

Overcoming the challenges of quantum interference in Higgs physics with high-dimensional statistical inference

Aishik Ghosh

BNL

04 November 2024



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What's to come

Statistical inference methods developed for Higgs width
You can follow technical details / intuitive explanations

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Measuring quantum interference in the off-shell Higgs to four leptons process with Machine Learning

Aishik Ghosh

Université Paris-Saclay, CNRS/IN2P3, IJCLab, 91405 Orsay, France

Abstract — The traditional machine learning approach to optimize a particle physics measurement breaks down in the presence of quantum interference between the signal and background processes. A recently developed family of physics-aware machine learning techniques that rely on the extraction of additional information from the particle physics simulator to train the neural network could be adapted to a signal strength measurement problem. The networks are trained to directly learn the likelihood or likelihood ratio between the test hypothesis and null hypothesis values of the theory parameters being measured. We apply this idea to a signal strength measurement in the off-shell Higgs to four leptons analysis for the Vector Boson Fusion production mode from simulations of the high energy proton-proton collisions at the Large Hadron Collider. Promising initial results indicate that a model trained on simulated data at different values of the signal strength outperforms traditional approaches in the presence of quantum interference.

1 Introduction

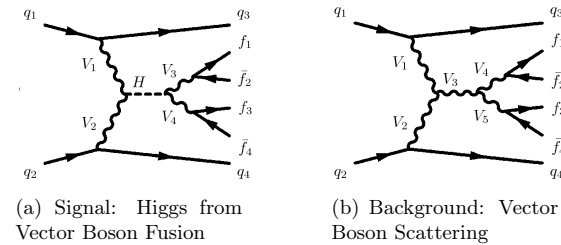


Figure 1: Feynman Diagrams of the processes under study, (a) signal Higgs diagram, (b) interfering background diagram

The Heisenberg uncertainty principle of quantum mechanics ($\sigma_E \sigma_t \geq \frac{\hbar}{2}$) allows particles to become “virtual”, with a mass going far away from the one described by special relativity’s mass-energy equivalence formula $E^2 - |\vec{p}|^2 c^2 = m_0^2 c^4$ (where the energy E is given in terms of the rest mass m_0 and momentum \vec{p} of the particle and c is the speed of light in vacuum). They are referred to as “off-shell” particles. Quantum mechanics also prescribes that given an initial and final state, all possible intermediate states can and will occur, and they may interfere with one another.

A study of the off-shell Higgs boson decaying to two Z bosons that decay to four leptons (henceforth referred to as “offshell h4l”), such the 2018 study [2] in the ATLAS Collaboration [1] is one of the most interesting studies in high energy particle physics because it allows to break certain degeneracies between the Higgs couplings, and constrain the Higgs width (under certain model dependent assumptions) that cannot be disentangled by an on-shell measurement alone. An update to the previous ATLAS study using the entire Run2

data will have develop innovative methodology to deal with quantum interference between the Higgs Feynman diagram (referred to as “signal”) and other standard model processes (referred to as “background”). While the previous round used simple cuts to define the region of interest, we investigate a recently developed family of physics-aware machine learning techniques to improve the sensitivity of such an analysis. The two main diagrams studied here are shown in Figure 1. Other signal and background processes will be included in future studies. The objective of the analysis is to measure the “signal strength”, μ , of the signal, which is a proxy for measuring how strongly the Higgs interacts with other fields. Interestingly, the usual notion that the signal strength corresponds to the ratio of the observed in data to the expected in Monte Carlo simulation signal yield breaks down in the presence of quantum interference.

This study is performed with data simulated with MadGraph5_aMC [3], Pythia 8 [4] and Delphes 3 [5].

2 Machine Learning in a signal strength measurement

Traditionally, in analyses without quantum interference, one can train a machine learning classifier (such as a Boosted Decision Tree) to separate the signal and background samples (referred to as “events”) that are simulated separately, and under the assumption that it is an optimal classifier, due to the Neyman-Pearson lemma [6], one can get the likelihood ratio [7] between a test hypothesis and the null hypothesis from the output of the classifier. The output of the classifier can be used for a fit to measure the signal strength, μ , optimally. In the presence of quantum interference, this strategy is no longer optimal. Figure 2 shows how a physics variable (the invariant mass of the four leptons) that is

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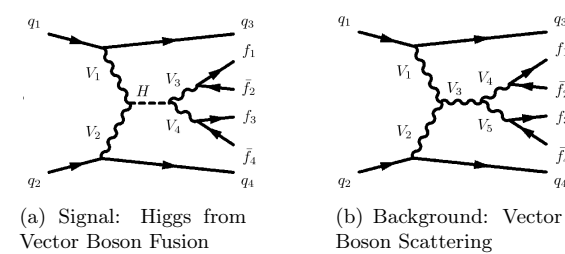


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data will have developed with quantum interference diagram (referred to as “interfering background”) in the previous round of interest, we investigate the sensitivity of machine learning studies. The objective is to measure how strong the signal strength corresponds to the expected yield breaks down into.

This study is part of the MadGraph5_aMC3

2 Machine strength

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ATLAS CONF Note

ATLAS-CONF-2024-015

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An implementation of Neural Simulation-Based Inference for Parameter Estimation in ATLAS

The ATLAS Collaboration

Neural Simulation-Based Inference (NSBI) is a powerful class of machine learning (ML)-based methods for statistical inference that naturally handles high-dimensional parameter estimation without the need to bin data into low-dimensional summary histograms. Such methods are promising for a range of measurements, including at the Large Hadron Collider (LHC), where no single observable may be optimal to scan over the entire theoretical phase space under consideration, or where binning data into histograms could result in a loss of sensitivity. This work develops an NSBI framework for statistical inference, using neural networks to estimate probability density ratios, which enables the application of NSBI to a full-scale LHC analysis. It incorporates a large number of systematic uncertainties, quantifies the uncertainty coming from finite training statistics, develops a method to construct confidence intervals, and demonstrates a series of intermediate diagnostic checks that can be performed to validate the robustness of the method. As an example, the power and feasibility of the method are demonstrated on simulated data for a simplified version of an off-shell Higgs boson couplings measurement in the four-leptons final states. This NSBI framework is an extension of the standard statistical framework used by LHC experiments and can benefit a large number of physics analyses.

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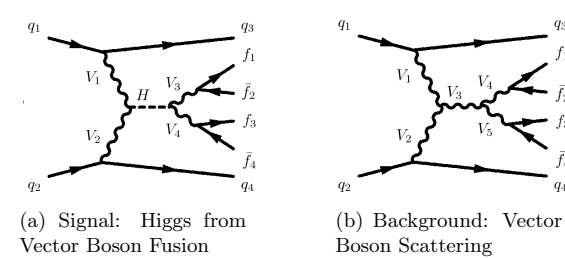


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ATLAS CONF Note

ATLAS-CONF-2024-016

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Measurement of off-shell Higgs boson production in the $H^* \rightarrow ZZ \rightarrow 4\ell$ decay channel using a neural simulation-based inference technique with the ATLAS detector at $\sqrt{s} = 13$ TeV

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A measurement of off-shell Higgs boson production in the $H^* \rightarrow ZZ \rightarrow 4\ell$ decay channel is presented. The measurement uses the 140 fb^{-1} of integrated luminosity collected by the ATLAS detector during the Run 2 proton-proton collisions of the Large Hadron Collider at $\sqrt{s} = 13$ TeV and supersedes our previous result in this decay channel using the same dataset. The data analysis is performed using a neural simulation based-inference method, which builds per-event likelihood ratios using neural networks. The observed (expected) off-shell Higgs boson production signal strength in the $ZZ \rightarrow 4\ell$ decay channel is $0.87^{+0.75}_{-0.54}$ ($1.00^{+1.04}_{-0.95}$) at 68% CL. The previous result was not able to achieve expected sensitivity to quote a two-sided interval at this CL. The expected plus-side uncertainty is reduced by 10%. The evidence for off-shell Higgs boson production has an observed (expected) significance of 2.5σ (1.3σ) using the $ZZ \rightarrow 4\ell$ decay channel only. The expected significance score is 2.6 times that of our previous result using the same dataset. When combined with our most recent measurement in $ZZ \rightarrow 2\ell 2\nu$ decay channel, the evidence for off-shell Higgs boson production has an observed (expected) significance of 3.7σ (2.4σ). The off-shell measurements are combined with the measurement of on-shell Higgs boson production to obtain constraints on the Higgs boson total width. The observed (expected) value of the Higgs boson width is $4.3^{+2.7}_{-1.9}$ ($4.1^{+3.5}_{-3.4}$) MeV at 68% CL.

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Similar story for neutron star
astrophysics

Journal of **Cosmology and Astroparticle Physics**
An IOP and SISSA journal

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Neural simulation-based inference of the neutron star equation of state directly from telescope spectra

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ⁱPhysics Division, Oak Ridge National Laboratory, Oak Ridge, TN 37831, U.S.A.

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ABSTRACT: Neutron stars provide a unique opportunity to study strongly interacting matter under extreme density conditions. The intricacies of matter inside neutron stars and their equation of state are not directly visible, but determine bulk properties, such as mass and radius, which affect the star's thermal X-ray emissions. However, the telescope spectra of these emissions are also affected by the stellar distance, hydrogen column, and effective surface temperature, which are not always well-constrained. Uncertainties on these nuisance parameters must be accounted for when making a robust estimation of the equation of state. In this study, we develop a novel methodology that, for the first time, can infer the full posterior distribution of both the equation of state and nuisance parameters directly from

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JCAP09(2024)009



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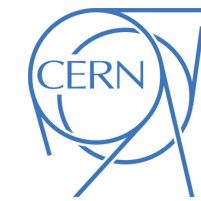
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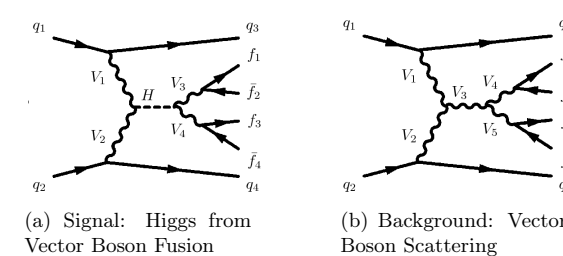


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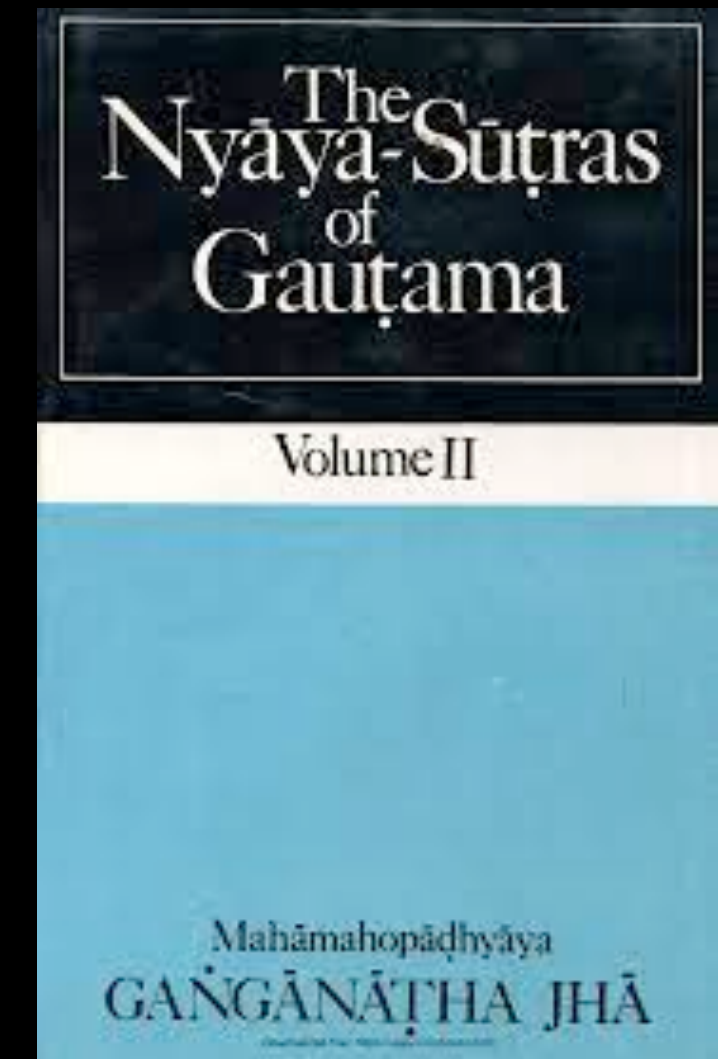
Some of the oldest questions



Image: Source

What elements make up the universe ?
(5 century BCE)

How sure are we?
Theory of Errors & Empirical Knowledge
(6 century BCE)



Some of the oldest questions

Theorists



What elements make up the universe ?
(5 century BCE)

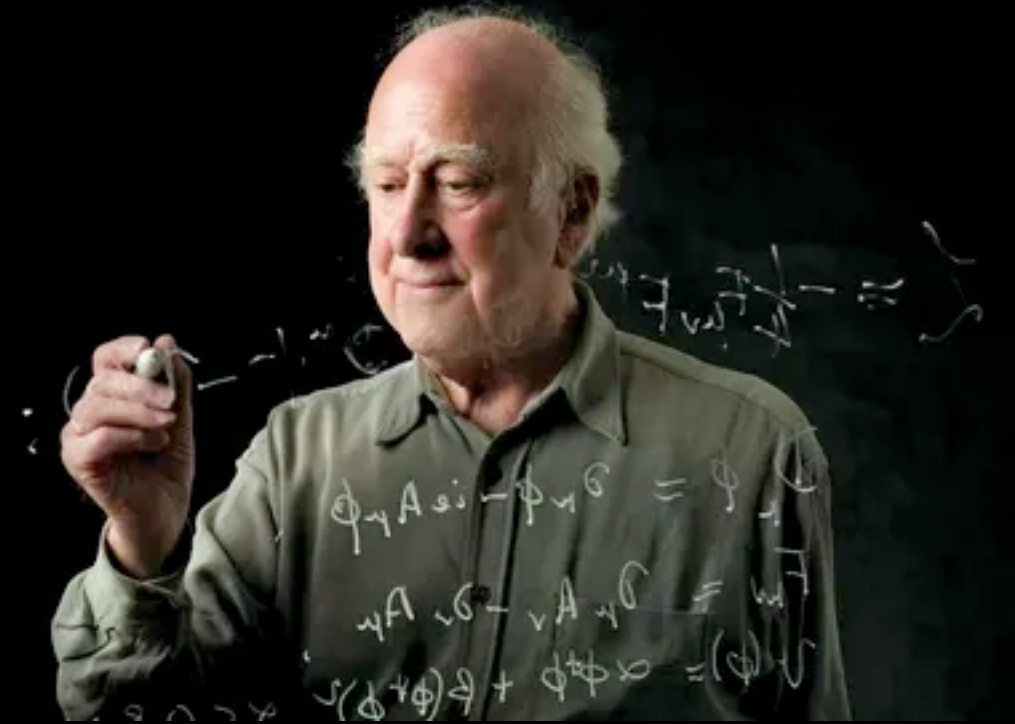
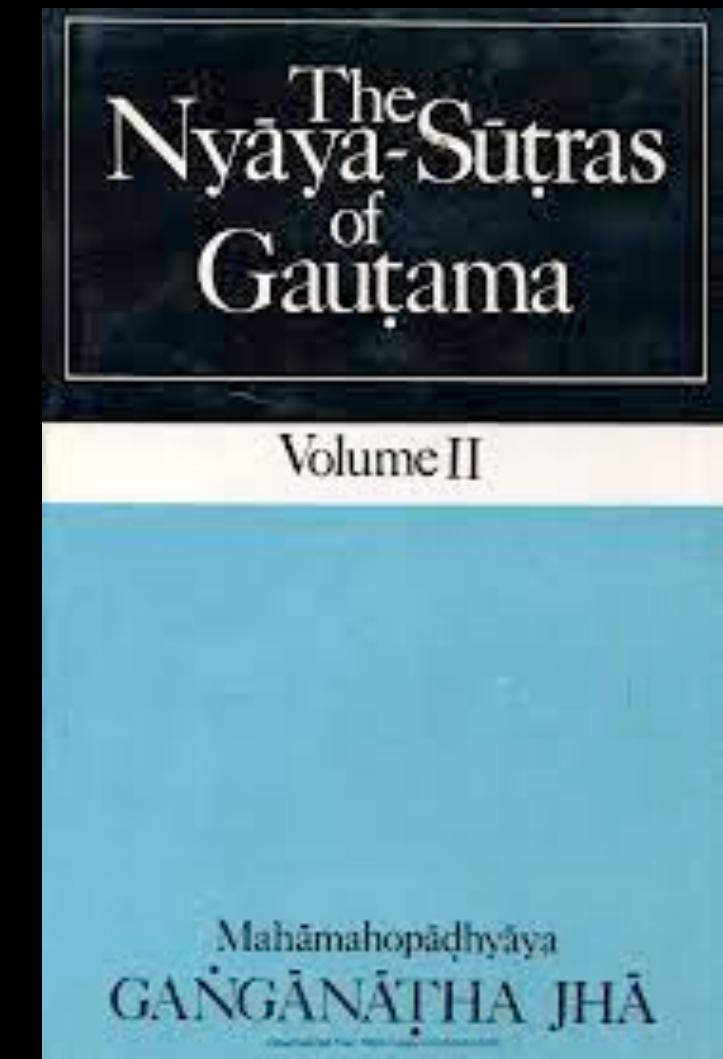


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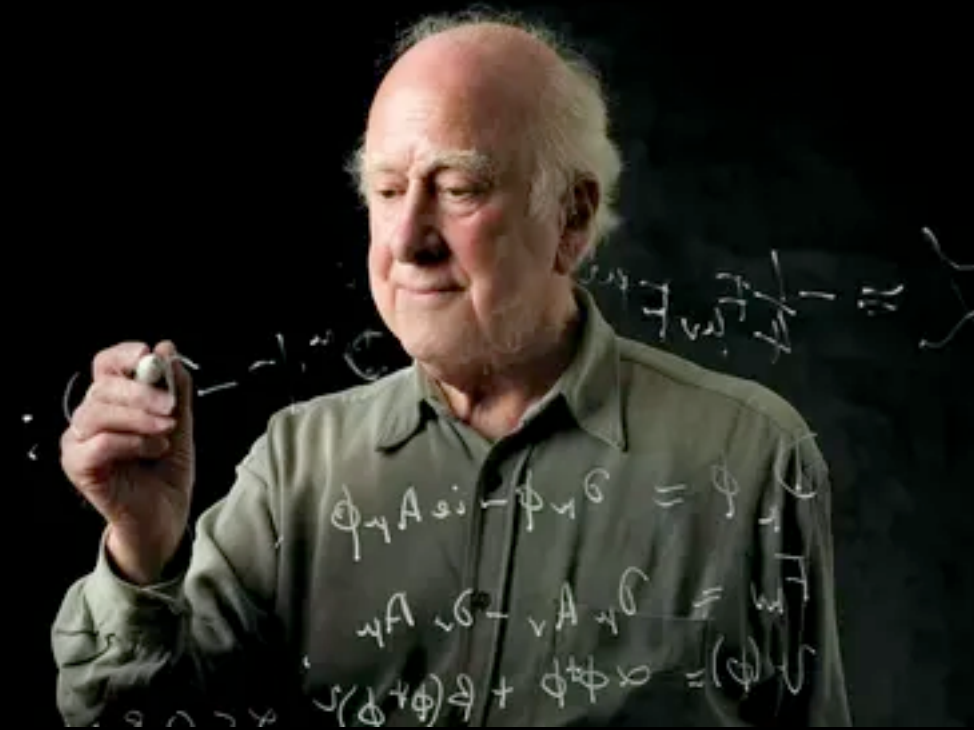
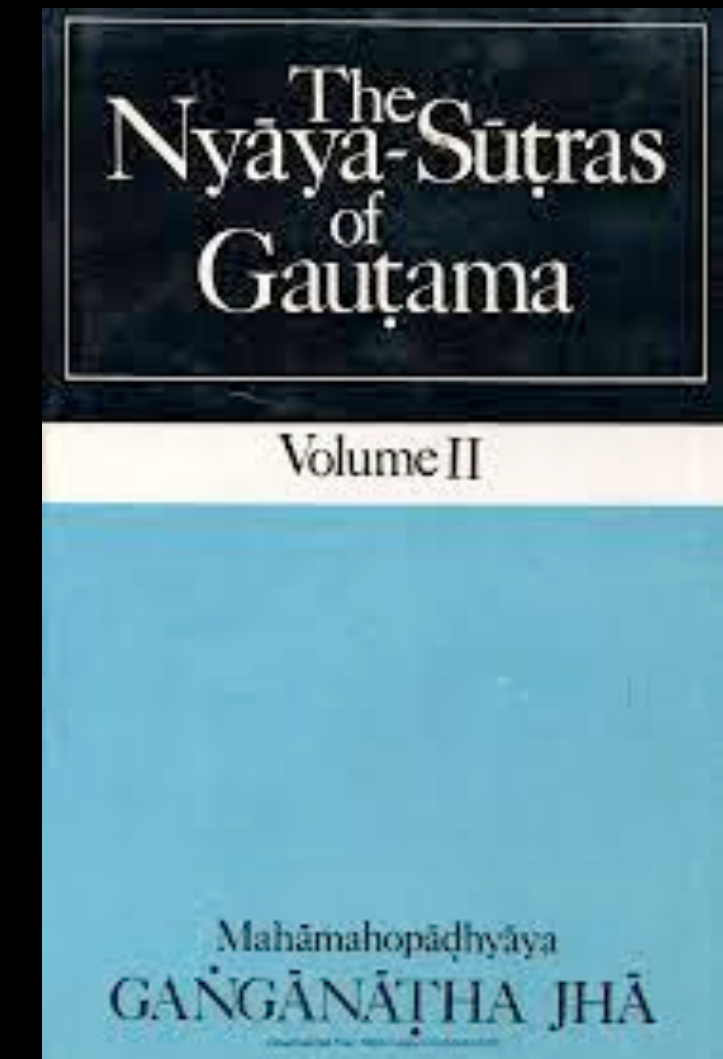


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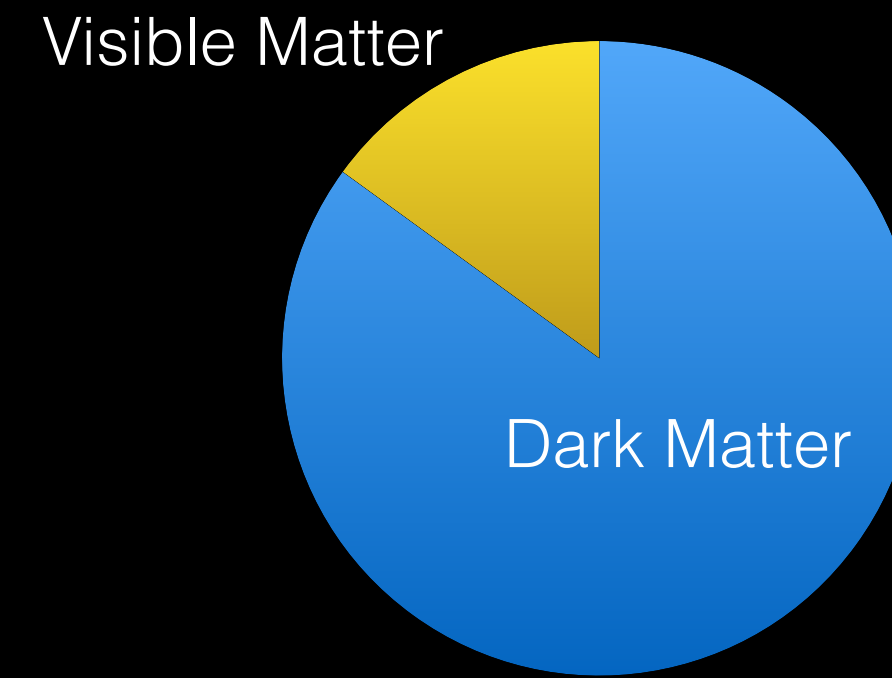


Experimentalists

Questions about the universe today...

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There's so much more dark matter than visible matter in the universe. What is it ?



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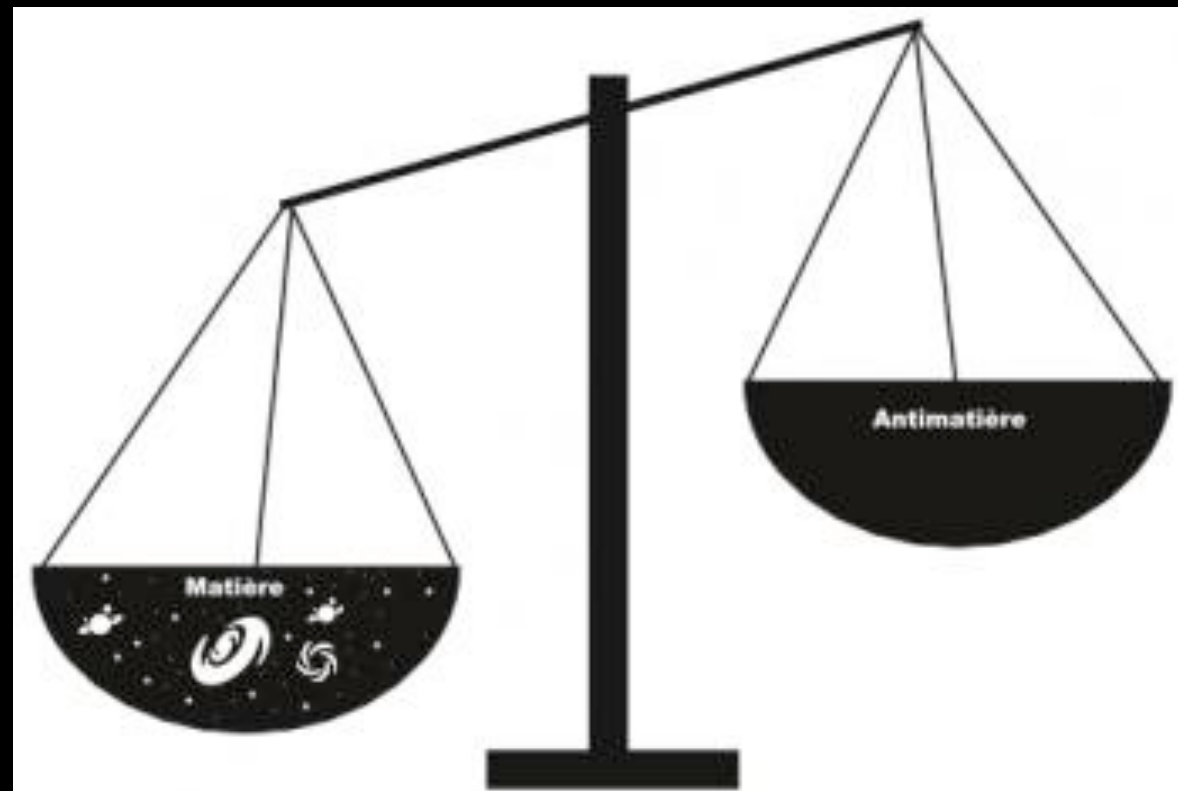
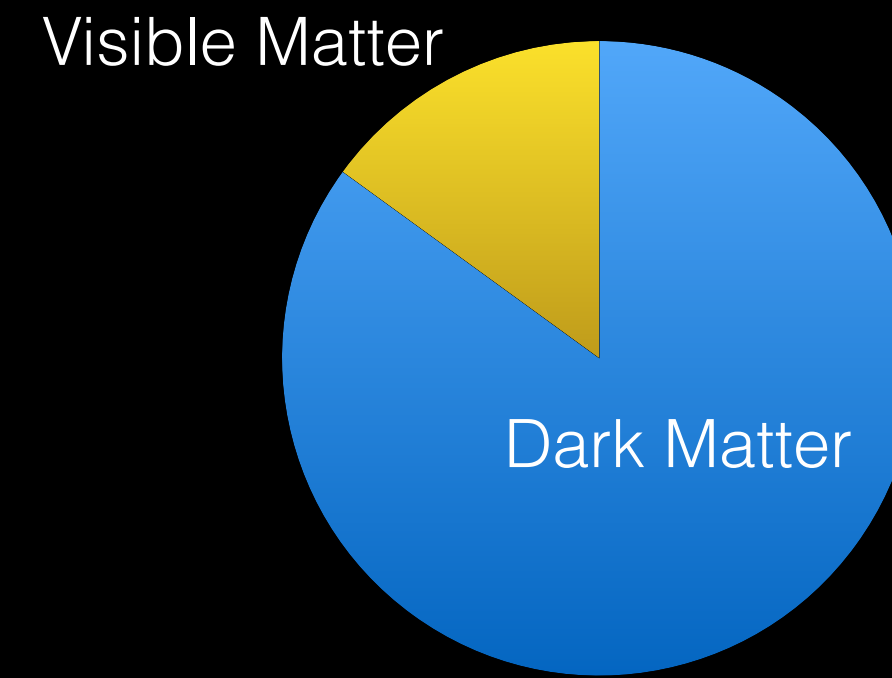


Image: GANIL

Why more matter than anti-matter ?

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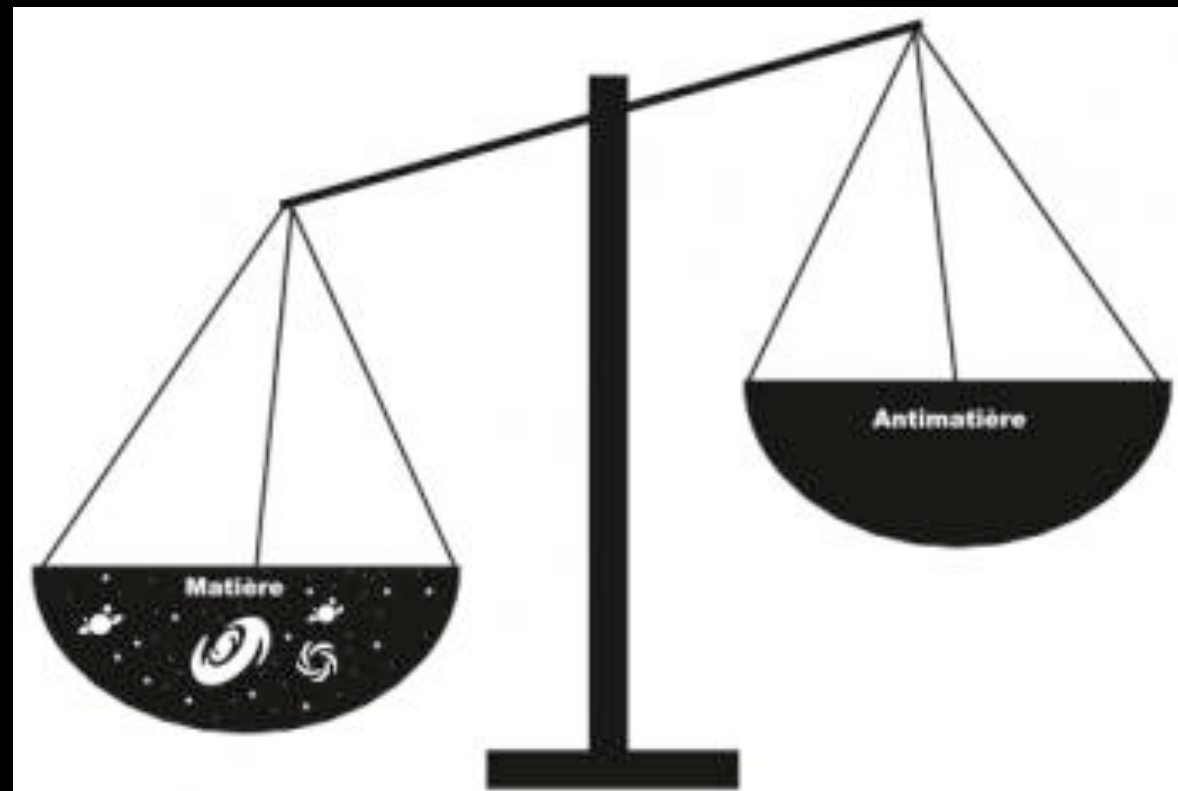
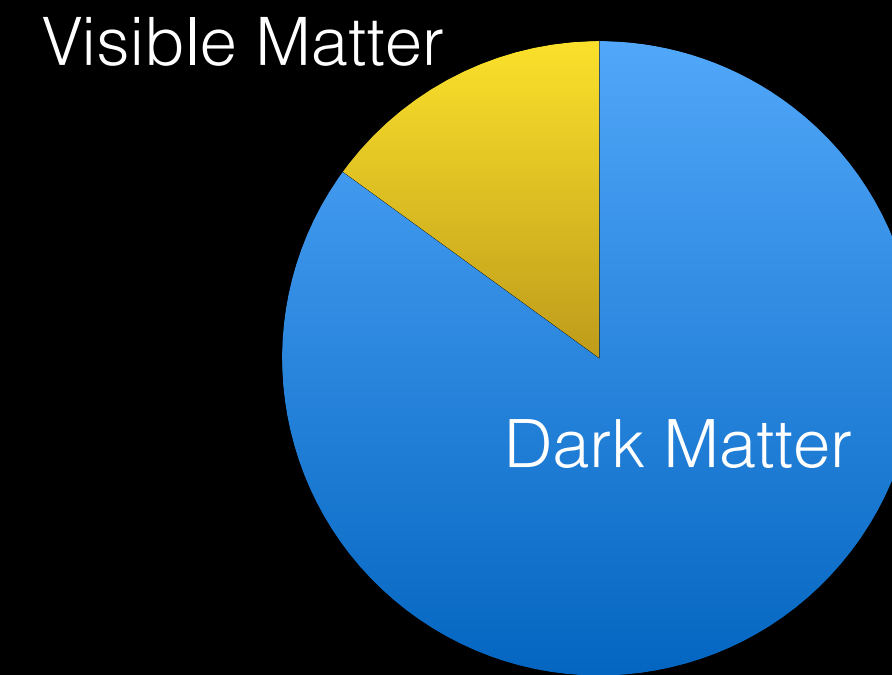


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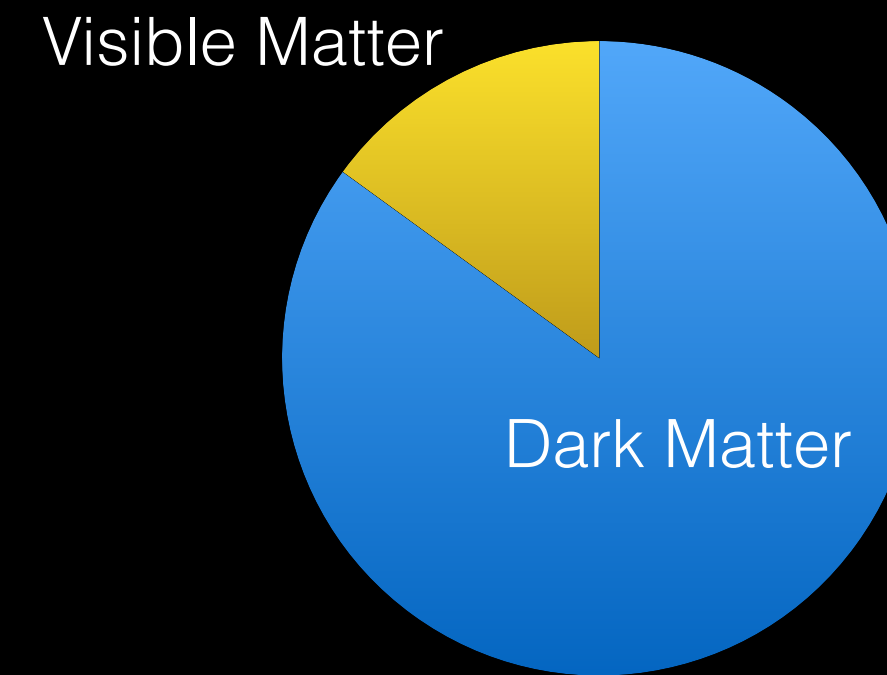


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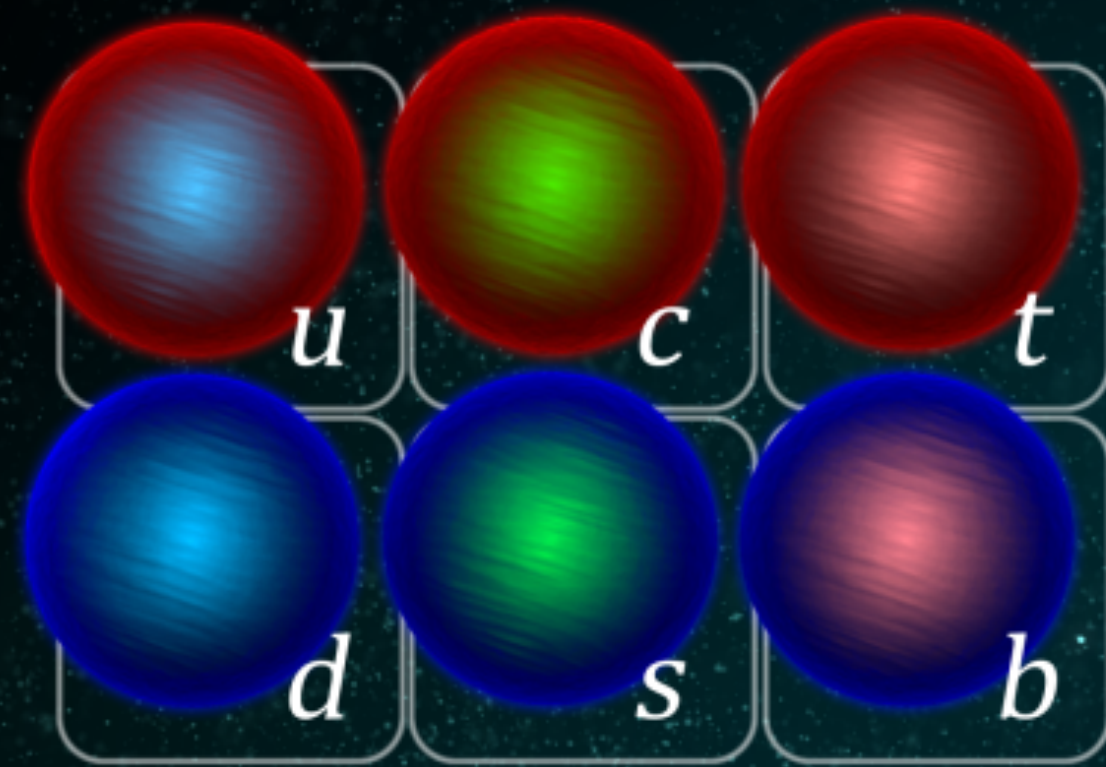
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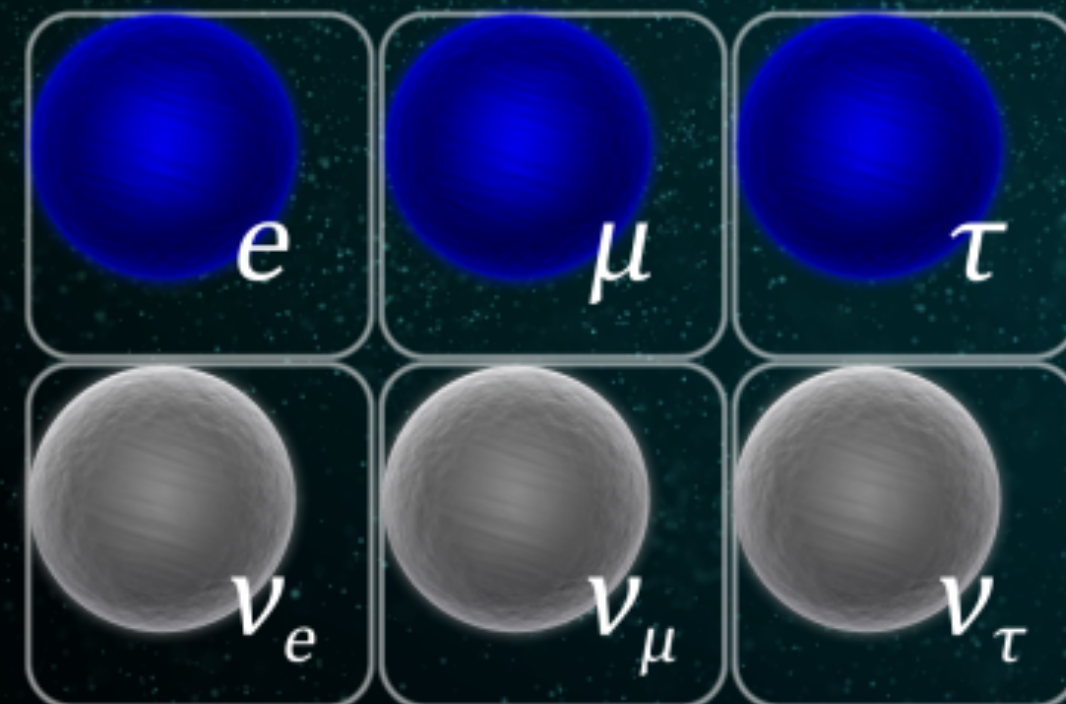
New theories often predict new particles yet to be discovered



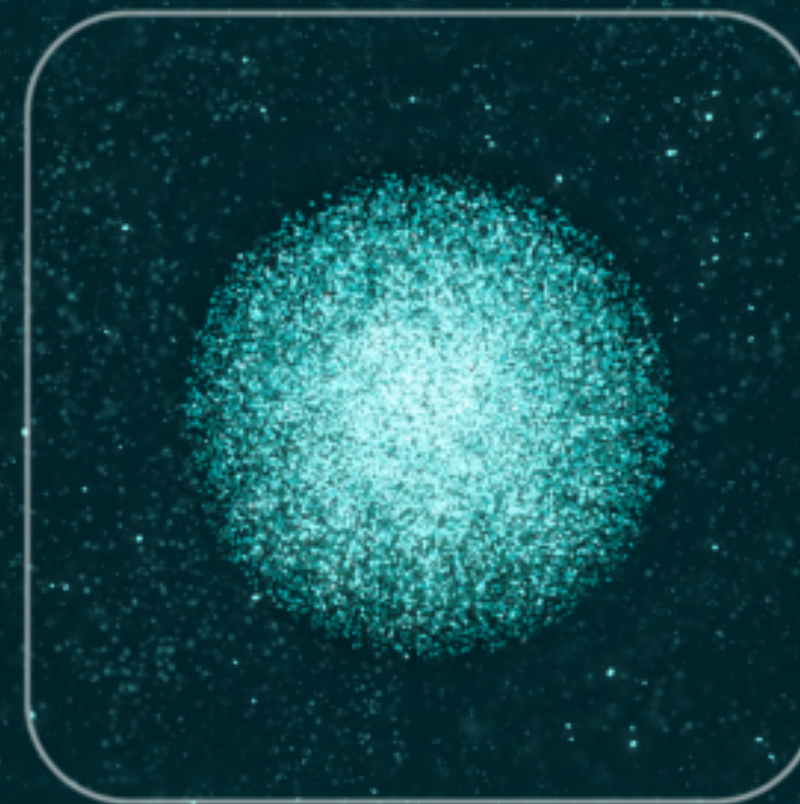
The most fundamental constituents of matter (that we know of...)



Quarks



Leptons



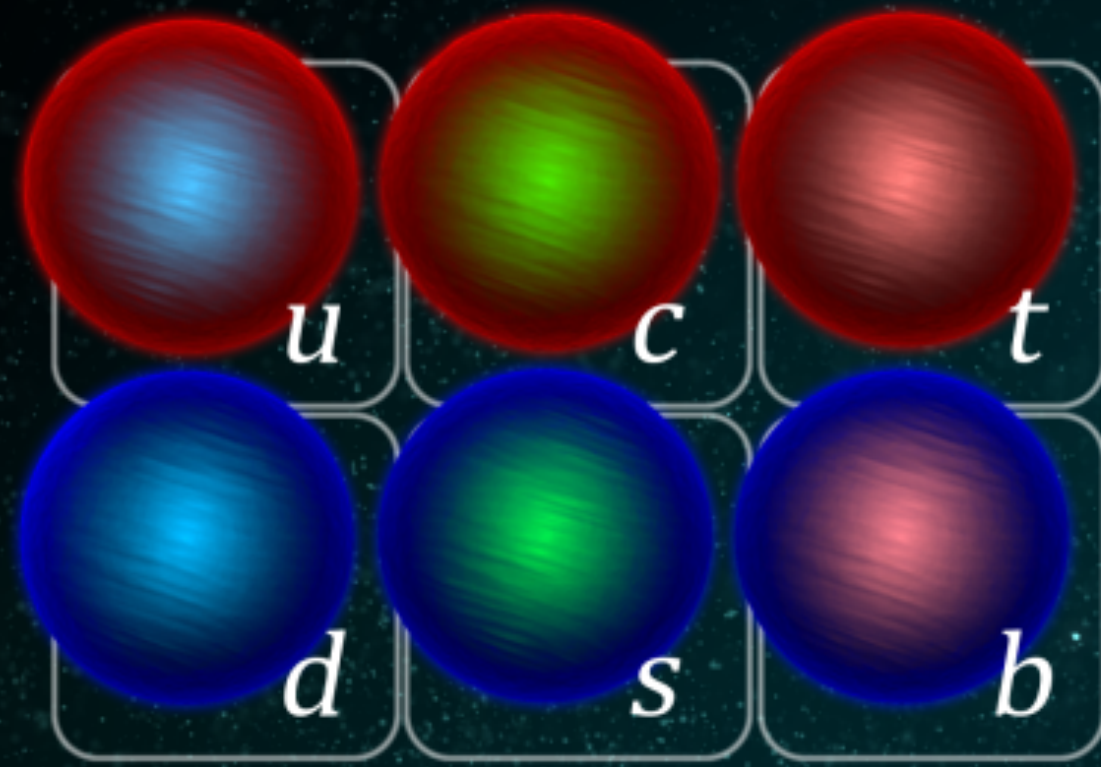
Higgs boson



Forces

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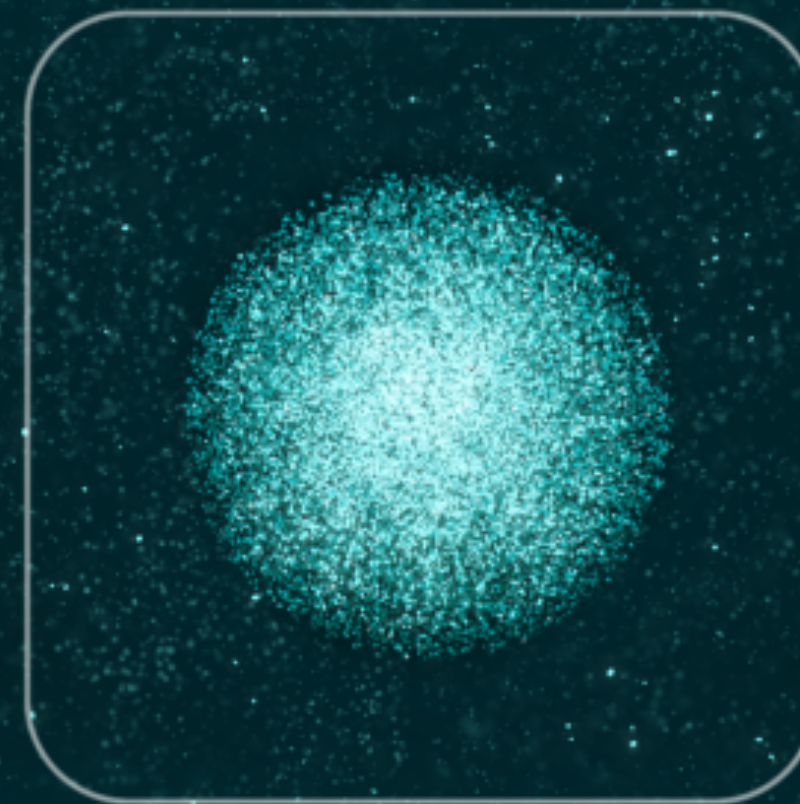
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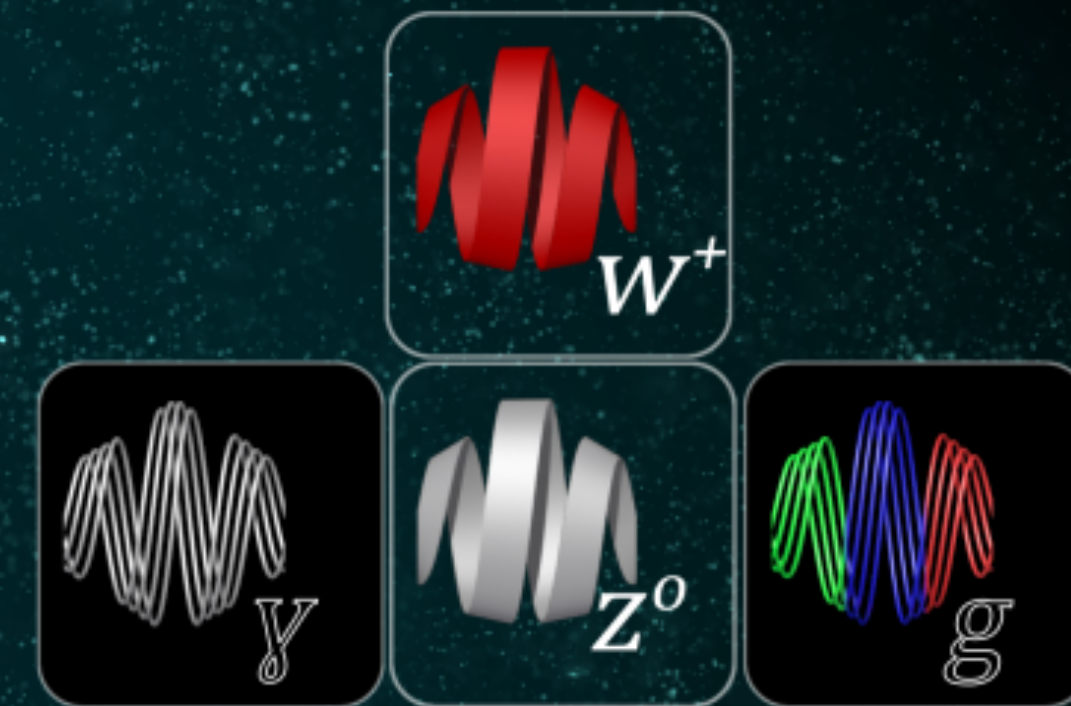
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Leptons



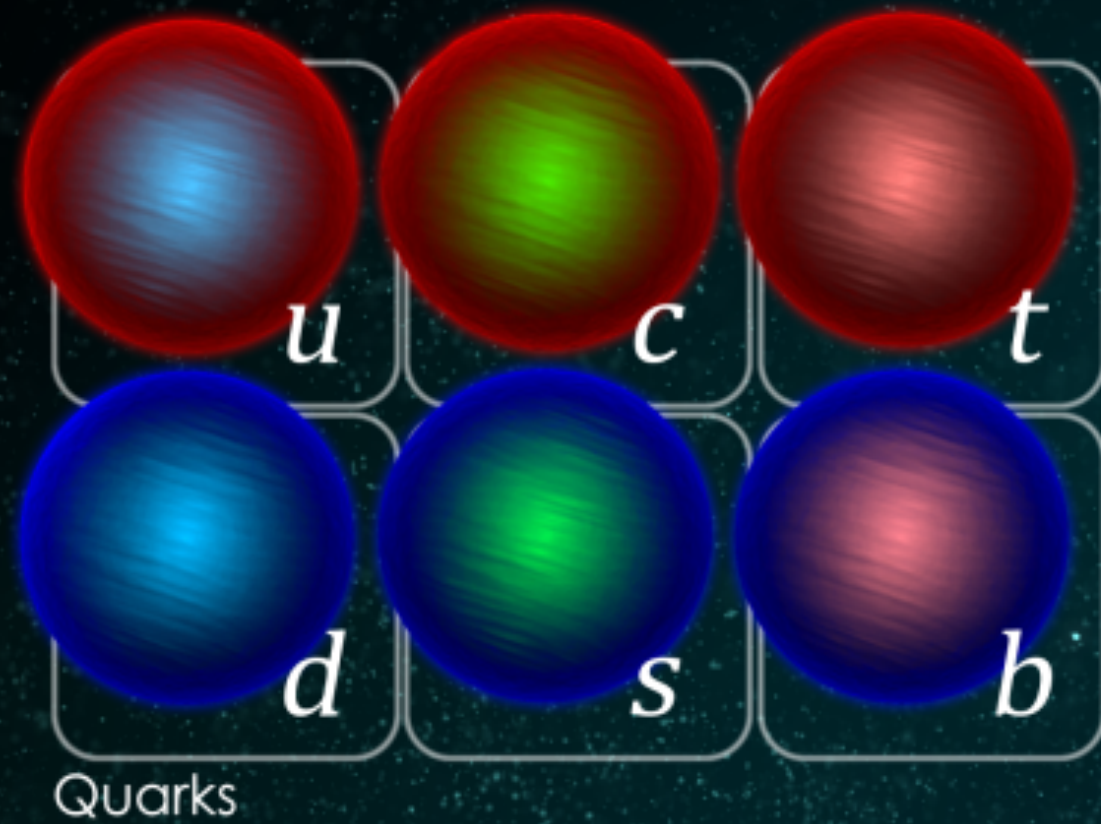
Higgs boson



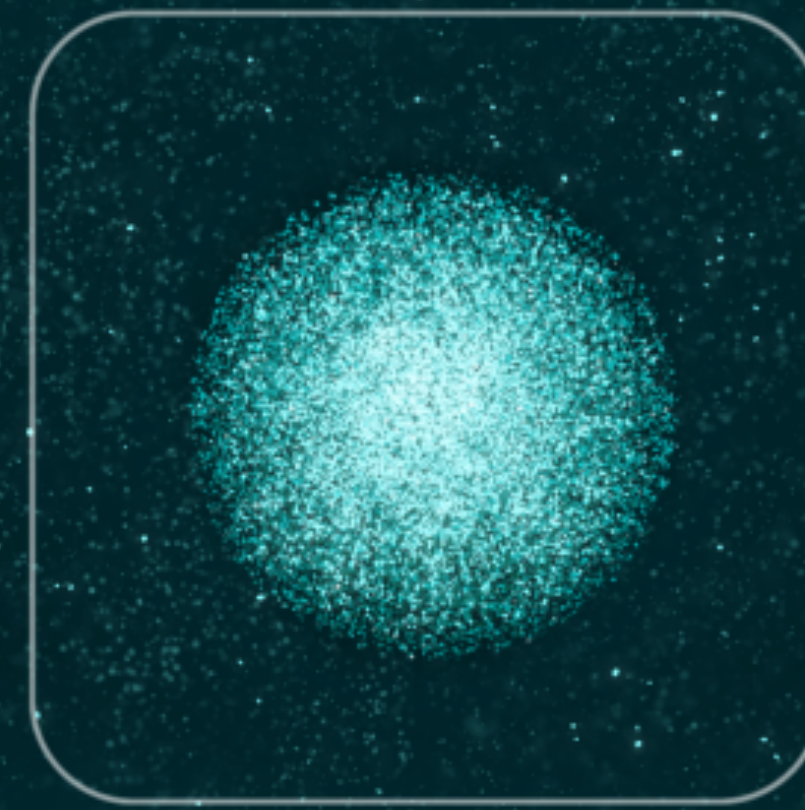
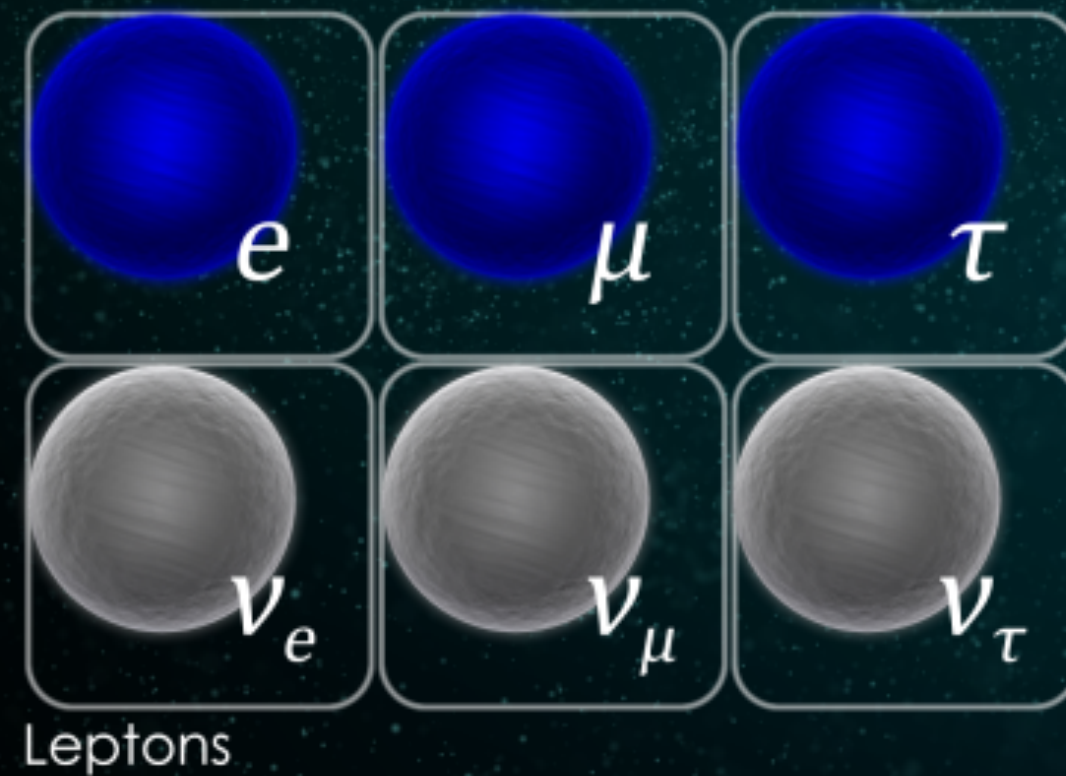
Forces

The most fundamental constituents of matter (that we know of...)

