

Analysis Plan during INTT workshop

Analysis topic

Detection efficiency of INTT with p+p using vertex

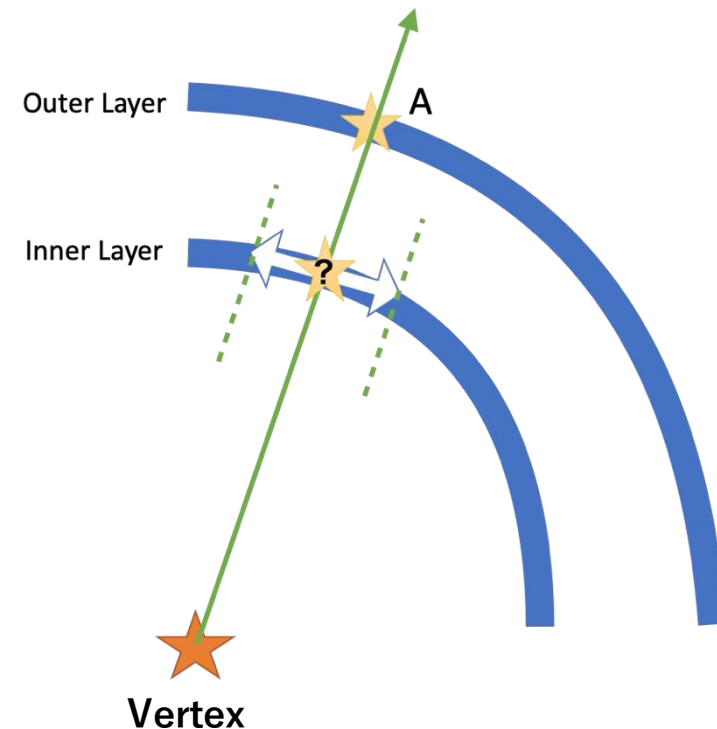
Goal for the workshop

- Estimating detection efficiency of INTT with vertex using simulation.
- Getting information about how to decide vertex position
- Establishing the method to connect the information between vertex and cluster

Method

1. Find the coordinates A of the cluster in the Outer Layer
2. Connect the collision point and A with the cluster and determine the range expected for the Inner cluster
3. If there are clusters within the expected range and if there are no clusters within the expected range, count the number of clusters in each case as N_{Yes} and N_{No} respectively.

$$\varepsilon = N_{yes}/(N_{yes} + N_{No})$$



Analysis Plan during INTT workshop

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Detection efficiency of INTT with p+p using vertex

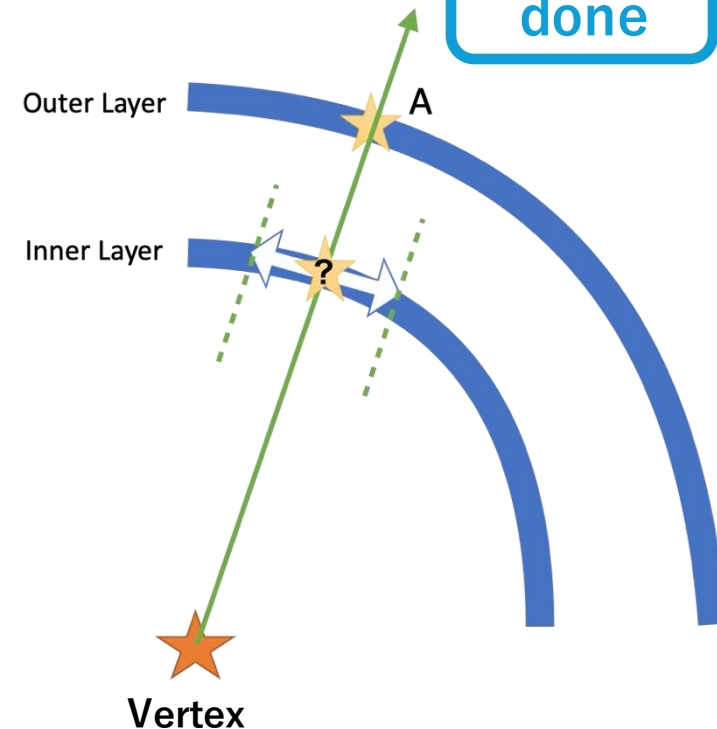
Goal for the workshop

- Estimating detection efficiency of INTT with vertex using simulation. **Almost**
- Getting information about how to decide vertex position **<-skip**
- ~~-Establishing the method to connect the information between vertex and cluster~~

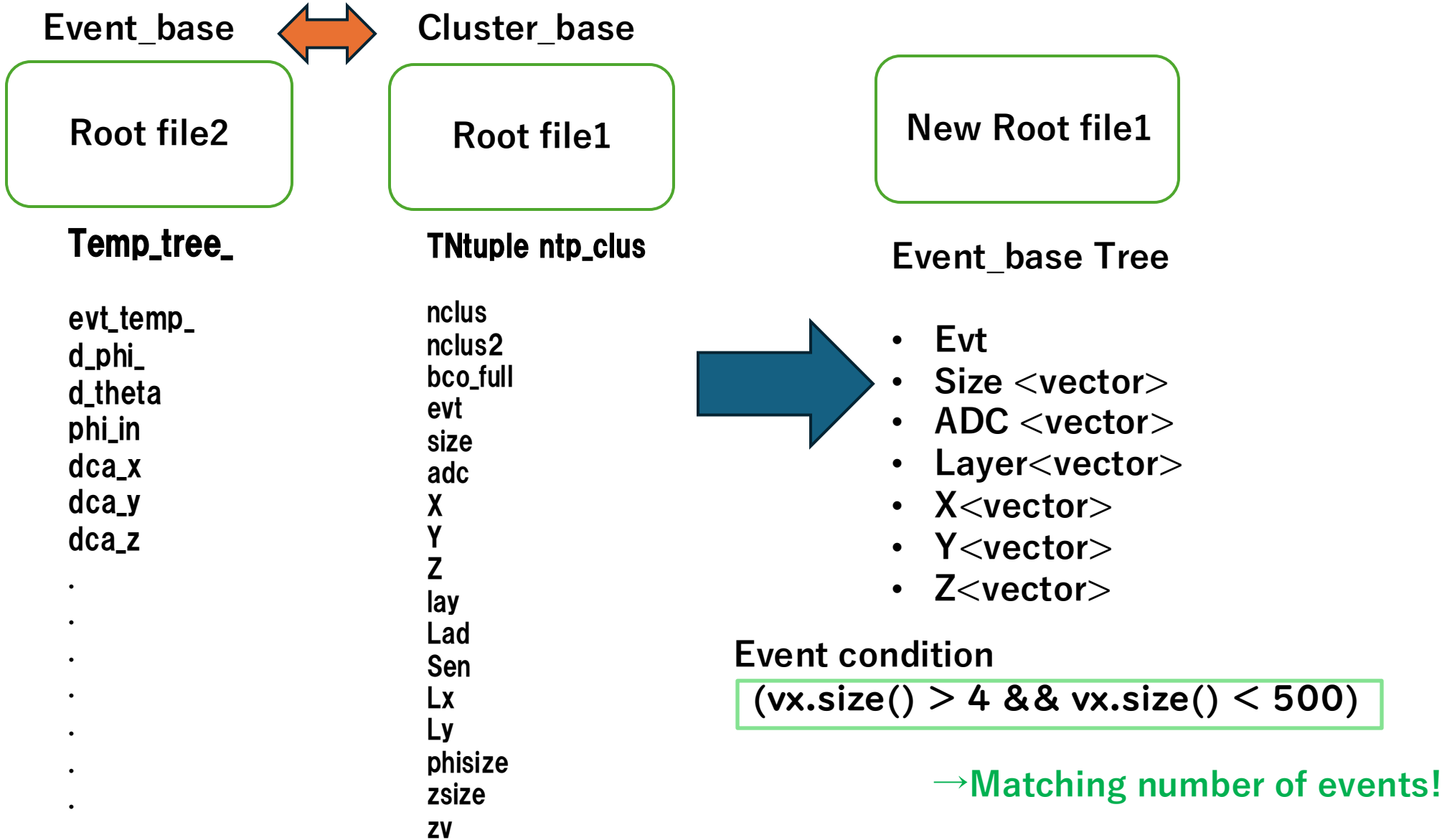
Method

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Connect the information between vertex and cluster



Result

Root file1

```
*Br 0 :nclus : Float_t
*Br 1 :nclus2 : Float_t
*Br 2 :bco_full : Float_t
*Br 3 :evt : Float_t
*Br 4 :size : Float_t
*Br 5 :adc : Float_t
*Br 6 :x : Float_t
*Br 7 :y : Float_t
*Br 8 :z : Float_t
*Br 9 :lay : Float_t
*Br 10 :lad : Float_t
*Br 11 :sen : Float_t
*Br 12 :x_vtx : Float_t
*Br 13 :y_vtx : Float_t
*Br 14 :z_vtx : Float_t
```

Change type of tree
&
Event cut

(vx.size() > 4 || vx.size() < 500)



New Root file1

```
*Br 0 :evt : evt/l
*Br 1 :x : vector<float>
*Br 2 :y : vector<float>
*Br 3 :z : vector<float>
*Br 4 :lay : vector<int>
*Br 5 :lad : vector<int>
*Br 6 :sen : vector<int>
```



Estimating detection efficiency of INTT with vertex using simulation

1. Do simulation of p+p with zerofield
2. Make DST file
3. Run Hachiya-san code to make rootfile(include ntp_clus)
4. Run Ikemoto-san code to make rootfile(include vtx info)
5. Connect the information between vertex and cluster
6. Run my code to estimate detection efficiency

Estimating detection efficiency of INTT with vertex using simulation

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Estimating detection efficiency of INTT with vertex using simulation

- ~~1. Do simulation of p+p with zerofield~~
- ~~2. Make DST file~~
3. Run Hachiya-san code to make rootfile(include ntp_clus)  I couldn't make rootfile myself
- ~~4. Run Ikemoto-san code to make rootfile(include vtx info)~~
- ~~5. Connect the information between vertex and cluster~~
6. Run my code to estimate detection efficiency
 Not yet...

————— Success myself after learning

Run my code to estimate detection efficiency

```
Number of clusters in the first event: 75
Cluster 1:
  lay = 0
  x = 5.54895
  y = 4.61133
  z = -8.9
  zv_mean_1sgm_err_sq12 = 2.30657
Cluster 2:
  lay = 0
  x = -6.99612
  y = 1.6485
  z = -8.9
  zv_mean_1sgm_err_sq12 = 2.30657
```

Cluster info

vertex info

Summary

- Developed the method to connect two root file
- I can get almost all information about estimating detection efficiency of INTT with vertex using simulation.

Next step

- Learning how to decide vertex position
- Based on the information, I will estimate detection efficiency of INTT with vertex using simulation **soon**.