Results from Large Area AC-LGAD Test Beam campaign in 2023

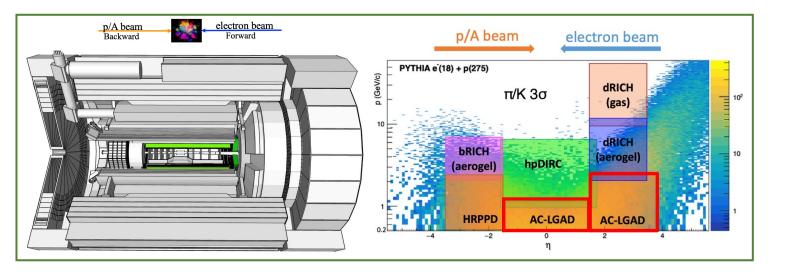
Shirsendu Nanda (On behalf of AC-LGAD team)

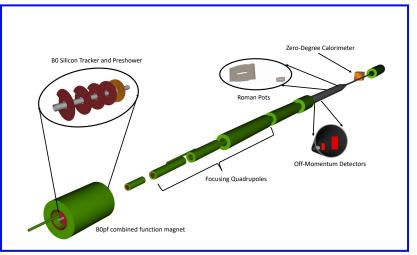
University of Illinois at Chicago (UIC)

ePIC Collaboration Meeting Argonne National Laboratory



#### Specifications of ePIC AC-LGAD detectors in EIC:



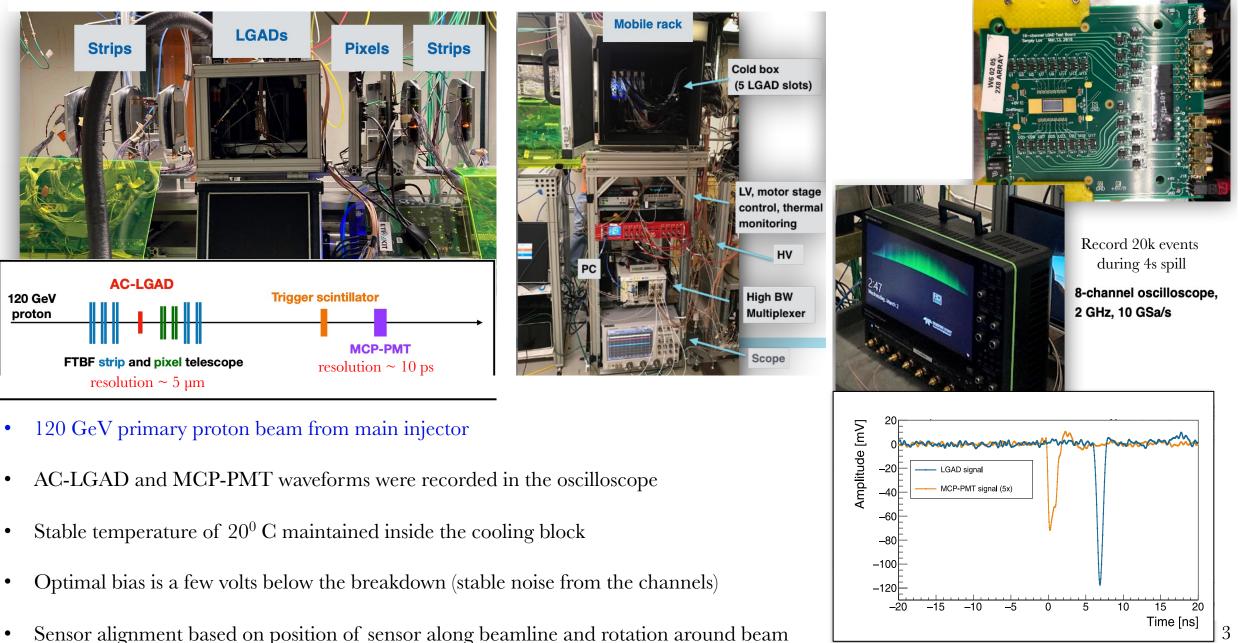


- Central: PID capabilities below the threshold of Cherenkov PID detectors
- Far forward:
  - B0: tracking capability for charged particles.
  - Roman Pots (RPs): scattered charged particles close to beam.
  - The off-momentum detector (OMD): charged particles from nuclear breakup.

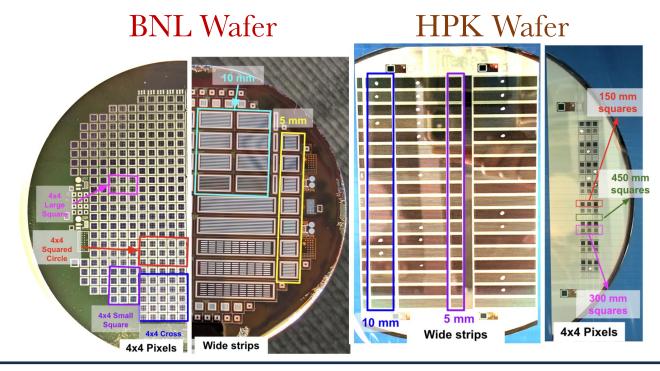
	Angular accept.	Channel size (mm <sup>2</sup> )	Timing Resolution	Spatial resolution	Material budget
Barrel ToF	$-1.4 < \eta < 1.4$	0.5*10	35 ps	30 μm in φ	0.01 X0
Forward ToF	$1.5 < \eta < 3.5$	0.5*0.5	25 ps	$30 \ \mu m$ in x and y	0.025 X0
B0 tracker	$4.6 < \eta < 5.9$	0.5*0.5	30 ps	$20 \ \mu m$ in x and y	0.05 X0
RPs/OMD	$\eta > 6$	0.5*0.5	30 ps	140 $\mu m$ in x and y	no strict req.

