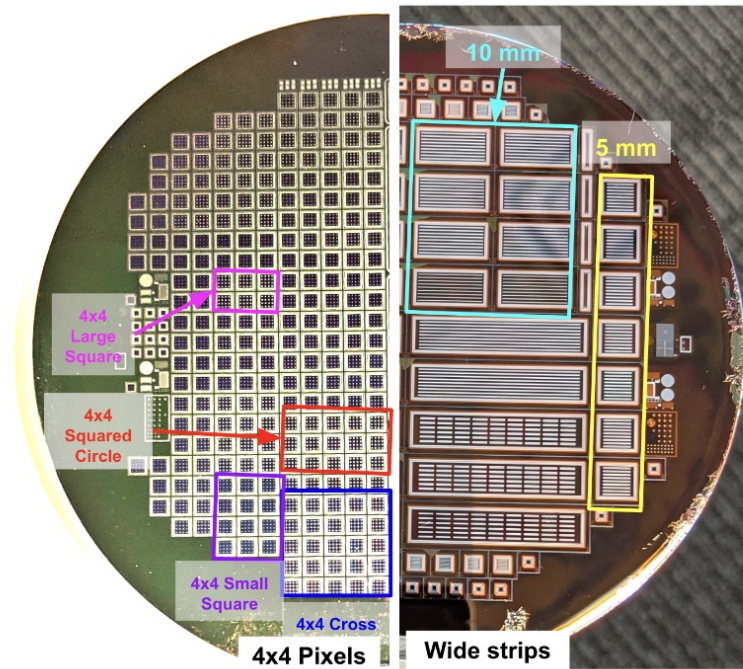


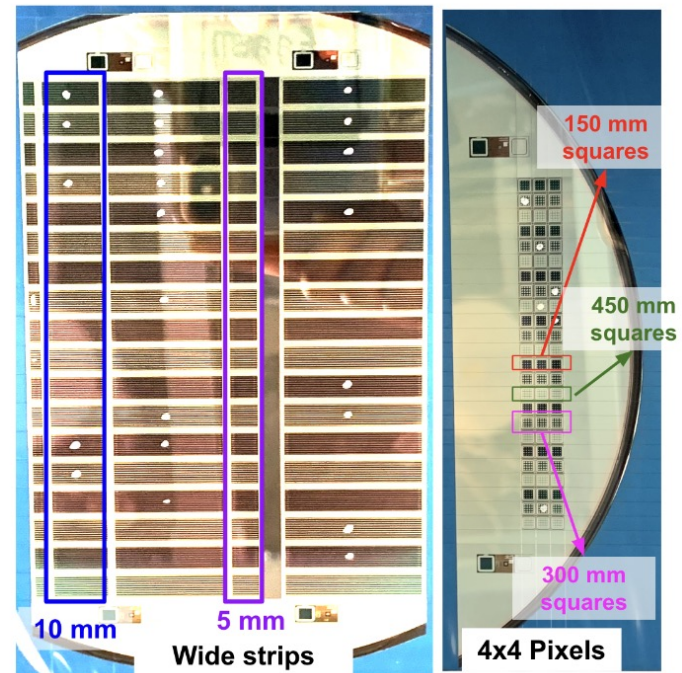
# HPK vs BNL AC-LGAD Sensors

ePIC AC-LGAD TOF DSC Weekly Meeting

Shirsendu Nanda

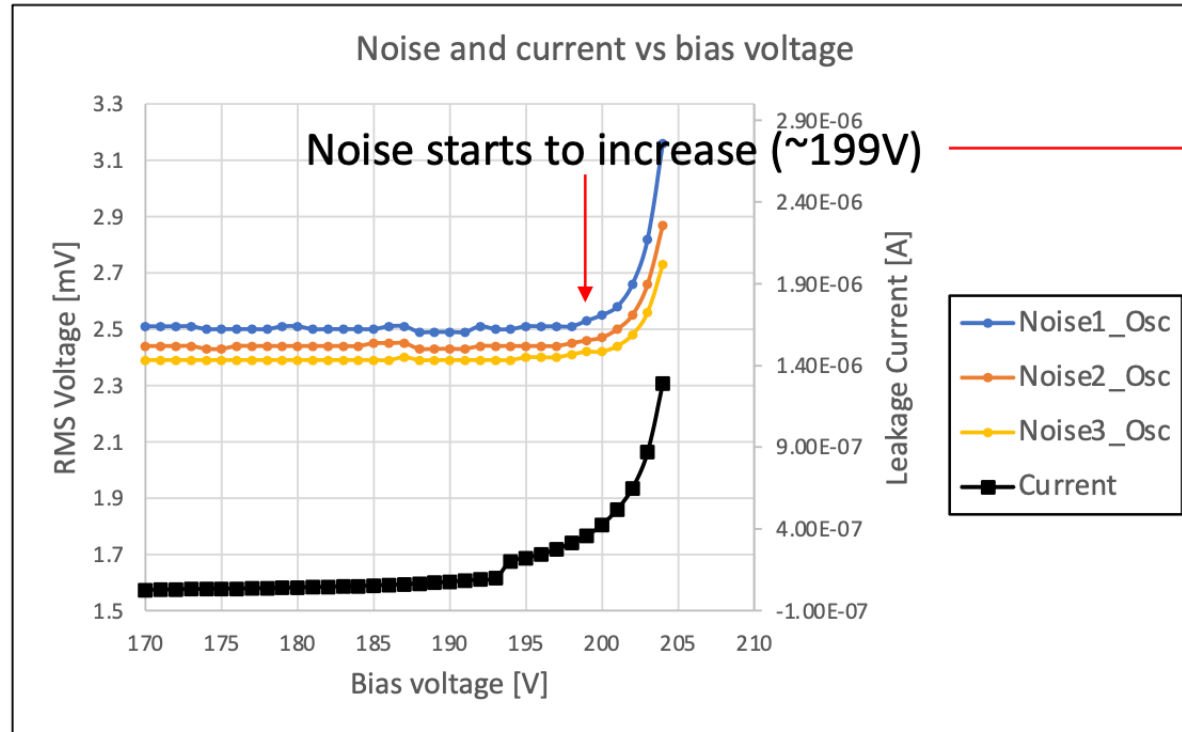


**BNL-IO**



**HPK**

# Choice of operating voltage:



Sensor is operated at 198V.

