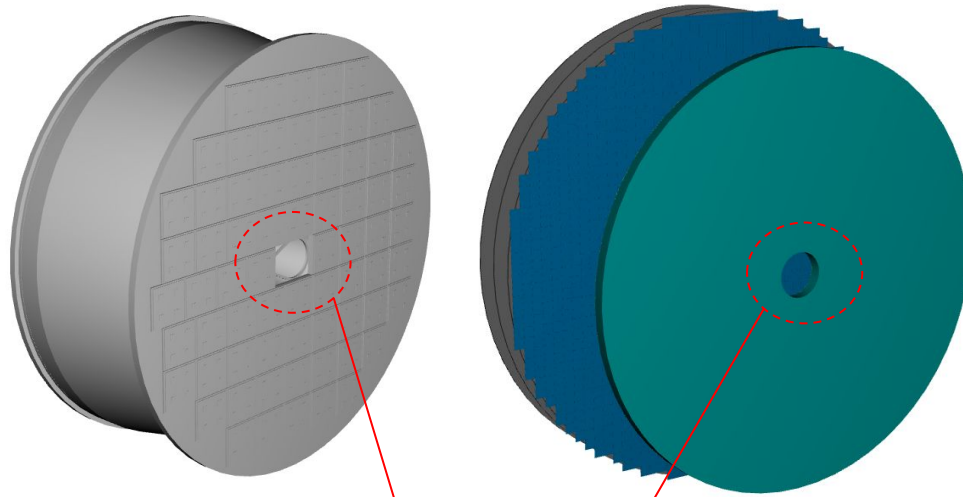


pfRICH Implementation in DD4Hep

Nov 12, 2023

Problem, Consueses and Plan (Old Slides)



CAD import

Standalone Geant4 import

Beampipe
implementation

Currently:

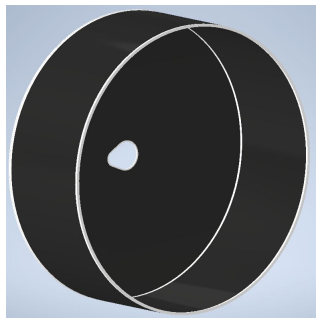
- **Two implementations:**
 - CAD import
 - Standalone Geant4 import
- **Problem:**
 - Neither implementations work within the ePIC DD4Hep framework
 - CAD import: significantly increase the overhead of the simulation
 - Standalone: doesn't remain non-standard beam pipe features
 - Both are not ideal

Consueses:

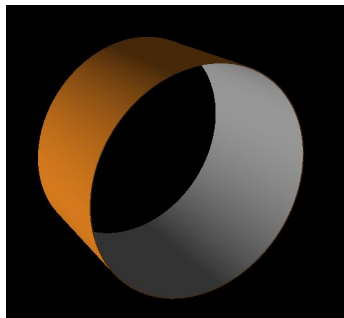
- A new implementation is needed
- The new pfRICH shouldn't increase the simulation overhead
- The new implementation should preserve the critical features from the CAD (such as the beam pipe geometry)

**Ambitious plan,
how do we do this?**

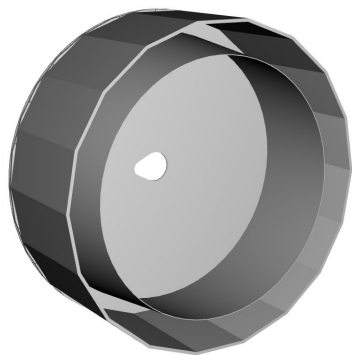
Tentative Plan (Old Slides)



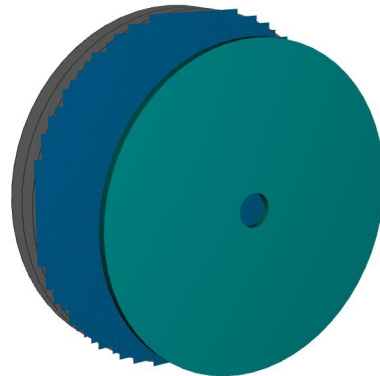
pFRICH outer shell
CAD GDML



Geant4 Object xml



- Step 1: Setting up a hybrid** (CAD import-xml description) base xml description in DD4Hep
- Preserve CAD feature, serve as bridge between CAD and Geant4