#### Fermilab test beam setup for AC-LGADs:

#### FNAL 16 Ch Board



#### Large area AC-LGAD sensors in test beam campaign 2023:



#### BNL

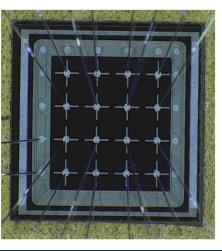
- Strip metal width variation
- Pixel sensors with different metal pad shapes

#### HPK

- Active thickness
- Strip or pad metal width
- Resistivity of n<sup>+</sup> layer
- Coupling capacitance of dielectric layer

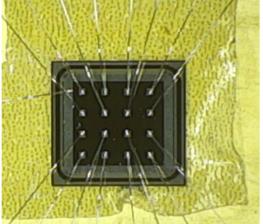
# BNL strip sensor

#### BNL pixel sensor (cross)



#### HPK strip sensor

# HPK pixel sensor



#### Large area AC-LGAD sensors in test beam campaign 2023:

Name	Wafer	Pitch (µm)	Strip length (mm)	$egin{array}{c} { m Metal} \ { m width} \ ({ m \mu m}) \end{array}$		$egin{array}{c} { m Active} \ { m thickness} \ { m (\mu m)} \end{array}$		$\begin{array}{c} \text{Resistivity} \\ (\Omega/\Box) \end{array}$		$ m Capacitance \ (pF/mm^2)$	Optimal bias voltage (V)
						The last set of a					
SH1	W9					20	Τ	1600	Τ	600	114
SH2	W4							400		240	204
$\mathbf{SH3}$	W8	500	10	50		50		400		600	200
SH4	W2					50	1600		240	180	
$\mathbf{SH5}$	W5							1000		600	190
SH6	W9			100		20		1600		600	112
SH7	W8					50		400		600	208

Large area strip sensors

- 1 cm length, 500 μm of pitch
- Metal width variation
- Active thickness variation
- Resistivity variation
- Capacitance variation

Name	Wafer	Pitch (µm)	Metal width (µm)	$\begin{array}{c} \text{Active} \\ \text{thickness} \\ (\mu\text{m}) \end{array}$	$\begin{array}{c} \text{Resistivity} \\ (\Omega/\Box) \end{array}$	$\begin{array}{ c } Capacitance \\ (pF/mm^2) \end{array}$	Optimal bias voltage (V)
HPK 2 x 2 Square pixel							
PH1	WP1			20	1600	600	105
PH2	WP2	500	450	30	1600	600	140
PH3	WP3			50	1600	600	190
HPK 4 x 4 Square pixel							
PH4	W11			20	400	600	116
PH5	W9		150	20	1600	600	112
PH6	W8	500		50	400	600	200
PH7	W5			50	1600	600	185
PH8	W9		300	20	1600	600	112

Large area pixel sensors

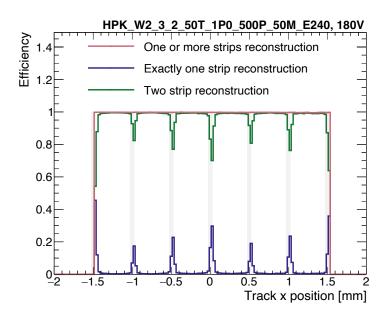
- 500 x 500 µm pitch
- Metal width variation
- Active thickness variation
- Resistivity variation

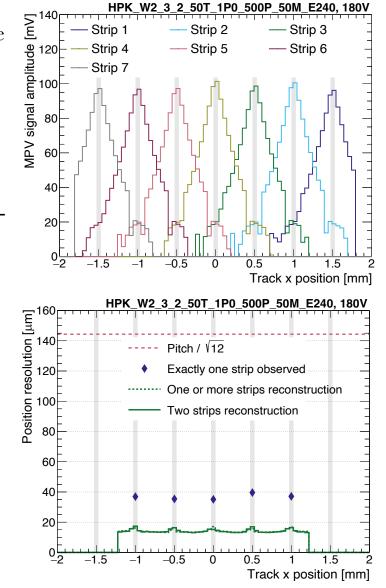
Strips

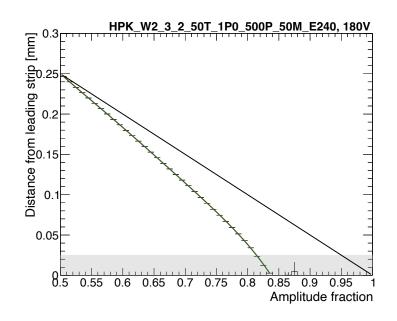
## Spatial resolution in AC-LGADs:

HPK Strip : 10 mm length, 500 µm pitch, 50 µm metal width, 1600 Ω/□ resistivity, and 240 pF/mm<sup>2</sup> capacitance

- Signal sharing between strips enables the *x* position reconstruction
- Amplitude fraction *f* = *a*1 / (*a*1 + *a*2) where *a*1 and *a*2 are the leading and sub-leading strip amplitudes
- Two-strip reconstruction at gap and onestrip reconstruction on metal







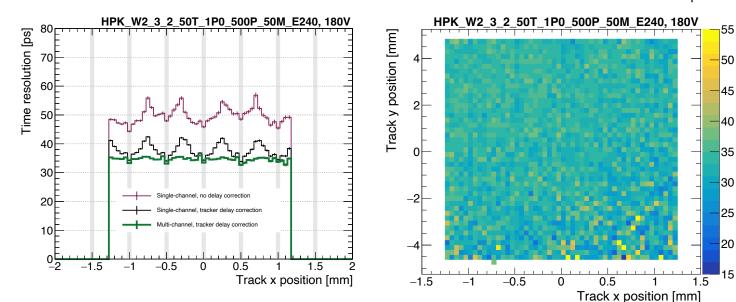
- Efficiency reaches  $\sim 100\%$
- Two-strip resolution  $\sim 12 15 \,\mu m$
- One-strip resolution  $\sim 40 \ \mu m$  on metal

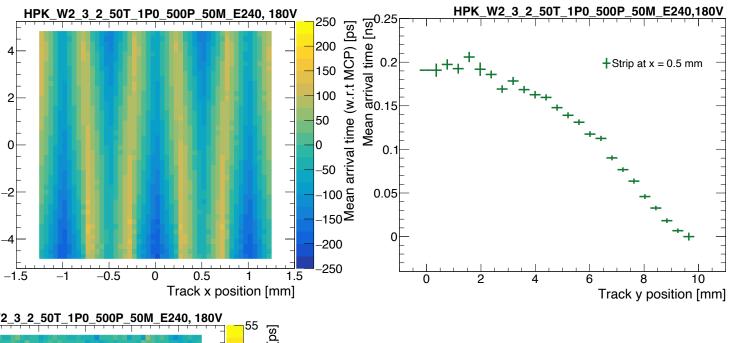
## Time resolution in AC-LGADs:

HPK Strip : 10 mm length, 500 µm pitch, 50 µm metal width, 1600 Ω/□ resistivity, and 240 pF/mm<sup>2</sup> capacitance

Frack y position [mm]

- Due to larger electrodes, distant signals arrival with delays O(100 ps)
- Position-dependent time delay correction is essential, using the external tracker
- Delay map use the resolution of 50 µm for x position and 200 µm for y position
- Multi-channel time stamp,  $t_{\text{reco}} = \frac{a_1^2 t_1 + a_2^2 t_2}{a_1^2 + a_2^2}$

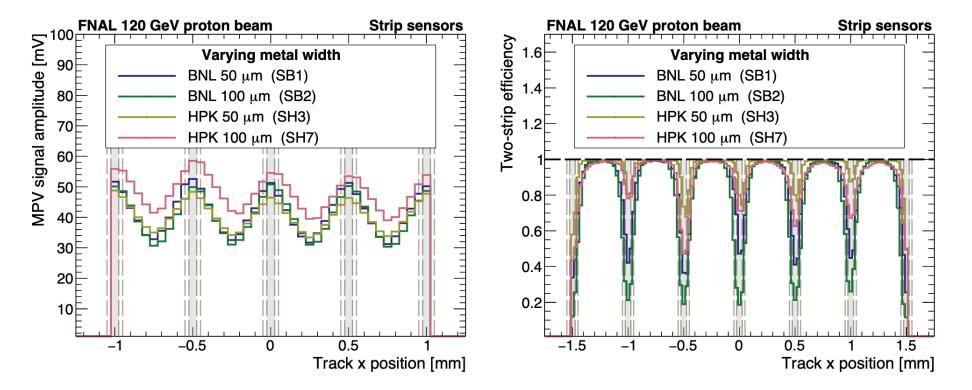




- Without delay correction, the time resolution ~ 45 55 ps
- Adding the tracker-based delay corrections improves the resolution to ~ 35 - 42 ps
- Using multi-channel timestamp with delay correction, time resolution ~ 34 ps