- Leakage current vs. bias voltage, and noise (from all channels) vs. bias voltage
- Find the bias voltage where the noise begins to increase. Sensor is operated at 1-2 volts below that bias voltage.
- At the same time keep a check on the leakage current (sensor not operated at very high current)

# Systematic Study of Sensor Performance: Strip

Name	Wafer	Pitch ( $\mu\text{m}$ )	Strip length (mm)	Metal width ( $\mu\text{m}$ )	Active thickness ( $\mu\text{m}$ )	Sheet resistance ( $\Omega/\square$ )	Capacitance (pF/mm <sup>2</sup> )	Optimal bias voltage (V)
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**HPK Wide strip**

SH1	W9				20	1600	600	114
SH2	W4	500	10	50	50	400	240	204
SH3	W8						600	200
SH4	W2						240	180
SH5	W5					1600	600	190
SH6	W9							
SH7	W8				50	400	600	208

**HPK 50  $\mu\text{m}$  thick**

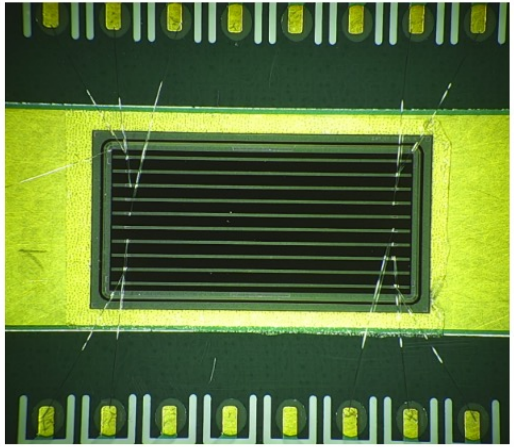
**BNL Wide strip**

SB1	WB1			50	50	1400	270	170
SB2	WB1	500	10	100	50	1400	270	160
SB3	WB2			50	50	1400	260	185

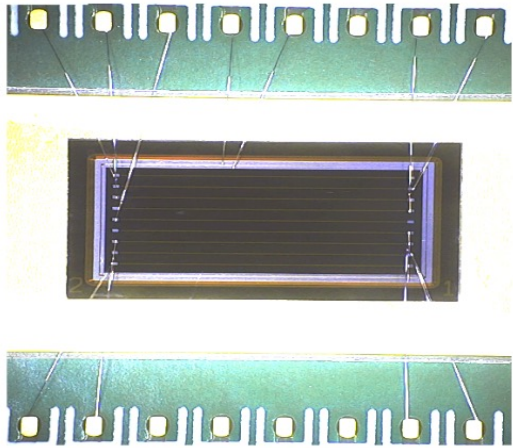
**BNL 50  $\mu\text{m}$  thick, higher capacitance**

**BNL 50  $\mu\text{m}$  thick, lower capacitance**

**SH7**



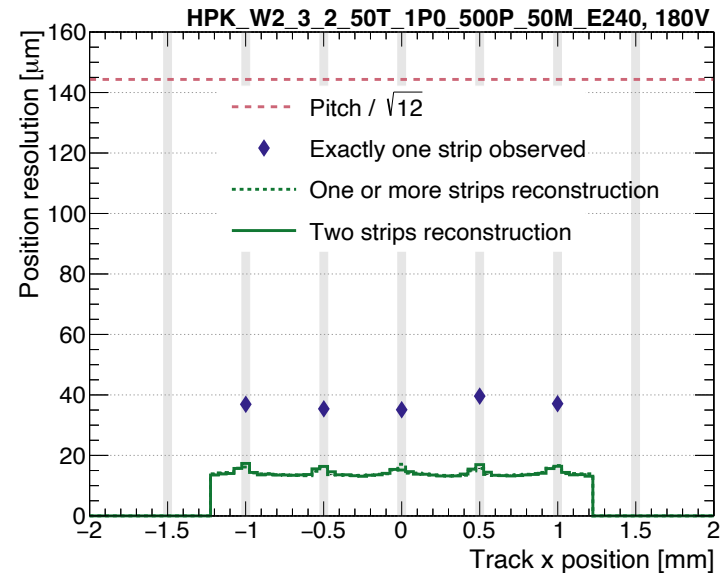
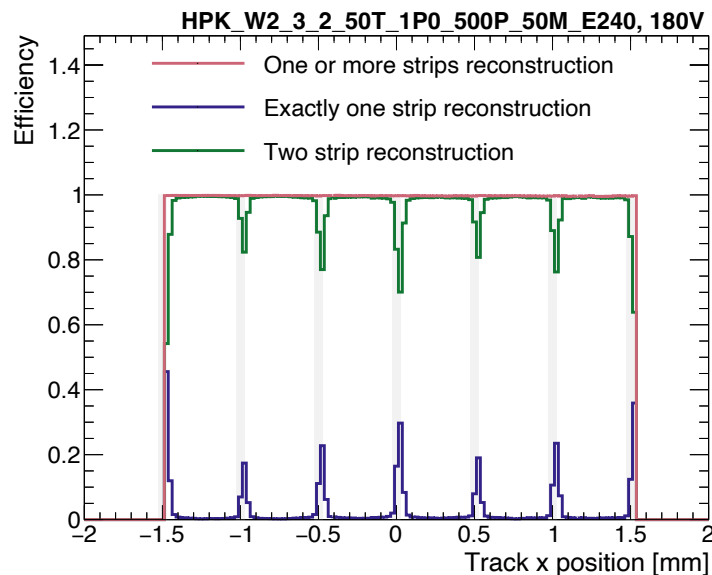
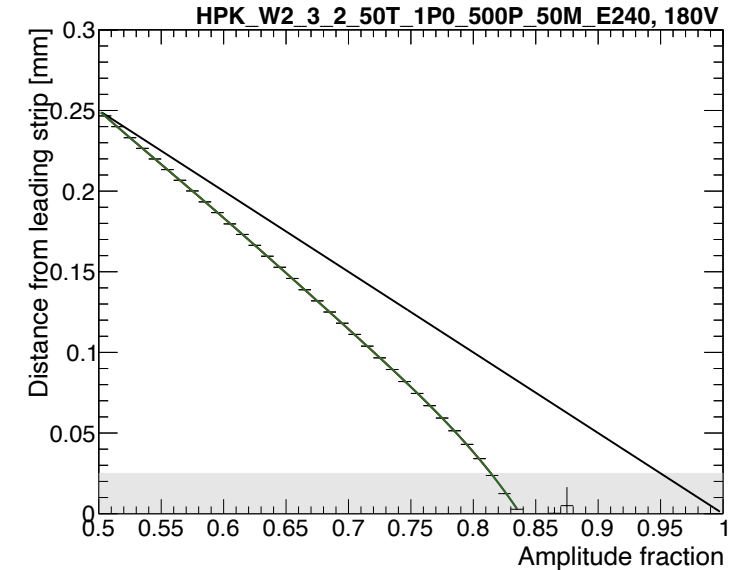
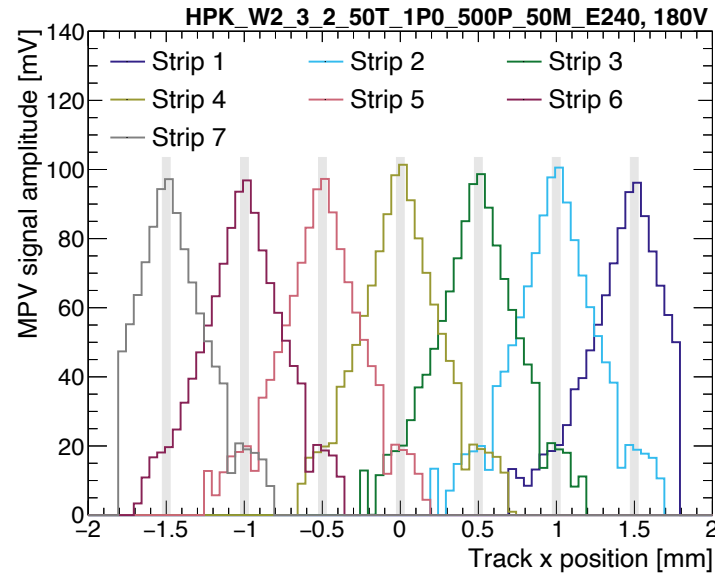
**SB1**



# Spatial resolution in AC-LGADs:

HPK Strip : 10 mm length, 500  $\mu\text{m}$  pitch, 50  $\mu\text{m}$  metal width, 1600  $\Omega/\square$  resistivity, and 240 pF/mm<sup>2</sup> capacitance

- Signal sharing between strips enables the  $x$  position reconstruction
- Amplitude fraction  $f = a_1 / (a_1 + a_2)$  where  $a_1$  and  $a_2$  are the leading and sub-leading strip amplitudes
- Two-strip reconstruction at gap and one-strip reconstruction on metal

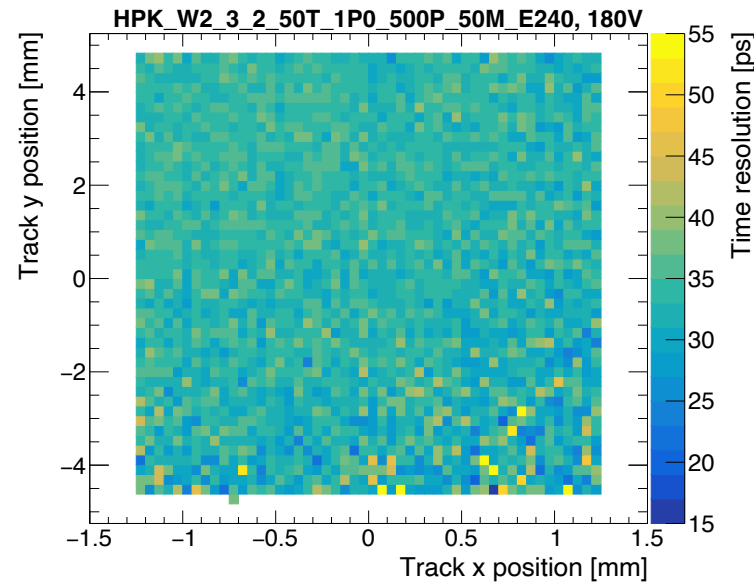
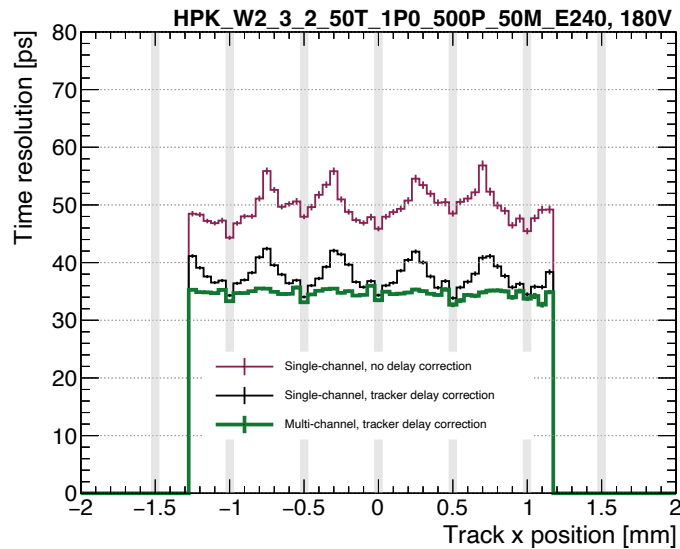
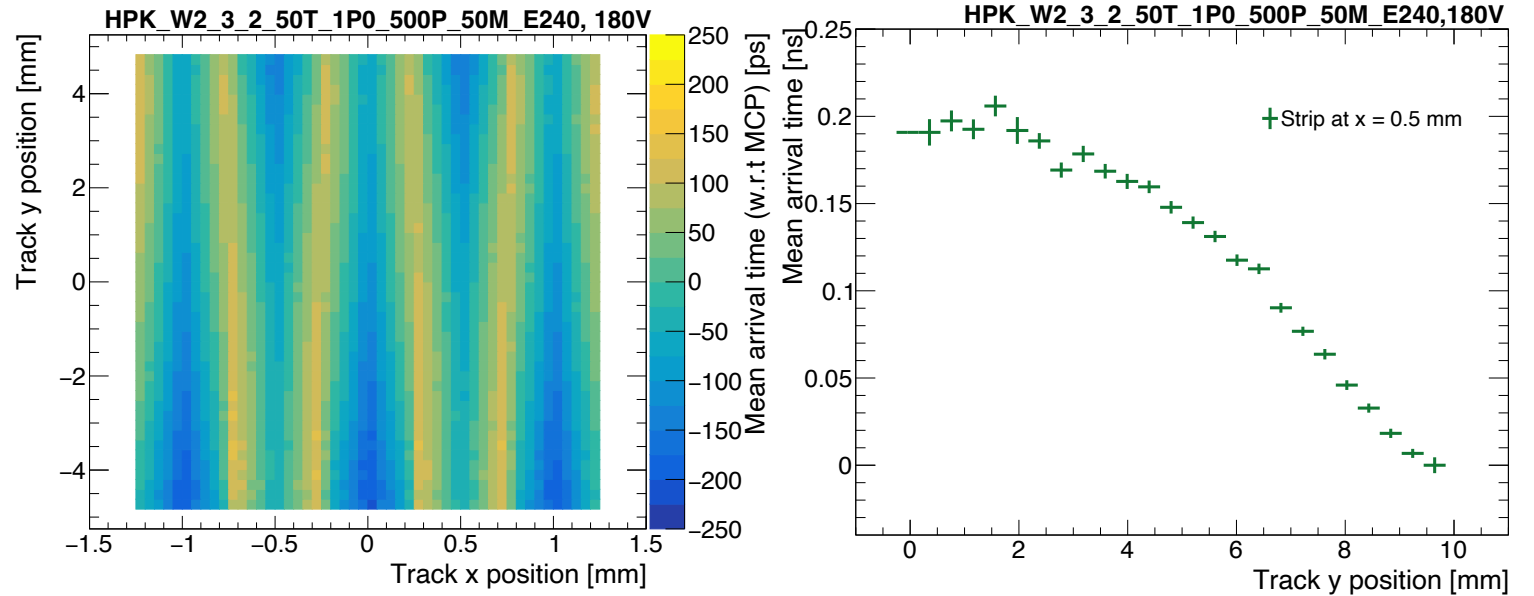


- Efficiency reaches  $\sim 100\%$
- Two-strip resolution  $\sim 12 - 15 \mu\text{m}$
- One-strip resolution  $\sim 40 \mu\text{m}$  on metal

# Time resolution in AC-LGADs:

**HPK Strip : 10 mm length, 500  $\mu\text{m}$  pitch, 50  $\mu\text{m}$  metal width, 1600  $\Omega/\square$  resistivity, and 240 pF/mm<sup>2</sup> capacitance**

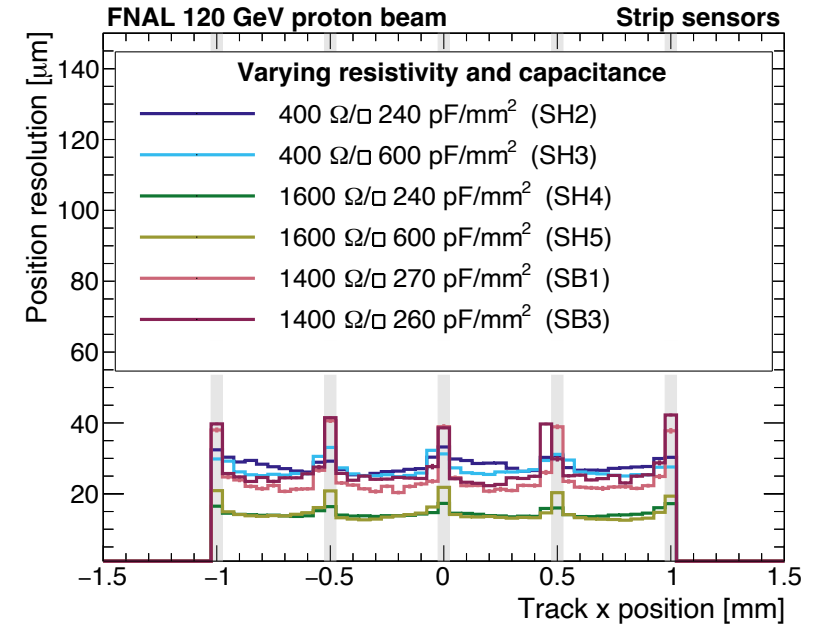
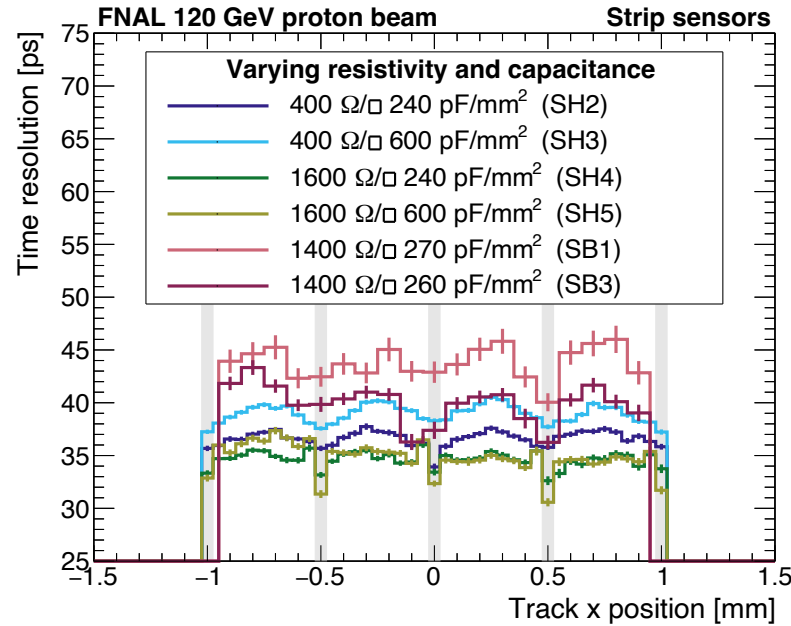
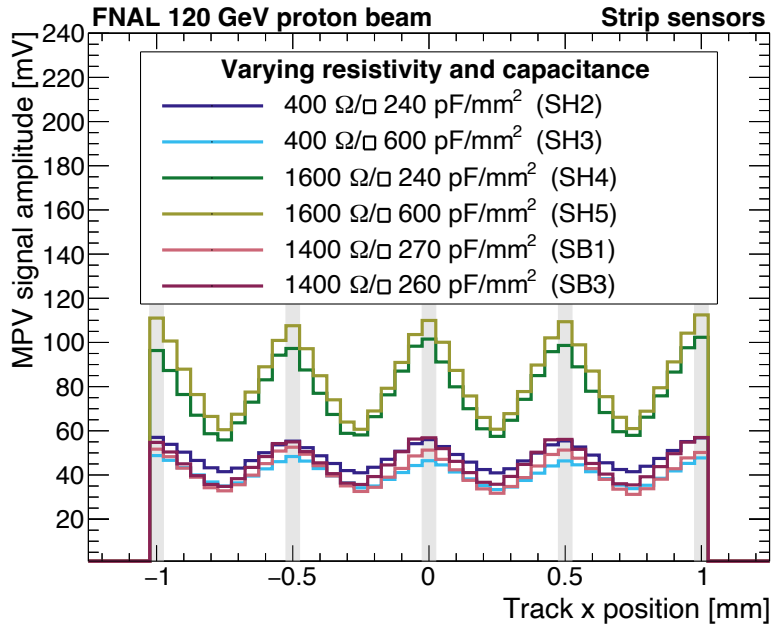
- Due to larger electrodes, distant signals arrival with delays O(100 ps)
- Position-dependent time delay correction is essential, using the external tracker
- Delay map use the resolution of 50  $\mu\text{m}$  for x position and 200  $\mu\text{m}$  for y position
- Multi-channel time stamp,  $t_{\text{reco}} = \frac{a_1^2 t_1 + a_2^2 t_2}{a_1^2 + a_2^2}$



- Without delay correction, the time resolution  $\sim 45 - 55$  ps
- Adding the tracker-based delay corrections improves the resolution to  $\sim 35 - 42$  ps
- Using multi-channel timestamp with delay correction, time resolution  $\sim 34$  ps

# Test Beam Results on Strip Sensors (BNL vs HPK):

50  $\mu\text{m}$  thick, 50  $\mu\text{m}$  metal width and 500  $\mu\text{m}$  pitch



## Summary

- **HPK (SH2, SH3, SH4, SH5):**
  - Higher n+ resistivity = less charge sharing = higher signal amplitude = less jitter = better timing resolution
  - Higher AC-coupling capacitance = less charge sharing = higher signal amplitude
- **HPK vs BNL (SB1, SB3)**
  - Amplitude and resolution of BNL sensors similar like lower resistivity (C-type) HPK sensors
  - Signal amplitude, timing and position resolutions of HPK sensors are much better than BNL-IO sensors

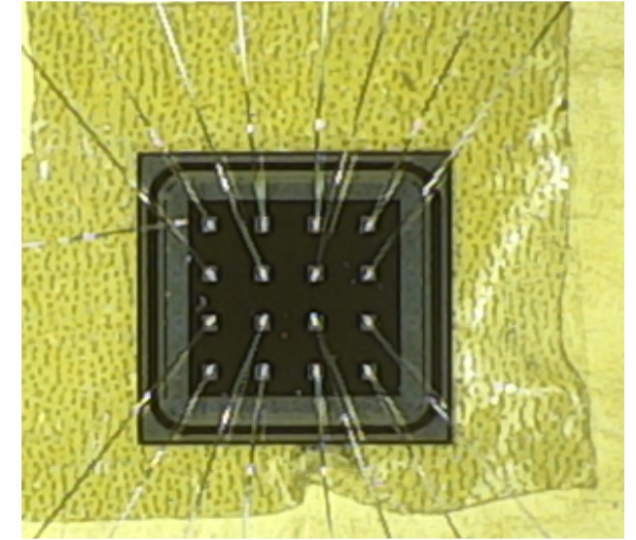
# Systematic Study of Sensor Performance: Pixel

Name	Wafer	Pitch [ $\mu\text{m}$ ]	Metal width [ $\mu\text{m}$ ]	Active thickness [ $\mu\text{m}$ ]	Sheet resistance [ $\Omega/\square$ ]	Capacitance [pF/mm <sup>2</sup> ]	Optimal bias voltage [V]
HPK 2 x 2 Square pixel							
PH1	WP1	510	500	20	1600	600	105
PH2	WP2			30	1600	600	140
PH3	WP3			50	1600	600	190

## HPK 4 x 4 Square pixel

PH4	W11	500	150	20	400	600	116
PH6	W8			50	400	600	200
PH7	W5			1600	600	185	
PH8	W9			300	1600	600	112

HPK 20  $\mu\text{m}$  thick square



PH4

## BNL 4 x 4 Square pixel

PB1	WP4	500	100	20	1400		76
PB2	WP4		200	20	1400	695	80

BNL 20  $\mu\text{m}$  thick

Small Square

Large Square

## BNL 4 x 4 Squared Circle pixel

PB3	WP4	500	110(*)	20	1400	695	85
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Squared circle

## BNL 4 x 4 Cross pixel

PB4	WP4	500	400x25(**)	20	1400	695	80
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Cross

## BNL 4 x 4 Square pixel

PB5	WP5	500	100	30	1400	385	115
PB6	WP5		200	30	1400	385	115

BNL 30  $\mu\text{m}$  thick

Small Square

Large Square

## BNL 4 x 4 Squared Circle pixel

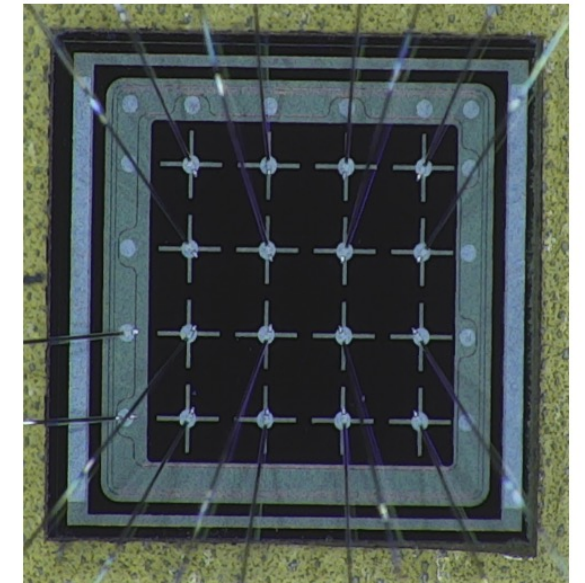
PB7	WP5	500	110(*)	30	1400	385	110
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Squared circle

## BNL 4 x 4 Cross pixel

PB8	WP5	500	400x25(**)	30	1400	385	115
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Cross



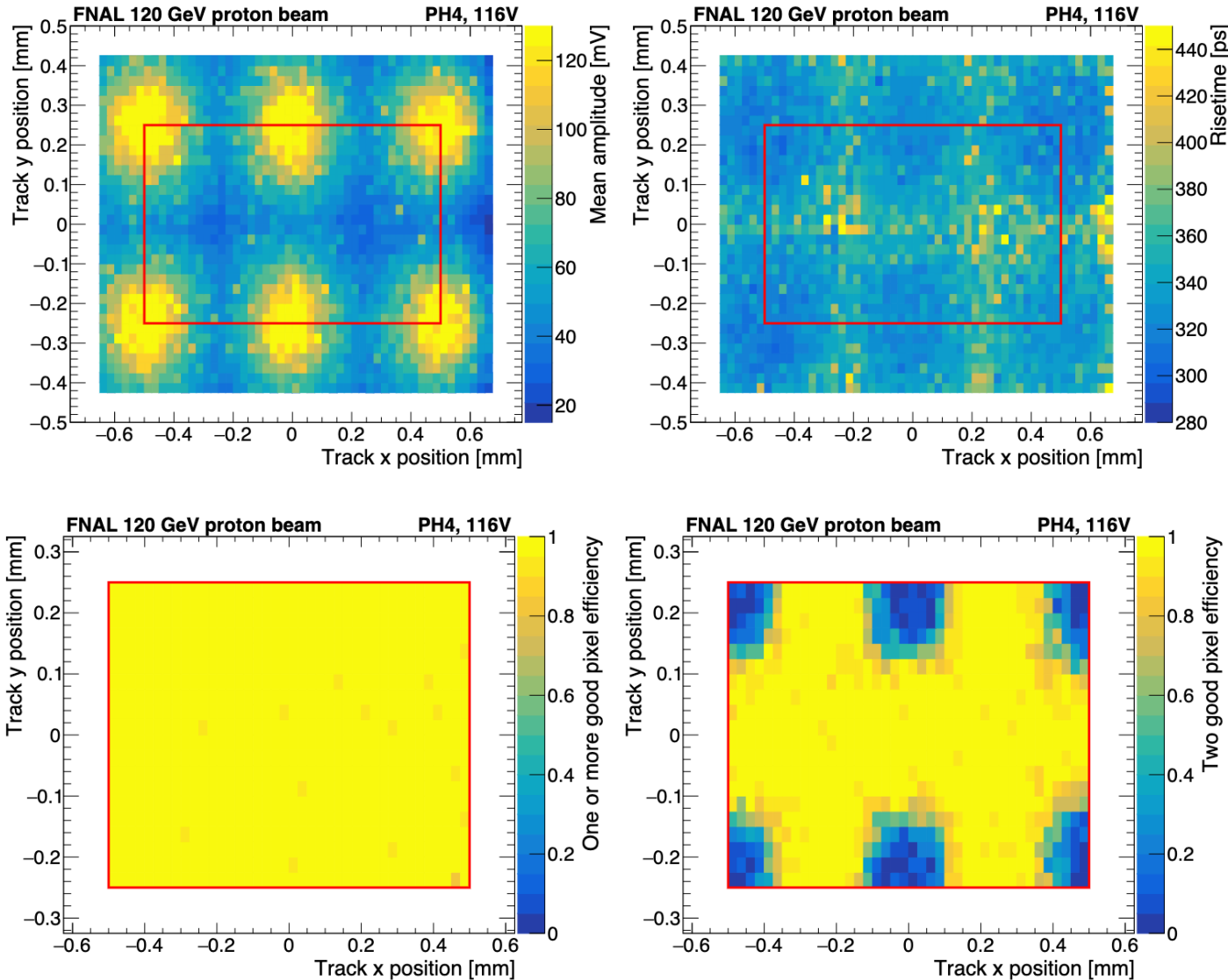
PB4

(\*) diameter of the circular metal pad

(\*\*) sensor pads form a cross shape with two metal strips that are 400  $\mu\text{m}$  long and 25  $\mu\text{m}$  wide

# AC-LGAD pixel sensors:

HPK Pixel : 500 x 500  $\mu\text{m}$  pitch, 20  $\mu\text{m}$  thickness, 150  $\mu\text{m}$  metal width, 400  $\Omega/\square$  resistivity, and 600 pF/mm<sup>2</sup> capacitance

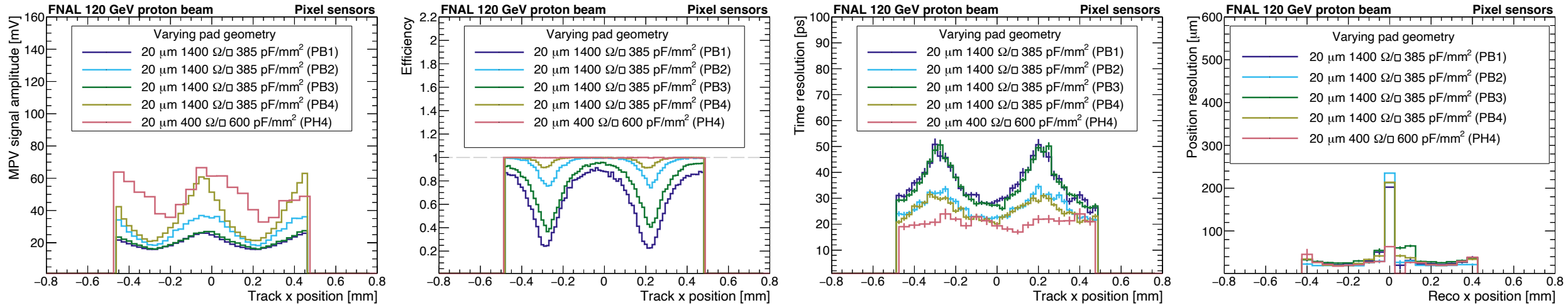


- Larger signal size in metal pads compared to gap region
- Faster signals in metal pads and relatively slower in gap region
- For each event, the amplitude from two channels in column has been added to enhance the charge sharing in gap regions
- Two-channel efficiency  $\sim 1$  in gap region and suffers in metal region



# Test Beam Results on Pixel Sensors (BNL vs HPK):

20  $\mu\text{m}$  thick, 500 X 500  $\mu\text{m}$  pitch with different metal width

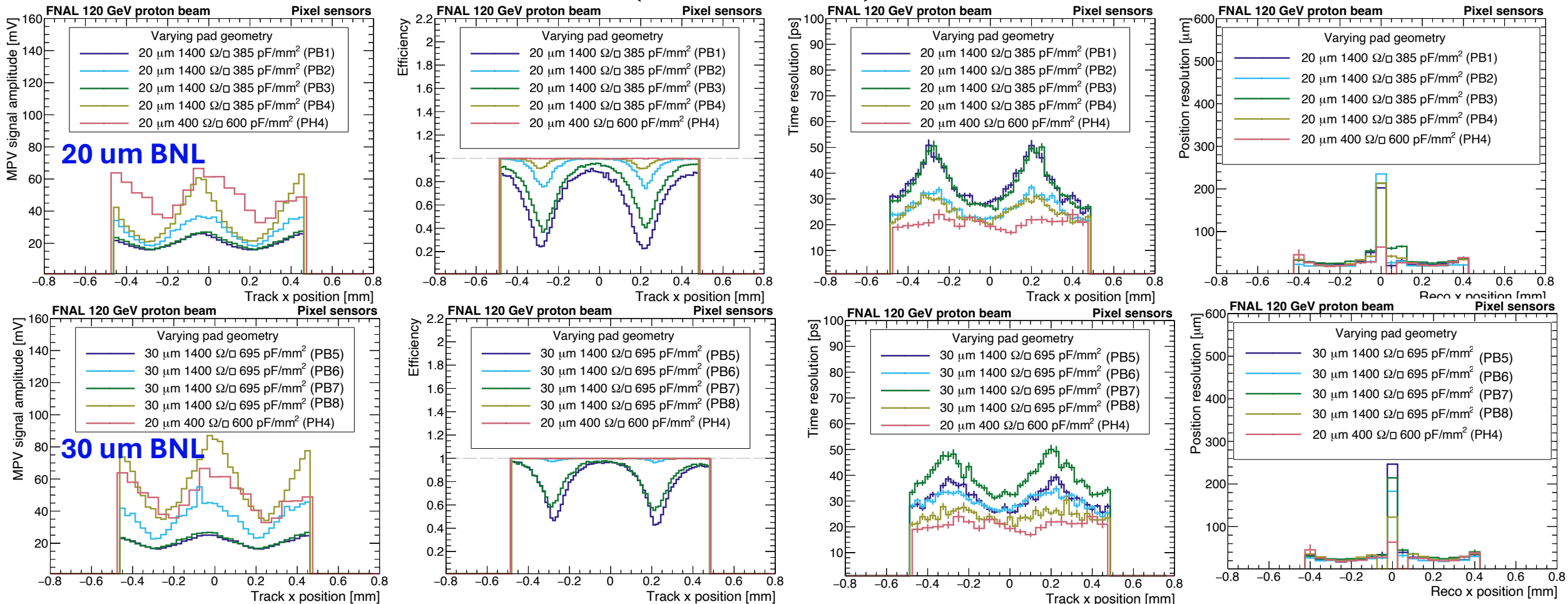


## Summary

- **BNL 20  $\mu\text{m}$  (PB1, PB2, PB3, PB4)**
  - PB1 and PB3 have significantly smaller signal size
  - BNL pixel sensors with smaller signal size not able to achieve 100% efficiency across the surface
  - Poor timing resolution in the gap region and poor position resolution on metal pad
- **HPK 20  $\mu\text{m}$  (PH4) vs BNL 20  $\mu\text{m}$  (PB1, PB2, PB3, PB4)**
  - Signal amplitude, efficiency, timing and position resolutions of HPK sensors are much better than BNL-IO sensors

**PB1:** Small square **PB2:** Large square **PB3:** Squared circle **PB4:** Cross

# Test Beam Results on Pixel Sensors (BNL vs HPK)

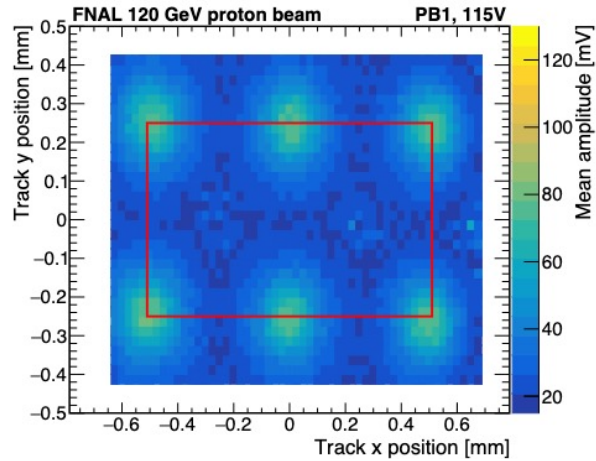


- **HPK 20  $\mu\text{m}$  (PH4) vs BNL 20  $\mu\text{m}$  (PB1, PB2, PB3, PB4)**
  - Signal amplitude, efficiency, timing and position resolutions of HPK sensors are much better than BNL-IO sensors
- **HPK 20  $\mu\text{m}$  (PH4) vs BNL 30  $\mu\text{m}$  (PB5, PB6, PB7, PB8)**
  - Efficiency, timing and position resolutions of HPK sensors are better than BNL-IO sensors
  - Cross sensor (PB8) performance is similar like PH4
    - Slightly worse timing resolution due to larger Landau term in PB8
    - PB8 position resolution (140 $\mu\text{m}$ ) at the metal worse than PH4 (60 $\mu\text{m}$ ). Unclear if this can be improved

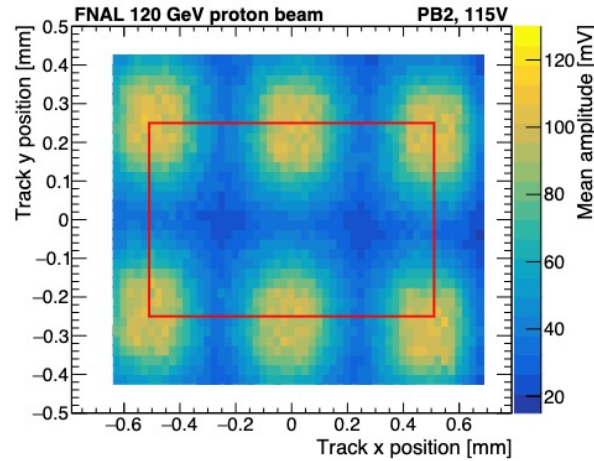
# Extra slides

# BNL Pixel Sensors (500 x 500 um pitch): 30 um thick

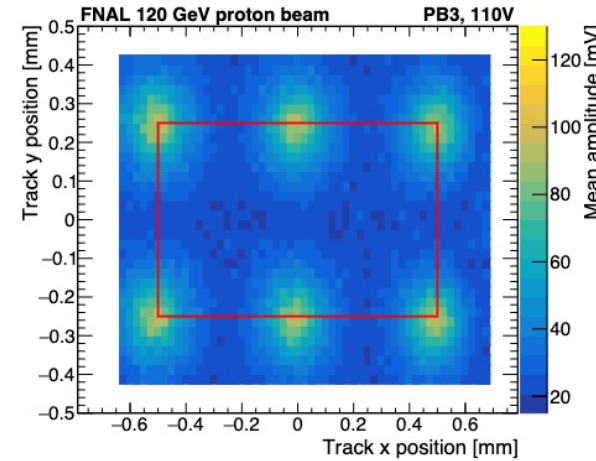
## small squares



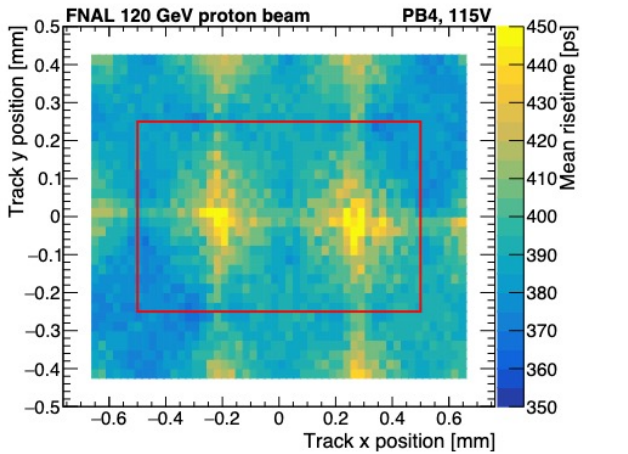
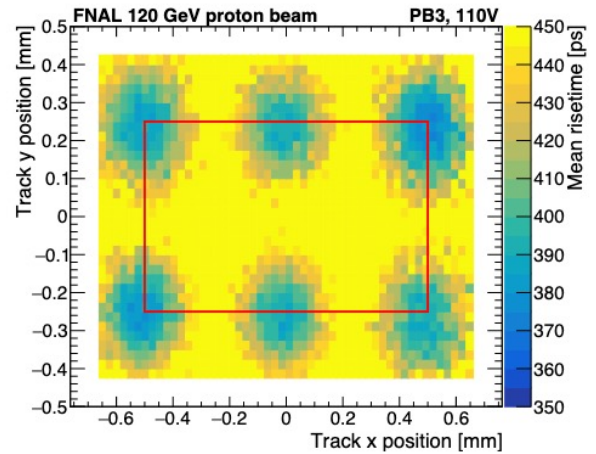
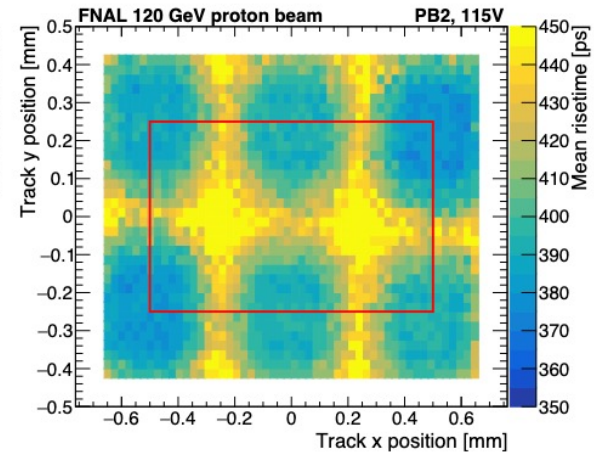
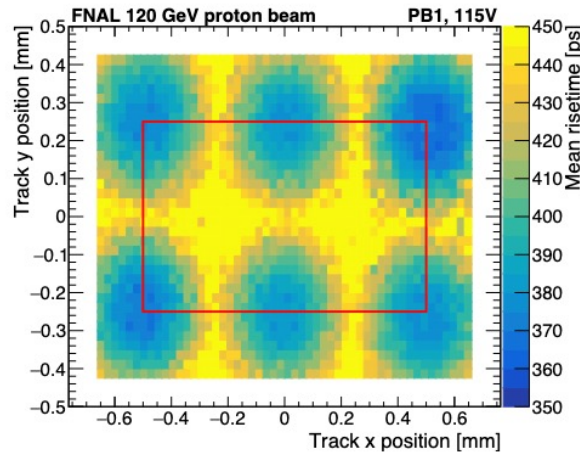
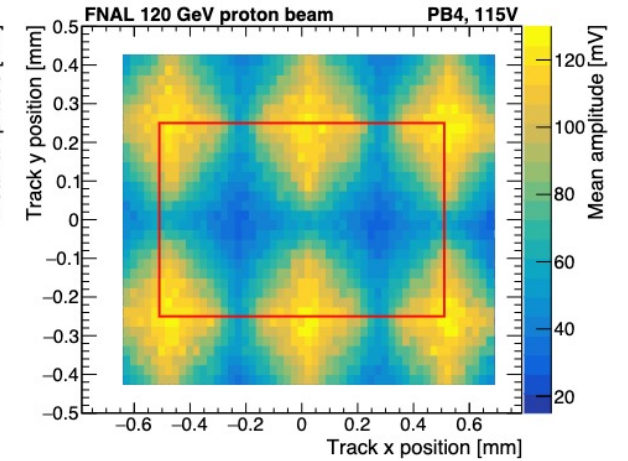
## large squares



## squared circles



## crosses



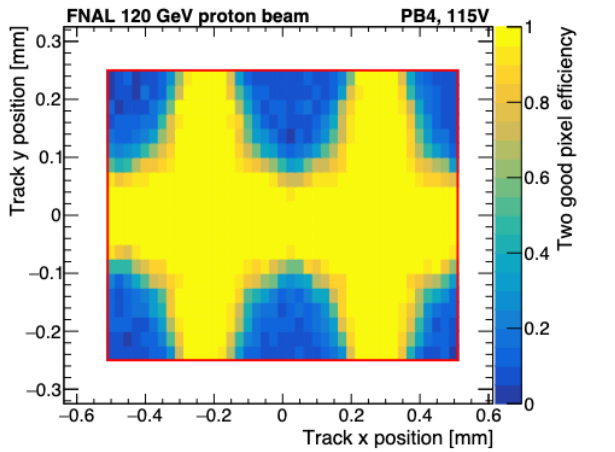
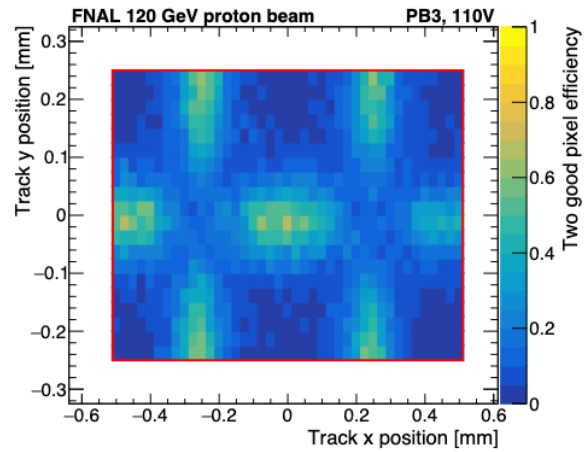
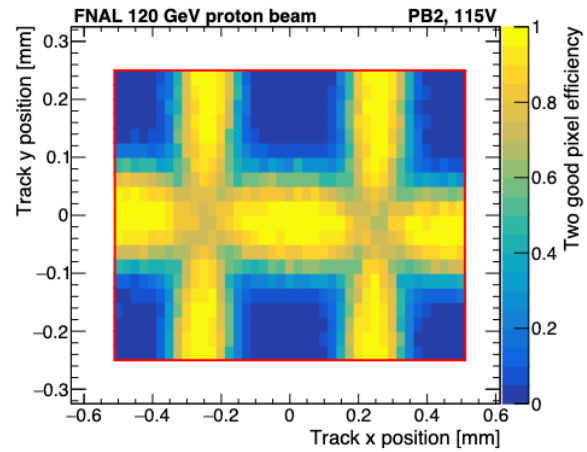
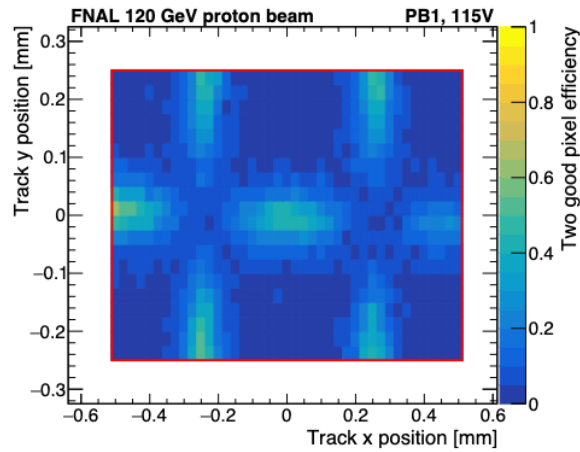
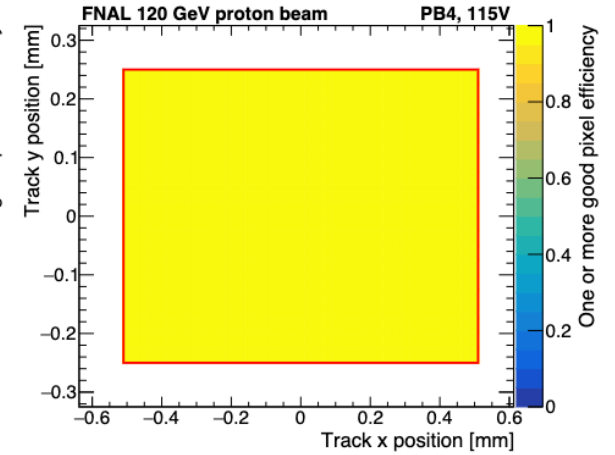
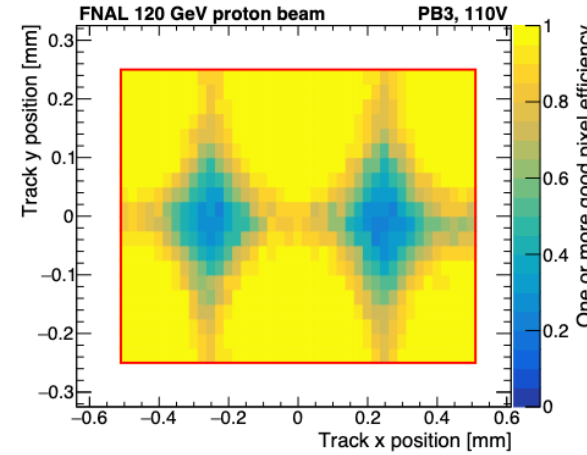
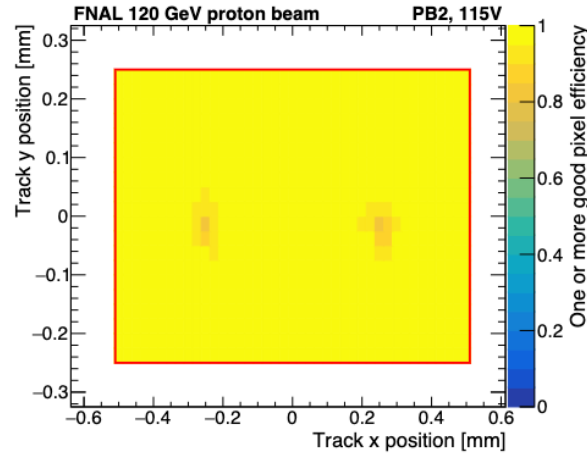
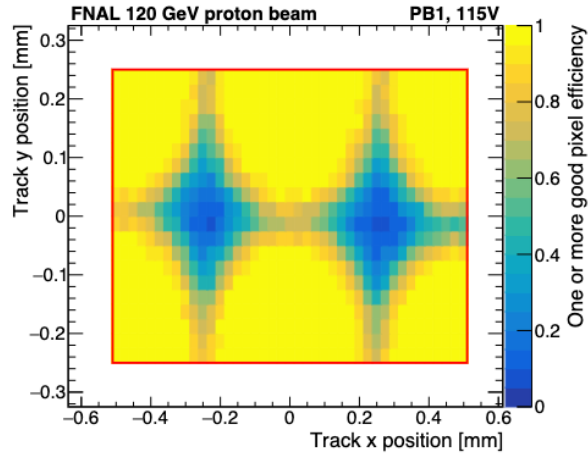
# BNL Pixel Sensors (500 x 500 um pitch): 30 um thick

## small squares

## large squares

## squared circles

## crosses



# BNL and HPK Pixel Sensors (500 x 500 um pitch): Two-column Efficiency

