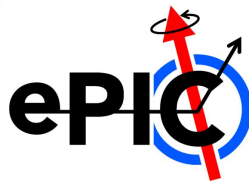
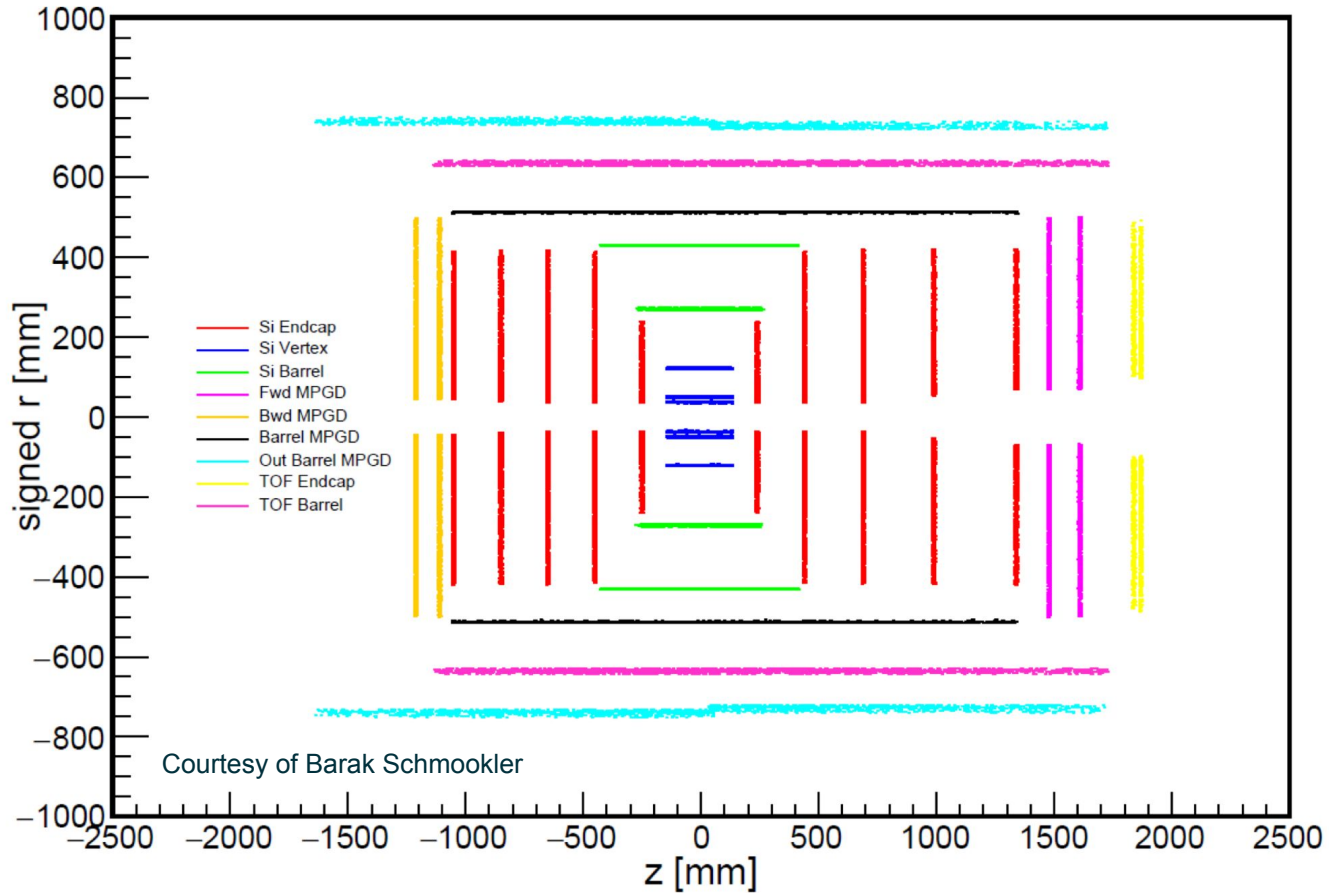


Status of Tracking and Vertexing

Shujie Li, Xin Dong
Lawrence Berkeley National Laboratory



Geant-level tracker hits



Track Reconstruction Framework

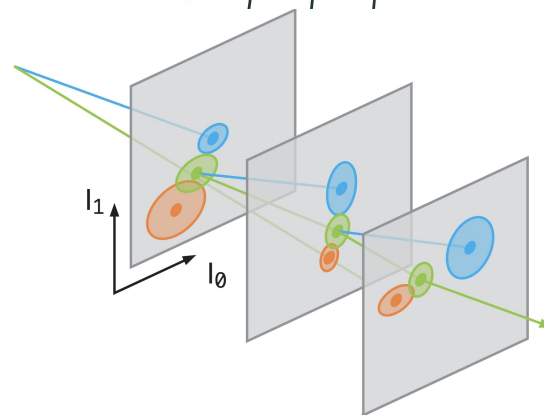
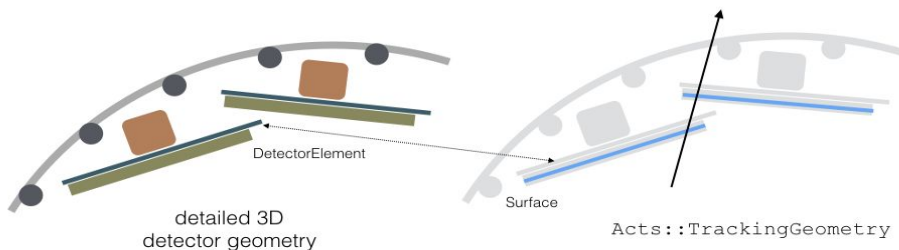
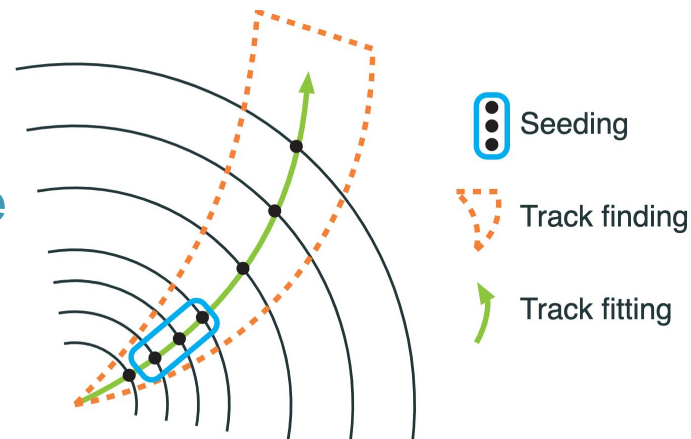
- Reconstruction Framework (**ElCrecon** <http://eicrecon.epic-eic.org/>)
 - Hits digitization
 - Track finding/fitting:



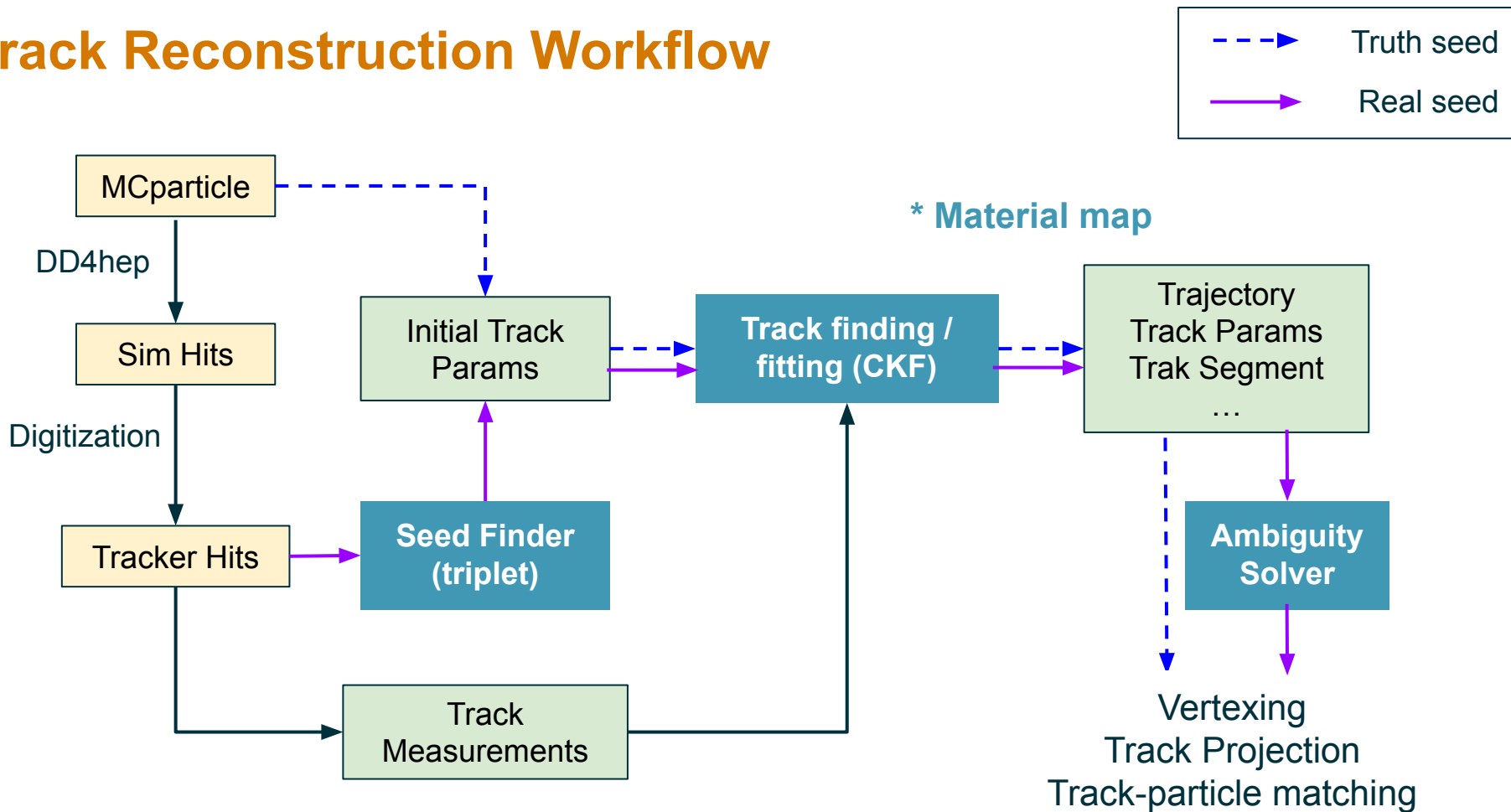
arXiv:1910.03128

A Common Tracking Software

- Combinatorial Kalman Filter (CKF)**
 - Combined track finding and fitting
 - Realistic seeder to provide initial guess



Track Reconstruction Workflow



Track Reconstruction Workflow

EICrecon/src/global/tracking/tracking.cc

Truth seed

```
app->Add(new JOmniFactoryGeneratorT<CKFTracking_factory>(
    "CentralCKFTrajectories",
    {
        "InitTrackParams",
        "CentralTrackerMeasurements"
    },
    {
        "CentralCKFTrajectories",
        "CentralCKFTrackParameters",
        "CentralCKFActsTrajectories",
        "CentralCKFActsTracks",
    },
    app
));

app->Add(new JOmniFactoryGeneratorT<IterativeVertexFinder_factory>(
    "CentralTrackVertices",
    {"CentralCKFActsTrajectories"},
    {"CentralTrackVertices"},
    {},
    app
));
```

Real seed

```
app->Add(new JOmniFactoryGeneratorT<CKFTracking_factory>(
    "CentralCKFSeededTrajectories",
    {
        "CentralTrackSeedingResults",
        "CentralTrackerMeasurements"
    },
    {
        "CentralCKFSeededTrajectories",
        "CentralCKFSeededTrackParameters",
        "CentralCKFSeededActsTrajectories",
        "CentralCKFSeededActsTracks",
    },
    app
));
```



Most downstream algorithm still uses tracking output with truth seeding to avoid duplicated tracks and other potential uncertainties.