#### Metal width variation in AC-LGAD strip sensors:

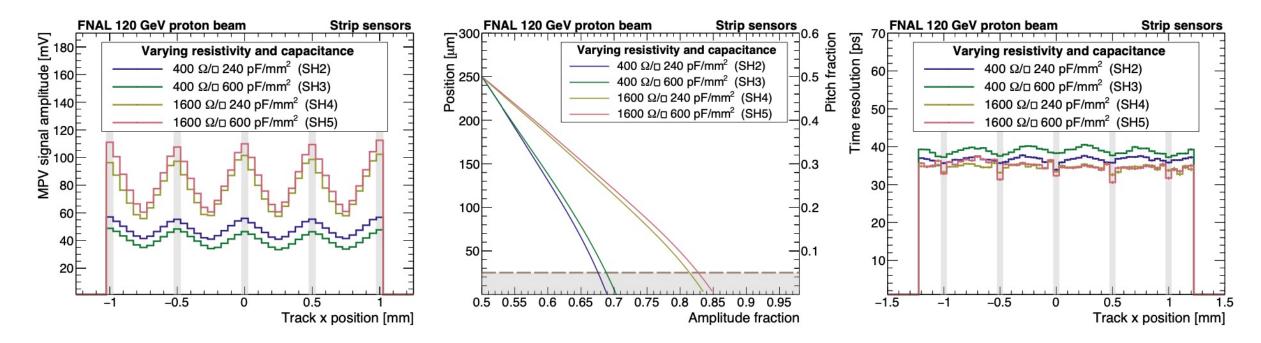
HPK & BNL Strip : 10 mm length, 500 µm pitch, and 50 µm thickness



- Resistivity, capacitance were kept same for BNL and HPK strips sensors separately
- No significant difference in signal sizes has been observed
- Smaller metal width corresponds to slightly larger two-strip efficiency

#### Resistivity and capacitance variation in AC-LGAD strip sensors :

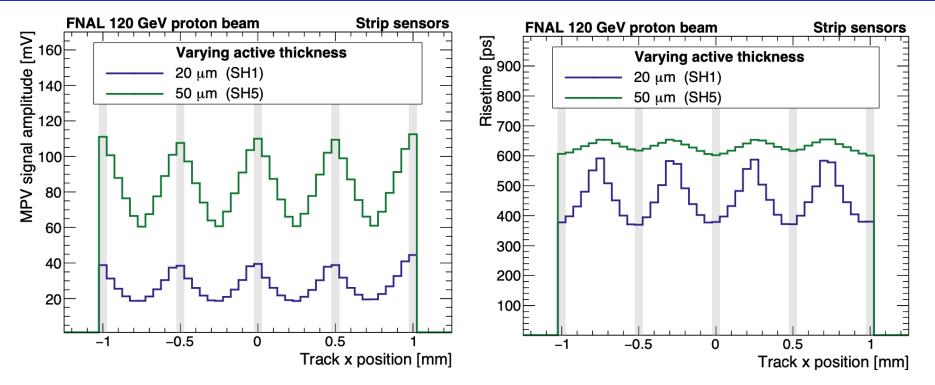
#### HPK Strip : 10 mm length, 500 µm pitch, and 50 µm thickness



- Larger resistivity shows larger signal size
- A slight variation in amplitude between different coupling capacitance
- Larger charge sharing observed for smaller resistivity, a slight variation for different coupling capacitance
- Time resolution ~ 34 ps for 1600  $\Omega/\Box$  resistivity, around 3 6 ps improvement from 400  $\Omega/\Box$

## Active thickness variation in AC-LGAD strip sensors :

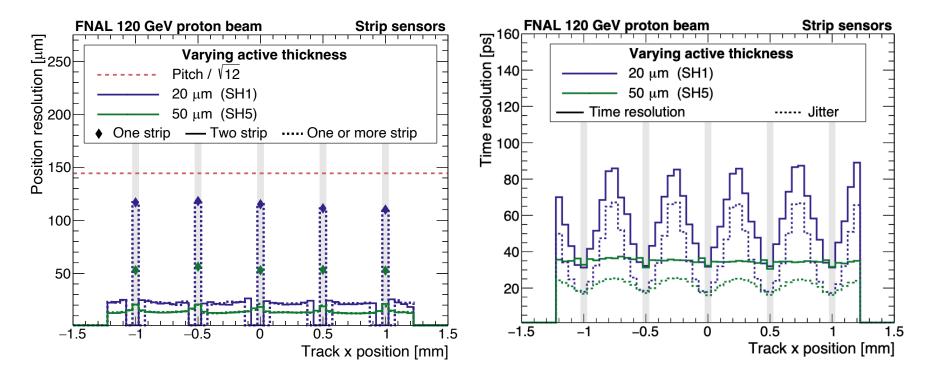
HPK Strip : 10 mm length, 500 µm pitch, 50 µm metal width, 1600  $\Omega/\Box$  resistivity, and 600 pF/mm<sup>2</sup> capacitance



- 2.5 3 times larger signal for 50 µm thick sensor compared to 20 µm
- Almost uniform risetime across the surface for 50 um thick sensor
- A large variation in risetime between gap and metal for 20  $\mu$ m thick sensor
- Slower signal and smaller amplitude in gap contribute to larger jitter = risetime/(S/N) component in 20 µm thick sensor

