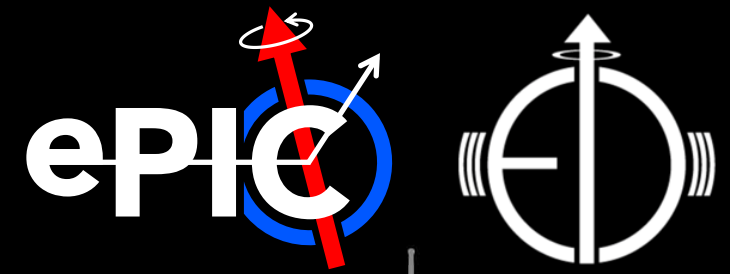




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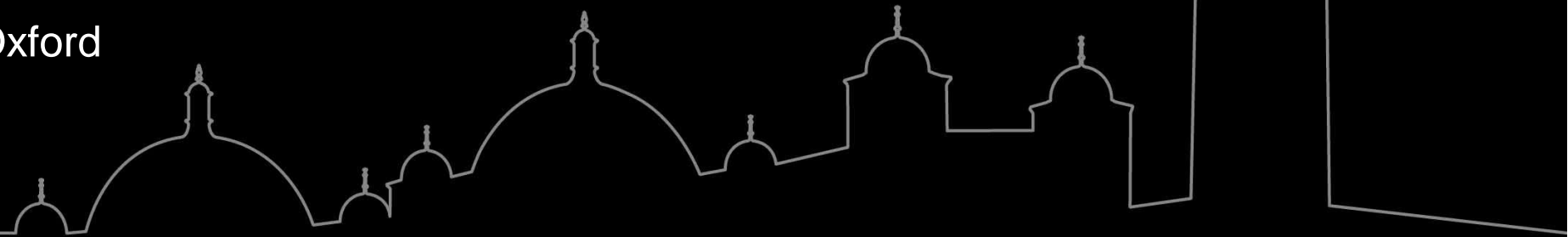


# ePIC SVT Outer Barrel Layout

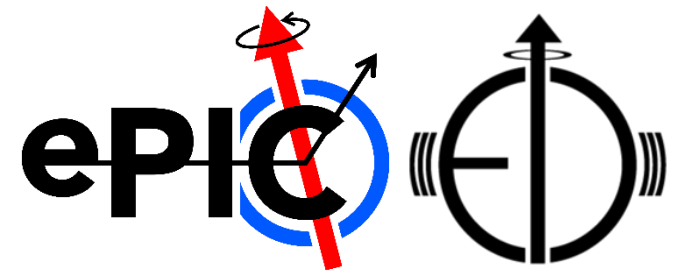
James Glover

EIC-UK WP1 (MAPS)  
Face-to-Face meeting @ Oxford

Thu, 3<sup>rd</sup> October 2024




# ePIC Silicon Vertex Tracker (SVT)

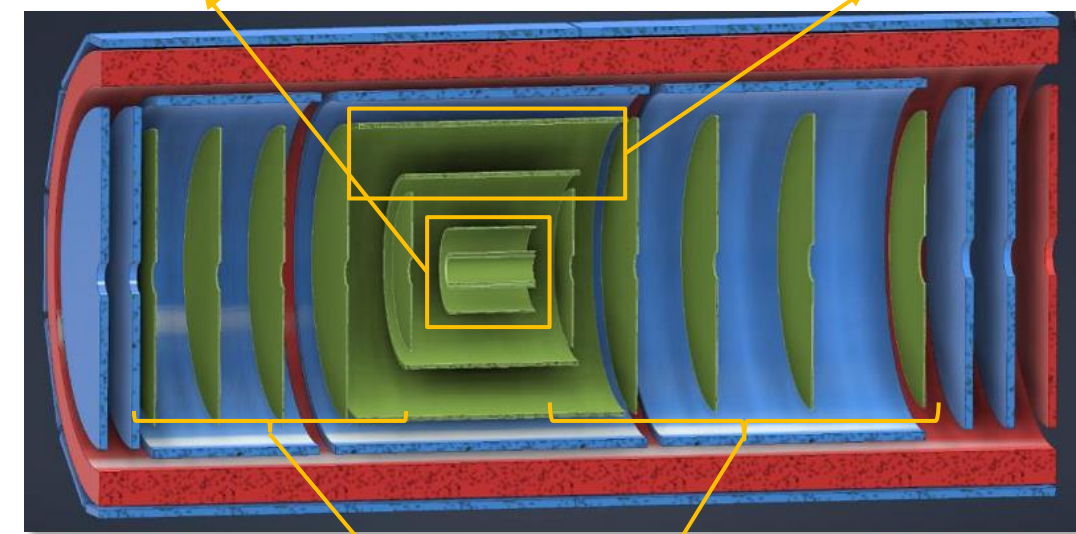


- The ePIC SVT will be the combination of 5 barrel layers and 10 endcap discs.
  - 3 Inner Barrel (IB) layers – same curved, wafer-scale stitched MAPS used within ITS3.
  - 2 Outer Barrel (OB) layers – longer than IB, optimised sensor for EIC.
    - Focus of EIC-UK WP1 (MAPS).
  - 5 discs for Electron and Hadron (going) Endcaps (EE/HE).
    - Same optimised sensor as OB.

(MAPS – Monolithic Active Pixel Sensor)

Inner Barrel (IB)  
3 curved layers

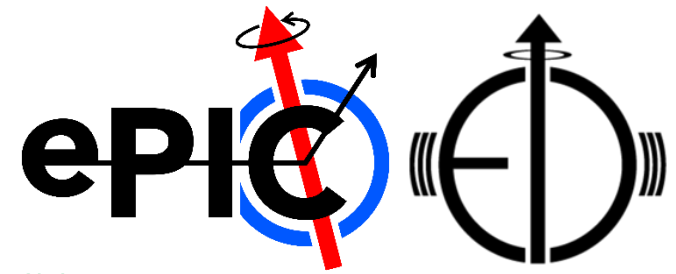
 Outer Barrel (OB)  
2 stave-based layers



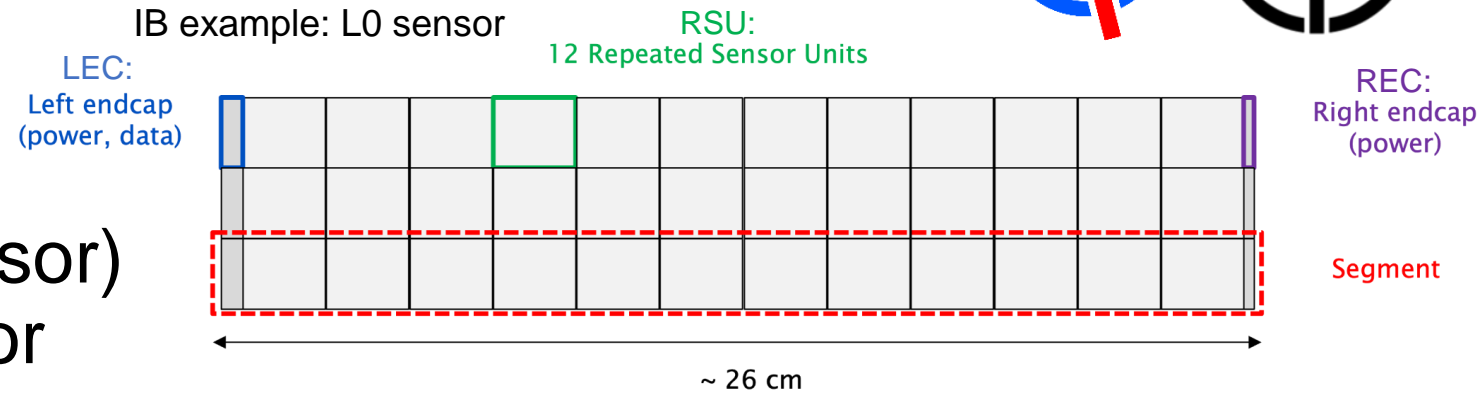
SVT      MPGDs      ToF (fiducial volume)