Step 2: Rewrite/improve
PFRICH_geo.cc, to parse the gdml geometry and merge the existing detector components (regular shaped)



Where we are

Step 3: Testing

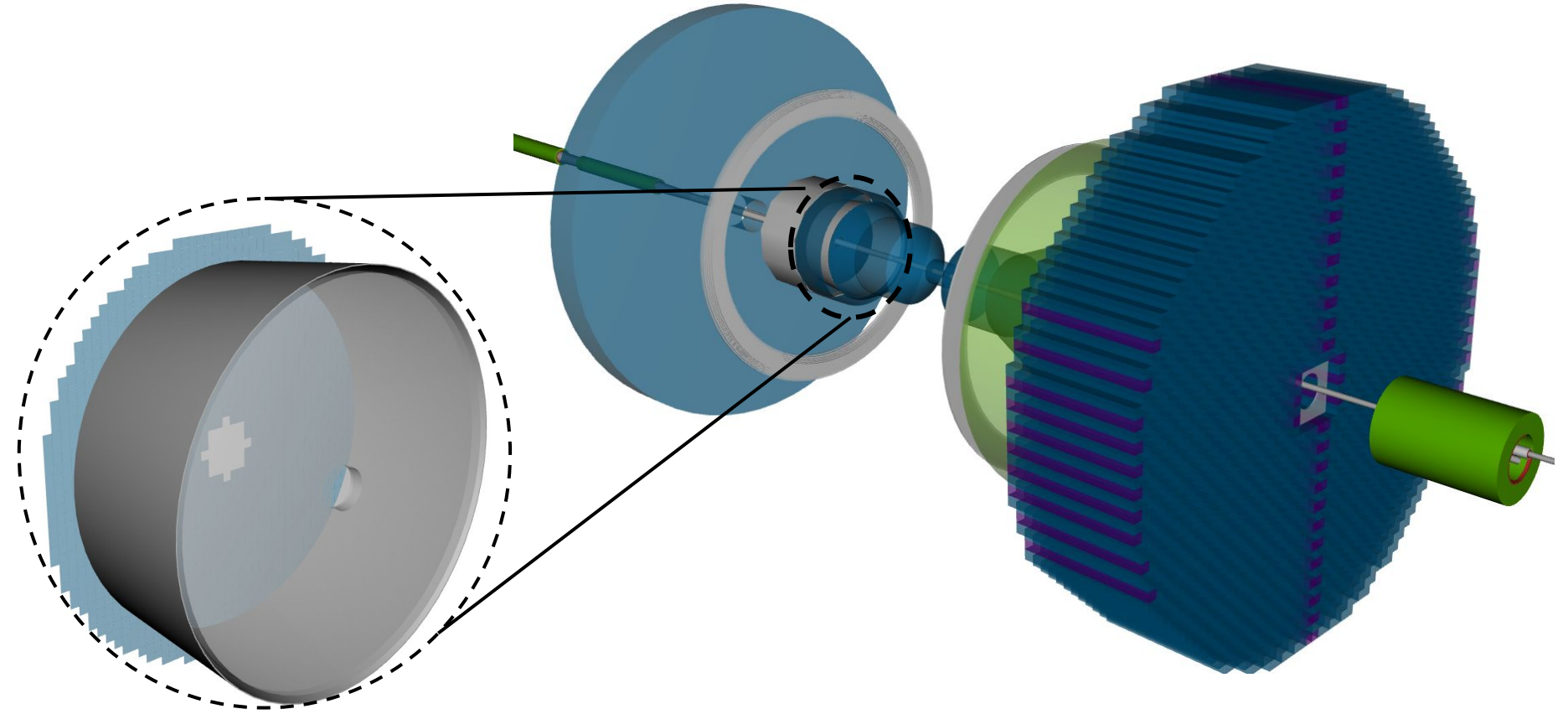
GDML outer shell will be outside of the Cherenkov volume, and it will be excluded if it is identified to increase the simulation overhead

Step 4: Writing a geometry cross-checking software (between Geant4 vs CAD)