Track Propagation and Material Effects

$$\vec{x} = (l_0, l_1, \phi, \theta, q/p, t)^T$$

$$C = \begin{bmatrix} \sigma^2(l_0) & \text{cov}(l_0, l_1) & \text{cov}(l_0, \phi) & \text{cov}(l_0, \theta) & \text{cov}(l_0, q/p) \\ . & \sigma^2(l_1) & \text{cov}(l_1, \phi) & \text{cov}(l_1, \theta) & \text{cov}(l_1, q/p) \\ . & . & \sigma^2(\phi) & \text{cov}(\phi, \theta) & \text{cov}(\phi, q/p) \\ . & . & . & \sigma^2(\theta) & \text{cov}(\theta, q/p) \\ . & . & . & . & \sigma^2(q/p) \end{bmatrix}$$

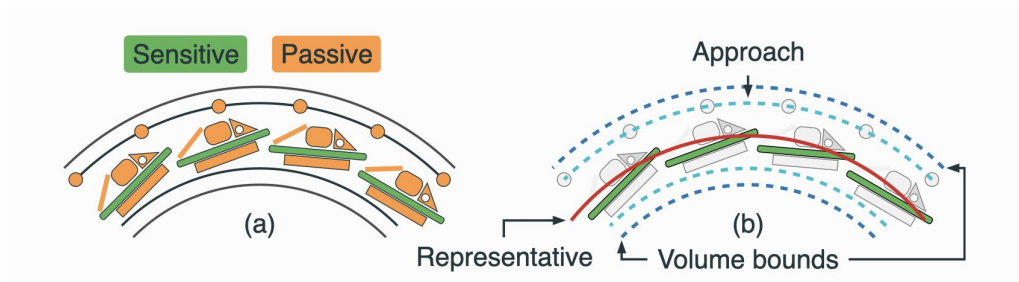
Initial to final step propagation: evolve covariance in time

$$C^f = J \cdot C^i \cdot J^T,$$

$$J = \begin{bmatrix} \frac{\partial l_0^f}{\partial l_0^i} & \dots & \frac{\partial l_0^f}{\partial (q/p)^i} \\ \vdots & \ddots & \vdots \\ \frac{\partial (q/p)^f}{\partial l_0^i} & \dots & \frac{\partial (q/p)^f}{\partial (q/p)^i} \end{bmatrix},$$

Material effects:

- Deflection and offset → averaged to 0, increased uncertainties
- Energy loss → reduced trajectory energy
- Hadronic process → disintegration etc.



❖ Workforce needed to update material map for track projection

Track Finding/Fitting Quality Check

Track residuals for truth-seeded tracking in event #1

- Si Endcap
- Si Vertex
- Si Barrel
- Fwd MPGD
- Bwd MPGD
- Barrel MPGD
- Out Barrel MPGD
- TOF Endcap
- TOF Barrel

For truth-seeded tracking, we save the track states (x,y,z) at the various tracking layers. So, we can calculate residuals.

Vertex layer residual: $\sqrt{r\Delta\phi^2 + \Delta z^2}$

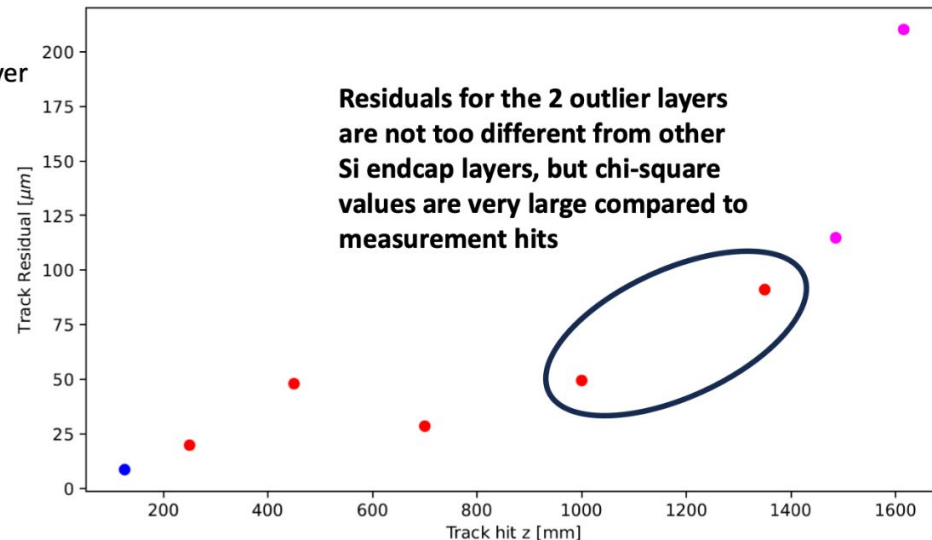
Si endcap and Fwd MPGD residuals: $\sqrt{\Delta x^2 + \Delta y^2}$

