

ePIC Progress Report

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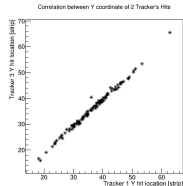
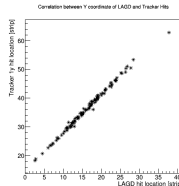


Updates on LAGD Resolution Studies

- ▶ Fixed Mapping problems in Amore
 - Combination of a few issues and misunderstandings
- ▶ Calculated potential final resolution plots

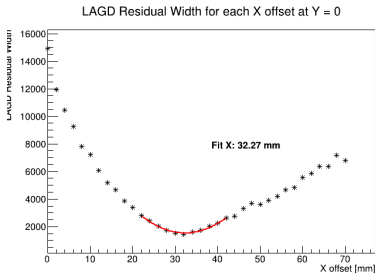
Lessons learned about Amore

- ▶ Understanding the use of SRSMapping, SRSAPVEvent, and SRSHit
- ▶ Followed similar mapping scheme used for Trackers
 - Except for pin to strip mapping
- ▶ Ultimately the X and Y APVs were swapped in the config file, which led to strip correlation plots with no correlation



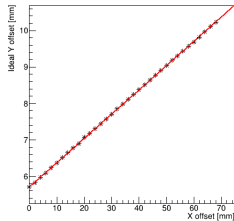
Better Xoffset Alignment

- ▶ Having issues with fit functions before
 - Applied parabola around the minimum data value ± 10 mm
 - much better results for X offset
- ▶ Makes both methods ive used agree, and makes M2 unnecessary
- ▶ Tested my code with data from another hit location, gave expected result! :)

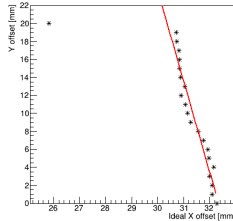


New Tracker Offset plots

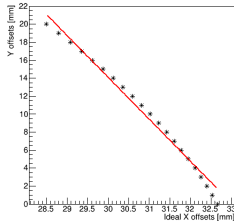
Ideal Y offset Per X offset



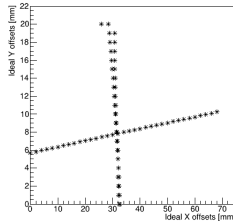
Ideal X offset Per Y offset method 1



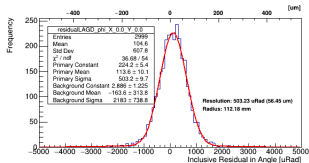
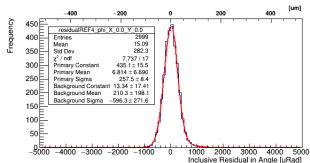
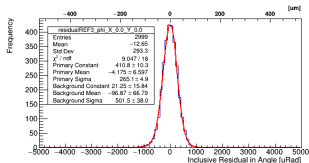
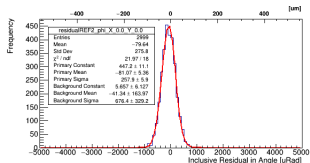
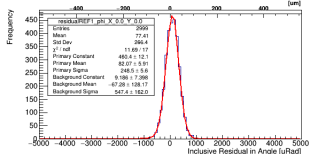
Method 2 to find X offset



Ideal X and Y offsets

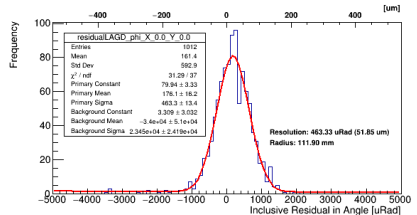
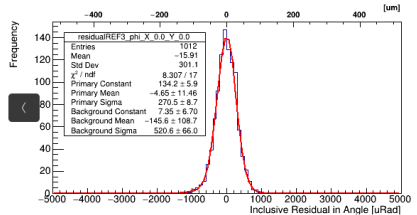


New LAGD and Tracker Angular Residual plots



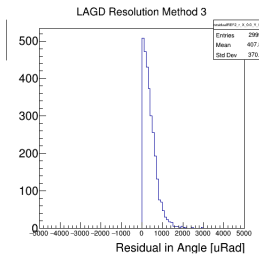
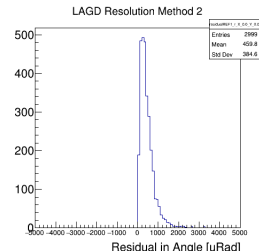
New residual plots

- New residual plots with new stats and axis
 - converted to uRad and um
 - All gaussian stats



Calculating Resolution

- ▶ Error from the data is combination of LAGD and Tracker intrinsic error add in quadrature
- ▶ $res_{M2} = \sqrt{|\sigma_{EXC}^2 - \sigma_{Tracker}^2|}$
 - or $res_{M3} = \sqrt{\sigma_{EXC} * \sigma_{INC}}$
- ▶ Tried histogramming individual resolutions for easier stats determination
- ▶ M2 gives $460.2 \text{ uRad} \pm 7.0 \text{ uRad}$
- ▶ M3 gives $407.8 \text{ uRad} \pm 6.8 \text{ uRad}$



TECH

Calculating Tracker Resolution

- ▶ Using Method 2, I wrote a code to determine the Resolutions for the Trackers
- ▶ Iterates through each tracker and finds σ_{Exc} and σ_{Track}
- ▶ All Trackers around 50 μm as expected

