# 2nd FLUSH REPORT INTT tracking in pp with SIM

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# **INTT tracking in pp with SIM**

**Development of tracking algorithm in pp collision with simulation** 

**Goal in this workshop**: Evaluation of my tracking algorithm with the truth information and sPHENIX tracking group

### My To-Do List

- Evaluation of my tracking algorithm with the truth track
  - Calculation of the angles ( $\phi$  and  $\theta$ ) of my track
  - Checking the angles of the truth track
  - Comparison of the angles between my track and the truth track
- Evaluation of my tracking algorithm with the track which is made by sPHENIX tracking group
  - Understanding the tracking system of sPHENIX tracking group \_
  - Taking the tracking data of sPHENIX tracking group
  - Comparison between my track and the track which is made by sPHENIX tracking group

# The angles of the truth track

- The truth angles are taken from PYTHIA.
- $\phi$  and  $\theta$  are the angles in the x-y plane and the r-z plane respectively.
- In this study, the final-state particles in  $\eta < 2$  are used.



## Calculation of the angles of reconstructed track

- The tracks are defined as y = ax + b in x-y plane and r-z plane each. • The angles ( $\phi$  and  $\theta$ ) are calculated as below.



- $\phi = \operatorname{Arctan}(a_{xy})$
- $\theta = \operatorname{Arctan}(a_{rz})$

# The angular difference

- all of the truth tracks in one event is calculated.
- The bottom plot shows the difference of 100 events.



Both of distributions have peak.

# The angular difference between one angle of reconstructed track and

### The angular correlation between truth & reconstructed truck



- But the  $\theta$  has no correlation.

### • The $\phi$ between the truth and reconstructed track has good correlation.



### 402326 1.627 1.557 0.8313 0.8144

## The $\phi$ cut

- The  $\phi$  cut which selects only the peaks of the  $\phi$  distribution (  $\phi$  < 0.01) is applied in the  $\theta$
- theta[rad] h\_theta\_corr iruth theta[rad] 5299 Entries 1.627 Mean x 1.602 Mean y Std Dev x 0.8427 0.7364 Std Dev y 0.5 1.5 2.5 track theta[rad]
- The  $\theta$  distribution has good correlation and  $\theta$  difference has more stronger peak.







- $\Delta \phi$  vs.  $\Delta \theta$  distribution has peak.
- The correct combinations of the the reconstructed track and the truth track is in this peak.

### Next step

 After setting the window, I'd like to calculate the ratio of the correct combination in the window.

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BACK UP

## TRACKING METHOD



<Simulation> PYTHIA + GEANT4 (100 events) p + p collision,  $\sqrt{s} = 200$ GeV, no magnetic field.

- Selection a cluster A on the inner barrel and a cluster B on the outer barrel.
- Connection them with a line (tracklet).
- 3. Determination the beam spot using tracklets.
- 4. Connection the three points (A, B, beam spot) by the least-squares method (track).



### HOW TO GET THE BEAM SPOT4



Unit vector between A and O :  $\vec{u}$ 

- To find the beam spot, the distance of • closest approach (DCA) between each tracklet and origin was calculated.
  - Calculating  $DCA_{2D}$  and  $DCA_{L}$ . •

 $DCA_{2D} = \vec{v} \times \vec{u} = \vec{u} \cdot \sin \phi$  $DCA_{L} = \vec{v} \cdot \vec{u} = \vec{u} \cdot \cos \phi$ 

• Using  $DCA_I$ , the DCA position of the tracklet can be calculated.

$$DCA_X = DCA_L \times \vec{u}_x + A_x$$

 $DCA_Y = DCA_L \times \vec{u}_y + A_y$ 

 $DCA_{Z} = DCA_{L} \times \vec{u}_{z} + A_{z}$ 

<u>The beam spot is the average of the DCA.</u> •

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## TRACKLET

 Tracklets are defined as tracklets with angular difference in the X-Y plane between A and B  $\Delta \phi < 0.01$ [rad].

<u>Some tracklets share a cluster.</u> Some DCA, s seem to be extremely far from the beam <u>spot.</u>





x-y plane





# In this study, only tracklets that $DCA_{2D}$ and $DCA_z$ is within 1 sigma from the

mean are used.



# **RESULT OF TRACKING**

Blue : clusters and tracklets Green : reconstructed tracks

Glay : excluded clusters and tracklets





## # of tracks