Measurement chi-square per-layer

1.8605283
0.5367326
0.5832352
0.7475767
0.0013756
6.546e-06

Outlier chi-square per layer

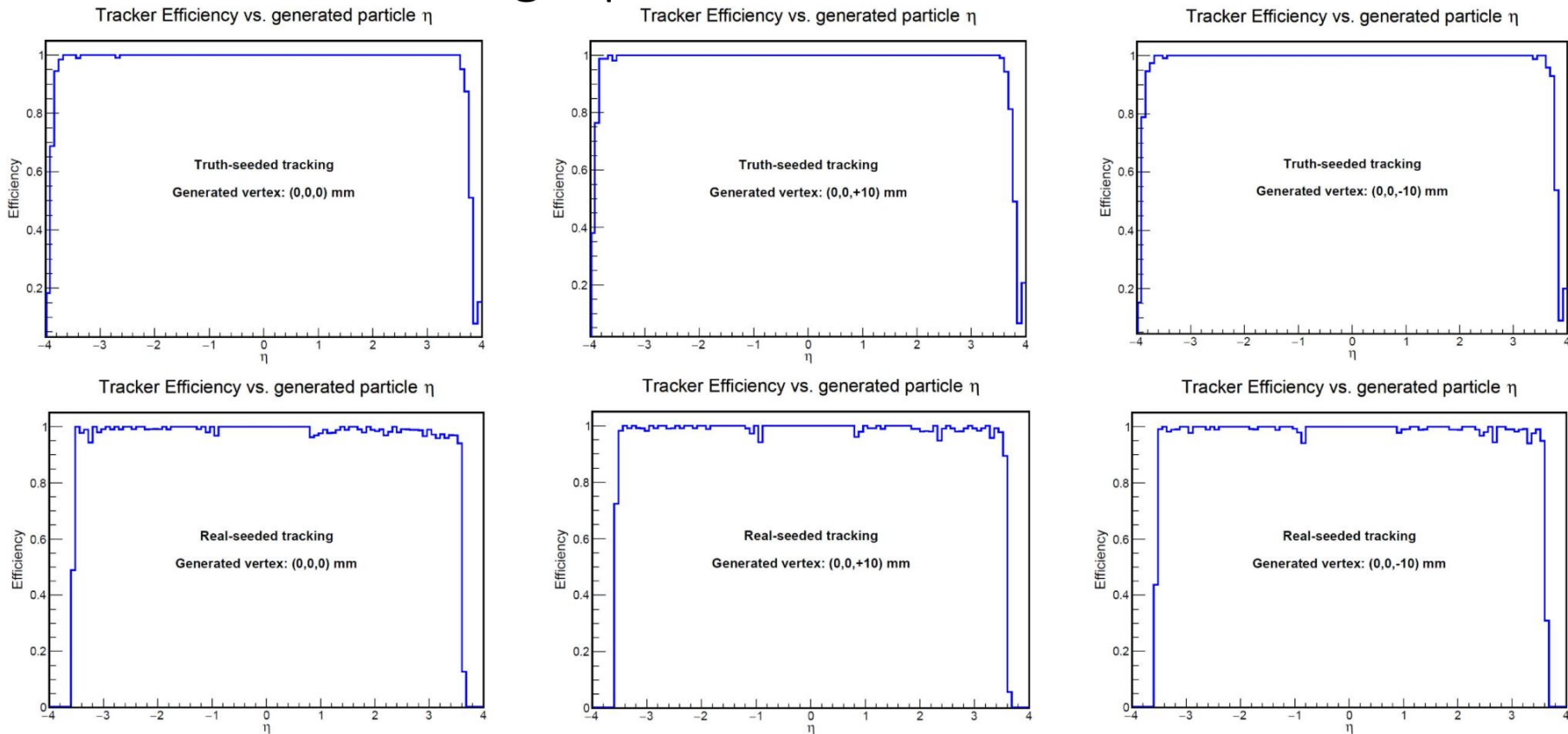
53.284168
26.377220



Tracking Efficiency

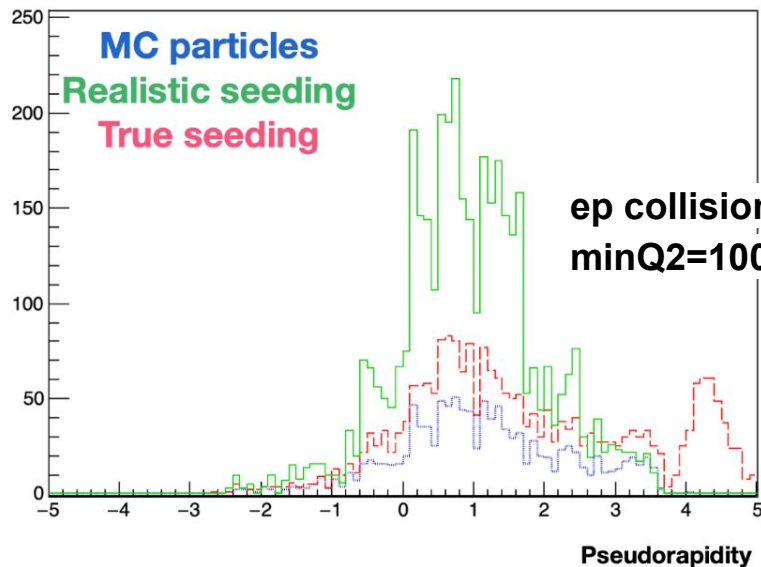
Courtesy of B. Schmookler and J. Gupta
https://indico.bnl.gov/event/21238/contributions/83543/attachments/51067/87297/tracking_111623.pdf

Single-particle reconstruction

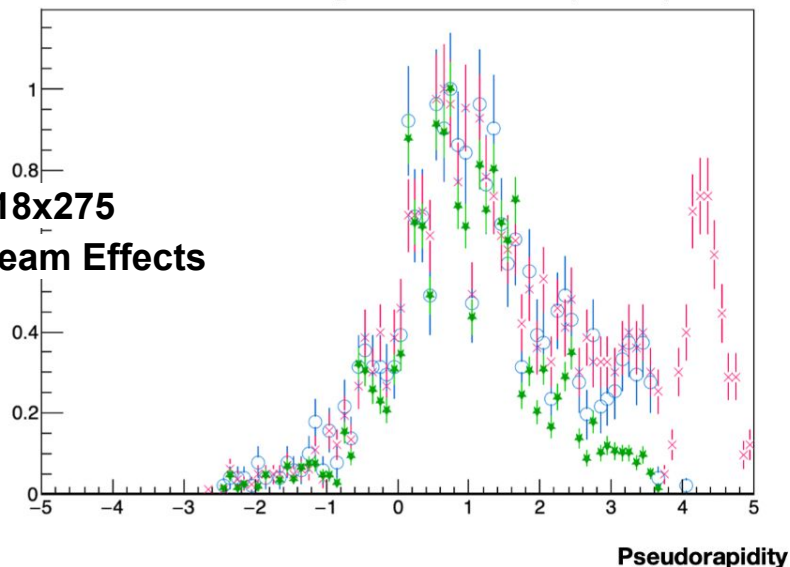


Remove Duplicates

of tracks



of tracks normalized by maximum for shape comparison



- MC particles: stable particles generating at 3 hits on silicon trackers
- Much larger entries w.r.t. MC particles in realistic seeding: duplicate seeds visible as expected
- Larger entries in true seeding w.r.t. MC particles in true seeding, with seeds in B0 acceptance

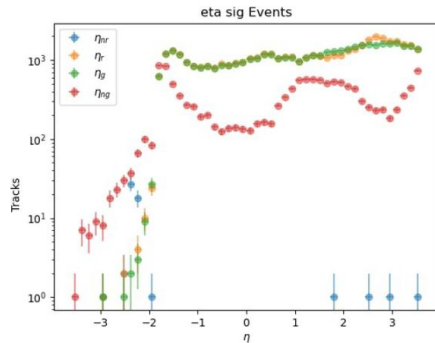
<https://indico.bnl.gov/event/20473/contributions/85366/>

