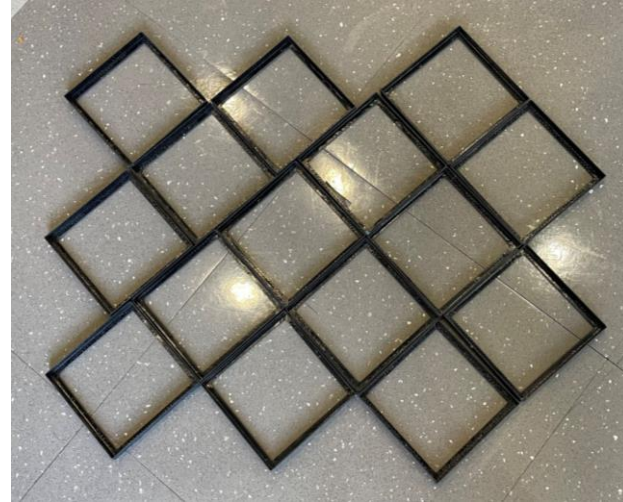


# pfRICH Sensor Plate Prototype



Simon SnyderSmith, Sam Langley-Hawthorne, Ian Holda, Sushrut Karmarkar,  
Andreas Jung

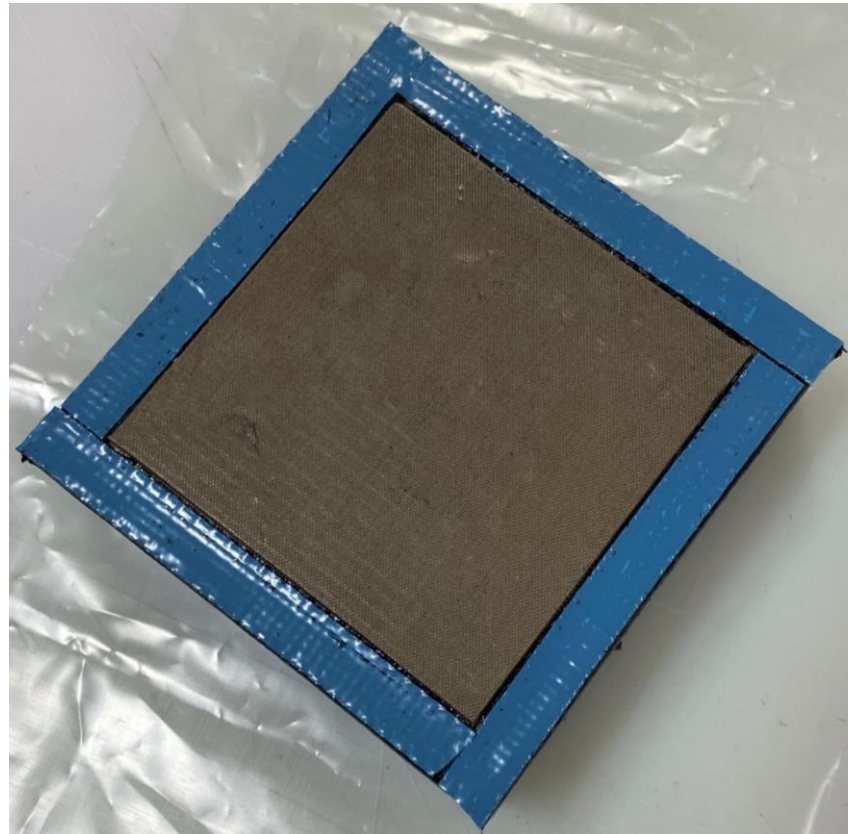
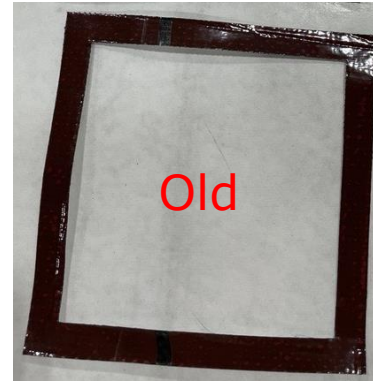
1 August 2024

- ◊ 15 sensor frames are made plus 5 extra
- ◊ All frames are machined and sanded
- ◊ L-brackets for bonding to outer plate are made
- ◊ Still need to lay up plate for outer frame and interstitial beams
- ◊ More metrology to be done on sensor frames



