

ePIC MPGDs Angular Resolution

Matt Posik
Temple University

❑ Role of MPGDs in ePIC

1. Additional hit points
2. Fast timing hits for pattern recognition
- 3. Provide precision hit point over large angular range for PID detectors (~ 1 mrad)**

❑ **Study Goal:** Determine spatial resolution needed for outer MPGD layer to meet PID angular resolution requirement of 1 mrad

- Understand central rapidity first before moving out to larger rapidity where there is more material and shallower angles where interoperation can be more complicated
- Access angular resolution via multiple scattering calculations, and two simulation assessments (Method 1 and Method 2)

Currently, not all information is in hand for the tracking working group to make a definite conclusion on the needed MPGD spatial resolution to meet PID angular resolution.

However, what we have studied...

□ Use ePIC simulation material to calculate multiple scattering near $\eta = 0.175$, with assumptions:

- Treat cumulative materials as one layer - an actual tracking algorithm will handle this differently
- $\beta = c = z = 1$
- Use PDG θ_0 formula

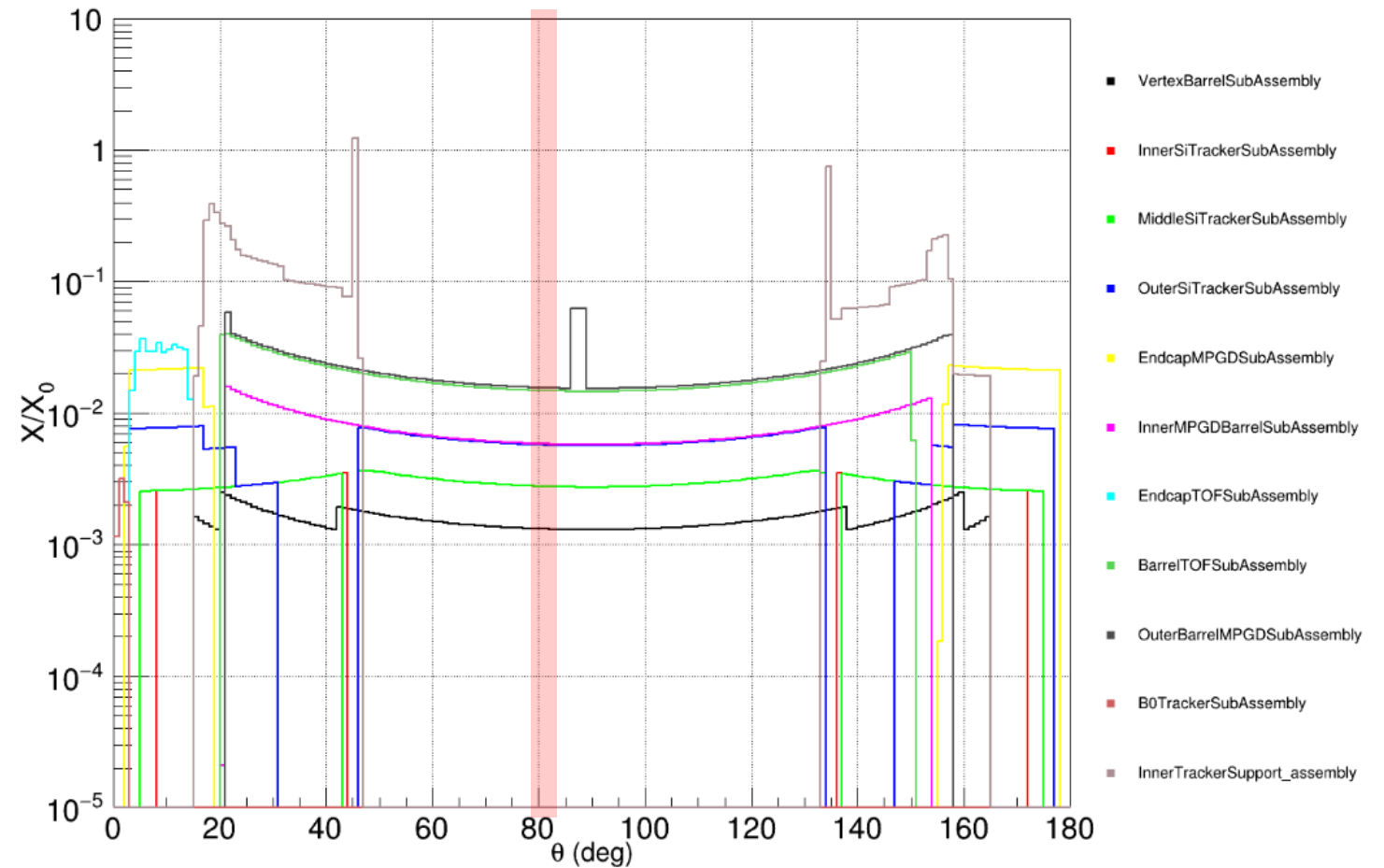
$$\theta_0 = \theta_{\text{plane}}^{\text{rms}} = \frac{1}{\sqrt{2}} \theta_{\text{space}}^{\text{rms}},$$

$$\theta_0 = \frac{13.6 \text{ MeV}}{\beta c p} z \sqrt{\frac{x}{X_0}} \left[1 + 0.088 \log_{10} \left(\frac{x z^2}{X_0 \beta^2} \right) \right]$$

$$= \frac{13.6 \text{ MeV}}{\beta c p} z \sqrt{\frac{x}{X_0}} \left[1 + 0.038 \ln \left(\frac{x z^2}{X_0 \beta^2} \right) \right]$$

Computed near $\theta = 80^\circ = \eta = 0.175$

	x/X_0
Full Tracker	0.0504
No outer MPGD Barrel	0.0344
Si Only	0.0135



[Shyam: Tracking WG](#)