First Look of DIS + Background Events

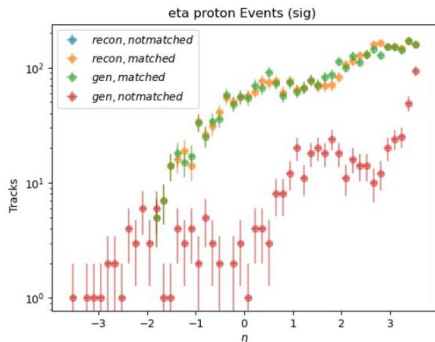
Courtesy of B. Sterwerf

<https://indico.bnl.gov/event/20473/contributions/85365/>

Sig eta



Sig eta events Protons



Breakdown By Particle Type

We see that the majority of not reconstructed MC particles are pions except in low eta regime where there is a strong electron peak

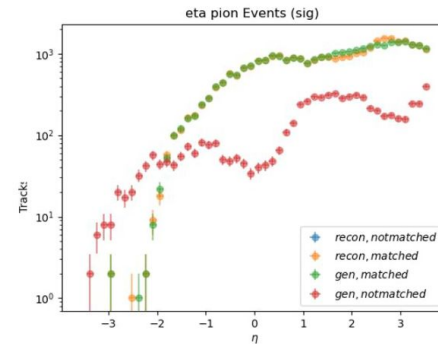
Blue=Reconstructed Particles that do not get matched

Yellow=Reconstructed Particles that get matched

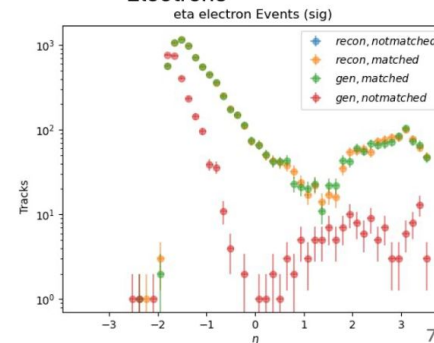
Green=MC Particles that get Reconstructed

- Red=MC Particles that do not get Reconstructed

Sig eta events Pions



Sig eta events Electrons



Plans for TDR (part 1)

- Reconstruction algorithm (to make real seed the default):
 - Check seeding and track finding at hit level
 - Check track optimization/error propagation:
 - Test initial cov matrix (Barak Schmookler, Jeet Gupta)
 - Check geometry segmentation and material map (need workforce)
 - Understand residual and χ^2 (Beatrice Liang-Gilman)
 - Remove duplicated tracks, match tracks to particles (Minjung Kim, Benjamin Sterwarf)
- Tracking performance study:
 - DIS+background (Minjung, Benjamin)
 - Prepare benchmark plots (need workforce)
 - Check the impact of BIC on tracking (need workforce)

* integration of far-forward detectors etc

Vertexing for Yellow Report

Detector Performance Matrix

η	Nomenclature			Tracking			
				Min p_T	Resolution	Allowed X/X_0	Si-Vertex
-3.5 — -3.0	Central Detector	Backwards Detectors	100 MeV π 135 MeV K	$\sigma_p/p \sim 0.1\% \times p + 2.0\%$	$\sim 5\%$ or less	$\sigma_{xy} \sim 30 \mu\text{m}/p_T + 40 \mu\text{m}$	
-3.0 — -2.5							
-2.5 — -2.0							
-2.0 — -1.5				$\sigma_p/p \sim 0.05\% \times p + 1.0\%$		$\sigma_{xy} \sim 30 \mu\text{m}/p_T + 20 \mu\text{m}$	
-1.5 — -1.0		Barrel					
-1.0 — -0.5							
-0.5 — 0.0				$\sigma_p/p \sim 0.05\% \times p + 0.5\%$		$\sigma_{xyz} \sim 20 \mu\text{m},$ $d_0(z) \sim d_0(r\phi)$ $\sim 20/p_T \text{ GeV}$ $\mu\text{m} + 5 \mu\text{m}$	
0.0 — 0.5							
0.5 — 1.0							
1.0 — 1.5		Forward Detectors		$\sigma_p/p \sim 0.05\% \times p + 1.0\%$		$\sigma_{xy} \sim 30 \mu\text{m}/p_T + 20 \mu\text{m}$	
1.5 — 2.0							
2.0 — 2.5						$\sigma_{xy} \sim 30 \mu\text{m}/p_T + 40 \mu\text{m}$	
2.5 — 3.0				$\sigma_p/p \sim 0.1\% \times p + 2.0\%$		$\sigma_{xy} \sim 30 \mu\text{m}/p_T + 60 \mu\text{m}$	
3.0 — 3.5							

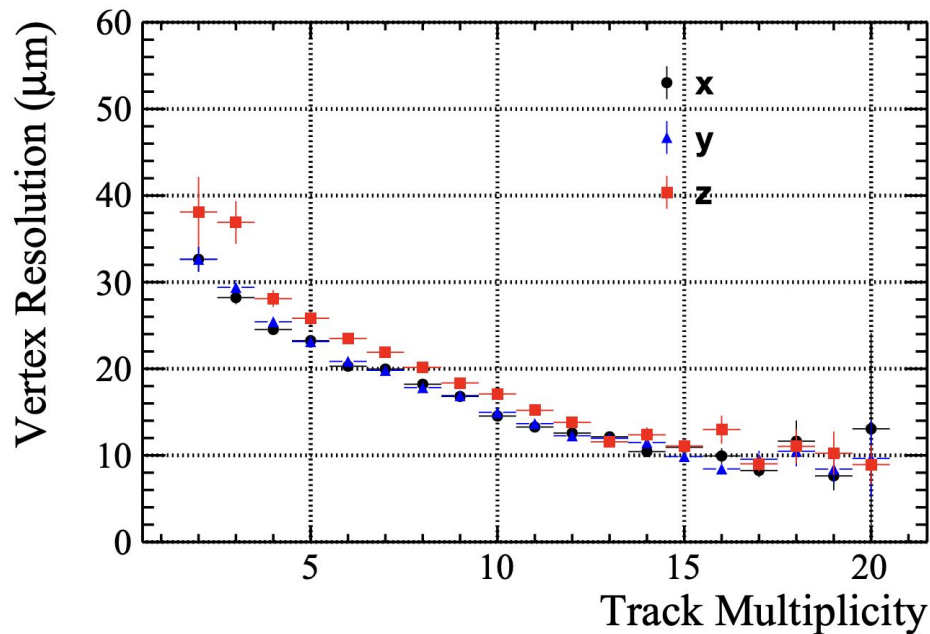
Yellow Report

Fast simulation:

DCA point smearing according to YR DCA resolution

Simple average of DCA position of primary tracks

- no error or covariance



Vertexing Algorithm in ElCrecon

- Acts::IterativeVertexFinder implemented in ElCrecon
- Trajectories used as input to Acts
- Fitted vertices filled into edm4eic::Vertex objects, stored in PODIO output
 - Collection: “CentralTrackVertices”

*edm4eic::Vertex struct missing key fields
- to-be-updated (see discussion later)*

Details in Joe Osborn’s presentation on May 18 at ePIC Track Reconstruction Meeting

<https://indico.bnl.gov/event/19358/contributions/76588/attachments/47593/80693/vertexing.pdf>

```
std::vector<const Acts::BoundTrackParameters> inputTrackPointers;

for (const auto& trajectory : trajectories) {
    auto tips = trajectory->tips();
    if (tips.empty()) {
        continue;
    }
    /// CKF can provide multiple track trajectories for a single input seed
    for (auto& tip : tips) {
        inputTrackPointers.push_back(&(trajectory->trackParameters(tip)));
    }
}

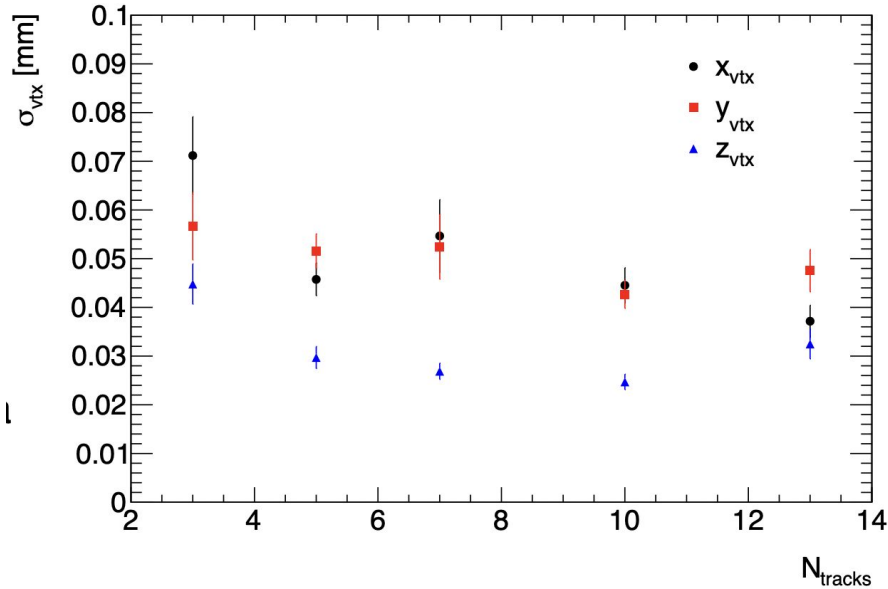
std::vector<Acts::Vertex<Acts::BoundTrackParameters>> vertices;
auto result = finder.find(inputTrackPointers, finderOpts, state);
if (result.ok()) {
    vertices = std::move(result.value());
}

for (const auto& vtx : vertices) {
    edm4eic::Cov3f cov(vtx.covariance()(0, 0), vtx.covariance()(1, 1), vtx.covariance()(2, 2),
        vtx.covariance()(0, 1), vtx.covariance()(0, 2), vtx.covariance()(1, 2));

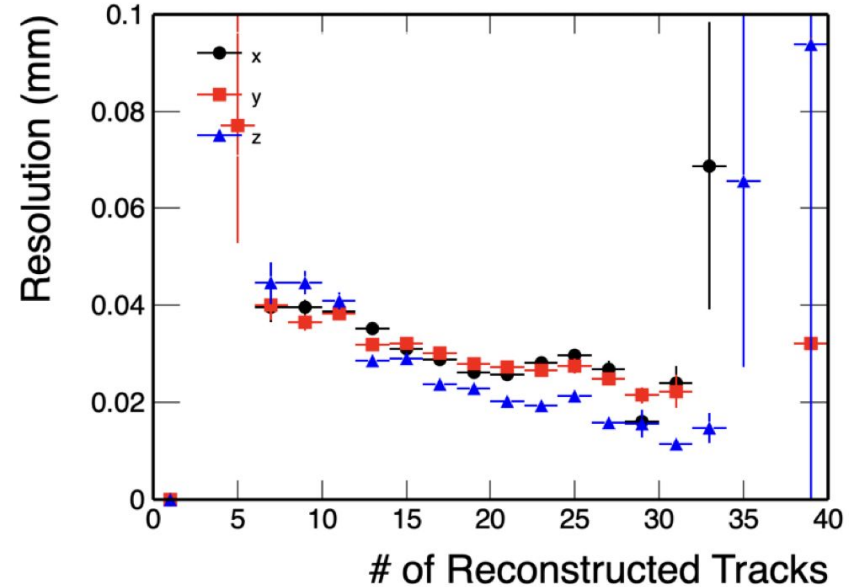
    edm4eic::Vertex* eicvertex = new edm4eic::Vertex{
        1, // boolean flag if vertex is primary vertex of event
        (float)vtx.fitQuality().first, // chi2
        (float)vtx.fitQuality().second, // ndf
        {(float)vtx.position().x(), (float)vtx.position().y(),
        (float)vtx.position().z()}, // vtxposition
        cov, // covariance
        1, // algorithmtype
        (float)vtx.time(), // time
    };
};
```

Performance Test - events starting from (0,0)

A-few-track simu - vertex (0,0,20)