Electron/Hadron Endcaps (EE, HE)  
5 discs on either side of the IP

# MAPS for EIC



- Wafer-scale sensor used in IB.
- EIC-LAS (Large Area Sensor) is the EIC optimised sensor variant to help minimise the material required due to service (data/power/control) connections and improve yield for large area coverage.
  - For OB, EE, and HE of SVT.



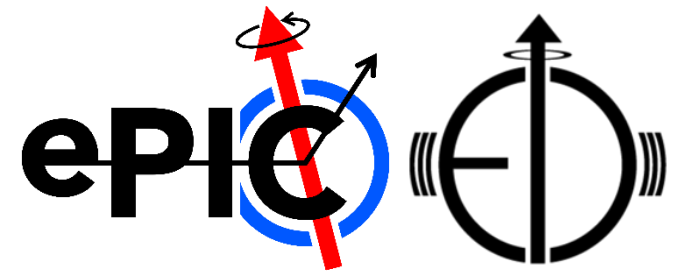
From: [https://wiki.bnl.gov/EPIC/index.php?title=Si\\_Vertex\\_Tracker](https://wiki.bnl.gov/EPIC/index.php?title=Si_Vertex_Tracker)

IB	– Inner Barrel
OB	– Outer Barrel
EE	– Electron Endcap
HE	– Hadron Endcap
SVT	– Silicon Vertex Tracker

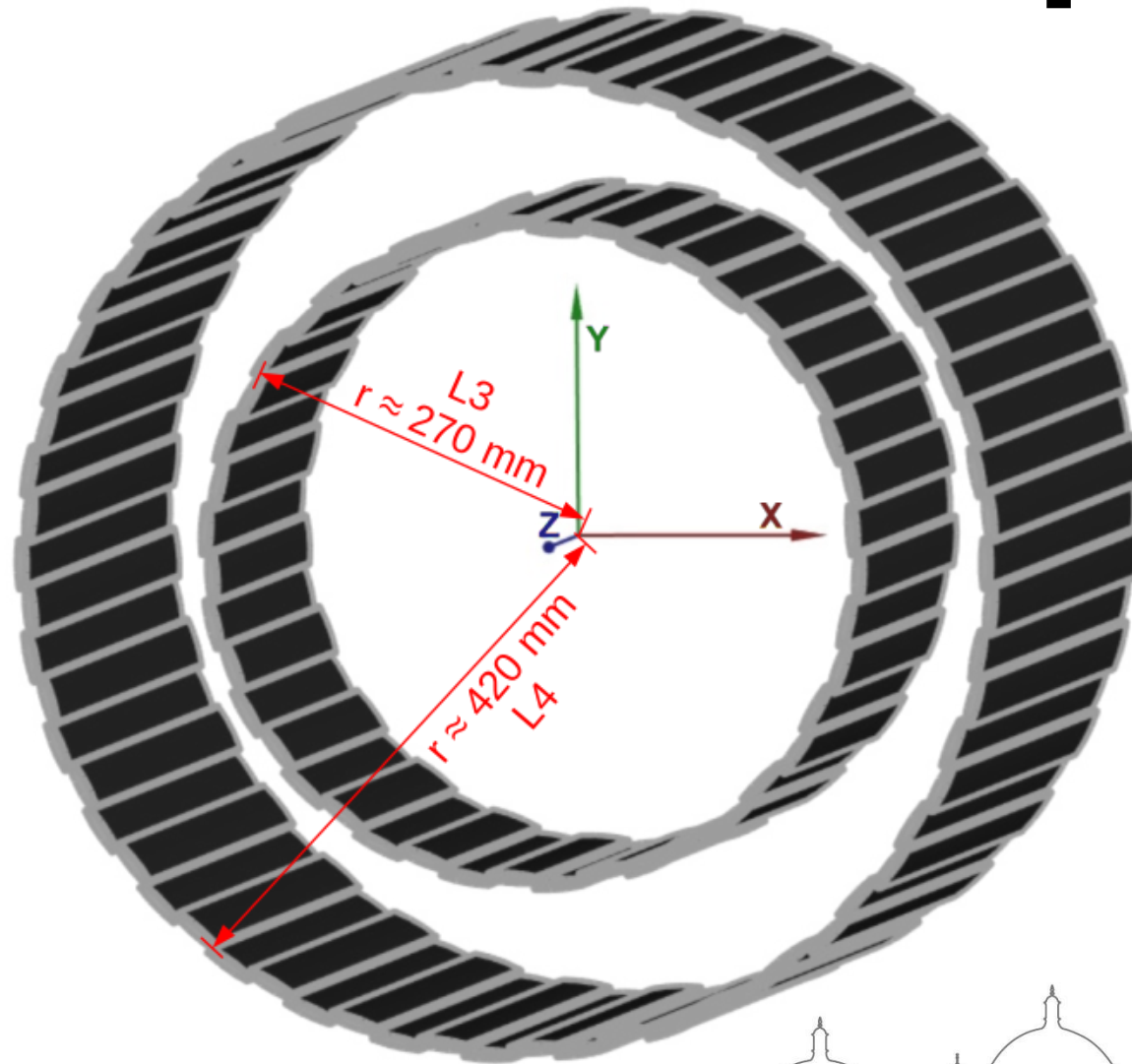


EIC-LAS

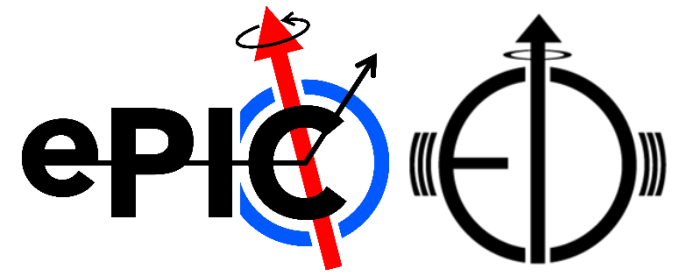
# Outer barrel



- 2 stave-based layers (L3 and L4) of stitched MAPS.
- Stave repeated around the Z-axis until (active silicon of) staves fully cover the circumference (at target radii).