And

Reconstruction

Update of pfRICH in DD4Hep



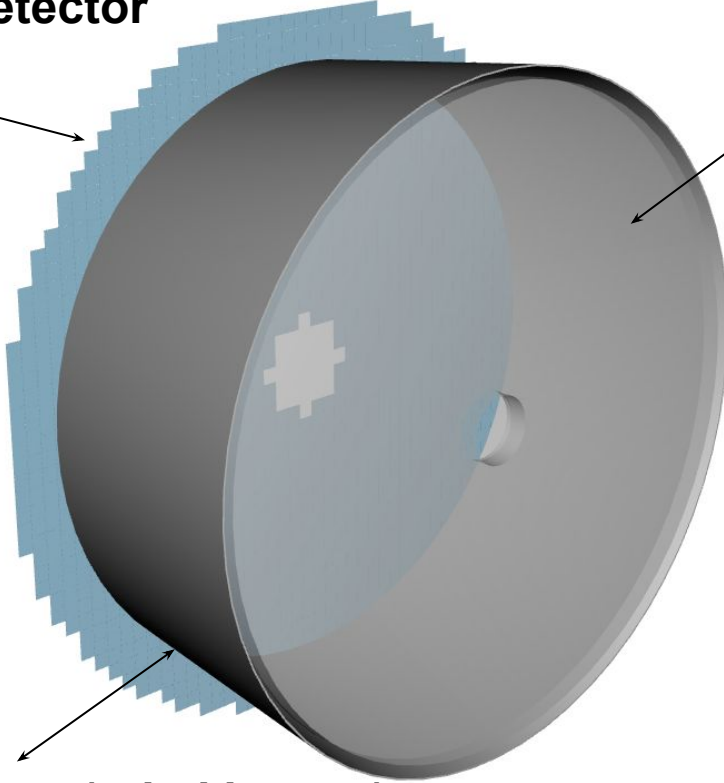
Update of pfRICH in DD4Hep

**Sensitive detector
Plane
(DD4Hep)**

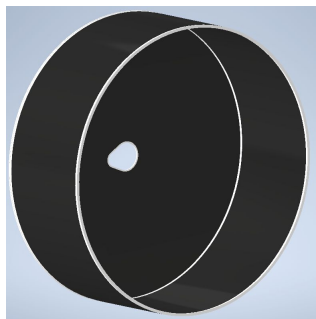
**Aerogel + Filter Plane
(DD4Hep)**

Mirror cone (gdml import)

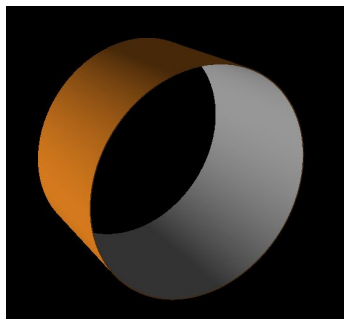
- **New update:**
 - Mirror Cone
 - Aerogel + Filter Plane
 - Detector Plane



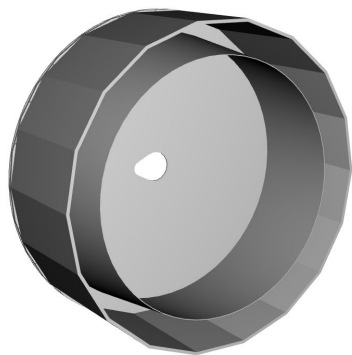
Tentative Plan



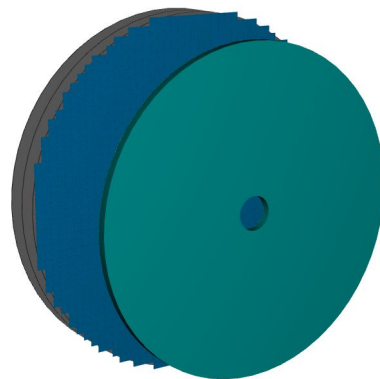
pFRICH outer shell
CAD GDML



Geant4 Object xml



- Step 1: Setting up a hybrid** (CAD import-xml description) base xml description in DD4Hep
- Preserve CAD feature, serve as bridge between CAD and Geant4



Step 2: Rewrite/improve
[PFRICH_geo.cc](#), to parse the gdml geometry and merge the existing detector components (regular shaped)

Done !