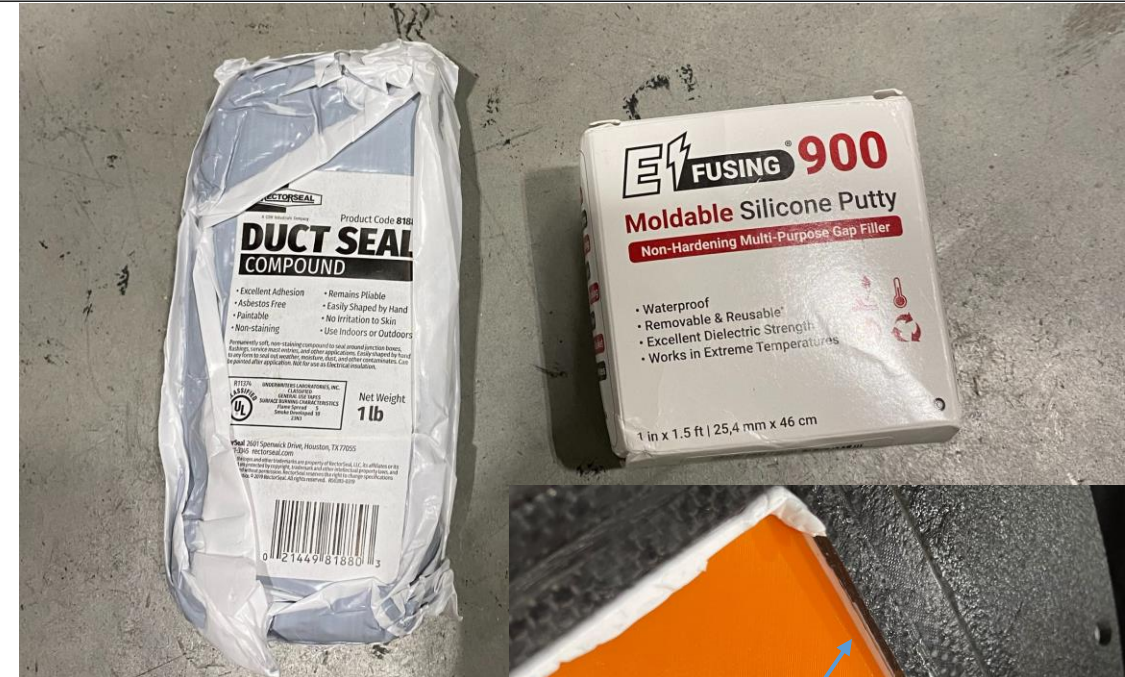


- ⬠ Replaced the hollow box plies with 4 strips which cover the perimeter
- ⬠ Reduces waste compared to original plies
- ⬠ Strips were laid across the top of the picture frame mold and cut to length.
- ⬠ Seams were alternated to prevent weak spots
- ⬠ Resulted in a small visible seam in the final product





- Two different sealing putties were tested
- Duct Seal worked but left residue on the sensor blanks and frames
- Silicone putty left little residue and easily scraped off
- Putty sealed to almost perfect vacuum and stayed sealed after pump removed
- Silicone putty is easy to apply and works better than any solid seal tested
- Effects of radiation and time on the silicone's sealing capacity remain to be tested



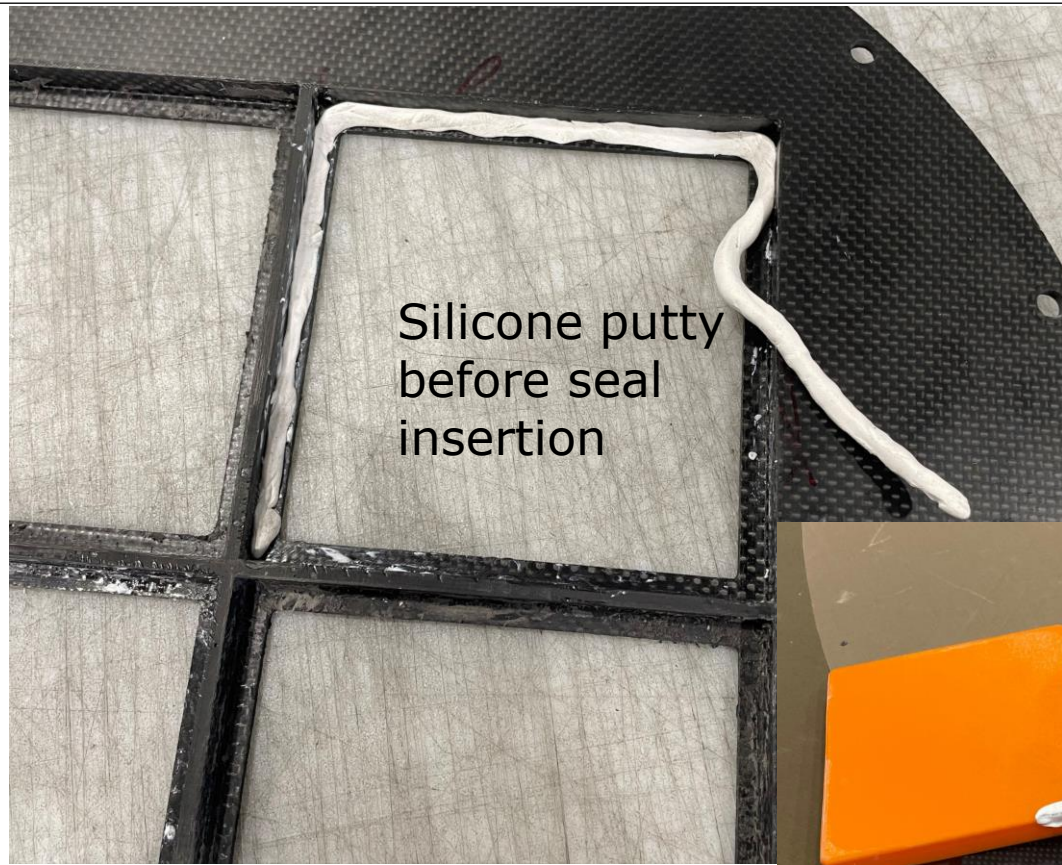
Pump Pressure is 27.2 Pa away from perfect vacuum