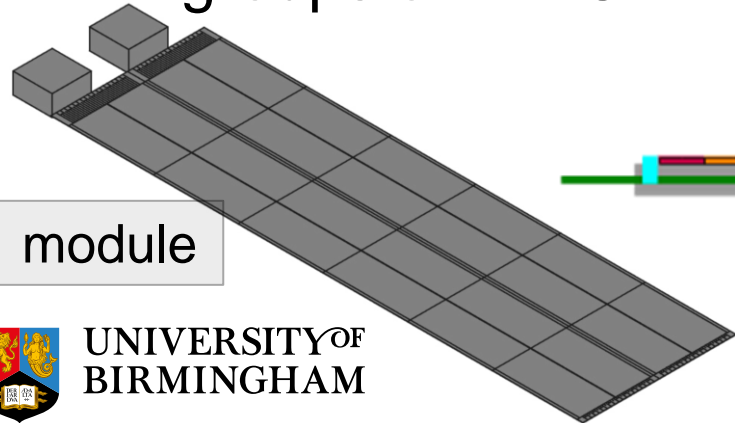


# Construction of staves



## Outer Barrel – Layer3

- Double-sided staves
- Using EIC-LAS with 6 RSUs
- 2 EIC-LAS wide (1 module)
- 4 modules long
- 2 groups of 4 EIC-LAS (8 total)



OB L3 (EIC-LAS with 6 RSUs)

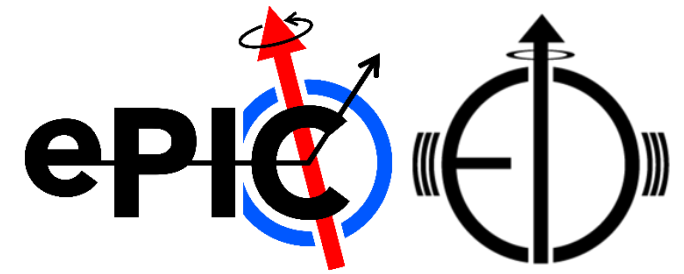


1 module

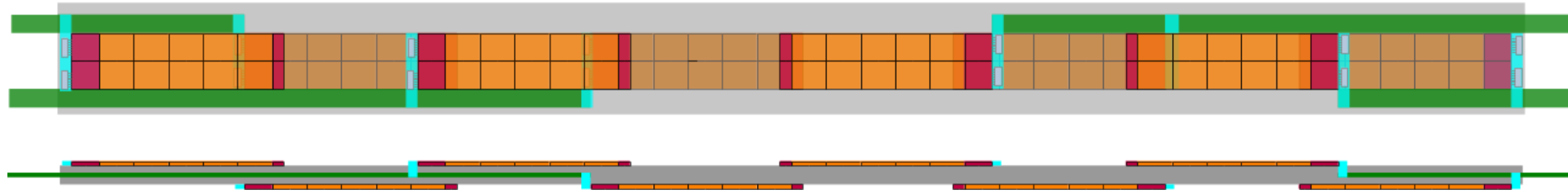
## Outer Barrel – Layer4

- Double-sided staves
- Using EIC-LAS with 5 RSUs
- 2 EIC-LAS wide (1 module)
- 8 modules long
- 4 groups of 4 EIC-LAS (16 total)

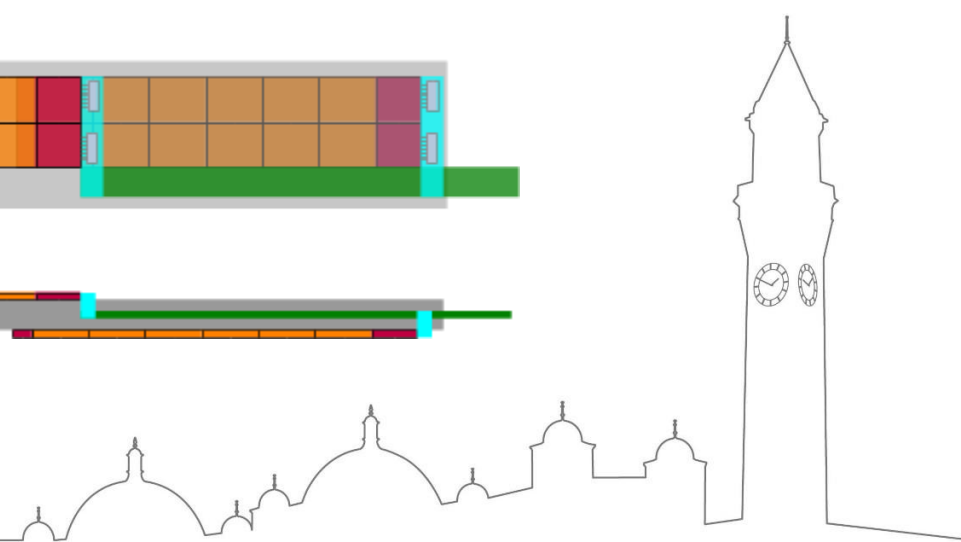
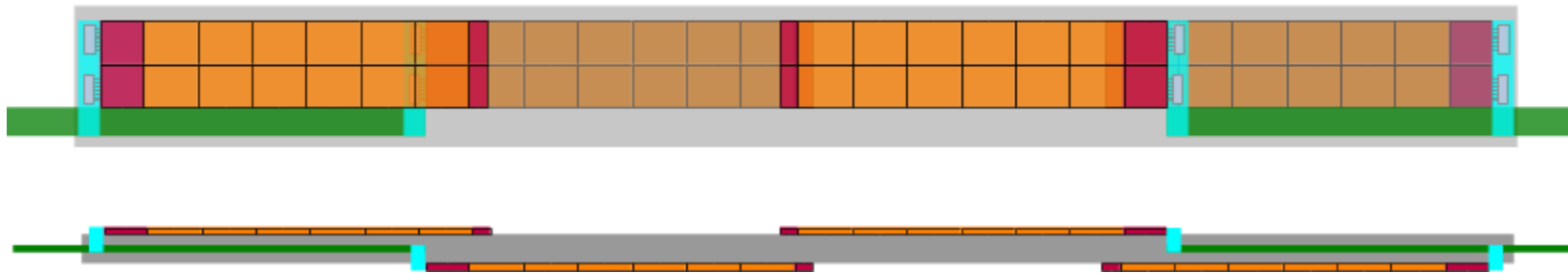
# Stave per SVT layer (cartoon)



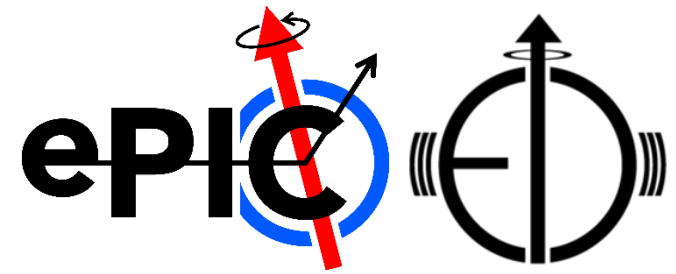
Layer 4 (EIC-LAS w. 5\*RSU)