- Use ePIC simulation material to calculate multiple scattering near $\eta = 0.175$, with assumptions:
 - Treat cumulative materials as one layer - an actual tracking algorithm will handle this differently
 - $\beta = c = z = 1$
 - Use PDG θ_0 formula

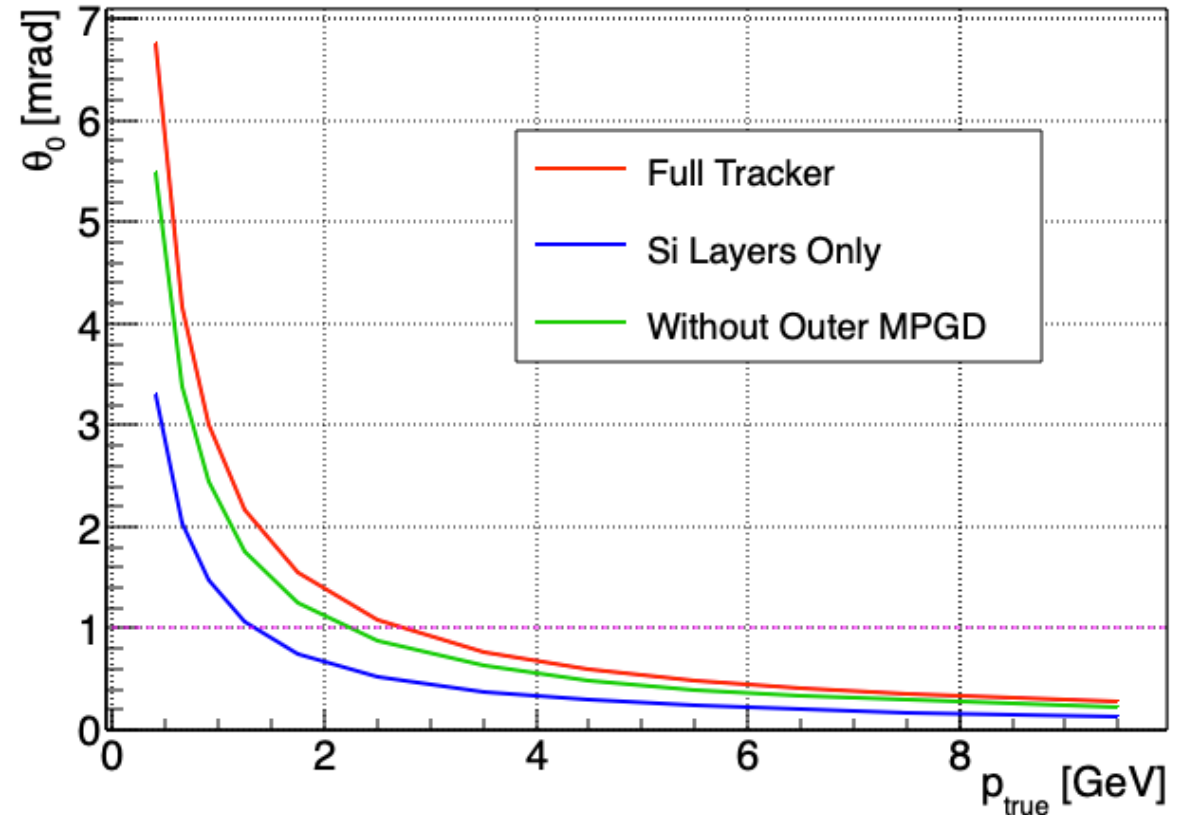
$$\theta_0 = \theta_{\text{plane}}^{\text{rms}} = \frac{1}{\sqrt{2}} \theta_{\text{space}}^{\text{rms}},$$

$$\theta_0 = \frac{13.6 \text{ MeV}}{\beta c p} z \sqrt{\frac{x}{X_0}} \left[1 + 0.088 \log_{10} \left(\frac{x z^2}{X_0 \beta^2} \right) \right]$$

$$= \frac{13.6 \text{ MeV}}{\beta c p} z \sqrt{\frac{x}{X_0}} \left[1 + 0.038 \ln \left(\frac{x z^2}{X_0 \beta^2} \right) \right]$$

Computed near $\theta = 80^\circ = \eta = 0.175$

	x/X_0
Full Tracker	0.0504
No outer MPGD Barrel	0.0344
Si Only	0.0135



These calculations are for $\eta = 0.175$ and entail simplifying assumptions.

ePIC Simulation Angular Resolution Definition: Method 1

- Agreed upon method between tracking and PID. ([meeting page](#))
- DIRC photon propagation turned off and volume made sensitive to provide “truth” reference hit
- Use position projected point vectors of **projected track point (H1)** and **nearest DIRC hit (H2)** to obtain angles:

- Projected Point (x,y,z) hits $\rightarrow \theta_{proj}, \phi_{proj}$

- DIRC Point (x,y,z) hits $\rightarrow \theta_{dirc}, \phi_{dirc}$

- Angular differences are:

- $\theta_{proj} - \theta_{dirc}$

- $\phi_{proj} - \phi_{dirc}$

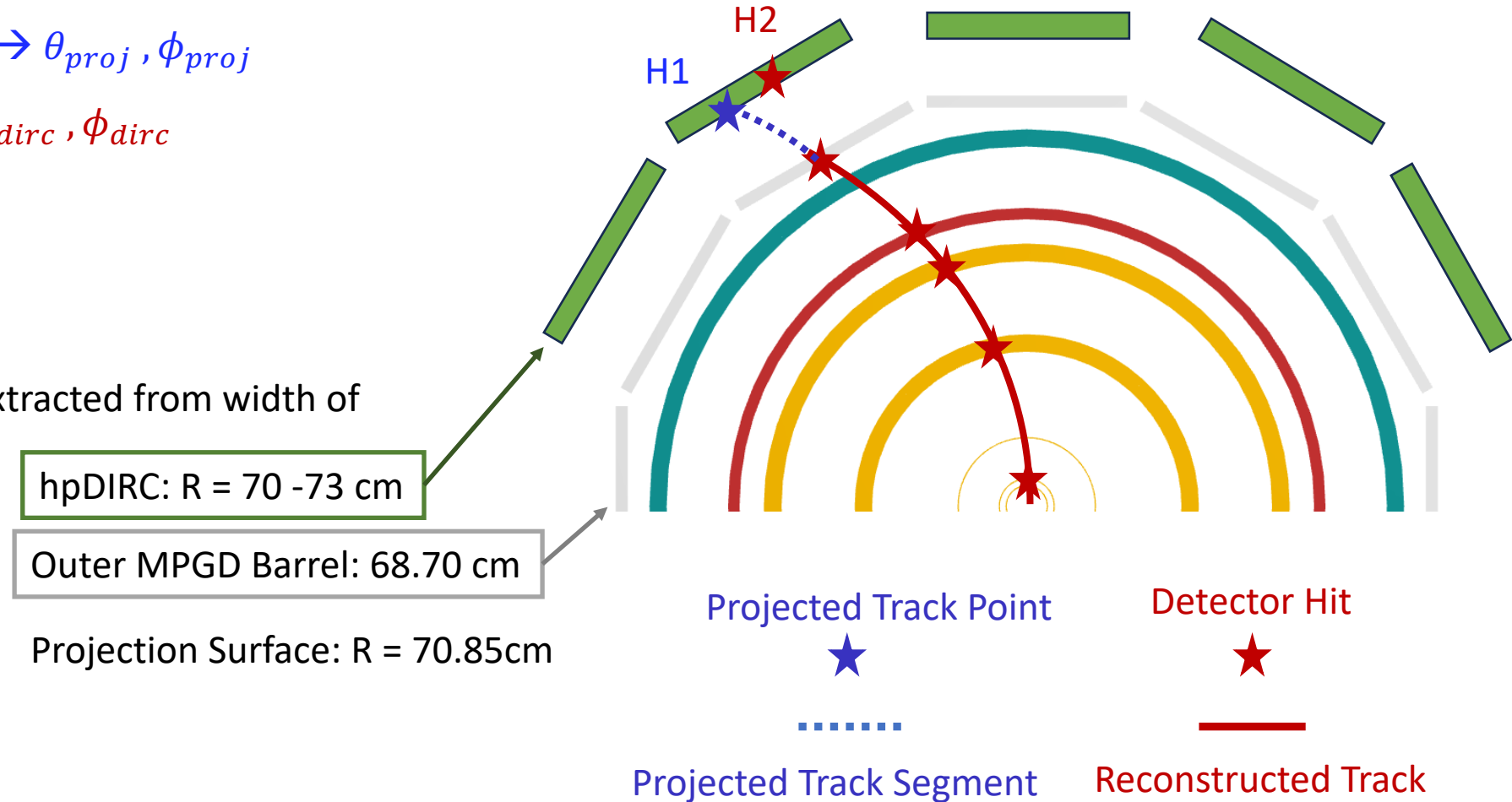
- Angular resolution $\sigma_{\theta}, \sigma_{\phi}$ are extracted from width of assumed Gaussian distribution

hpDIRC: R = 70 -73 cm

- Angular resolution $\sigma_{\theta}, \sigma_{\phi}$ are extracted from width of assumed Gaussian distribution

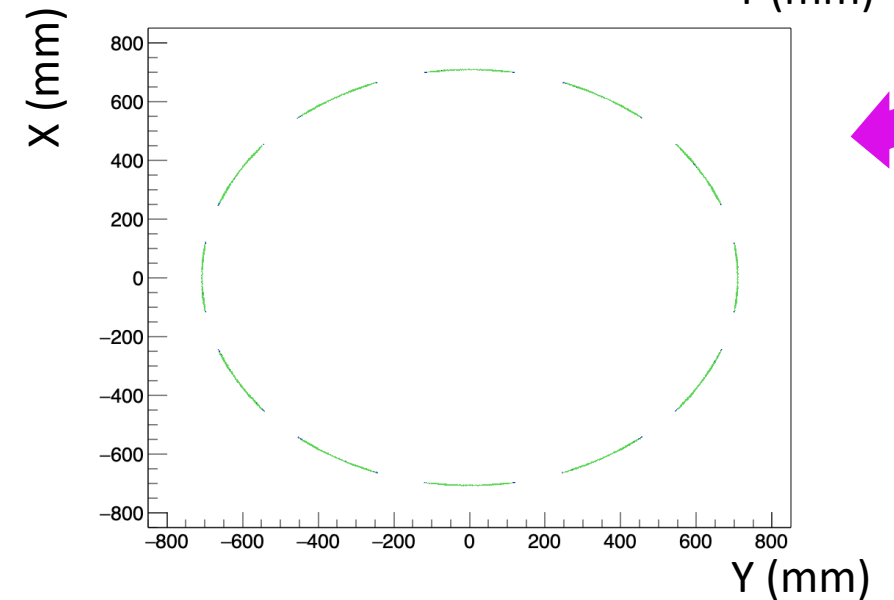
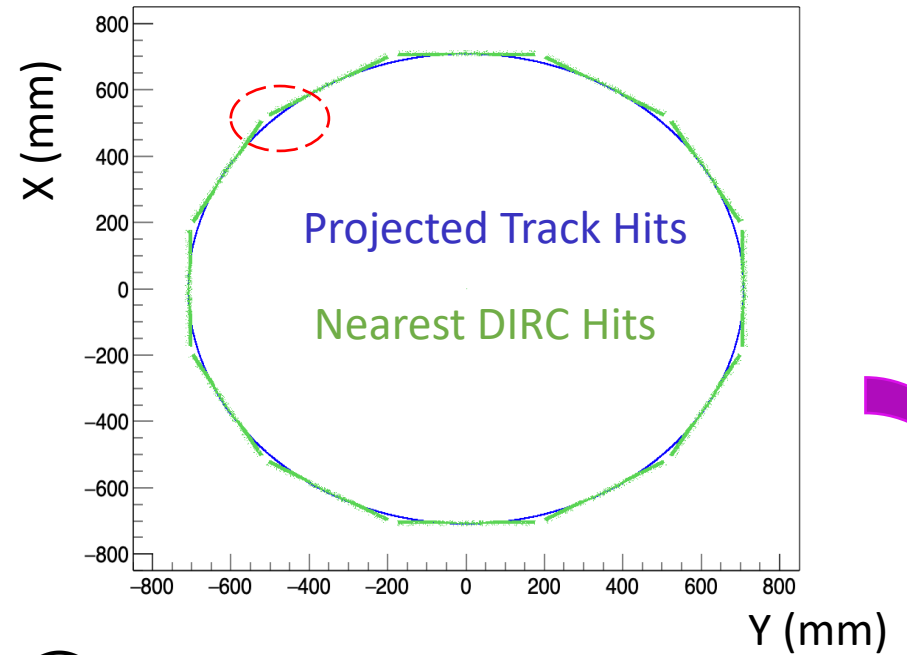
Outer MPGD Barrel: 68.70 cm