Edge trimmed with plastic knife after insertion

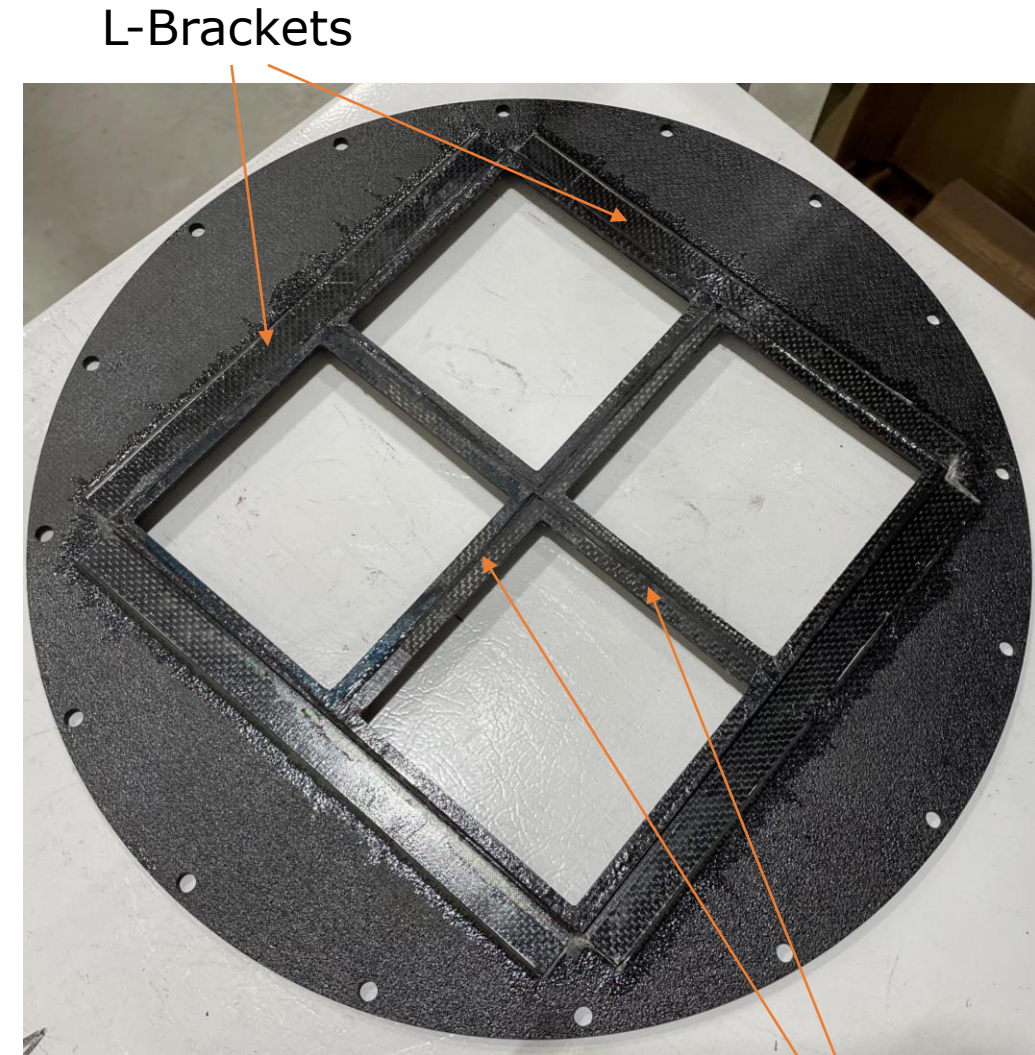
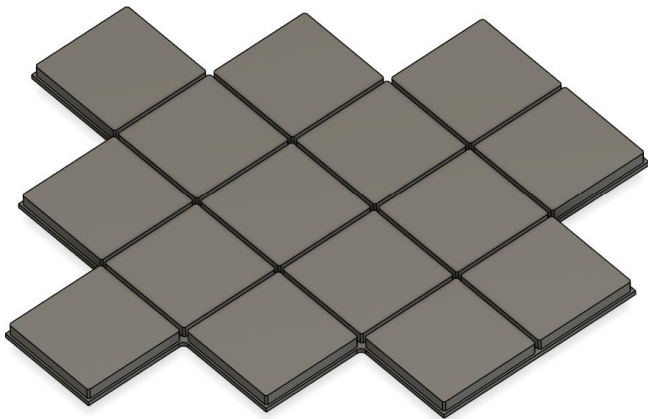


# Sealing





- ⬠ Frames will be bonded in groups of five to ensure enough adhesive working time
- ⬠ Bonding jig is scaled up version of previous with more clearance
- ⬠ Frames and interstitial beams will be bonded in jig first
- ⬠ Frame assembly will then be bonded to outer plate with L-brackets