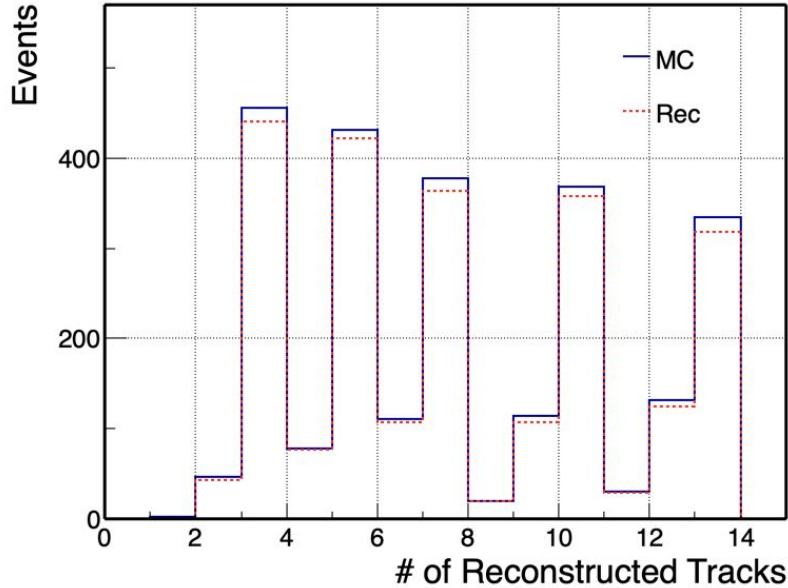
DIS (HF) simu - vertex (0,0,0)



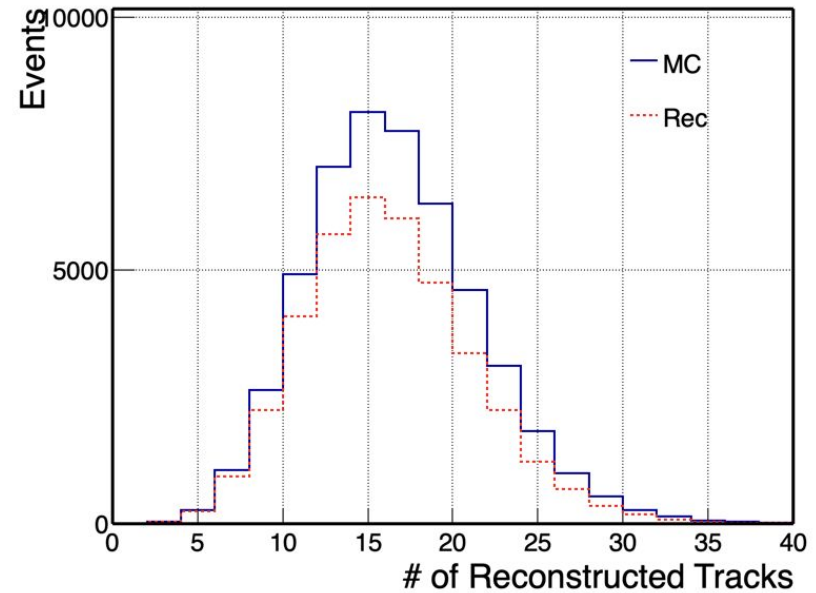
Vertexing resolution shows decent performance for events starting from (0,0)
- may be fine-tuned for optimization for different process, kinematics etc.)

Performance Test - events starting from (0,0)

A-few-track simu - vertex (0,0,20)

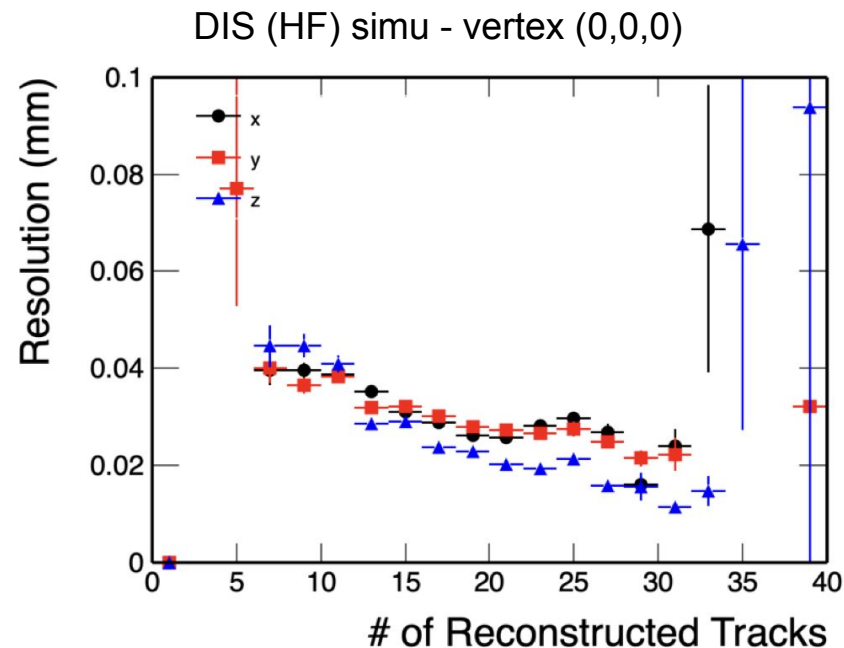
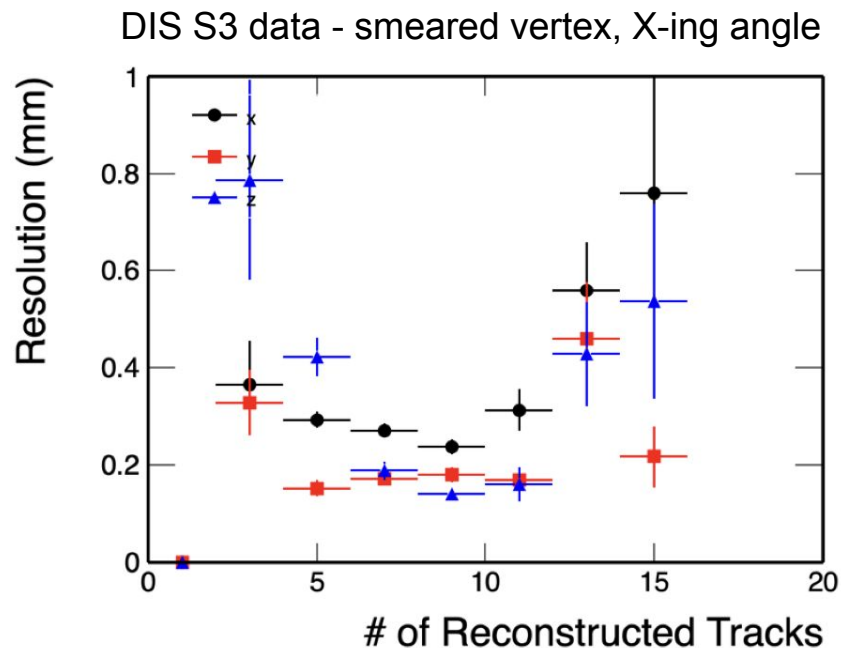