Projection Surface: R = 70.85cm



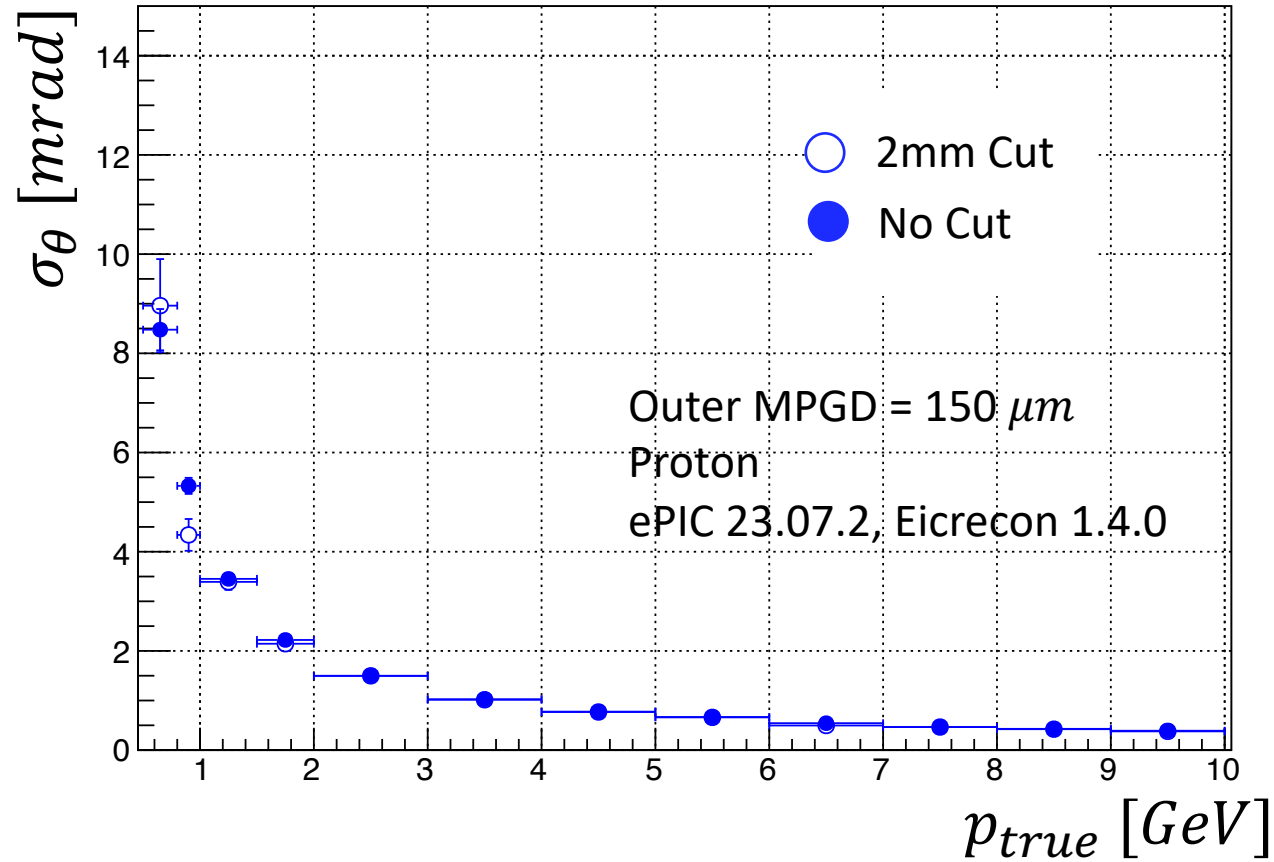
ePIC Simulations Method 1: Complications

- ❑ Two complications found in Method 1 approach
 1. Spatial resolution used in DIRC hit point found to be $3\text{mm}/\sqrt{12}$, this leads to angular uncertainty of $\sim 1.2\text{ mrad}$
 1. ACTS projection surface is cylindrical, while DIRC volume is planar, which leads to geometrical mismatch
 - Mostly removed by applying cut
 - $|(x, y)_{proj} - (x, y)_{DIRC}| < 2\text{ mm}$
 - Resolutions have minimal sensitivity to tighter cuts, particularly at larger momentum ($>2\text{ GeV}$)