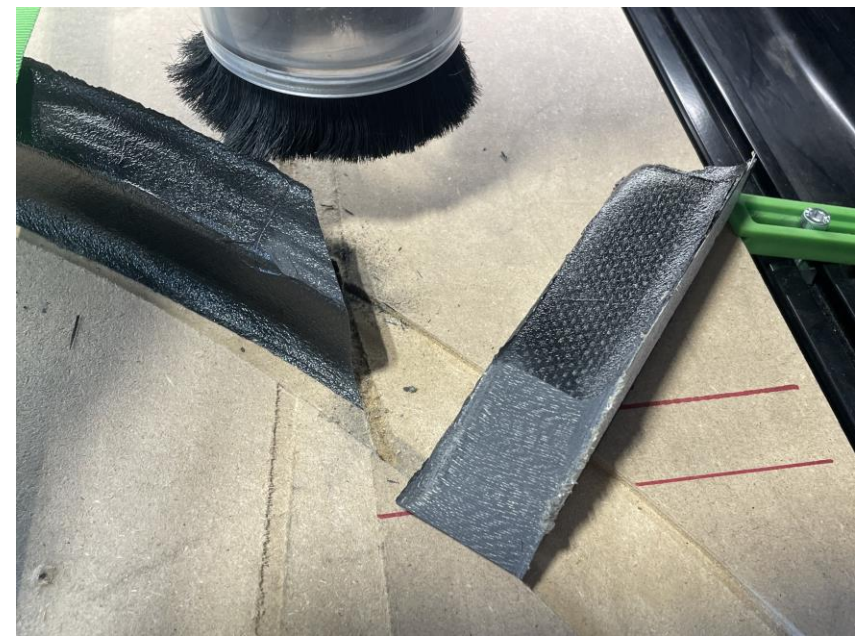
L-Brackets

Interstitial Beams

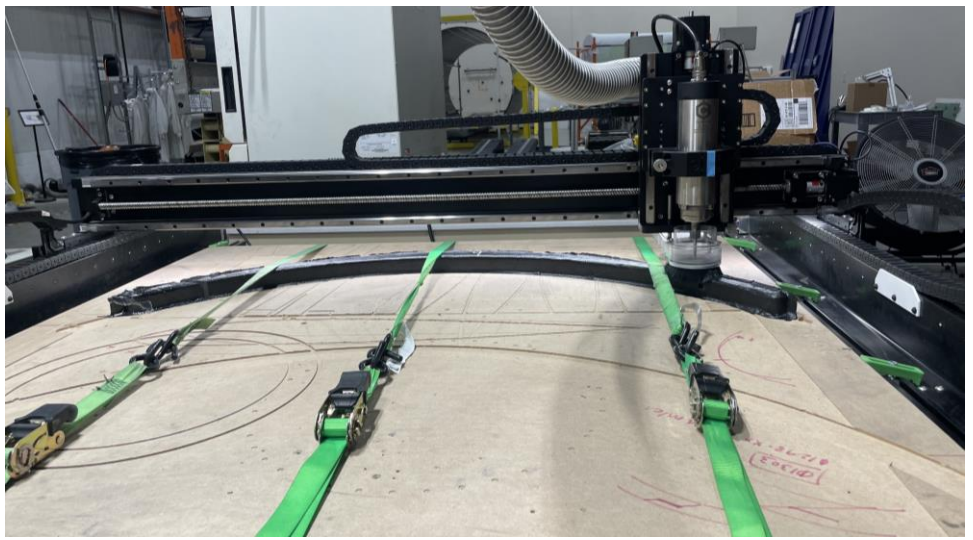




Started with 4 cured end ring layups (nominal outer diameter = 1303 mm)

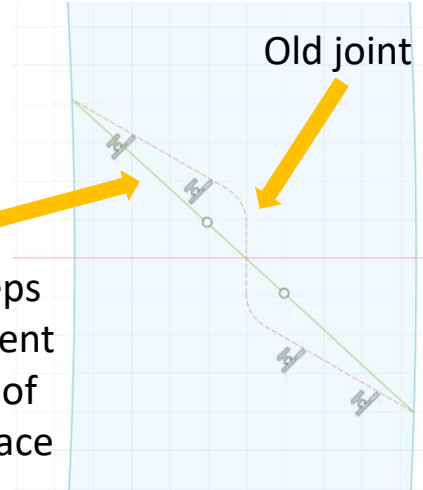


Machined scarf joint on both sides, accounting for 0.05 mm adhesive bond line thickness



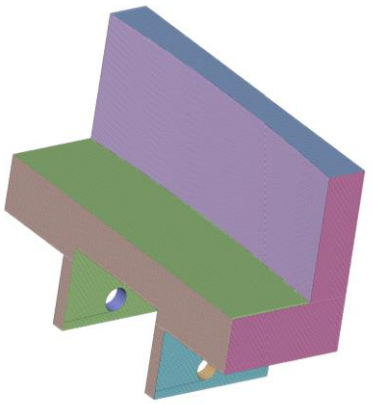
0.05 mm bond line scarf joint

New scarf joint; keeps bonded joint consistent for later machining of inner and outer surface

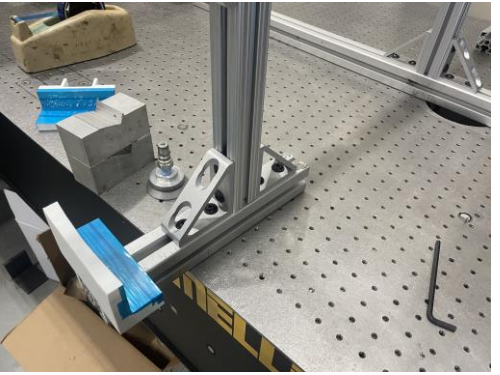


Old joint





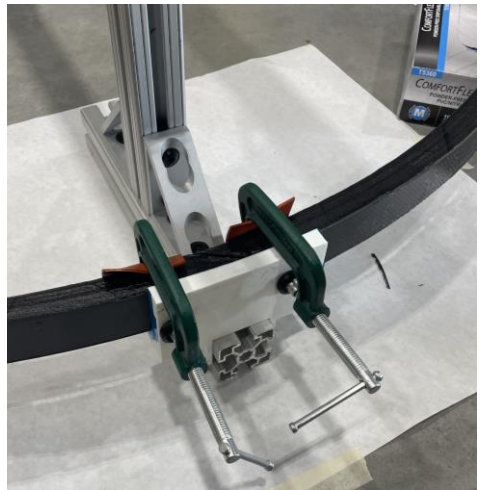
New 3D printed bracket to fit outer curvature