Protons
are made
up of u
and d



That's the
electron
and it's
cousins

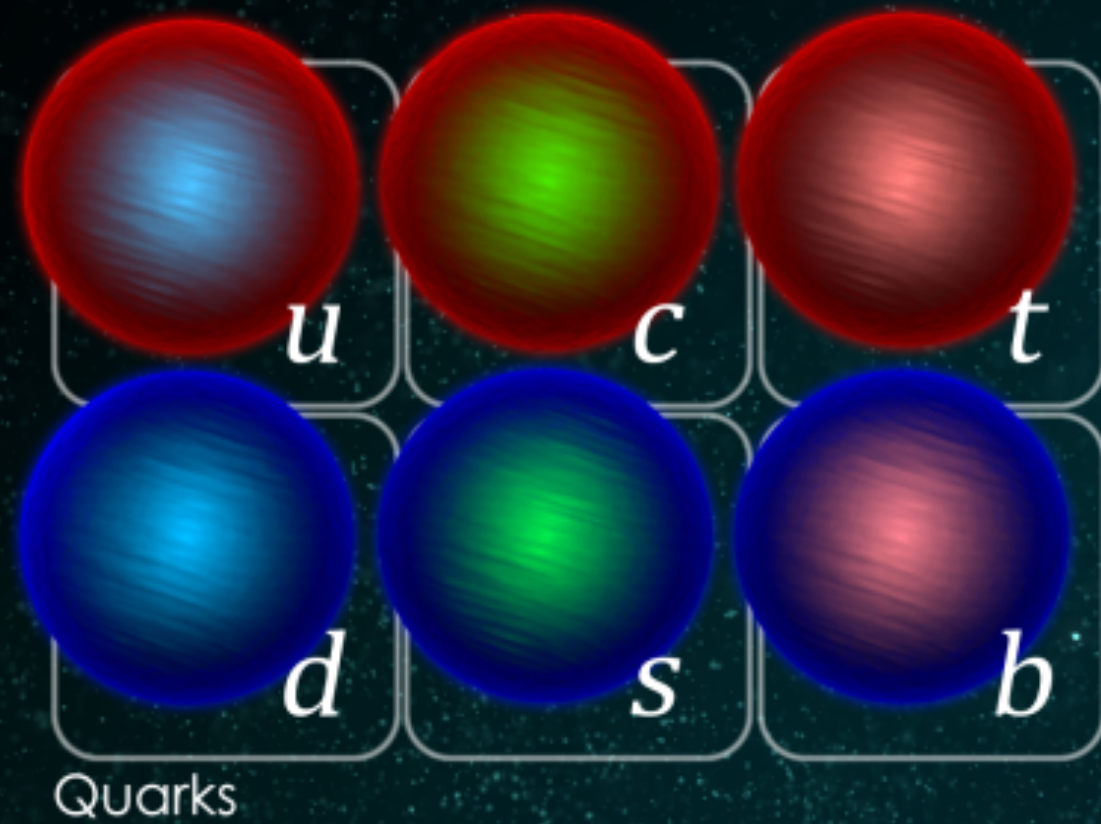


Higgs boson

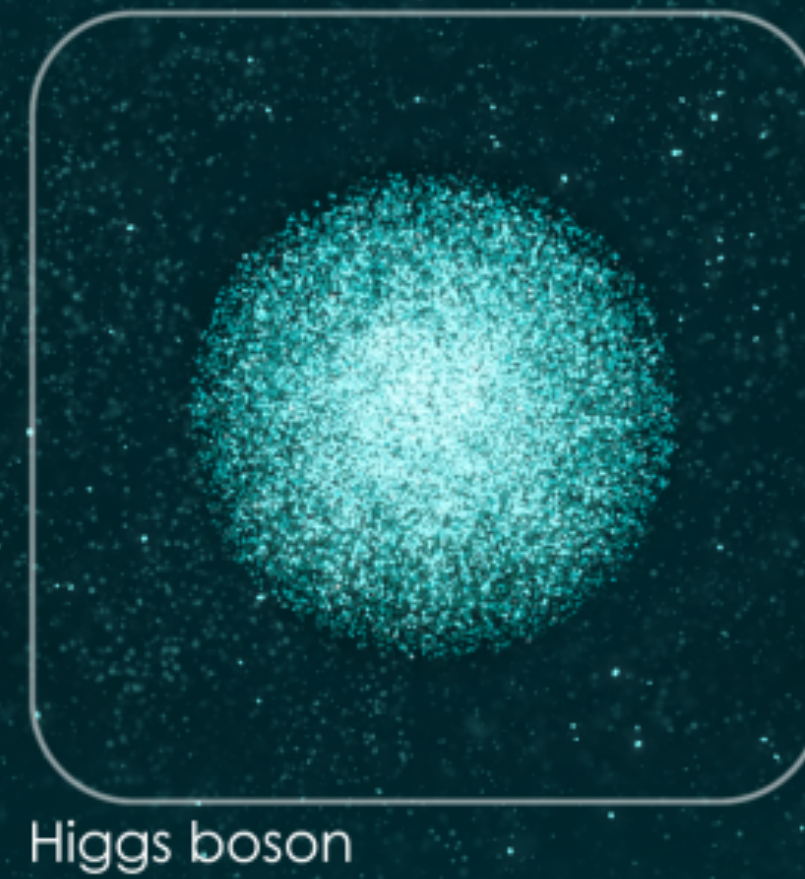
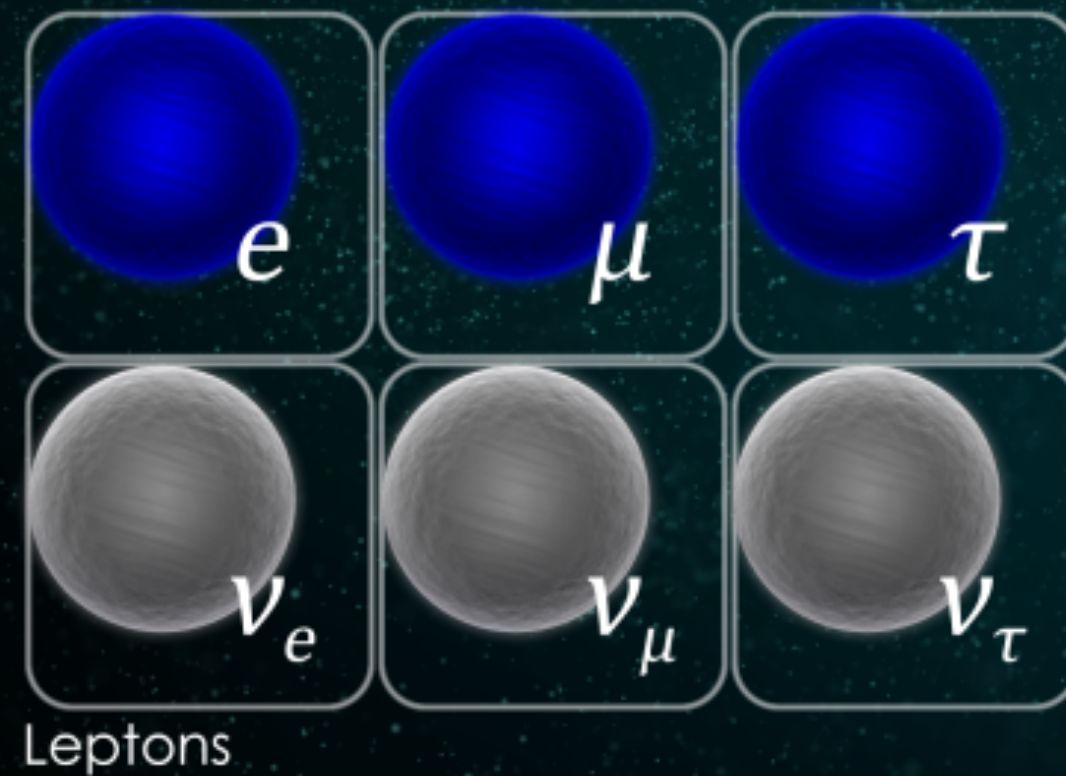


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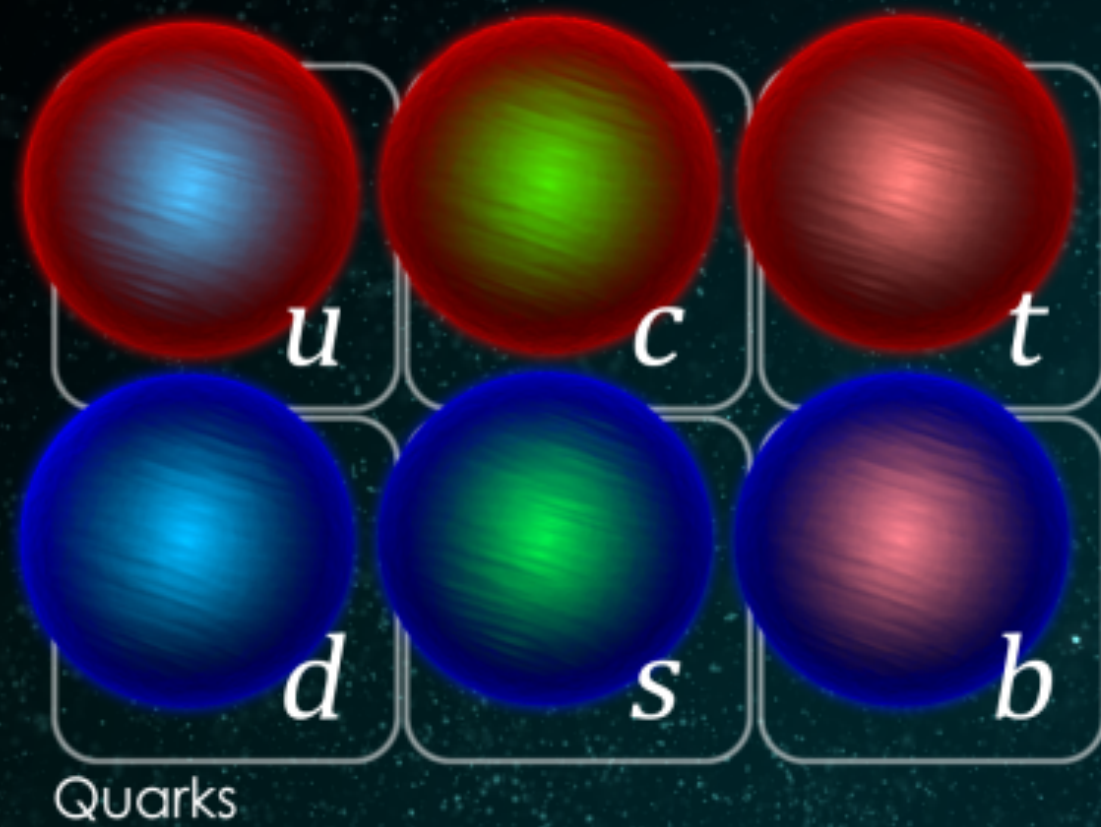


Force
carrier
particles

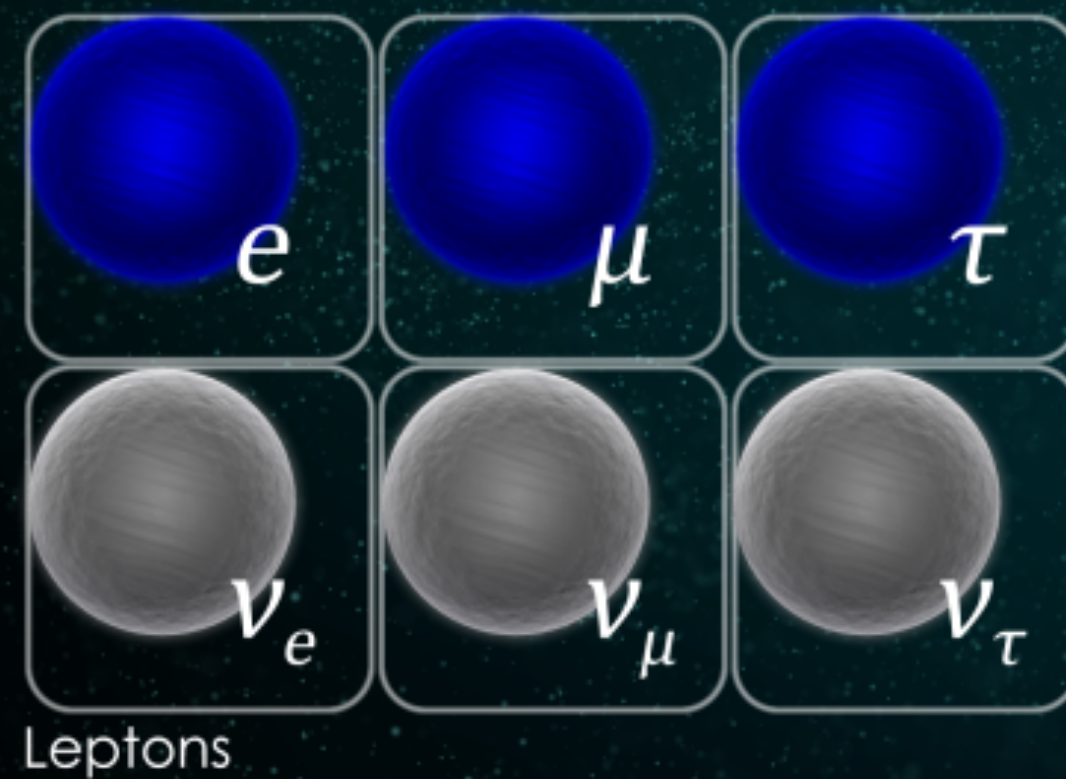


The most fundamental constituents of matter (that we know of...)

Protons are made up of u and d



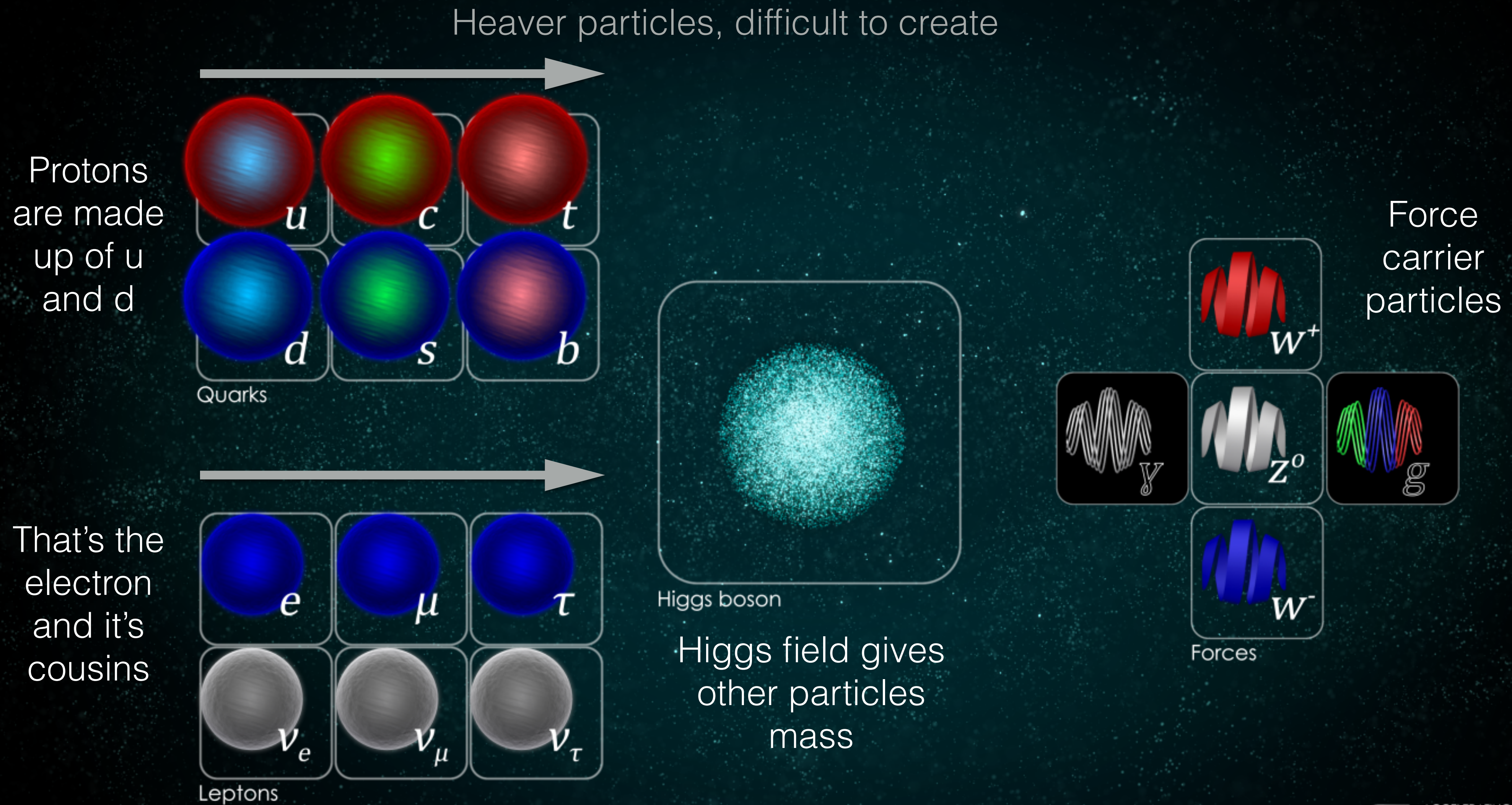
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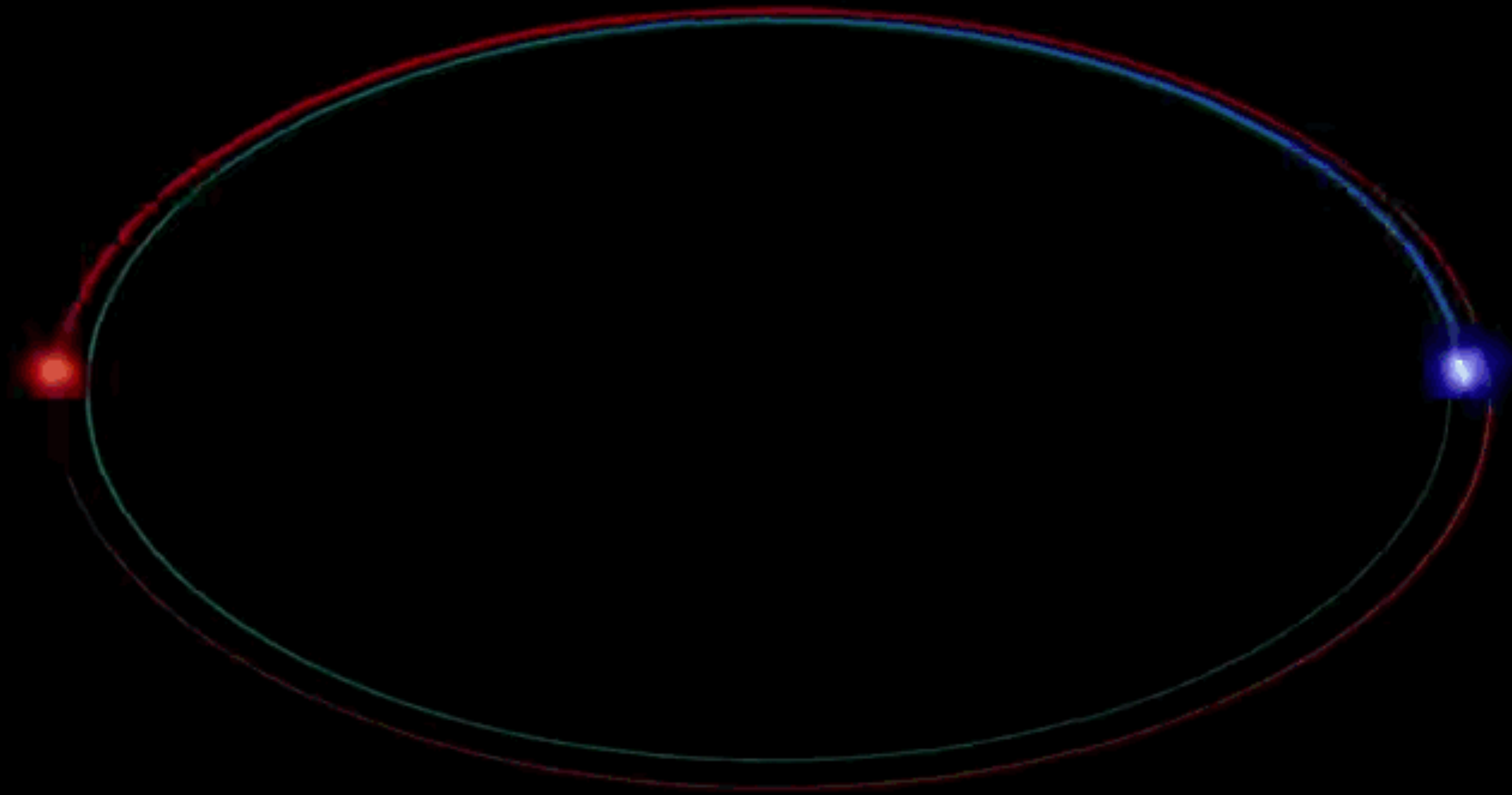
Higgs field gives other particles mass



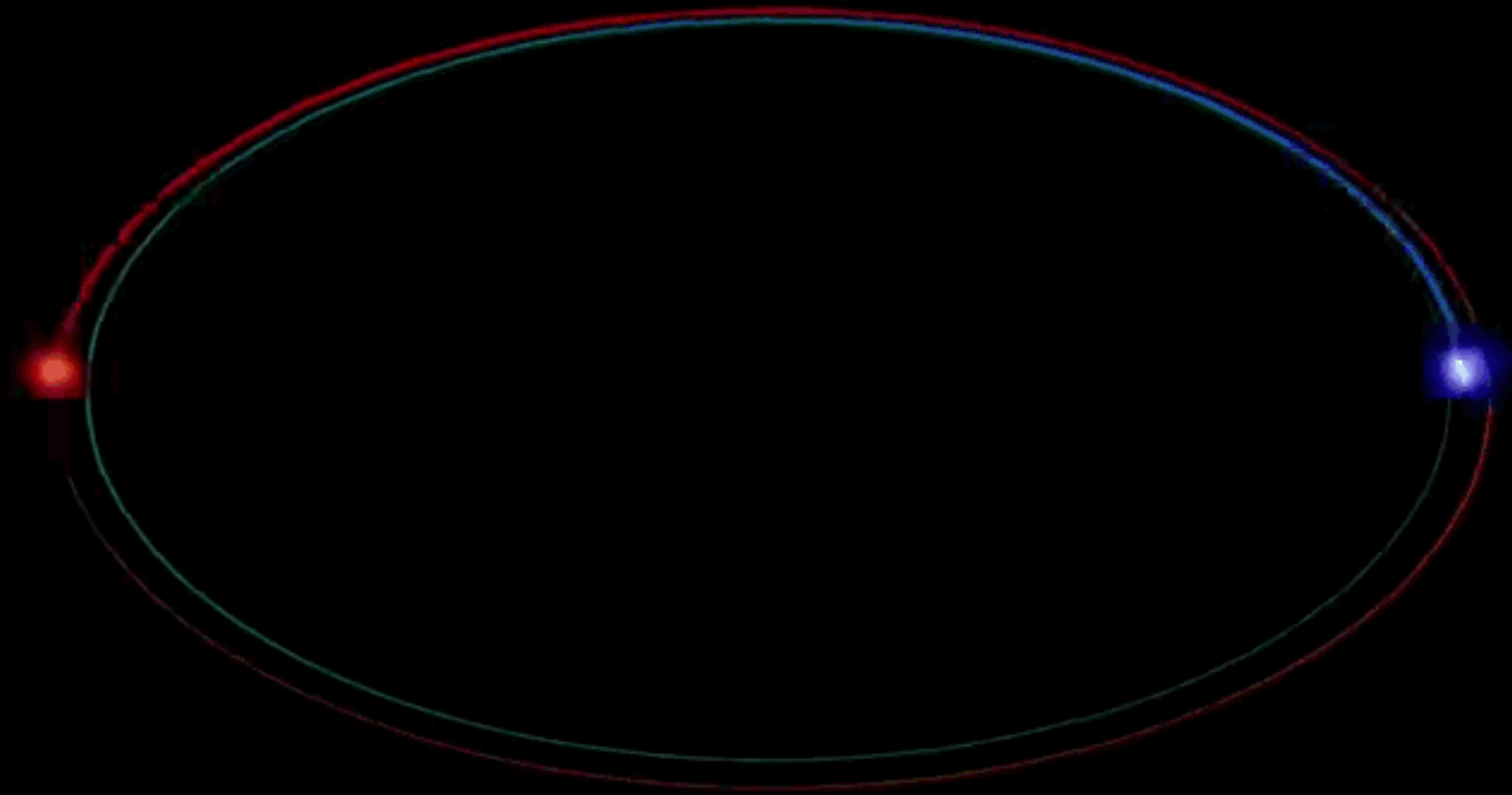
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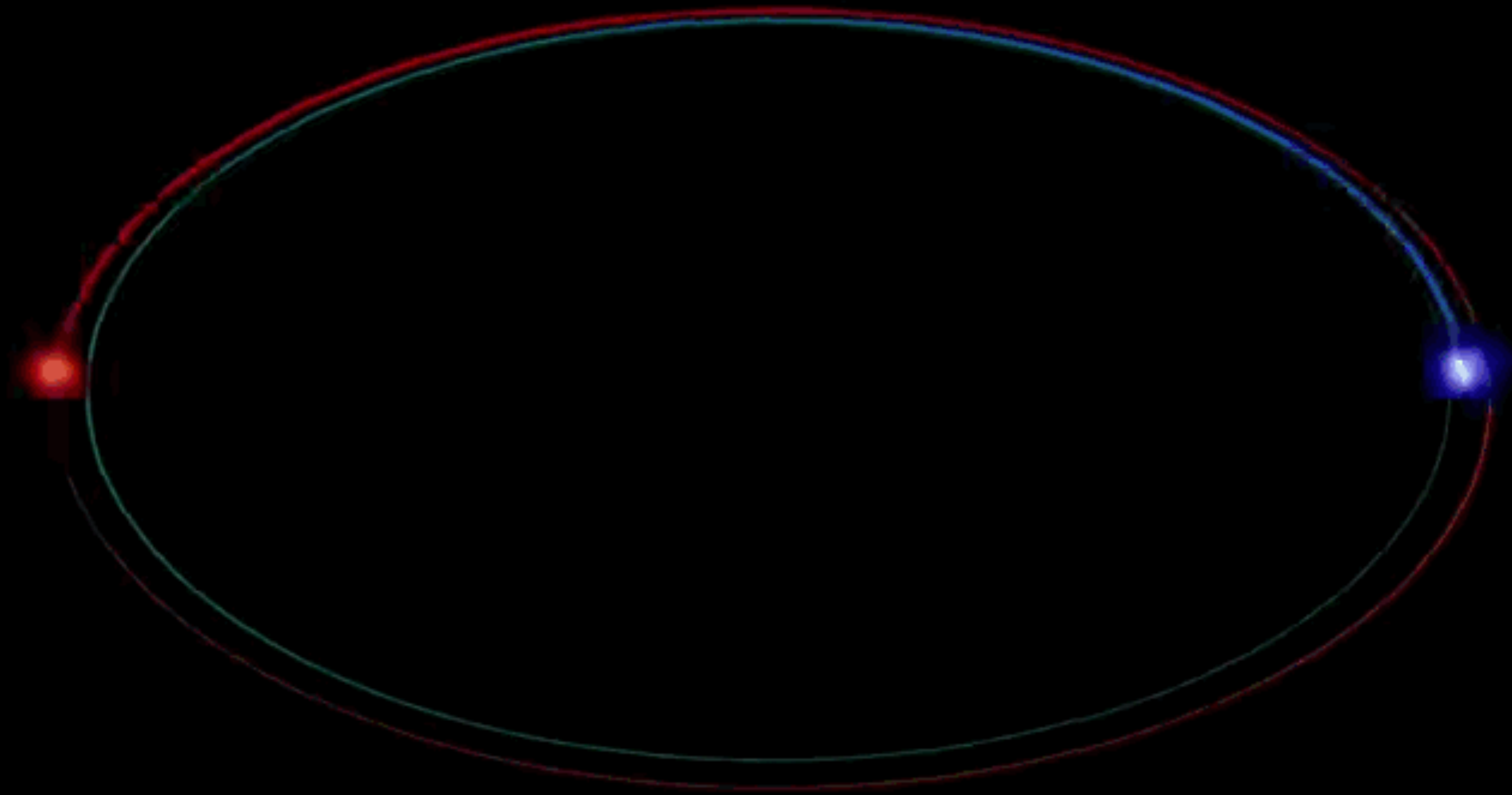
Smash particles at Large Hadron Collider



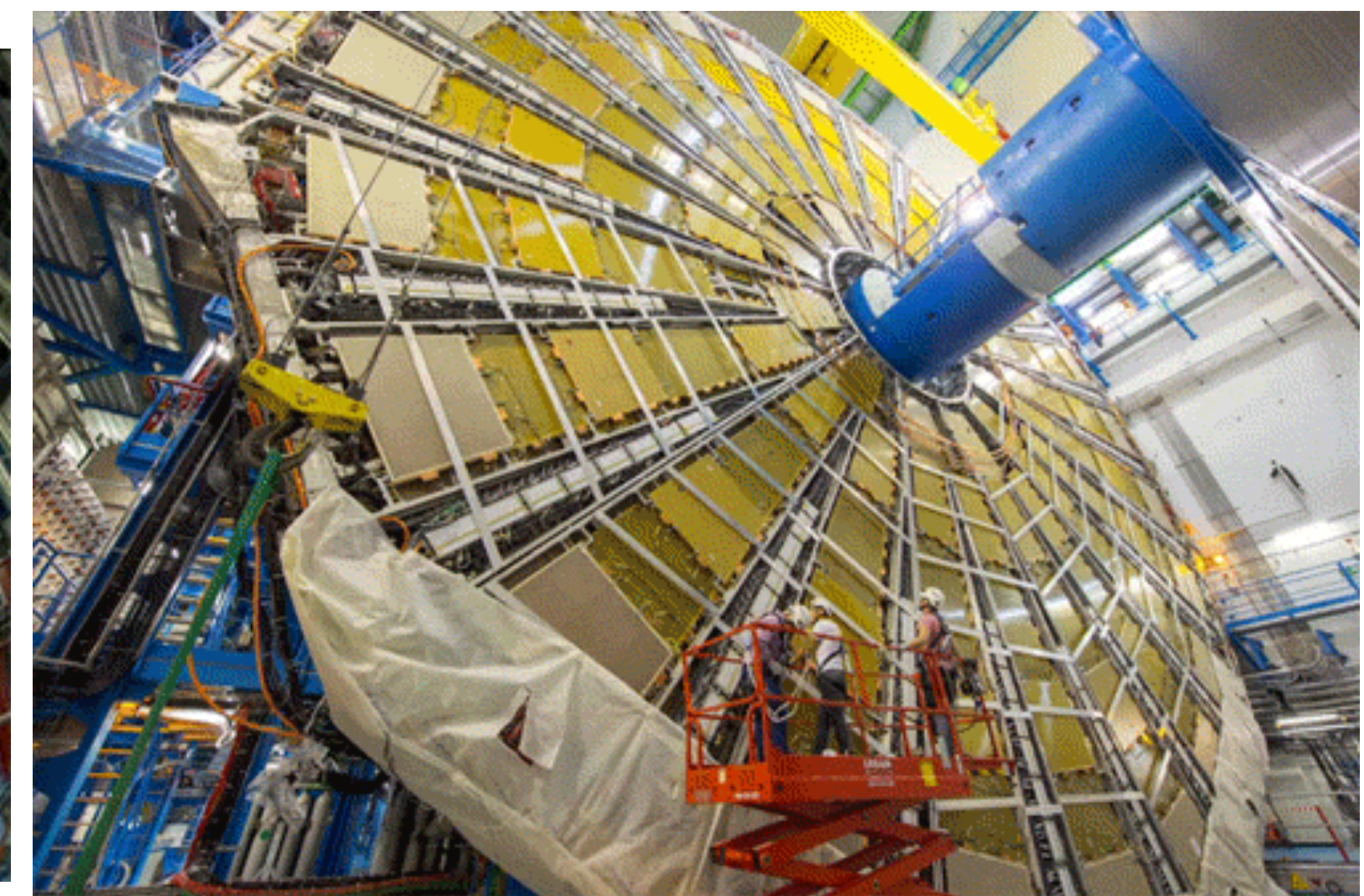
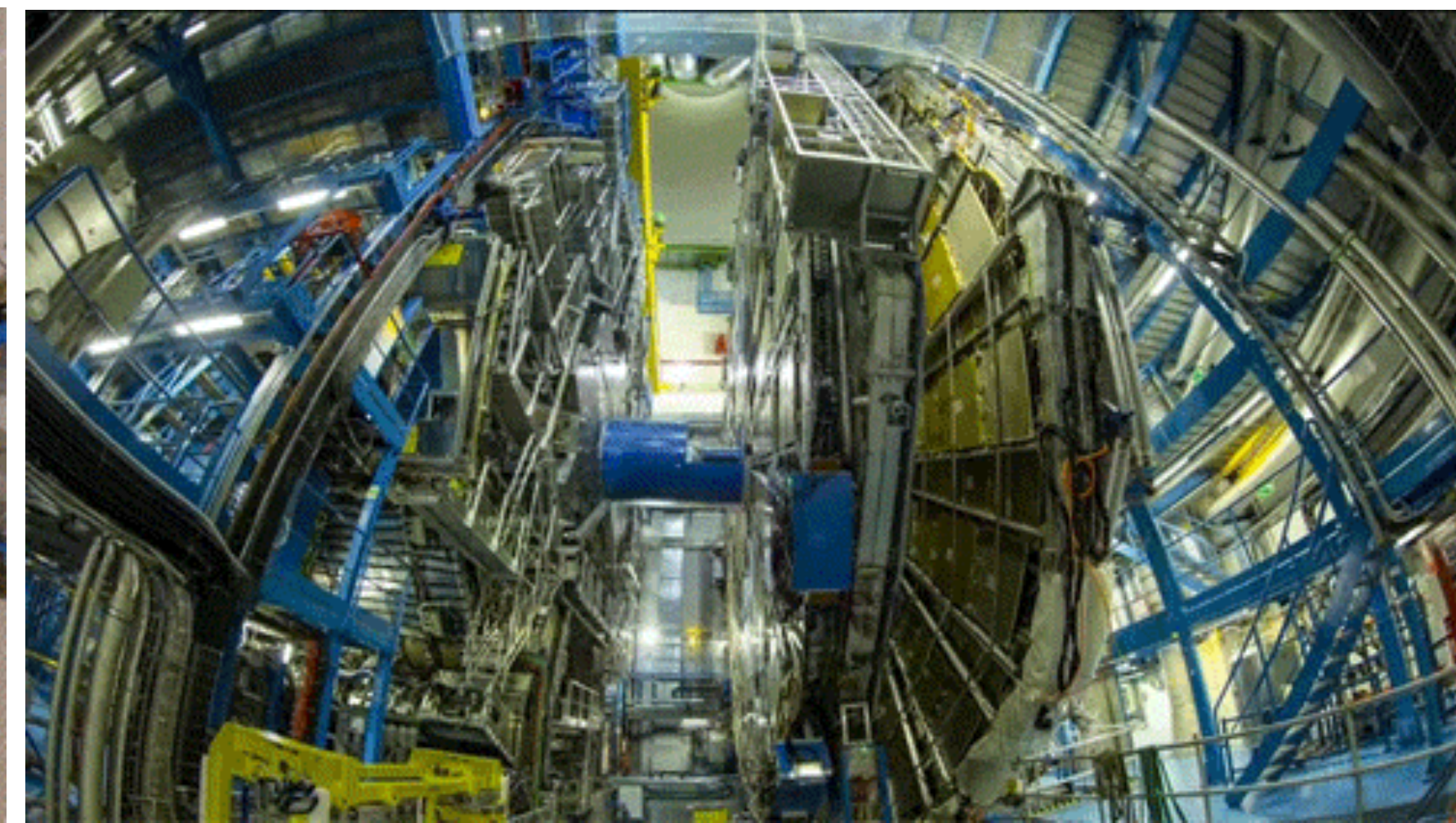
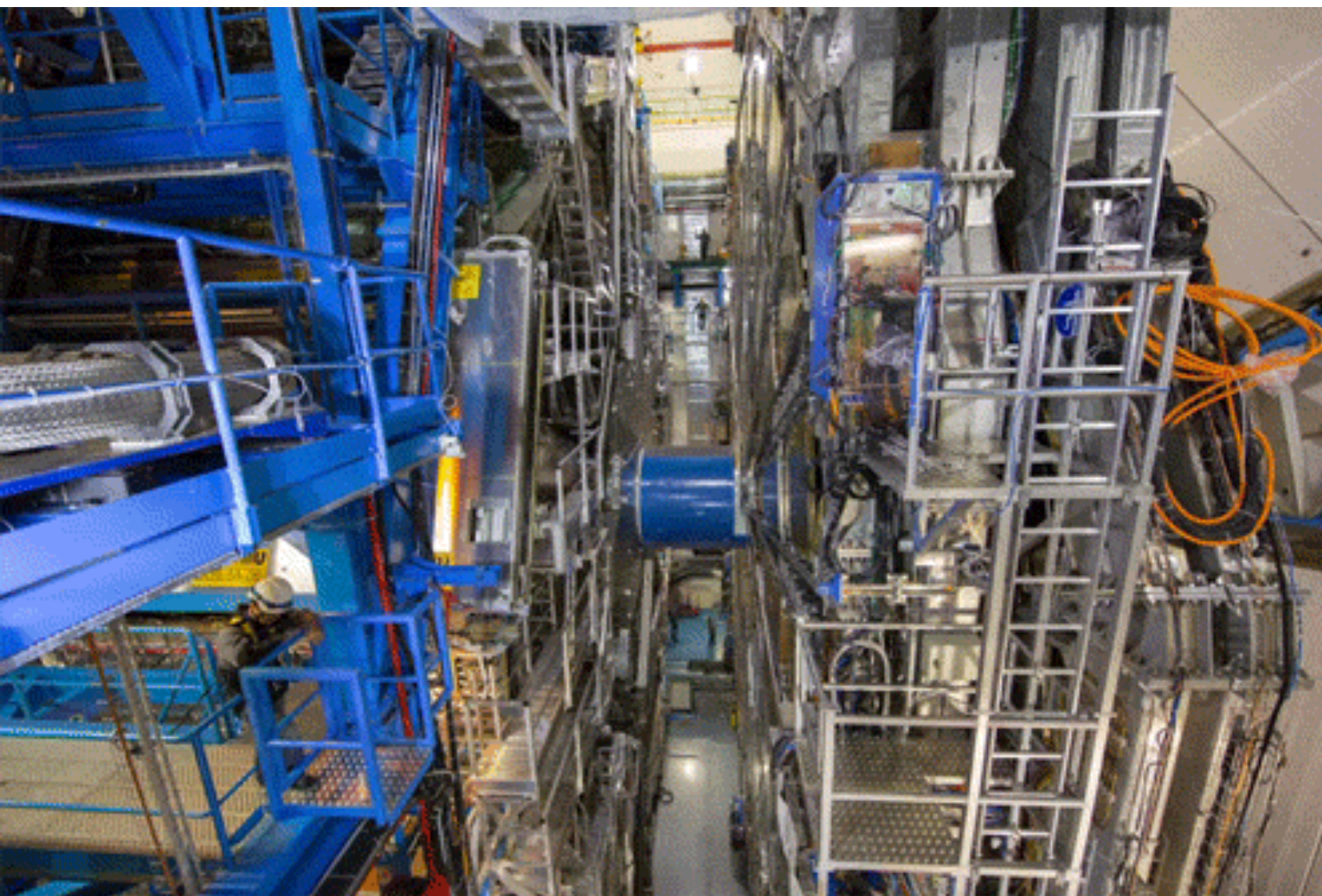
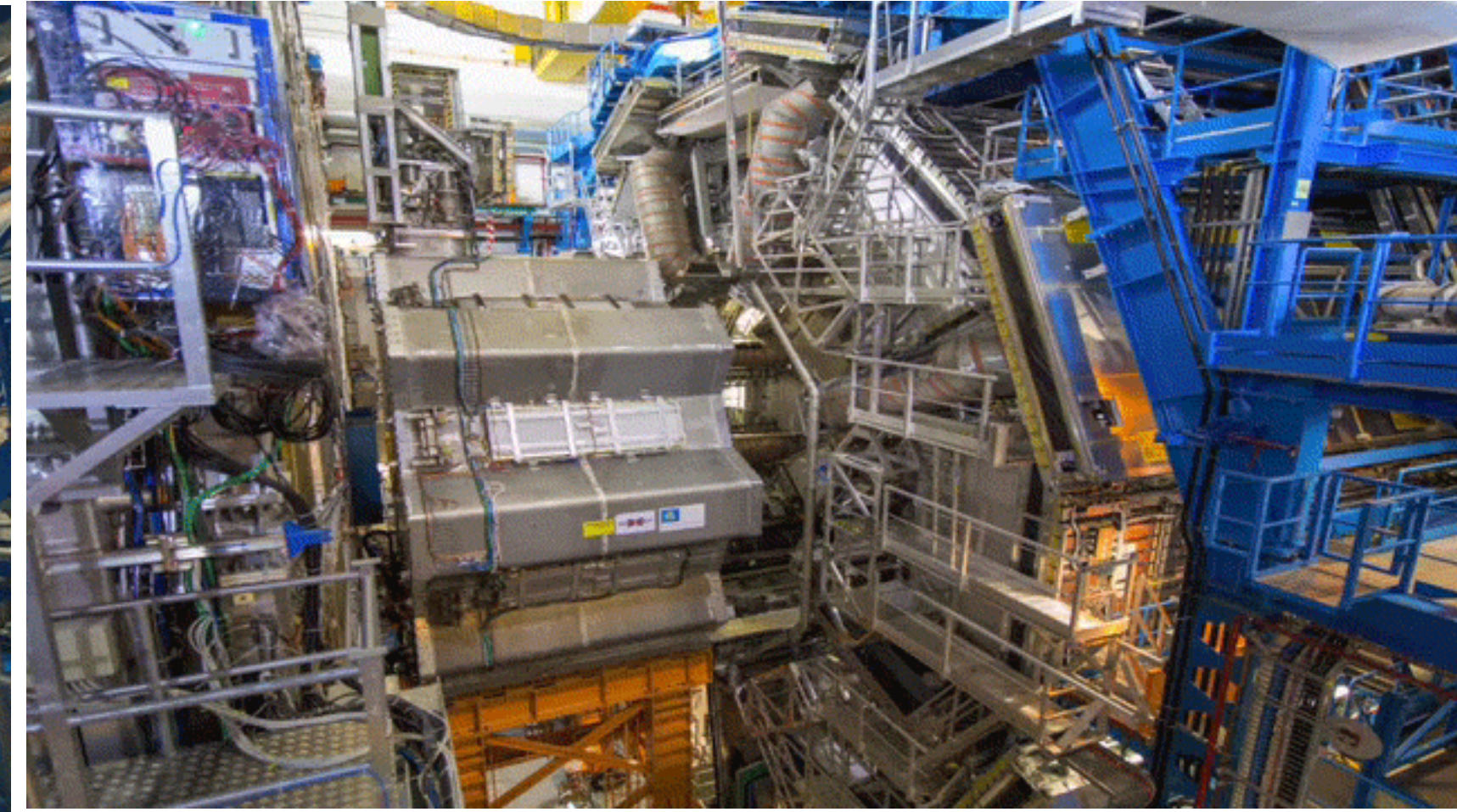
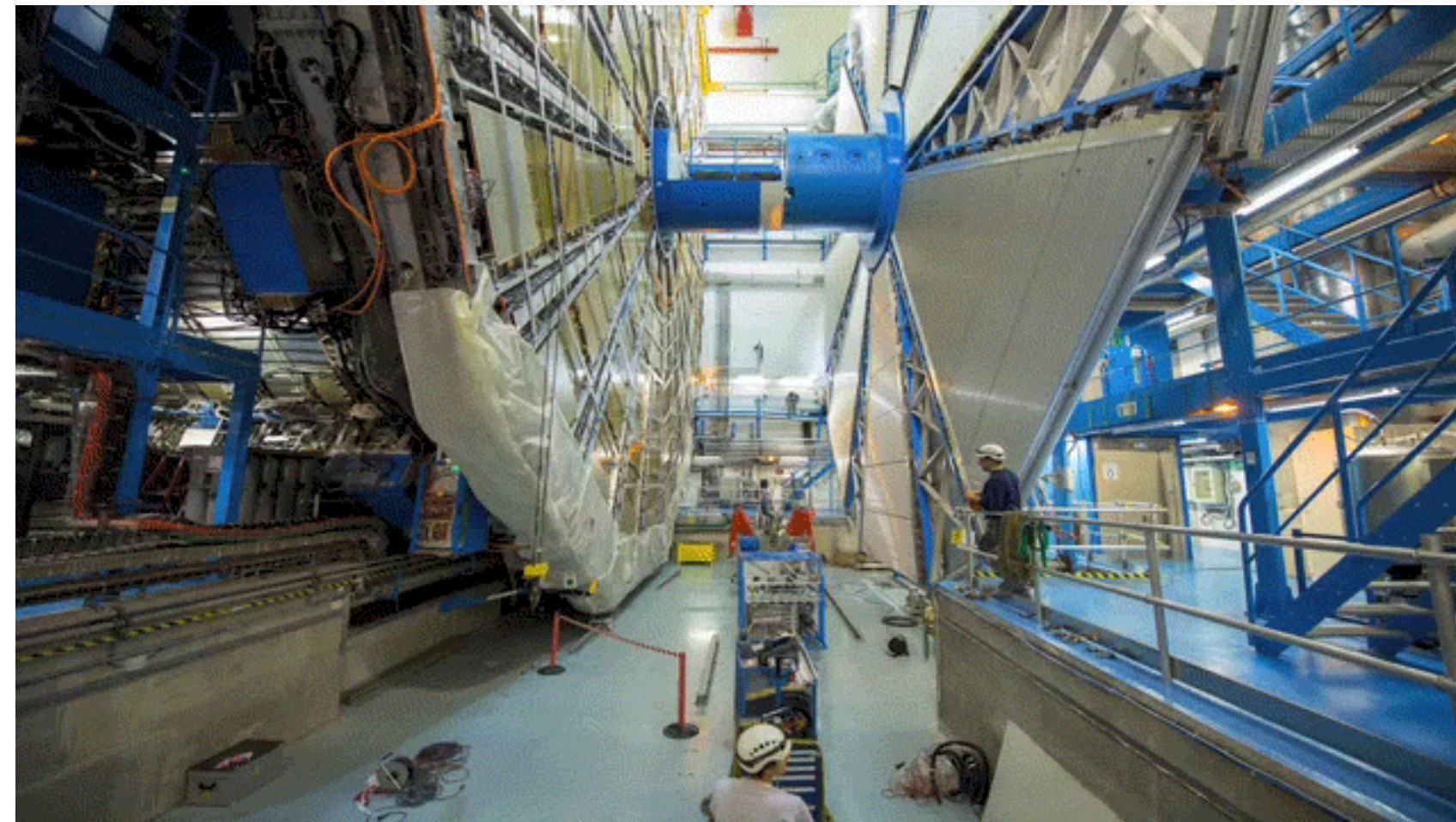
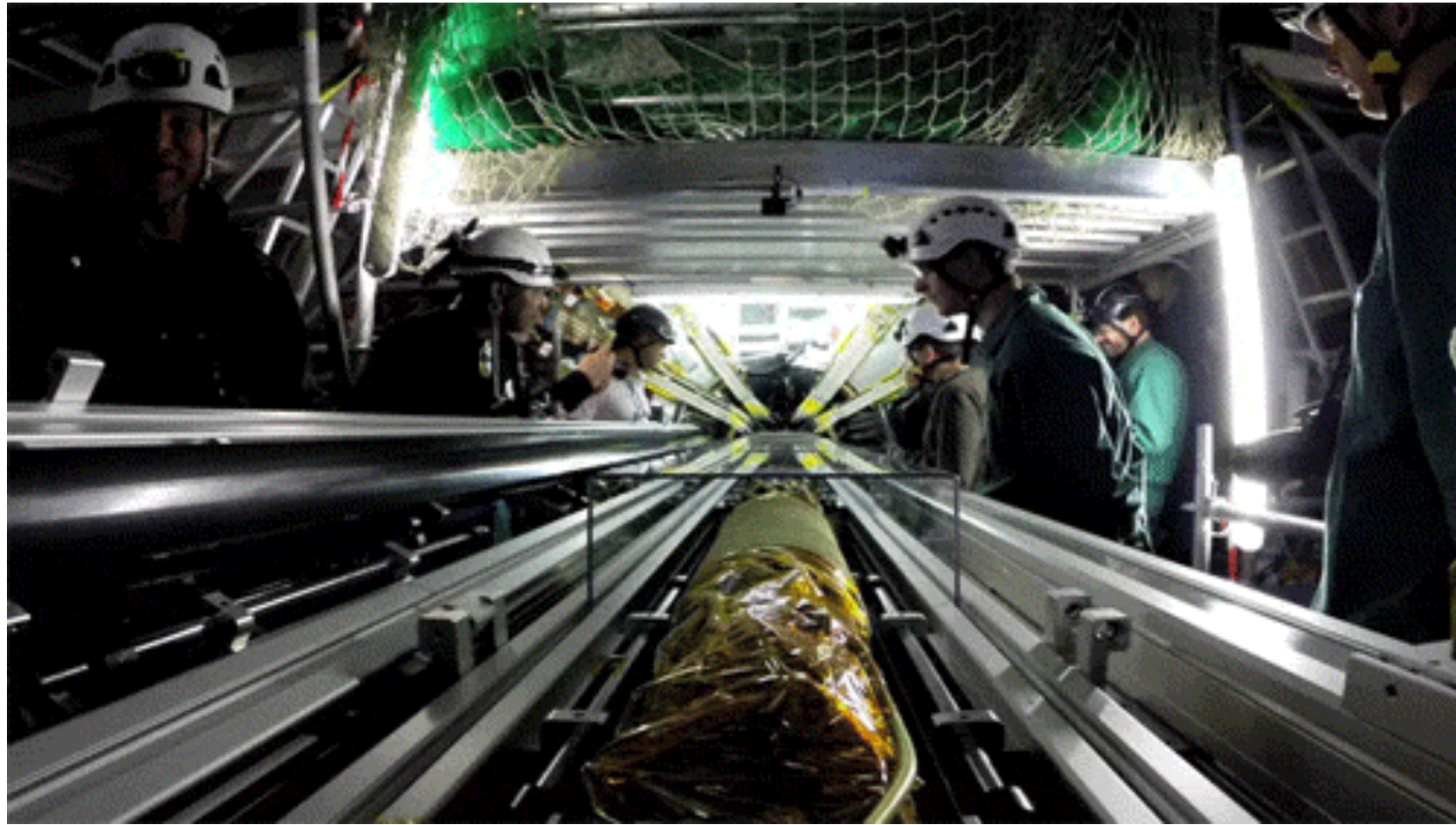
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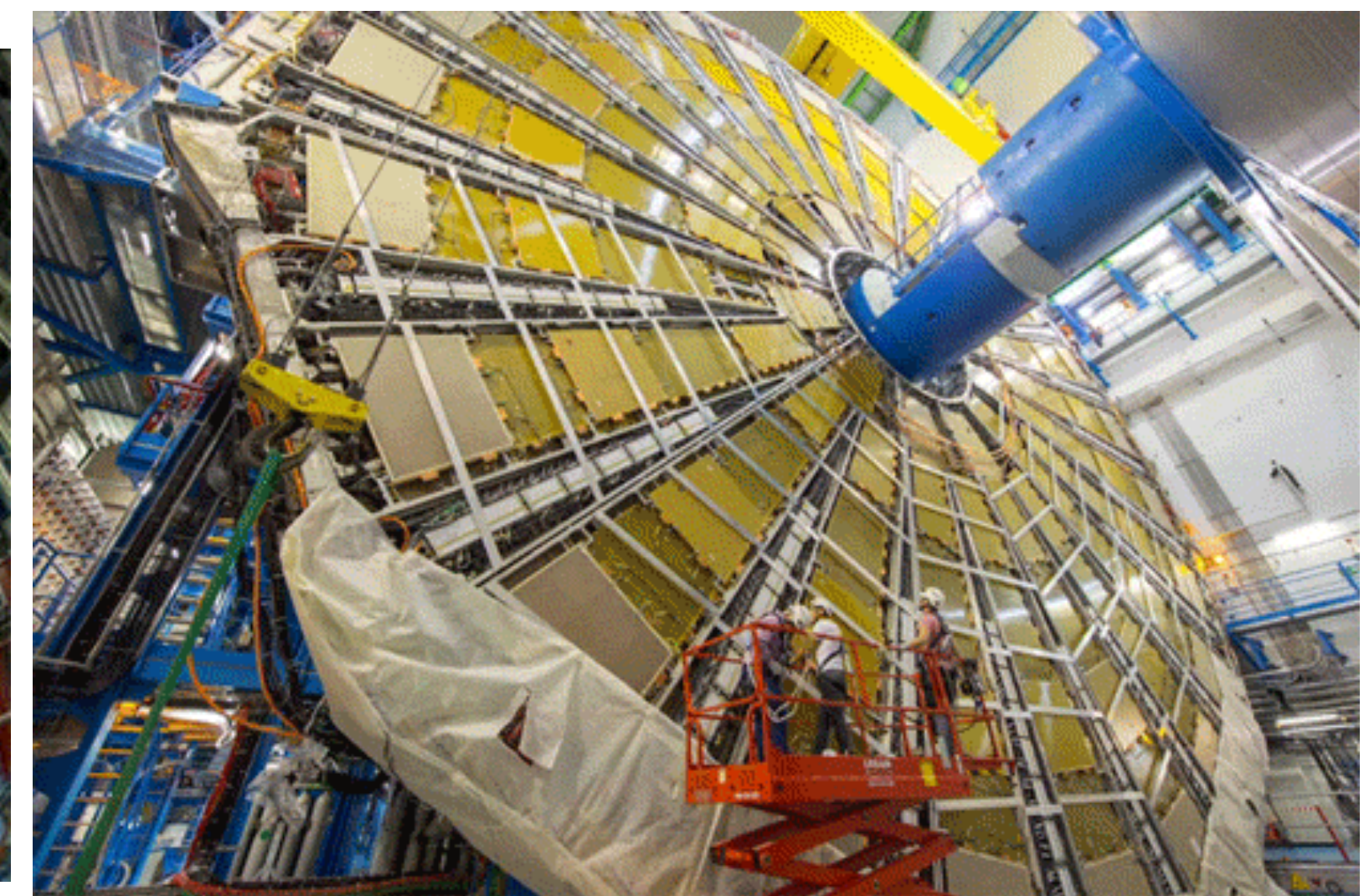
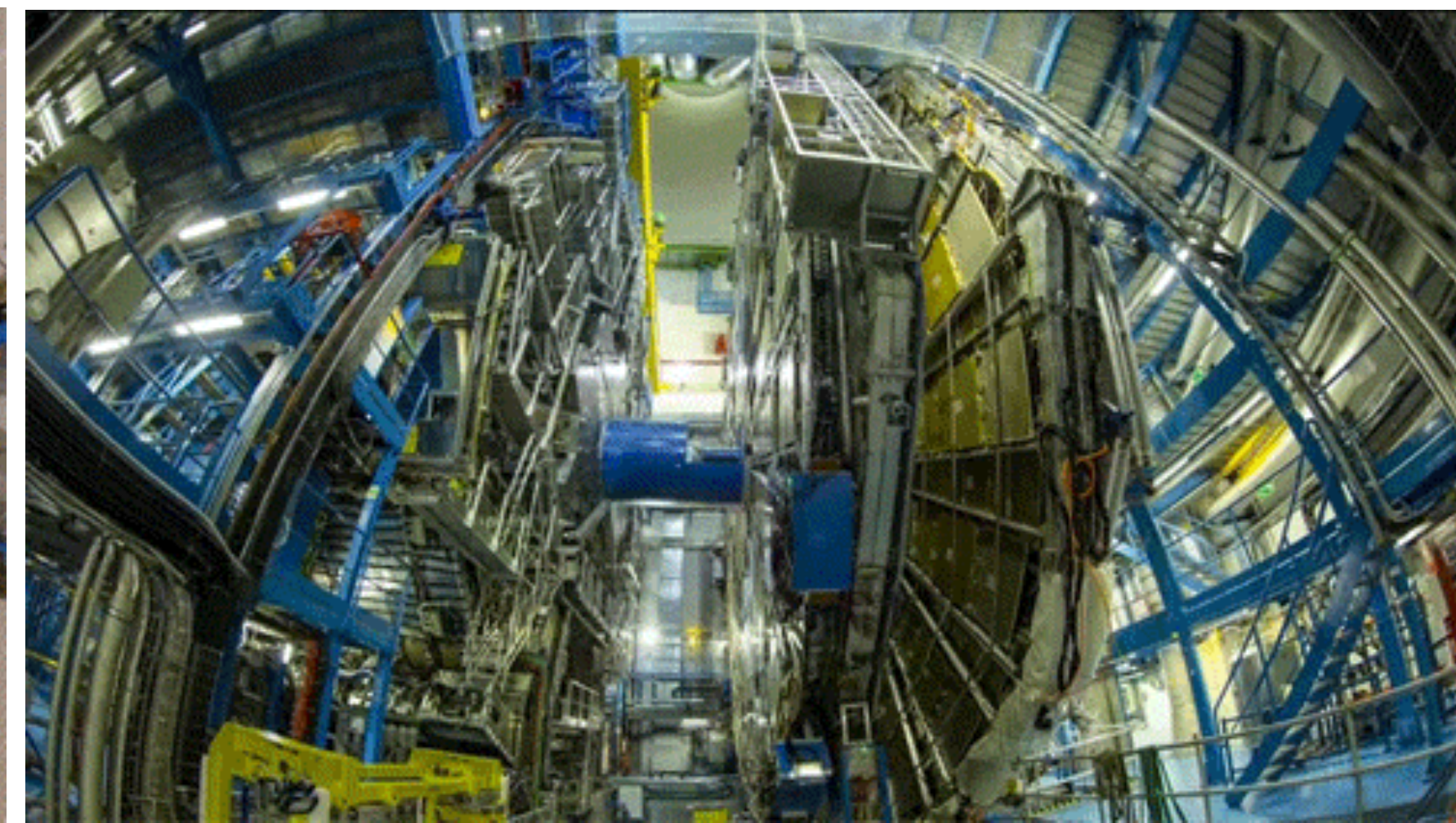
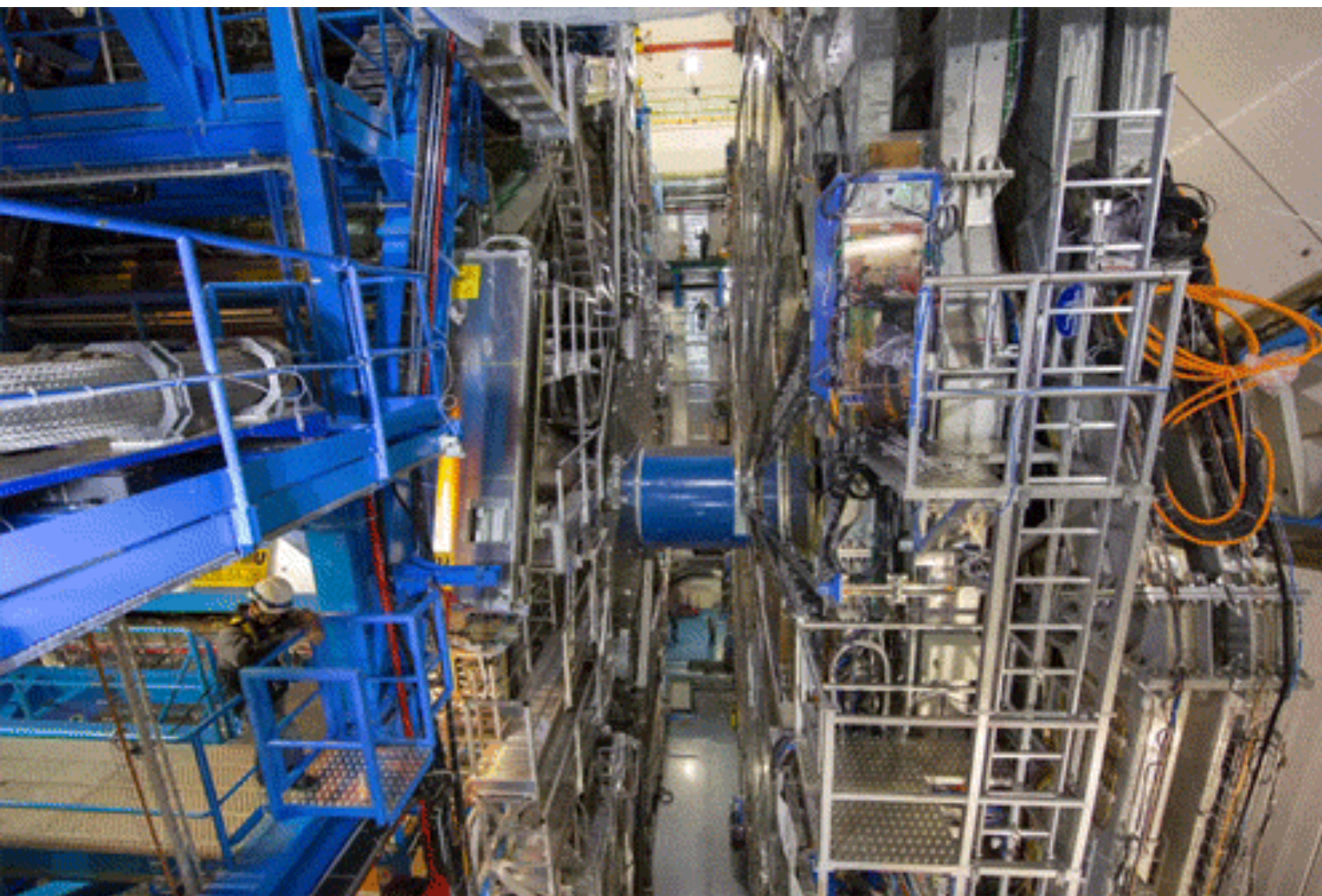
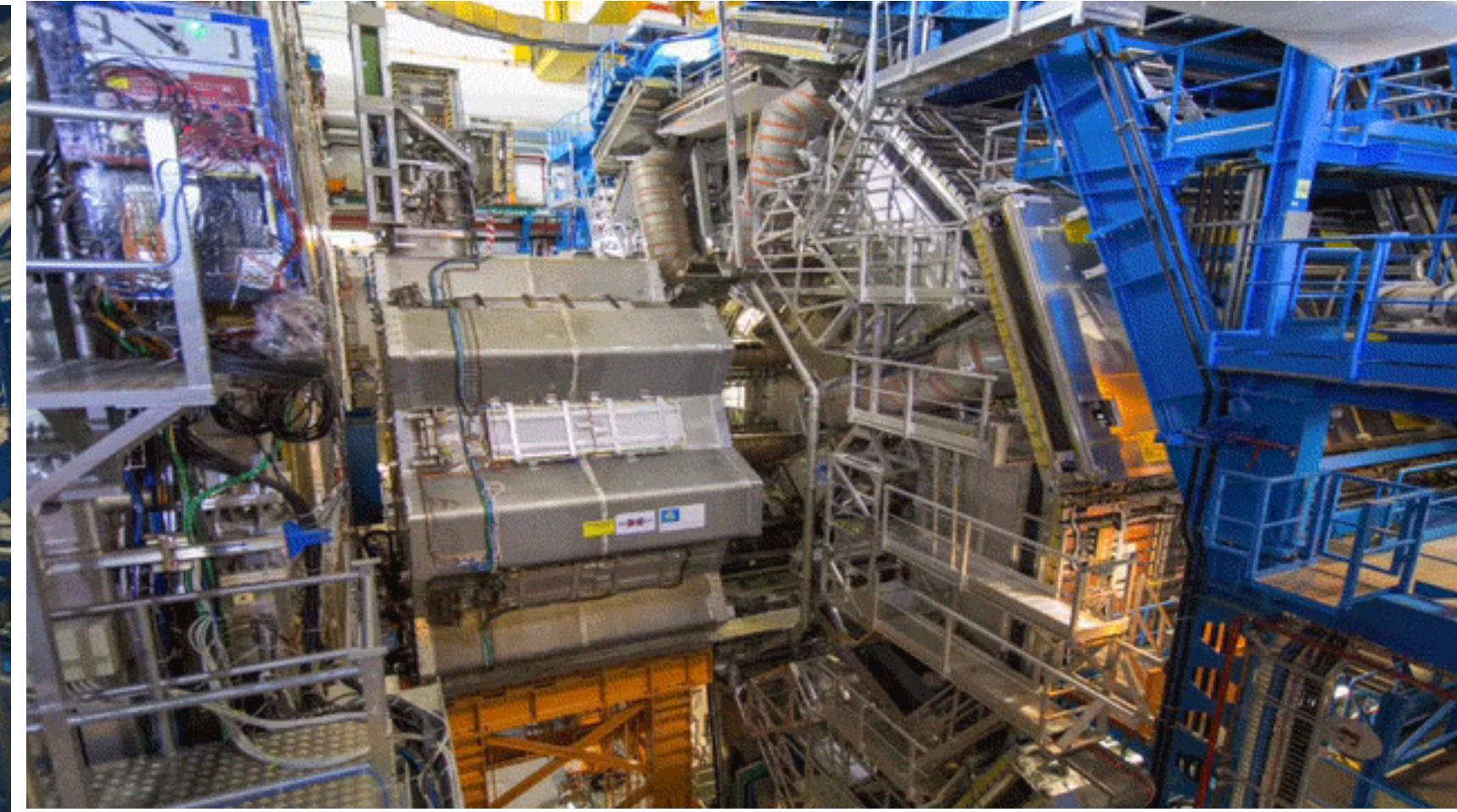
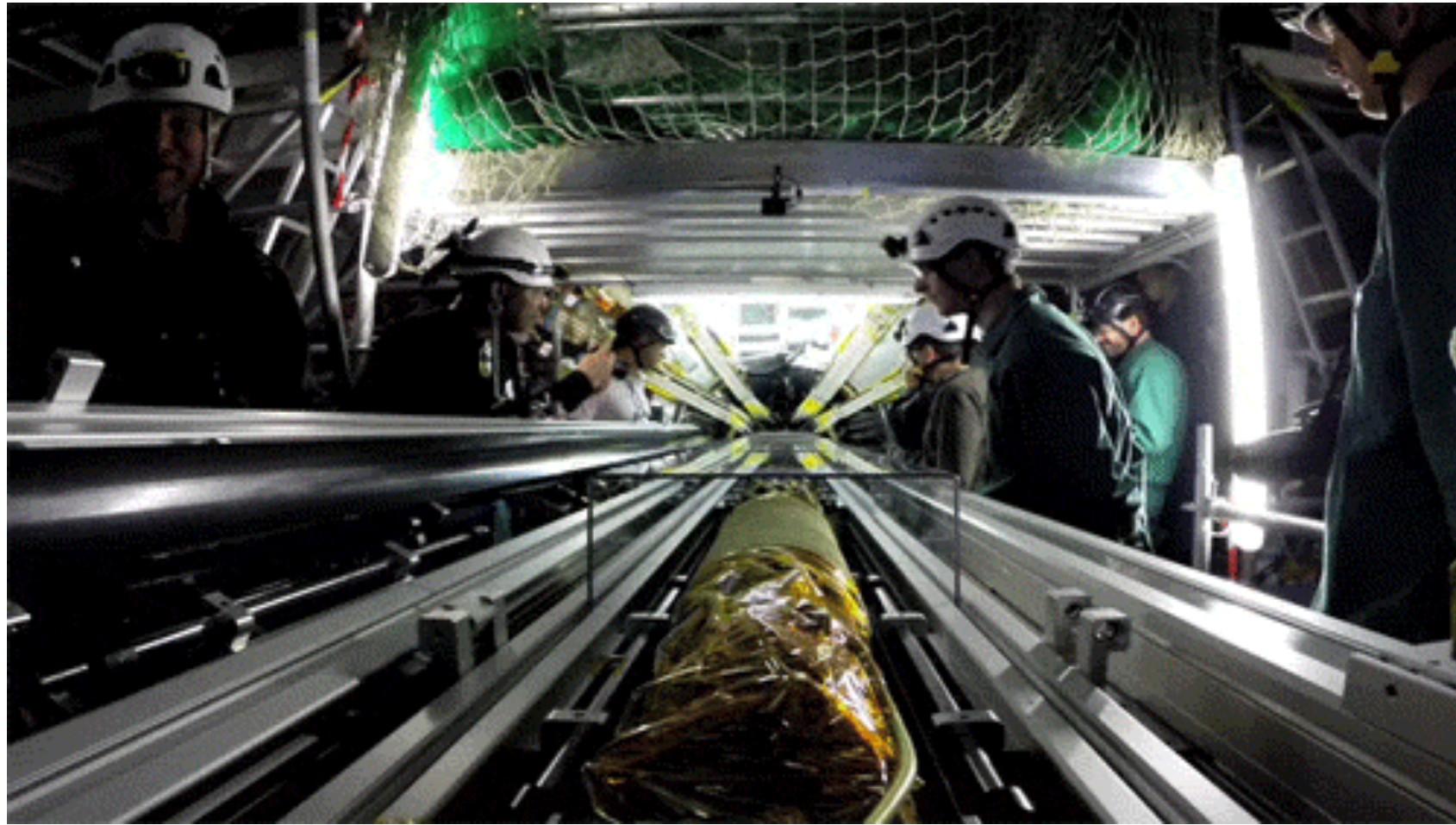
Smash particles at Large Hadron Collider