#### Active thickness variation in AC-LGAD strip sensors :

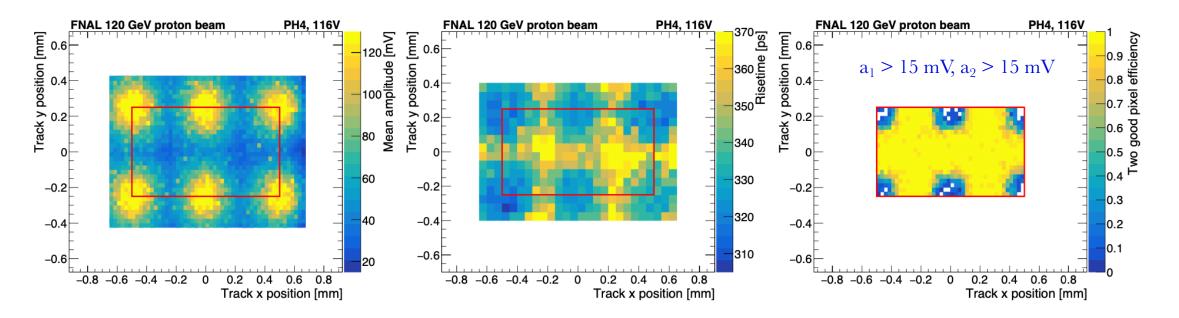
HPK Strip : 10 mm length, 500 µm pitch, 50 µm metal width, 1600  $\Omega/\Box$  resistivity, and 600 pF/mm<sup>2</sup> capacitance



- Two strip position resolution ~  $12 15 \mu m$  for 50 um thick sensor and ~ 20 um for 20 um thick sensor
- Exactly one strip position resolution ~ 50  $\mu$ m for 50 um thick sensor and ~ 110 120  $\mu$ m for 20 um thick sensor
- Larger jitter component in gap contribute to poor time resolution for 20 um thick strip sensor
- Time resolution is uniform (~ 34 ps) across surface for 50 um thick strip sensor

## AC-LGAD pixel sensors:

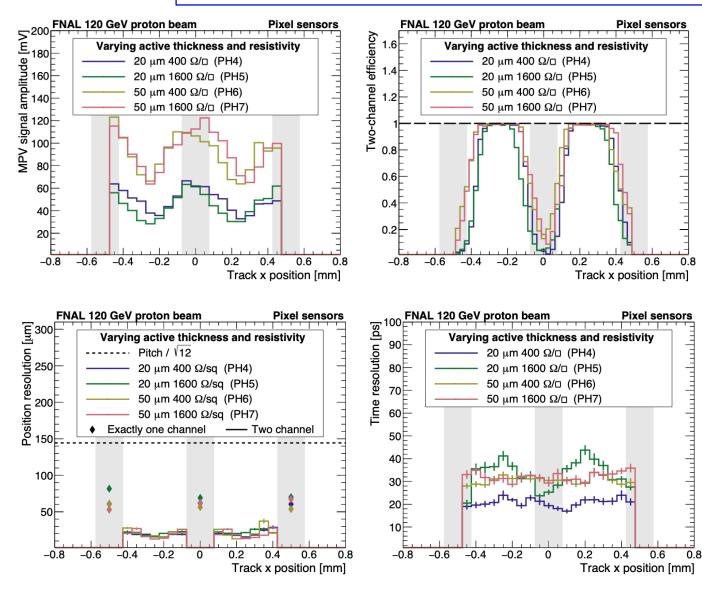
HPK Pixel : 500 x 500 µm pitch, 20 µm thickness, 150 µm metal width, 400  $\Omega/\Box$  resistivity, and 600 pF/mm<sup>2</sup> capacitance



- Larger signal size in metal pads compared to gap region
- Faster signals in metal pads and relatively slower in gap region
- For each event, the amplitude from two channels in column has been added to enhance the charge sharing in gap regions
- Two-channel efficiency  $\sim 1$  in gap region and suffers in metal region

#### Active thickness and resistivity variation in AC-LGAD pixel sensors :

#### HPK Pixel : 500 x 500 µm pitch, 150 µm metal width, and 600 pF/mm<sup>2</sup> capacitance

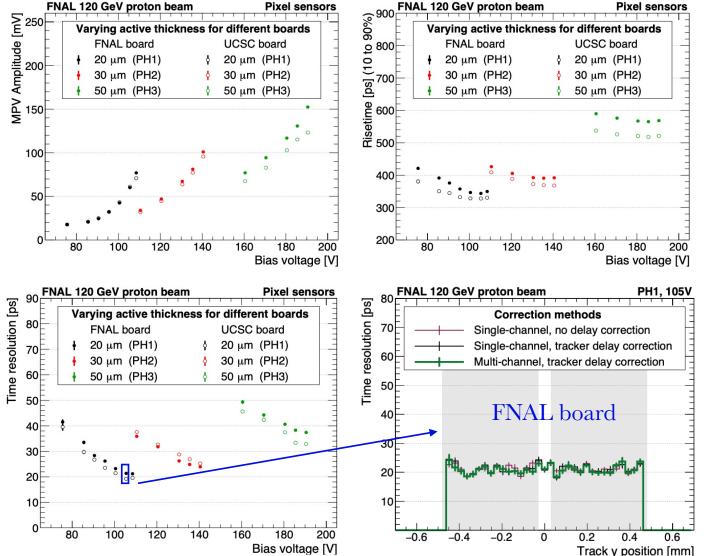


- Overall signal sizes are similar for different resistivity with same thickness
- Two-channel efficiency reaches unity in the mid-gap region
- Two-channel position resolution  $\sim 15 30 \,\mu m$
- Position resolution in metal pads can be improved by further reducing the metal pad width
- Time resolution ~ 20 ps for 400  $\Omega/\Box$  resistivity and 20 µm active thickness