Bracket assembled onto same aluminum extrusion jig as previous end ring bonding



Fully-assembled bonding jig

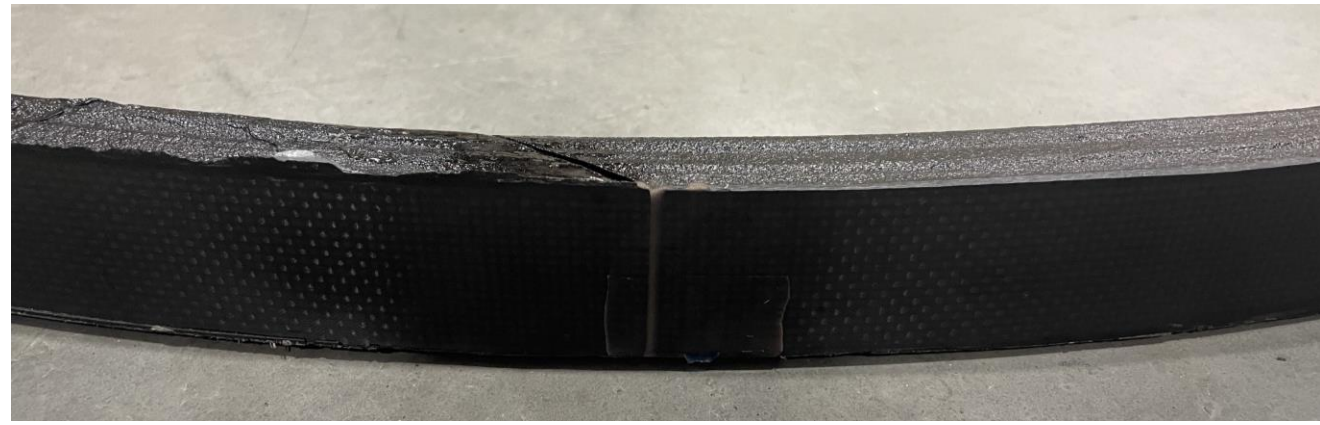


Clamps + silicon pads hold end ring to bracket

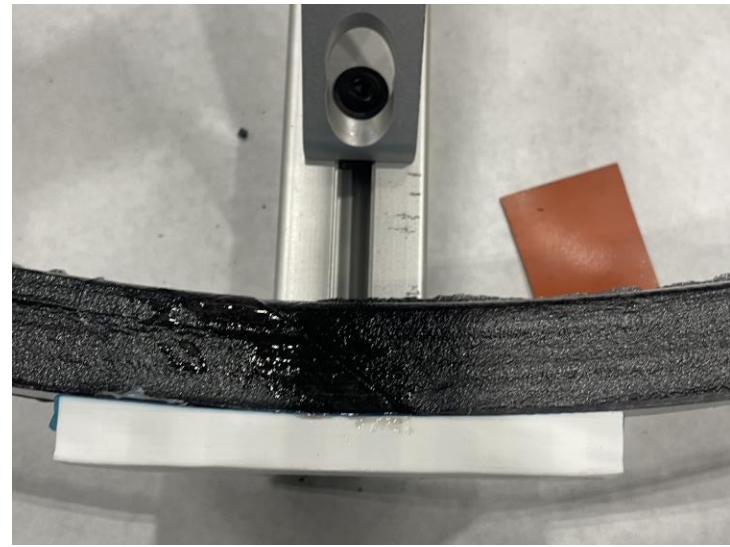


Bonded scarf joints with Araldite 2011 mixed with microballoons (to ensure 0.05 mm bond line)





Bond lines appear larger than 0.05 mm, could be due to bonding jig inaccuracies

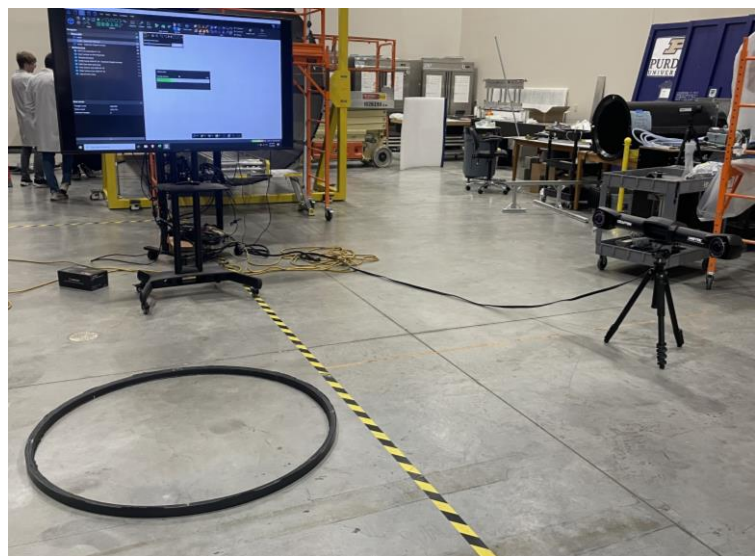


Bonded joints show some adhesive sag on top face (area to machine still has full adhesive coverage)

