Vertex
    float
                         parameters
 OneToOneRelations:
   ## @TODO: why one and not multiple particles?
   - edm4eic::ReconstructedParticle associatedParticle // reconstructed particle associated to this vertex.
```

- Current vertex object in edm4eic that is created at end of vertexing algorithm IterativeVertexFinder
- Missing some notable pieces of data, and in any case does not match the Acts vertex EDM well

Current Vertex Object

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```

- What is "probability of the vertex fit?" Acts returns no such object, unless this is referring to the NDF of the fit (this is currently stored in this object)
- No uncertainty on the time why not just make this a 4D vector with a complete 4D covariance matrix?
- No way to associate which reconstructed tracks belong to a vertex
- Do we need an "algorithmType" and 32 bit integer for a boolean noting whether or not the vertex is primary?

Proposal

edm4eic::Vertex

```
edm4eic::Vertex:
  Description: "EIC vertex"
  Author: "J. Osborn"
  Members:
                                        // Boolean flag, if vertex is the primary vertex of the event
    - bool
                          primary
                          chi2
                                        // Chi-squared of the vertex fit
    - float

    float

                          ndf // NDF of the vertex fit

    edm4hep::Vector4f fullPosition

                                            // [mm] position + time t0 of the vertex.
    ## this is named "covMatrix" in EDM4hep, renamed for consistency with the rest of edm4eic
                          fullPositionError // Covariance matrix of the position
     edm4eic::Cov4f
  VectorMembers:
     - float
                                        // Additional parameters related to this vertex - check/set the collect
                          parameters
" for the parameters meaning.
  OneToManyRelations:
     - edm4eic::ReconstructedParticle associatedParticles // reconstructed particles associated to this vertex.
```

- Vertex object should contain:
 - 4 vector (position, t₀)
 - Full 4D covariance to include timing information
 - χ² and NDF
 - Pointers to the reconstructed tracks associated to a vertex (or some way to relate tracks to vertex)
- What else?

Acts::Vertex

```
private:
    Vector4 m_position = Vector4::Zero();
    SymMatrix4 m_covariance = SymMatrix4::Zero();
    std::vector<TrackAtVertex<input_track_t>> m_tracksAtVertex;
    double m_chiSquared = 0.; // chi2 of the fit
    double m_numberDoF = 0.; // number of degrees of freedom
```

Proposal

- We also need to consider how truth vertices will be handled, especially with the implementation of background
- As of now there is no way to directly evaluate the vertexing performance other than comparing MCParticle vertices to the reconstructed vertex
 - This will be very cumbersome soon and is not a long term solution
- Do we need a truth vertex object? Would it be useful for keeping track of backgrounds?
 - e.g. truth vertex might have a flag for what type of event it is associated to (primary, beam-gas, synchrotron, something else...
 - Truth vertex inherently needs less information, so would offer some memory savings (e.g. truth vertex does not have covariance, χ^2 , etc.

Thoughts?