Step 3: Testing

GDML outer shell will be outside of the Cherenkov volume, and will be excluded if it is identified to increase the simulation overhead



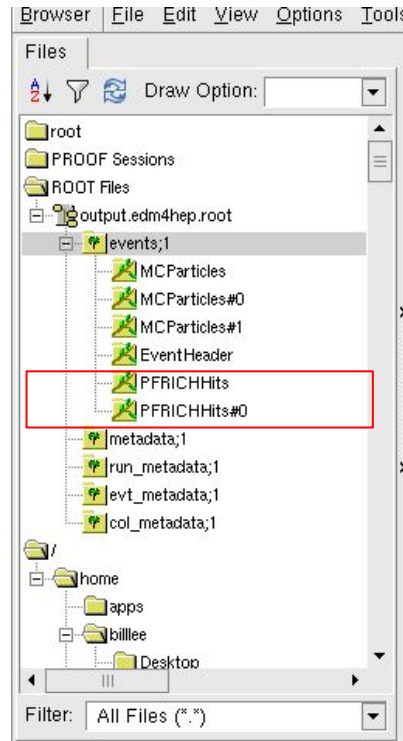
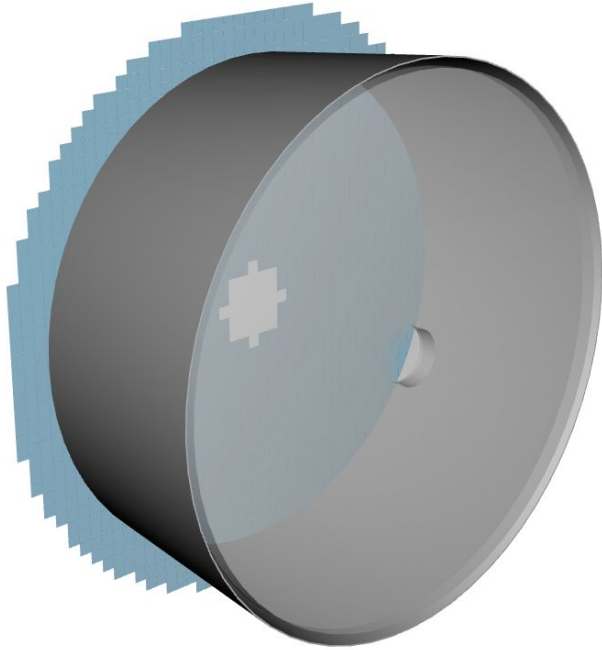
Where we are

Step 4: Writing a geometry cross-checking software (between Geant4 vs CAD)

And

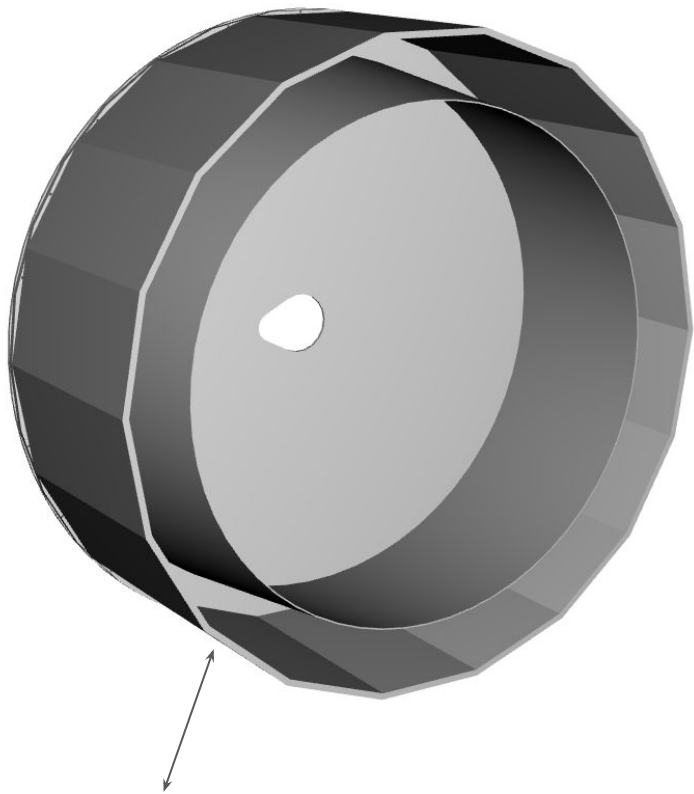
Reconstruction

Simulation Read Out



- The PFRICHHits works with the implementation
- Simulation ready !