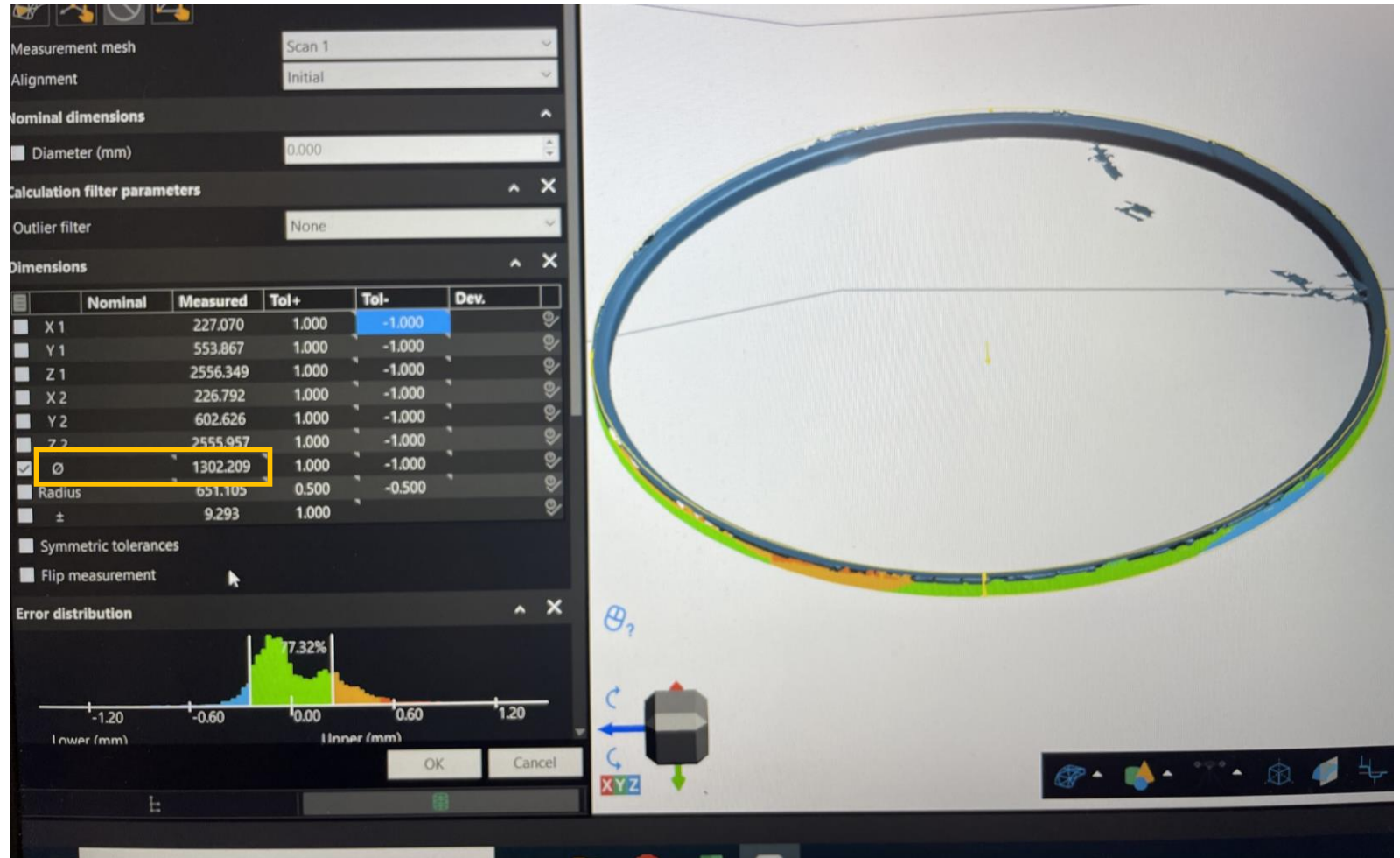




Assembled end ring (~0.05 mm bond line)



Laser scanning setup (using Creaform MetraSCAN)

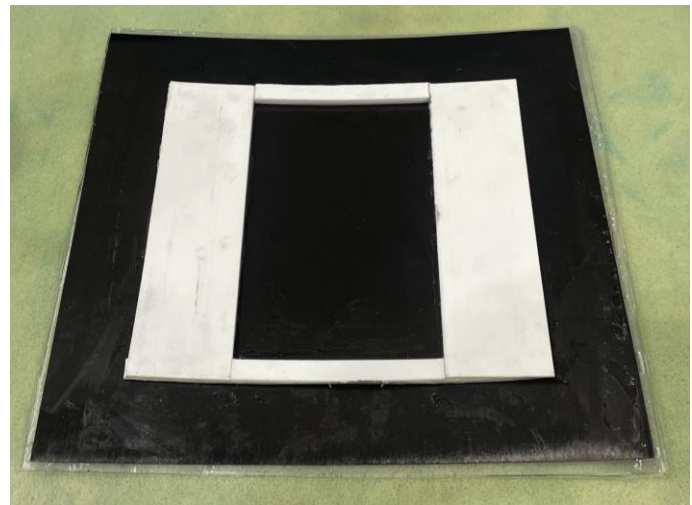
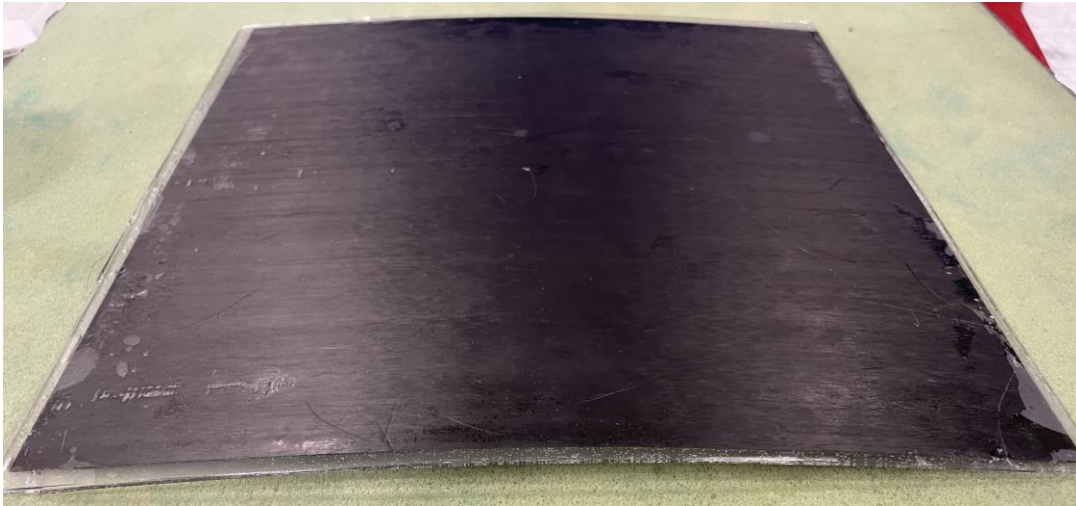
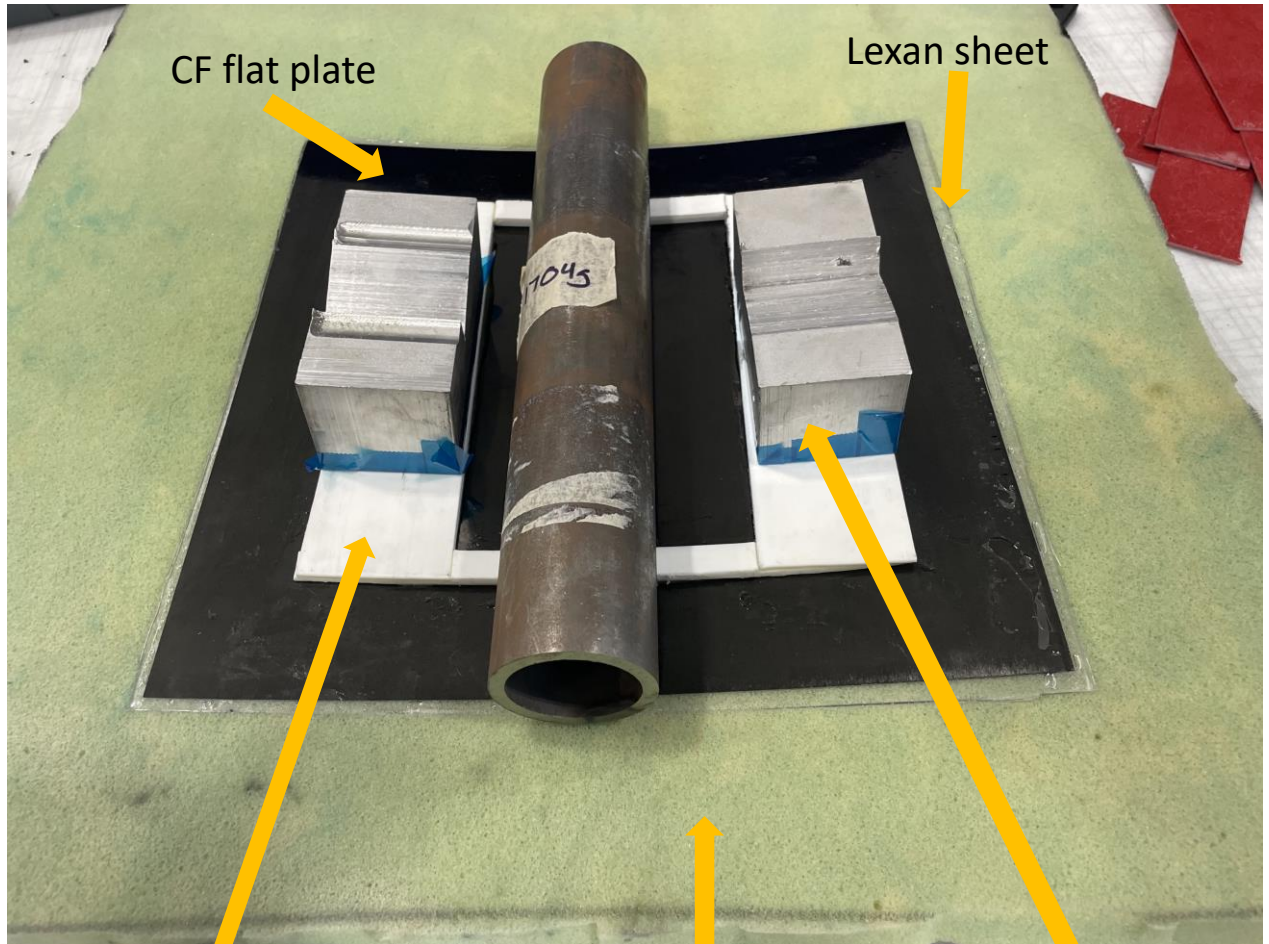


Best-fit cylinder has diameter of 1302.209 mm (0.791 mm difference compared to nominal)

Outer surface deviations fall within +/- 0.5 mm (surface is machined anyway)



Bonded 3D printed curvature fixture to Lexan-CFRP mirror substrate test with Araldite 2011





Outlier filter: None

Dimensions	Nominal	Measure	Tol+	Tol-	Dev.
X 1	99.187	99.187	1.000	-1.000	
Y 1	227.040	227.040	1.000	-1.000	
Z 1	4211.817	4211.817	1.000	-1.000	
X 2	105.712	105.712	1.000	-1.000	
Y 2	533.398	533.398	1.000	-1.000	
Z 2	4227.763	4227.763	1.000	-1.000	
∅	2736.415	2736.415	1.000	-1.000	
Radius	1368.207	1368.207	0.500	-0.500	
±	2.902		1.000		

Symmetric tolerances  
 Flip measurement

**Error distribution**

69.99%

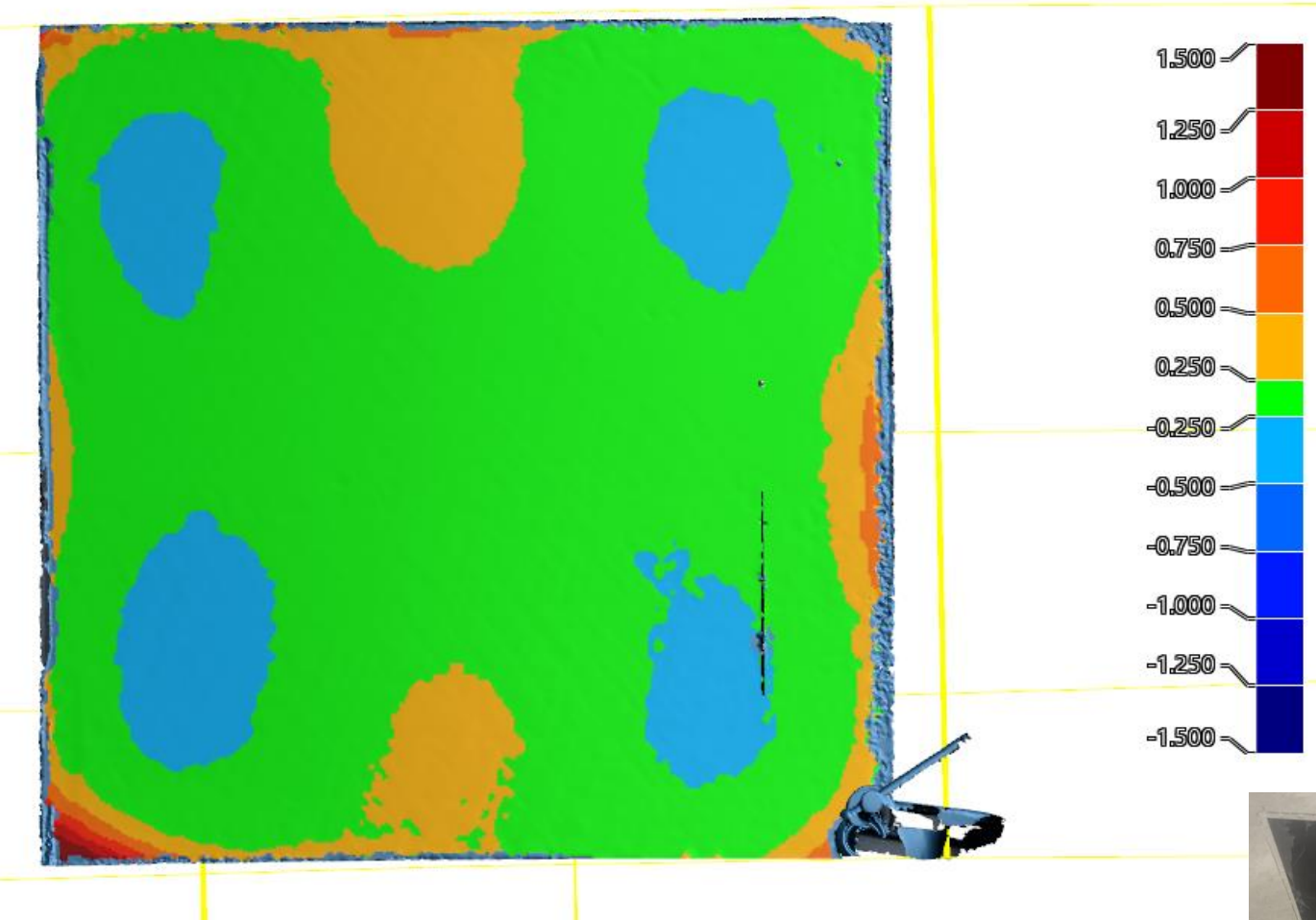
Lower (mm): -1.500 Upper (mm): 1.500

Automatic values  
 Symmetric

[Edit color map](#)

**GD&T**

Callout	Measured	Out of tol
∅ 1.000	1.800	0.800



Laser scanning setup:



Surface error distribution falls within +/- 0.5 mm (keep in mind protective plastic covering is still on Lexan sheet, potentially causing surface variations)

**Radius: 1368 mm**  
**Cylindricity: 1.8**



Multiple curved as well as flat mirror substrates and co-bonded lexan substrates have been sent to SBU on August 7<sup>th</sup>