# Effects of changing the initial covariance matrix

(trackparam.setLocError({...})

Jeetendra Gupta Barak Schmookler Particle : muon # of events = 10k P = [0,20] GeV/c Eta = [-4,4] Phi = [0,2pi] epic\_craterlake.xml Motivation behind studying/changing the covariance matrix (trackparam.setLocError({...}))

trackparam.setLocError({0.1,0.1})

We observe that loc a for real seeding (before and after CKF) is asymmetric and has a resolution of more than 0.1 mm



trackparam.setLocError({1,1})

By changing the error to 1 mm, we observe a big improvement in the loc a for real seeding after CKF. It becomes symmetric and is almost same as that of truth seeding



### consequences

1) Improvement in charge calculation for real seeding after CKF



### Before changing the covariance matrix



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## After changing the covariance matrix



### 2) Improvement in unique tracks for real seeding after CKF (2 mrad angle cut)

trackparam.setLocError({0.1,0.1})



trackparam.setLocError({1,1})
More single unique tracks are observed



#### 3) Improvement in Momentum distribution for real seeding after CKF (2 mrad angle cut)

trackparam.setLocError({0.1,0.1})



![](_page_8_Figure_4.jpeg)

Momentum distribution

Vertex = (0,0,0) mm

trackparam.setLocError({1,1}) Momentum distribution looks more uniform now for real seeding after CKF, especially in low momentum region

### 4) Improvement in Phi distribution for real seeding after CKF (2 mrad angle cut)

trackparam.setLocError({0.1,0.1})

![](_page_9_Figure_2.jpeg)

trackparam.setLocError({1,1}) Phi distribution for real seeding after CKF also improves

![](_page_9_Figure_4.jpeg)

Vertex = (0,0,0) mm

### 5) Improvement in Theta distribution for real seeding after CKF (2 mrad angle cut)

trackparam.setLocError({0.1,0.1})

![](_page_10_Figure_2.jpeg)

trackparam.setLocError({1,1}) Theta distribution also becomes better for real seeding after CKF

![](_page_10_Figure_4.jpeg)

Vertex = (0,0,0) mm

## Working progress

trackparam.setLocError({0.1,0.1}) More tracks with 2 measurements are observed

number of measurements

![](_page_11_Figure_3.jpeg)

trackparam.setLocError({1,1}) Less tracks with 2 measurements are observed

number of measurements

8000 7000 6000 5000 4000 3000 2000 1000

Vertex = (0,0,0) mm

## Number of outliers

trackparam.setLocError({0.1,0.1})

#### trackparam.setLocError({1,1})

![](_page_12_Figure_3.jpeg)

#### trackparam.setLocError({0.1,0.1})

![](_page_13_Figure_1.jpeg)

number of holes

Vertex = (0,0,0) mm

trackparam.setLocError({1,1})

Vertex = (0,0,0) mm

![](_page_14_Picture_0.jpeg)

trackparam.setLocError({0.1,0.1})

![](_page_14_Figure_2.jpeg)

![](_page_14_Figure_3.jpeg)

Vertex = (10,0,0) mm

#### trackparam.setLocError({1,1})

![](_page_14_Figure_6.jpeg)