The detectors

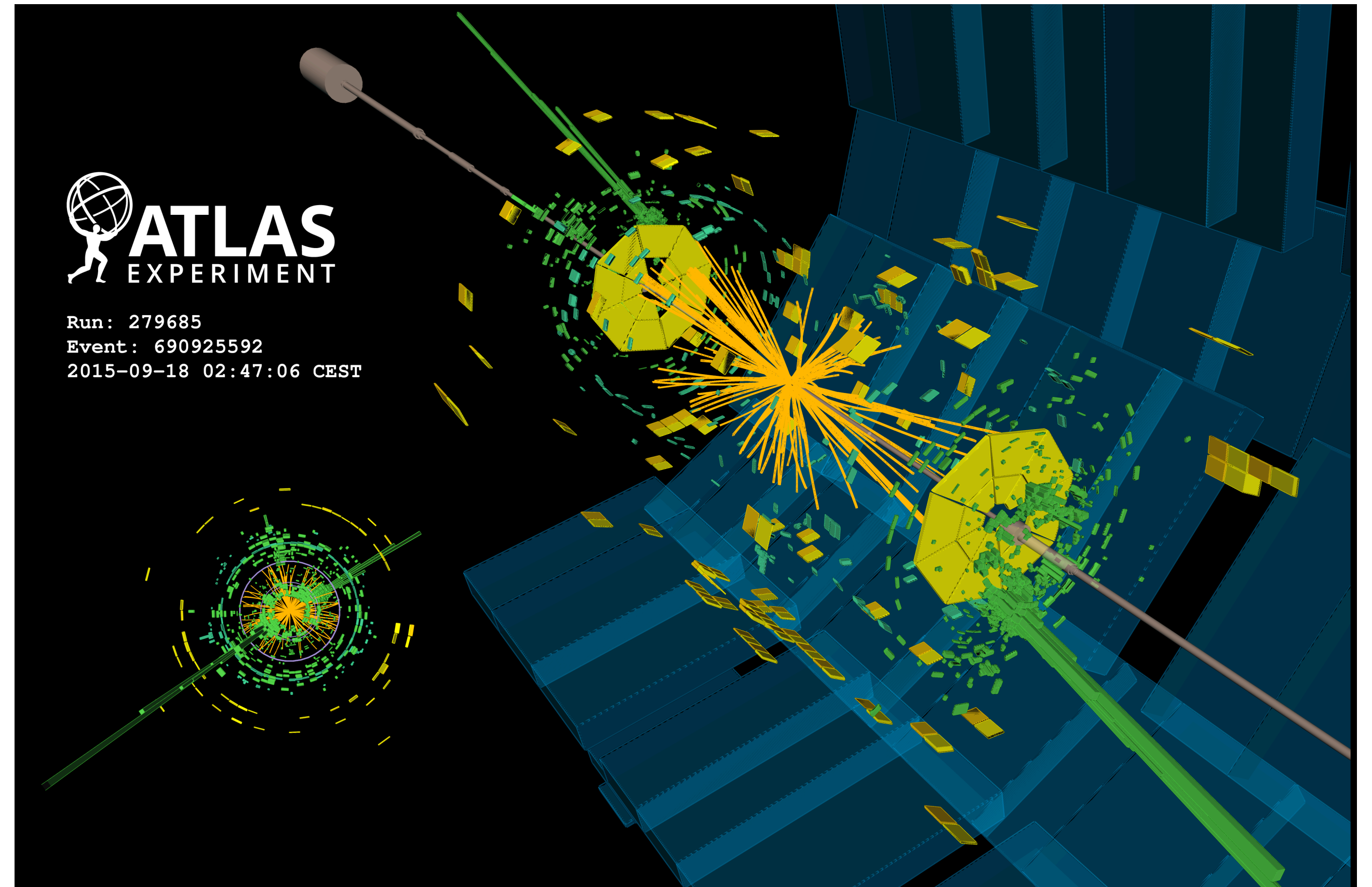


The detectors



Summarise in low dimensions

- Detector has $O(100 \text{ million})$ sensors
- Can't build 100M dimensional histogram
- ▶ Reconstruction pipeline, event selection
- ▶ Design sensitive one-dimensional observable



Summarise in low dimensions

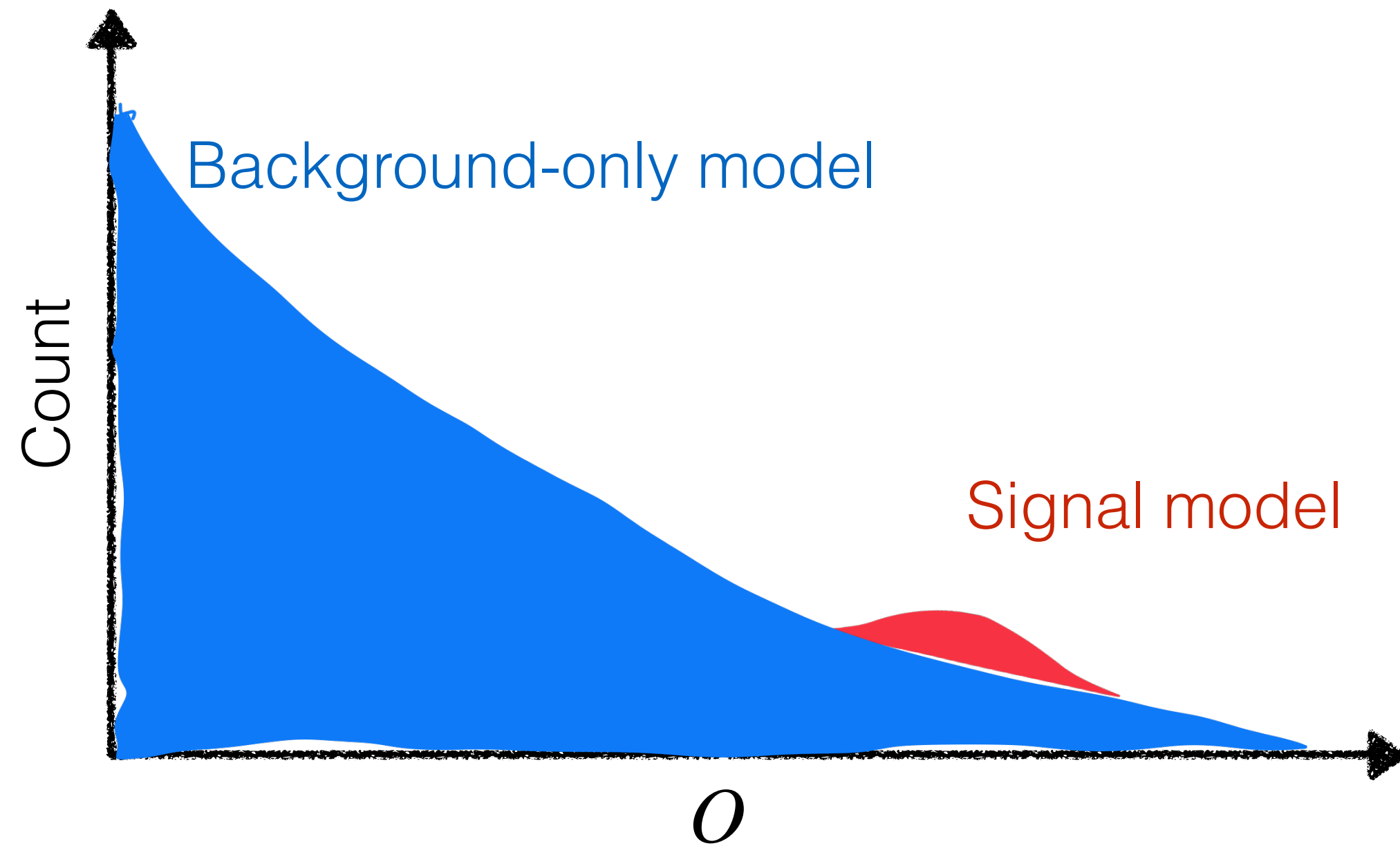
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1 number

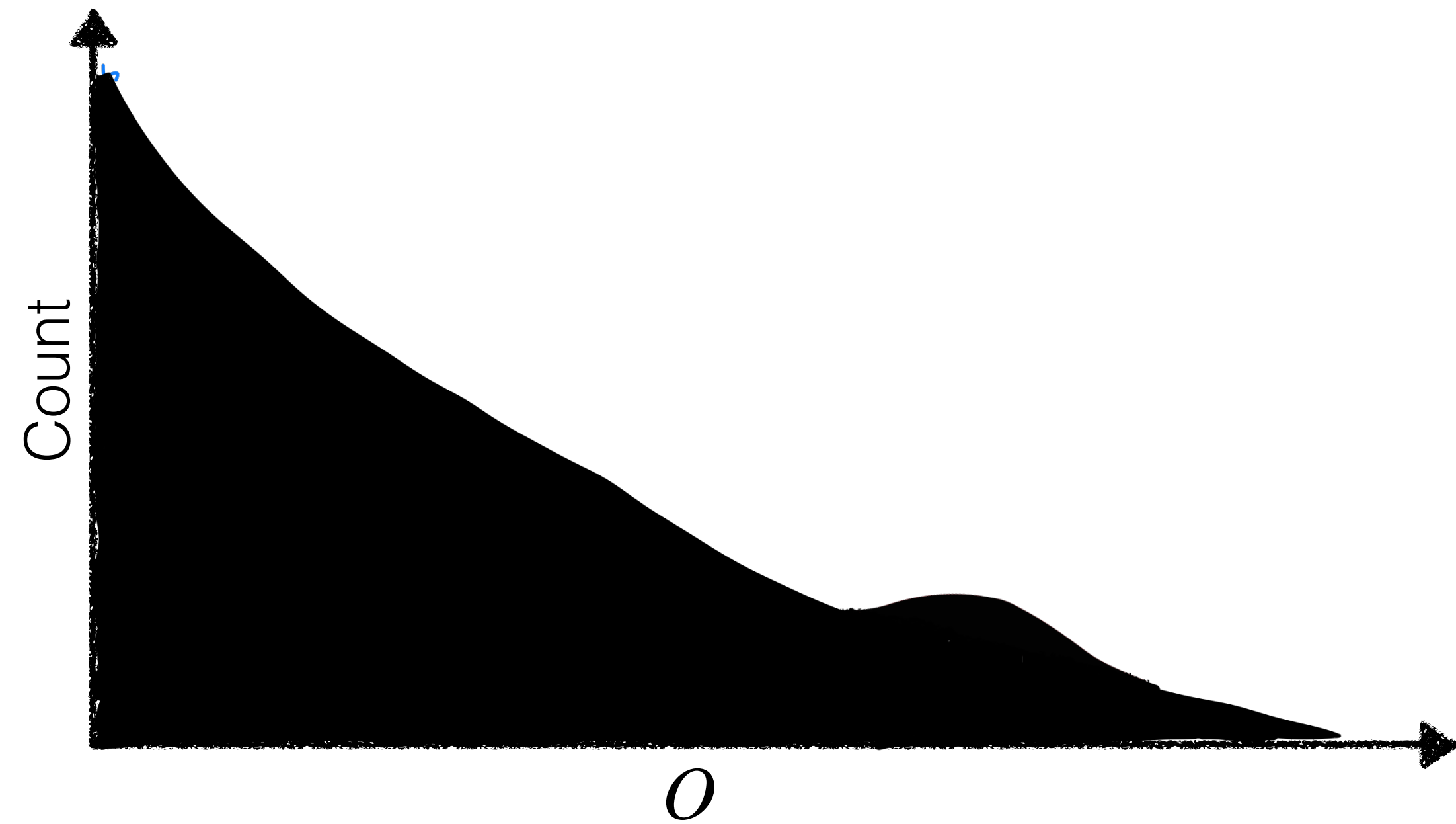


Probability Density Estimation: What we're used to doing..

Theory Predictions

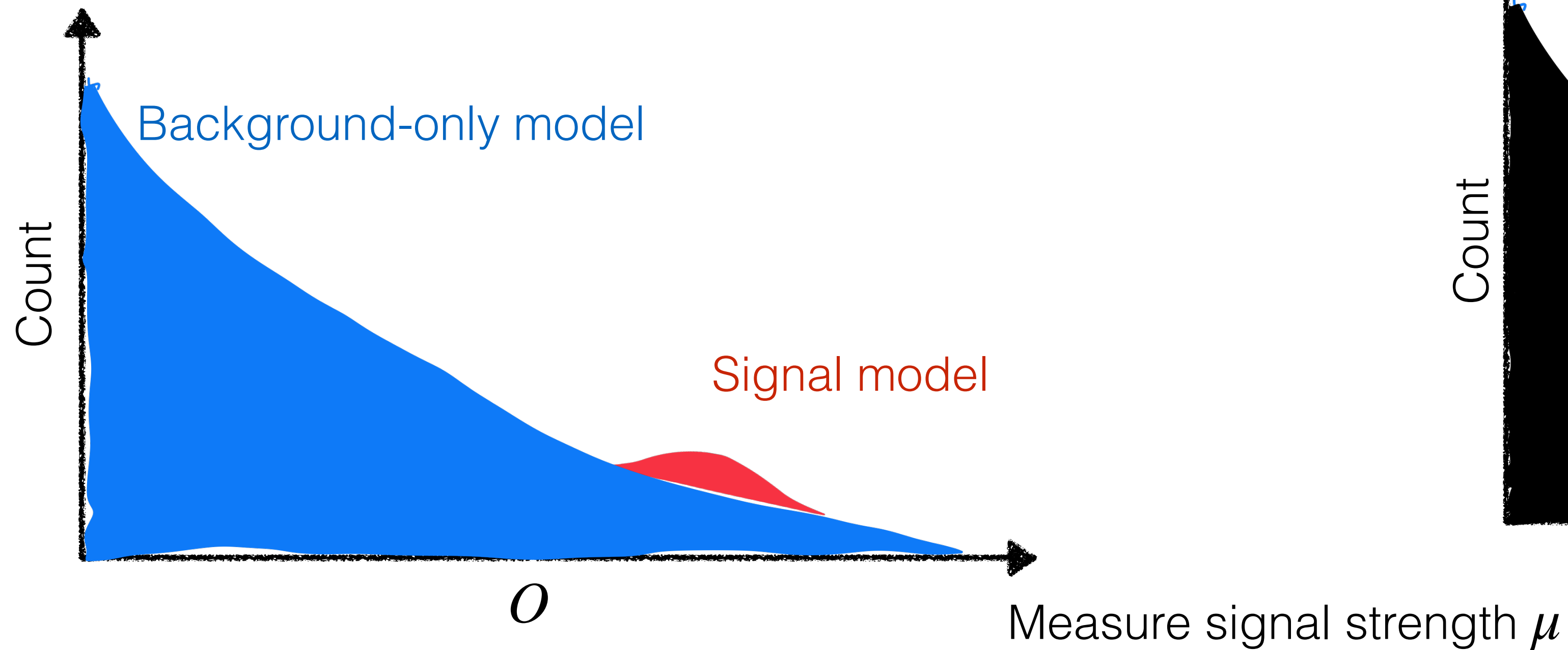


Data

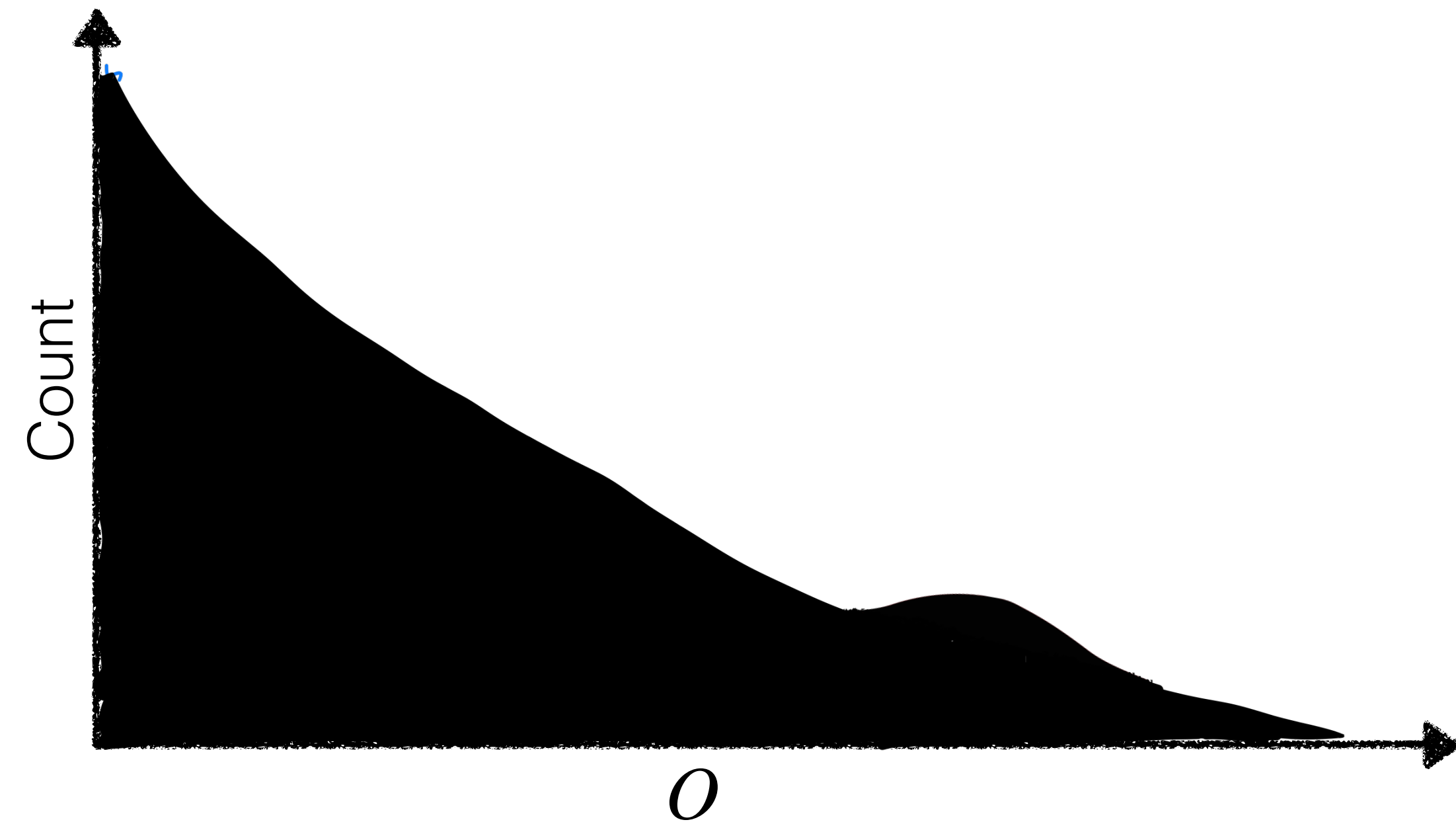


Probability Density Estimation: What we're used to doing..

Theory Predictions



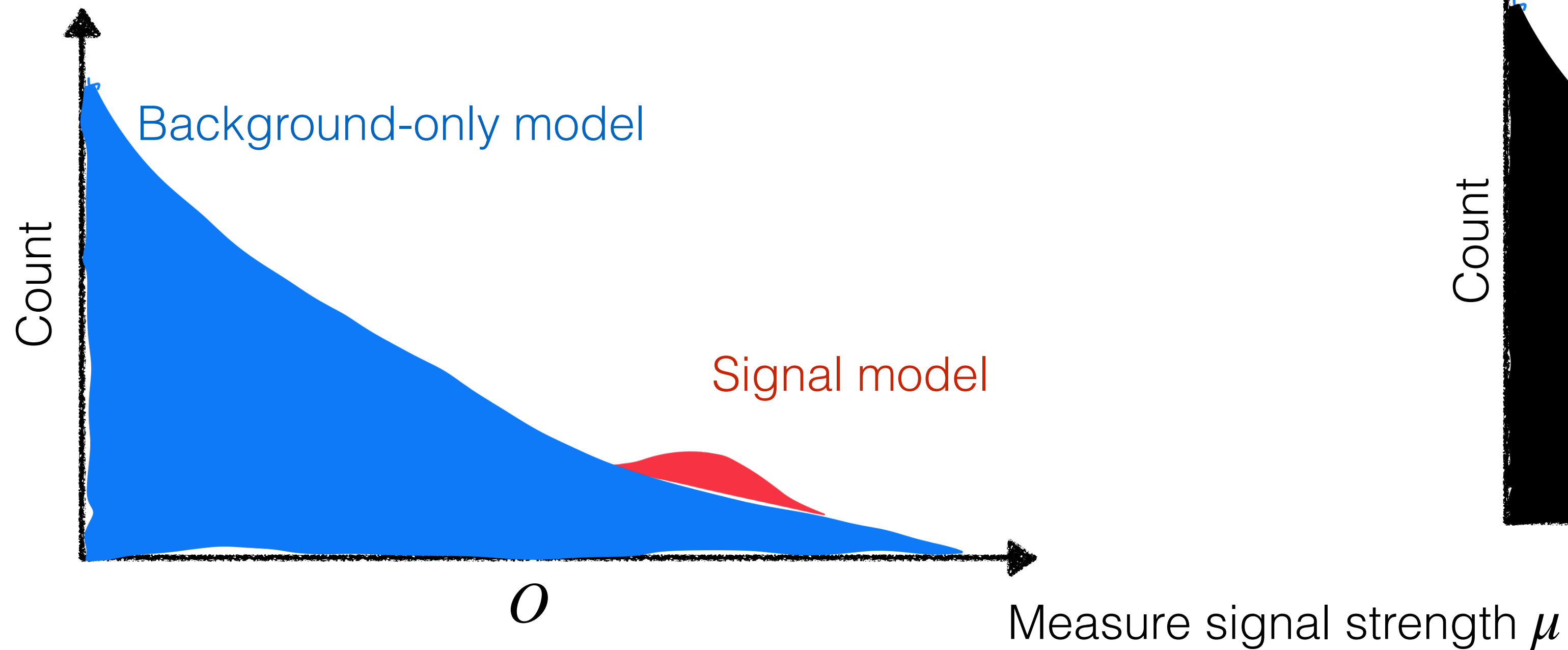
Data



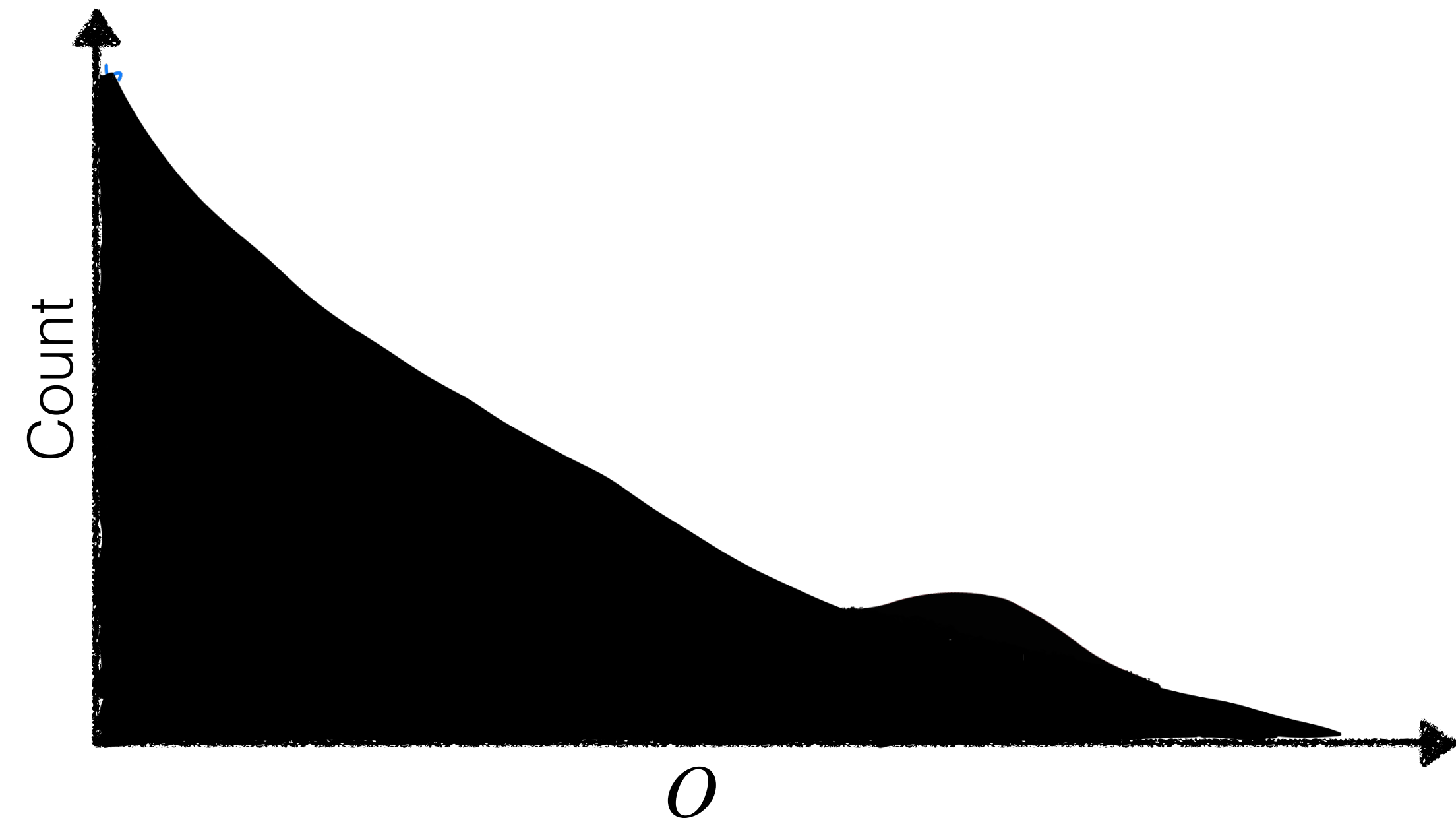
With histograms we can ask "Given the data, what is the likelihood of $\mu = 1$ hypothesis vs $\mu = 2$ hypothesis?"

Probability Density Estimation: What we're used to doing..

Theory Predictions

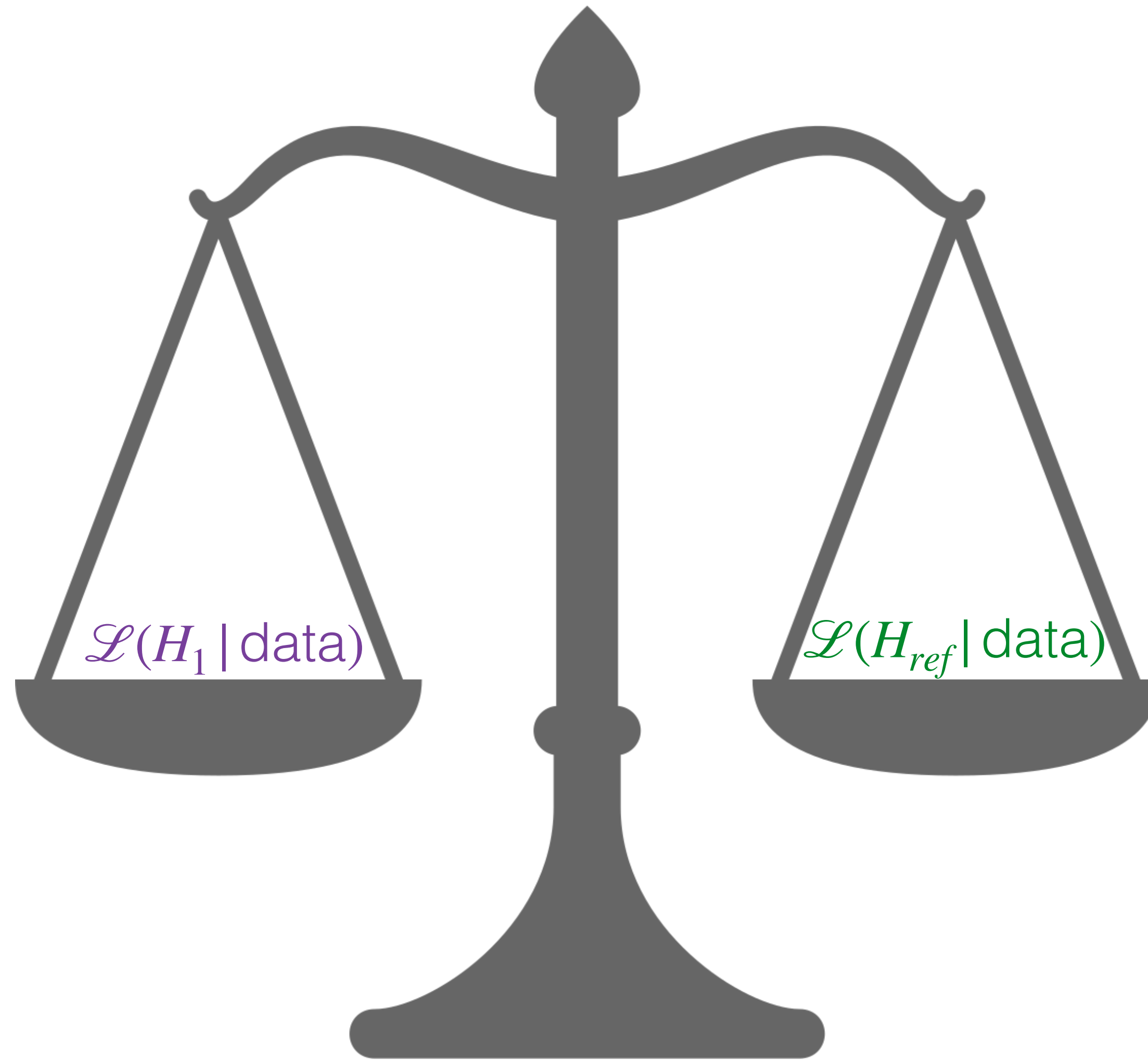


Data



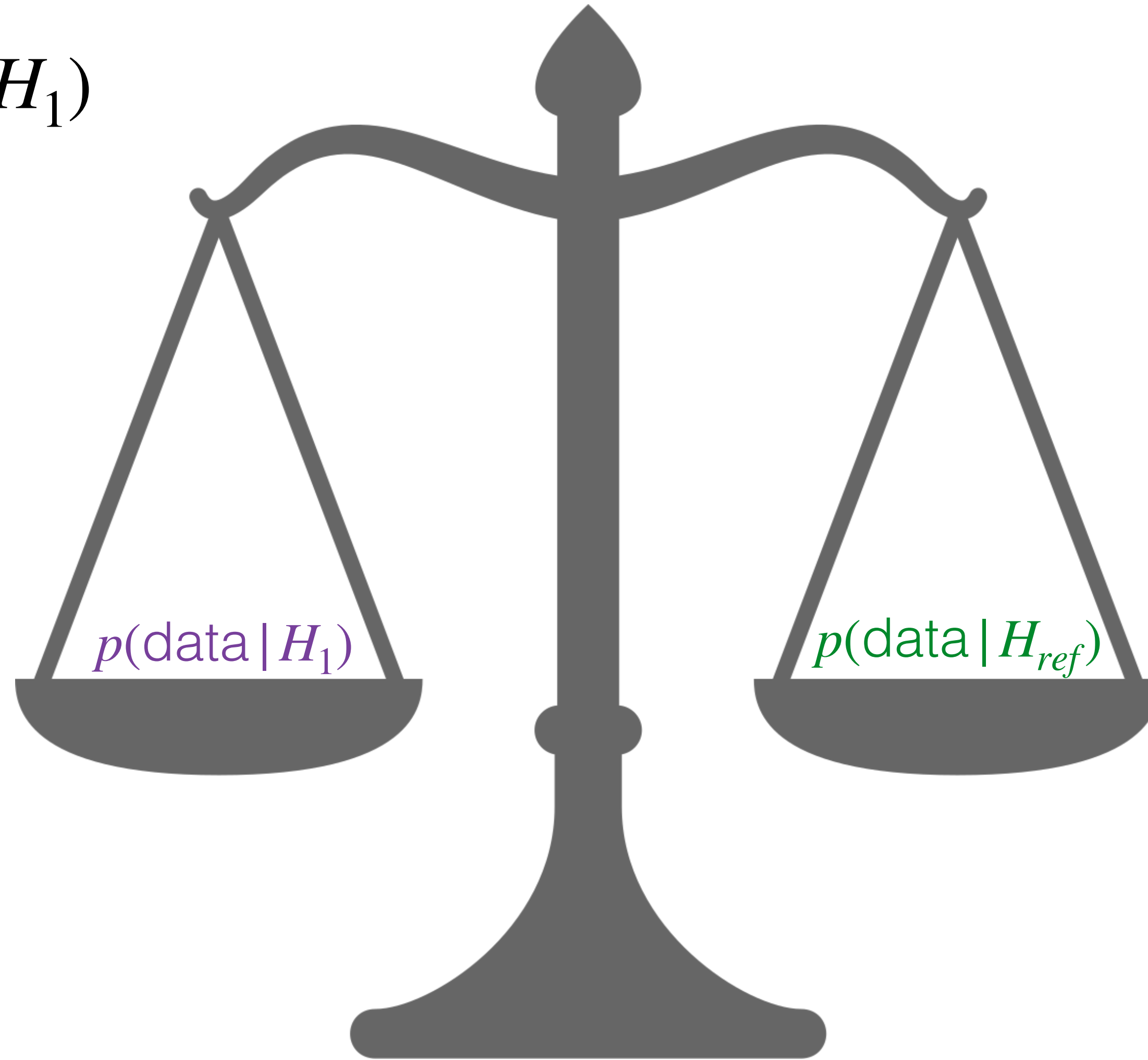
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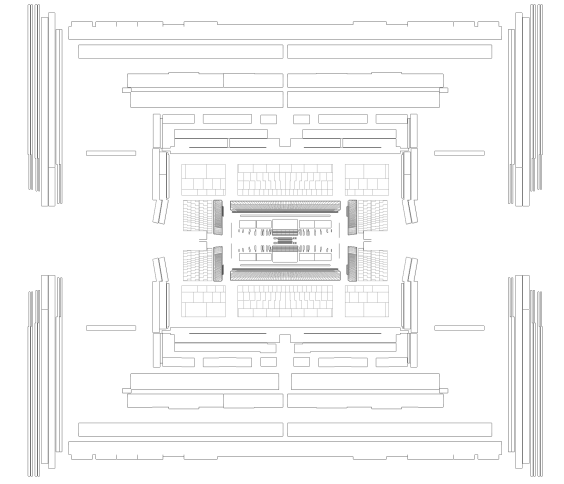
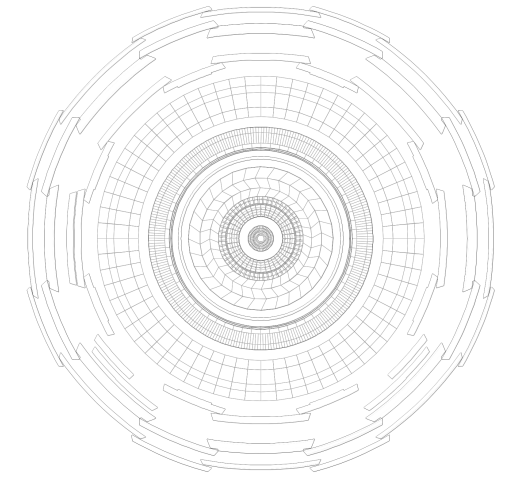
(Frequentist) Hypothesis tests



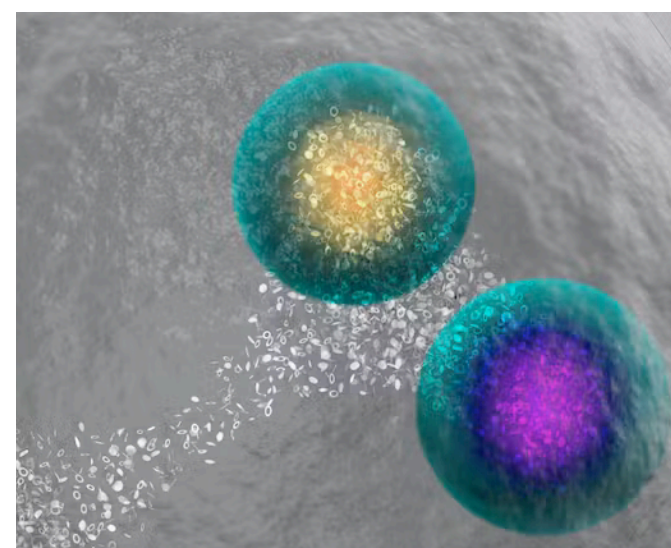
(Frequentist) Hypothesis tests

$$\mathcal{L}(H_1 | \text{data}) = p(\text{data} | H_1)$$





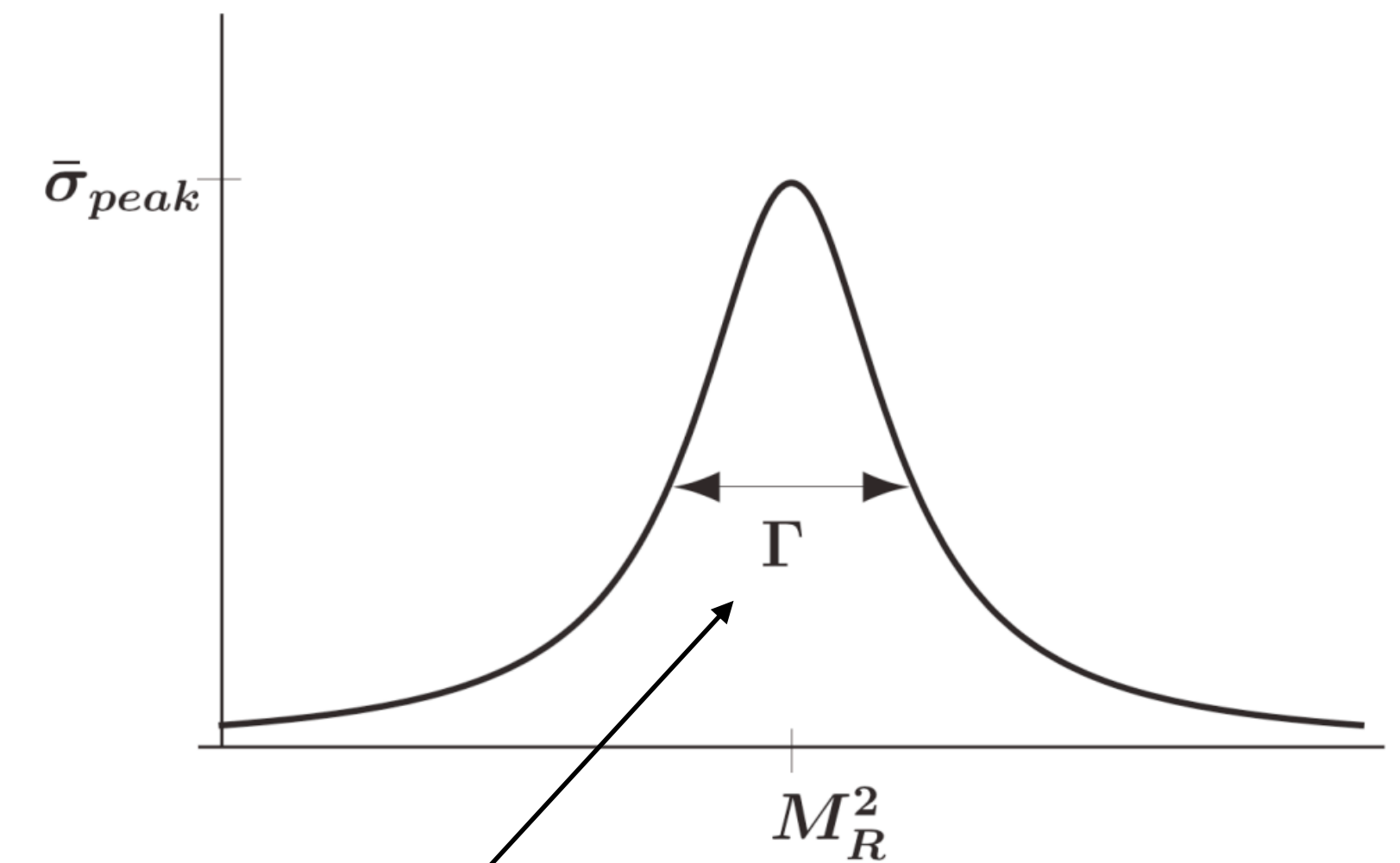
A measurement of the Higgs width



H

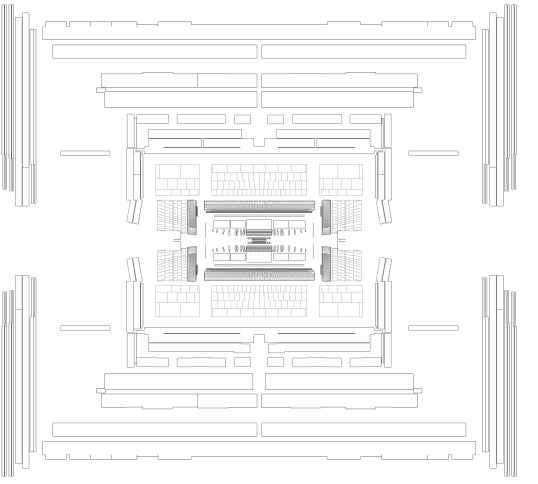
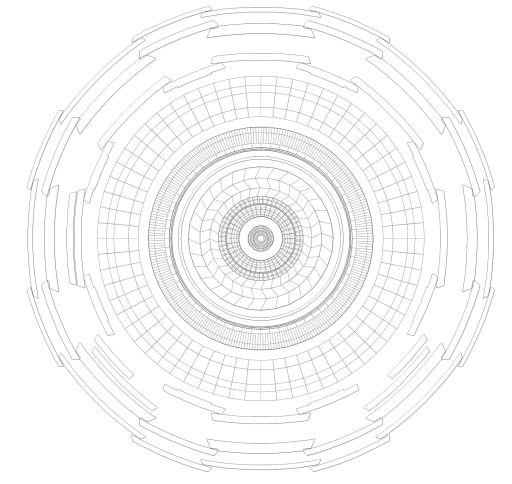


Γ_H



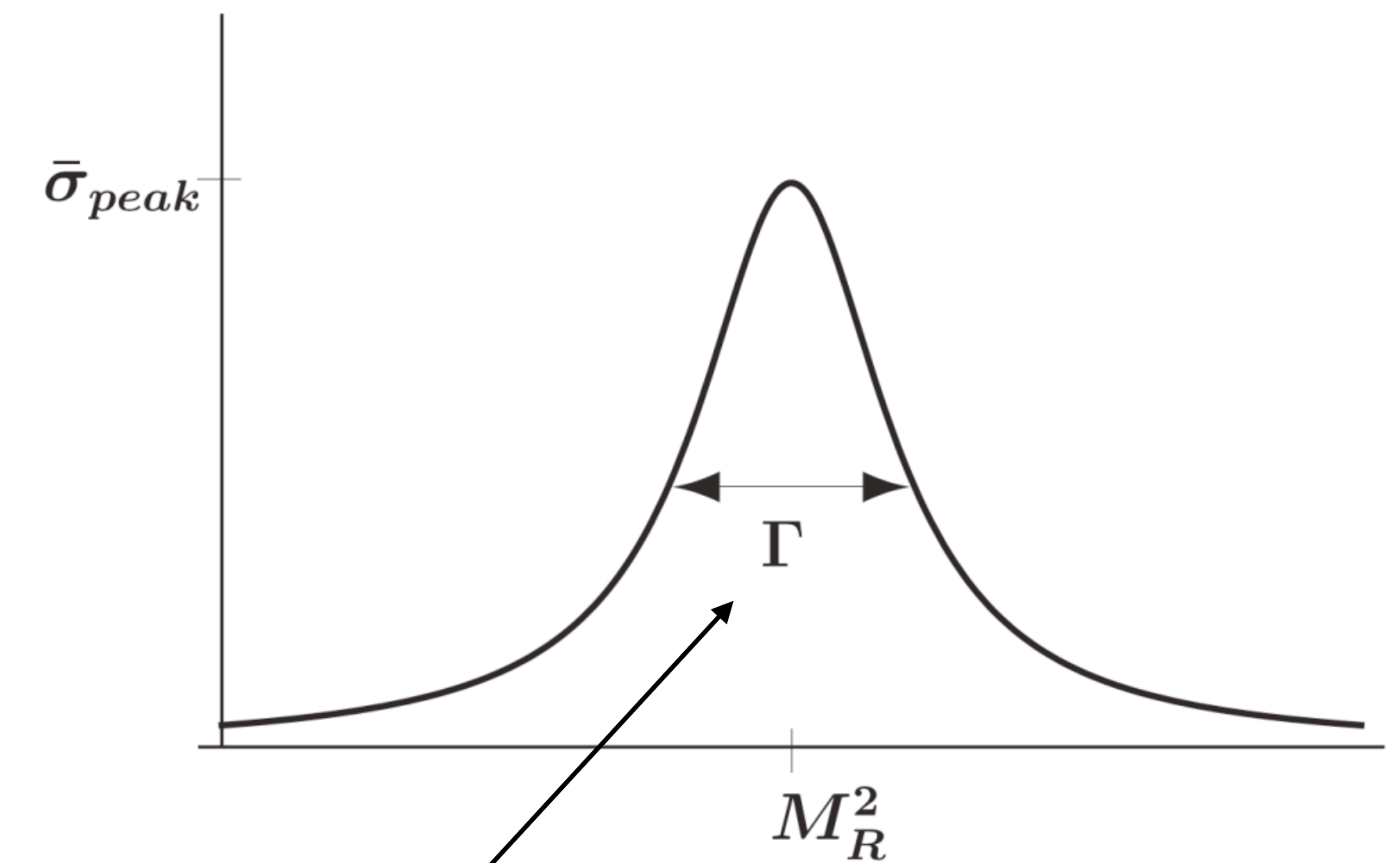
"Width" of the particle

Undiscovered massive particles

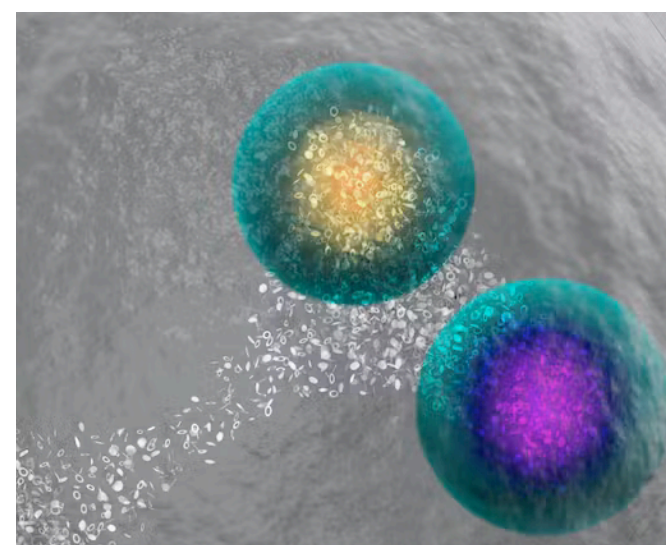


A measurement of the Higgs width

- Enables the probe of a wide variety of new massive particles, other new physics
- Central topic for future colliders



“Width” of the particle



H

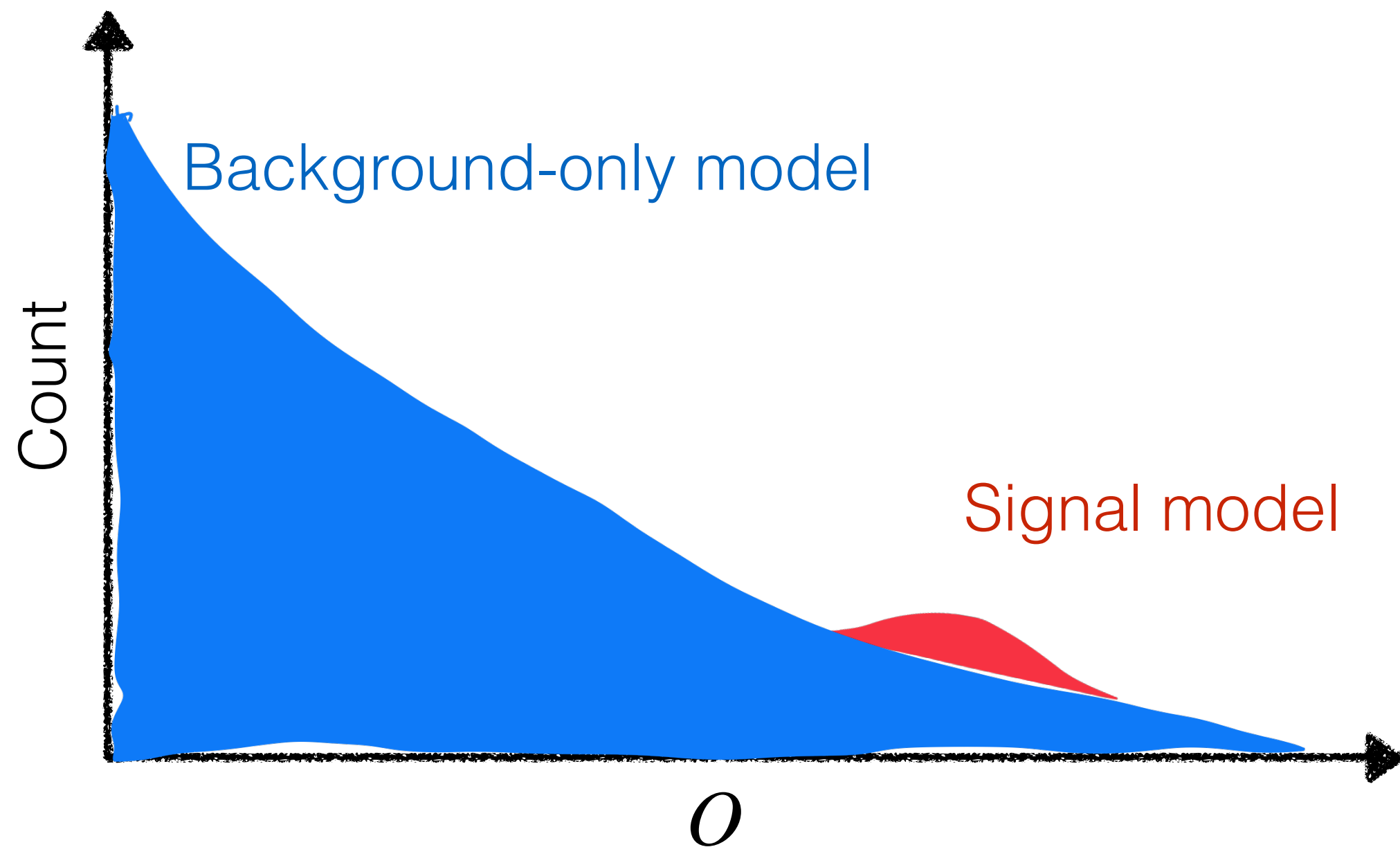


Γ_H

Undiscovered massive particles

New challenge: Quantum interference

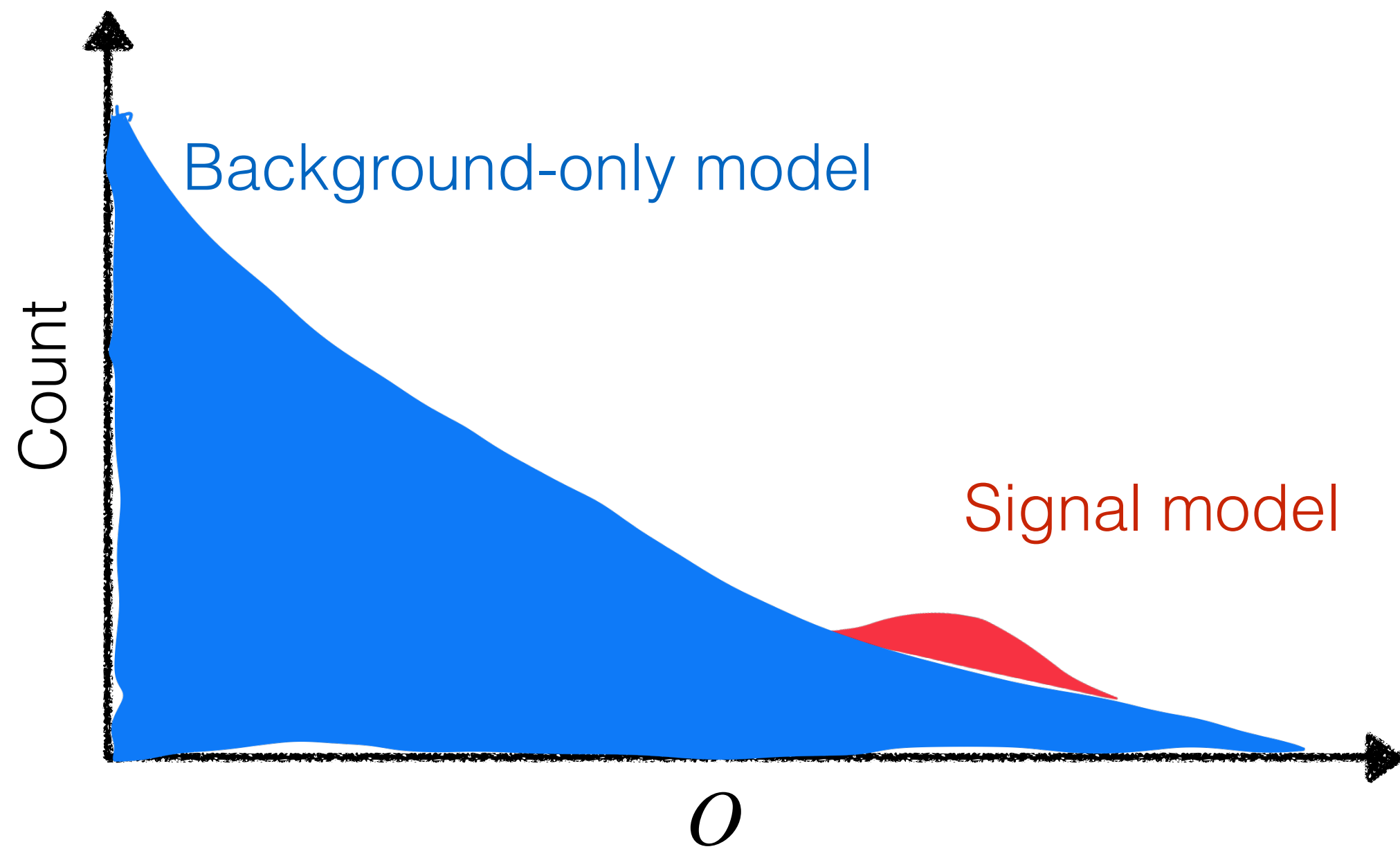
Non-linear changes in kinematics



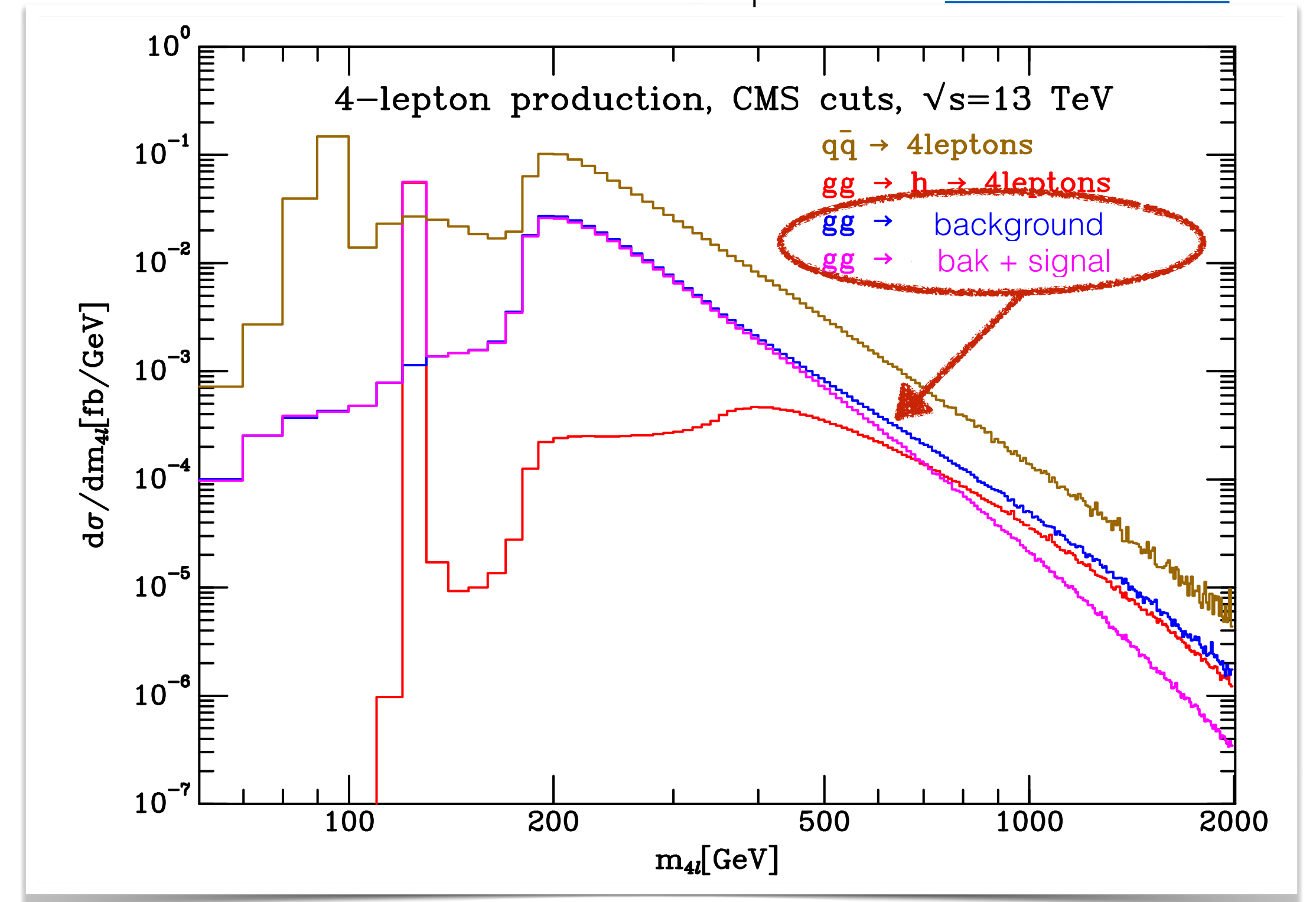
Data can no longer be summarised in 1D histogram (see Ghosh et al: [hal-02971995\(p172\)](https://arxiv.org/abs/1907.08771)) !

New challenge: Quantum interference

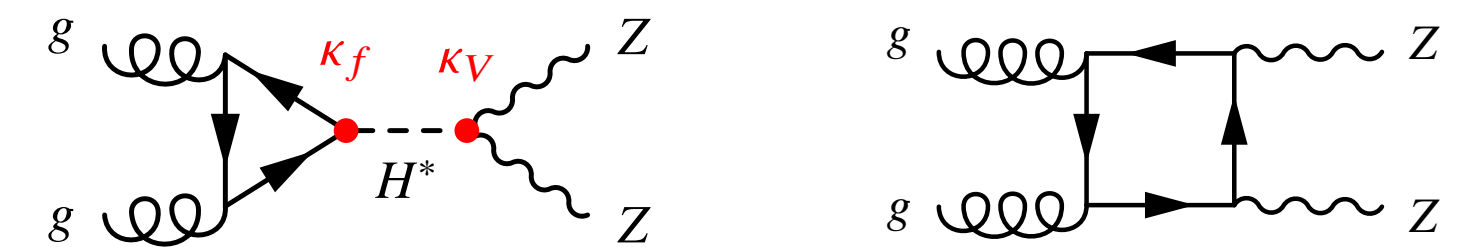
Non-linear changes in kinematics



Campbell et al: [arXiv:1311.3589](https://arxiv.org/abs/1311.3589)



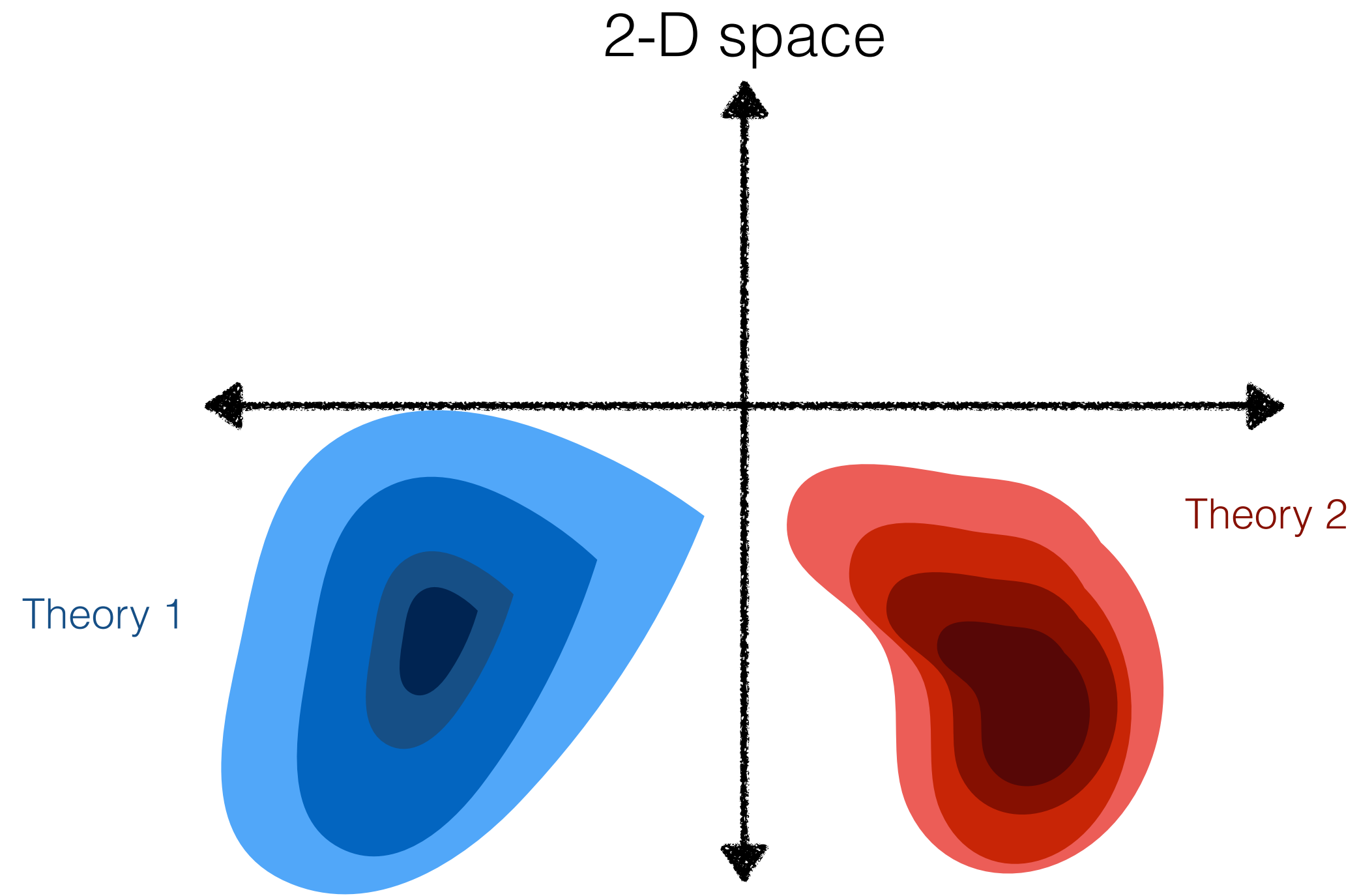
Quantum interference:



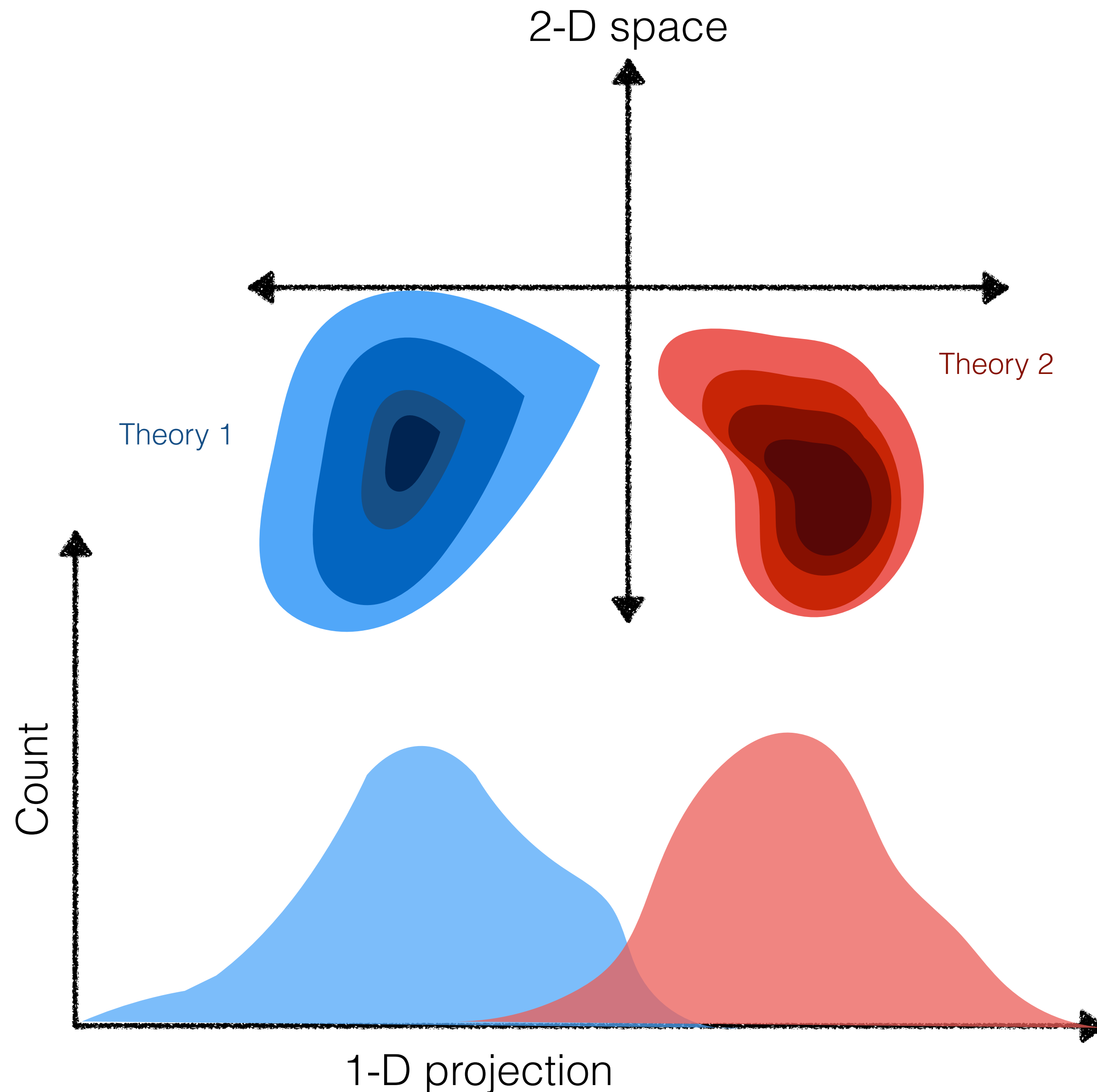
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The problem with one-dimensional summaries...