DIS (HF) simu - vertex (0,0,0)



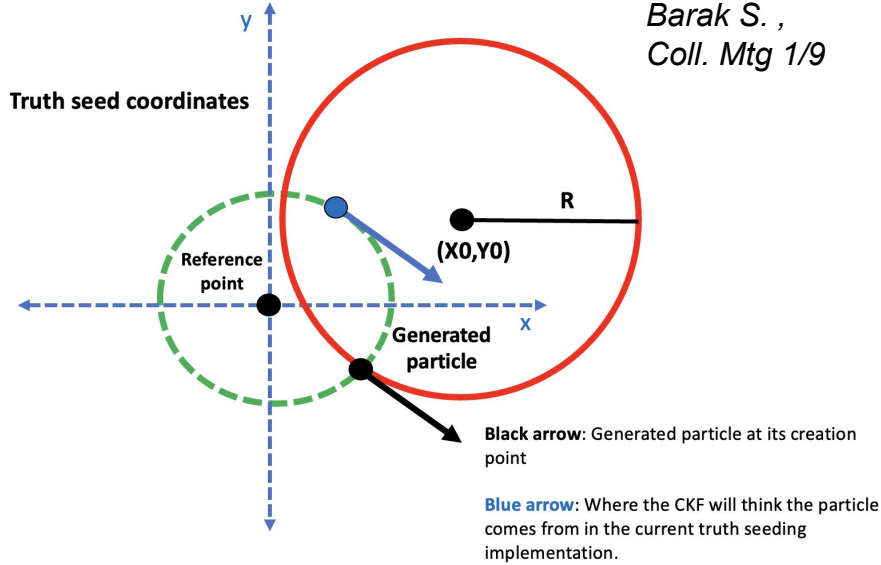
Vertexing efficiency seems to be OK, may need improvements for DIS events

Performance Test - events starting away from (0,0)

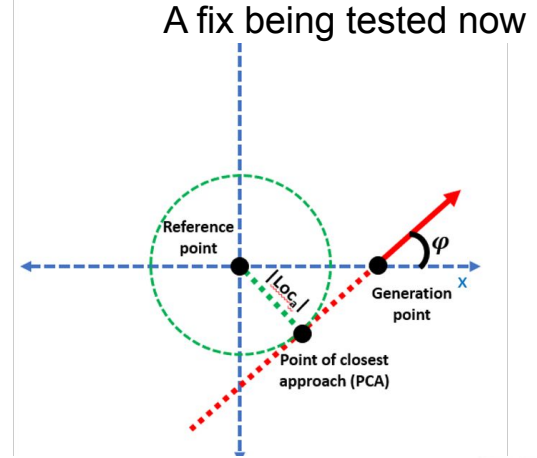


Vertexing resolution for DIS S3 events (smeared vertex) degraded by a factor of 5-10

Tracking Issue with Off-Axis Tracks



Barak S. ,
Coll. Mtg 1/9

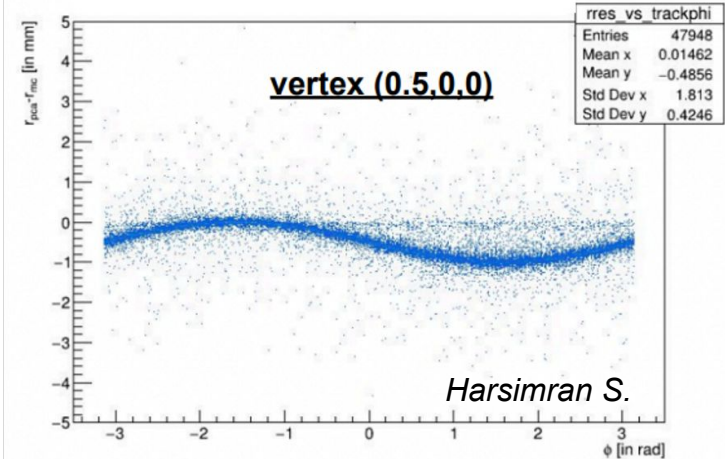


Truth-seeding:

- issue of coordinates conversion (fix being tested now)

Realistic-seeding:

- Fix to globalToLocal seed conversion. EICRecon PR [#1185](#)
- Fix to seed charge calculation. EICRecon PRs [#1213](#), [#1214](#)
- Removal of duplicate seeds



Vertex Objects in edm4eic

Current edm4eic::Vertex definition - updated recently to include a few missing information

- Need to update the corresponding filling method

Simulated Vertex: - no structure so far, using the same/similar structure? - to be discussed

- Generator level vertices (HepMC data)
- GEANT Vertices

```
edm4eic::Vertex:
  Description: "EIC vertex"
  Author: "J. Osborn"
  Members:
    - int32_t          type          // Type flag, to identify what type of vertex it is (e.g. primary,
    - float            chi2          // Chi-squared of the vertex fit
    - int              ndf           // NDF of the vertex fit
    - edm4hep::Vector4f position     // position [mm] + time t0 [ns] of the vertex. Time is 4th compone
    ## this is named "covMatrix" in EDM4hep, renamed for consistency with the rest of edm4eic
    - edm4eic::Cov4f   positionError // Covariance matrix of the position+time. Time is 4th component,
  OneToManyRelations:
    - edm4eic::ReconstructedParticle associatedParticles // particles associated to this vertex.
```

Status and Plans for TDR (part 2)

Vertexing performance for DIS events from (0,0) looks reasonable

Fix or understand tracking and vertexing performance for off-axis tracks/events

Continue evaluation of vertexing performance for a few key physics processes

Refine vertex struct objects (Rc and Mc) and their filling methods in ElCrecon

Longer term:

- Vertexing algorithm optimization

- Secondary vertex performance evaluation