One Detail Regarding GDML Import



**Outershell is not currently
implemented**

- **Issues with importing the GDML**
 - Overlaps when importing the GDML structure and placement (our current route)
- **Solution: important structure only**
 - Placement inside .cpp file

Parameters in the xml file

```
<!-- Actual global parameters -->
<constant name="PFRICH_length" value="BackwardRICHRegion_length" /> <!-- vessel z-length -->
<constant name="PFRICH_zmax" value="-BackwardRICHRegion_zmax"/> <!-- vessel front -->
<constant name="PFRICH_zmin" value="PFRICH_zmax + PFRICH_length"/> <!-- vessel back -->
<constant name="PFRICH_rmin0" value="-PFRICH_zmin * Eta3_9_tan * 0.95"/> <!-- bore radius at vessel frontplane -->
<constant name="PFRICH_rmin1" value="-PFRICH_zmax * Eta3_9_tan * 0.85"/> <!-- bore radius at vessel backplane -->
<constant name="PFRICH_rmax" value="BackwardPIDRegion_rmax"/> <!-- vessel radius -->
<constant name="PFRICH_bore_slope" value="(PFRICH_rmin1 - PFRICH_rmin0) / PFRICH_length"/> <!-- slope of bore radius -->

<!-- ++++++ -->

<constant name="PFRICH_proximity_gap" value="30*cm"/> <!-- distance between aerogel exit plane and sensor entrance plane -->
<constant name="PFRICH_services_length" value="15*cm"/> <!-- span of service materials behind the sensors -->
<constant name="PFRICH_wall_thickness" value="0.5*cm"/> <!-- thickness of radial walls -->
<constant name="PFRICH_window_thickness" value="0.1*cm"/> <!-- thickness of entrance and exit walls -->
<constant name="PFRICH_aerogel_thickness" value="3.0*cm"/> <!-- aerogel thickness -->
<constant name="PFRICH_filter_thickness" value="0.3*mm"/> <!-- filter thickness -->
<constant name="PFRICH_aerogel_filter_gap" value="0.01*mm"/> <!-- air gap between aerogel and filter FIXME: currently a gas gap -->

<!-- FIXME: change to LAPPD(?) -->
<constant name="PFRICH_sensor_size_default" value="25.8*mm"/> <!-- sensor side length (full size, with enclosure) -->
<constant name="PFRICH_sensor_size_lores" value="PFRICH_sensor_size_default * 4"/> <!-- lores sensor size, used for global visualizations_only -->
<constant name="PFRICH_sensor_size" value="PFRICH_sensor_size_default"/>
<constant name="PFRICH_pixel_gap" value="0.2*mm"/> <!-- size of gaps between adjacent pixels AND gaps between edge pixels and sensor side -->
<constant name="PFRICH_sensor_sensitive_size" value="PFRICH_sensor_size - PFRICH_pixel_gap"/> <!-- side length of photosensitive surface (to be segmented) -->
<constant name="PFRICH_sensor_thickness" value="0.5*mm"/>
<constant name="PFRICH_num_px" value="8"/> <!-- number of pixels along one side of the sensor -->
<constant name="PFRICH_pixel_size" value="3.0*mm"/> <!-- a single SiPM pixel size -->
<constant name="PFRICH_pixel_pitch" value="PFRICH_pixel_size + PFRICH_pixel_gap"/> <!-- center-to-center distance between SiPMs in a 8x8 panel -->

<constant name="PFRICH_debug_optics" value="0"/>
</define>
```

A Little messy, and requires touch up

Next step

- **Configure gas volume and double check material profile**
- **Reflective coating of mirror cone**
- **Important outershell**
 - **Resolve the overlapping issue**
- **Generate photon occupancy plots**
- **Consolidate a list of parameters in the xml file**

Backups

Update on Step 2

DD4hep_GdmlDetector.cpp

PFRICH_geo.cpp

BarrelHCalCalorimeter_geo.cpp

```
// Copyright (C) 2022 Christopher Dilks, Sylvester Joosten
//
// -----
// pFRICH: Proximity Focusing RICH
// Author: C. Dilks
// -----
#include "DD4hep/DetFactoryHelper.h"
#include "DD4hep/OpticalSurfaces.h"
#include "DD4hep/Printout.h"
#include "DDRec/DetectorData.h"
#include "DDRec/Surface.h"

#include <XML/Helper.h>

// ROOT includes
#include "TGDMLParse.h"
#include "TGDMLWrite.h"
#include "TGeoElement.h"
#include "TGeoManager.h"
#include "TInterpreter.h"
#include "TUri.h"

using namespace std;
using namespace dd4hep;
using namespace dd4hep::rec;

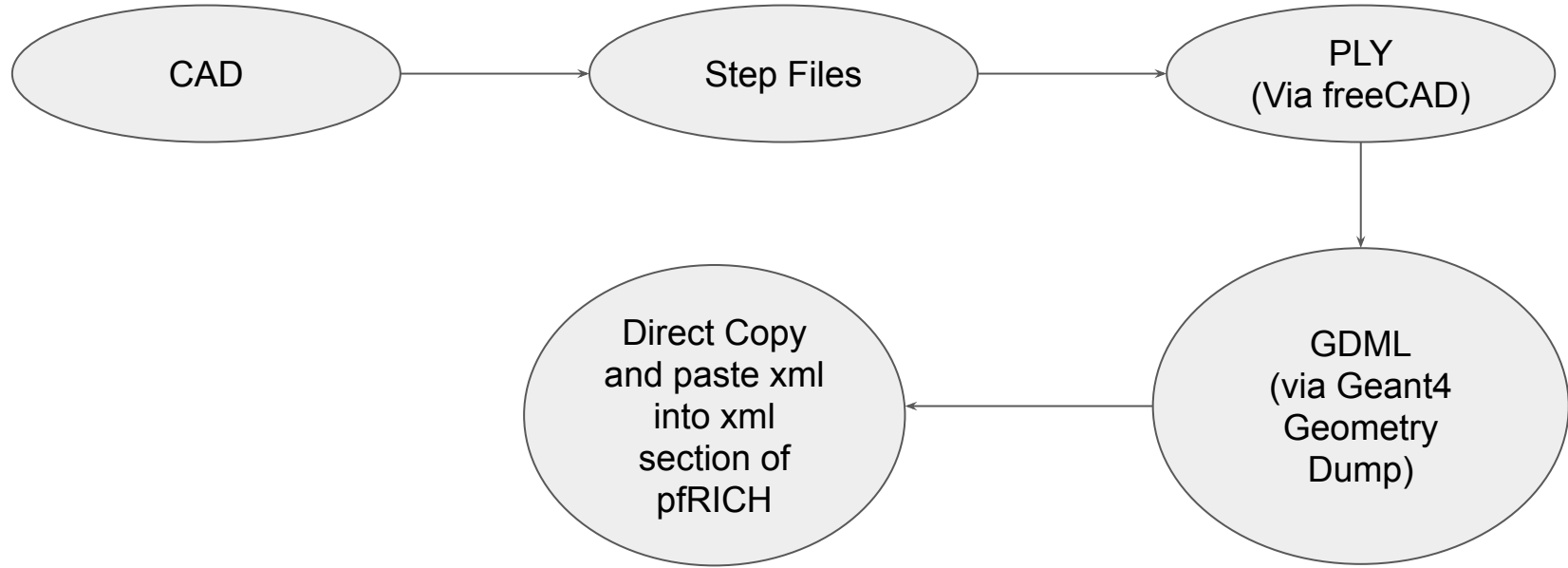
// create the detector
static Ref_t createDetector(Detector& description, xml_h e, SensitiveDetec
{
```

PFRICH_geo_v1.cpp

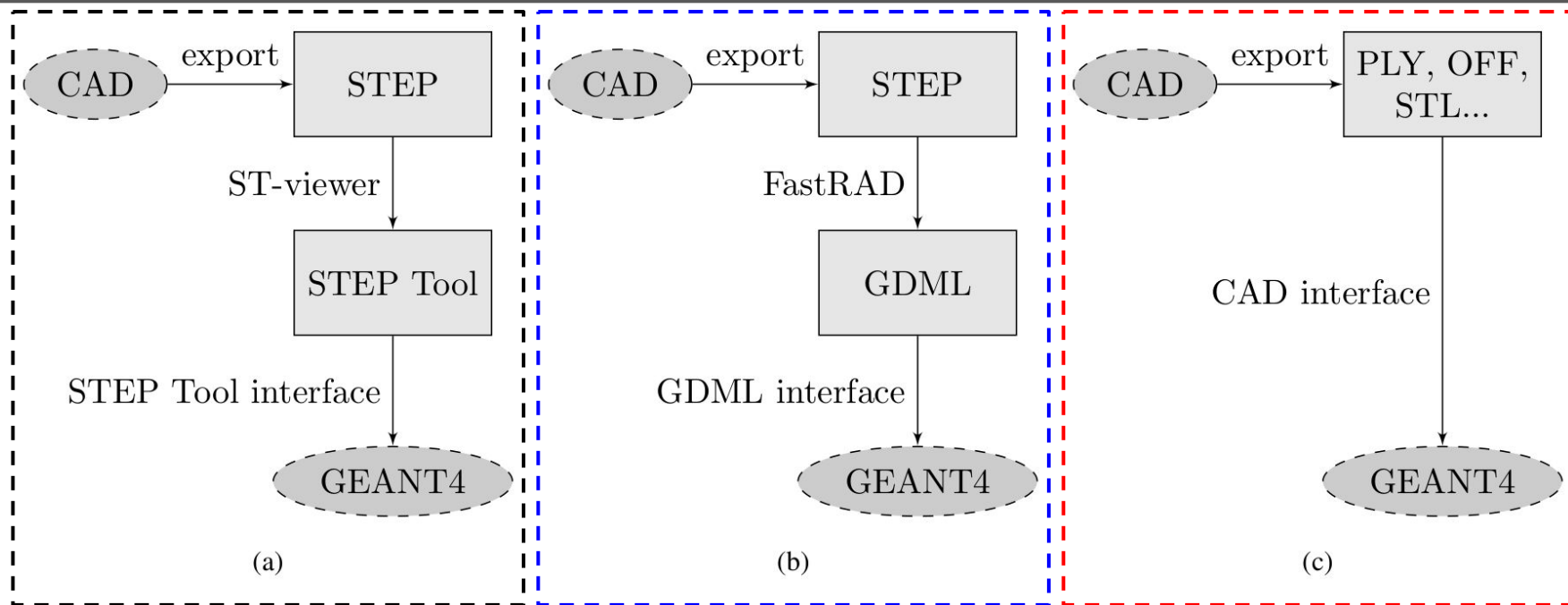
Branch:

<https://github.com/billlee77/epic/tree/pfRICH>

Documentation on Step 1



From CAD to Geant4 Model



Method 1

Indirect method

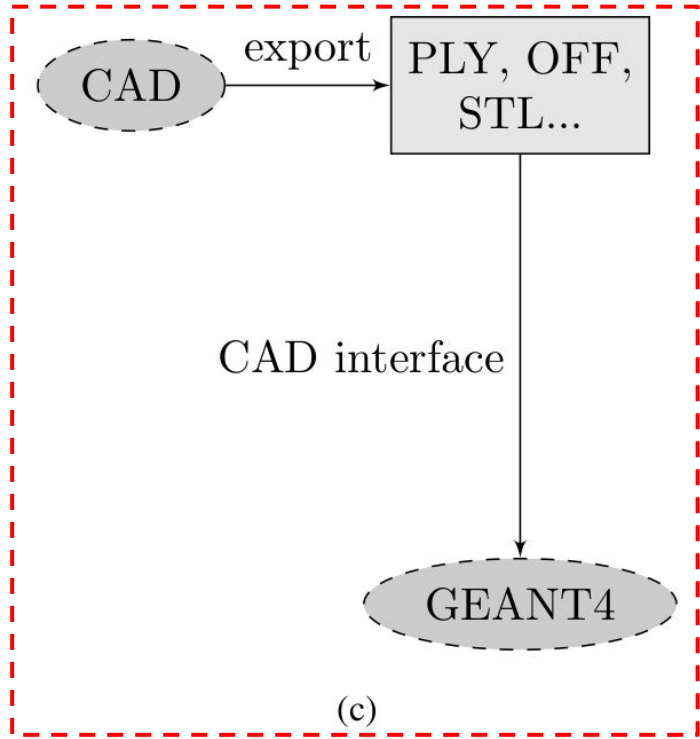
Method 2

Indirect method

Method 3

Direct method

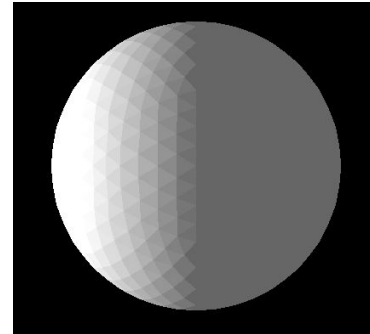
CADMesh Plugin



cow.obj



rabbit.stl



rabbit.ply