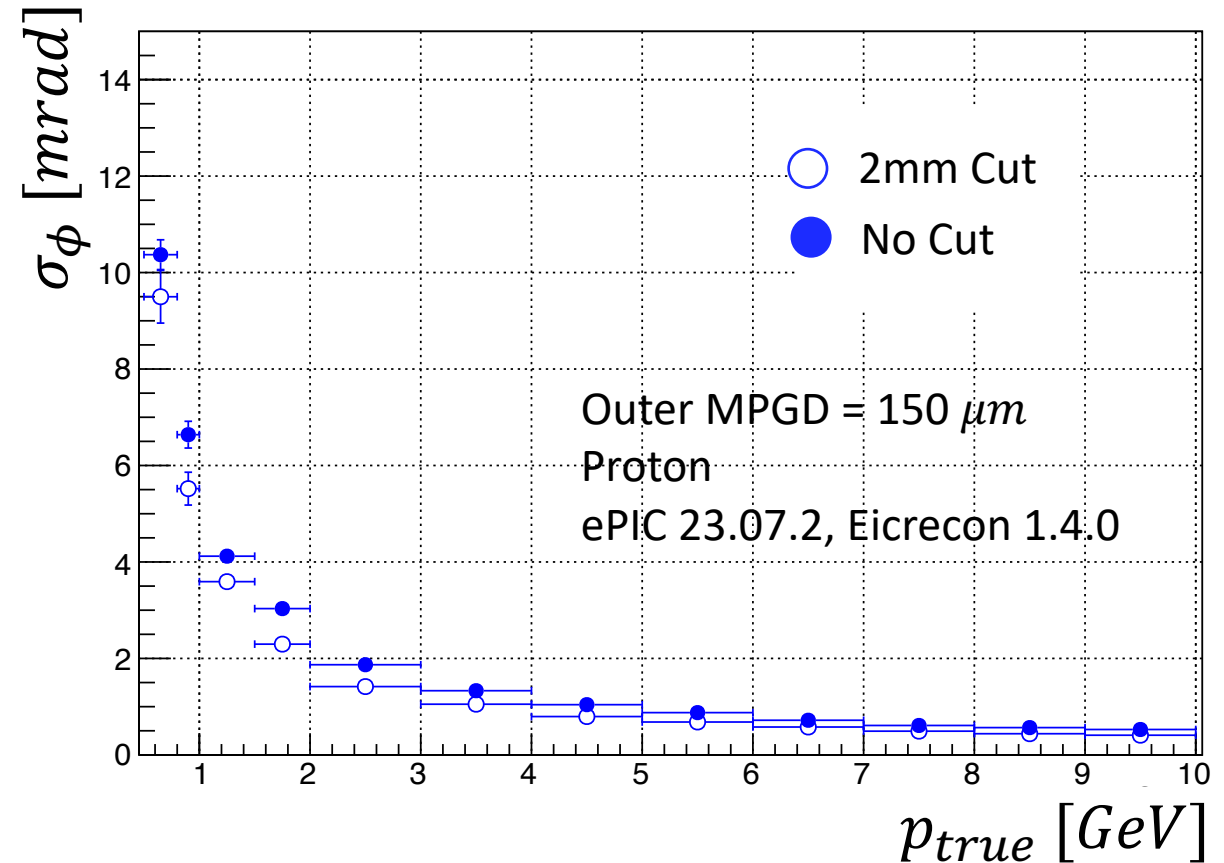


- Generally, cut provides better resolution, mainly at lower momentum

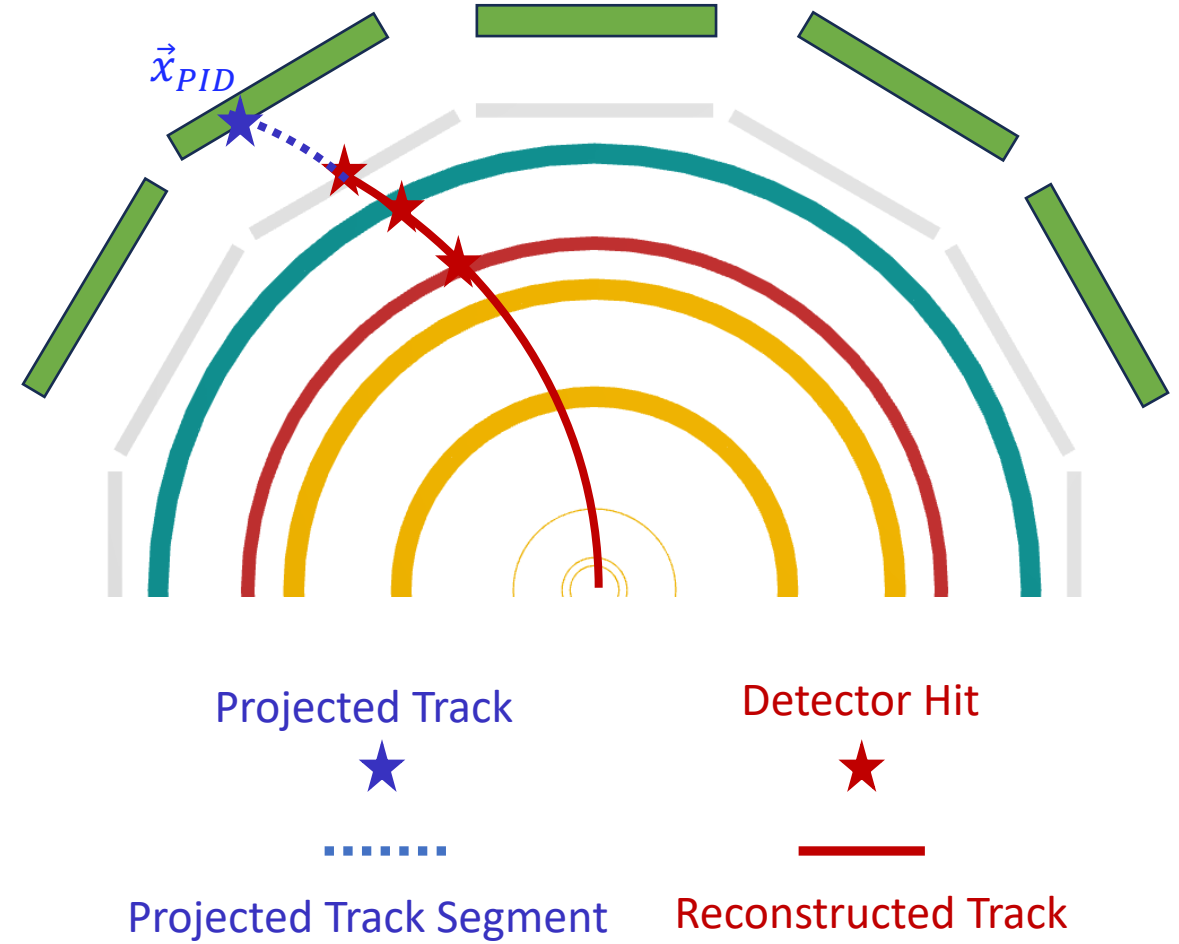