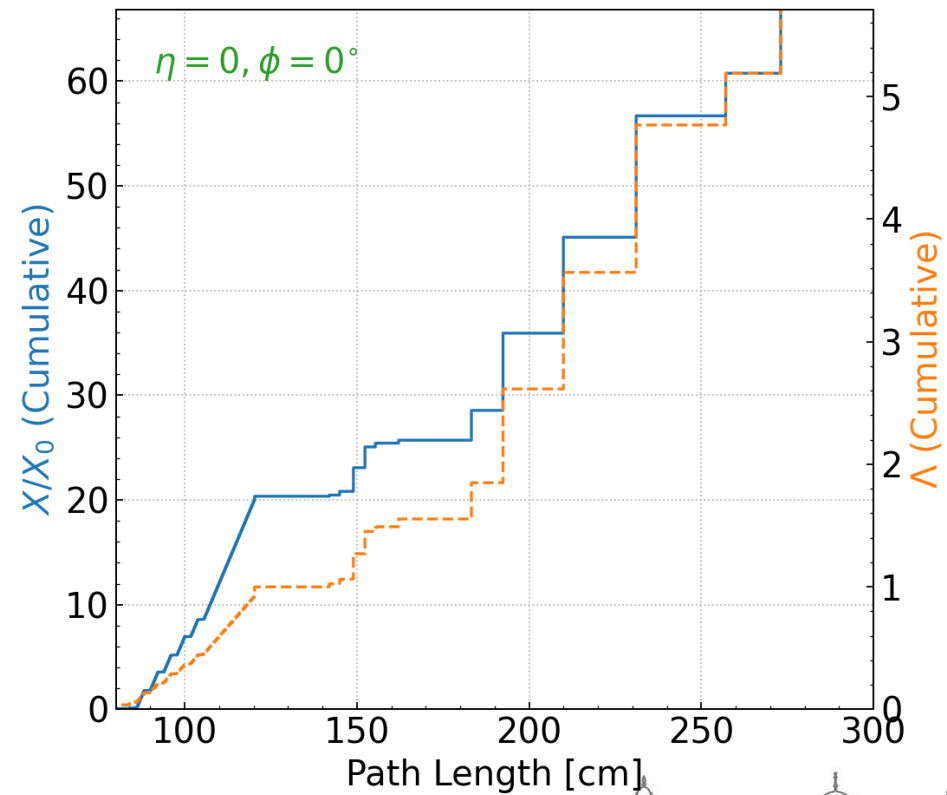
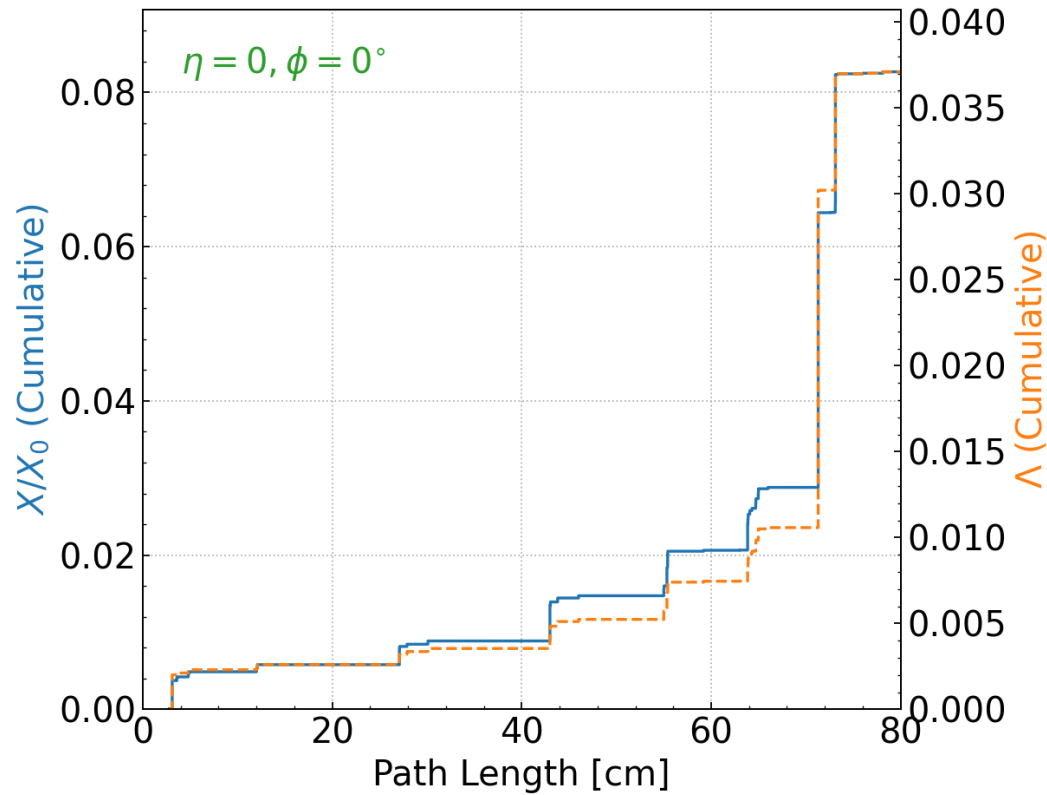
Layer 3 (EIC-LAS w. 6\*RSU)



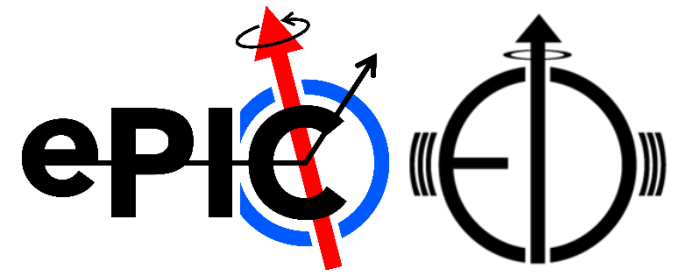
# Current Material (for simulations)



Recent [general meeting](#) showed how the material is positioned in the simulation framework:

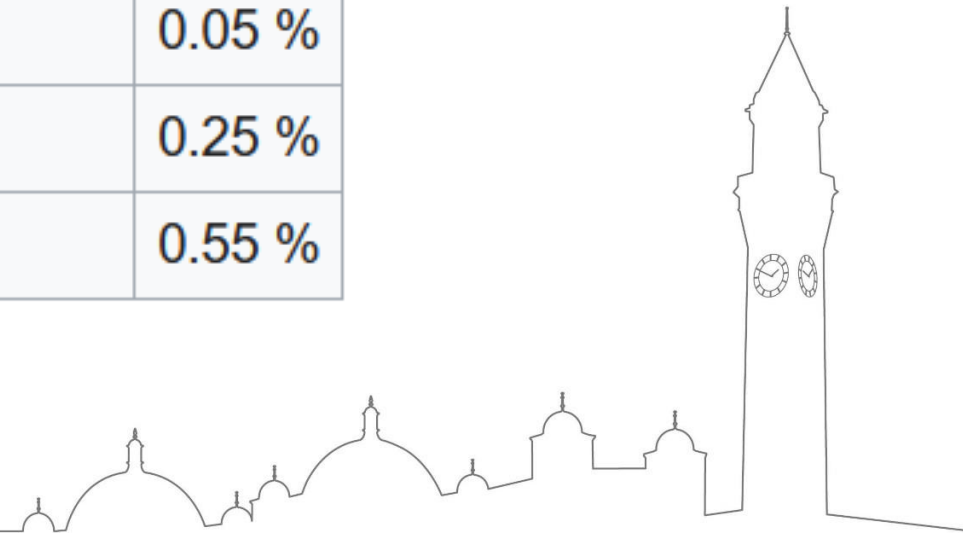


# Ideal Layer Radii (from twiki)



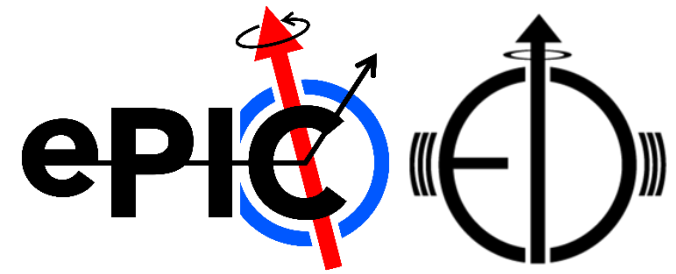
The ideal radii for each SVT layer is documented on the [ePIC twiki](#):

Region	Layer	radius [mm]	length [mm]	X/X0
IB	L0	36	270	0.05 %
	L1	48	270	0.05 %
	L2	120	270	0.05 %
OB	L3	270	540	0.25 %
	L4	420	840	0.55 %

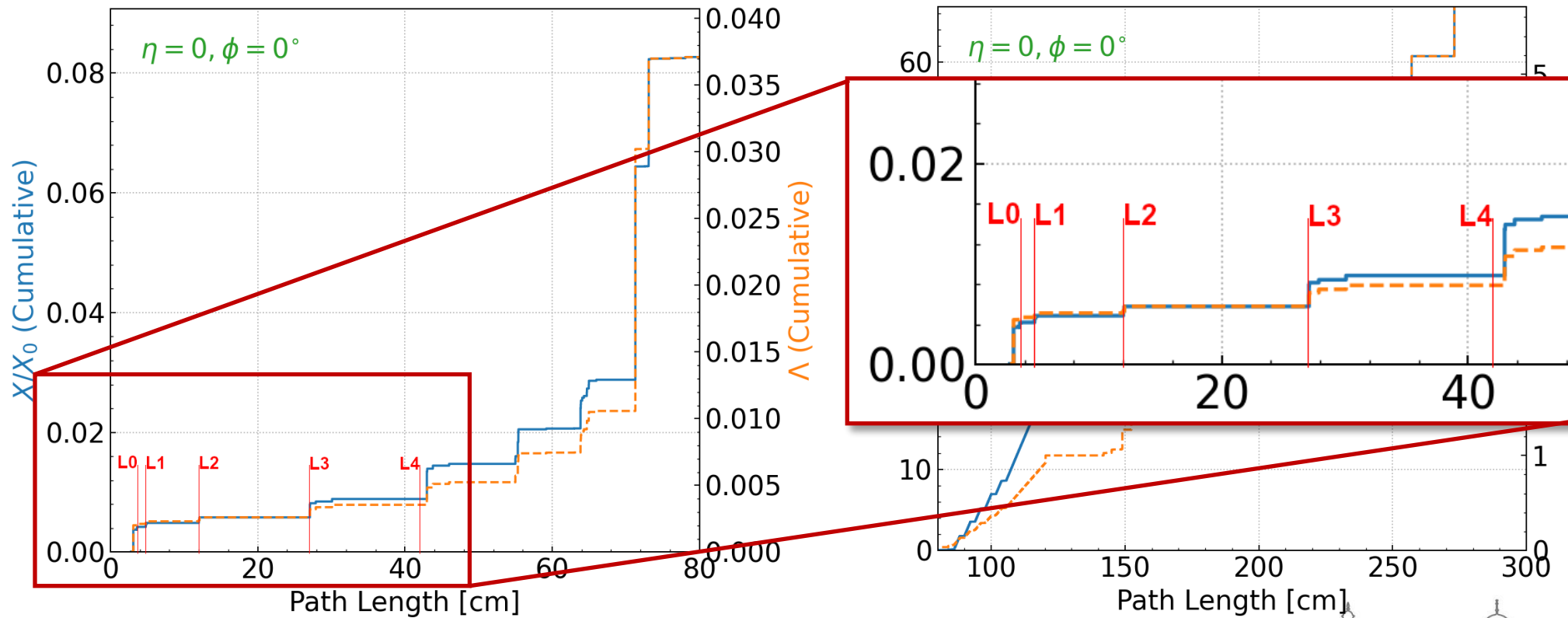




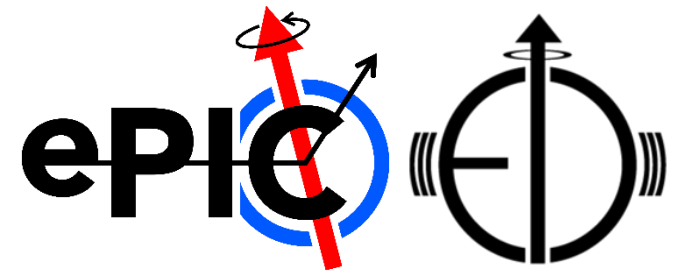
# Current Material (with SVT radii)