(\*) the gray box only represents the location of metal pad; it also contain the gap region between metal pads in same column

#### Bias scan of AC-LGAD pixel sensors with 450 um metal width :

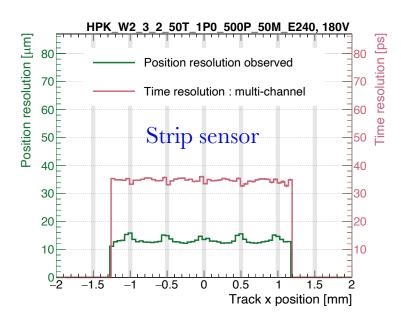
HPK Pixel : 500 x 500  $\mu$ m pitch, 450  $\mu$ m metal width, 1600  $\Omega/\Box$  resistivity, and 600 pF/mm<sup>2</sup> capacitance

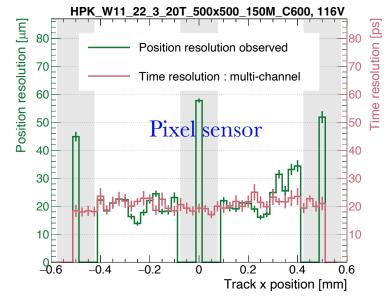


- Operational bias ranges differs with thickness variation
- Faster signal (smaller rise time) for 20  $\mu m$  thick sensors at the optimal bias
- $\sim 20 21$  ps of timing resolution for 20 um thick sensor at optimal bias 105 V
- Time resolution is almost uniform across the surface
- Similar performance between FNAL and UCSC boards

## Summary:

- Large, coarse pitch AC-LGAD sensors show promising 4D performance with timing resolution comparable to LGADs,
  - spatial resolution  $\sim 20$  30x smaller than pitch
  - 100% fill factor
- Optimal strip sensor with 50  $\mu$ m thickness, 50  $\mu$ m metal width, 1600  $\Omega/\Box$  resistivity, and 240 pF/mm<sup>2</sup> capacitance
  - position resolution  $\sim 12 15 \,\mu m$
  - time resolution  $\sim 34 \text{ ps}$
  - prototype strip sensor promising for BToF in EIC
- Optimal pixel sensor with 20  $\mu$ m thickness, 150  $\mu$ m metal width, 400  $\Omega/\Box$  resistivity, and 600 pF/mm<sup>2</sup> capacitance
  - position resolution ~  $15 30 \mu m$  in gap and ~  $50 \mu m$  in the metal
  - time resolution  $\sim 20 \text{ ps}$
  - prototype pixel sensor shows potential for FToF, B0, RPs/OMD





#### AC-LGAD team:

Fermilab: Christopher Madrid, Irene Dutta, Artur Apresyan, Sergey Los, Cristián Peña, Si Xie BNL: Wei Chen, Gabriele Giacomini, Alessandro Tricoli, Gabriele D'Amen, Enrico Rossi LBNL: Ryan Heller, Zhenyu Ye

Caltech: Si Xie

Universidad Técnica Federico Santa María: Claudio San Martín, William K. Brooks, Matías Barría

University of Illinois at Chicago: Shirsendu Nanda, Danush Shekar, Zhenyu Ye

The University of Iowa: Ohannes Kamer Köseyan

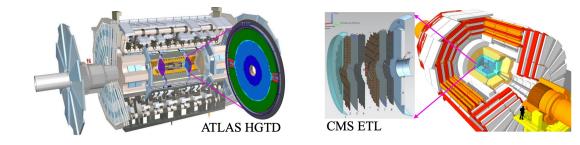
Yerevan Physics Institute: Aram Hayrapetyan

\*The work is supported in part by the Office of Nuclear Physics within the U.S. DOE Office of Science through grant No. DE-FG02-94ER40865 and the University of Illinois at Chicago.