$0.00 < \eta < 0.25$



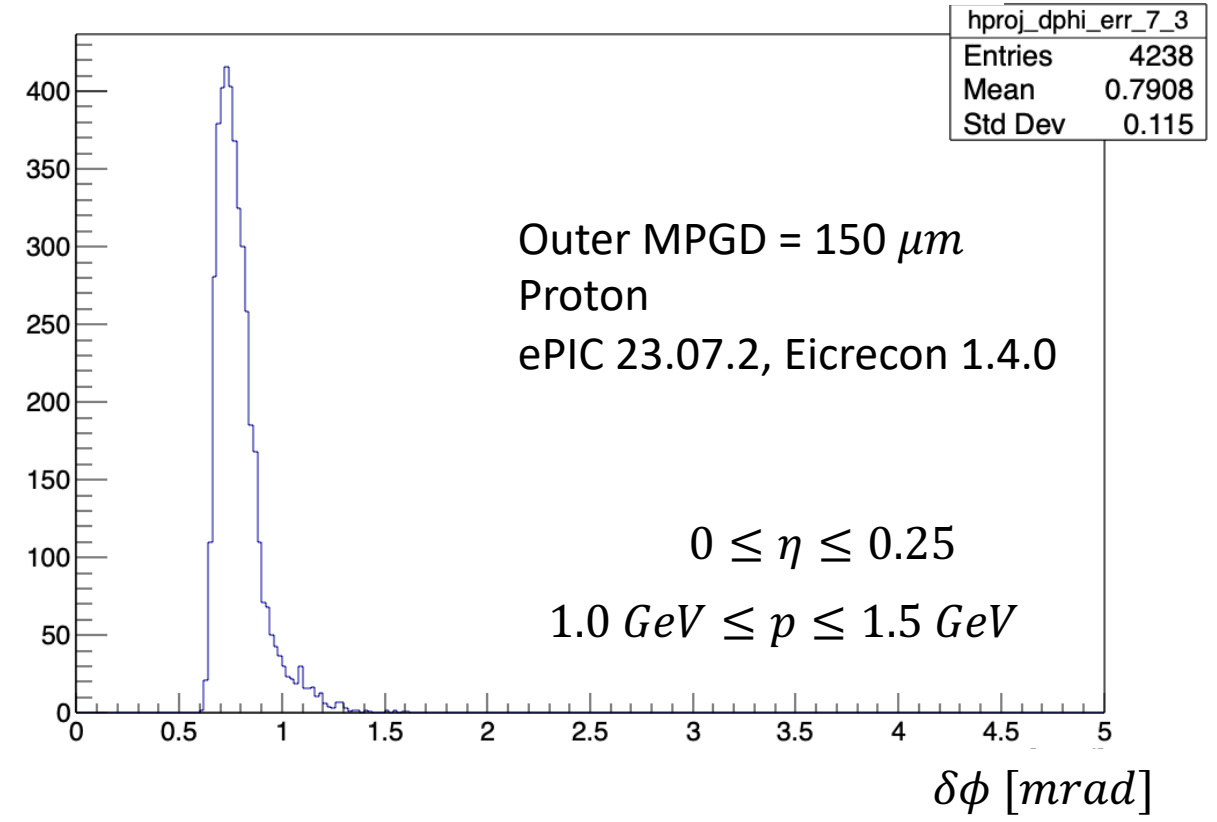
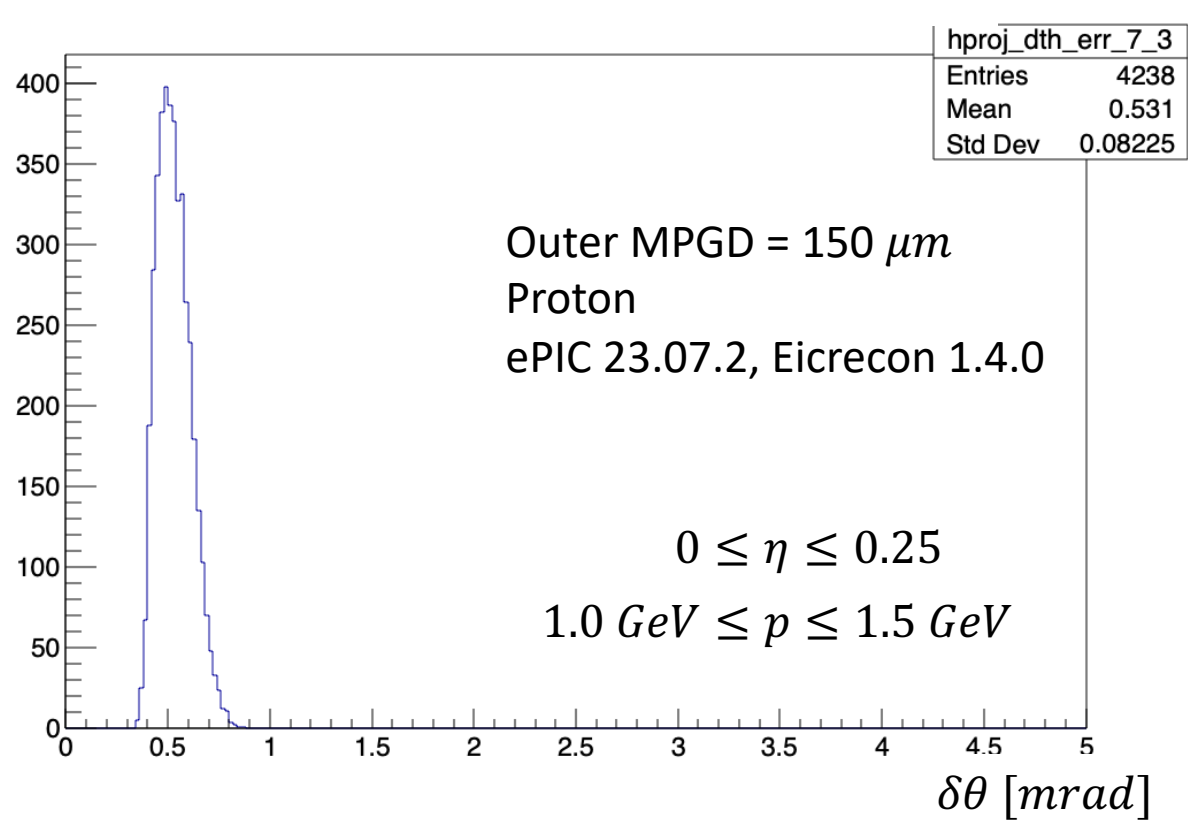
$0.00 < \eta < 0.25$

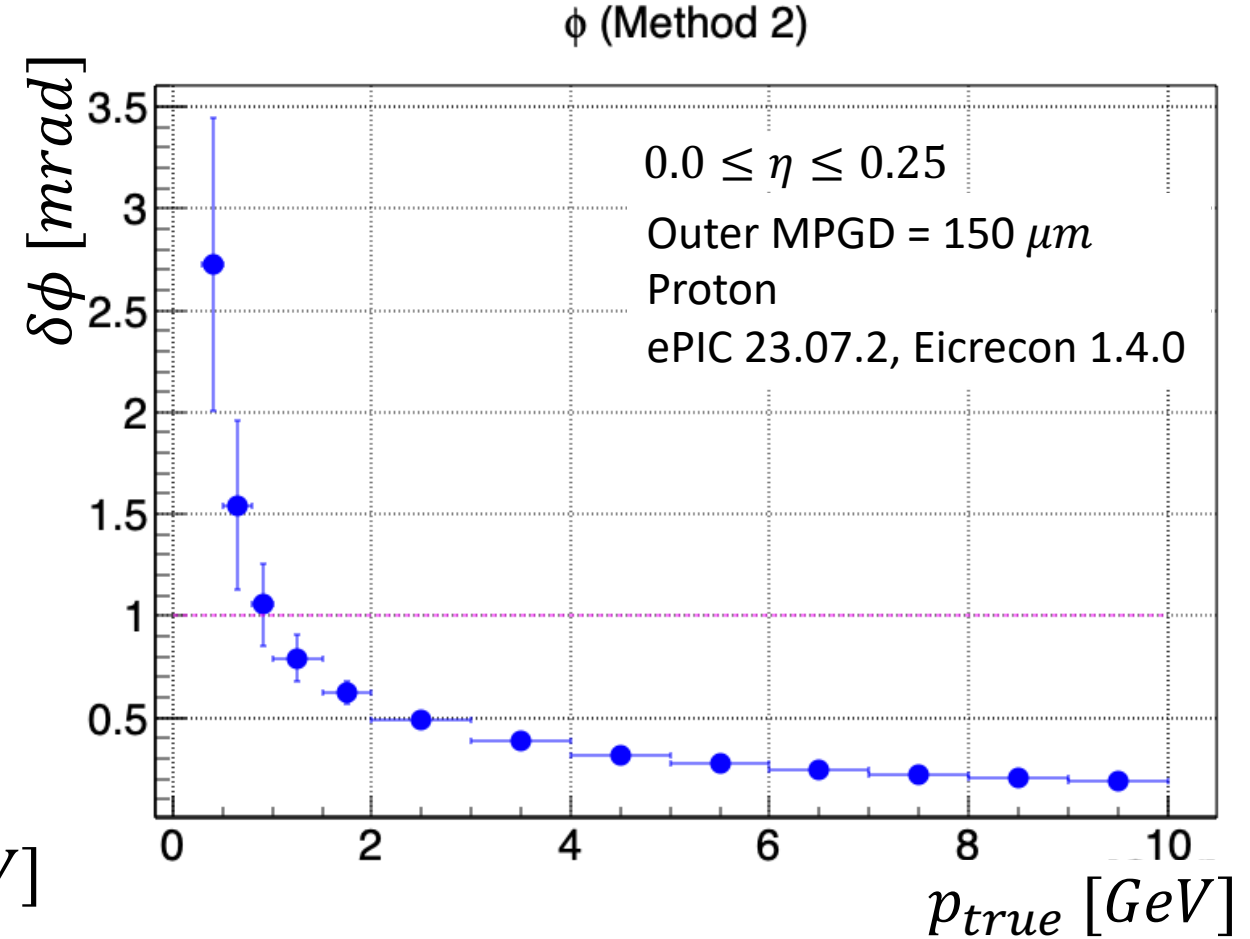
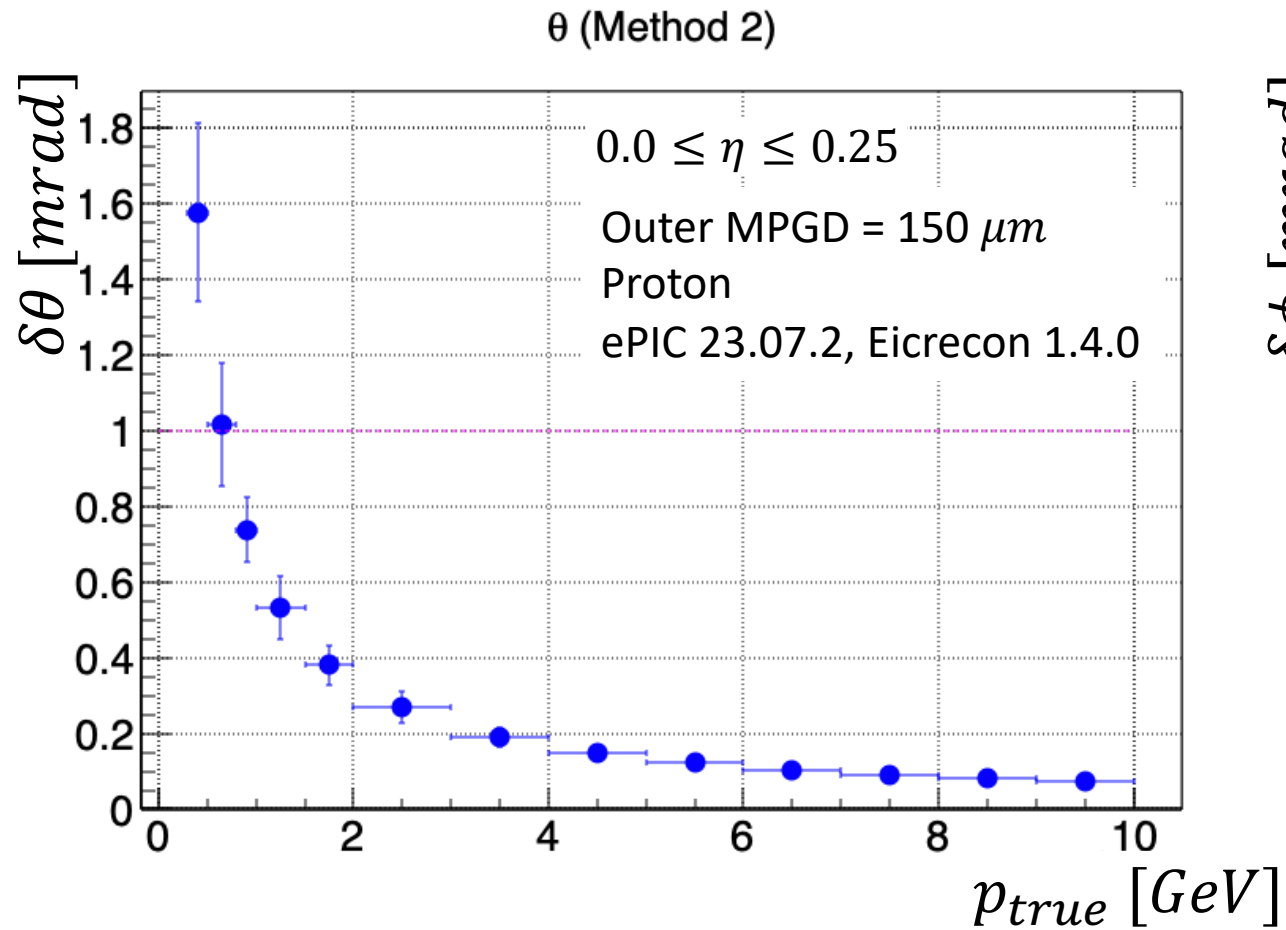


- Use **projected track state vector** \vec{x}_{PID} to get track direction impacting PID surface
 - $\vec{x}_{PID} = \left(l_0, l_1, \theta, \phi, \frac{q}{p} \right)$
- Obtain track direction uncertainty from **covariance matrix** from the fitted track
 - $var(\theta), var(\phi), cov(\theta, \phi)$



- Plot sqrt(variance)
 - Variance obtained from covariance matrix taken from the fitted track
 - Histogram mean = angular uncertainty ($\delta\theta$, $\delta\phi$)





- Angular uncertainties much smaller than in Method 1
 - Method 1 includes $3\text{mm}/\sqrt{12}$ DIRC space point resolution, which needs to be removed.

□ Summary

- Discrepancy between angular resolutions of Method 1 and Method 2
- Within the central region, both Method 1 and Method 2 show no sensitivity to outer MPGD resolutions between $100\mu m - 300\mu m$
- Currently, not all information is in hand for the tracking working group to make a definite conclusion on the needed MPGD spatial resolution to meet PID angular resolution.

□ Next Steps

- Estimate multiple scattering within simulation of outer MPGD layer
 - Compare angular resolution of no outer MPGD (no material) to removing MPGD hits from track reconstruction (material)
- Discrepancy between angular resolutions of Method 1 and Method 2
 - Modify hit resolution of DIRC in method 1
 - Verify accurate error propagations and information in track fit covariance matrix
- Extend measurements to larger pseudorapidity, where services play a larger role