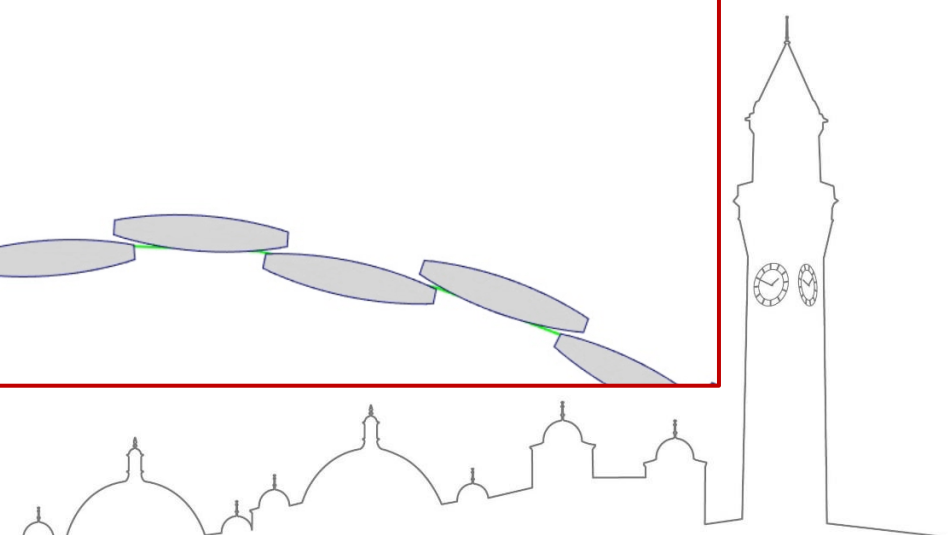
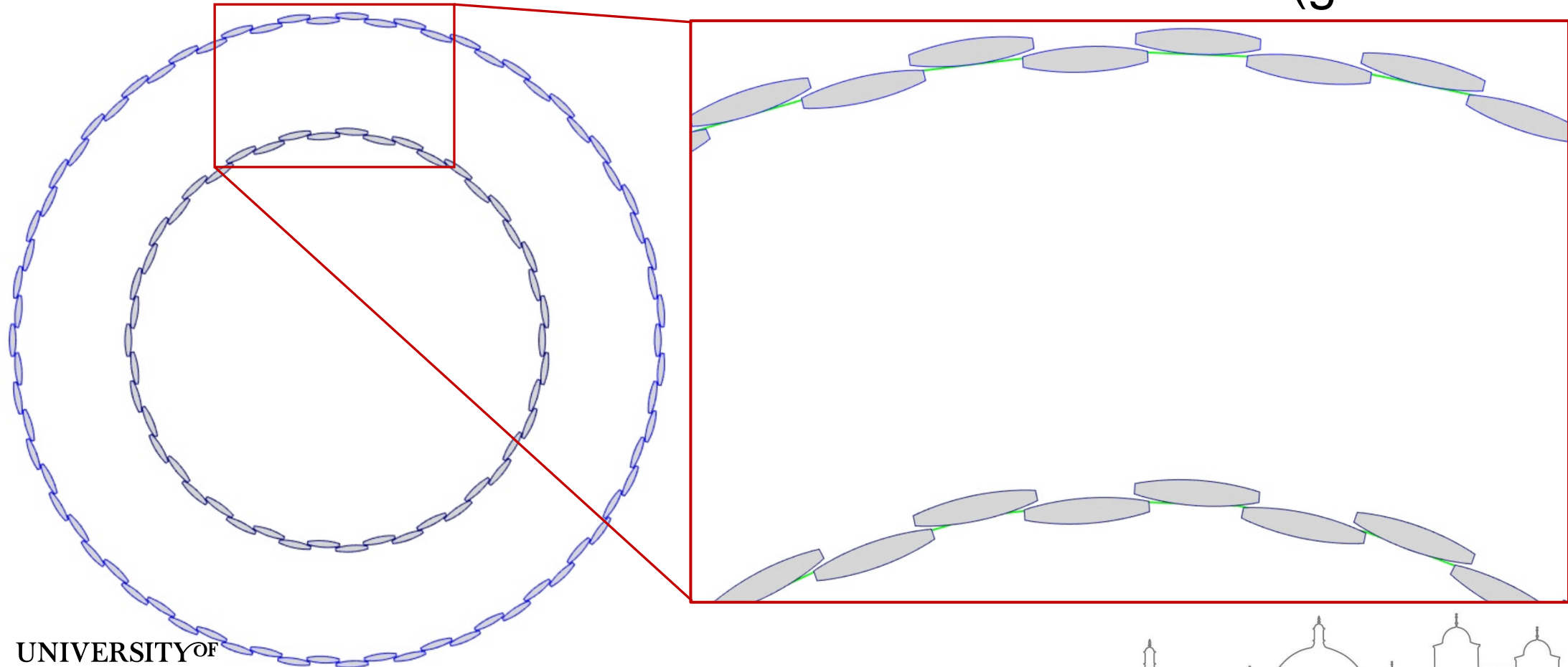
The material **starts** at the ideal radii (apart from L4):



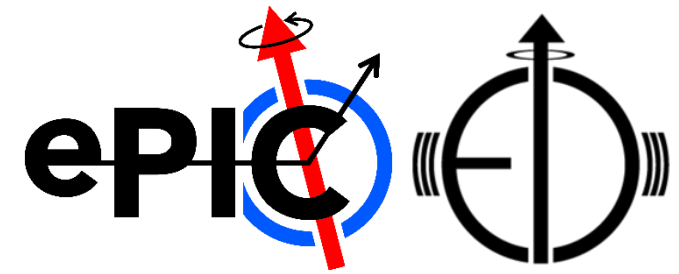
# Current OB layout



CAD models have stated a **COM** radius for L3 and L4 (green lines):



# Current OB dimensions



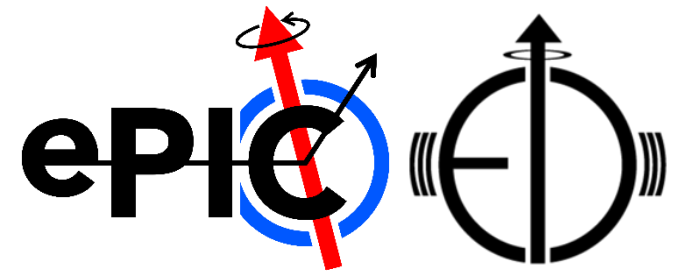
Layer	Radial Aim	Inner most Radii	Outer most Radii	#RSU per EIC-LAS	#Staves per layer	#EIC-LAS per layer
L3	272 mm	264.75 mm	279.25 mm	6RSU-LAS	46	368
L4	424 mm	416.75 mm	431.25 mm	5RSU-LAS	70	1,120

6 mm spacing from inner to outer sub-layer radius ( $\pm 3$  mm from radii of 272 and 424).

- This spacing may need to be increased to guarantee good, mechanical clearance between sub-layers.
- $\therefore$  Overlaps between staves would need to increase.
- Best achieved by reducing the radius.



# JLab documented envelop

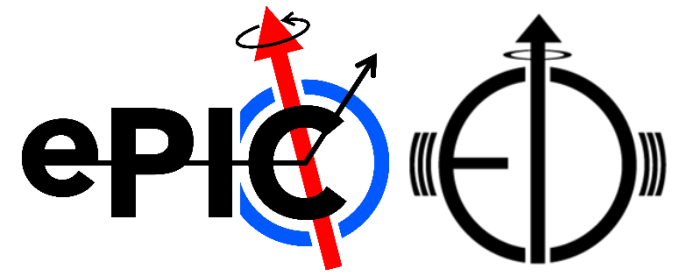


JLab have a repository of the ePIC detector geometries [here](#).