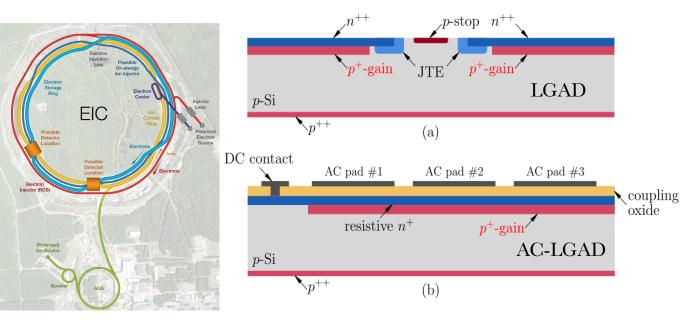
#### Extra slides:

## AC-coupled Low Gain Avalanche Diode (AC-LGAD) sensors:

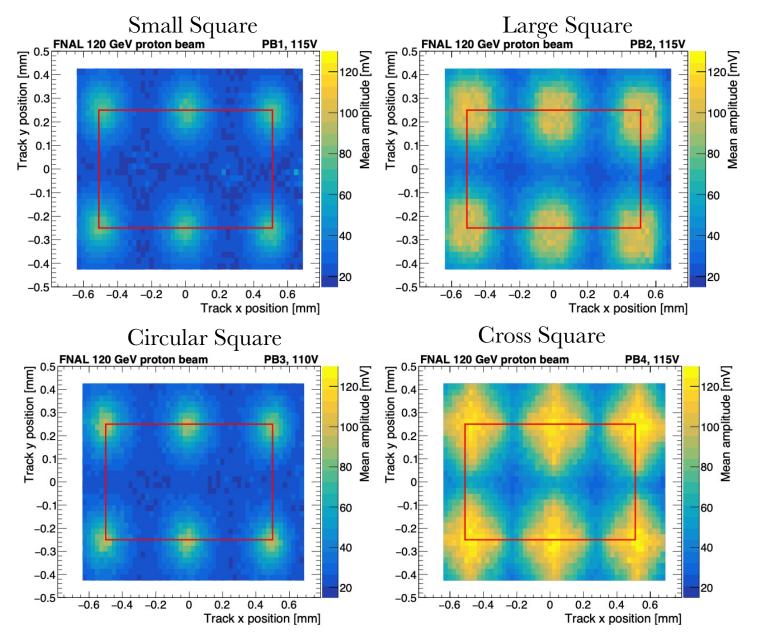
- Large area LGAD detectors for fast timing are being built by ATLAS (6.4 m<sup>2</sup>) and CMS (14 m<sup>2</sup>) for data taking in 2028+
  - Timing resolution of O(10 ps)
  - Not able to achieve a 100% fill factor
  - Position resolution limited to  $\sqrt{1/12}$  of cell size



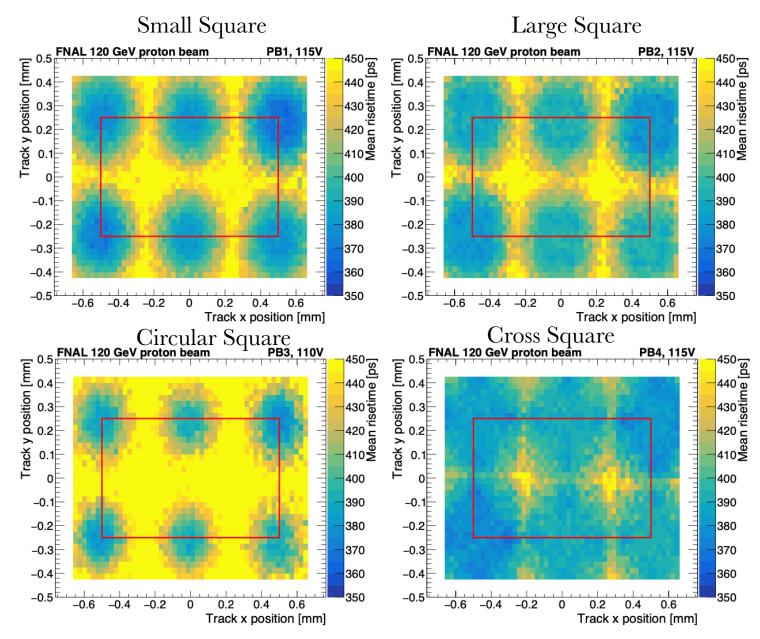
- **AC-LGAD:** Electrical signals in the resistive but continuous  $n^+$  layer are AC-coupled to metal electrodes
  - 100% fill factor
  - Much better spatial resolution due to signal sharing
  - Precise timing resolution similar like LGAD
  - 4D trackers at future high energy experiments
  - Proposed for EIC experiments
    - ➢ Central: ToF PID and tracking
    - ➢ Far forward: Timing and tracking



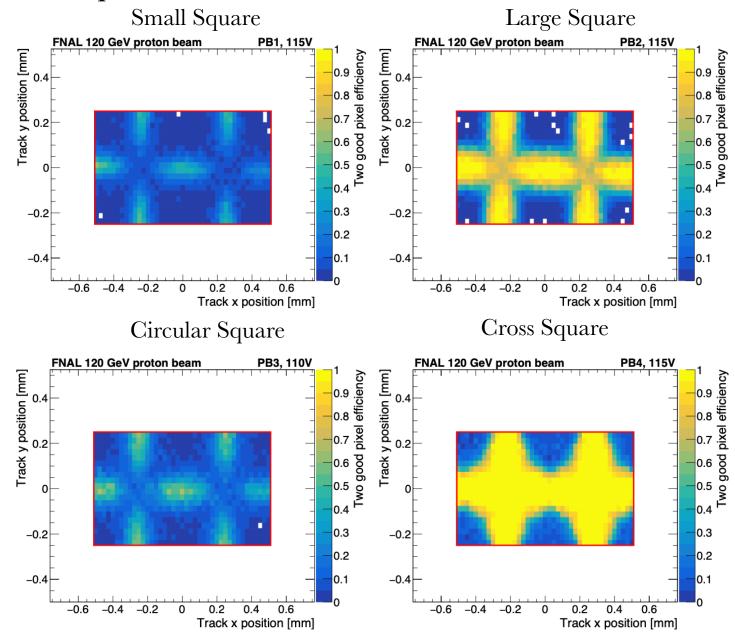
### BNL pixel sensors:



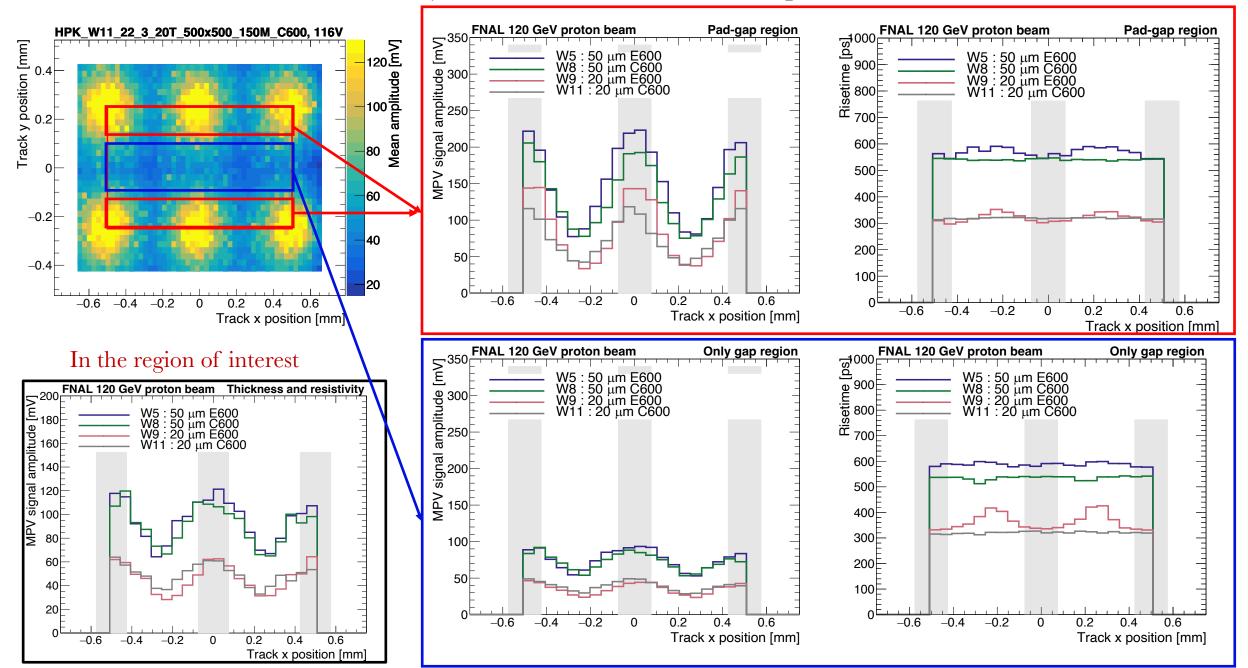
## BNL pixel sensors:



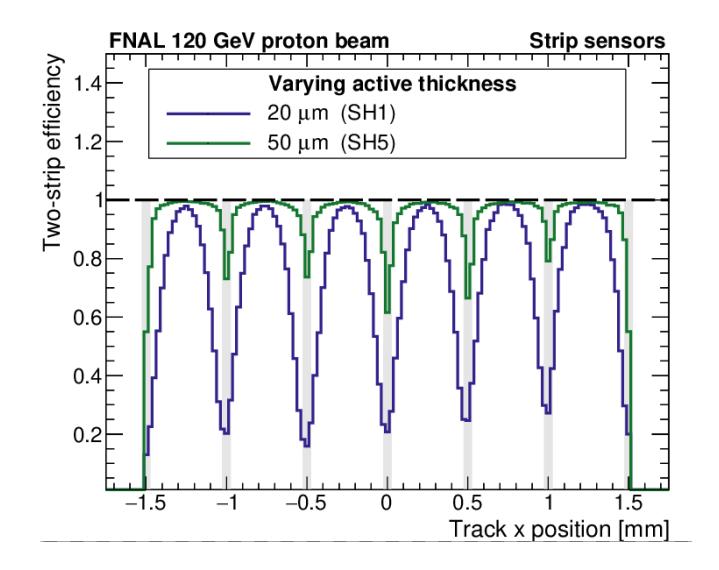
#### BNL pixel sensors:



#### Active thickness and resistivity variation in AC-LGAD pixel sensors :



#### Active thickness variation in AC-LGAD strip sensors :



#### x position reconstruction in pixel sensor:

