



μ RWELL-BOT Simulation Update

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- ☐ Simulation details
- ☐ Extracting angular resolutions are extracted
- $\square \mu$ RWELL-BOT spatial resolution impact on angular resolution
 - Drift gap dependance
 - Fast Simulation Comparisons
 - ACTS Track States
 - Fast Tracklets
- Next Steps

Simulation Details



☐ ePIC: 24.06.0

☐ ElCrecon: v1.14.0

 \square Single particle π^-

☐ Discrete momentum

> 1, 2, 4, 6, 8, 10 GeV

 $\square \ 0^o \le \phi \le 360^o$

 $\Box \Delta \theta = 2^o$

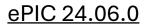
heta bins and corresponding η settings

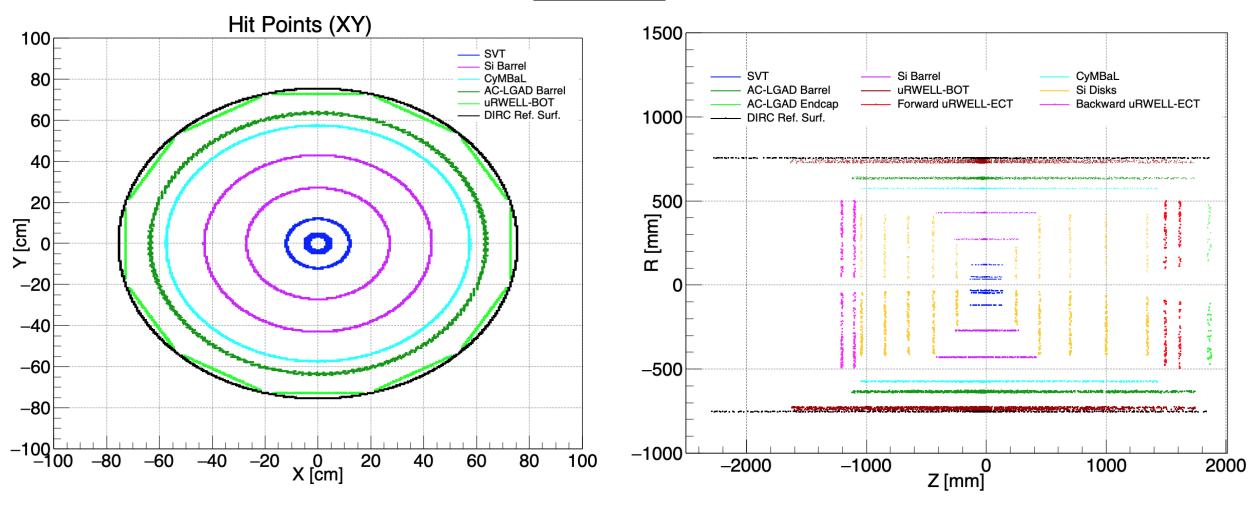
heta [deg]	$<\eta>$				
92-94	-0.05				
117-119	-0.51				
134-136	-0.88				
154-156	-1.51				

Extracting Angular Resolutions



☐ Define low mass DIRC reference surface (~R = 76cm) in DD4HEP to record truth hit information

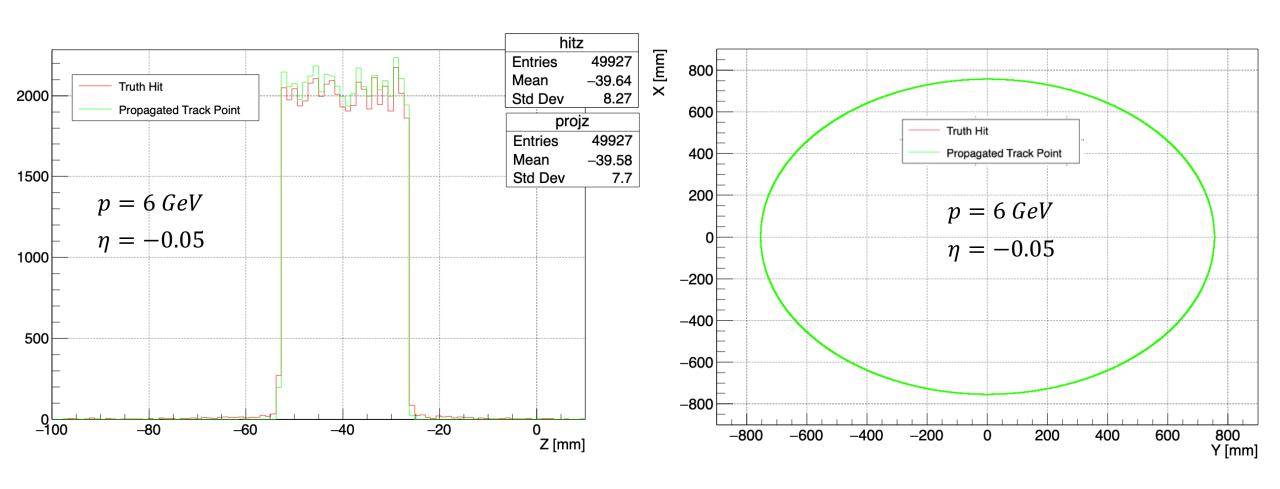




Extracting Angular Resolutions



- ☐ Define low mass DIRC reference surface in DD4HEP to record truth hit information
- ☐ Define ACTS surface that matches D44HEP DIRC reference surface to propagate tracks to

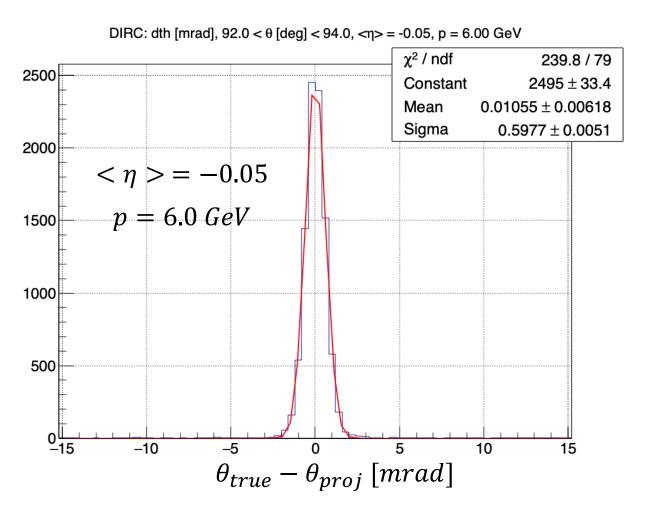


Extracting Angular Resolutions



- ☐ Take difference of truth hit and propagated track point
 - Resolution is given by Gaussian sigma

$$\succ \sigma_{\theta} = 0.6 \, mrad$$



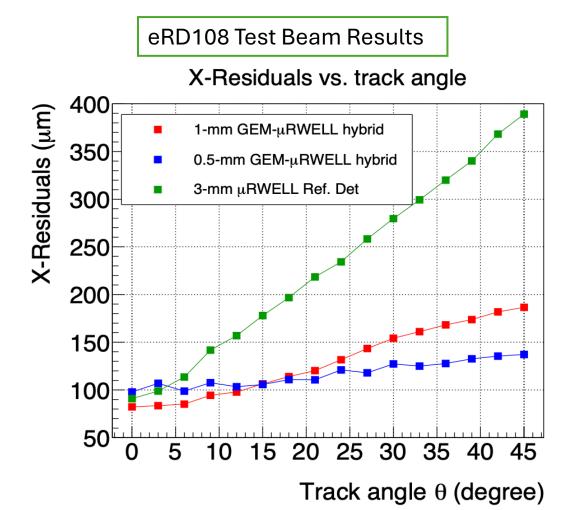


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μ RWELL Drift Gap Dependence



- ☐ MPGD resolution depends on track angle and size of the drift gap
 - Use test beam results to set resolution based on simulation η and drift gap sizes

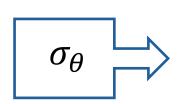


MPGD resolutions used in simulation

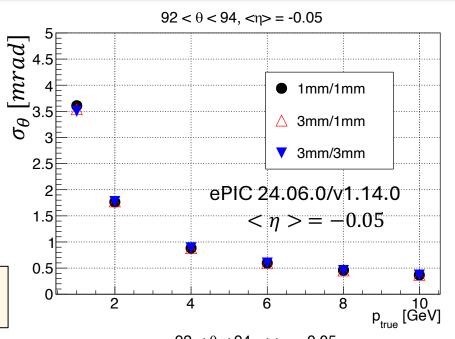
θ – 90° [deg]	$<\eta>$	1mm Resolution $[\mu m]$	3mm Resolution $[\mu m]$
2-4	-0.05	80	90
27-29	-0.51	150	250
44-46	-0.88	190	390
64-66	-1.51	240	520

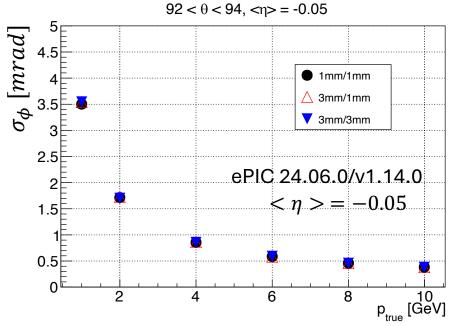
μ RWELL Drift Gap Dependence

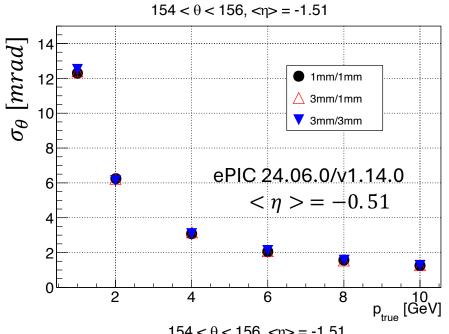


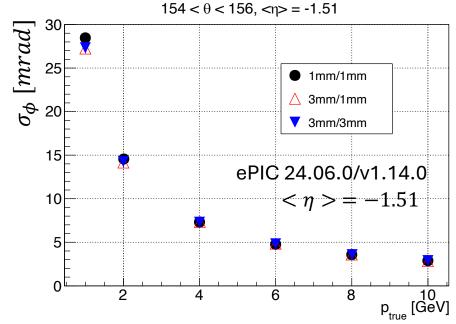


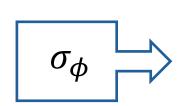
Legend is drift gap size for CyMBaL / μRWELL-BOT











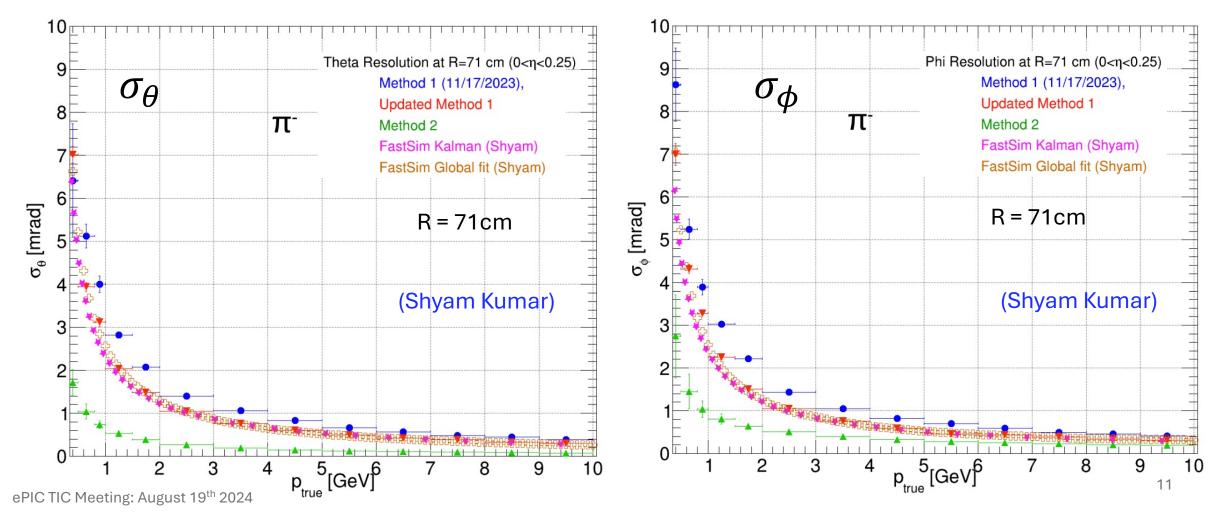


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Fast Simulation Comparison



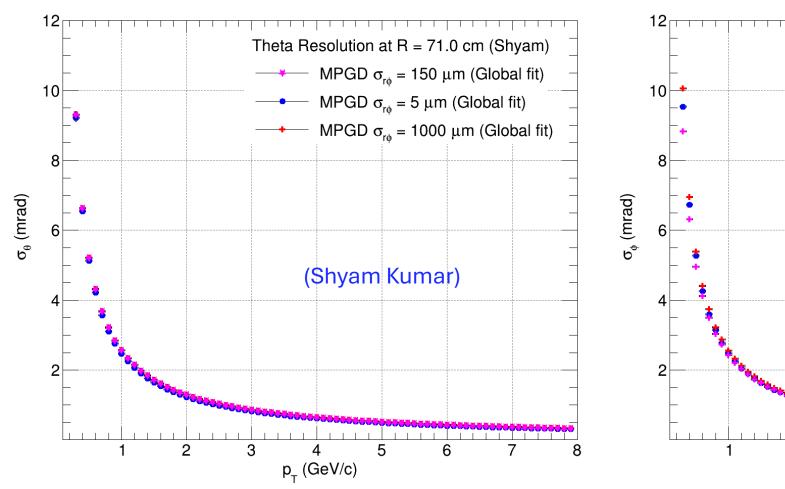
- ☐ Good agreement seen between ePIC full sim and fast sim
 - These Results are before DIRC move to R = ~76cm
 - Fast sim results produced by Shyam Kumar MPGD Simulation Meeting

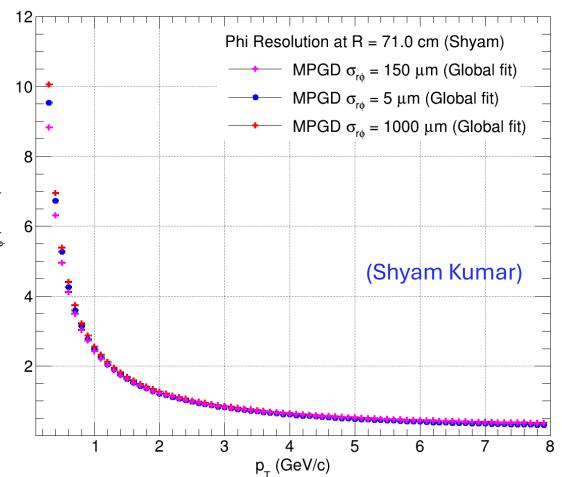


Fast Simulation Comparison



☐ Same dependance on spatial resolution as seen in fast simulations

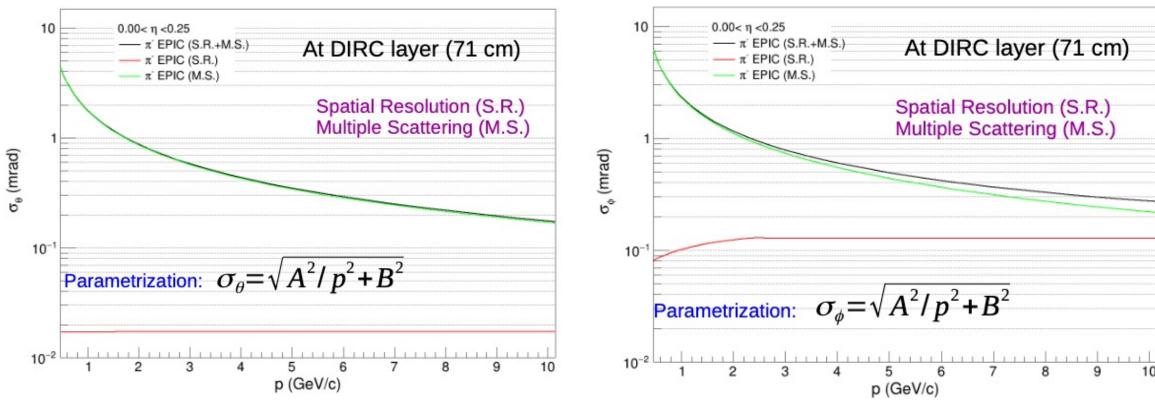




Multiple Scattering Contribution



- ☐ Contributions to angular resolutions from fast simulation
- Angular resolutions dominated by MS
 - MS more dominant in polar angle resolution



Shyam Kumar MPGD Simulation Meeting



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ACTS Track States



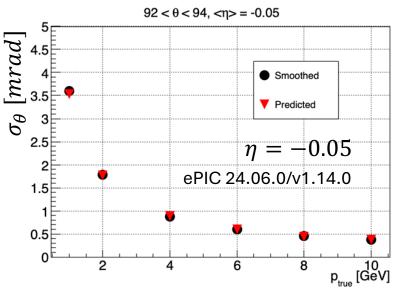
- 3 ACTS track states
 - ElCrecon currently saves predicted track states as default
 - Beatrice showed track residual improvement using the smoothed track state
 - Tracking WG Meeting

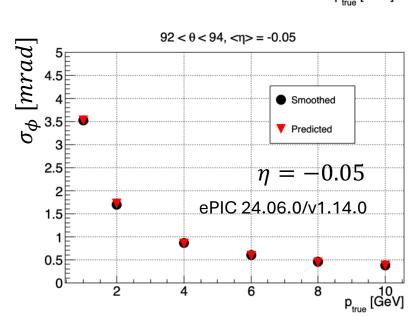
Predicted	Filtered	Smoothed
determines track state at state k based on previous k-1 measurements	adjusts predicted track stat e at state <i>k</i> by taking into account the measurement at state <i>k</i>	Adjusts the filtered track state with all measurements taken into account

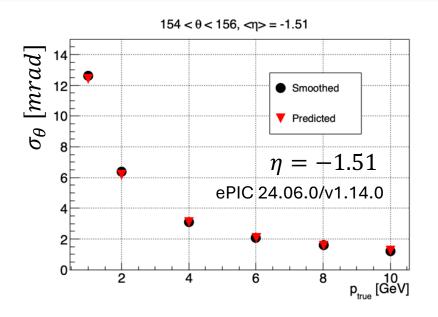
ACTS Track States Comparison

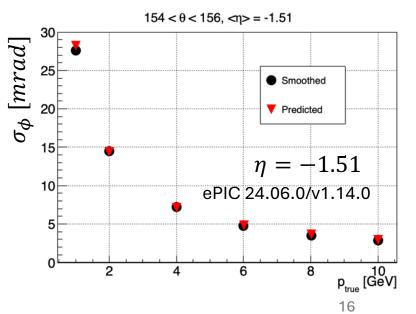


☐ Different track states yield comparable angular resolutions











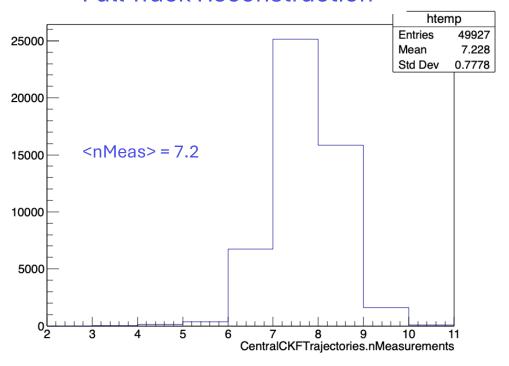
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Fast Tracks

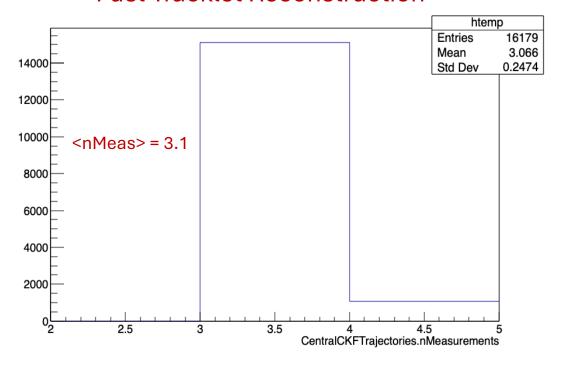


- ☐ Use only hits from MPGDs and AC-LGADs in track reconstruction
 - Three fast layers → ~3 measurements / track
 - Note this study used fixed MPGD resolutions (no track angle dependance)

Full Track Reconstruction



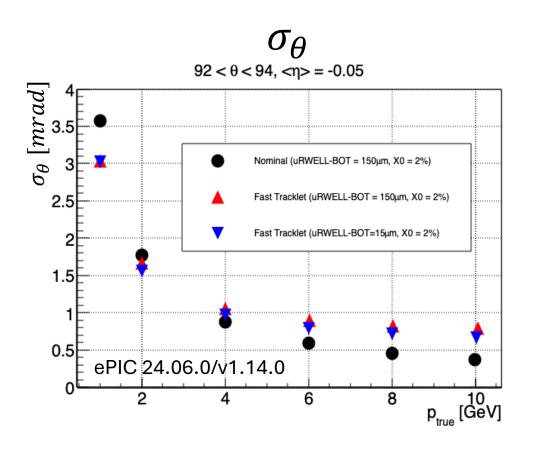
Fast Tracklet Reconstruction

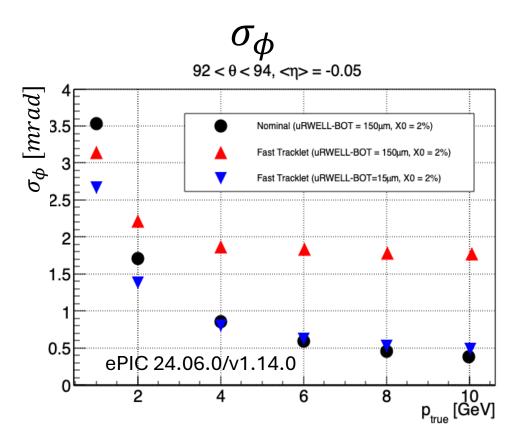


Fast Tracks: Angular Resolution Comparison



- ☐ Fast tracklet results show
 - lacktriangle Sensitivity to detector resolution, mostly in ϕ
 - Improvement at low p





Summary and Next Steps



☐ Summary

- Current track reconstruction seems to be dominated by multiple scattering that can not be overcome from improving detector resolution
- Fast tracklet results show sensitivity to detector resolution and improvement at lower momentum
- \square Next Steps (beyond just μ RWELL simulations)
 - Study impact of BIC tracking layer on angular resolutions
 - ➤ Integrating BIC hits into ACTS in progress: (PR#710, Wouter)
 - Try to improve angular estimates at large radii by reversing the track finding direction in ElCrecon
 - Assess tracking performance with more refined set of DIRC requirements, e.g. needed tracking resolutions vs. momentum and eta

Backup

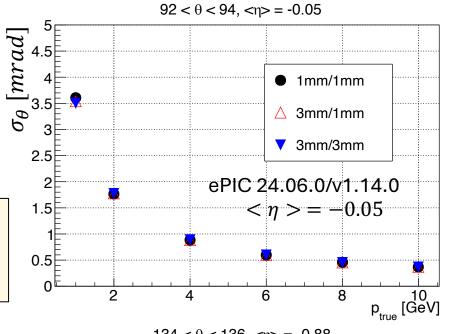


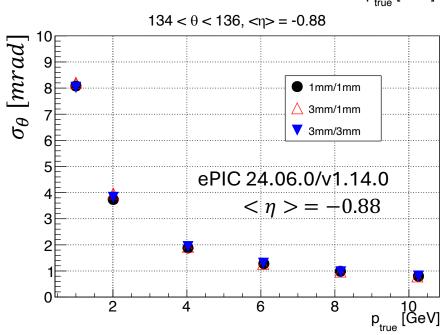
21

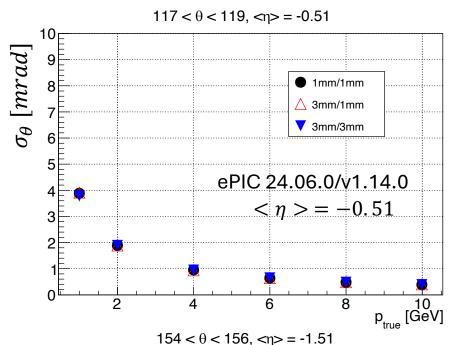
μ RWELL Drift Gap Dependence: σ_{θ}

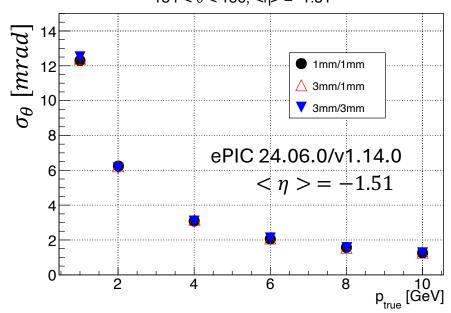




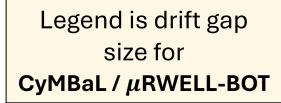


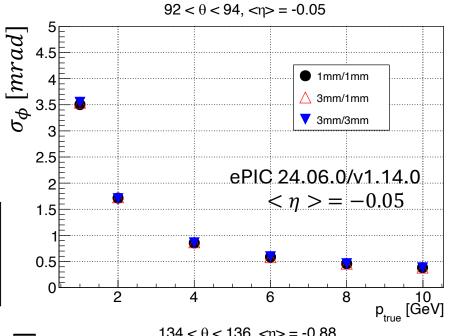


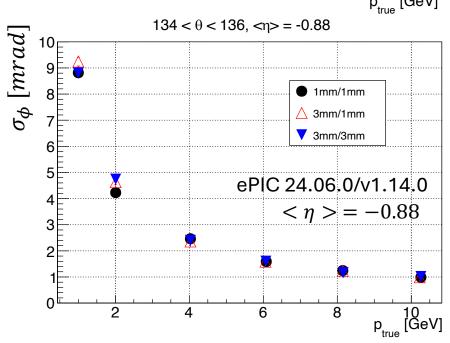


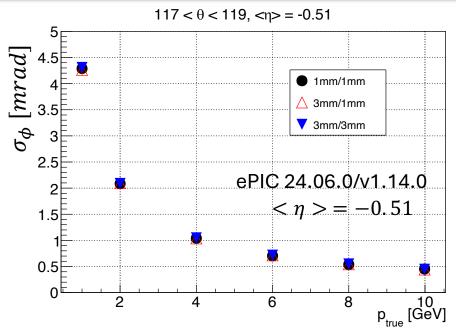


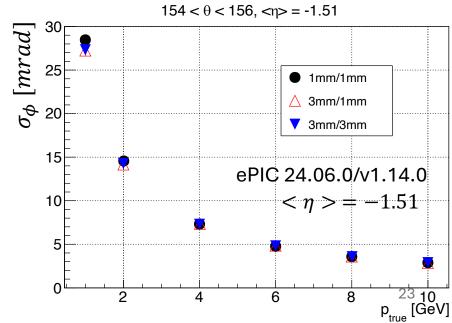








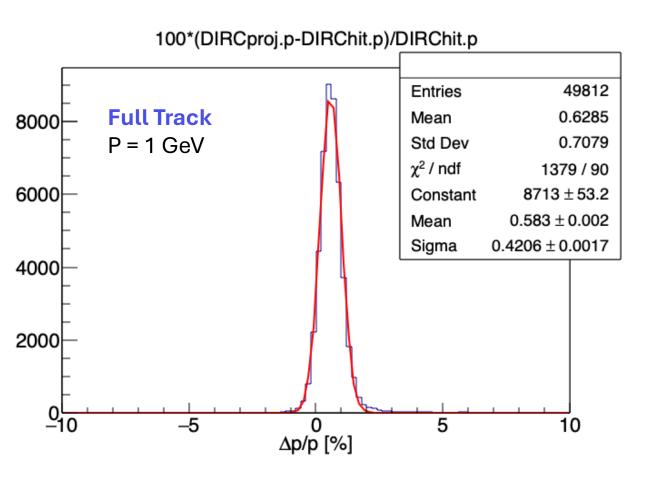


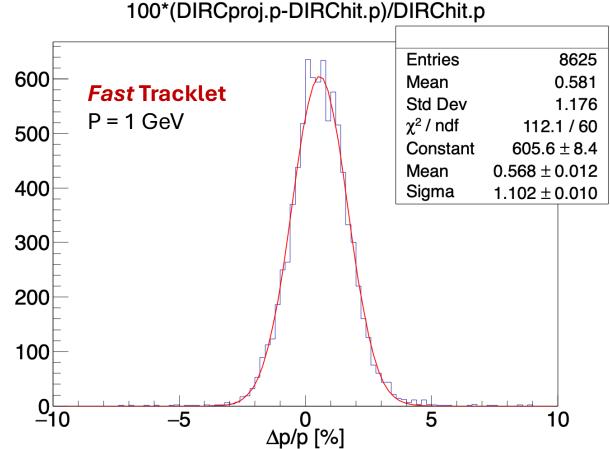


Evaluating Performance with *Fast* Tracklets



☐ Full track gives better momentum resolution at hpDIRC compared to fast tracklets





Evaluating Performance with *Fast* Tracklets



 \Box Clear μ RWELL-BOT spatial resolution impact seen in momentum resolution at hpDIRC seen in **fast tracklets**