- Currently the outer-most SVT radius is 430 mm (for Endcap Disks) – [in line with \(draft\) TDR wording](#).
- The next layer (Micromegas barrel) starts at a radius of 550 mm.
- SVT support cylinder needs to exist somewhere between, but at what radius?
  - Limits the outermost radius of L4.
  - Current layout already has [L4's outer radius at ~432 mm!](#)



# Summary

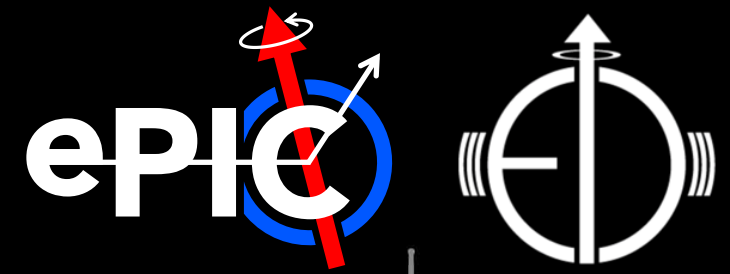


- No current change to the OB layout.
- Notes and caveats to remember when comparing the simulations and mechanical designs.
- Mechanical limitations are likely to reduce the radii of L3 and L4.
  - This may need to be fed into the simulation work to verify performance.
  - Do we just recommend an average radius for the material per layer?
  - We also need a more accurate estimate of material per layer (L3 and L4 will be closer together than the estimated 0.25 and 0.55 %  $X/X_0$ ).
    - Sam is already looking into this.





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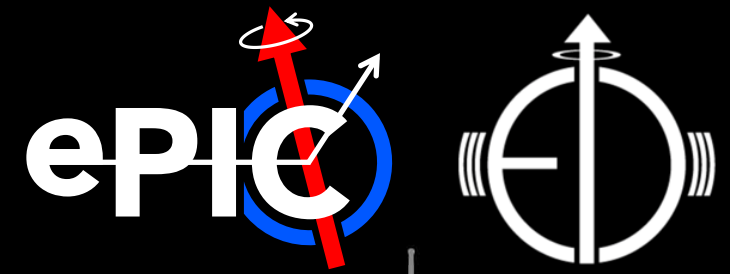
# Thank you very much!

Any questions?

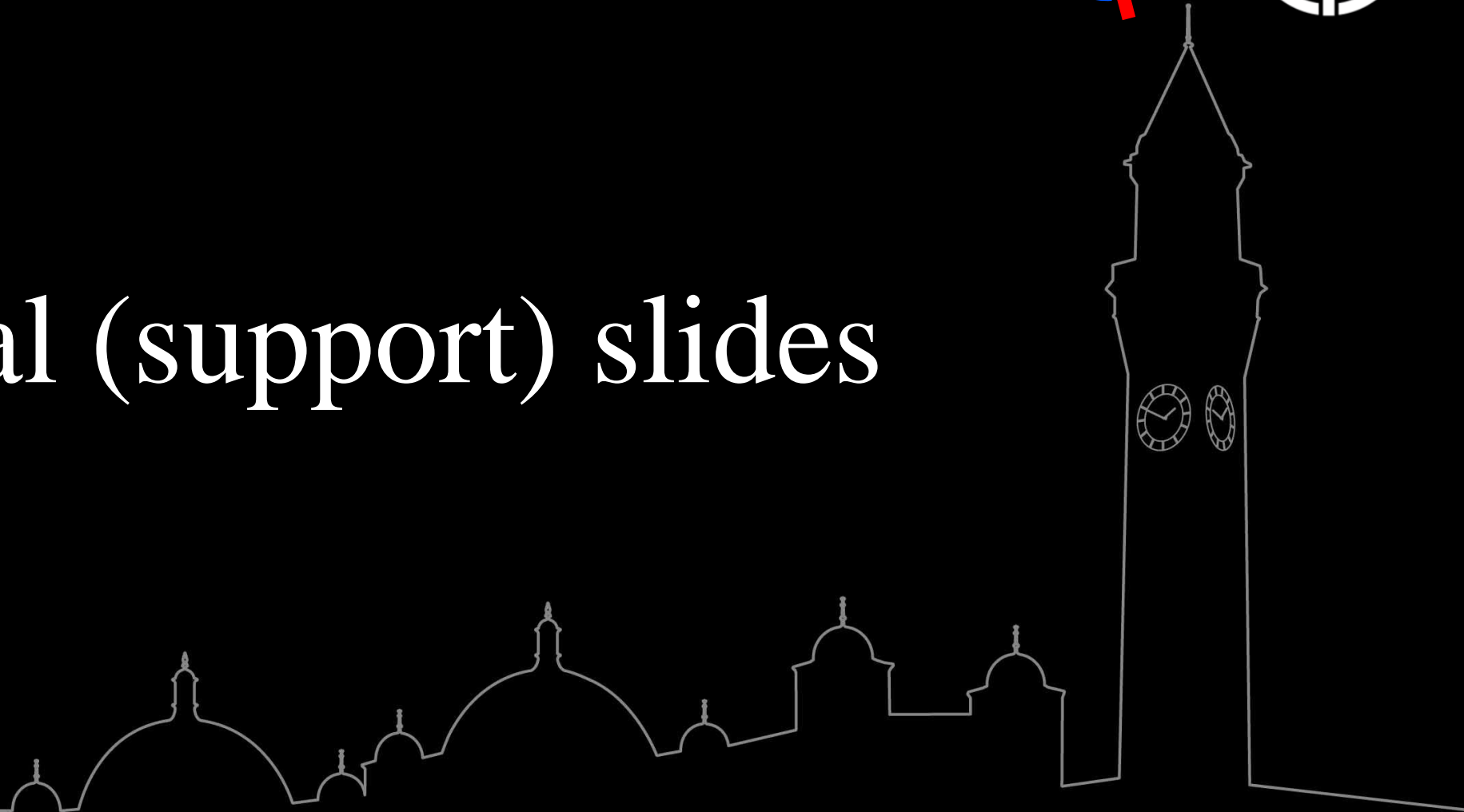




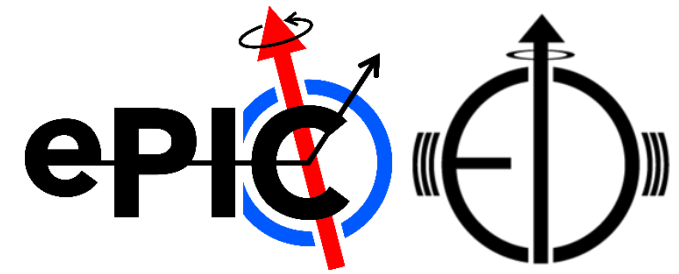
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Additional (support) slides