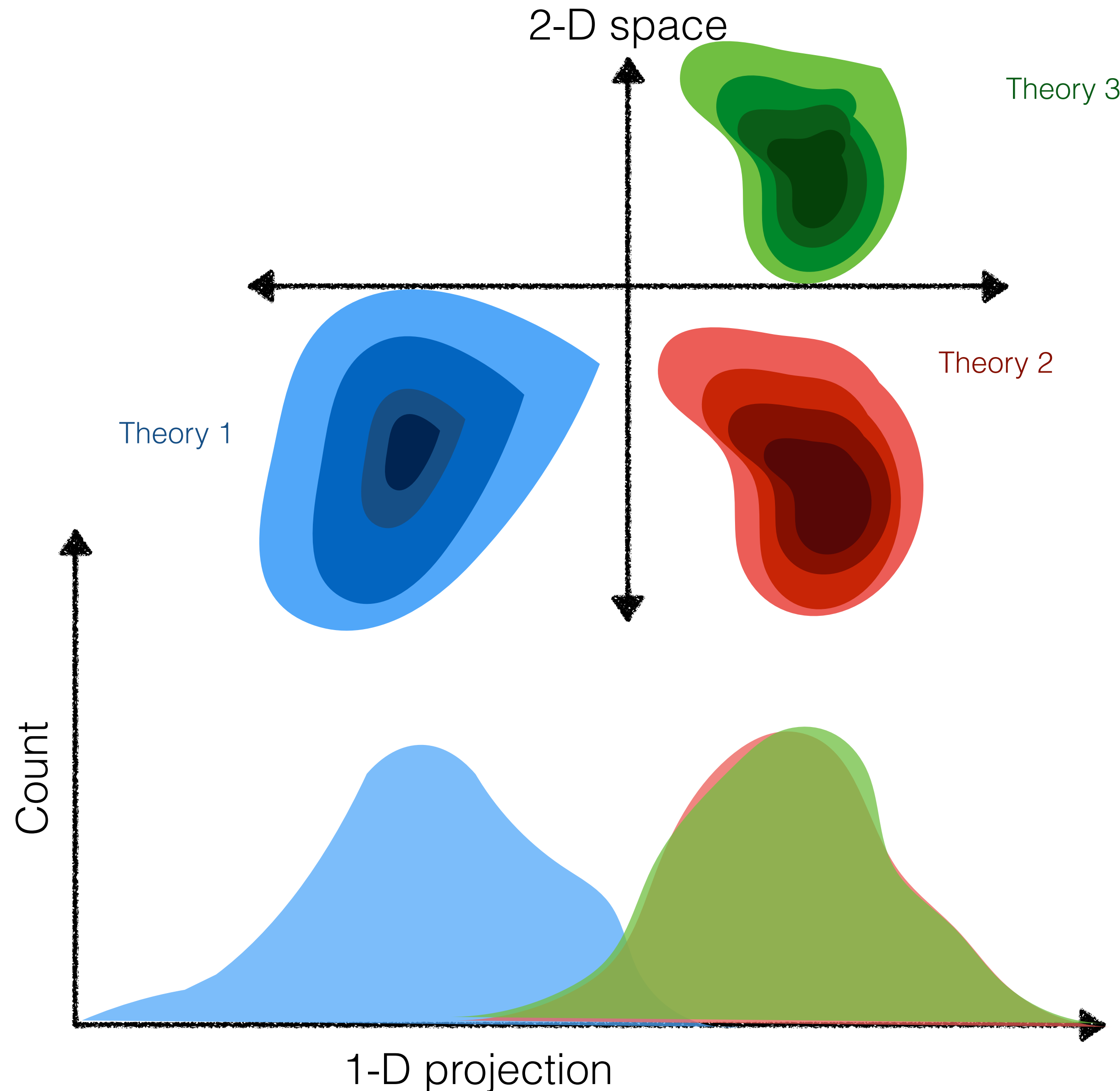
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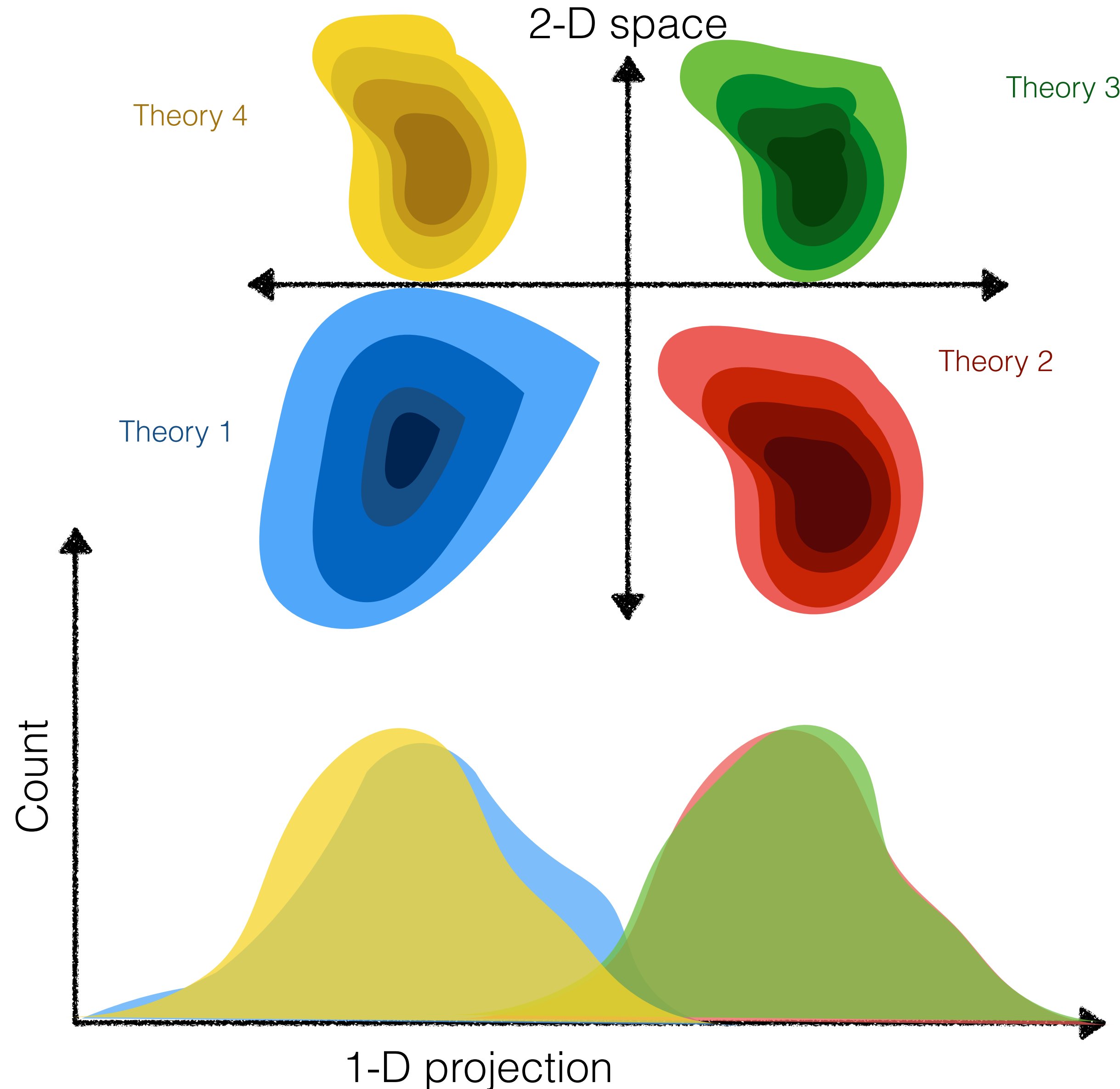
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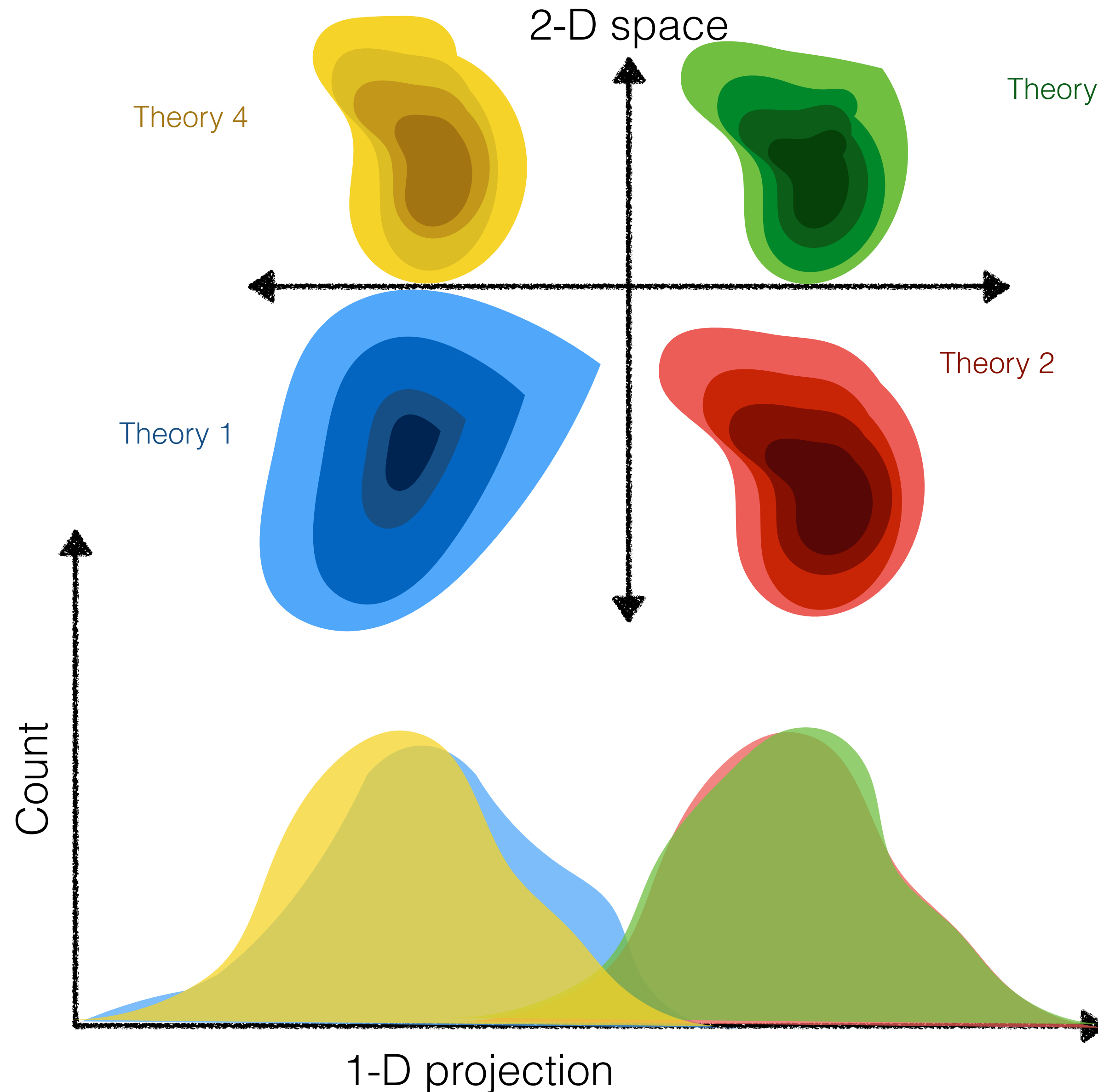
The problem with one-dimensional summaries...



The problem with one-dimensional summaries...



The problem with one-dimensional summaries...



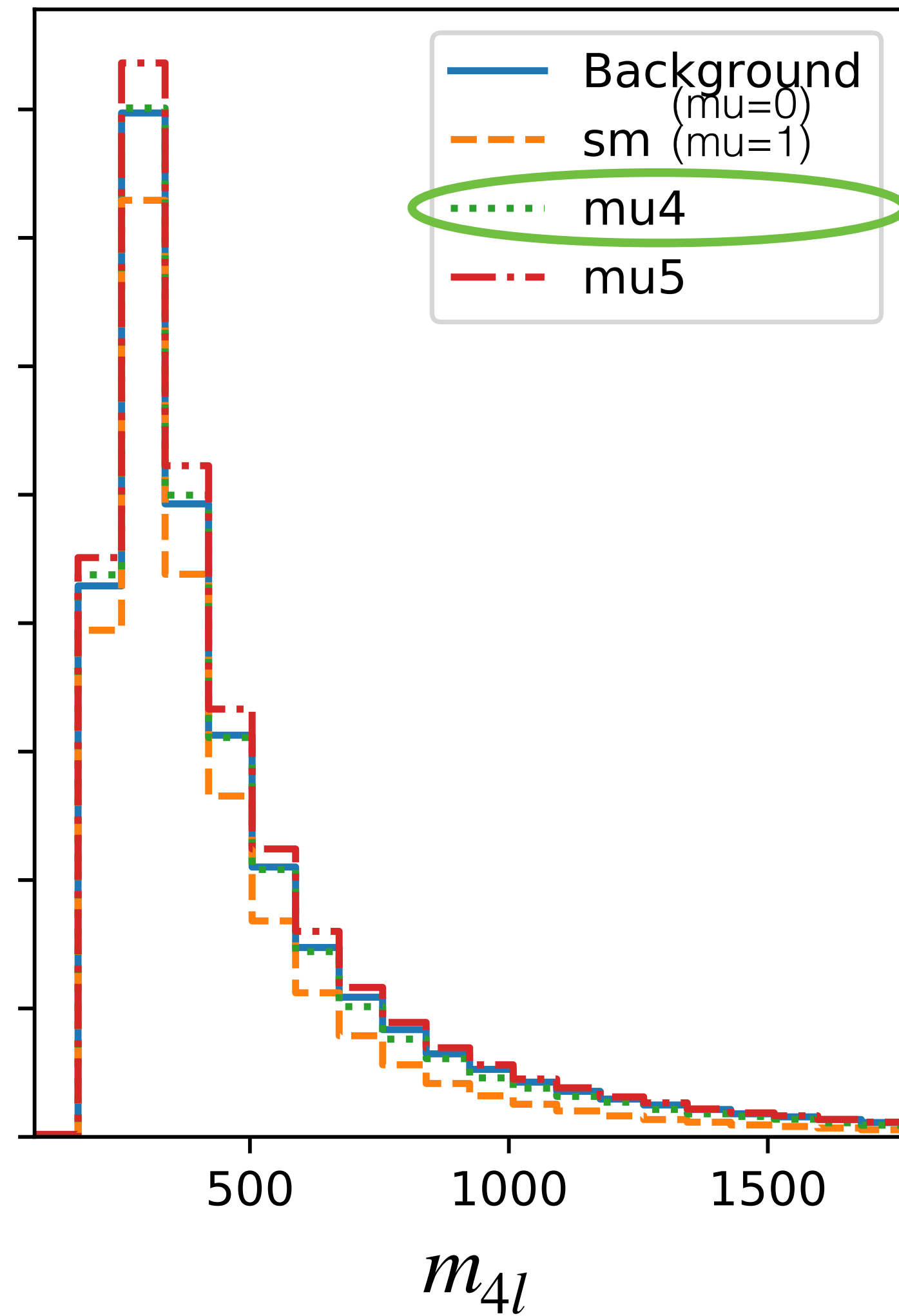
- Clearly separable in 2-D
- No 1-D summary statistic may contain all the information needed to optimally test all theory hypotheses!
- Valuable to have high-dimensional view of data

No single observable captures all information in Higgs width study

Signal-background-inference simulations: MG + Pythia

No single observable captures all information in Higgs width study

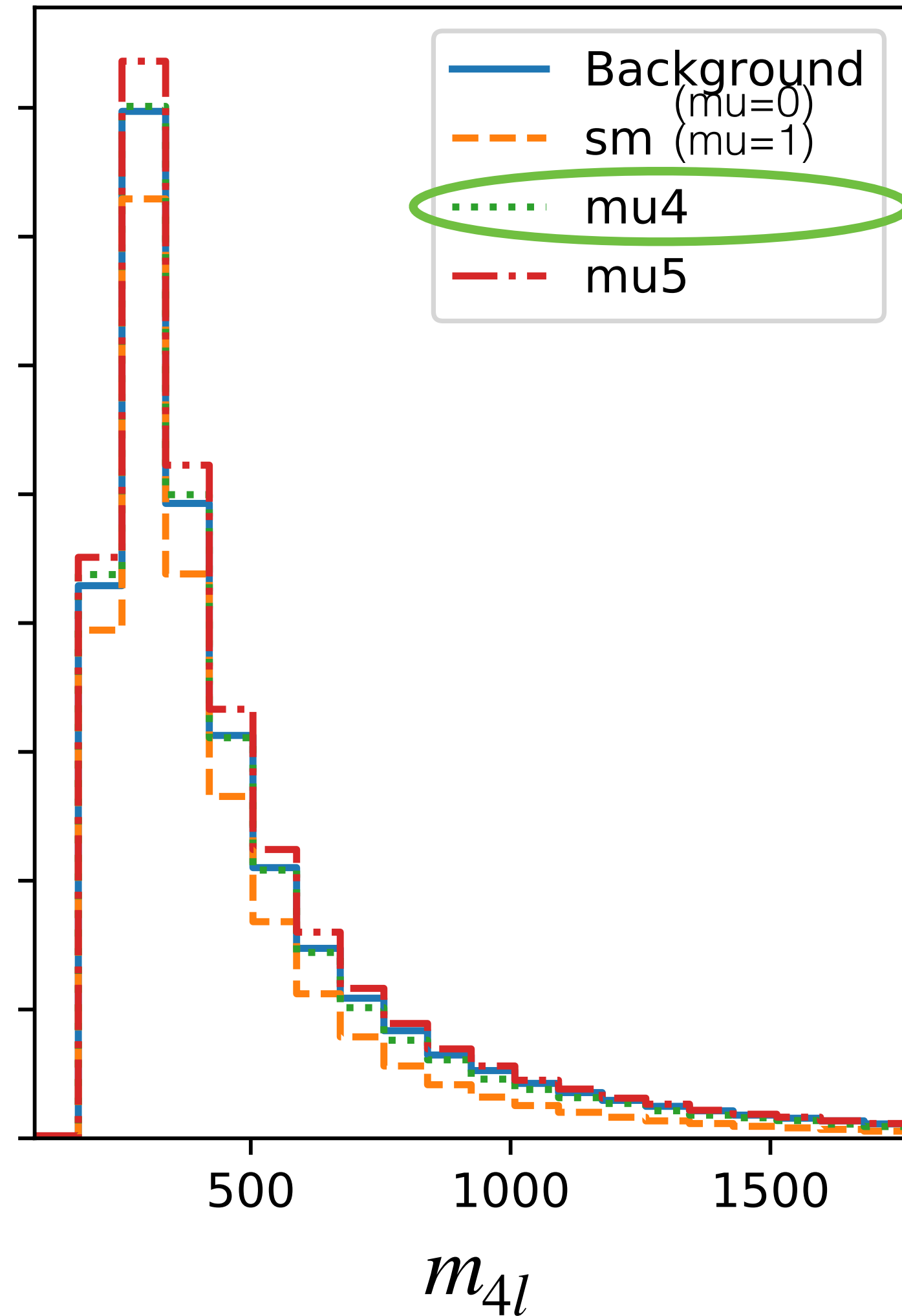
Signal-background-inference simulations: MG + Pythia



Can you spot the green plot?

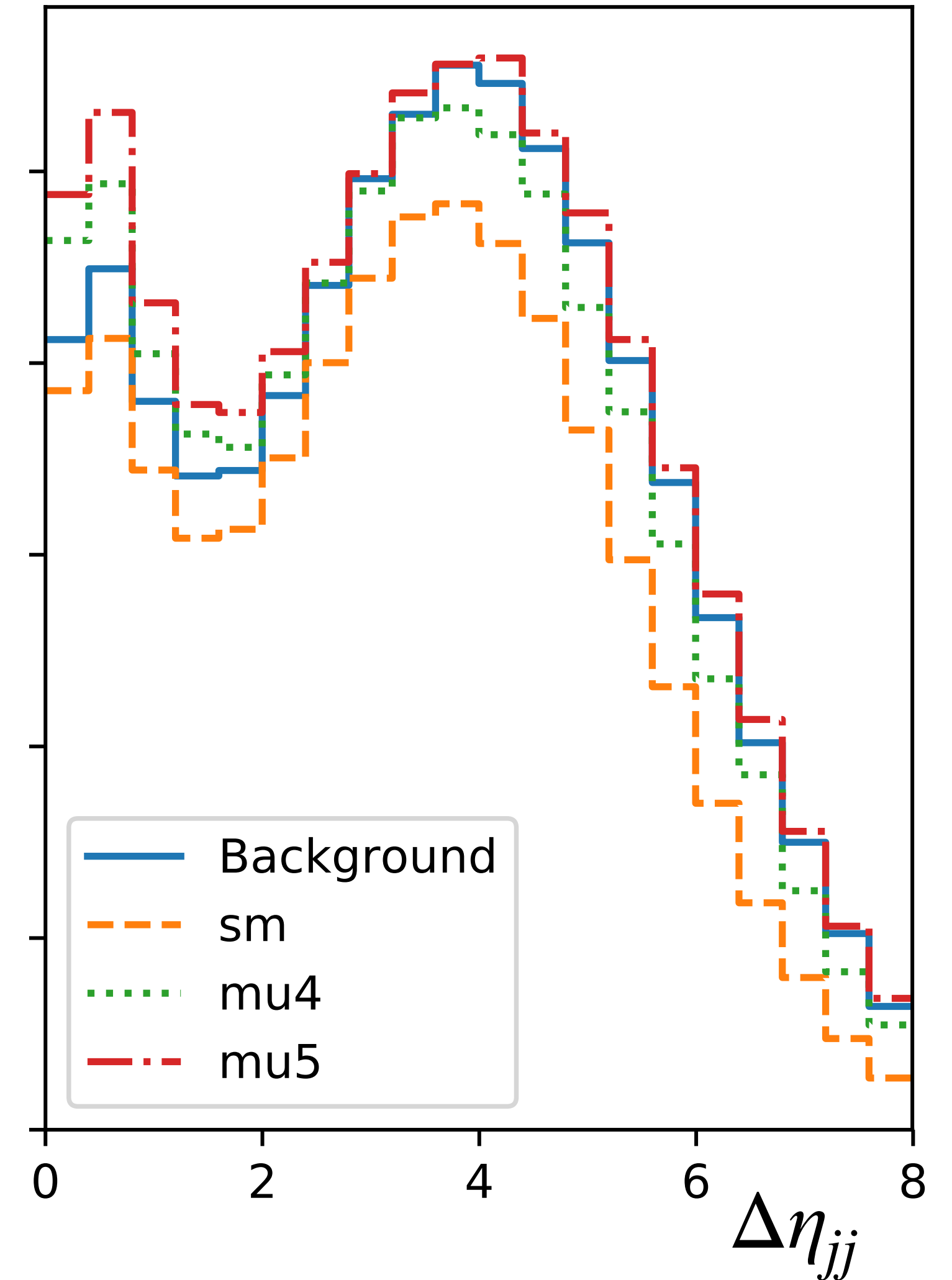
No single observable captures all information in Higgs width study

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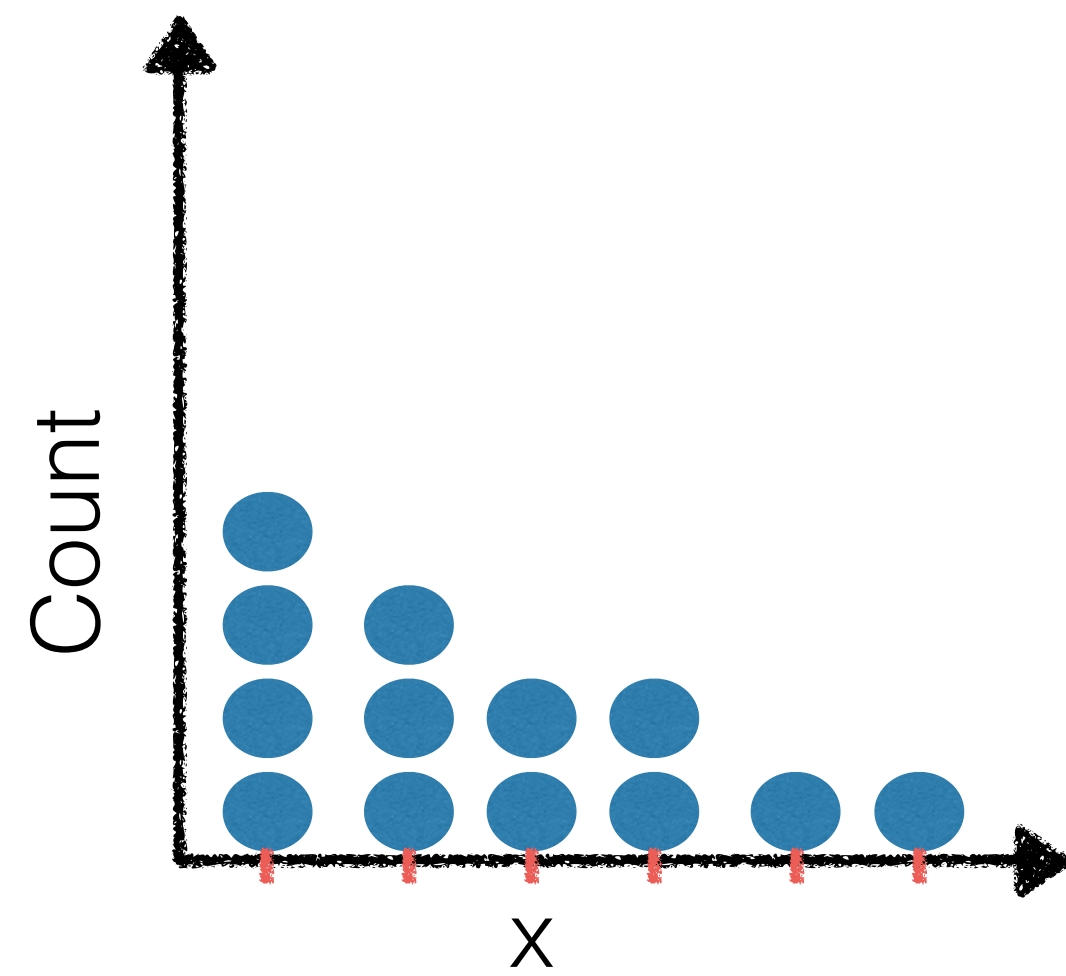
Can you spot the green plot?

=4 indistinguishable from $\mu=0$
 ut other observables can break
 the degeneracy

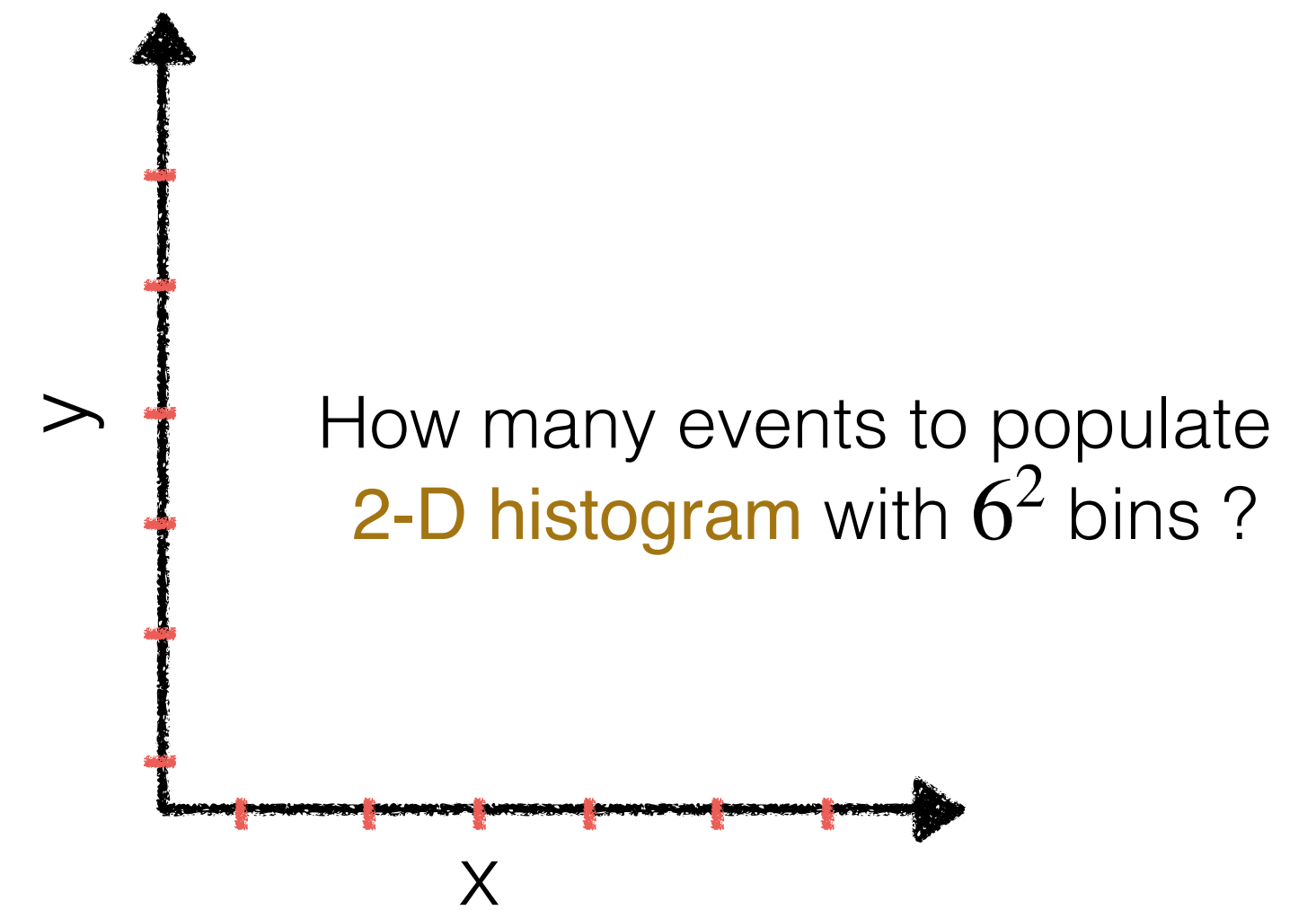


Optimal observable now changes as a function of μ : Cannot collapse problem to 1 dimension

But probability density estimation in higher dimensions is hard...

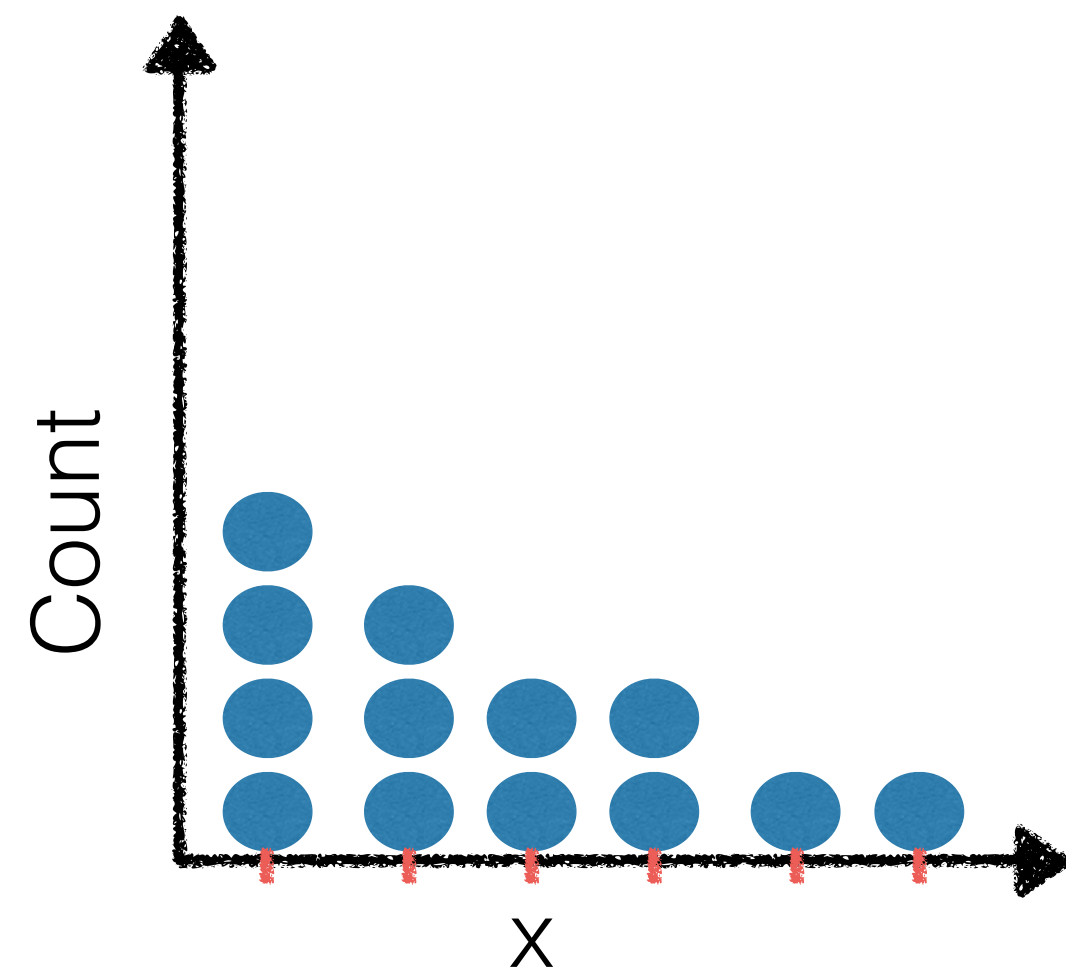


1-D histogram with 6 bins: few events enough to populate it

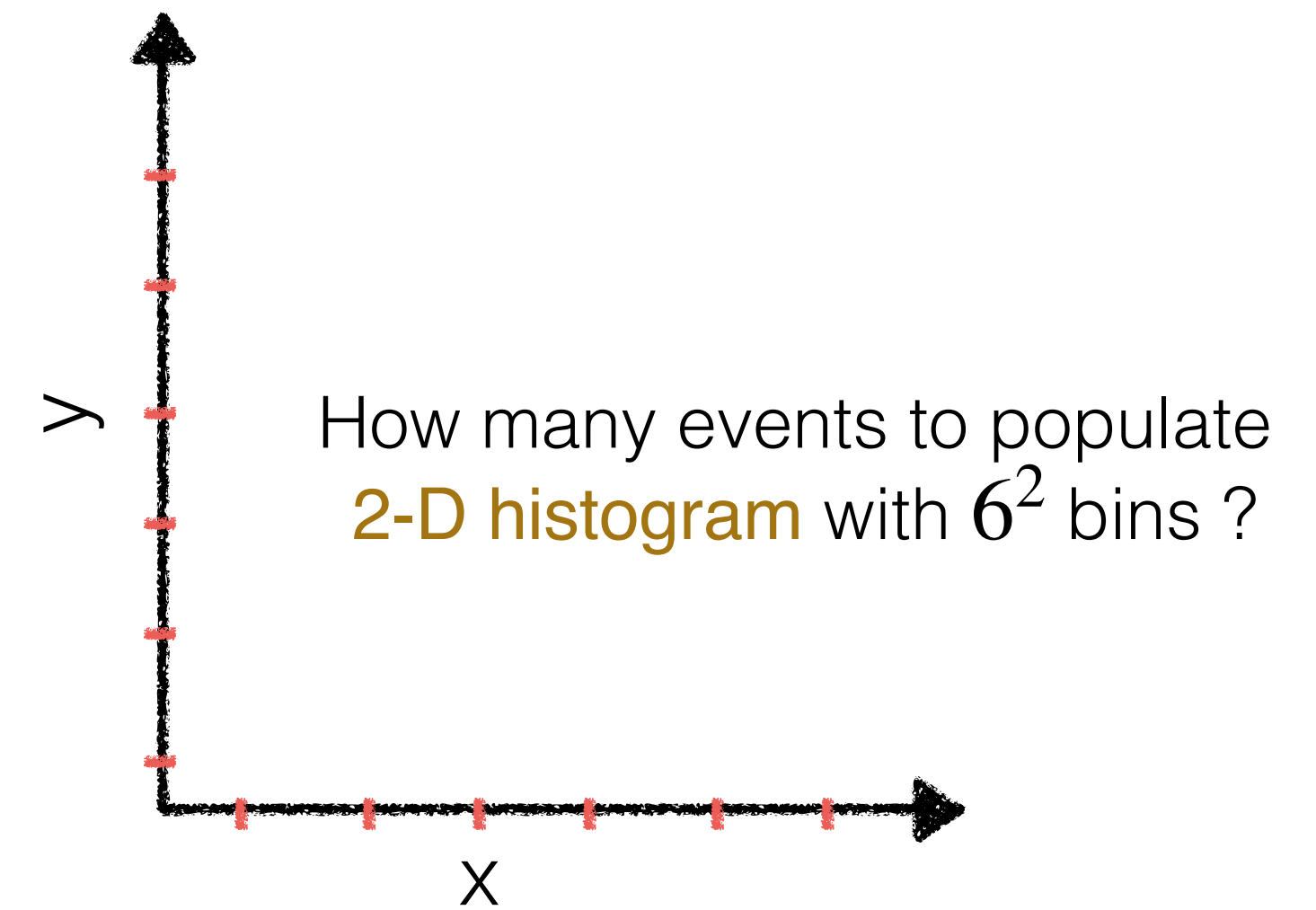


How many events for 50-D histogram with 6^{50} bins?

But probability density estimation in higher dimensions is hard...



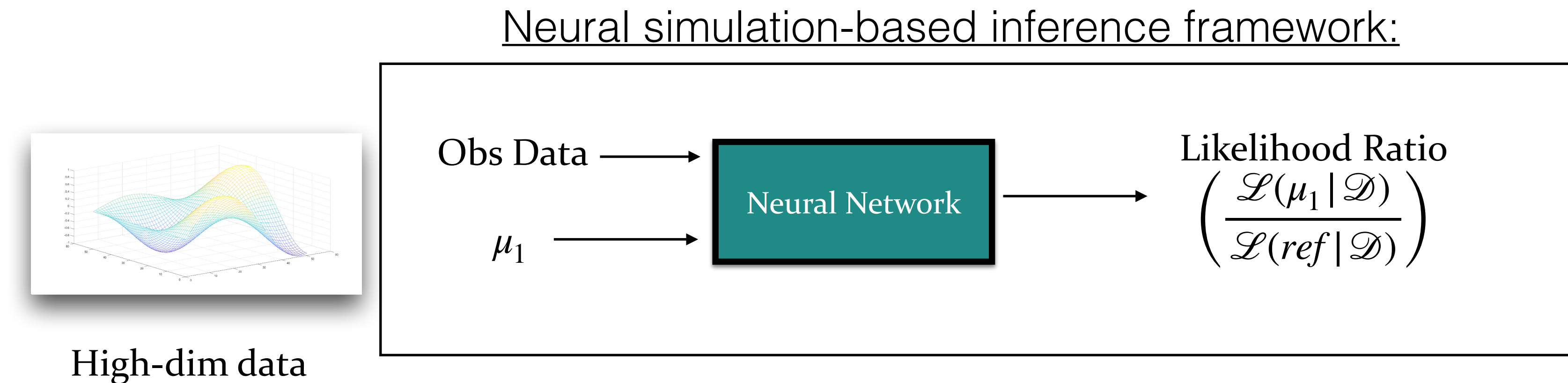
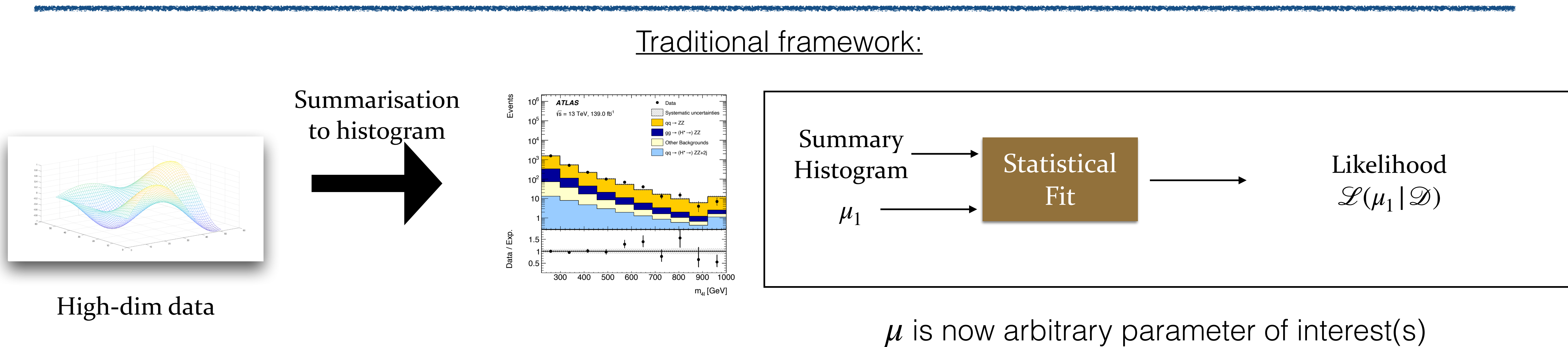
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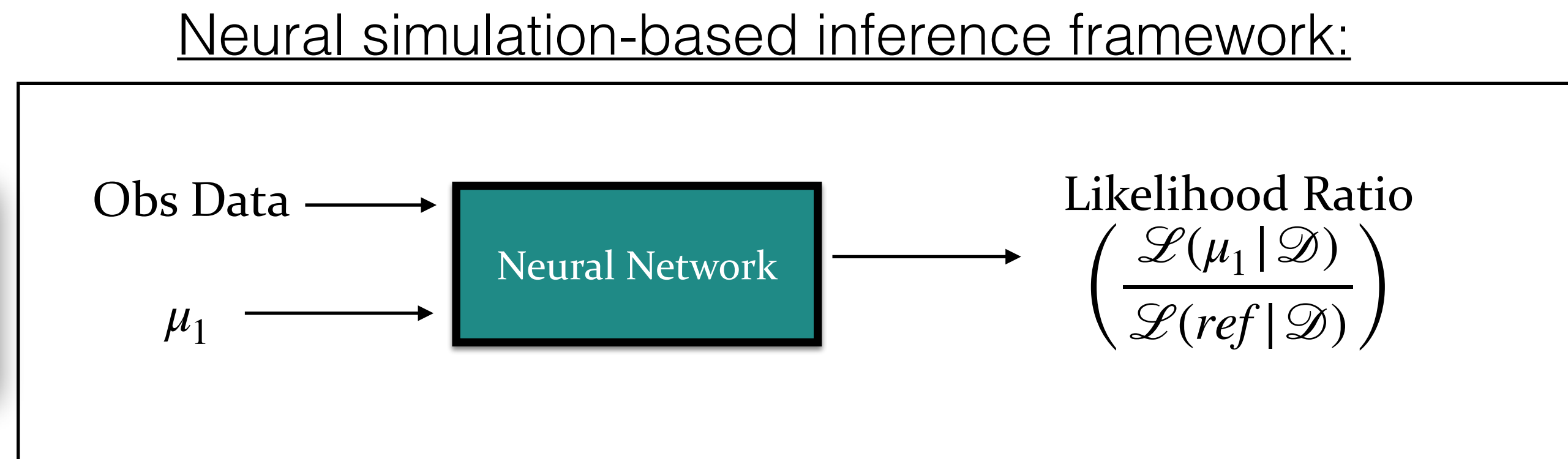
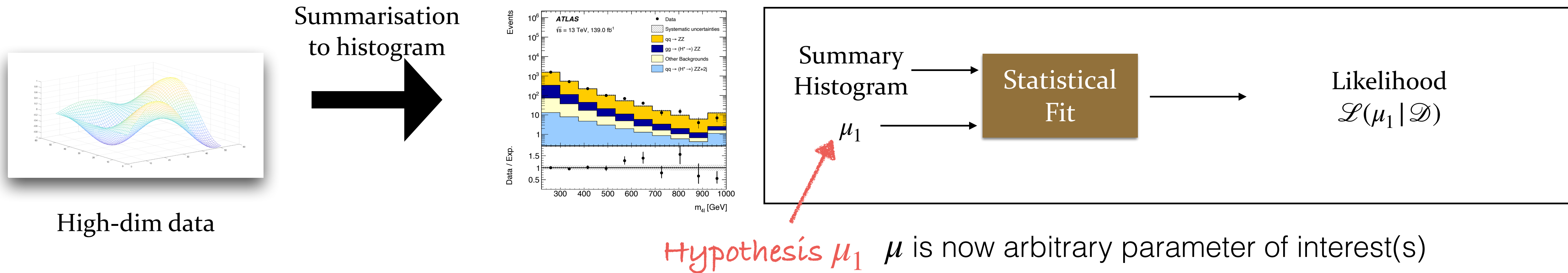
Curse of dimensionality

How many events for 50-D histogram with 6^{50} bins ?

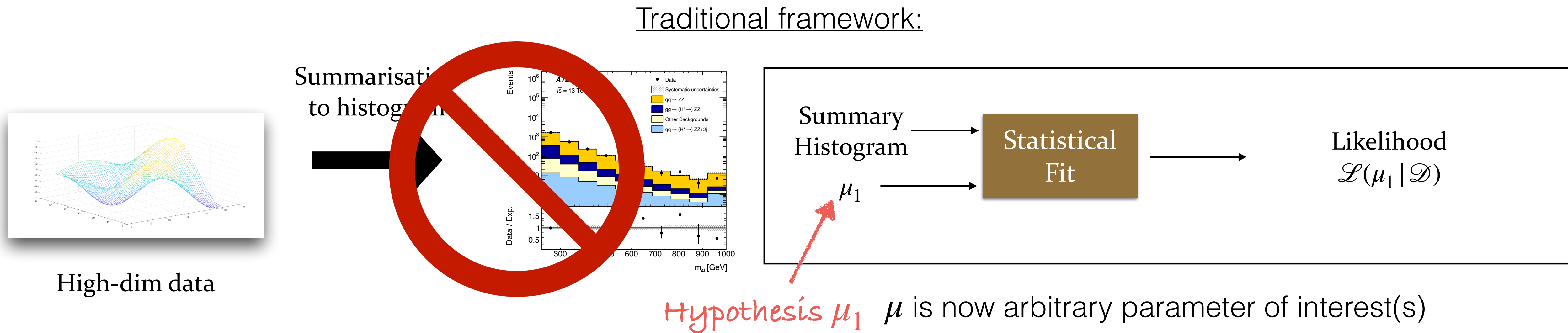
Neural networks can scale to higher dimensions



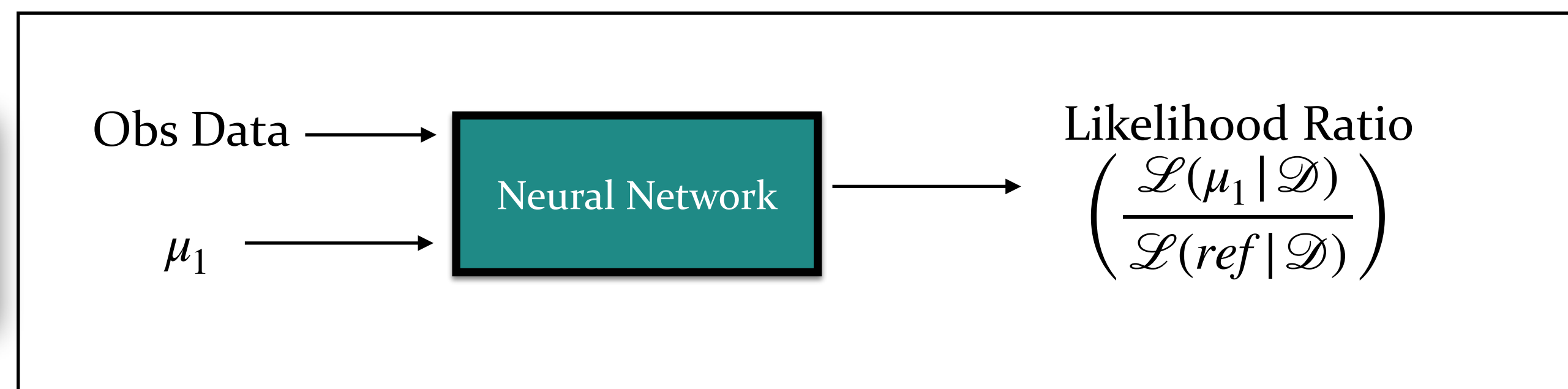
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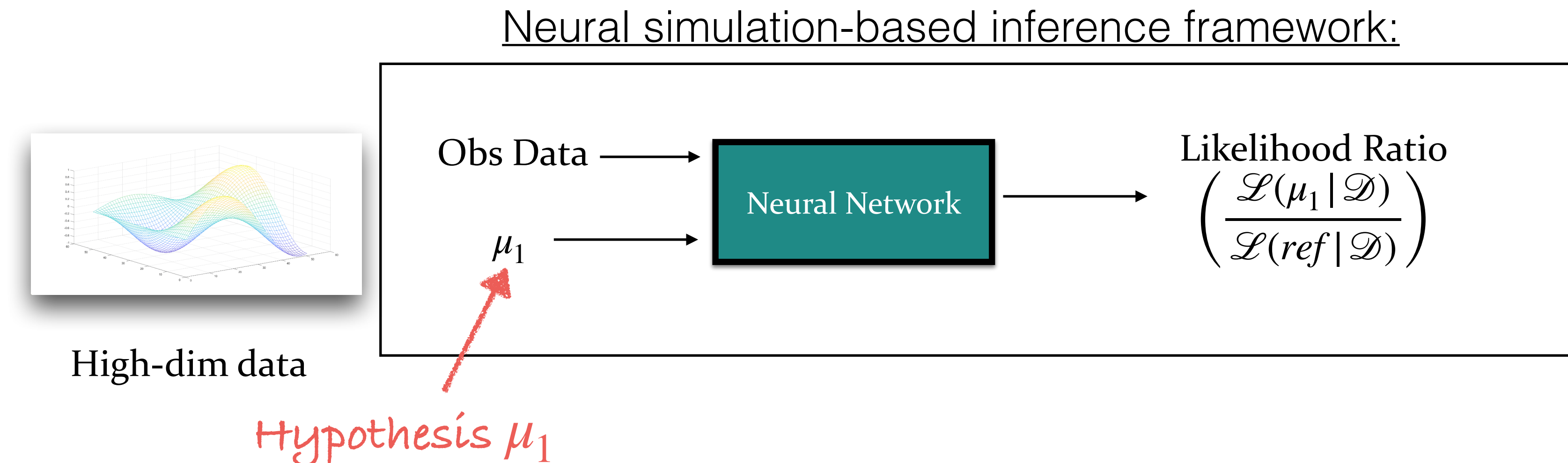
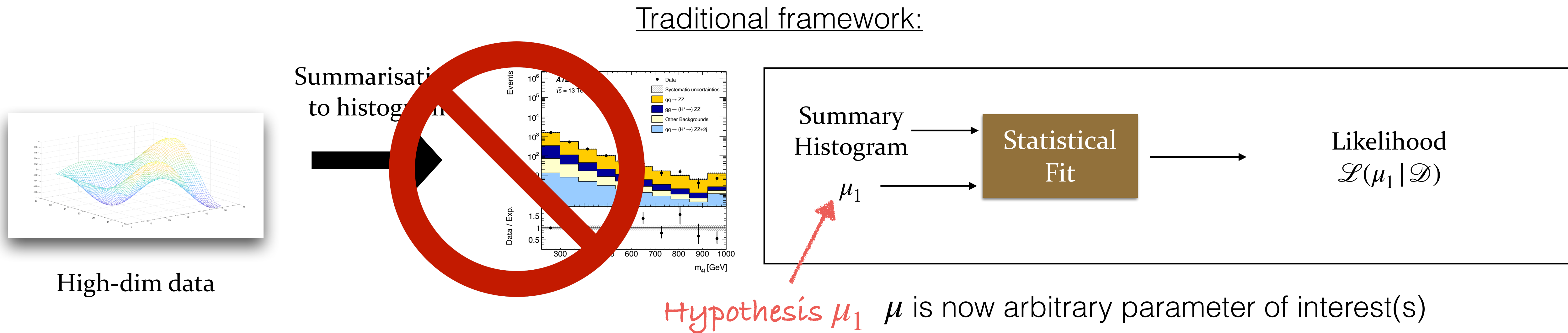
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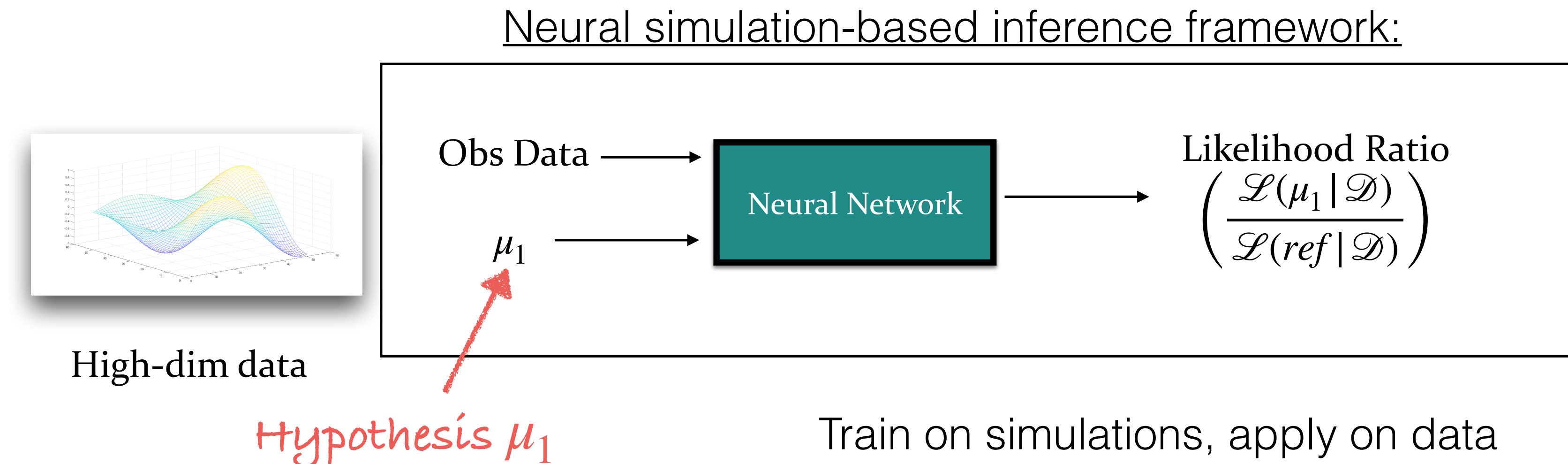
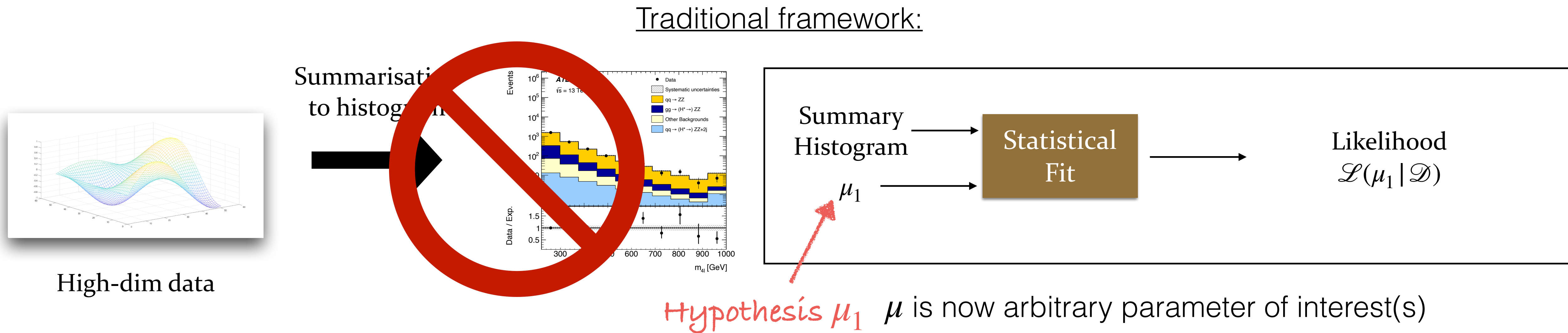
Neural simulation-based inference framework:



Neural networks can scale to higher dimensions



Neural networks can scale to higher dimensions



NSBI for Higgs width in proof-of-concept phenomenology study

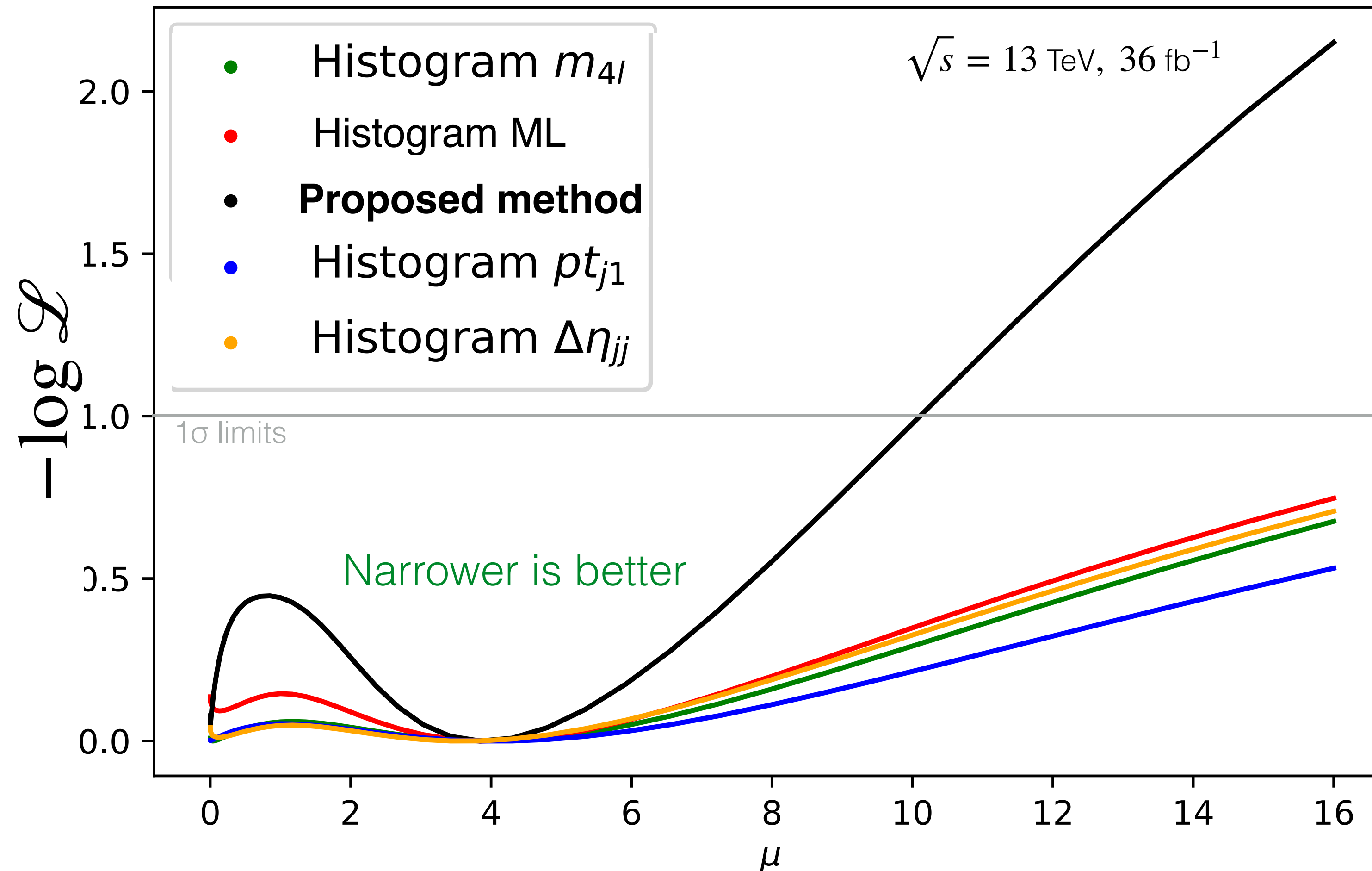
Expected sensitivity

[hal-02971995v3](#) (p172): **Aishik Ghosh**, David Rousseau

NSBI for Higgs width in proof-of-concept phenomenology study

Expected sensitivity

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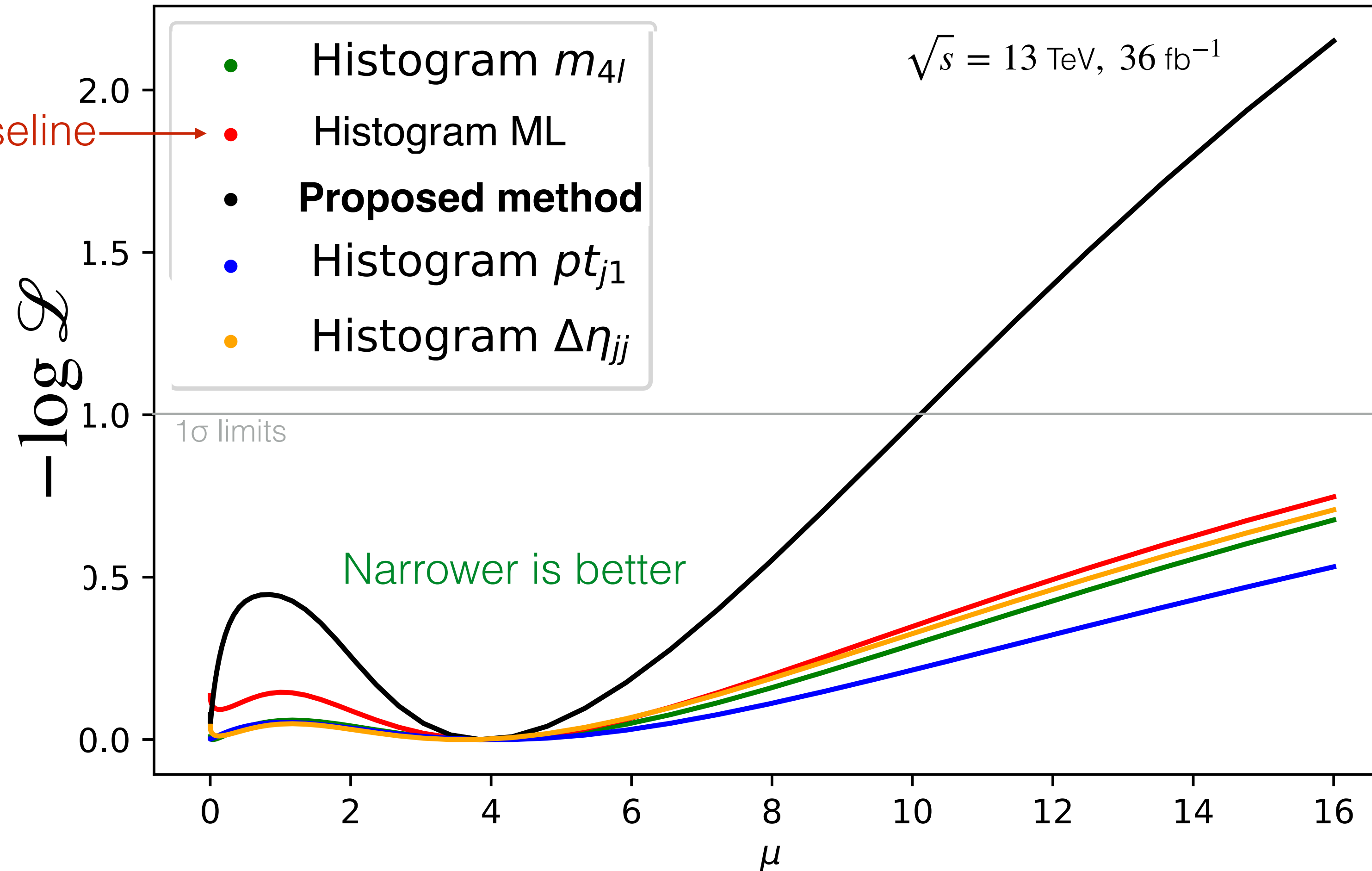


(Beyond Standard Model value) $\mu = 4$, without rate

NSBI for Higgs width in proof-of-concept phenomenology study

Expected sensitivity

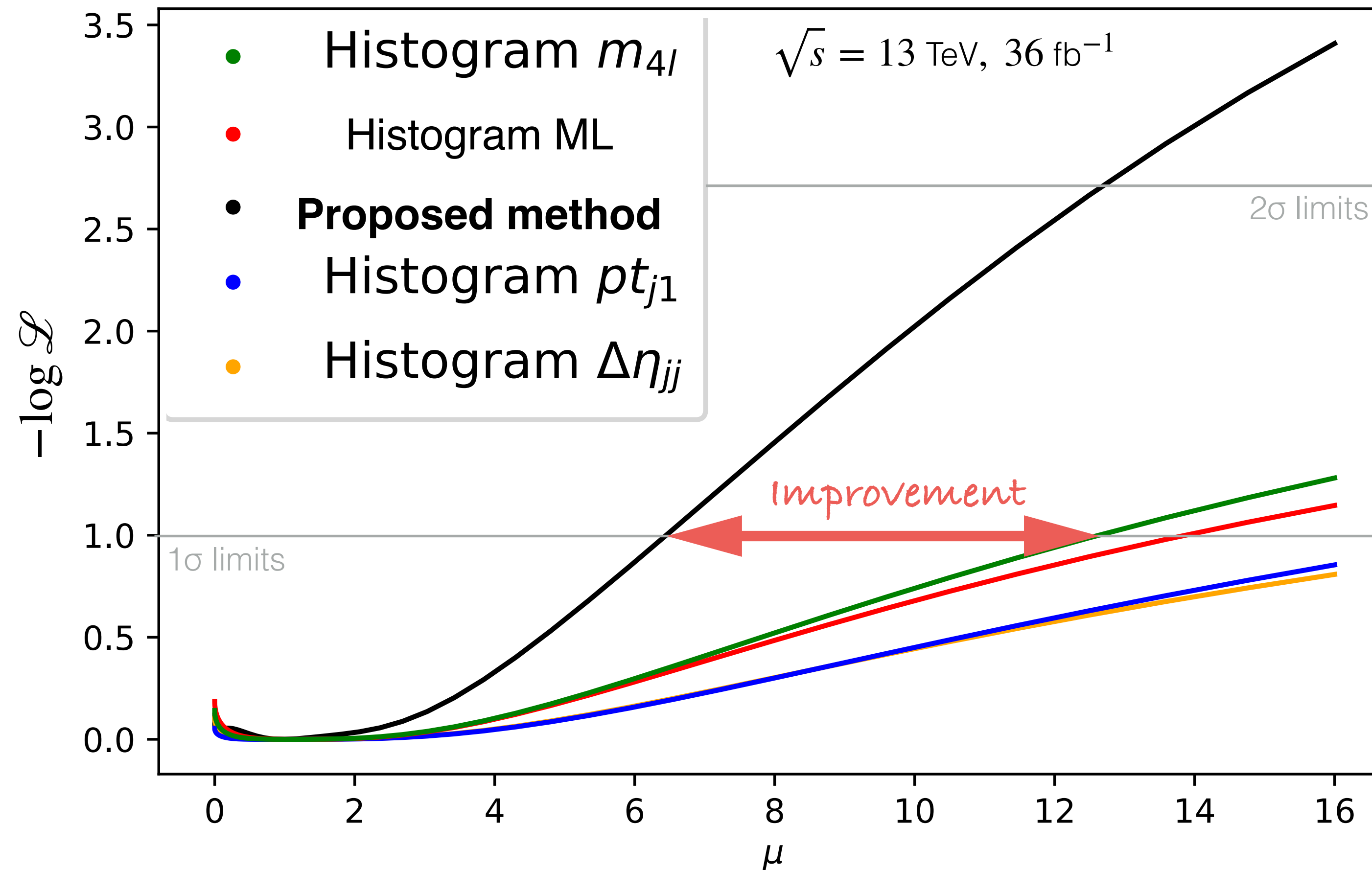
[hal-02971995v3](#) (p172): **Aishik Ghosh**, David Rousseau



(Beyond Standard Model value) $\mu = 4$, without rate

Expected improvement for Standard Model

[hal-02971995v3](#): Aishik Ghosh, David Rousseau



Exciting gains promised!

SM, without rate

Open problems to extend to full ATLAS analysis:

- Robustness: Design and validation
- Systematic Uncertainties: Incorporate them in likelihood (ratio) model
- Neyman Construction: Throwing toys in a per-event analysis

Open problems to extend to full ATLAS analysis:

Solved!



ATLAS CONF Note

ATLAS-CONF-2024-015

28th October 2024



An implementation of Neural Simulation-Based Inference for Parameter Estimation in ATLAS

The ATLAS Collaboration

Neural Simulation-Based Inference (NSBI) is a powerful class of machine learning (ML)-based methods for statistical inference that naturally handles high-dimensional parameter estimation without the need to bin data into low-dimensional summary histograms. Such methods are promising for a range of measurements, including at the Large Hadron Collider (LHC), where no single observable may be optimal to scan over the entire theoretical phase space under consideration, or where binning data into histograms could result in a loss of sensitivity. This work develops an NSBI framework for statistical inference, using neural networks to estimate probability density ratios, which enables the application of NSBI to a full-scale LHC analysis. It incorporates a large number of systematic uncertainties, quantifies the uncertainty coming from finite training statistics, develops a method to construct confidence intervals, and demonstrates a series of intermediate diagnostic checks that can be performed to validate the robustness of the method. As an example, the power and feasibility of the method are demonstrated on simulated data for a simplified version of an off-shell Higgs boson couplings measurement in the four-leptons final states. This NSBI framework is an extension of the standard statistical framework used by LHC experiments and can benefit a large number of physics analyses.

ATLAS-CONF-2024-015
28 October 2024

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Solved!

Open problems to extend to full ATLAS analysis:

Applied on Run2 data, superseding previous ATLAS paper on same data !

Presented at [CHEP 2024](#), [Higgs 2024](#)



ATLAS CONF Note

ATLAS-CONF-2024-015

28th October 2024



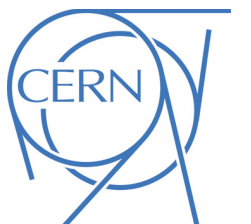
An implementation of Neural Simulation-Based Inference for Parameter Estimation in ATLAS



ATLAS CONF Note

ATLAS-CONF-2024-016

October 31, 2024

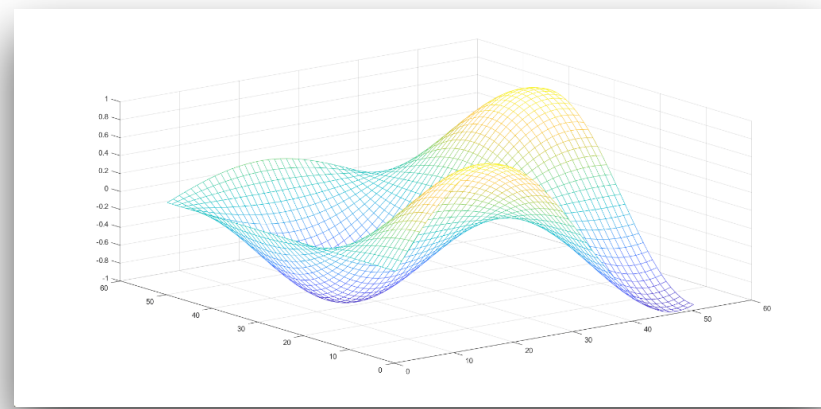


Measurement of off-shell Higgs boson production in the $H^* \rightarrow ZZ \rightarrow 4\ell$ decay channel using a neural simulation-based inference technique with the ATLAS detector at $\sqrt{s} = 13$ TeV

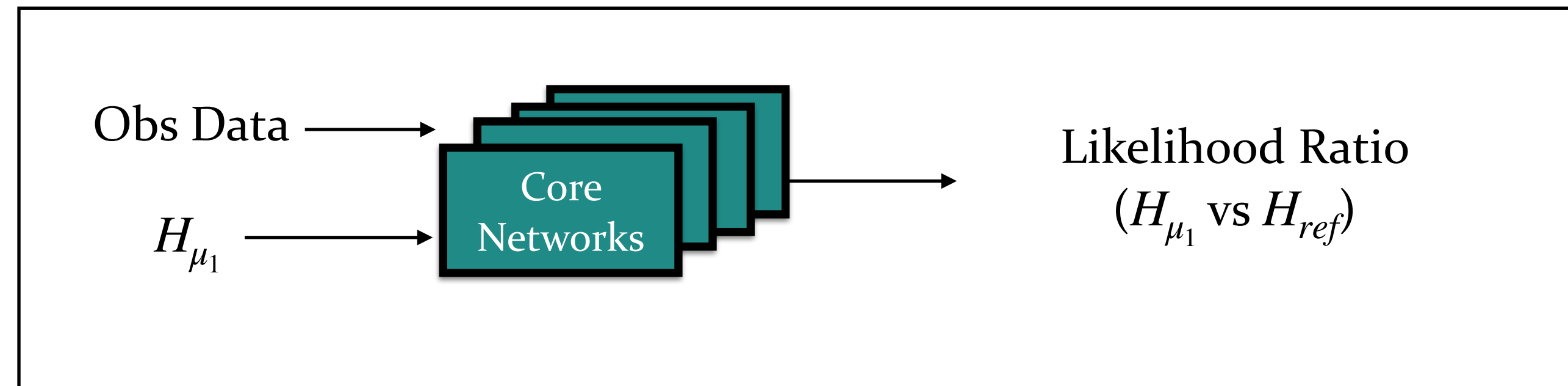
The ATLAS Collaboration

A measurement of off-shell Higgs boson production in the $H^* \rightarrow ZZ \rightarrow 4\ell$ decay channel is presented. The measurement uses the 140 fb^{-1} of integrated luminosity collected by the ATLAS detector during the Run 2 proton-proton collisions of the Large Hadron Collider at $\sqrt{s} = 13$ TeV and supersedes our previous result in this decay channel using the same dataset. The data analysis is performed using a neural simulation based-inference method, which builds per-event likelihood ratios using neural networks. The observed (expected) off-shell Higgs boson production signal strength in the $ZZ \rightarrow 4\ell$ decay channel is $0.87^{+0.75}_{-0.54}$ ($1.00^{+1.04}_{-0.95}$) at 68% CL. The previous result was not able to achieve expected sensitivity to quote a two-sided interval at this CL. The expected plus-side uncertainty is reduced by 10%. The evidence for off-shell Higgs boson production has an observed (expected) significance of 2.5σ (1.3σ) using the $ZZ \rightarrow 4\ell$ decay channel only. The expected significance score is 2.6 times that of our previous result using the same dataset. When combined with our most recent measurement in $ZZ \rightarrow 2\ell 2\nu$ decay channel, the evidence for off-shell Higgs boson production has an observed (expected) significance of 3.7σ (2.4σ). The off-shell measurements are combined with the measurement of on-shell Higgs boson production to obtain constraints on the Higgs boson total width. The observed (expected) value of the Higgs boson width is $4.3^{+2.7}_{-1.9}$ ($4.1^{+3.5}_{-3.4}$) MeV at 68% CL.

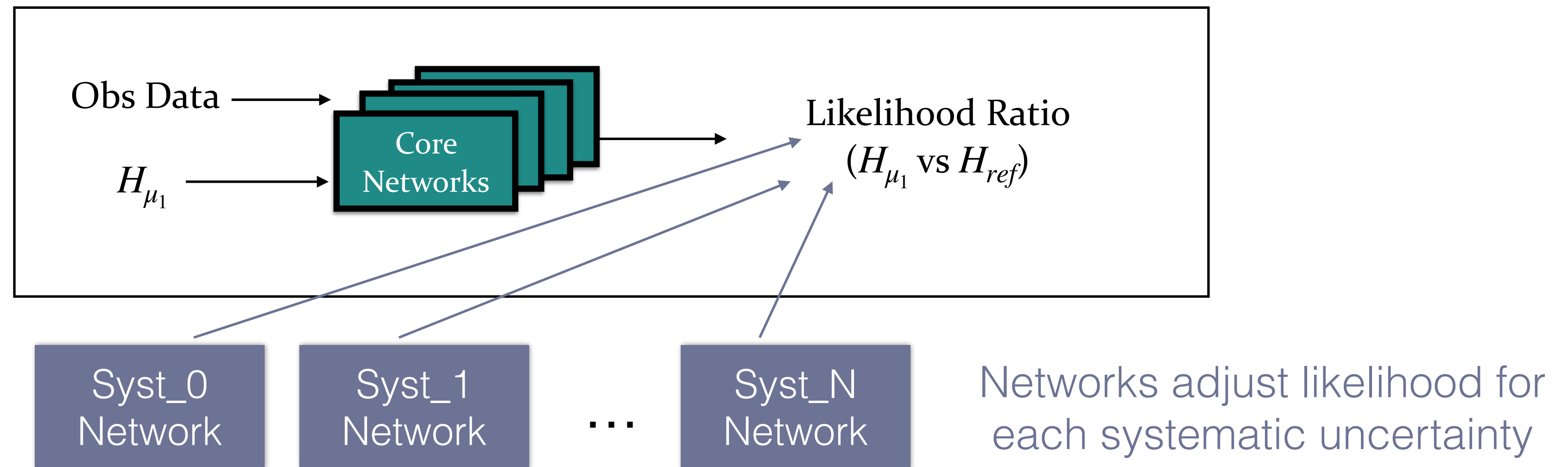
Big picture of full solution developed in ATLAS



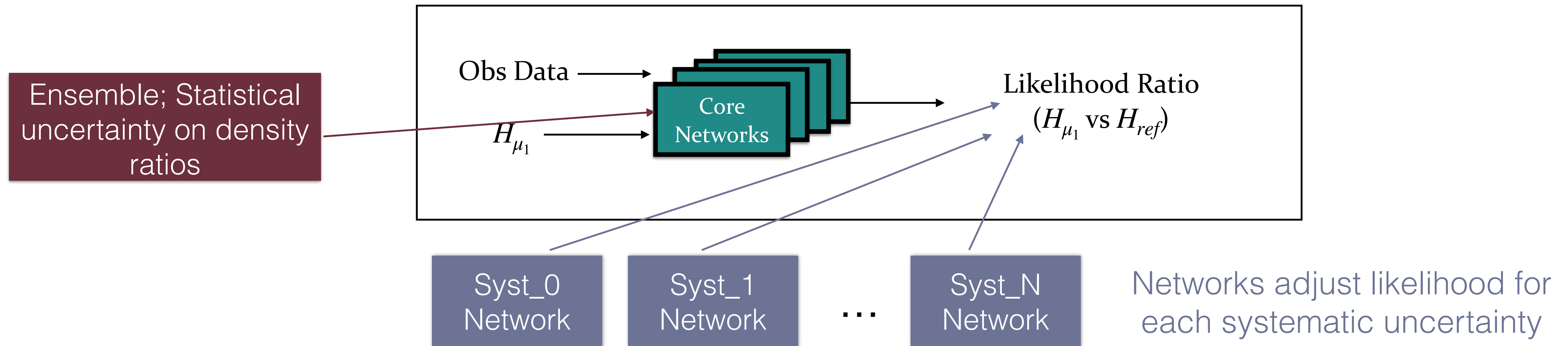
$O(16)$ observables



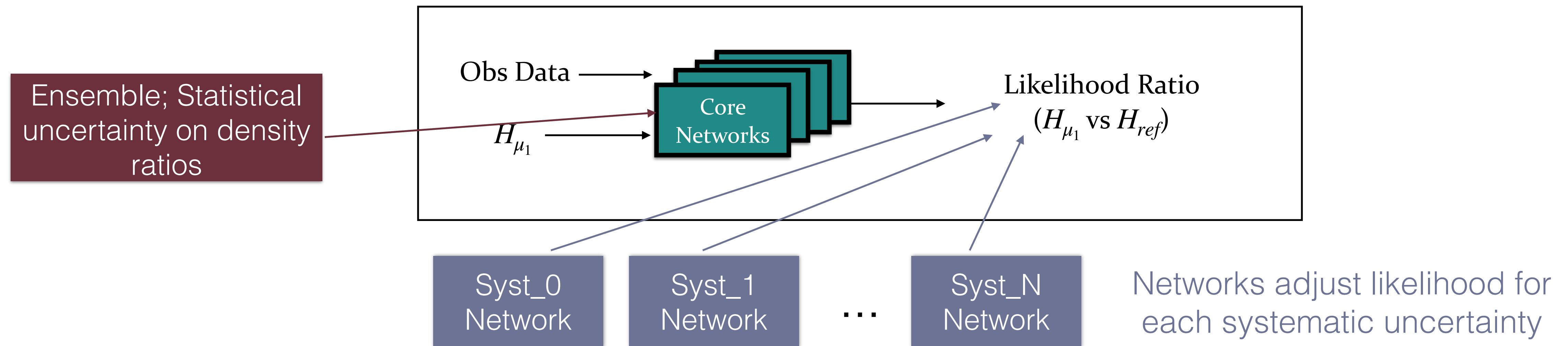
Big picture of full solution developed in ATLAS



Big picture of full solution developed in ATLAS



Big picture of full solution developed in ATLAS



- ◆ Train $O(10^4)$ networks on TensorFlow
- ◆ Computing resources provided by Google, SMU, other HPC clusters
- ◆ Fits with JAX



Open problems to extend to full ATLAS analysis:

- Robustness: Design and validation
- Systematic Uncertainties: Incorporate them in likelihood (ratio) model
- Neyman Construction: Throwing toys in a per-event analysis

Next 2 slides gets a bit technical

Search-Oriented Mixture Model

x_i is one individual event

General Formula

$$p(x_i|\mu) = \frac{1}{\nu(\mu)} \sum_j^{\mathcal{C}} f_j(\mu) \cdot \nu_j p_j(x_i)$$

j runs over different physics process
(Eg. $gg \rightarrow H^* \rightarrow 4l$, $gg \rightarrow ZZ \rightarrow 4l$)

Example use case

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Example use case

$$p_{\text{ggF}}(x|\mu) = \frac{1}{\nu_{\text{ggF}}(\mu)} \left[(\mu - \sqrt{\mu}) \nu_S p_S(x) + \sqrt{\mu} \nu_{\text{SBI}_1} p_{\text{SBI}_1}(x) + (1 - \sqrt{\mu}) \nu_B p_B(x) \right]$$

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Comes from theory model chosen to interpret data

Example use case

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Event rates estimated from simulations

Comes from theory model chosen to interpret data

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Example use case

$$p_{\text{ggF}}(x|\mu) = \frac{1}{\nu_{\text{ggF}}(\mu)} \left[(\mu - \sqrt{\mu}) \nu_S p_S(x) + \sqrt{\mu} \nu_{\text{SBI}_1} p_{\text{SBI}_1}(x) + (1 - \sqrt{\mu}) \nu_B p_B(x) \right]$$

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Reference hypothesis j runs over different physics process
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Estimated using an ensemble of networks

$$\frac{p(x_i|\mu)}{p_{\text{ref}}(x_i)} = \frac{1}{\nu(\mu)} \sum_j^C f_j(\mu) \cdot \nu_j \frac{p_j(x_i)}{p_{\text{ref}}(x_i)}$$

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Comes from theory model chosen to interpret data

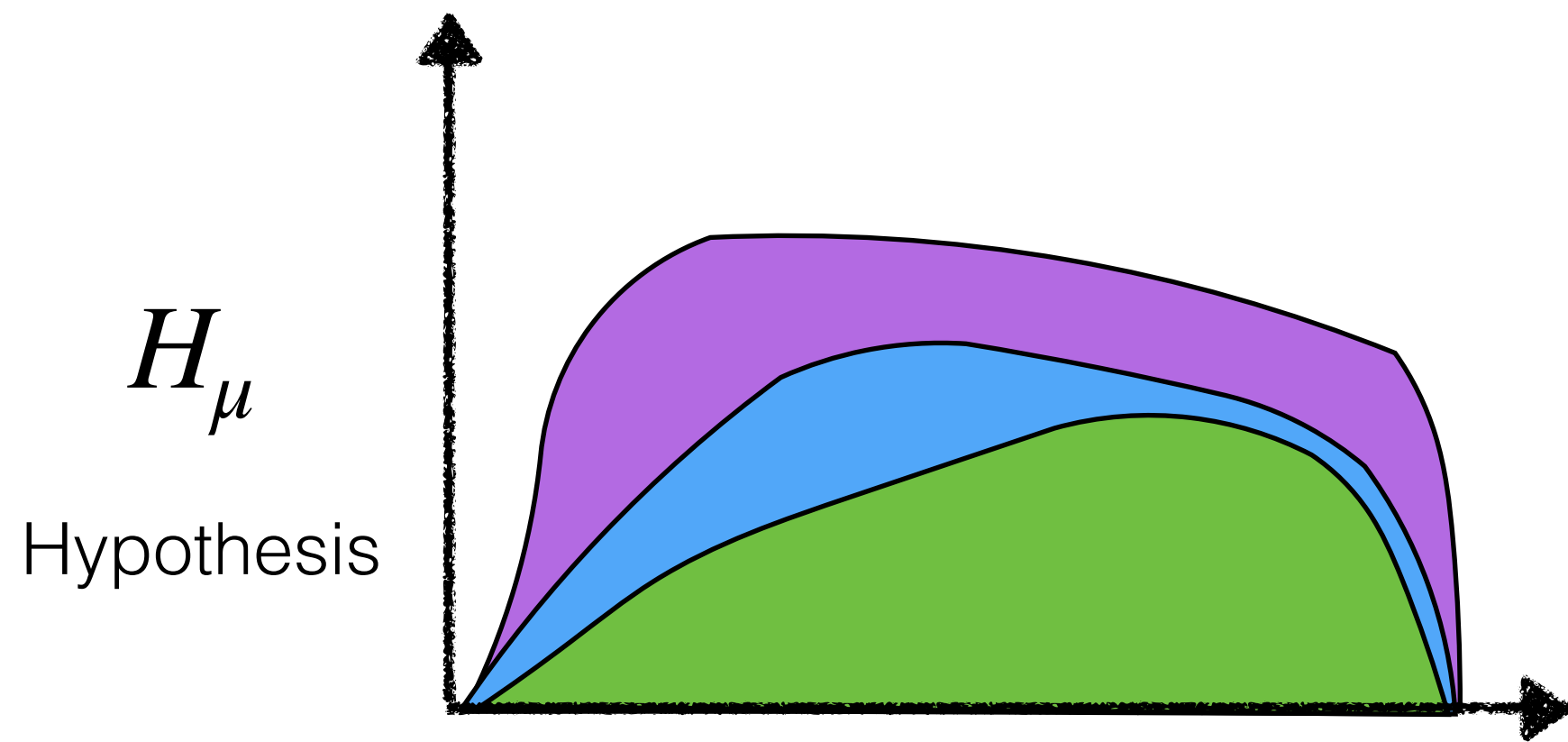
Example use case

$$p_{\text{ggF}}(x|\mu) = \frac{1}{\nu_{\text{ggF}}(\mu)} \left[(\mu - \sqrt{\mu}) \nu_S p_S(x) + \sqrt{\mu} \nu_{\text{SBI}_1} p_{\text{SBI}_1}(x) + (1 - \sqrt{\mu}) \nu_B p_B(x) \right]$$

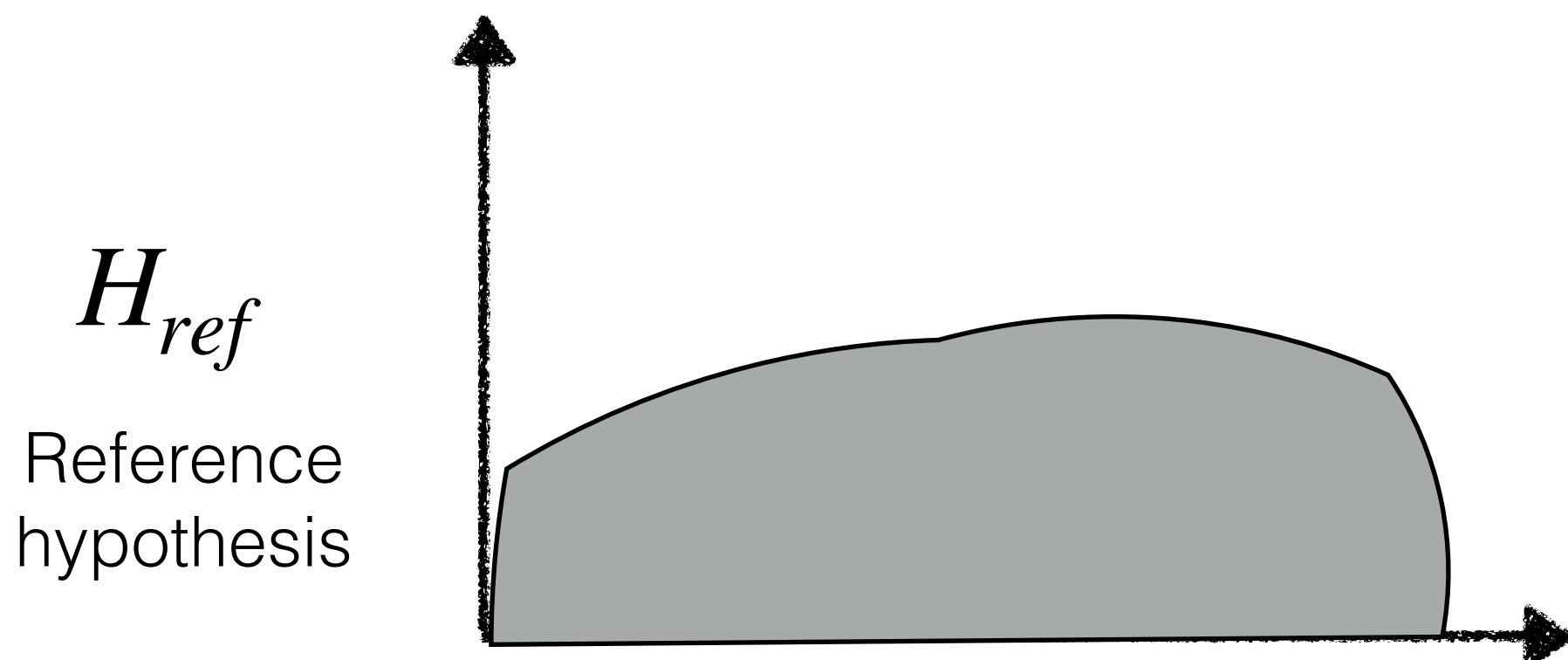
$$\frac{p(x|\mu)}{p_S(x)} = \frac{1}{\nu(\mu)} \left[(\mu - \sqrt{\mu}) \nu_S + \sqrt{\mu} \nu_{\text{SBI}_1} \frac{p_{\text{SBI}_1}(x)}{p_S(x)} + (1 - \sqrt{\mu}) \nu_B \frac{p_B(x)}{p_S(x)} \right]$$

Robust, parameterised classifier without parameterising

H_{ref} : Reference hypothesis



VS

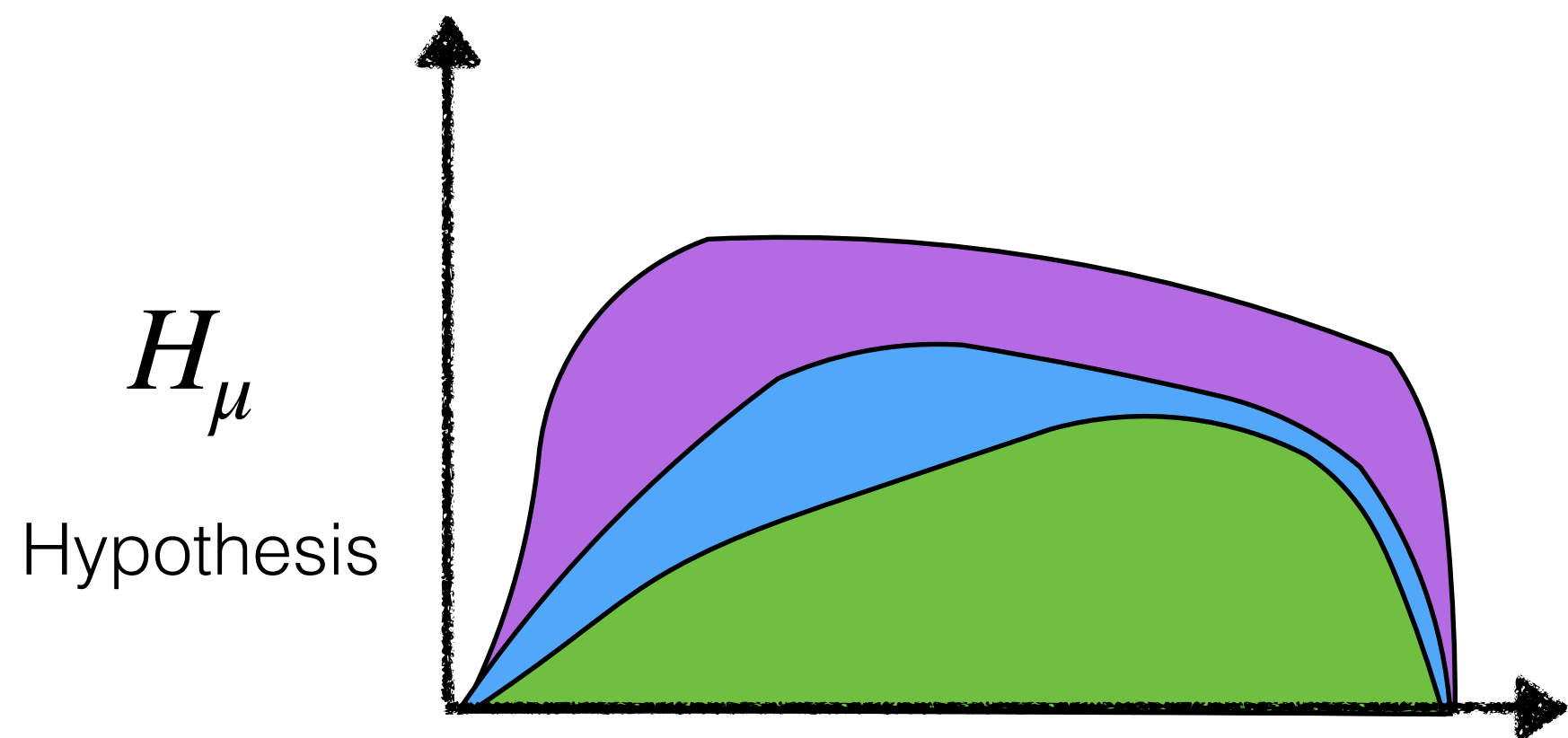


$$\frac{p(x_i|\mu)}{p_{ref}(x_i)} = \frac{1}{v(\mu)} \sum_j^C f_j(\mu) \cdot v_j \frac{p_j(x_i)}{p_{ref}(x_i)}$$

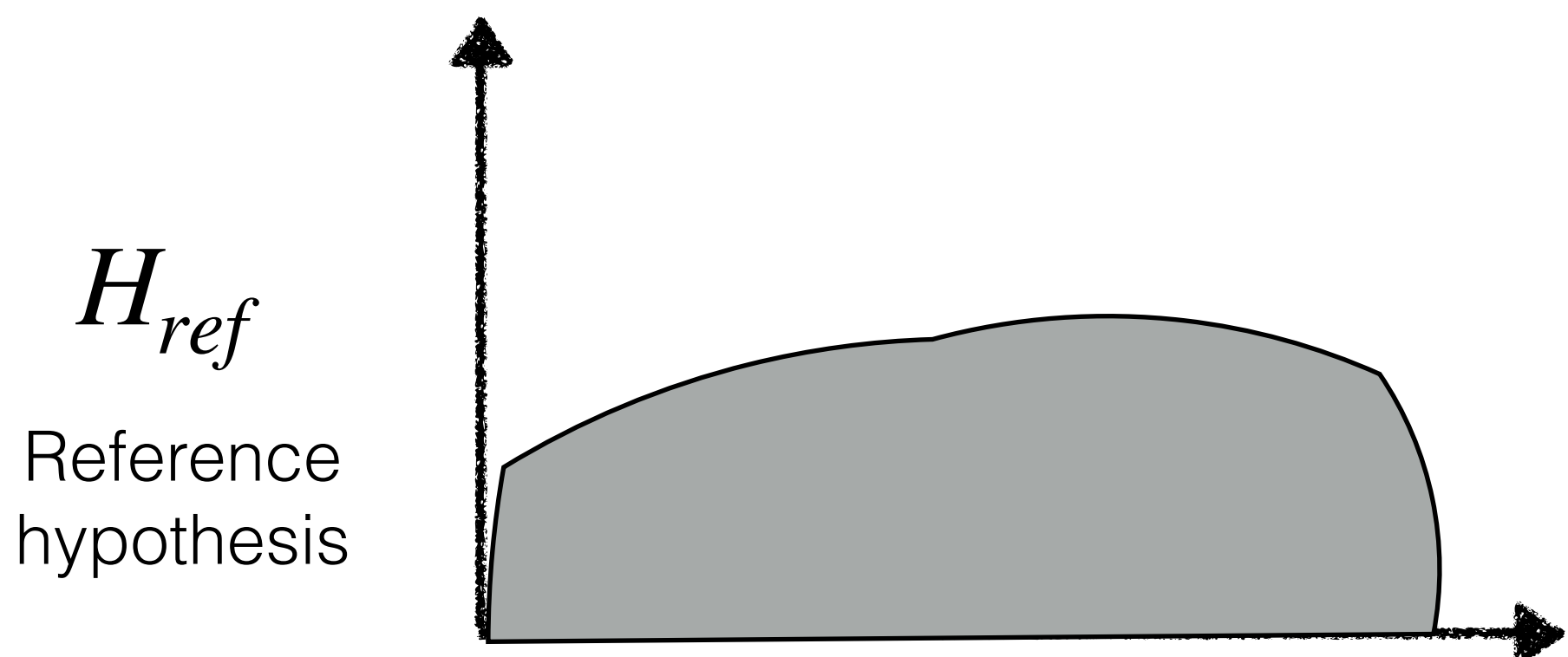
A separate classifier per physics process j
(Eg. $gg \rightarrow H^* \rightarrow 4l$, $gg \rightarrow ZZ \rightarrow 4l$)

Robust, parameterised classifier without parameterising

H_{ref} : Reference hypothesis



VS

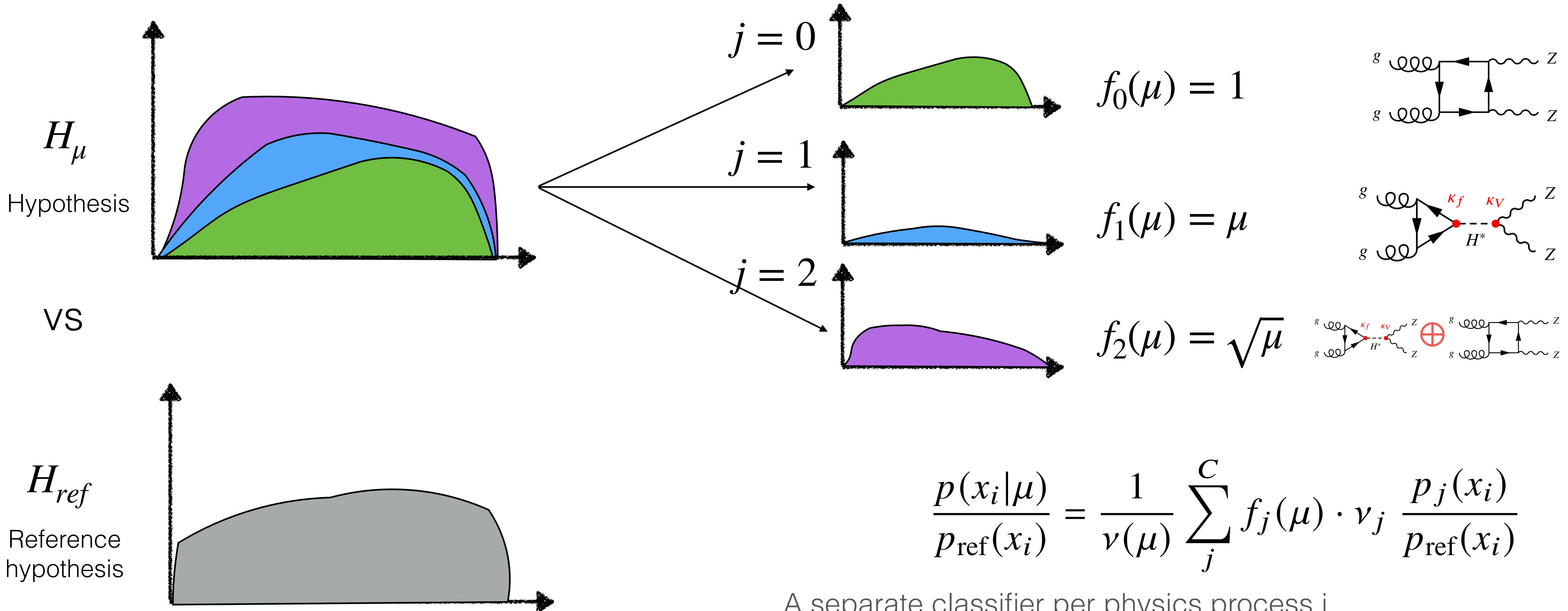


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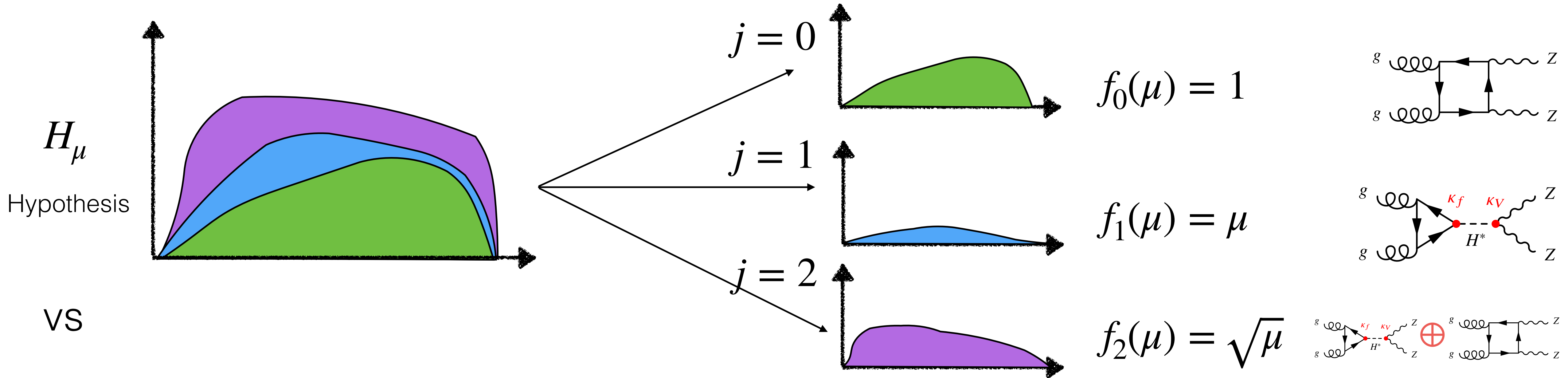
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Robust, parameterised classifier without parameterising

H_{ref} : Reference hypothesis



F_h

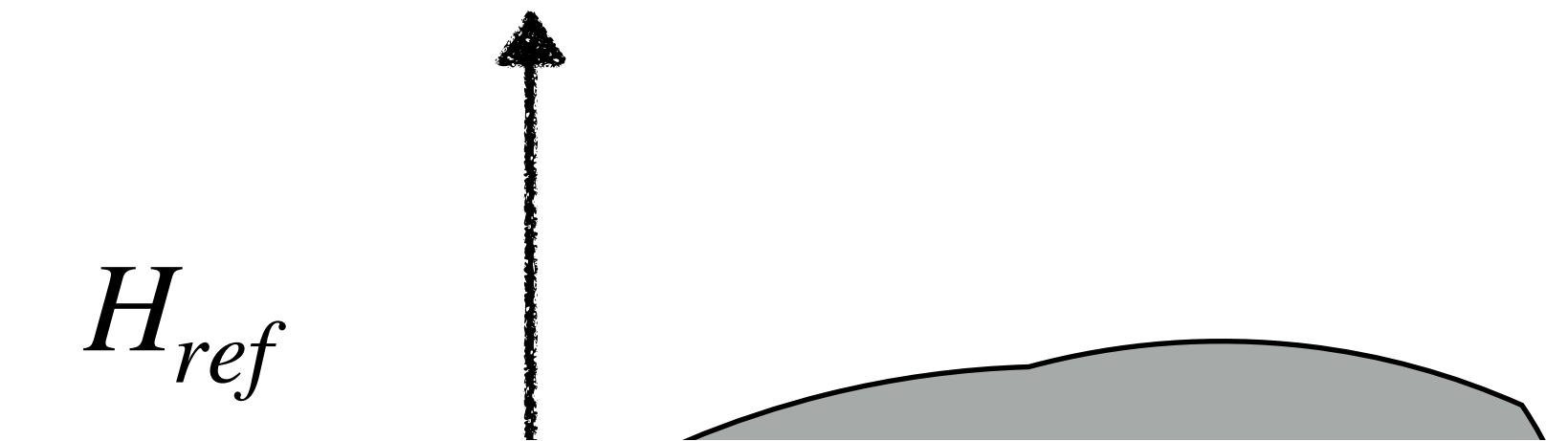
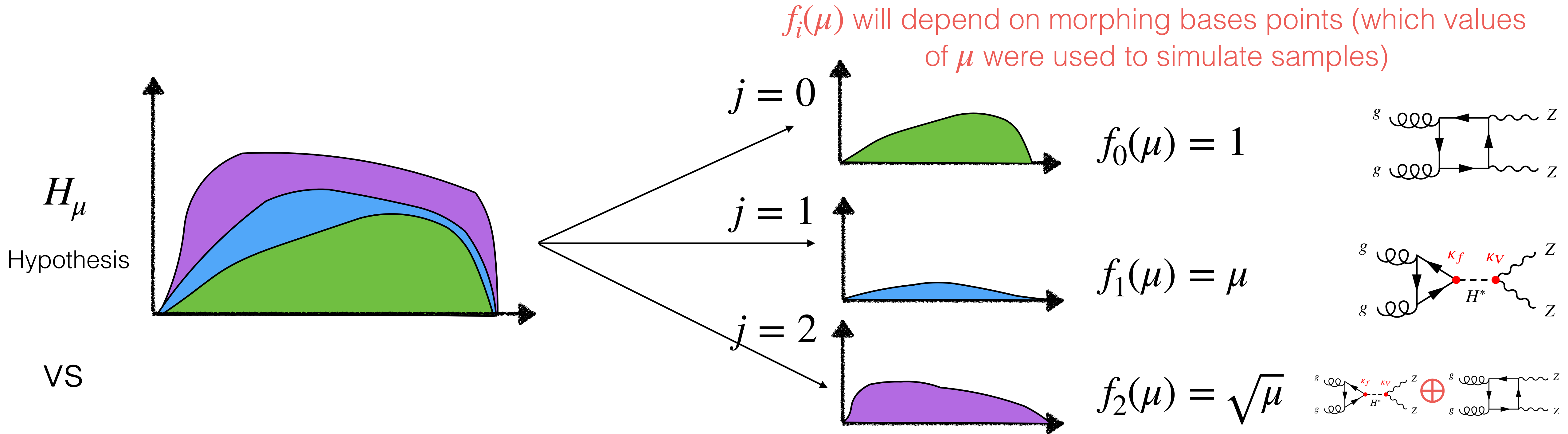
Analytically parameterised in μ , allows to get LR for any hypothesis μ without training parameterised networks !

$$\frac{p(x_i|\mu)}{p_{ref}(x_i)} = \frac{1}{v(\mu)} \sum_j^C f_j(\mu) \cdot v_j \frac{p_j(x_i)}{p_{ref}(x_i)}$$

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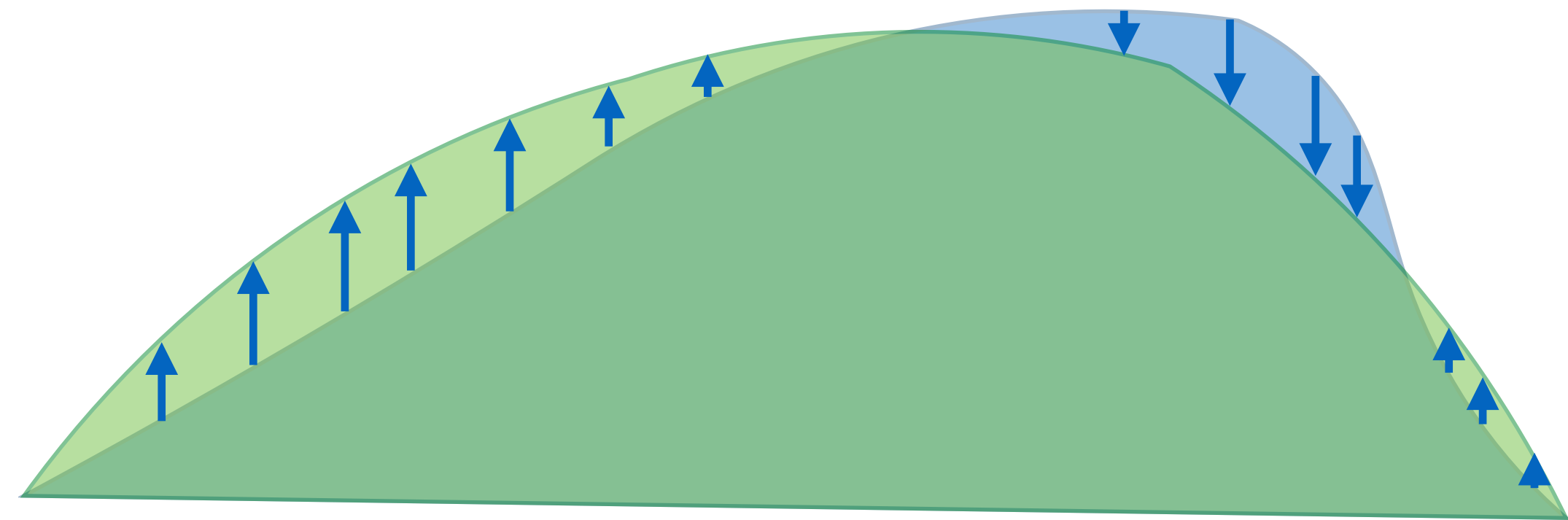
A separate classifier per physics process j
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Open problems to extend to full ATLAS analysis:

- Robustness: Design and validation
- Systematic Uncertainties: Incorporate them in likelihood (ratio) model
- Neyman Construction: Throwing toys in a per-event analysis


Validate quality of LR estimation with re-weighting task

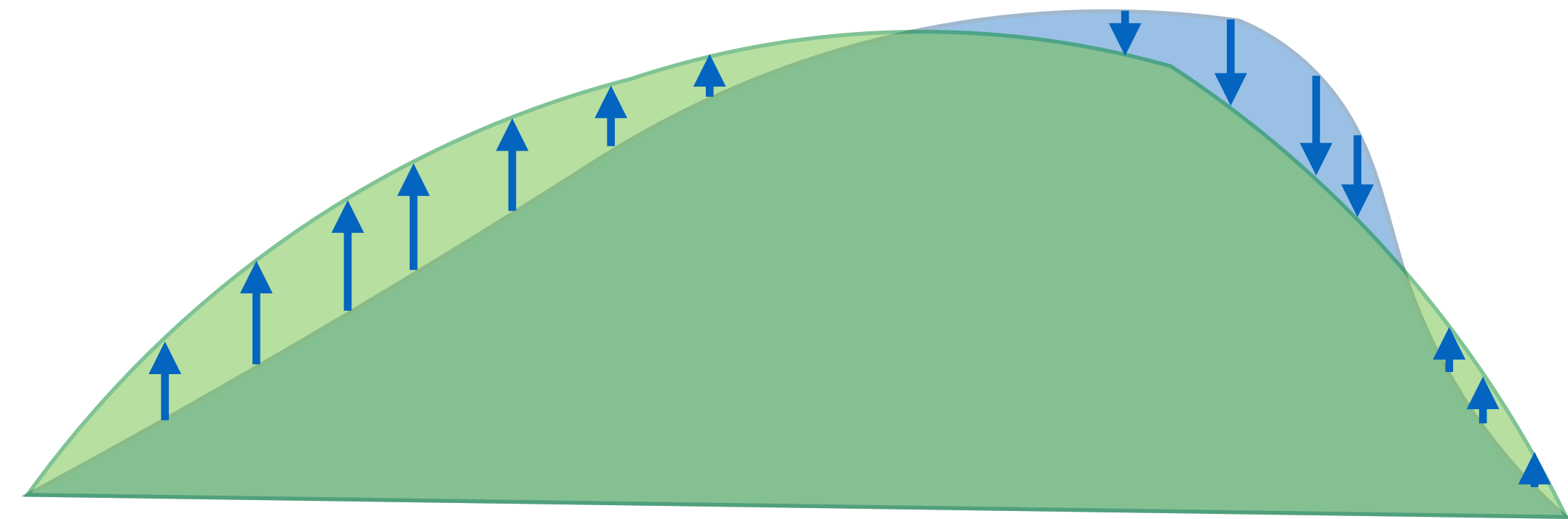
Reweighting: Calculate weights w_i for events x_i in blue sample to match green sample



Validate quality of LR estimation with re-weighting task

Reweighting: Calculate weights w_i for events x_i in **blue sample** to match **green sample**

$$w_i = r(x_i, \mu_0, \mu_1) = \frac{p(x_i | \mu_0)}{p(x_i | \mu_1)}$$




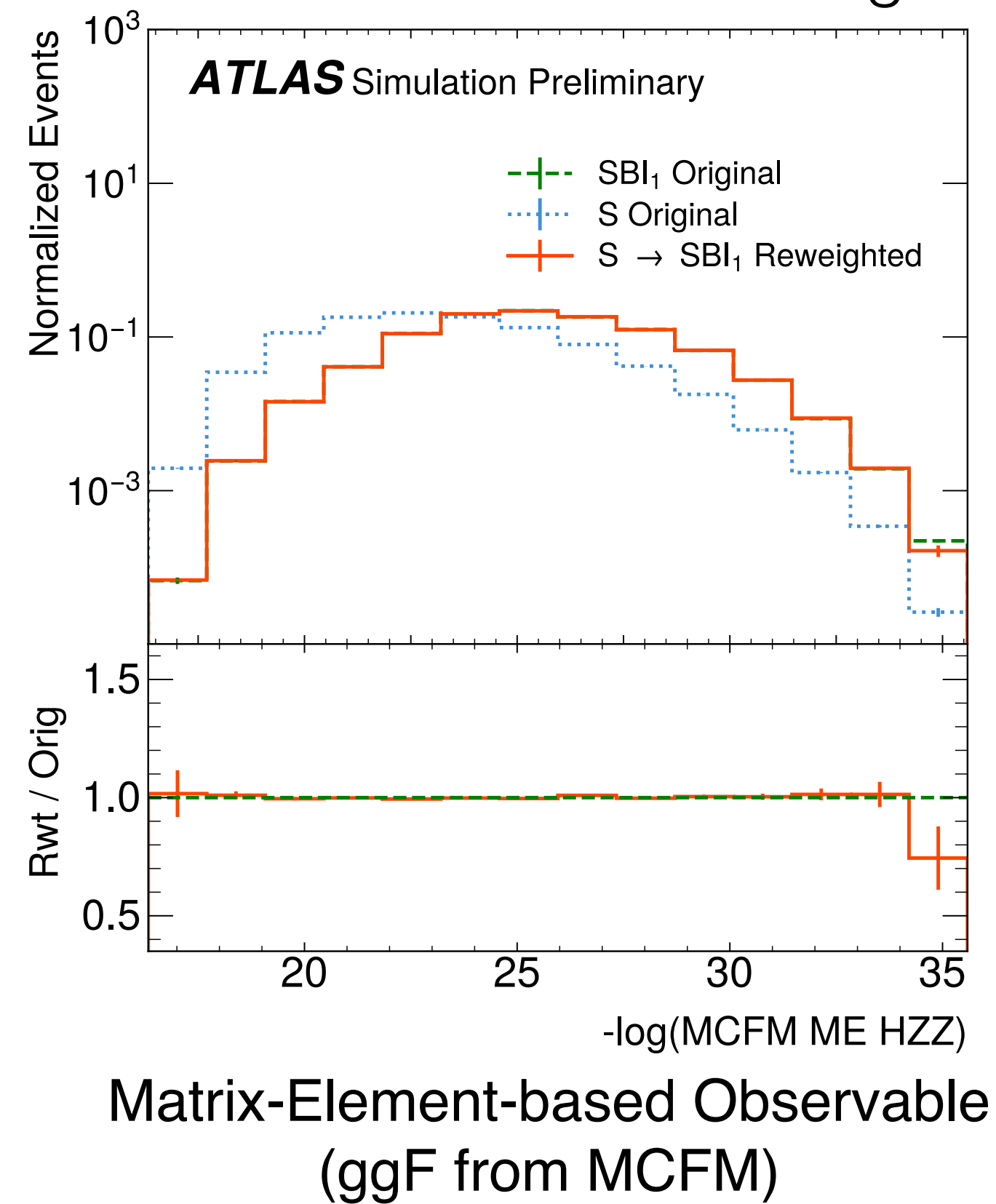
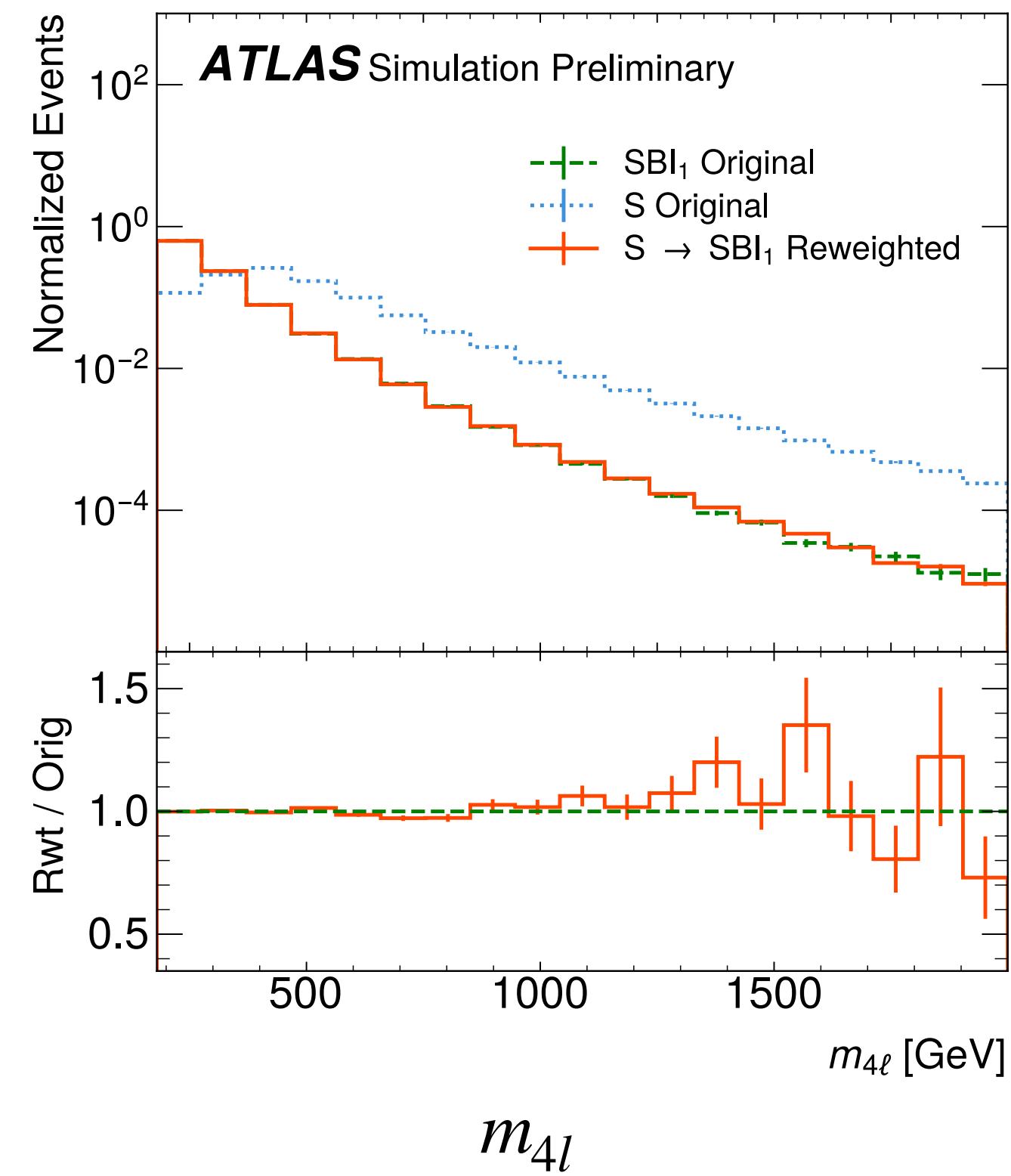
Already estimated using an ensemble of networks

Re-weight closures

Variable used in training

Source
Target
RW

High-level variable
never used in training



High-Dim Classifier Test:

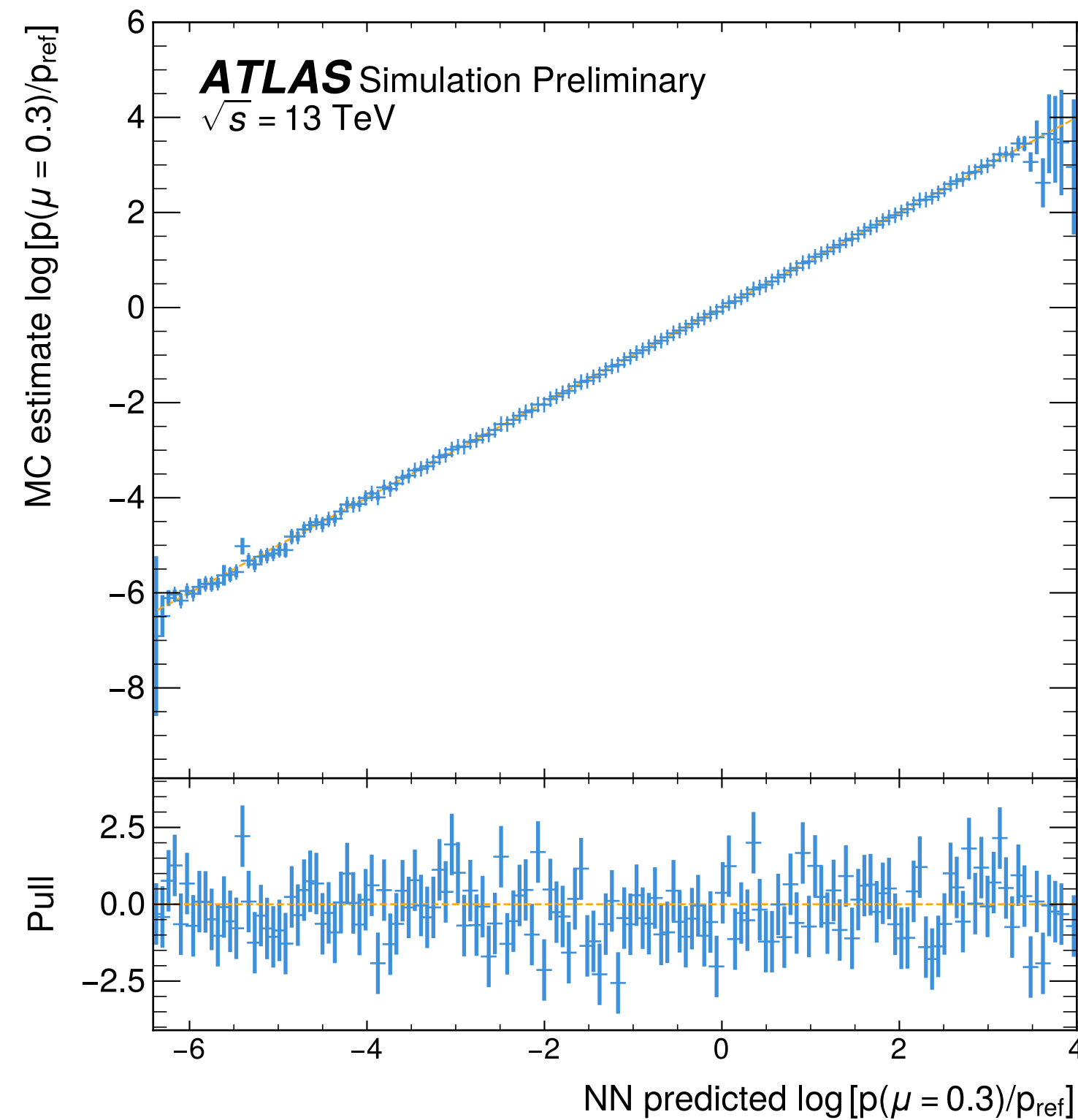
Train independent classifier on RW vs Target,
AUC=0.5 \Rightarrow LRs well estimated

Calibration curves of probability density ratios

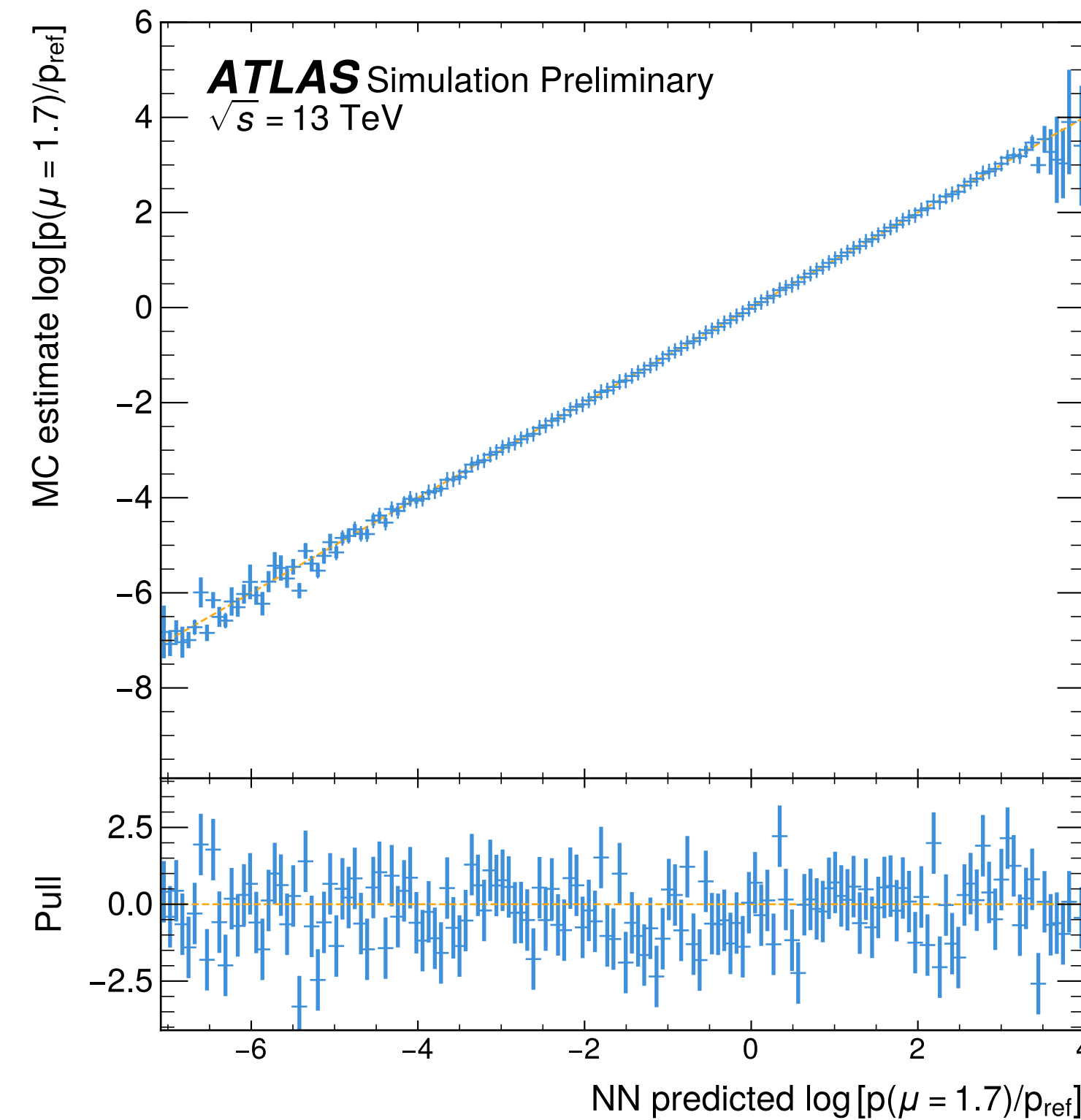
$$\frac{p_{\mu=0.3}(x_i)}{p_{ref}(x_i)}$$

$$\frac{p_{\mu=1.7}(x_i)}{p_{ref}(x_i)}$$

Binned estimate

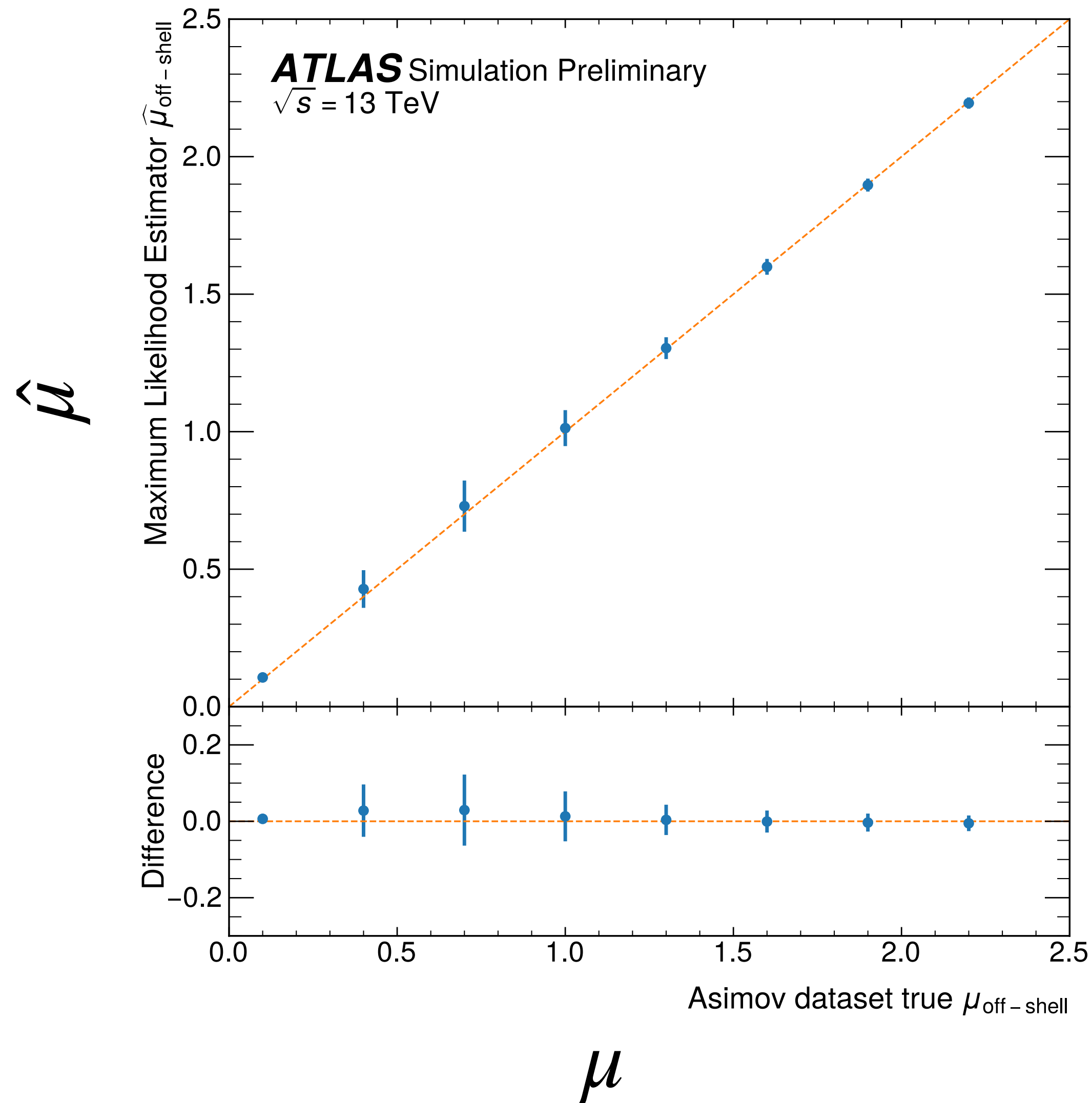


Ensemble prediction



Ensemble prediction

Testing full analysis on samples from different values of μ



No bias: Method recovers correct value of μ on average

(Correct value when tested on the median 'Asimov dataset')

And many more diagnostics (see [backup](#))

Open problems to extend to full ATLAS analysis:

- ✓ Robustness: Design and validation
- ▶ Systematic Uncertainties: Incorporate them in likelihood (ratio) model
- Neyman Construction: Throwing toys in a per-event analysis

Systematic uncertainties

Experimental uncertainties:

Eg. Inaccuracies in the calibration of our detector

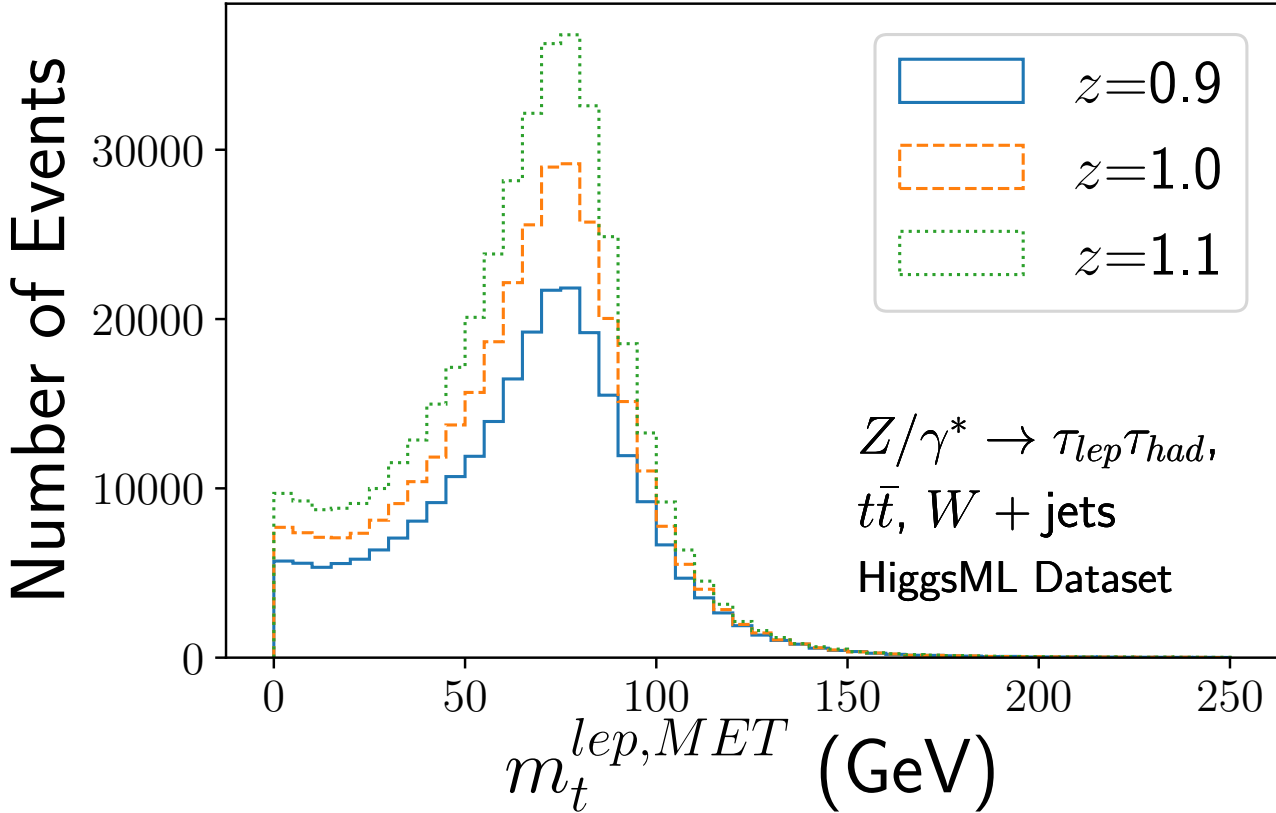


Image: arXiv:2105.08742

Theory uncertainties:

Eg. Inability to compute QFT to infinite order

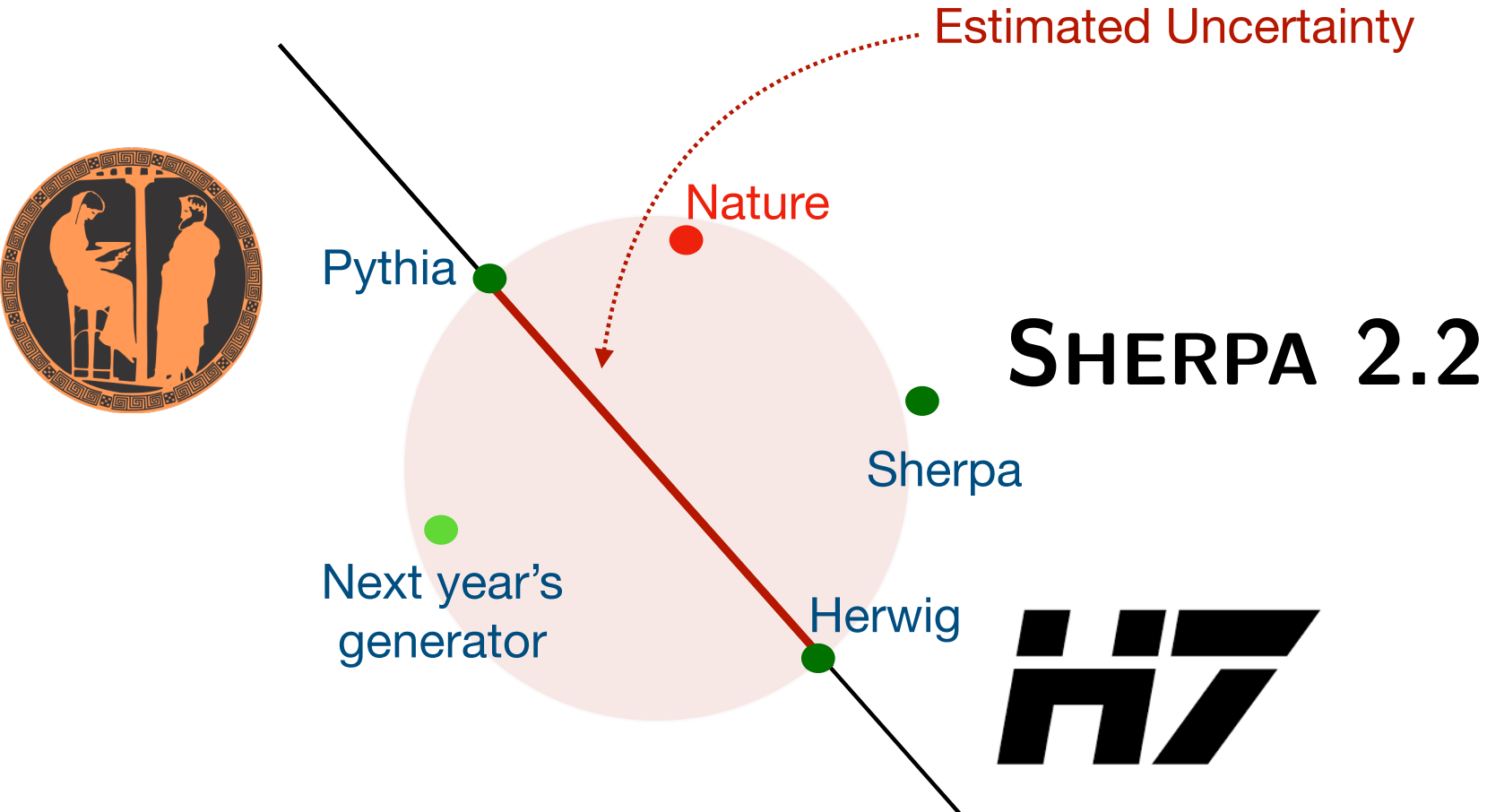


Image: arXiv:2109.08159

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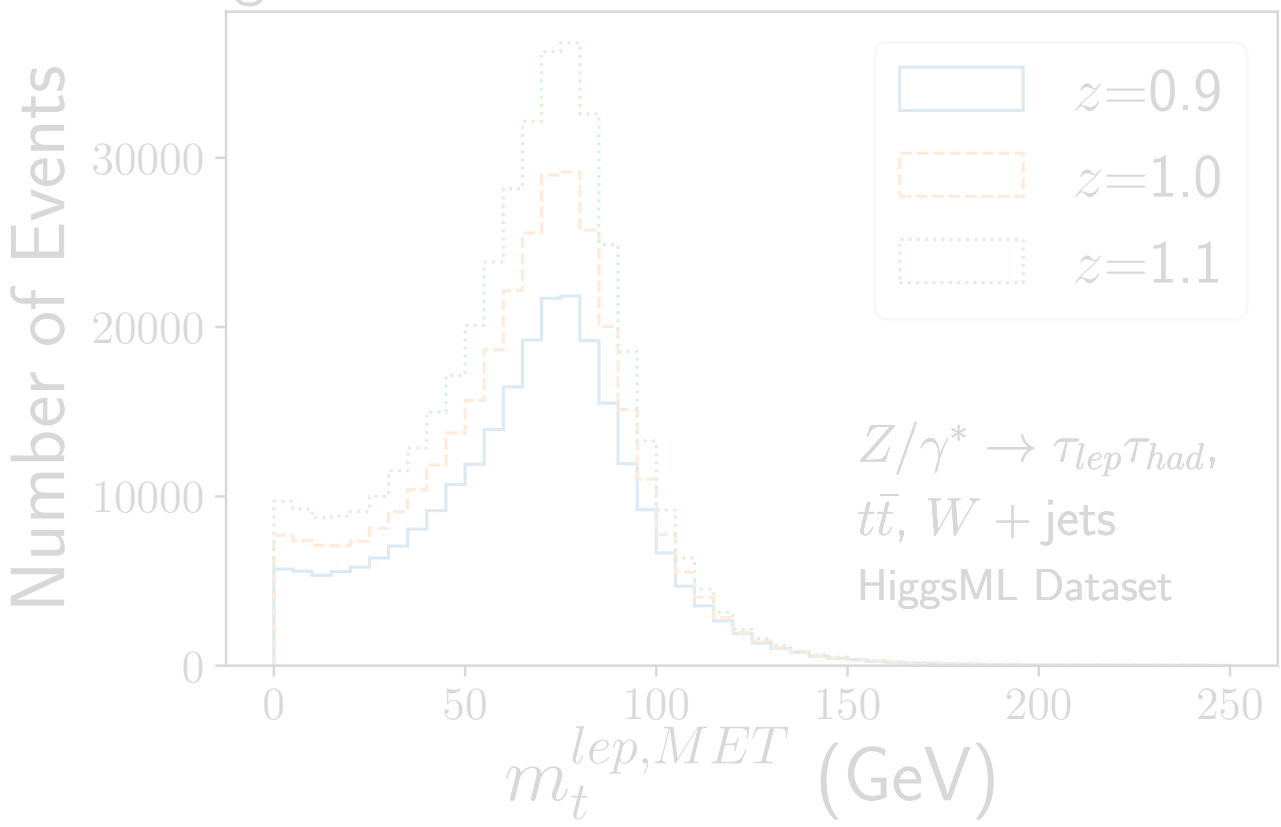


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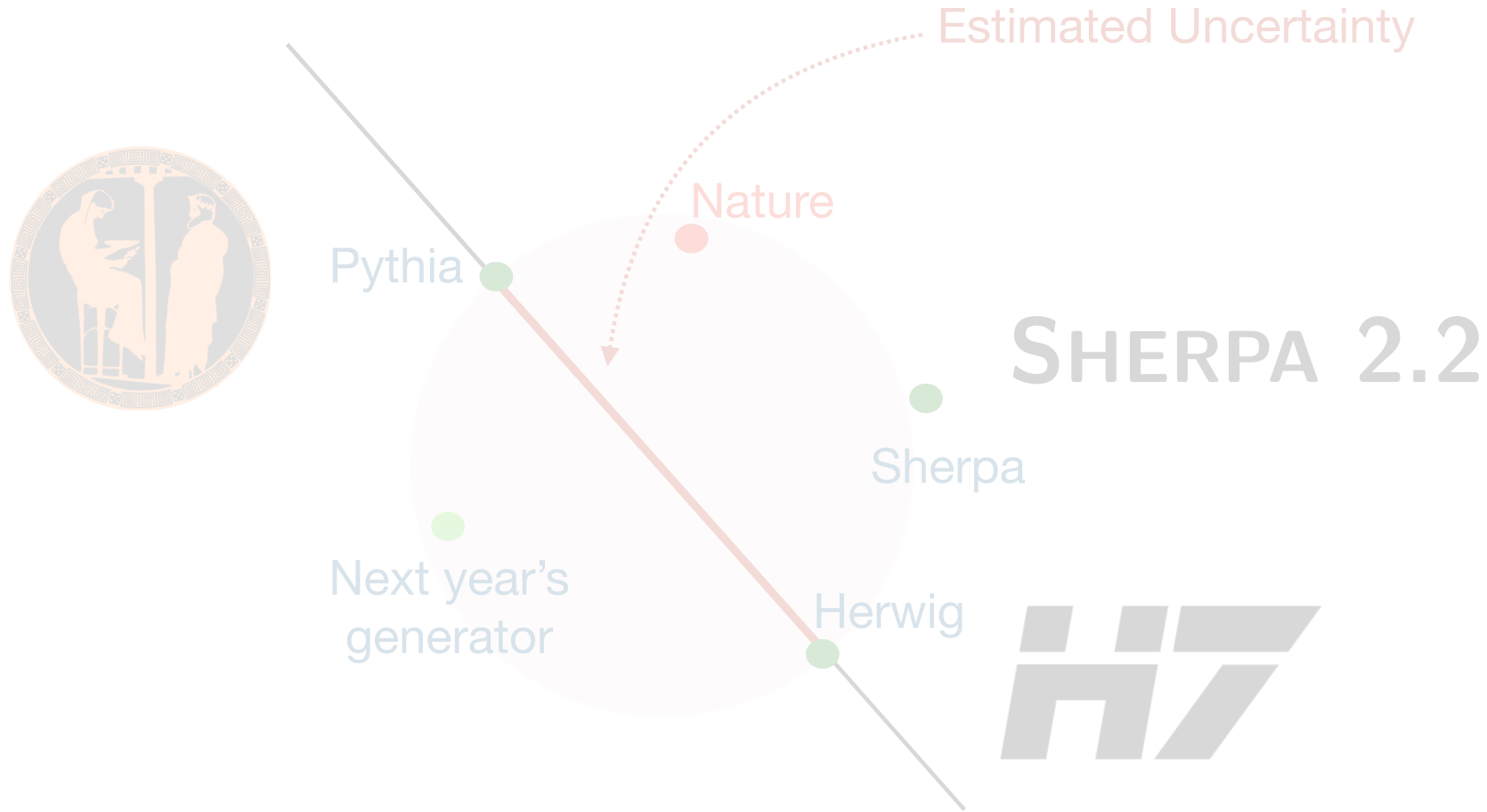
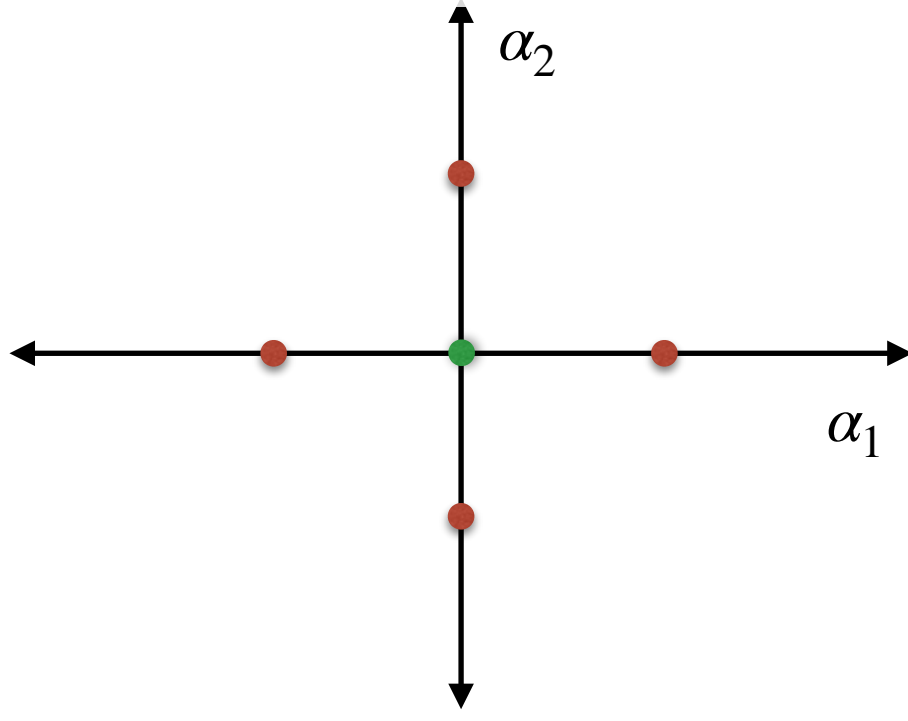


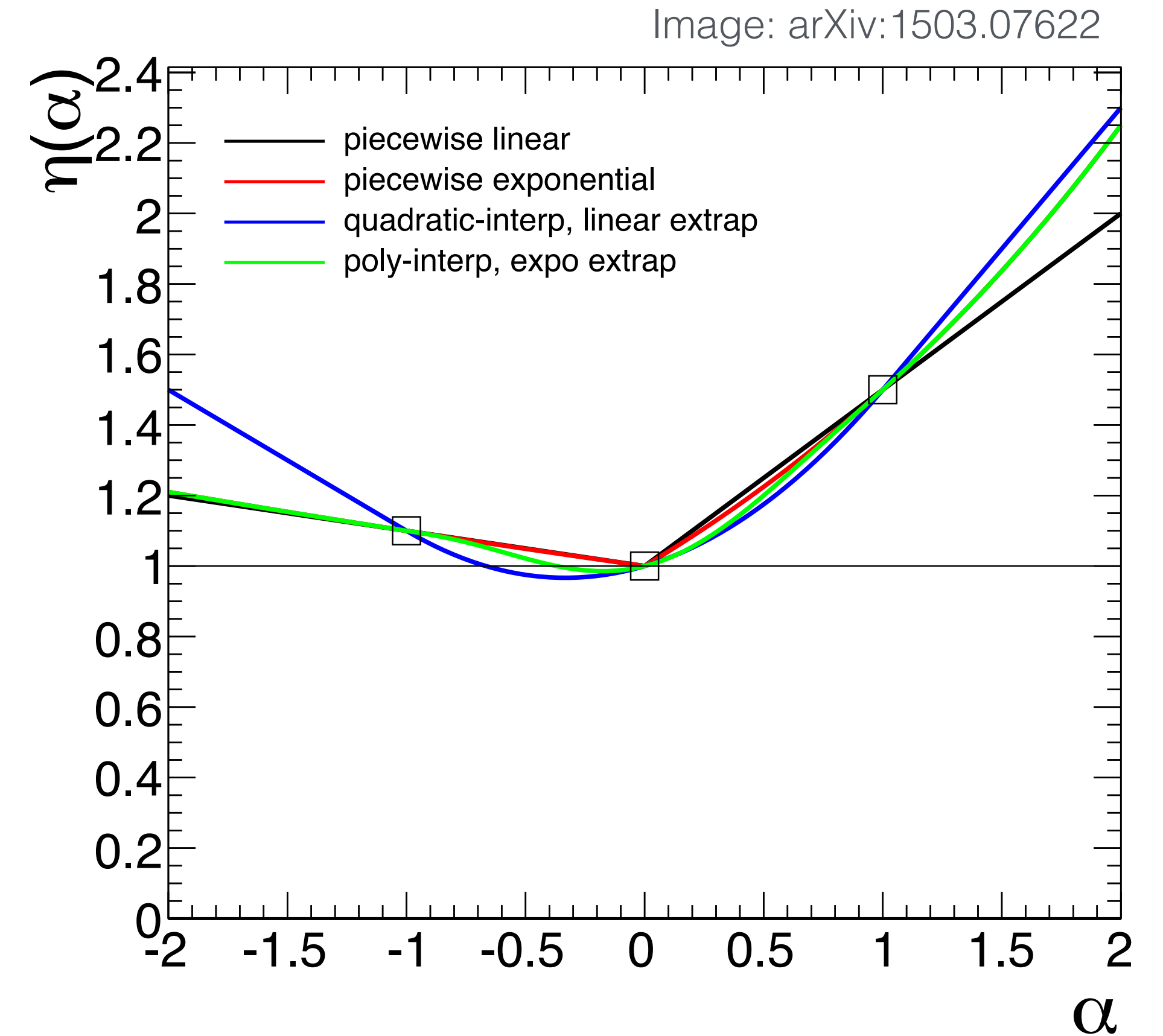
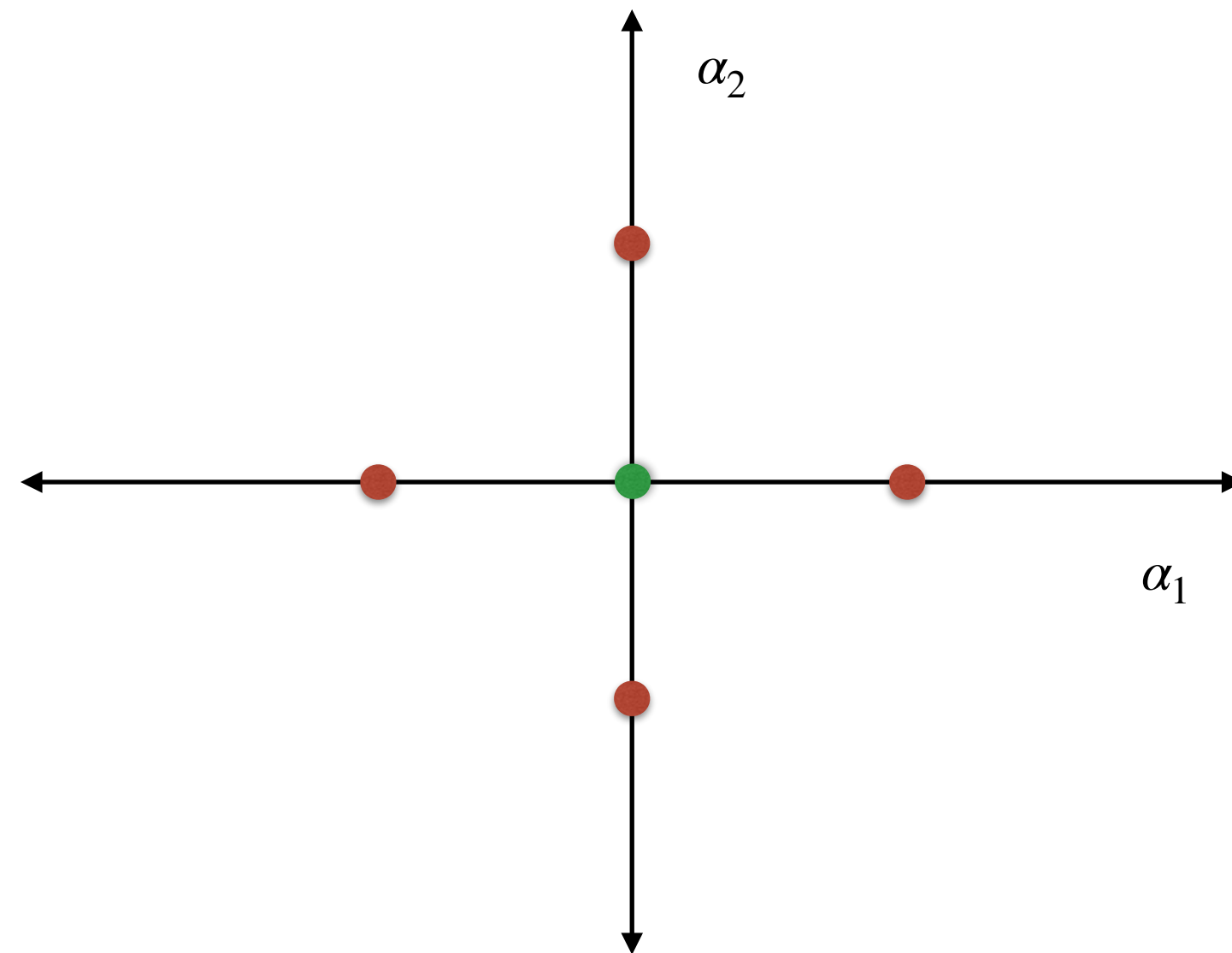
Image: arXiv:2109.08159

- We only have simulations at 3 variations of each nuisance parameter α_k



Known interpolation strategies

See formula used in backup

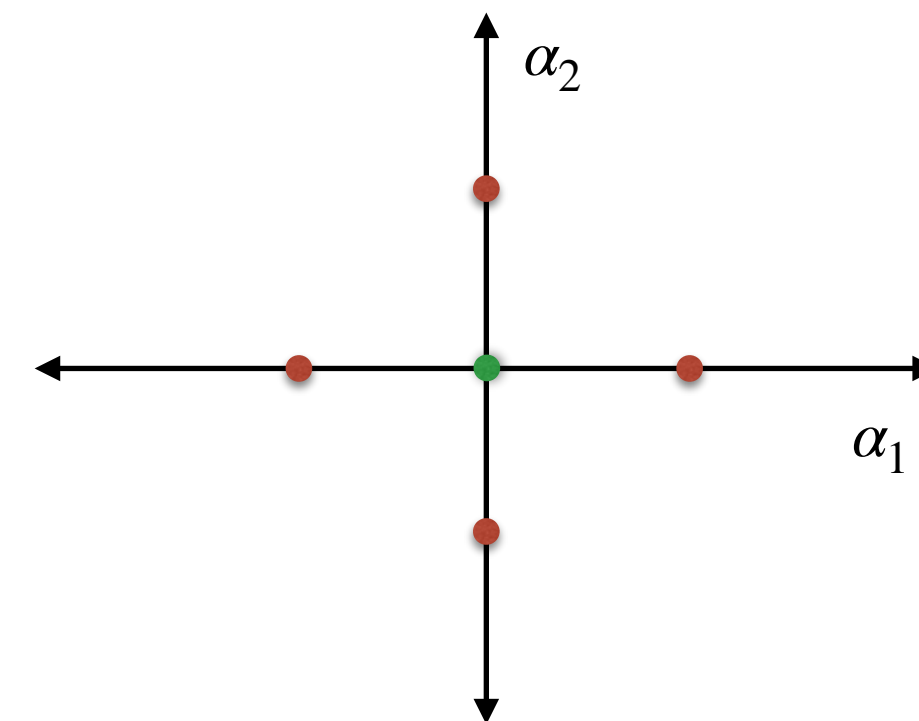


⇒ Combine these traditional interpolation with neural network estimation of per-event likelihood ratios

Probability density ratio including nuisance parameters (α)

x_i is one individual event

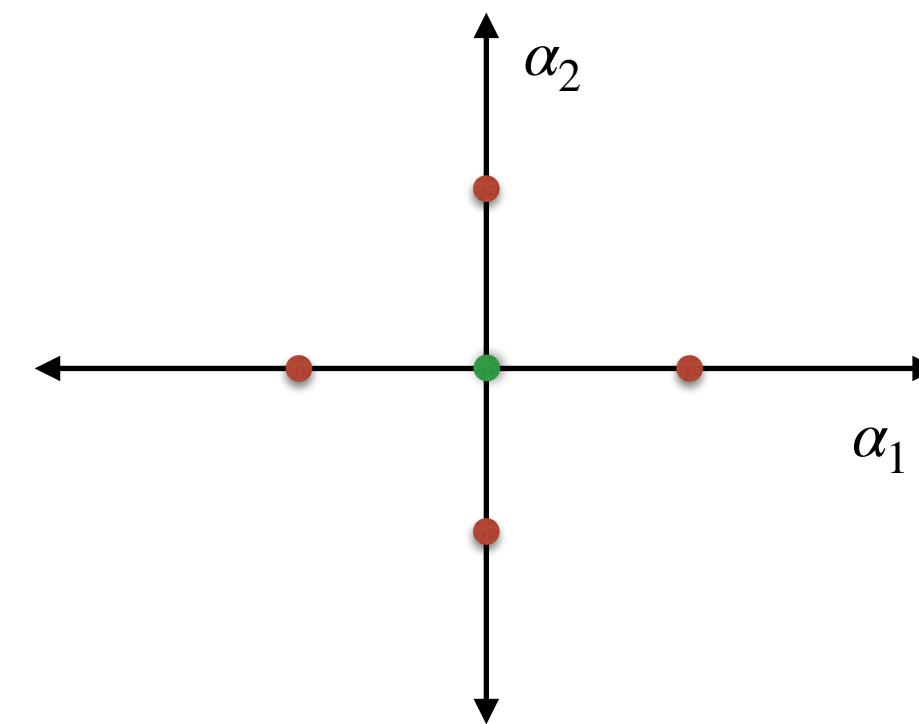
$$\frac{p(x_i | \mu, \alpha)}{p_{ref}(x_i)} =$$



Probability density ratio including nuisance parameters (α)

x_i is one individual event

$$\frac{p(x_i | \mu, \alpha)}{p_{ref}(x_i)} = \frac{1}{\nu(\mu, \alpha)} \sum_j^C f_j(\mu) \cdot \nu_j \cdot \frac{p_j(x_i)}{p_{ref}(x_i)} \cdot \prod_k^{N_{syst}} G_j(\alpha_k) \cdot g_j(x_i, \alpha_k)$$



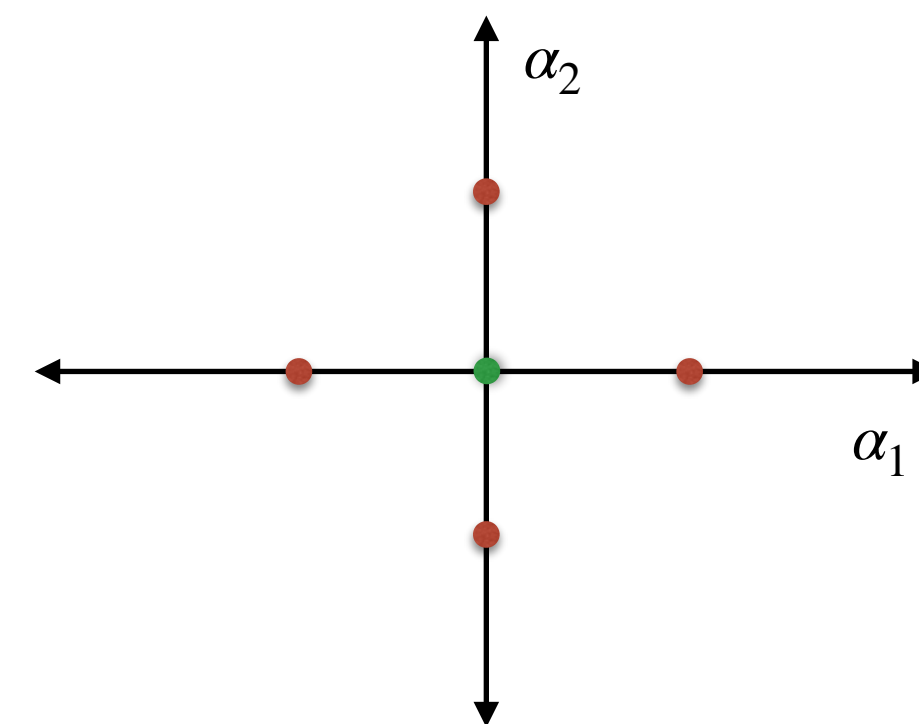
$$g_j(x_i, \alpha_k) = \frac{p_j(x_i, \alpha_k)}{p_j(x_i)}$$

Probability density ratio including nuisance parameters (α)

x_i is one individual event

$$\frac{p(x_i | \mu, \alpha)}{p_{ref}(x_i)} = \frac{1}{\nu(\mu, \alpha)} \sum_j^C \left(f_j(\mu) \cdot \nu_j \cdot \frac{p_j(x_i)}{p_{ref}(x_i)} \right) \cdot \prod_k^{N_{syst}} G_j(\alpha_k) \cdot g_j(x_i, \alpha_k)$$

We have this already



$$g_j(x_i, \alpha_k) = \frac{p_j(x_i, \alpha_k)}{p_j(x_i)}$$

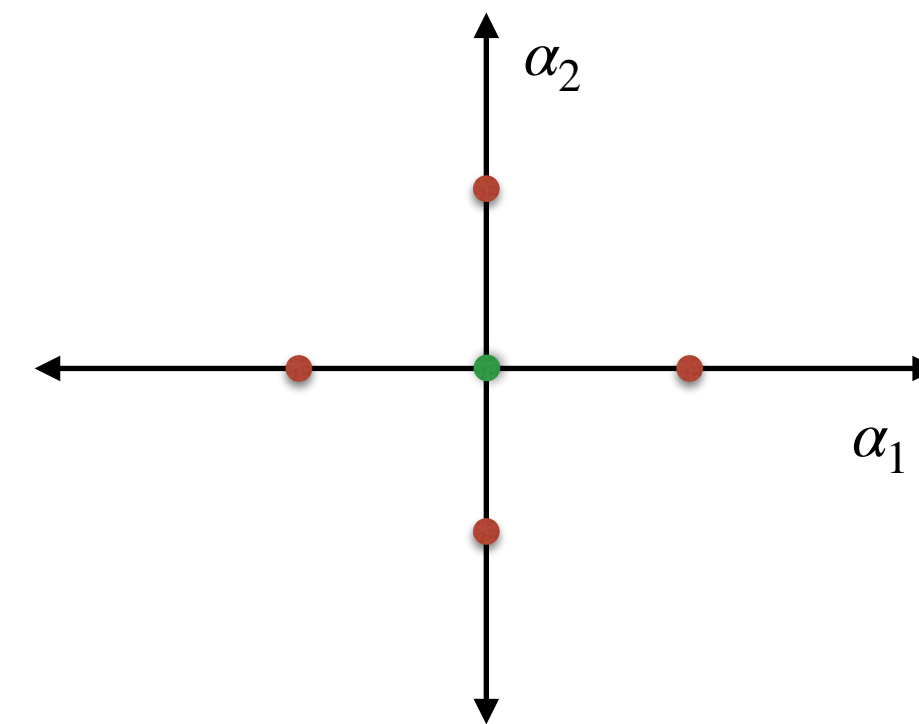
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We have this already

Estimate from simulations and existing interpolation methods



$$g_j(x_i, \alpha_k) = \frac{p_j(x_i, \alpha_k)}{p_j(x_i)}$$

Probability density ratio including nuisance parameters (α)

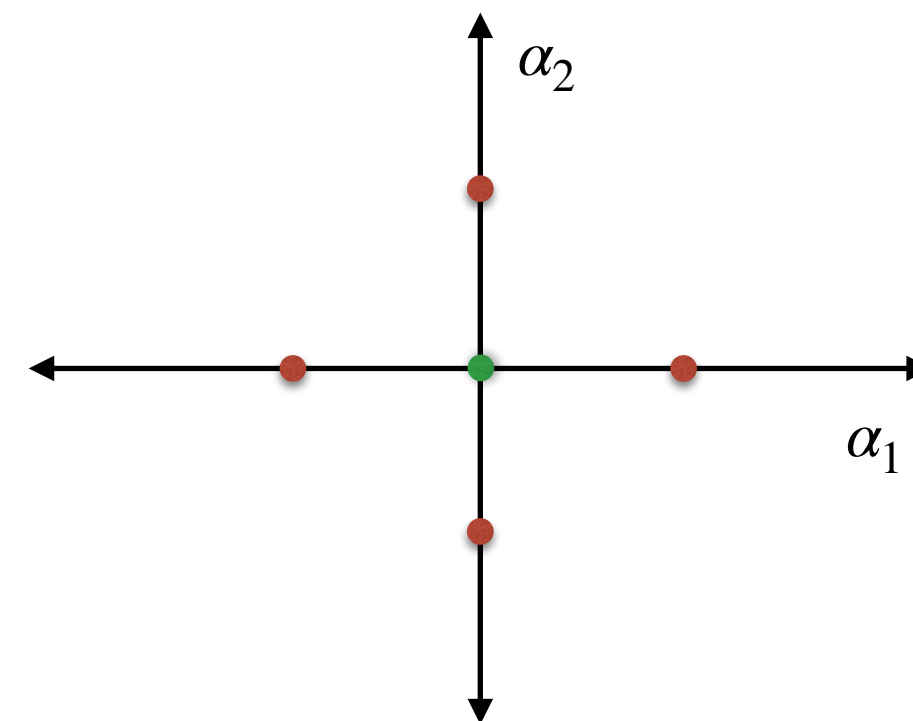
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We have this already

Per-event terms estimated using another ensemble of networks and interpolation methods

Estimate from simulations and existing interpolation methods



$$g_j(x_i, \alpha_k) = \frac{p_j(x_i, \alpha_k)}{p_j(x_i)}$$

Final test statistic

x_i is one individual event

$$\frac{L_{\text{full}}(\mu, \alpha | \mathcal{D})}{L_{\text{ref}}(\mathcal{D})} = \text{Pois}(N_{\text{data}} | \nu(\mu, \alpha)) \prod_i^{N_{\text{data}}} \frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)} \prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$$

Final test statistic

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From previous slide

Final test statistic

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From previous slide

Prod over events

Final test statistic

x_i is one individual event

$$\frac{L_{\text{full}}(\mu, \alpha | \mathcal{D})}{L_{\text{ref}}(\mathcal{D})} = \text{Pois}(N_{\text{data}} | \nu(\mu, \alpha)) \prod_i^{N_{\text{data}}} \frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)} \prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$$

Rate term

Prod over events

From previous slide

Final test statistic

x_i is one individual event

$$\frac{L_{\text{full}}(\mu, \alpha | \mathcal{D})}{L_{\text{ref}}(\mathcal{D})} = \text{Pois}(N_{\text{data}} | \nu(\mu, \alpha)) \prod_i^{N_{\text{data}}} \frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)} \prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$$

Rate term

Prod over events

From previous slide

Constrain term

Final test statistic

x_i is one individual event

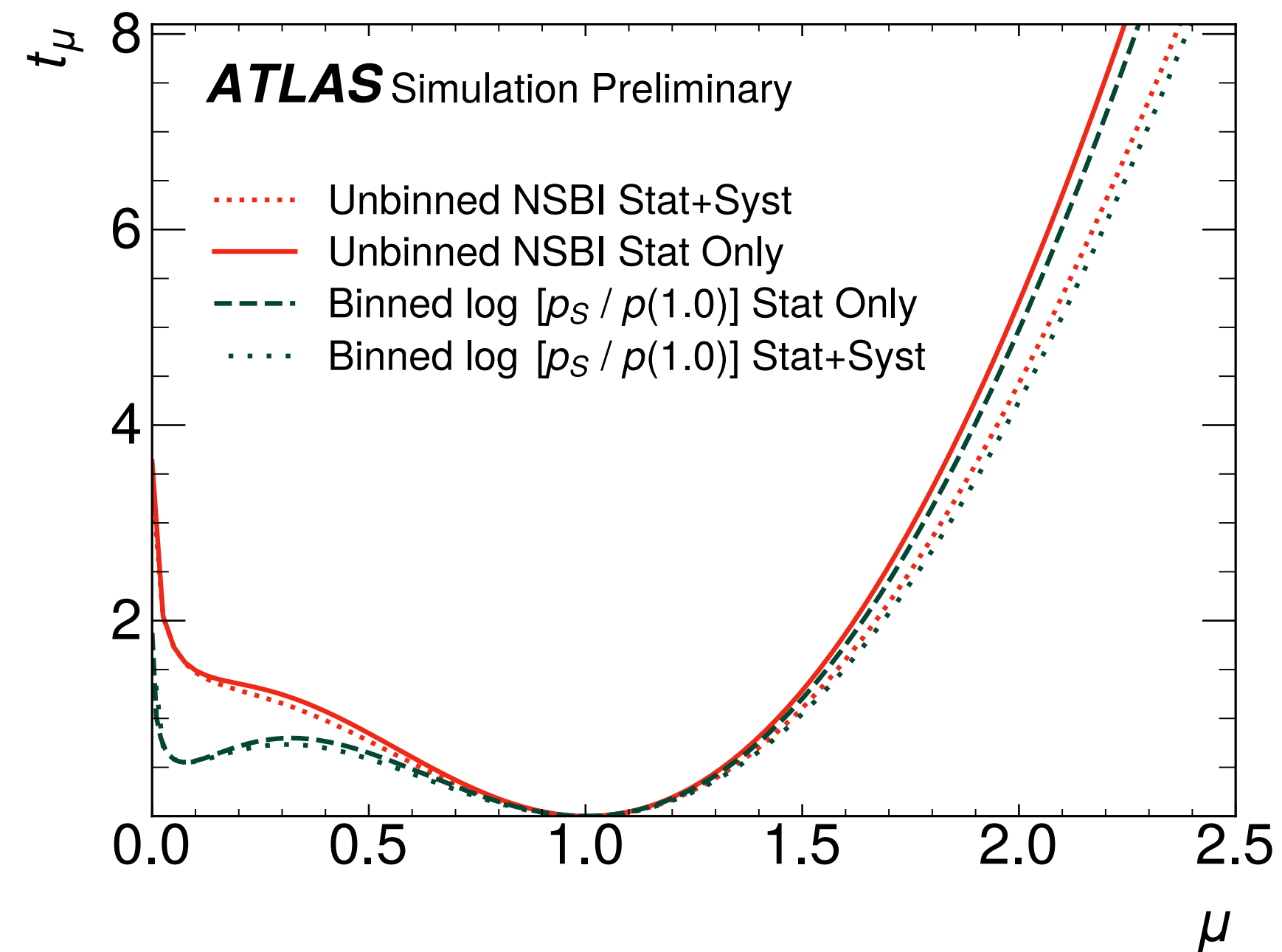
$$\frac{L_{\text{full}}(\mu, \alpha | \mathcal{D})}{L_{\text{ref}}(\mathcal{D})} = \text{Pois}(N_{\text{data}} | \nu(\mu, \alpha)) \prod_i^{N_{\text{data}}} \frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)} \prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$$

Rate term (points to Poisson term)
Prod over events (points to \prod_i)
From previous slide (points to $\frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)}$)
Constrain term (points to $\prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$)

Profiling:

$$t_\mu = -2 \ln \left(\frac{L_{\text{full}}(\mu, \hat{\hat{\alpha}}) / L_{\text{ref}}}{L_{\text{full}}(\hat{\mu}, \hat{\alpha}) / L_{\text{ref}}} \right)$$

This is why we define p_{ref} to be independent of μ



Final test statistic

x_i is one individual event

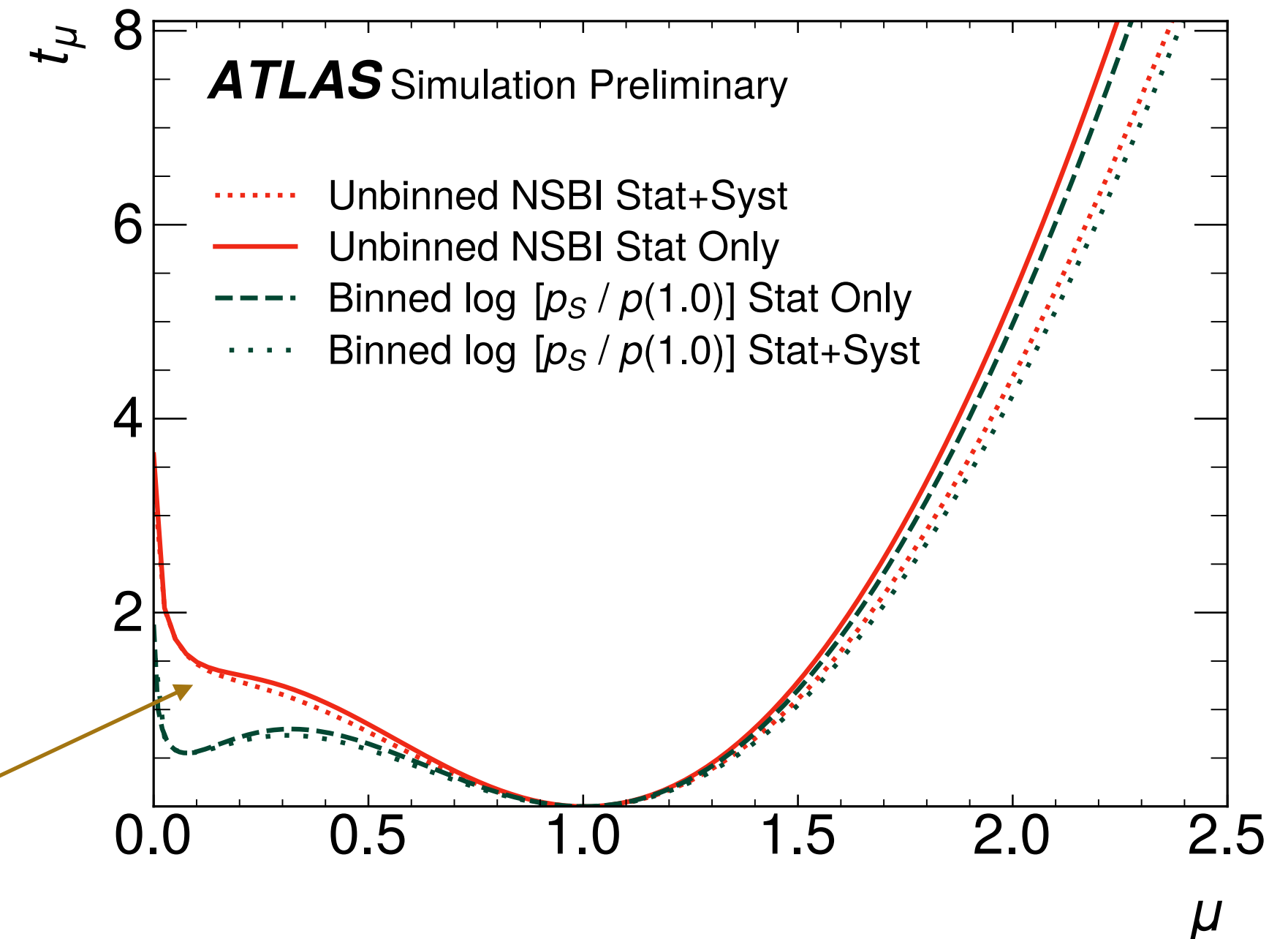
$$\frac{L_{\text{full}}(\mu, \alpha | \mathcal{D})}{L_{\text{ref}}(\mathcal{D})} = \text{Pois}(N_{\text{data}} | \nu(\mu, \alpha)) \prod_i^{N_{\text{data}}} \frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)} \prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$$

Rate term (points to $\text{Pois}(N_{\text{data}} | \nu(\mu, \alpha))$)
Prod over events (points to $\prod_i^{N_{\text{data}}}$)
From previous slide (points to $\frac{p(x_i | \mu, \alpha)}{p_{\text{ref}}(x_i)}$)
Constrain term (points to $\prod_k \text{Gaus}(a_k | \alpha_k, \delta_k)$)

Profiling:

$$t_\mu = -2 \ln \left(\frac{L_{\text{full}}(\mu, \hat{\hat{\alpha}}) / L_{\text{ref}}}{L_{\text{full}}(\hat{\mu}, \hat{\alpha}) / L_{\text{ref}}} \right)$$

This is why we define p_{ref} to be independent of μ



Non-parabolic shape due to non-linear effects from quantum interference

Reference Sample

A combination of signal samples, to ensure there's non-vanishing support entire region of analysis
Does not have to be physical!

$$p_{\text{ref}}(x_i) = \frac{1}{\sum_k v_k} \sum_k^{C_{\text{signals}}} v_k \cdot p_k(x_i)$$

\Rightarrow In our dataset, $p_{\text{ref}}(\cdot) = p_S(\cdot)$

Choice of $p_{\text{ref}}(\cdot)$ can be made purely on numerical stability of training, as it drops out in profile step

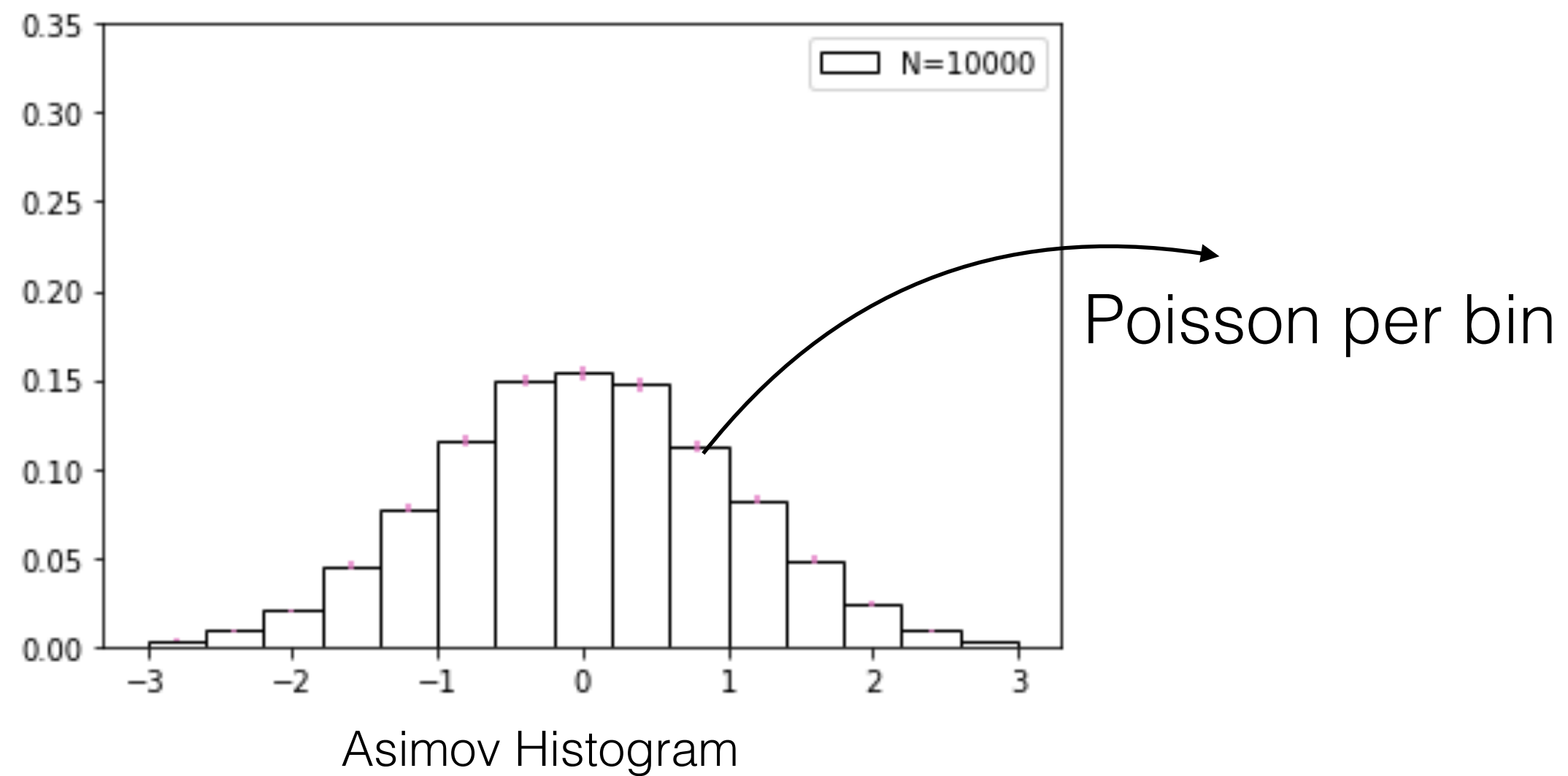
$$t_\mu = -2 \ln \left(\frac{L_{\text{full}}(\mu, \hat{\alpha}) / \cancel{L_{\text{ref}}}}{L_{\text{full}}(\hat{\mu}, \hat{\alpha}) / \cancel{L_{\text{ref}}}} \right)$$

Open problems to extend to full ATLAS analysis:

- ✓ Robustness: Design and validation
- ✓ Systematic Uncertainties: Incorporate them in likelihood (ratio) model
- ▶ Neyman Construction: Throwing toys in a per-event analysis

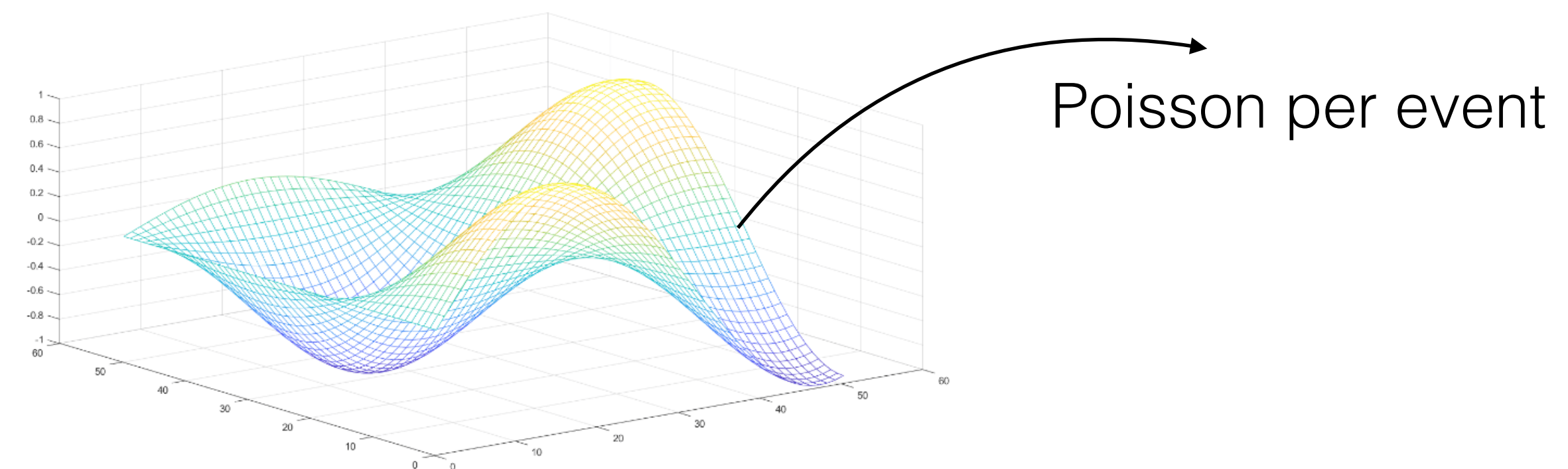
Throwing event-level toys

Traditionally:



$$N_i^{toy} = \text{Poisson}(N_i^{Asimov})$$

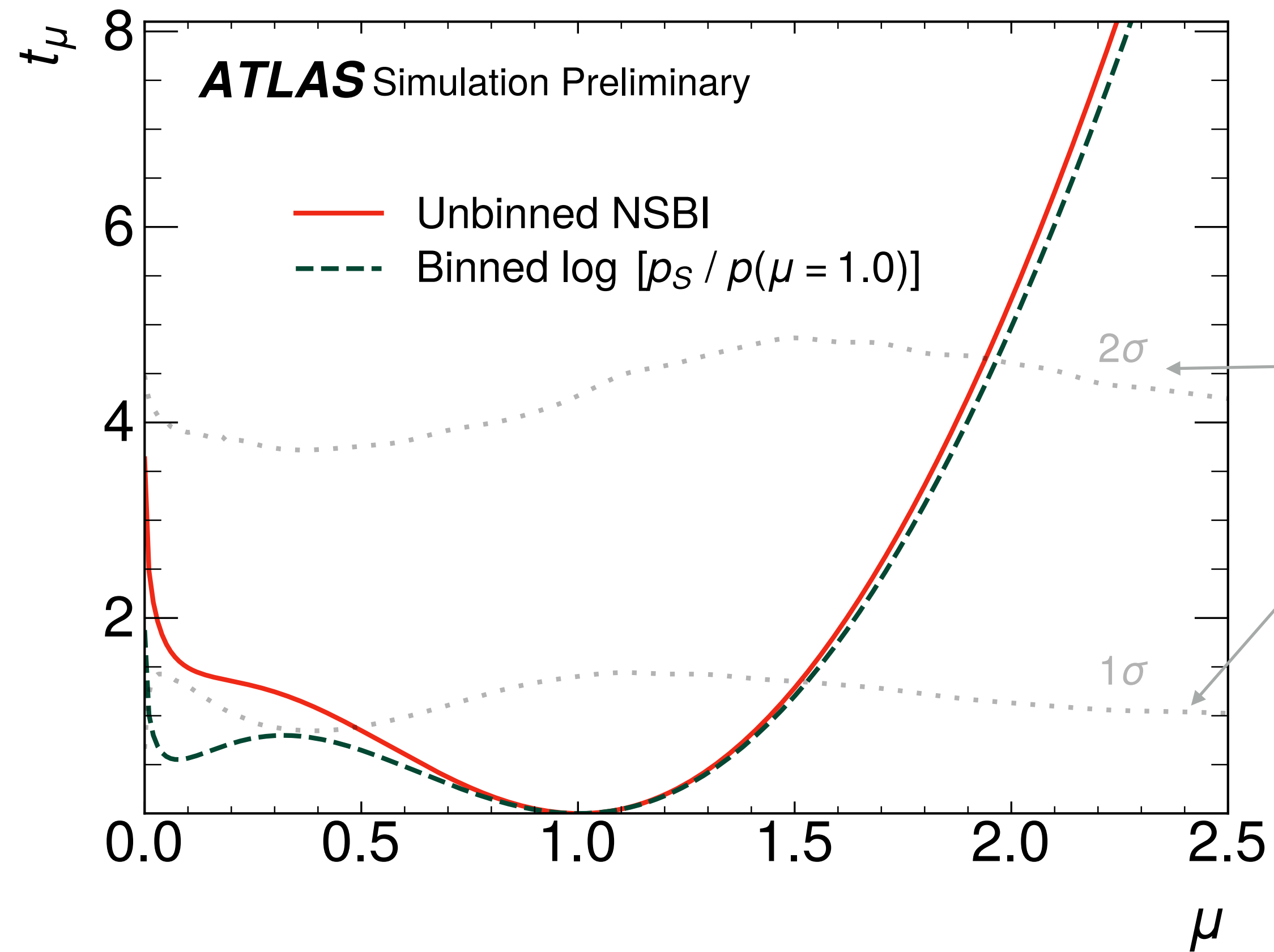
NSBI:



$$w_i^{toy} = \text{Poisson}(w_i^{Asimov})$$

(‘Unweighted’ events, i.e. integer weights)

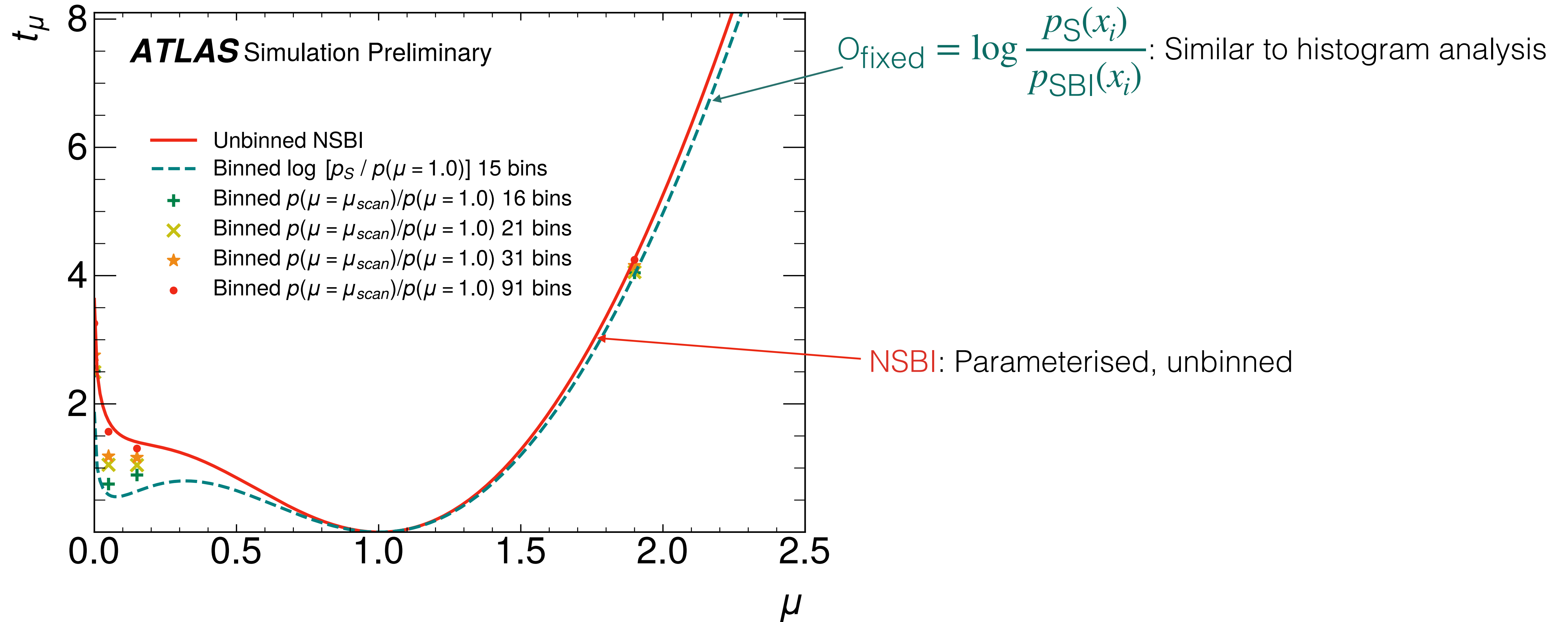
Confidence belts



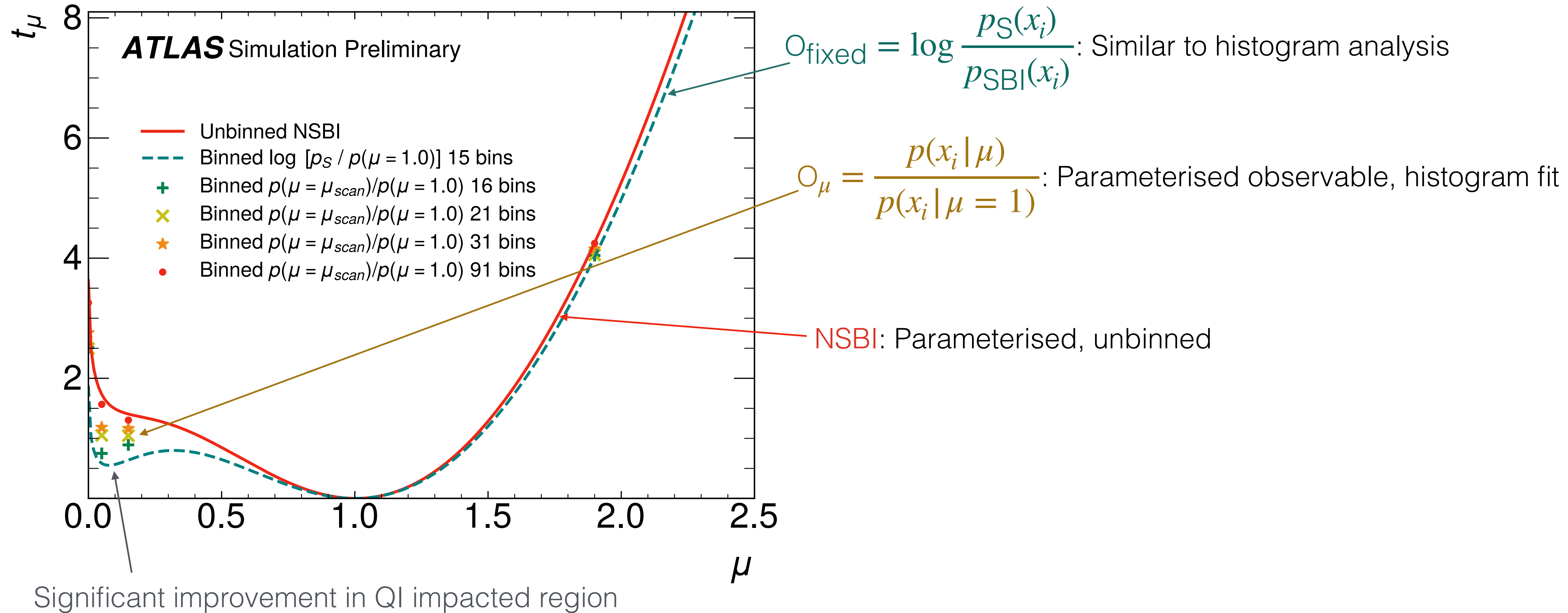
Similar to structure seen in histogram analysis

Why does NSBI work better than traditional analyses?

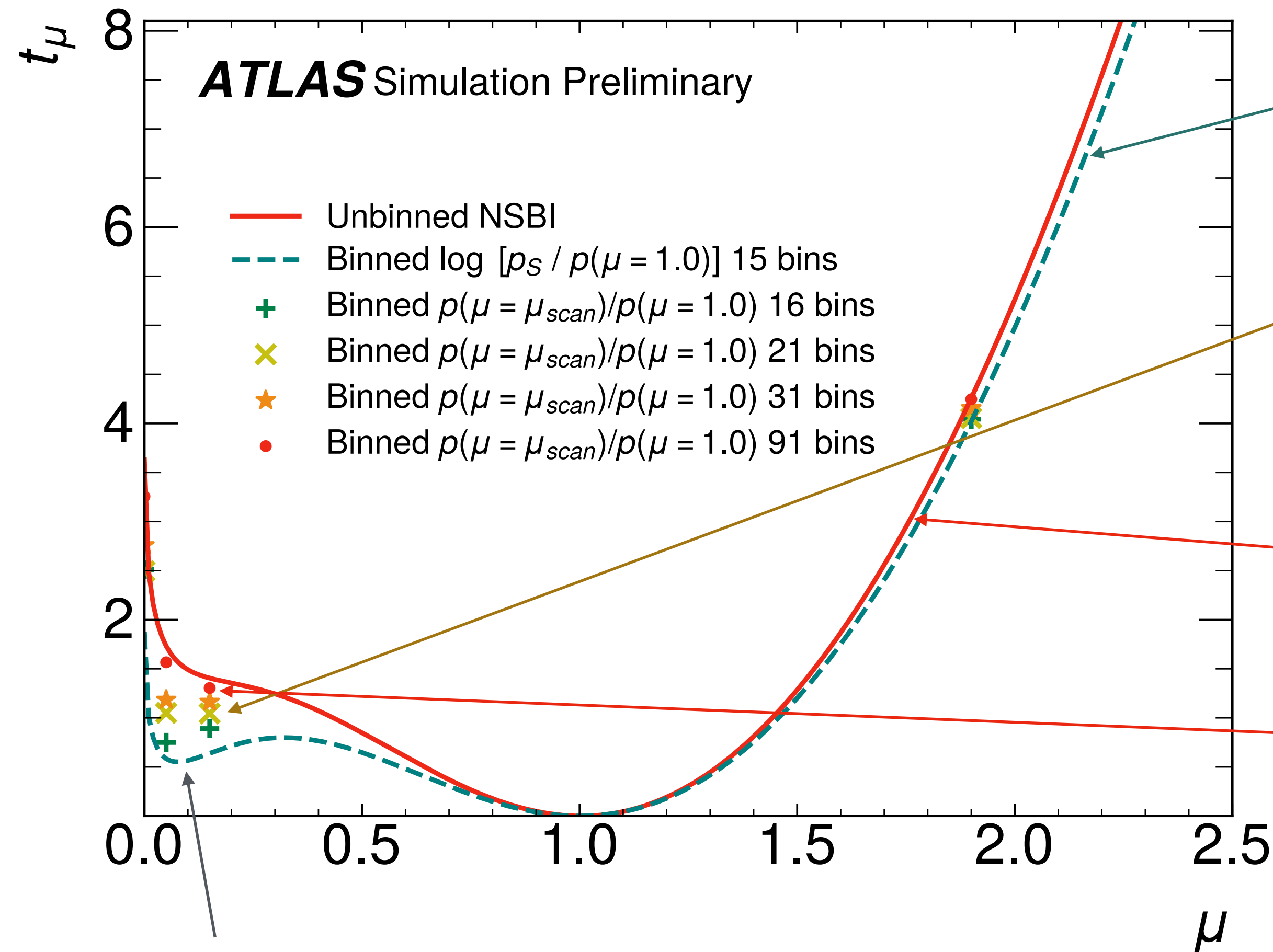
Why does it work better than traditional analyses?



Why does it work better than traditional analyses?



Why does it work better than traditional analyses?



$O_{\text{fixed}} = \log \frac{p_S(x_i)}{p_{\text{SBI}}(x_i)}$: Similar to histogram analysis

$O_\mu = \frac{p(x_i | \mu)}{p(x_i | \mu = 1)}$: Parameterised observable, histogram fit

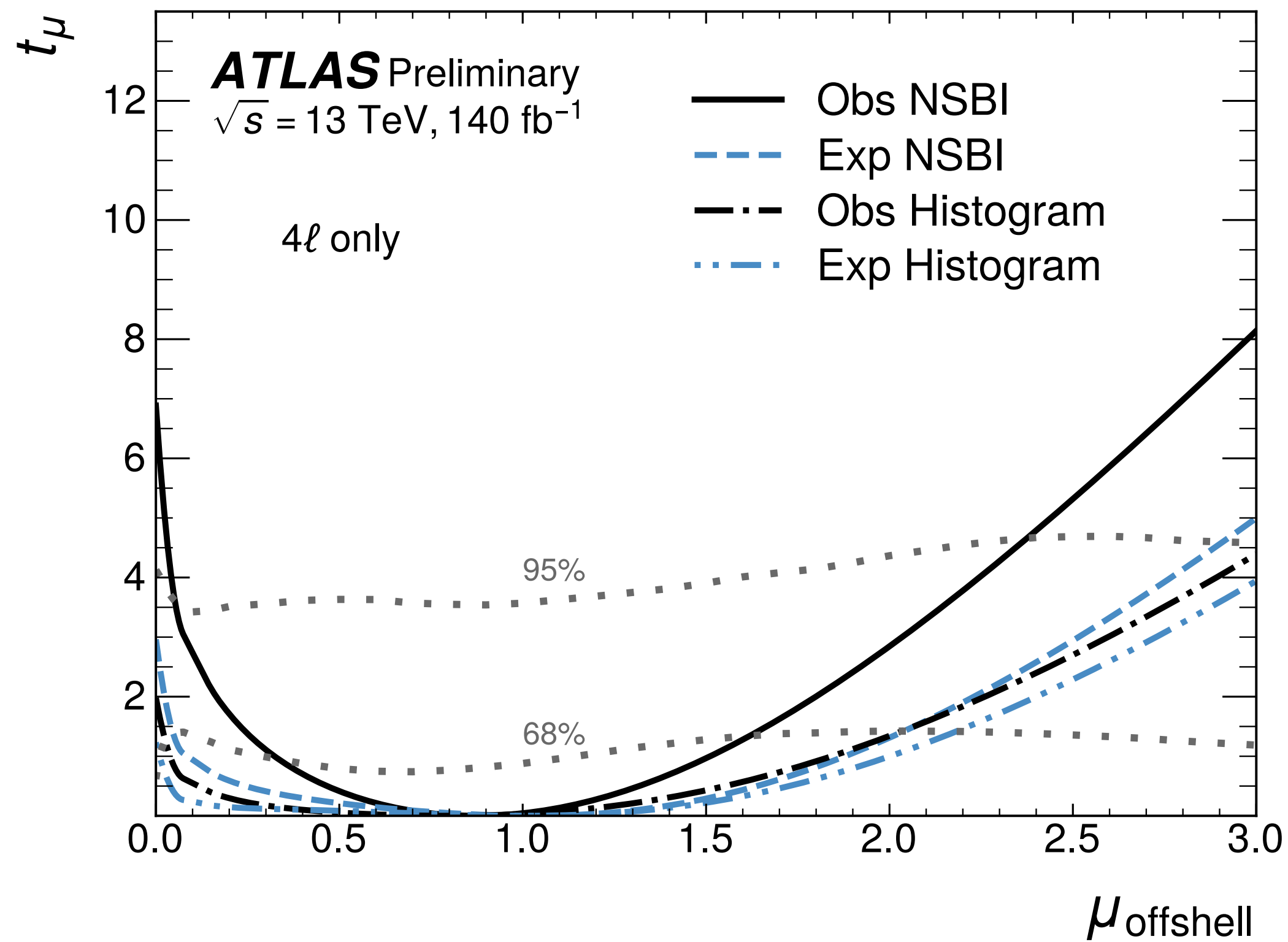
NSBI: Parameterised, unbinned

O_μ approaches NSBI as $n\text{Bins} \rightarrow \infty$

Significant improvement in QI impacted region

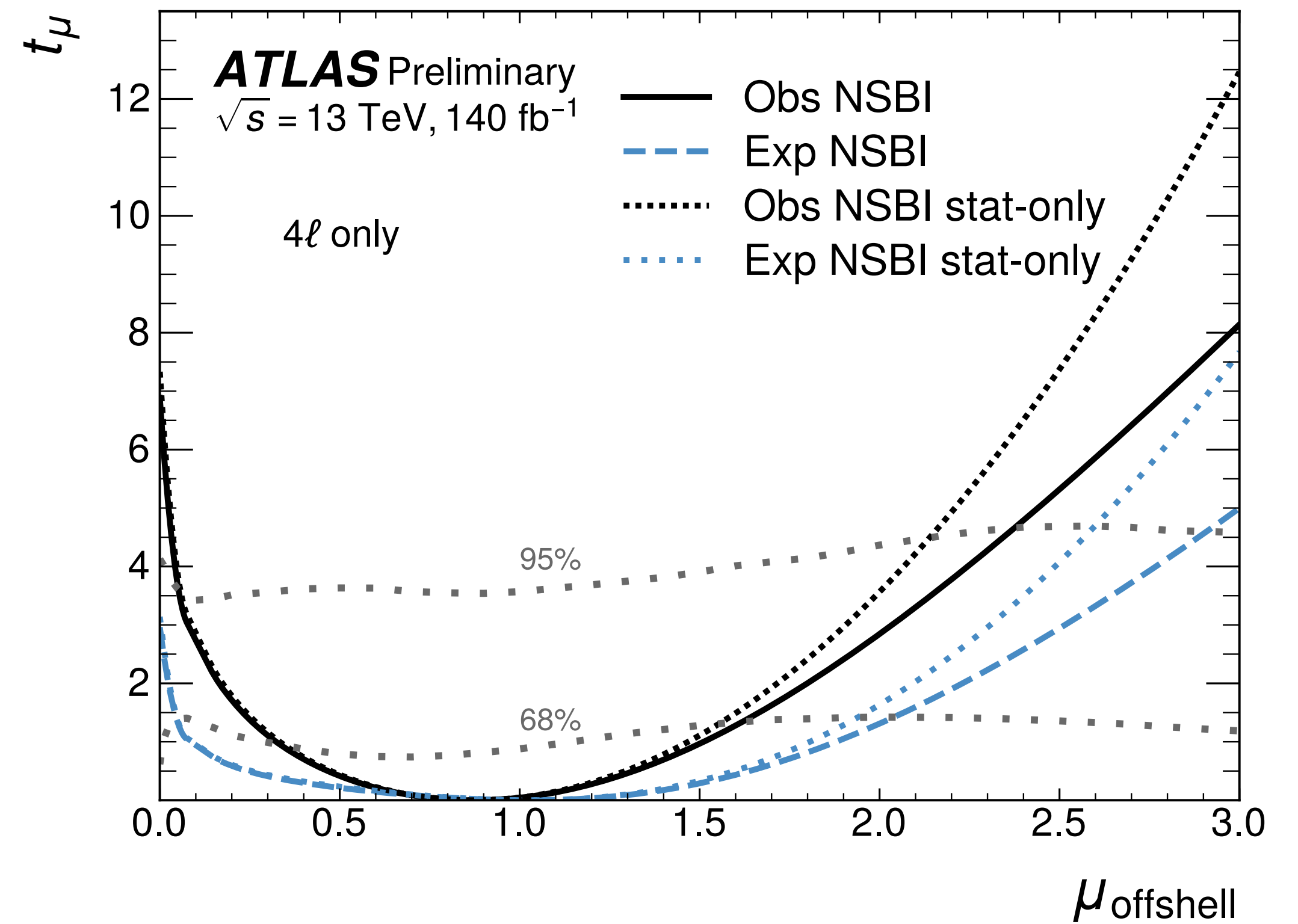
Results on data

NSBI vs histogram analysis

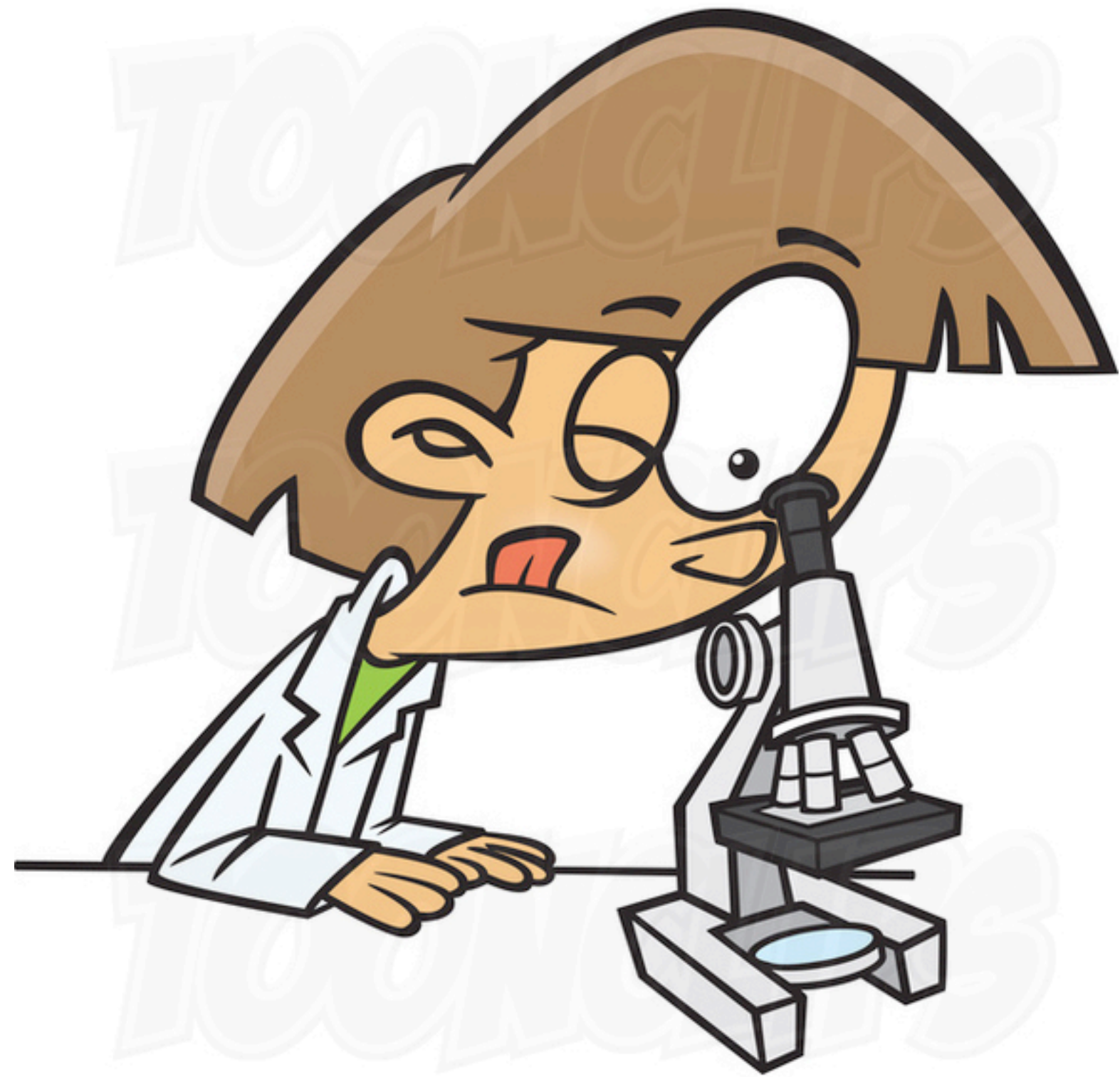


Observed data happens to provide stronger than expected constrains for both hist and NSBI (consistent)

Stat vs Stat+Syst



Nuisance parameters decrease sensitivity, as expected



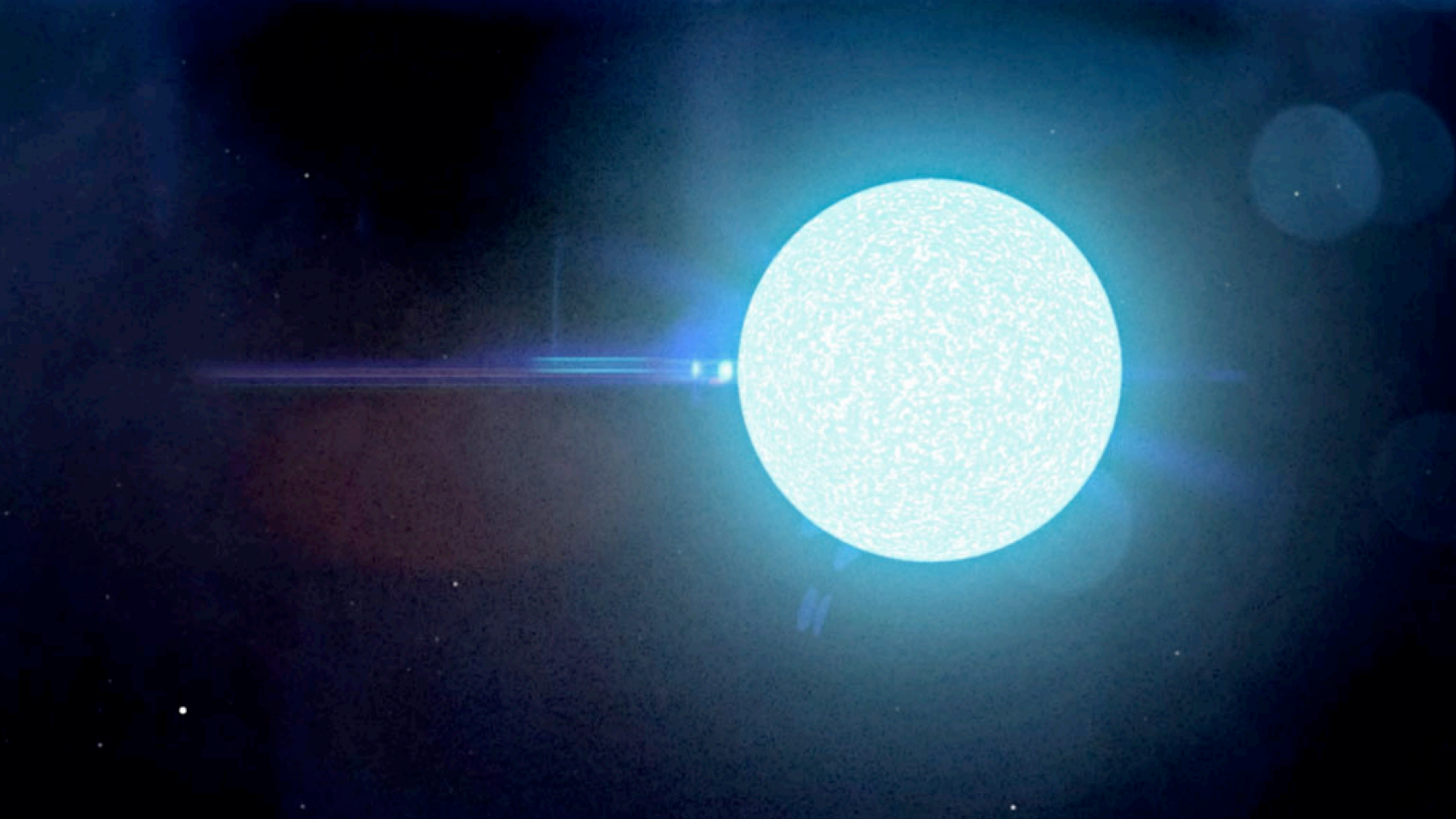
ToonClips.com

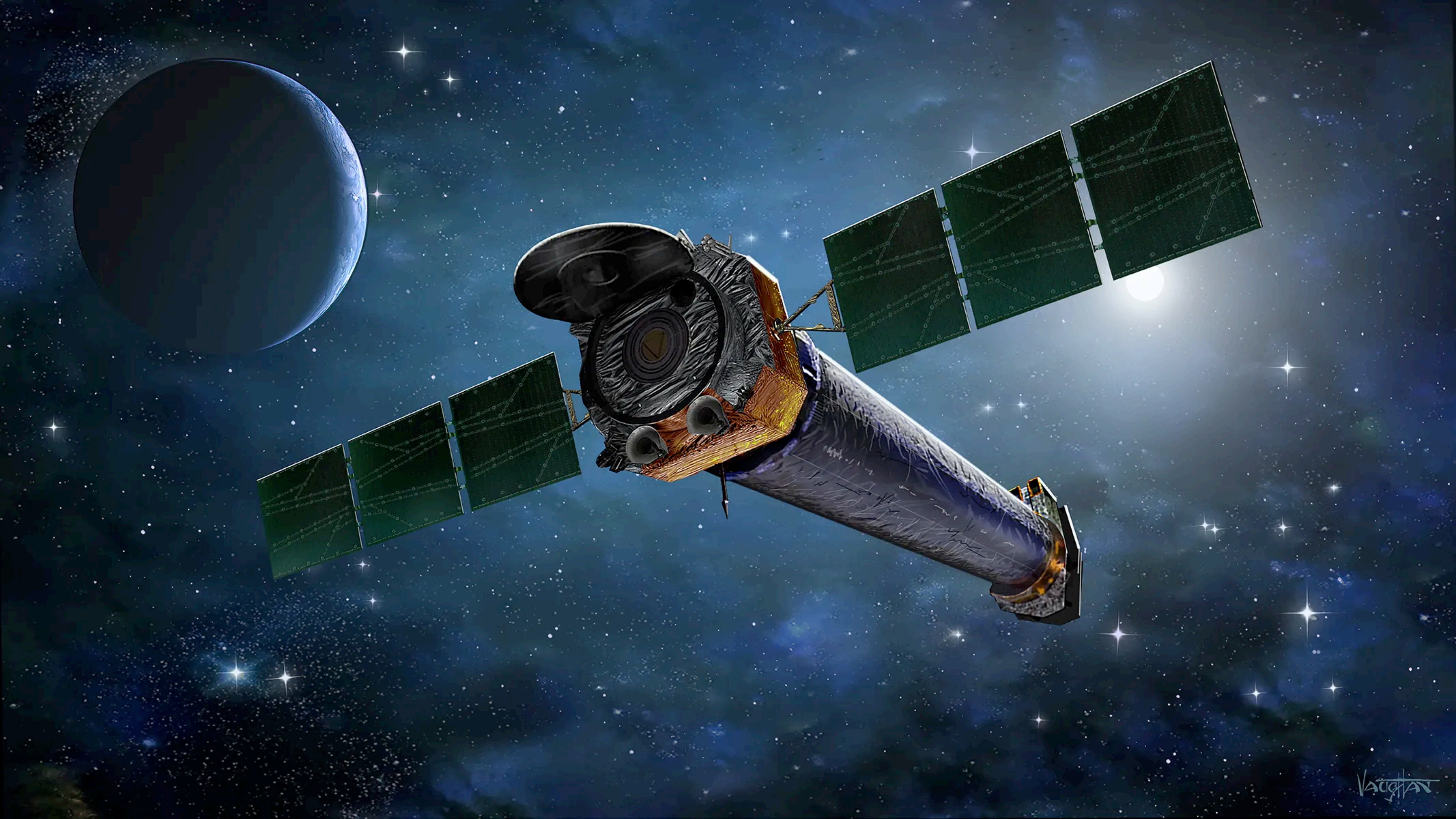
#56684

service@toonclips.com

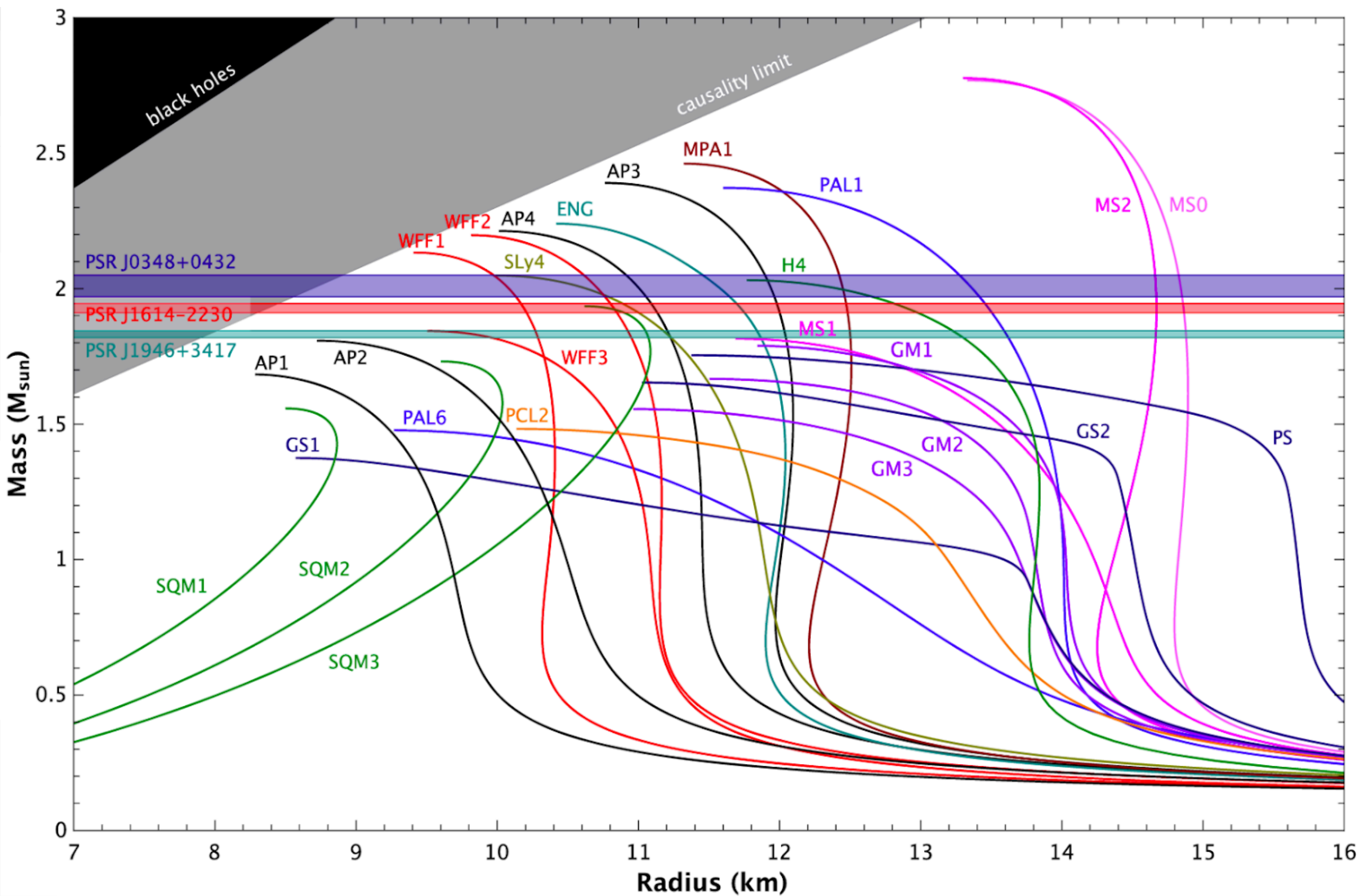


Image: [Source](#)





Telescope measurements of energy spectra of neutron stars



Mass-radius curves created by different equation of state (EoS) models

Horizontal bars show massive neutron star observations used to “rule out” EoS models.

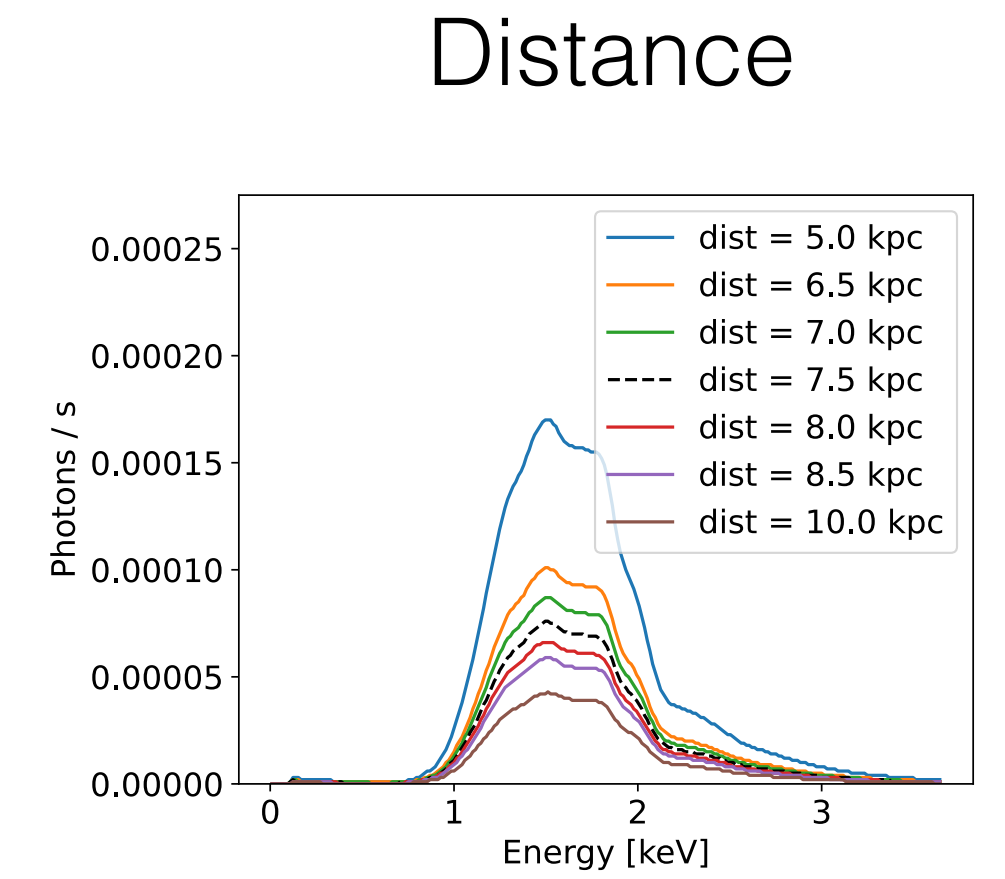
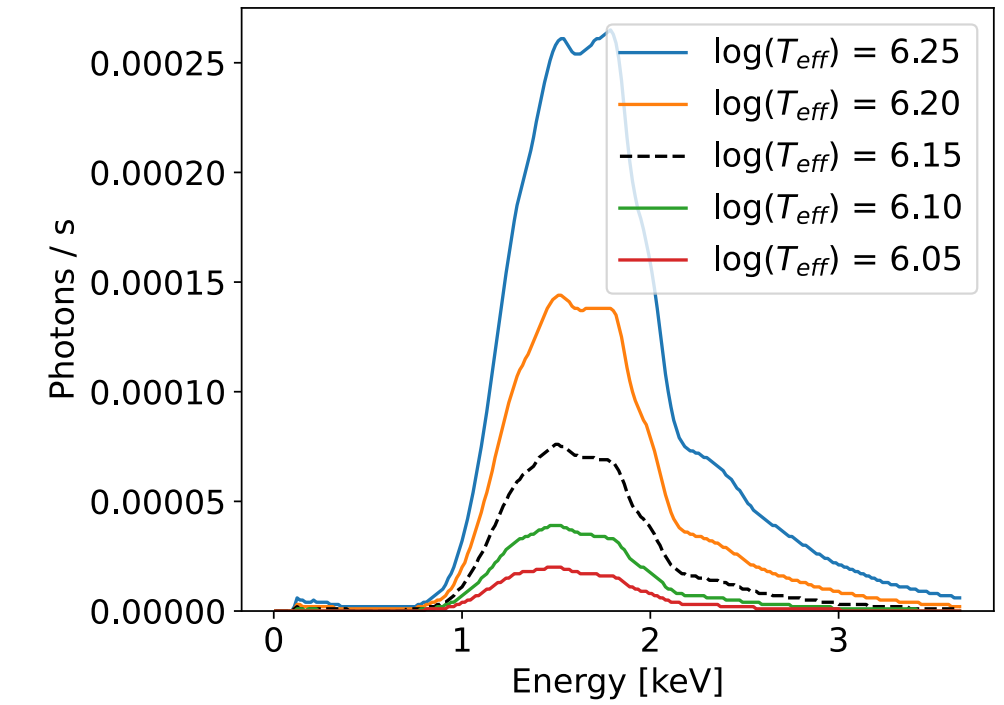
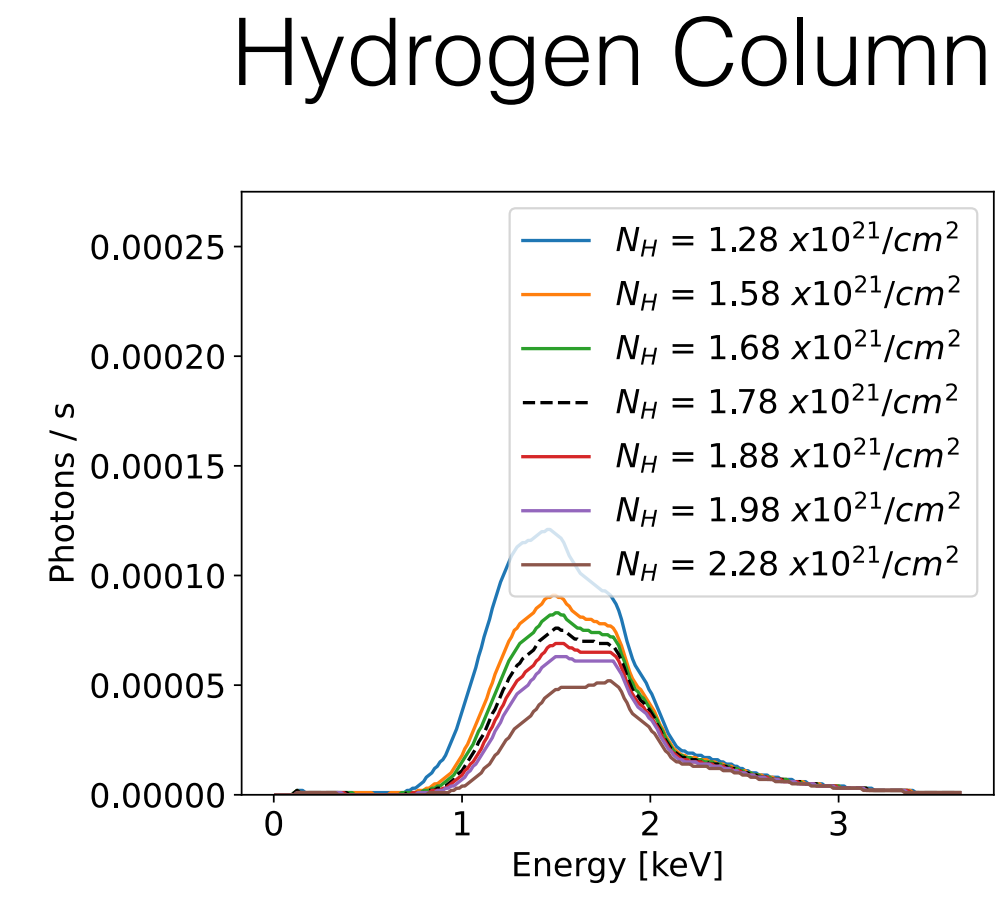
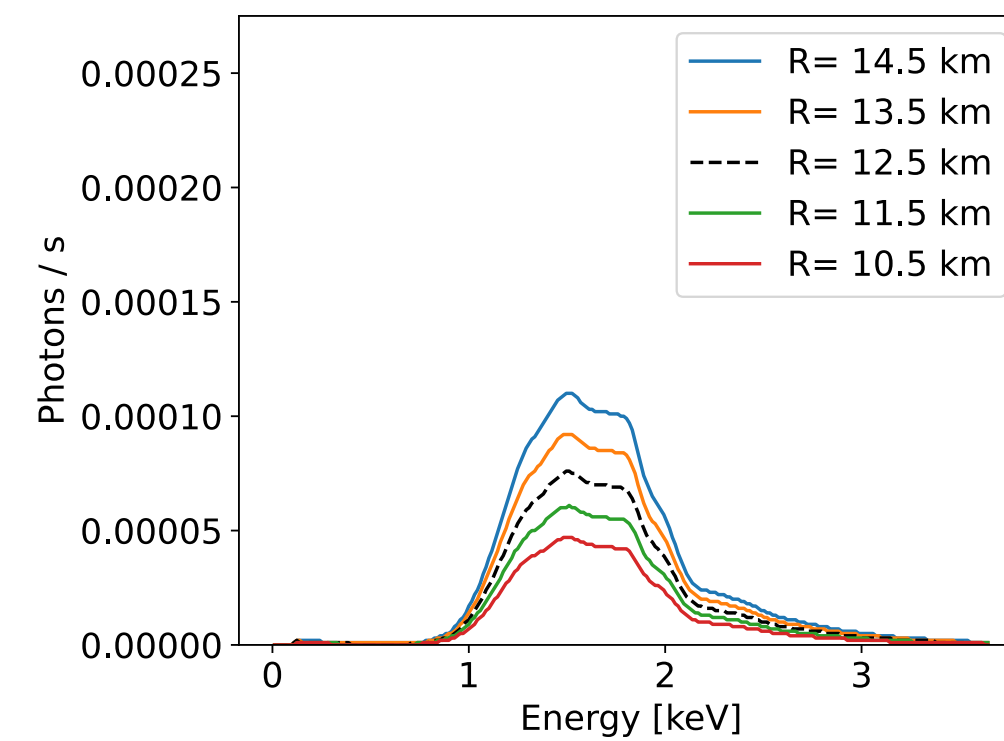
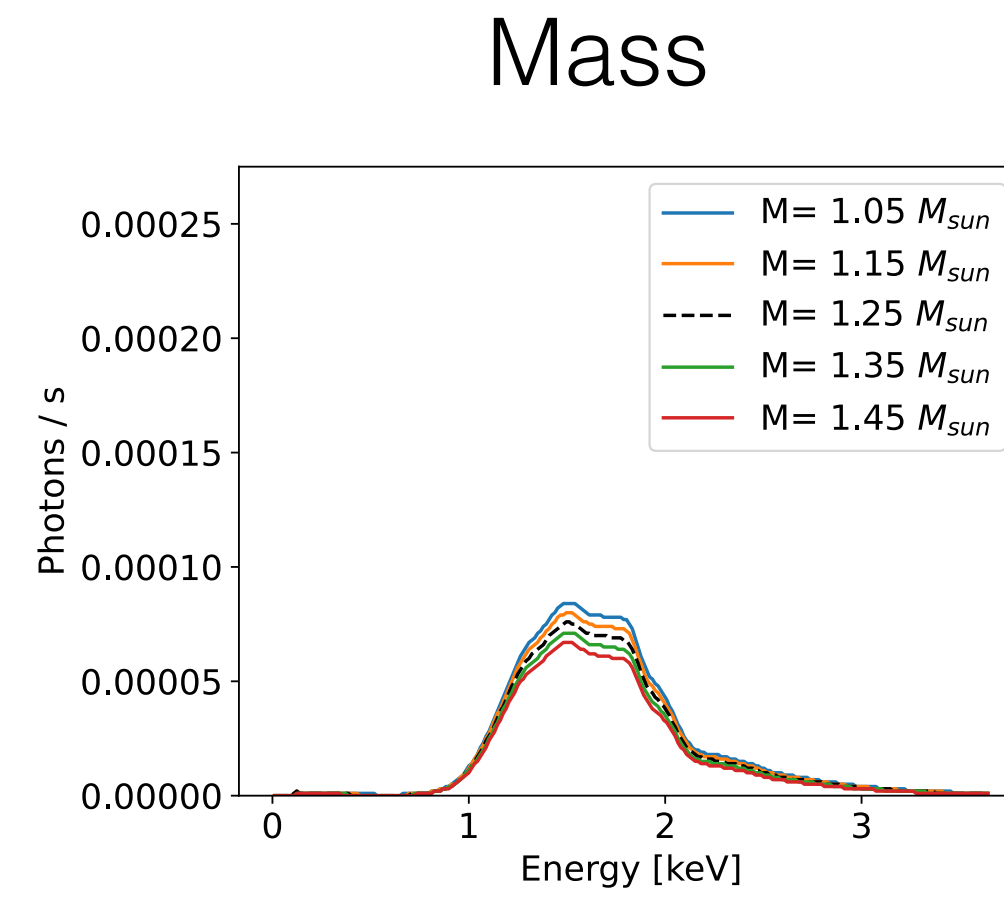
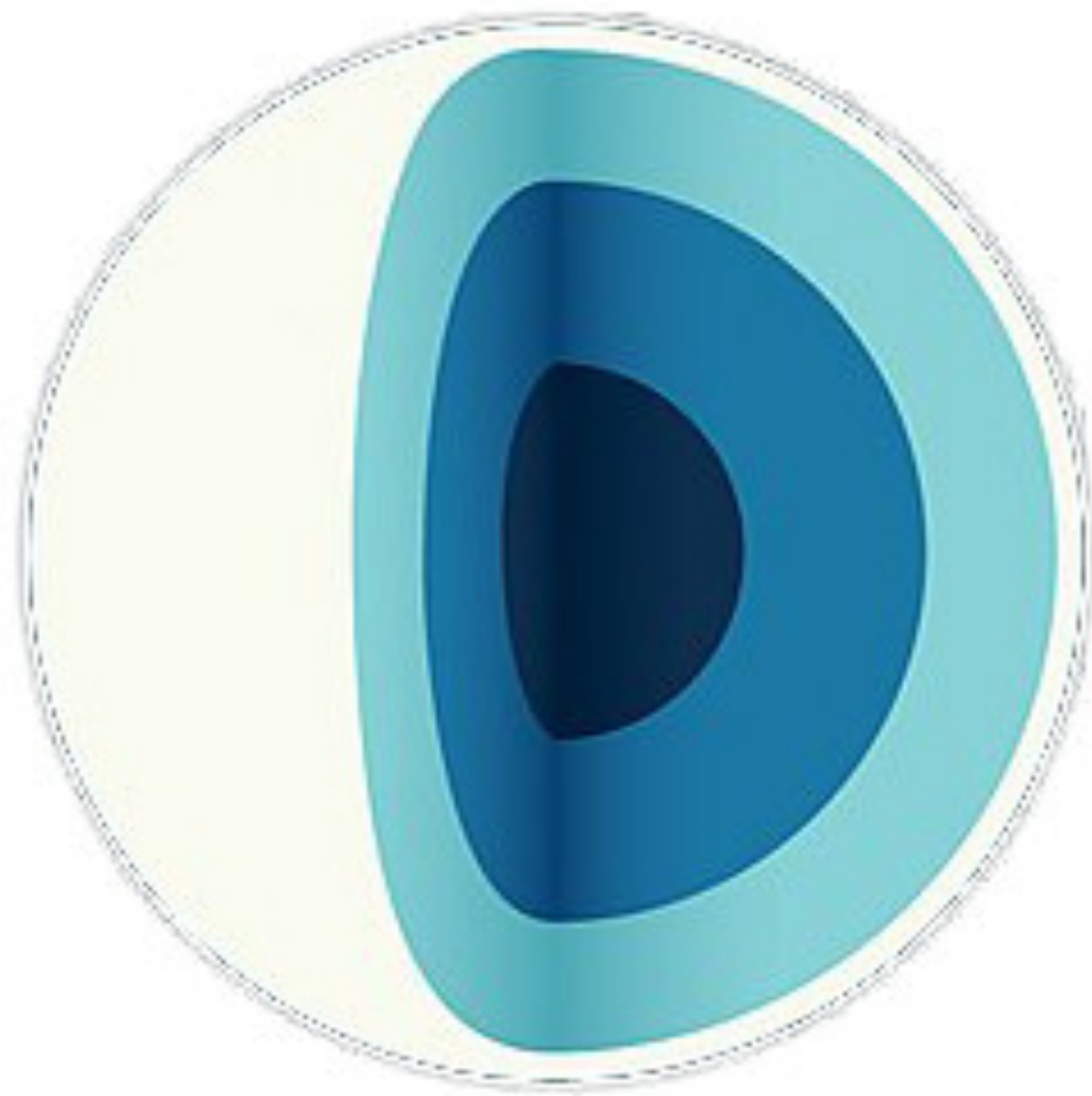
Two communities:

- **Astrophysicists** measure mass/radius from telescope
- **Nuclear theorists** measure EoS from mass/radius

Figure from Lattimer J. M., Prakash M., 2001, The Astrophysical Journal, 550, 426–442

Telescope measurements of energy spectra

Probe the interior:
Equation of State parameters
 λ_1, λ_2



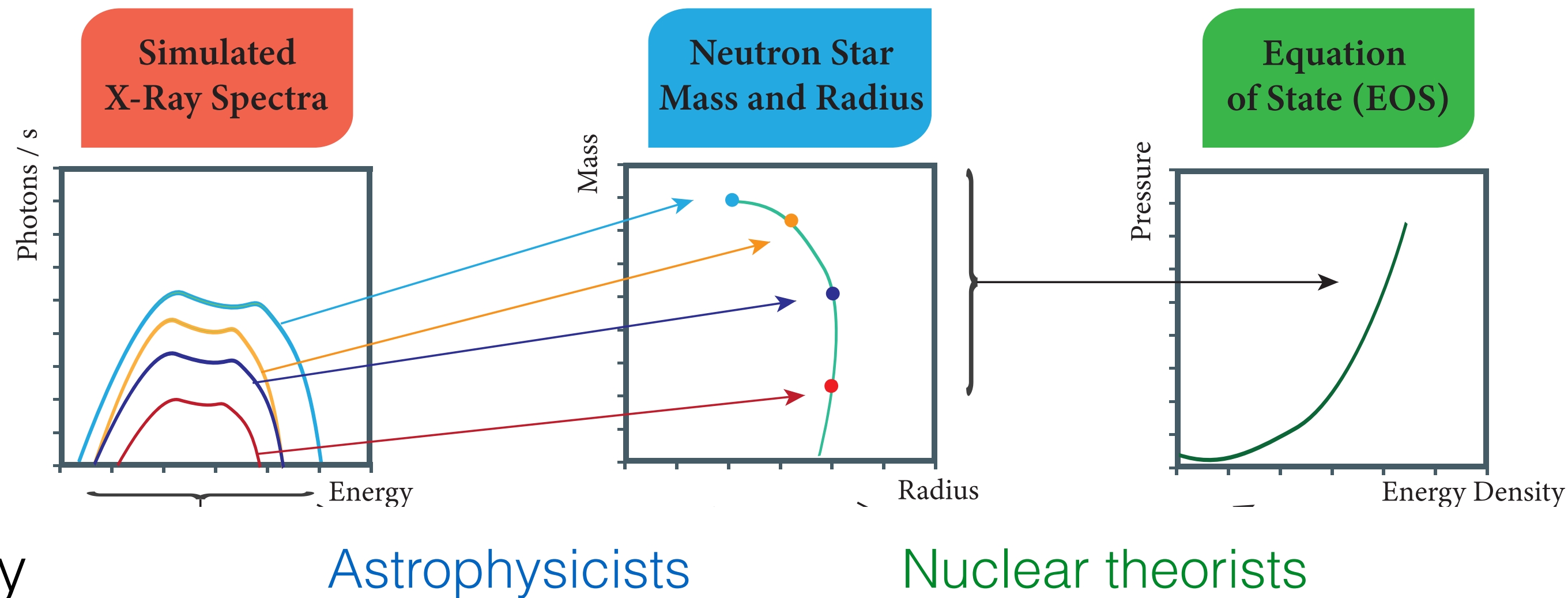
Radius

Effective Temperature

Traditional method: Two-step inference



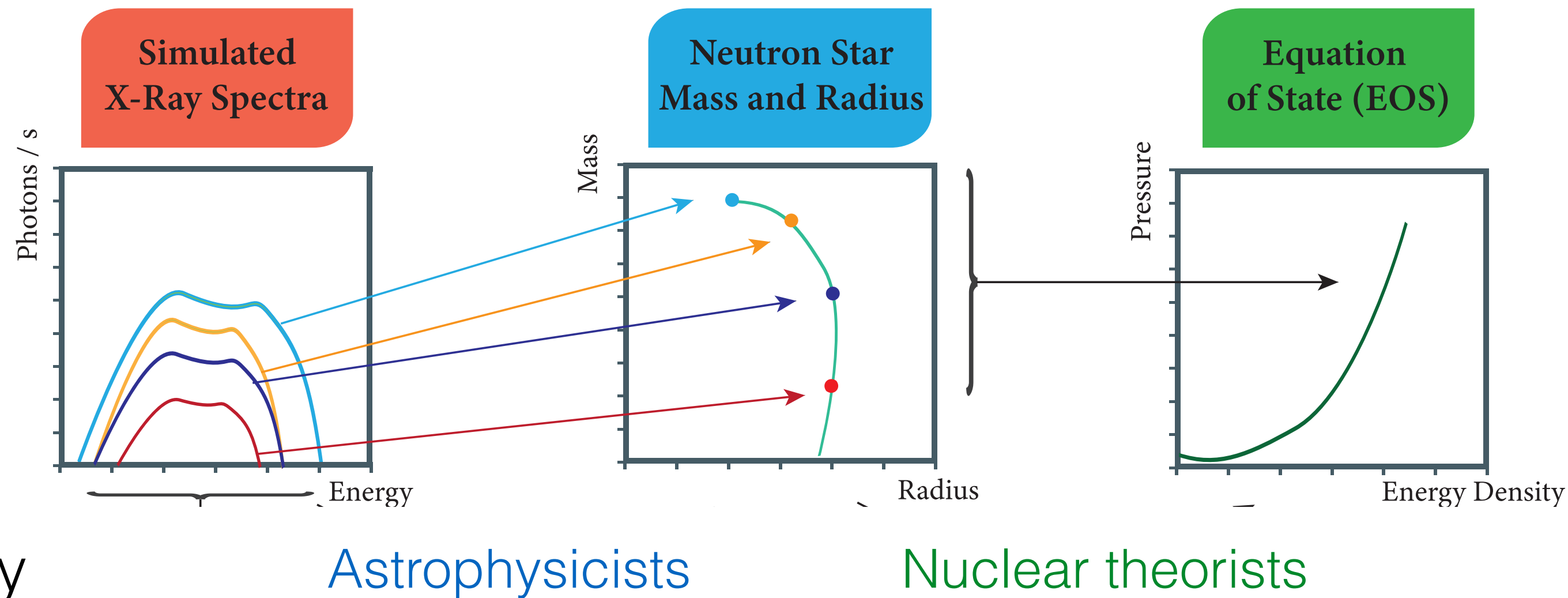
Neutron star in sky



Traditional method: Two-step inference

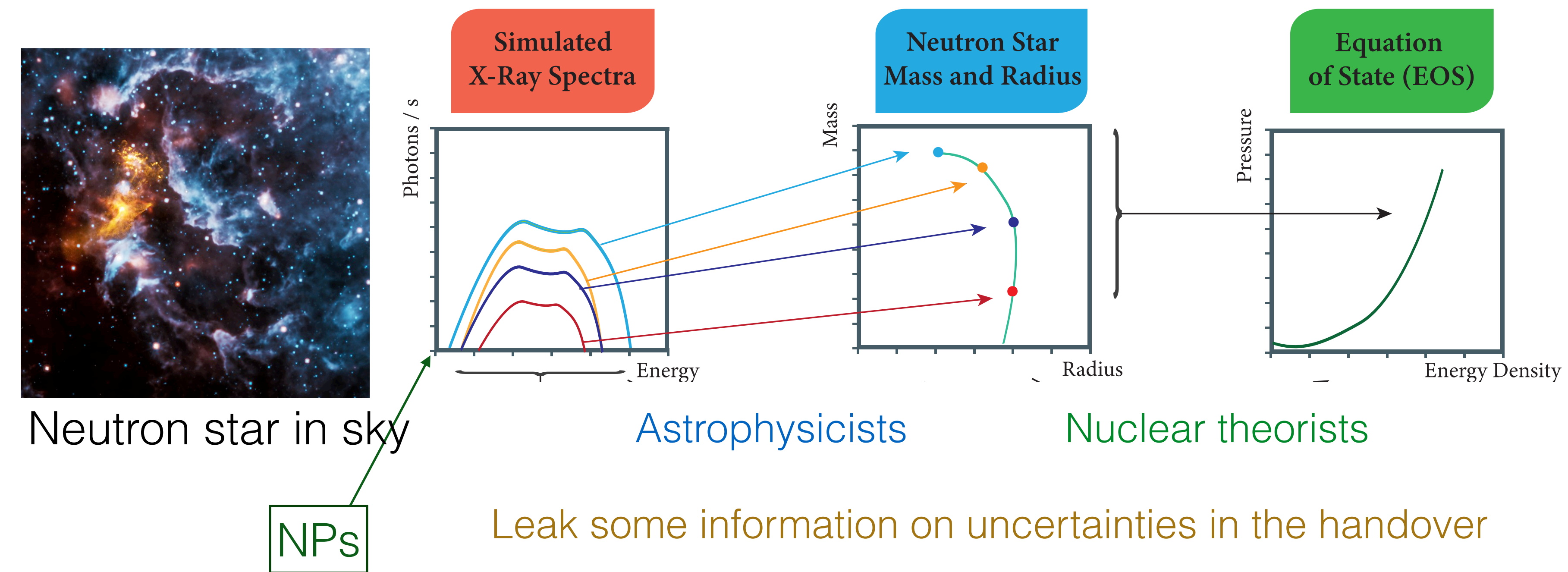


Neutron star in sky



Leak some information on uncertainties in the handover

Traditional method: Two-step inference

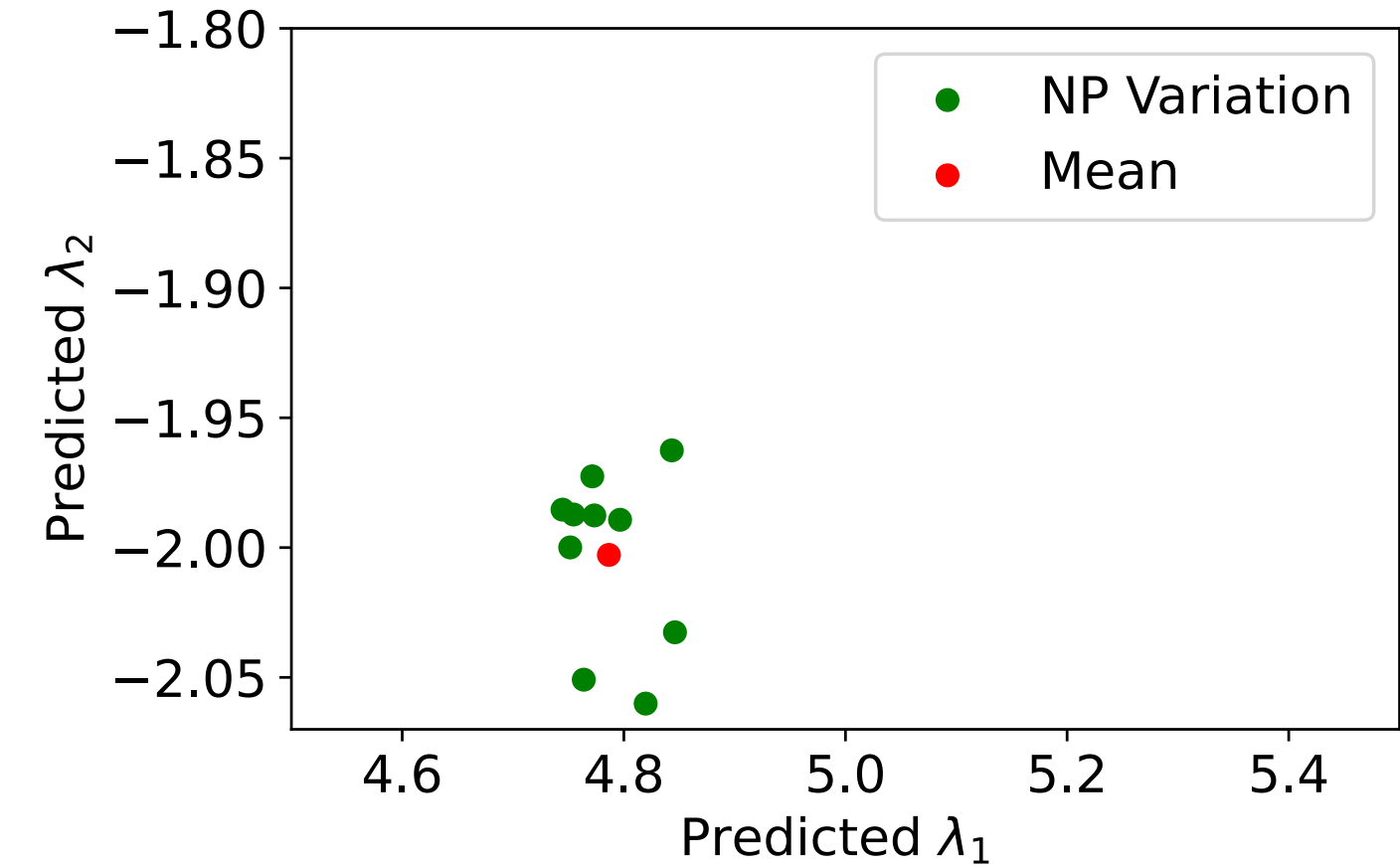
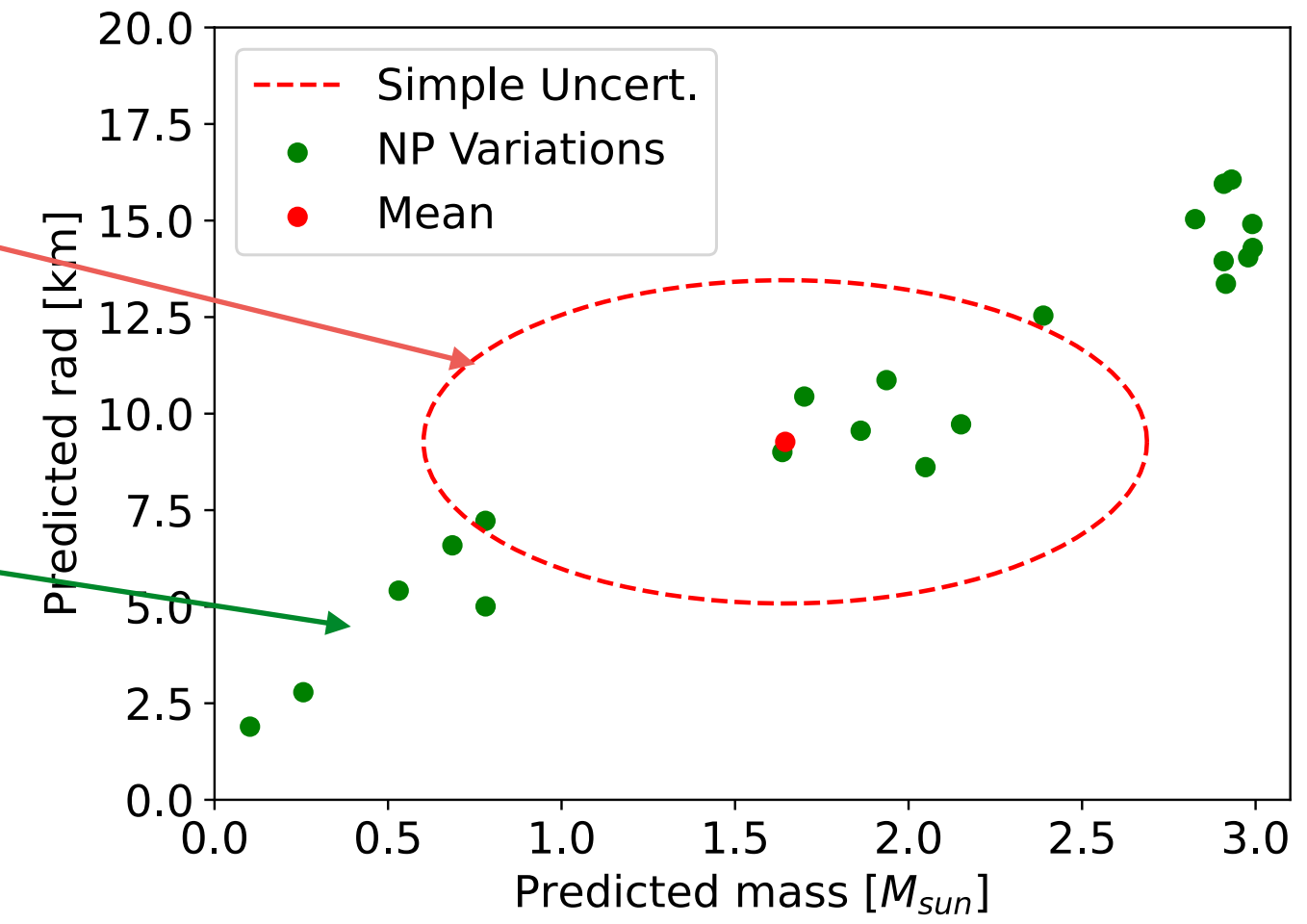