# Edits to JLab envelop

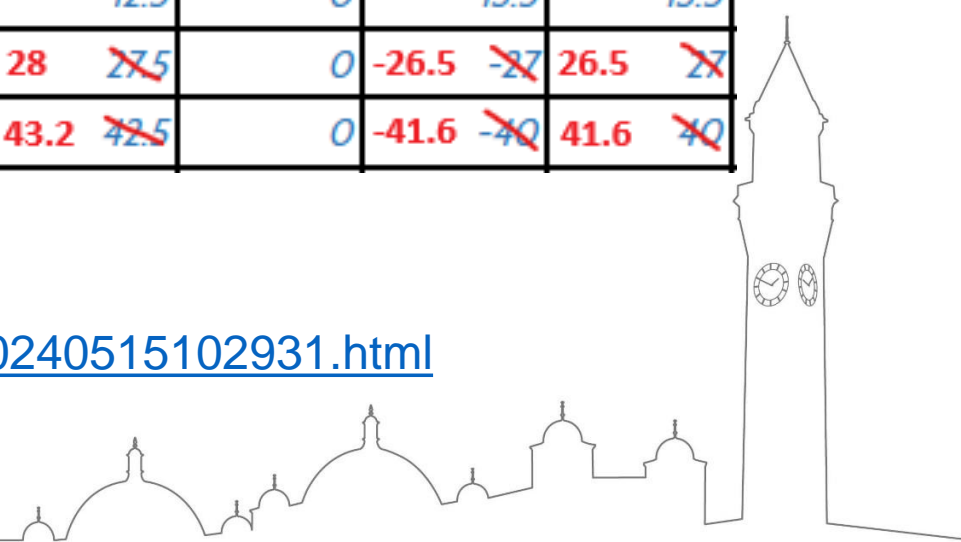


Component	Sub-Component	WBS	Length (cm)	Inner Radius (cm)	Outer Radius (cm)	Offset from Center (cm)	Physical Start (cm)	Physical End (cm)					
Inner Tracker (Si Barrel)		6.10.03	<del>80</del>	3.6	<del>42.5</del>	0	<del>-40</del>	<del>40</del>					
	Si Layer <del>X</del> 0		27	3.6	4.1	0	-13.5	13.5					
	Si Layer <del>X</del> 1		27	4.8	5.3	0	-13.5	13.5					
	Si Layer <del>X</del> 2		27	12	12.5	0	-13.5	13.5					
	Si Layer <del>X</del> 3		53	<del>54</del>	<del>26.5</del>	<del>27</del>	<del>28</del>	<del>27.5</del>	0	<del>-26.5</del>	<del>-27</del>	<del>26.5</del>	<del>27</del>
	Si Layer <del>X</del> 4		83.2	<del>80</del>	<del>41.6</del>	<del>42</del>	<del>43.2</del>	<del>42.5</del>	0	<del>-41.6</del>	<del>-40</del>	<del>41.6</del>	<del>40</del>

<https://eic.jlab.org/Geometry/Detector/Detector-20240515102931.html>

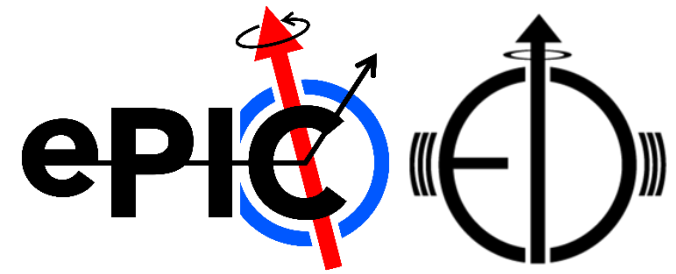


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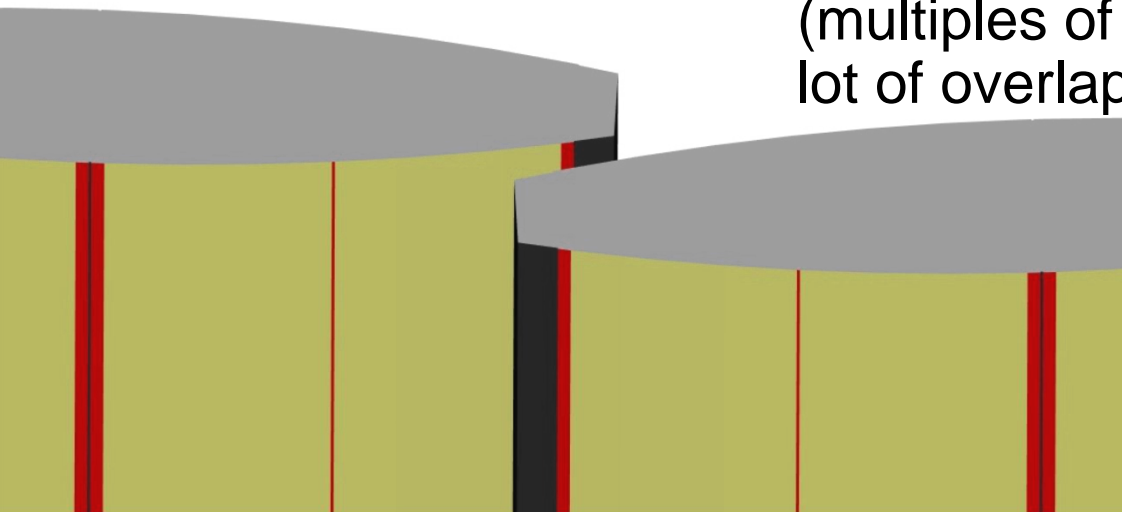
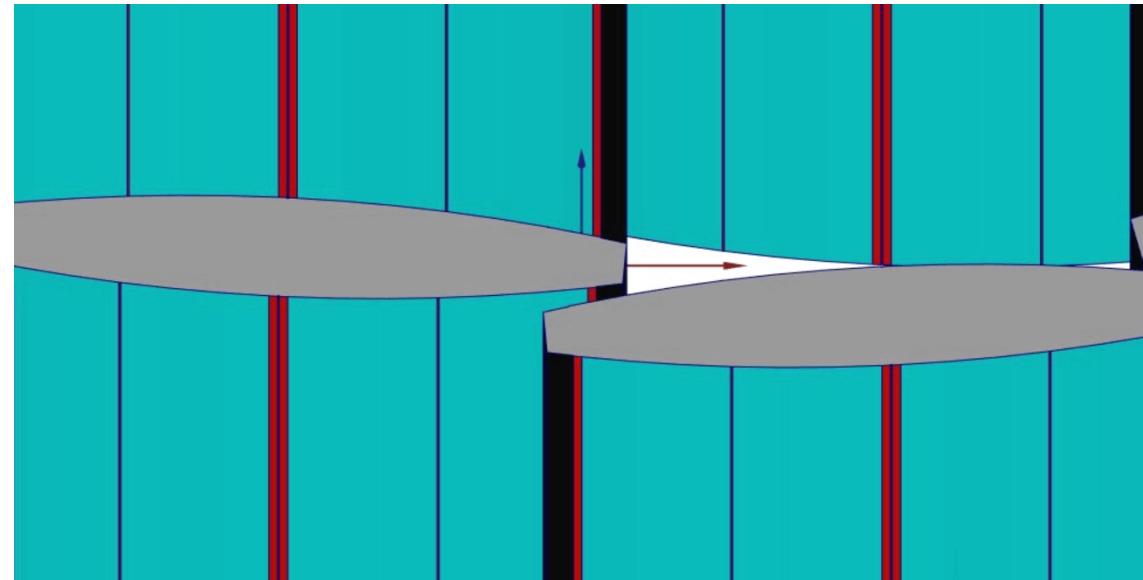




# Overlaps yet to be defined



- Overlaps are still to be (fully) accounted for.
- Fine tuning of overlaps will be done with adjustments to radii.
- Adding more staves (multiples of 2) adds a lot of overlap.



Started to look at minimum  $p_t$  to estimate worst case curvature of track (WIP).