Leak some information on uncertainties in the handover

Traditional method: Two-step inference

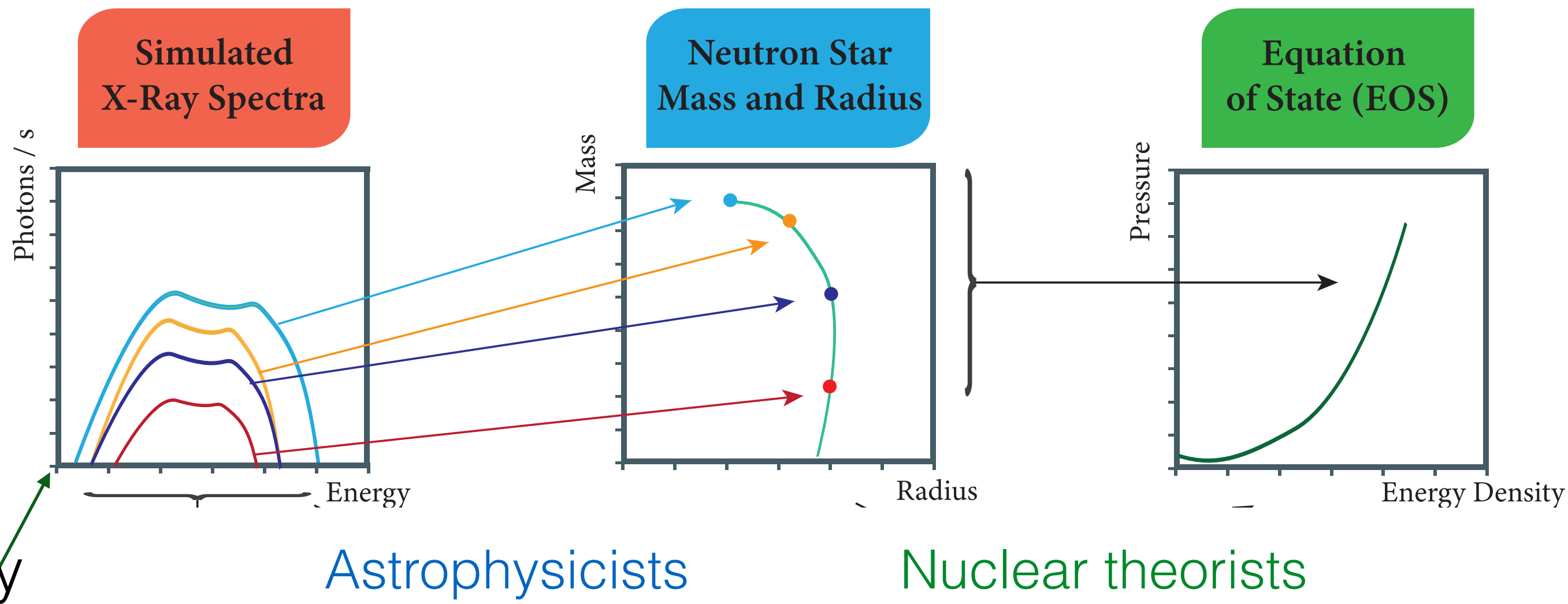
SOTA collapsed information into 2 numbers + assumed uncorrelated Gaussian uncertainties

Real uncertainties look quite different

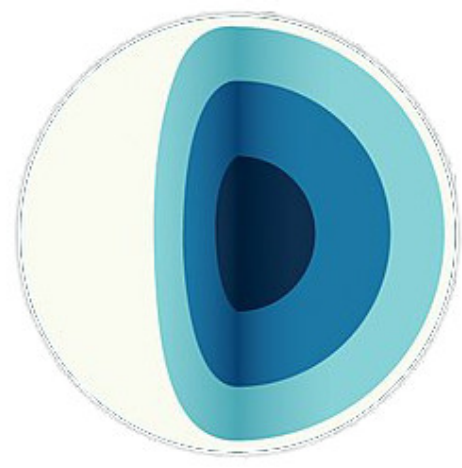


Neutron star in sky

NPs

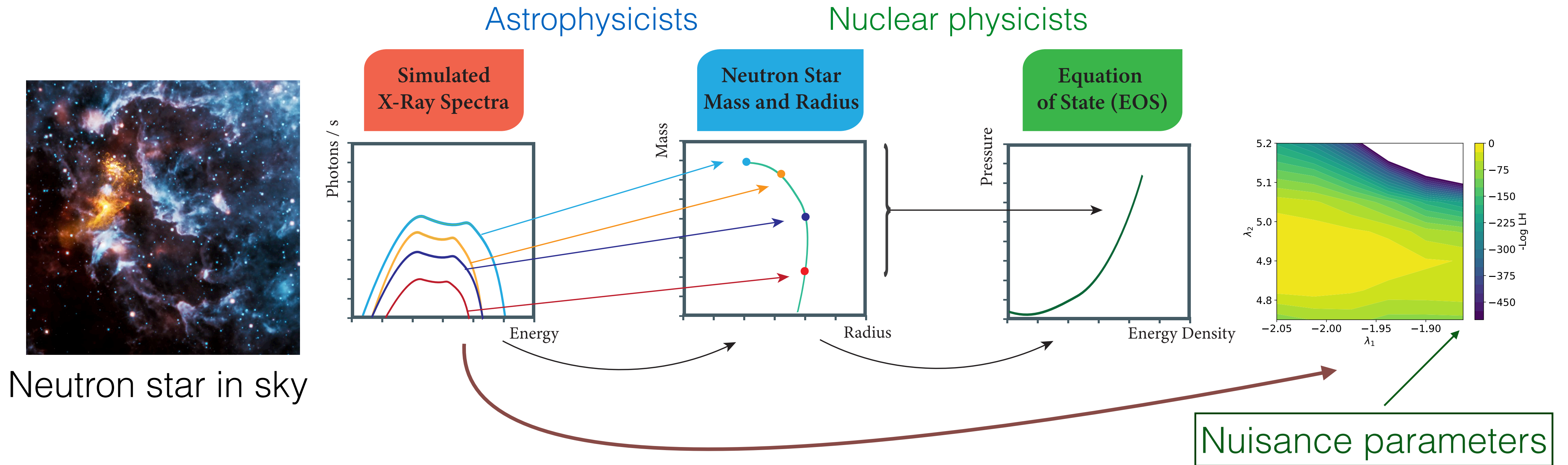


Leak some information on uncertainties in the handover



Inferring neutron star EoS parameters with NSBI

Recover the likelihood of EoS + NPs directly from the raw high-dimensional telescope spectra!

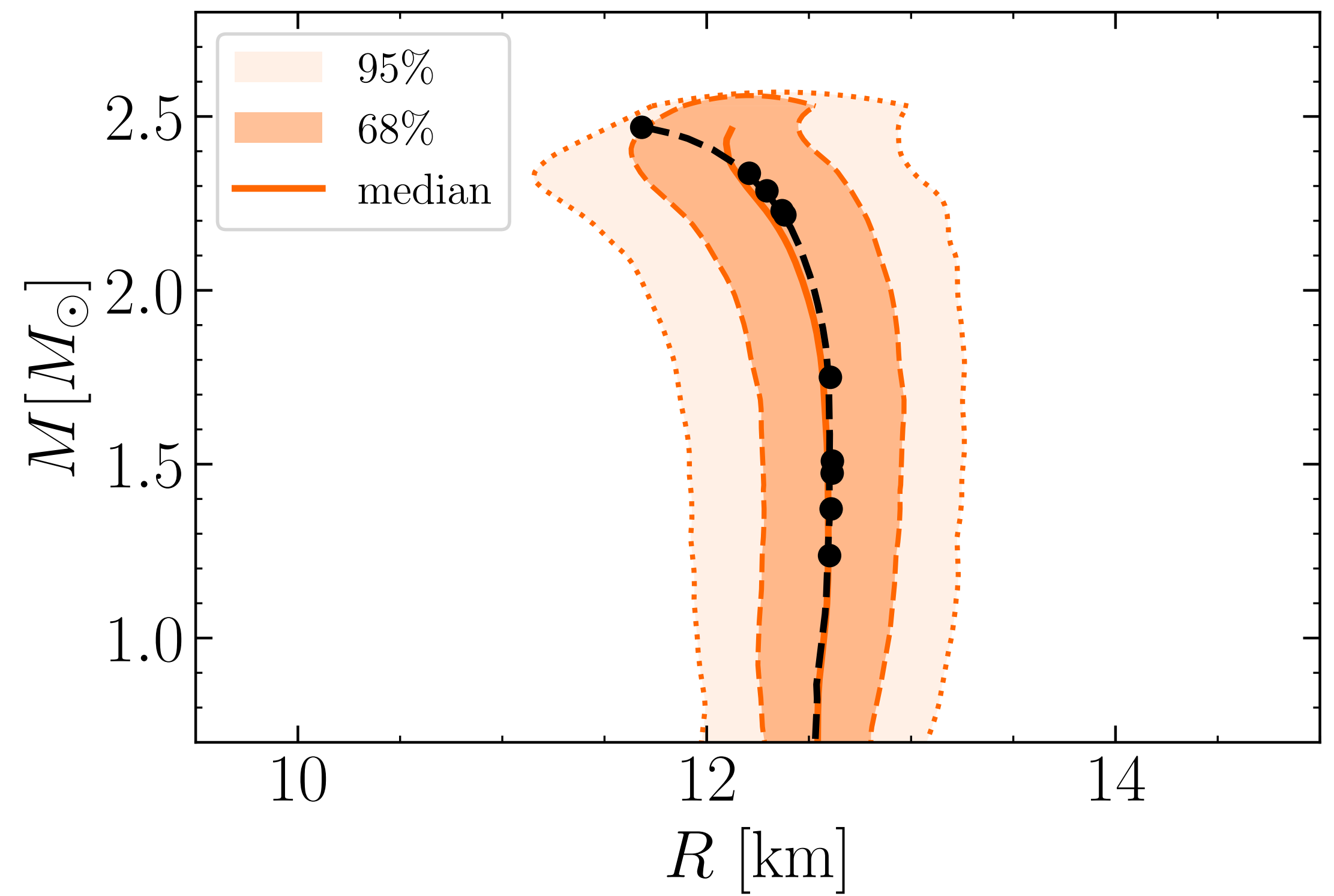
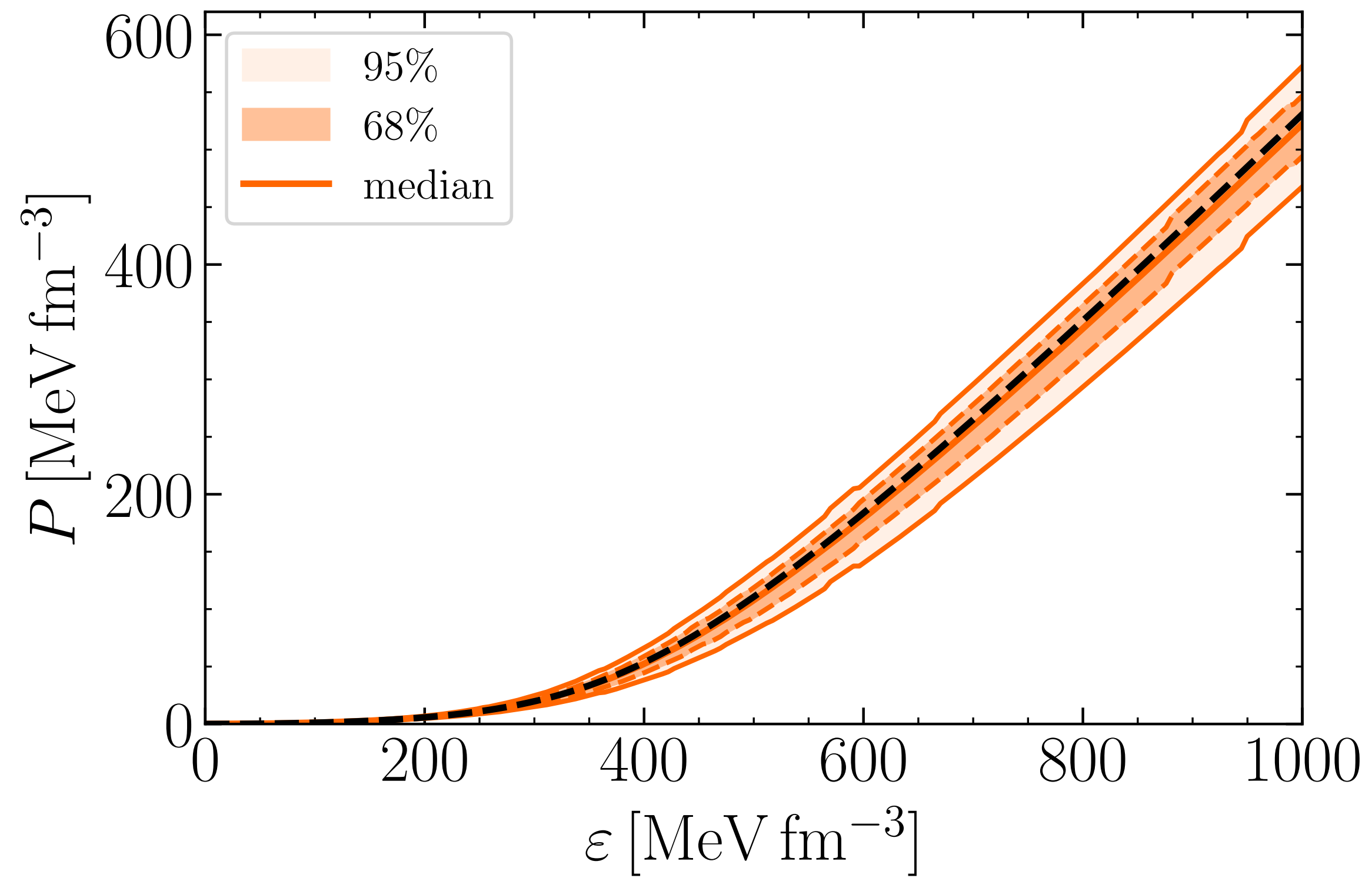


Neutron star in sky

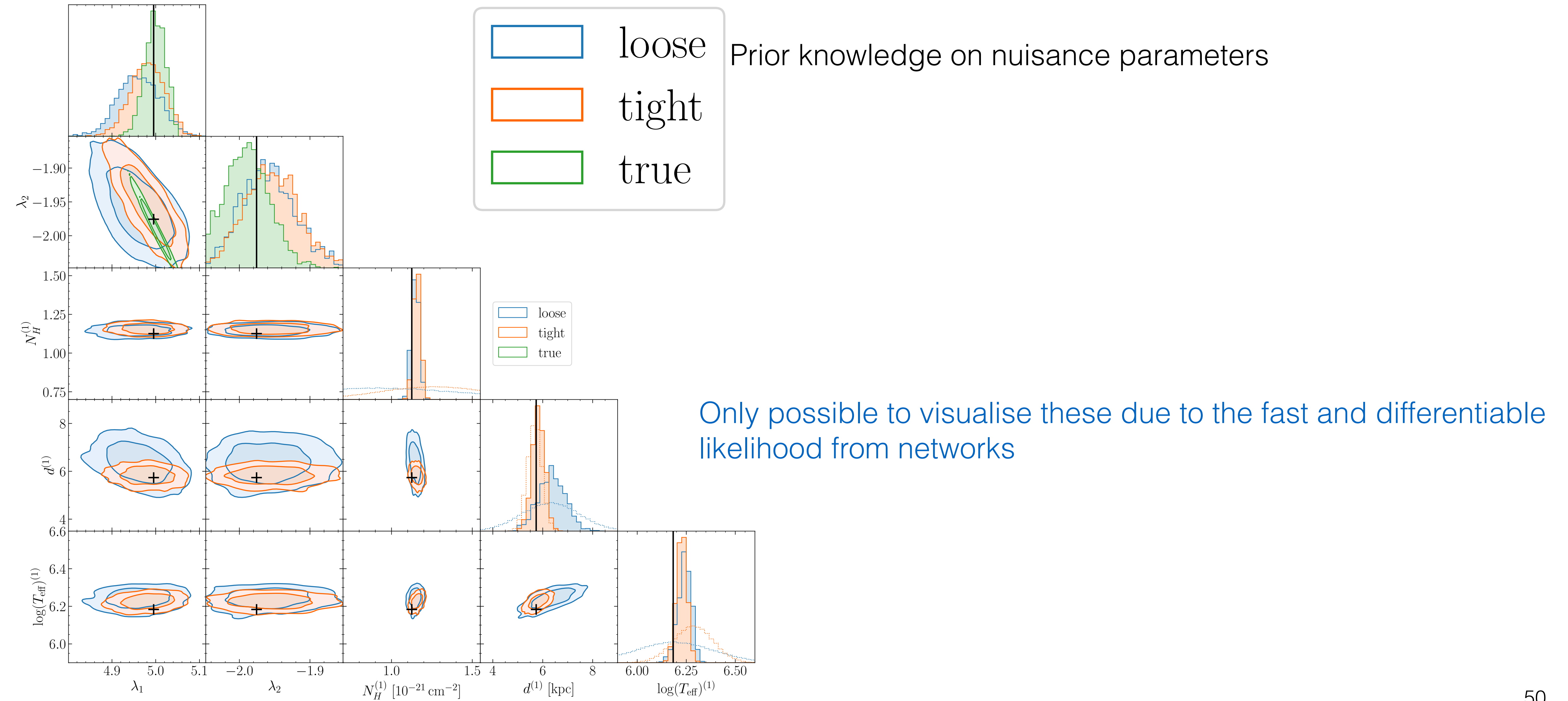
Direct estimation of likelihood from high-dimensional raw data allows more reliable uncertainty propagation and better measurements!

Meaningful posteriors, most sensitive method !

Bayesian Posteriors and credible intervals

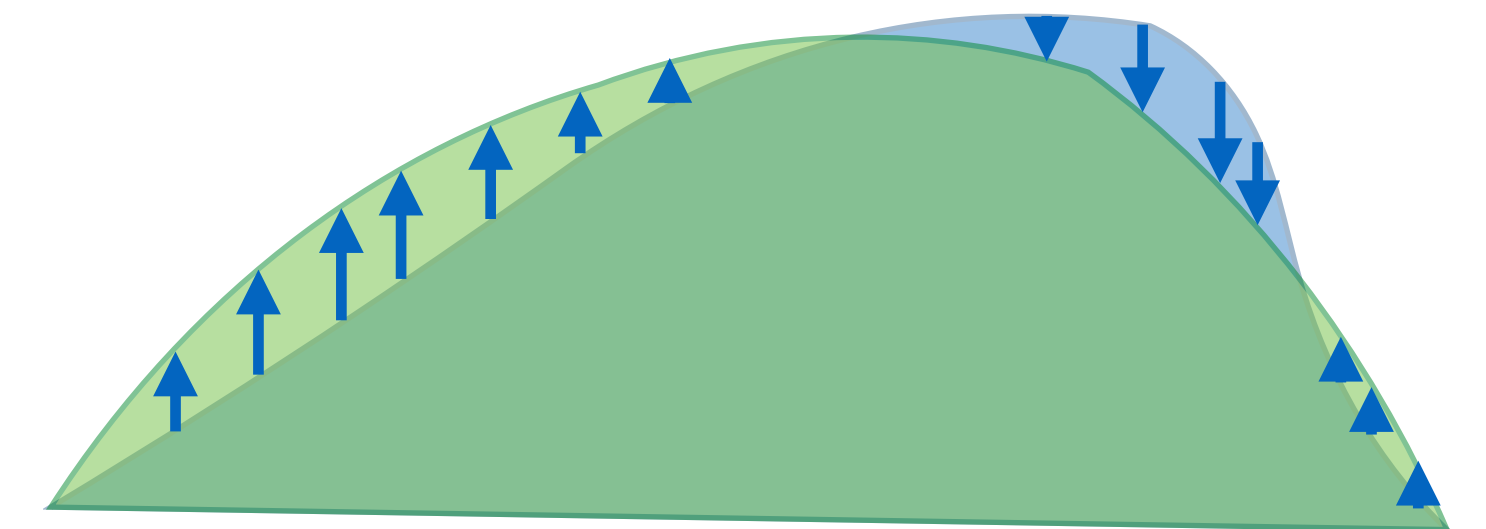
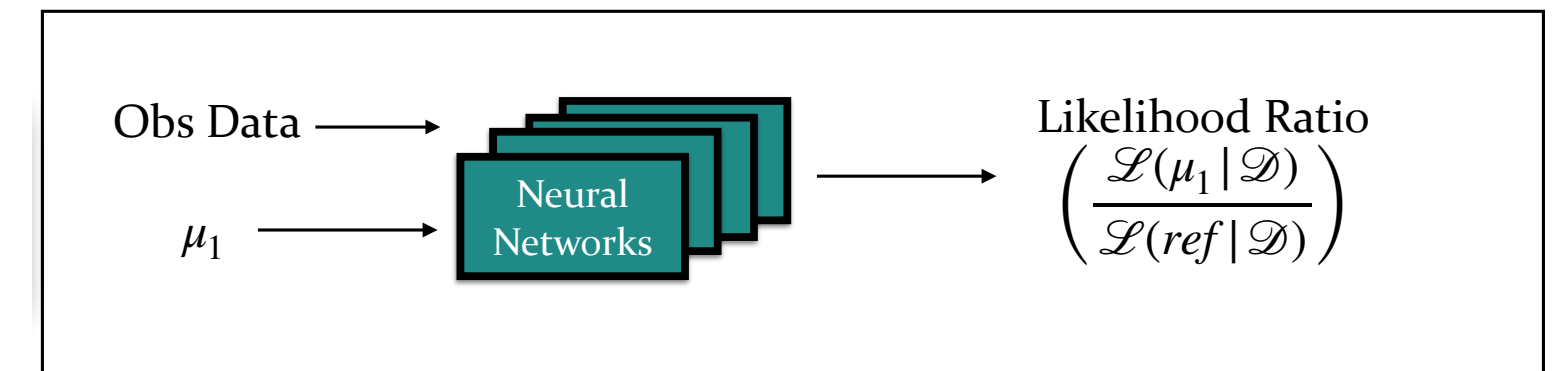


Enhanced Interpretability: Effect of nuisance parameters



Conclusion

- Quantum interference breaks assumptions in traditional statistical methods at LHC
- Neural inference can optimally handle these challenges for Higgs width:
 - Shown in phenomenology study
 - Developed method for deployment in ATLAS
 - Re-analysed Run 2 data and achieved a dramatic improvement in sensitivity ($H \rightarrow 4l$)
- NSBI has wide-ranging applications, in particle physics, astrophysics and beyond!
- Weaknesses: Same as traditional analyses (systematics, training statistics). Developed diagnostic tools to help



Thanks !

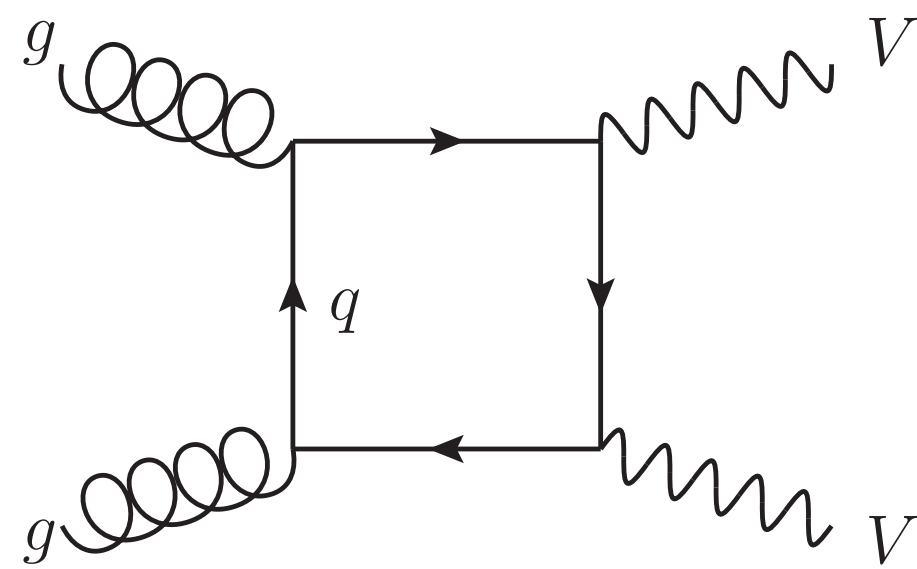
Reach out: Email

Non-linear problem

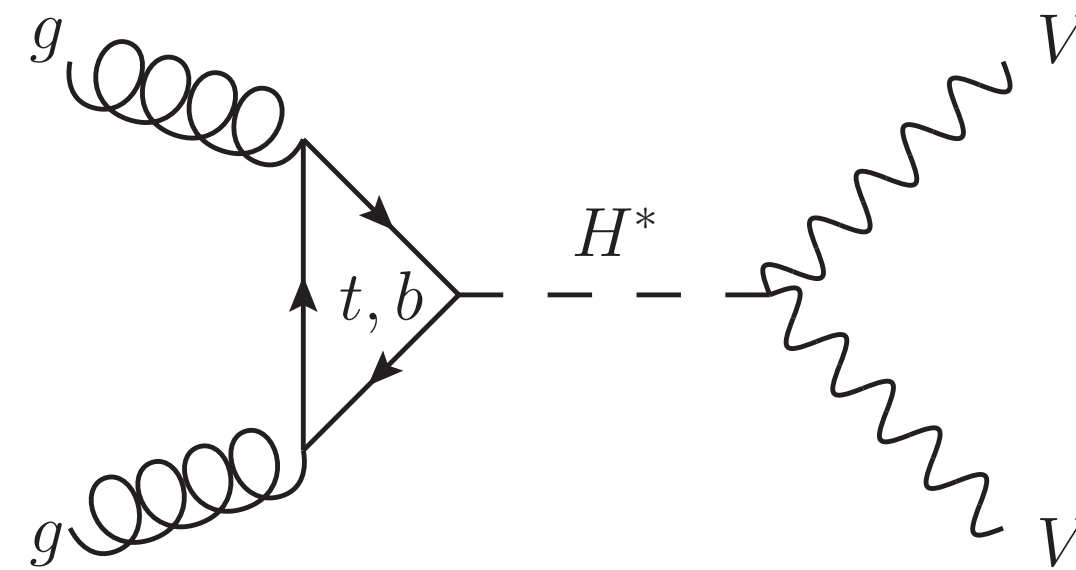
hal-02971995v3: Ghosh et al.

$$P(X) = |M_s(X) + M_b(X)|^2 = \underbrace{|M_s(X)|^2}_{P_s(X)} + \underbrace{|M_b(X)|^2}_{P_b(X)} + \underbrace{2 \operatorname{Re}(\overline{M_s(X)} M_b(X))}_{P_i(X)}$$

This term is negative



gg Background



ggF Signal

Scale by signal strength μ :

$$|M_s(X)|^2 \rightarrow |\sqrt{\mu} \cdot M_s(X)|^2,$$

$$P_{\text{scaled}}(X) = \mu \cdot P_s(X) + P_b(X) + \sqrt{\mu} \cdot P_i(X).$$

Choice of observable

Choice of observable

$$\mathcal{L}(\mu | \mathcal{D}) = p(\mathcal{D} | \mu)$$

Neyman–Pearson lemma: Likelihood ratio is the most powerful test statistic

$$\frac{p(\mathcal{D} | \mu)}{p(\mathcal{D} | \mu_0)}$$

We want to compare likelihoods:

Choice of observable

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$$\frac{p(\mathcal{D} | \mu)}{p(\mathcal{D} | \mu_0)}$$

A neural network classifier trained on S vs B, estimates the decision function*:

$$s(x_i) = \frac{p(x_i | S)}{p(x_i | S) + p(x_i | B)}$$

Choice of observable

$$\mathcal{L}(\mu | \mathcal{D}) = p(\mathcal{D} | \mu)$$

Neyman–Pearson lemma: Likelihood ratio is the most powerful test statistic

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$$\frac{p(\mathcal{D} | \mu)}{p(\mathcal{D} | \mu_0)}$$

A neural network classifier trained on S vs B, estimates the decision function*:

$$s(x_i) = \frac{p(x_i | S)}{p(x_i | S) + p(x_i | B)}$$

Which contains all the information required for the likelihood ratio:

$$\frac{p(x_i | \mu)}{p(x_i | \mu = 0)} = \frac{1}{\mu \cdot \nu_S + \nu_B} \frac{\mu \cdot \nu_S p(x_i | S) + \nu_B p(x_i | B)}{p(x_i | B)} = \frac{\mu}{\mu \cdot \nu_S + \nu_B} \cdot \frac{s(x_i)}{1 - s(x_i)} + \nu_B$$

Same observable s is optimal to test all μ hypotheses!

No need to develop separate analysis per hypothesis μ

* Equal class weights

What breaks down?

$$P(X) = |M_s(X) + M_b(X)|^2 = \underbrace{|M_s(X)|^2}_{P_s(X)} + \underbrace{|M_b(X)|^2}_{P_b(X)} + \underbrace{2 \operatorname{Re}(\overline{M_s(X)} M_b(X))}_{P_i(X)}$$

$$N_{exp} = \mu \cdot S + B + \sqrt{\mu} \cdot I$$

A neural network classifier trained on S vs B, estimates the decision function*: $s(x_i) = \frac{p(x_i|S)}{p(x_i|S) + p(x_i|B)}$

Which contains all the information required for the likelihood ratio:

$$\frac{p(x_i|\mu)}{p(x_i|\mu=0)} = \frac{1}{\mu \cdot \nu_S + \nu_B} \frac{\mu \cdot \nu_S p(x_i|S) + \nu_B p(x_i|B)}{p(x_i|B)} = \frac{\mu}{\mu \cdot \nu_S + \nu_B} \cdot \frac{s(x_i)}{1 - s(x_i)} + \nu_B$$

* Equal class weights

Same observable s is optimal to test all μ hypotheses!
No need to develop separate analysis per hypothesis μ

54

No longer in this convenient spacial case: The same observable **no longer optimal due to non-linear effects** coming from quantum interference

Also does not generalise to an arbitrary theory parameter θ , (eg. Effective Field Theory parameters)

Can we modify the LHC analysis methodology to **design near-optimal analyse for the general case?**

Estimating high-dimensional density ratios

$$\mathcal{L}(\mu | \mathcal{D}) = p(\mathcal{D} | \mu)$$

Neyman–Pearson lemma: Likelihood ratio is the most powerful test statistic

We want to compare likelihoods:

$$\frac{p(\mathcal{D} | \mu)}{p(\mathcal{D} | ref)}$$

A neural network classifier trained on simulated samples from θ_1 vs simulated samples from *ref*, estimates the decision function:

$$s(x_i) = \frac{p(x_i | \mu_1)}{p(x_i | \mu_1) + p(x_i | ref)}$$

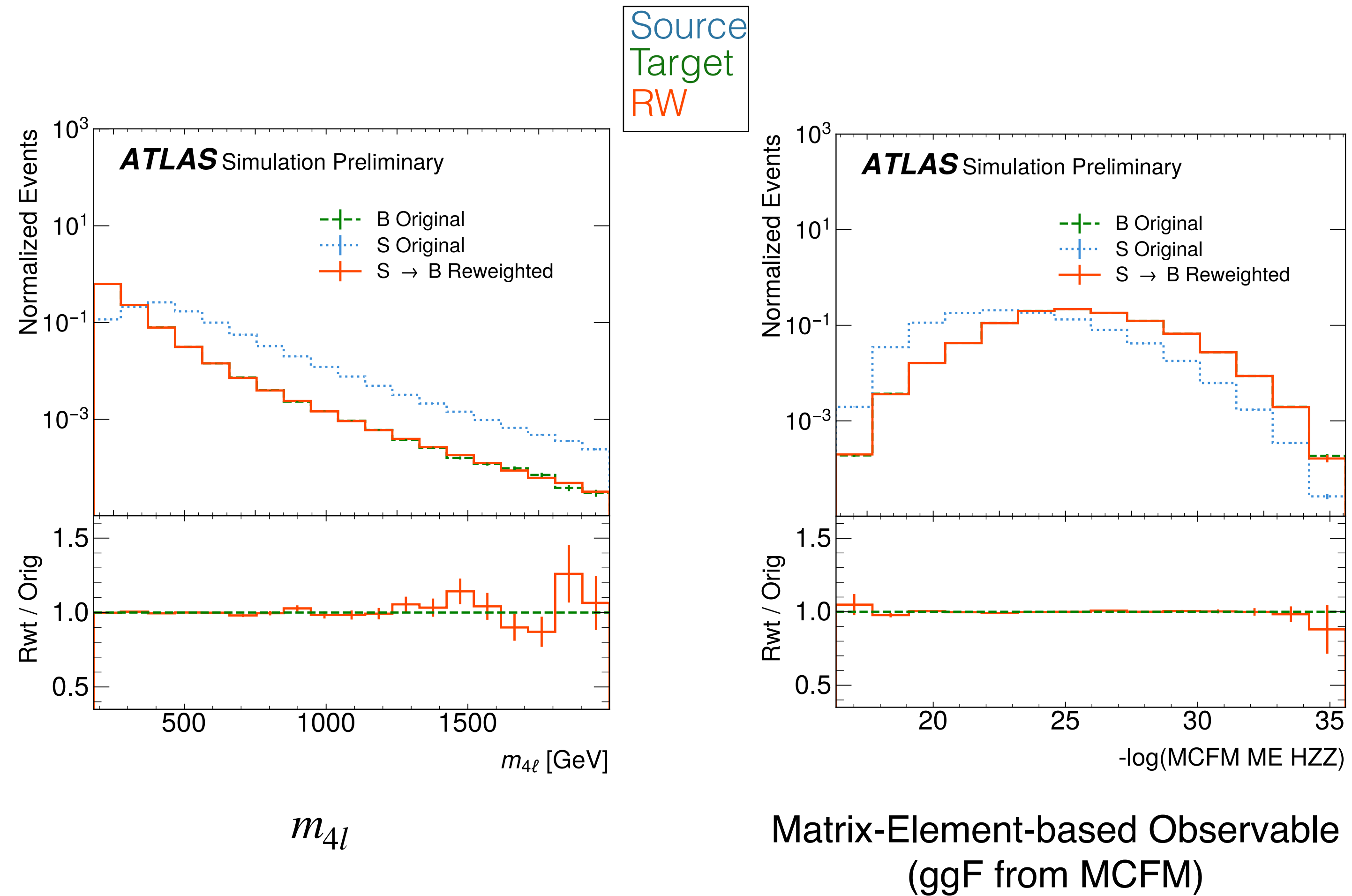
Which contains all the information required for the likelihood ratio:

$$\frac{p(x_i | \mu_1)}{p(x_i | ref)} = \frac{s(x_i)}{1 - s(x_i)}$$

- * Optimal statistic to test each value of μ
- * We get the LR *per event* (unbinned)

More diagnostics

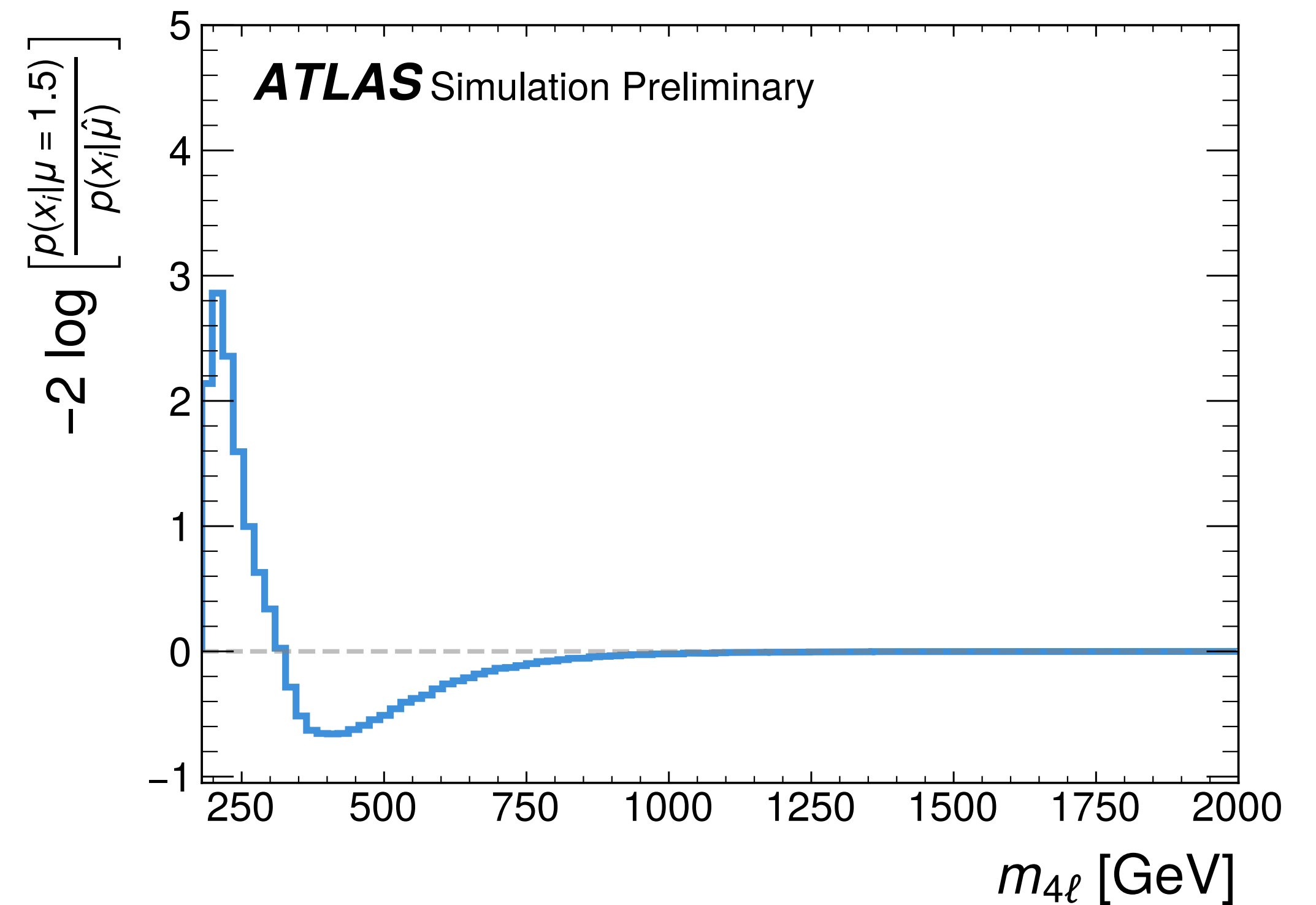
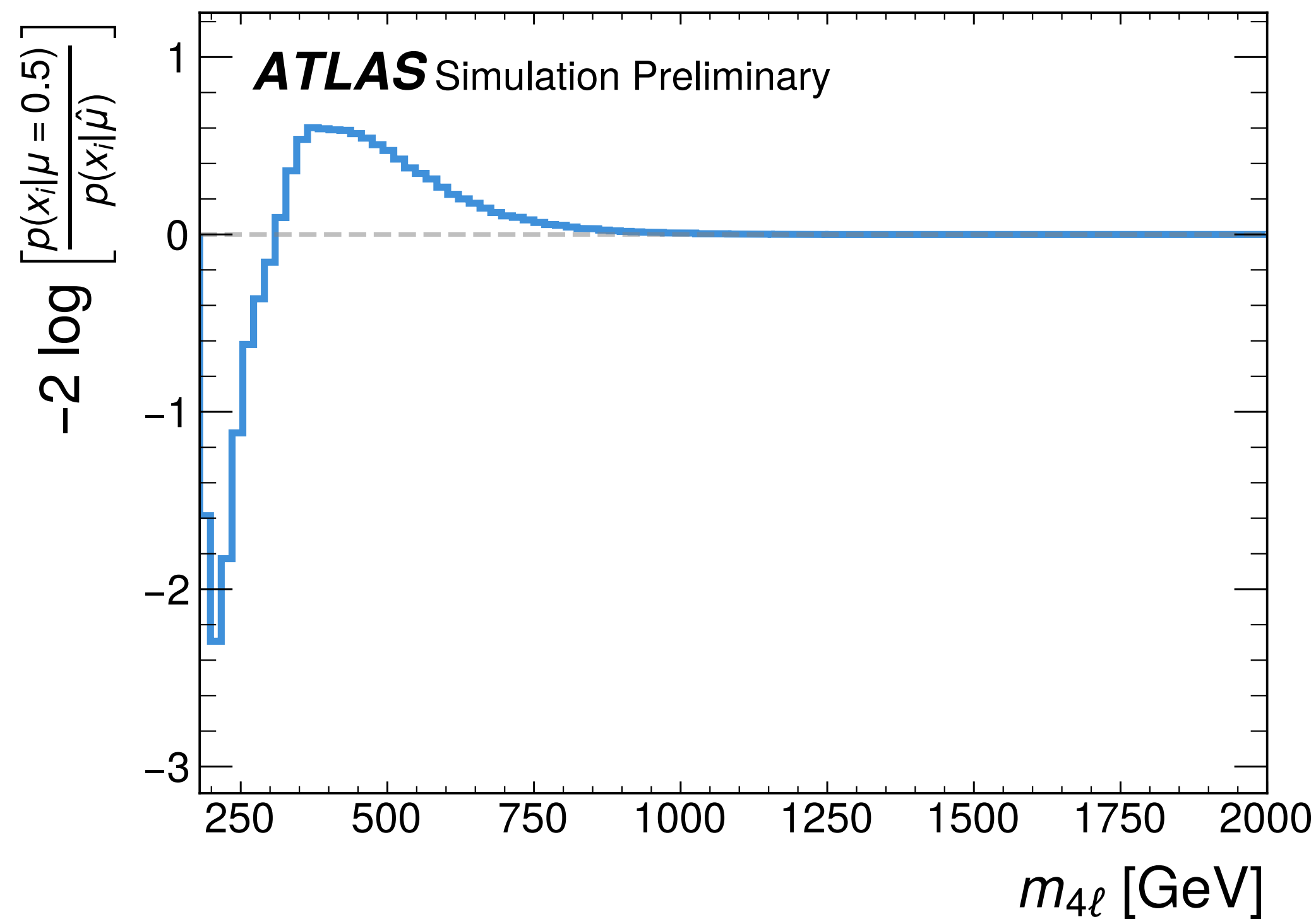
Re-weight closures for B



Interpretability:
Which phase space favours one hypothesis over another?

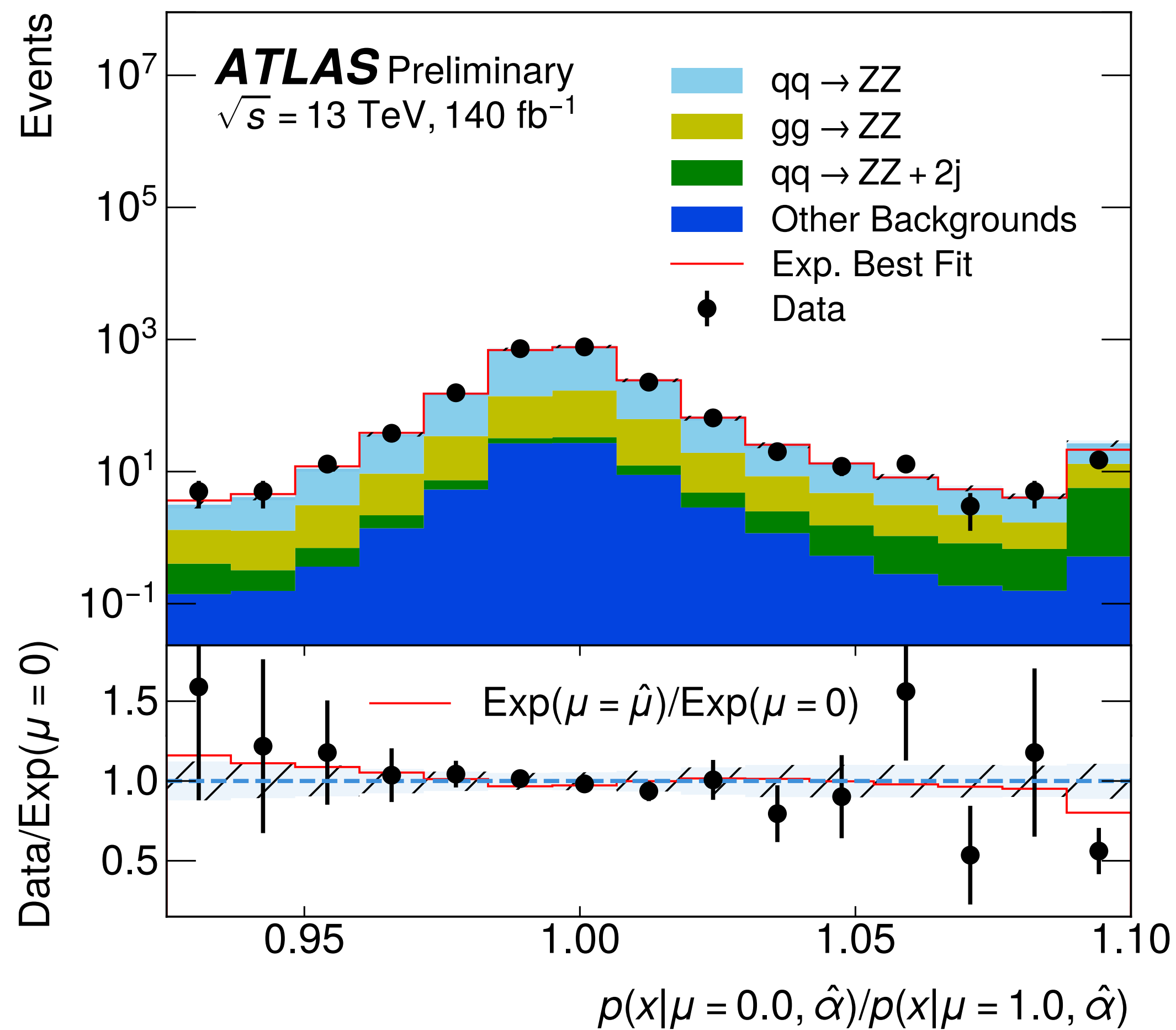
$$-2 \cdot \log \frac{P(x_i | \mu = 0.5)}{P(x_i | \mu = 1)}$$

$$-2 \cdot \log \frac{P(x_i | \mu = 1.5)}{P(x_i | \mu = 1)}$$

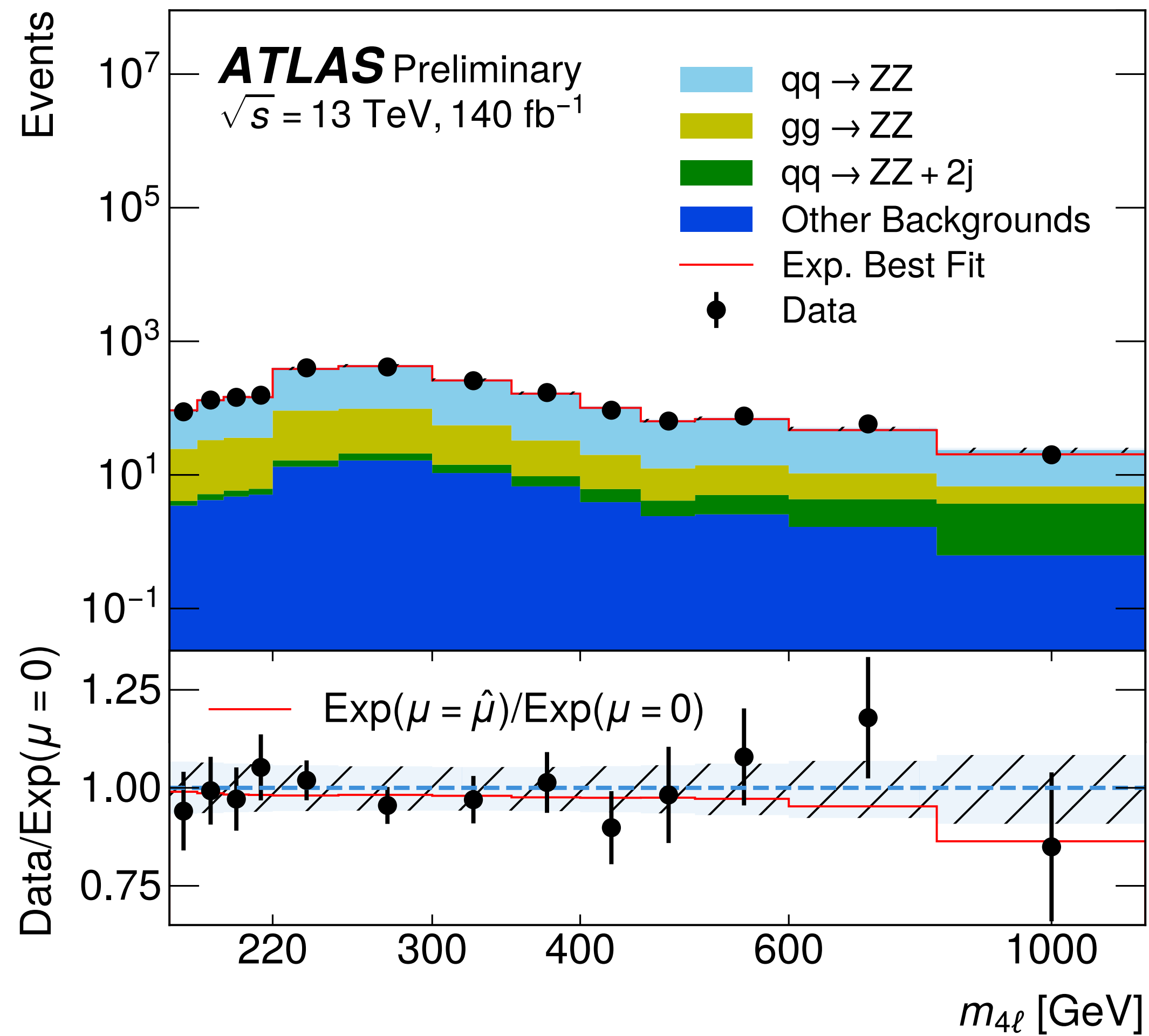


Data-MC validation

NN observable

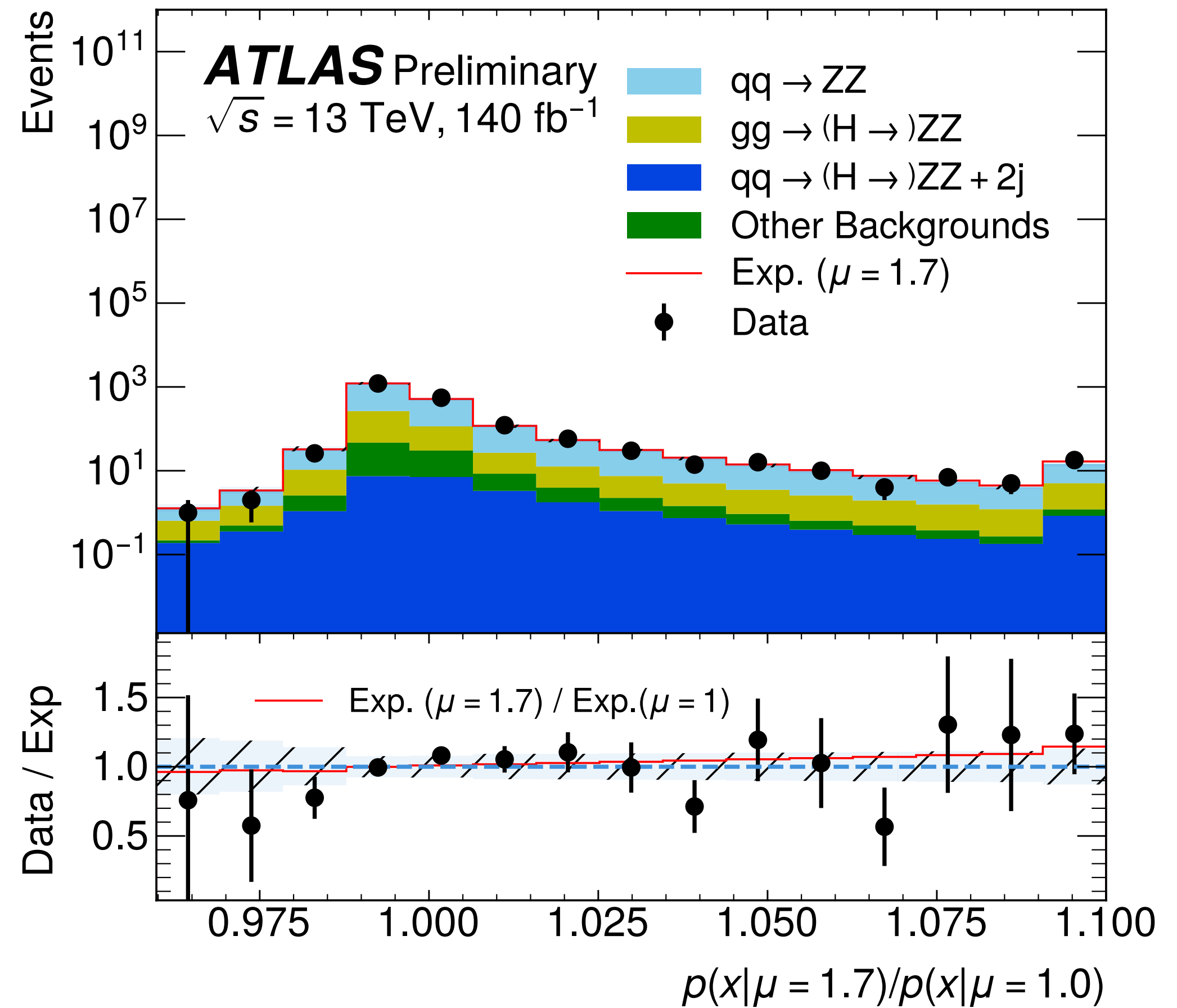
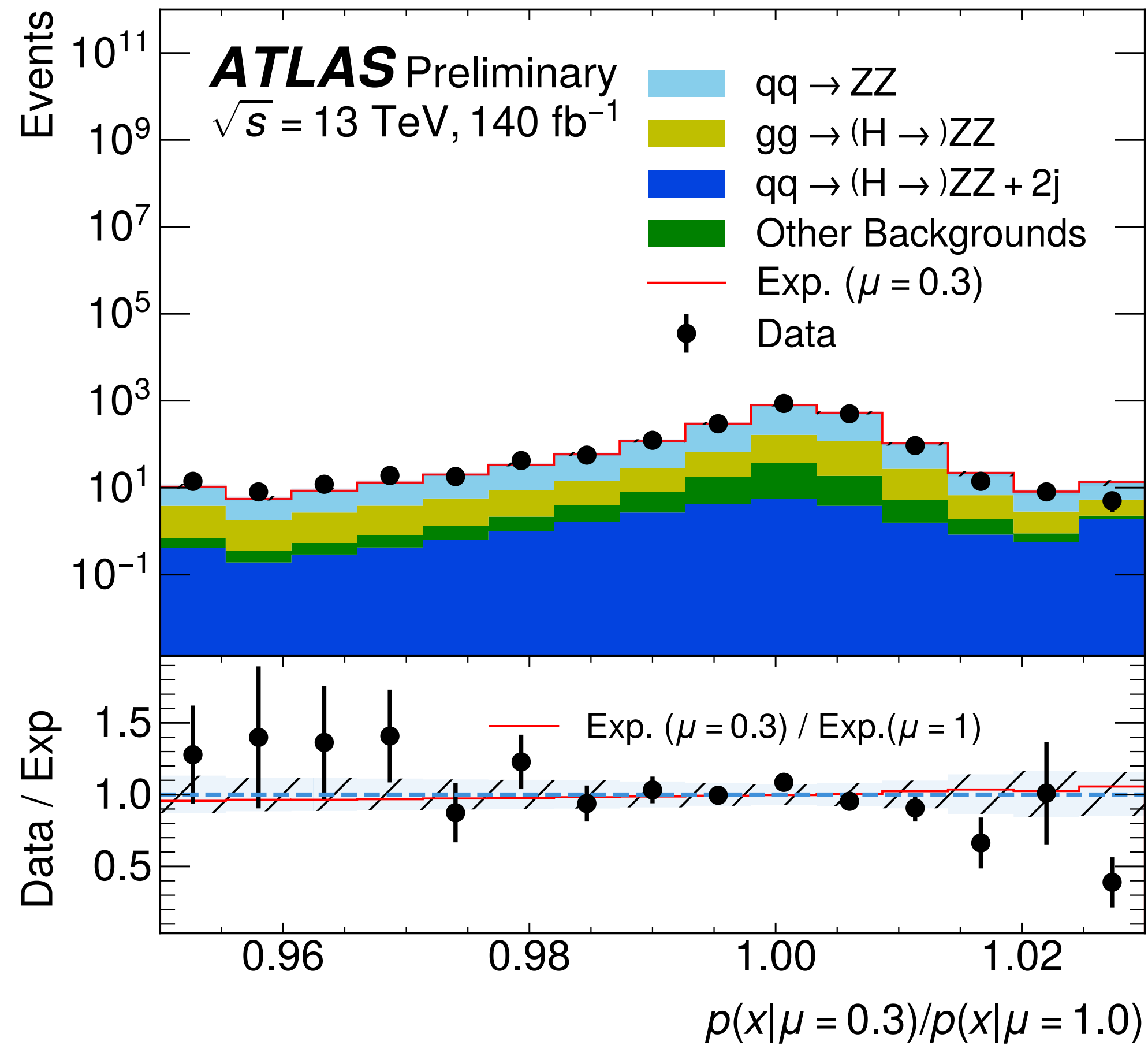


m_{4l}



Data-MC validation

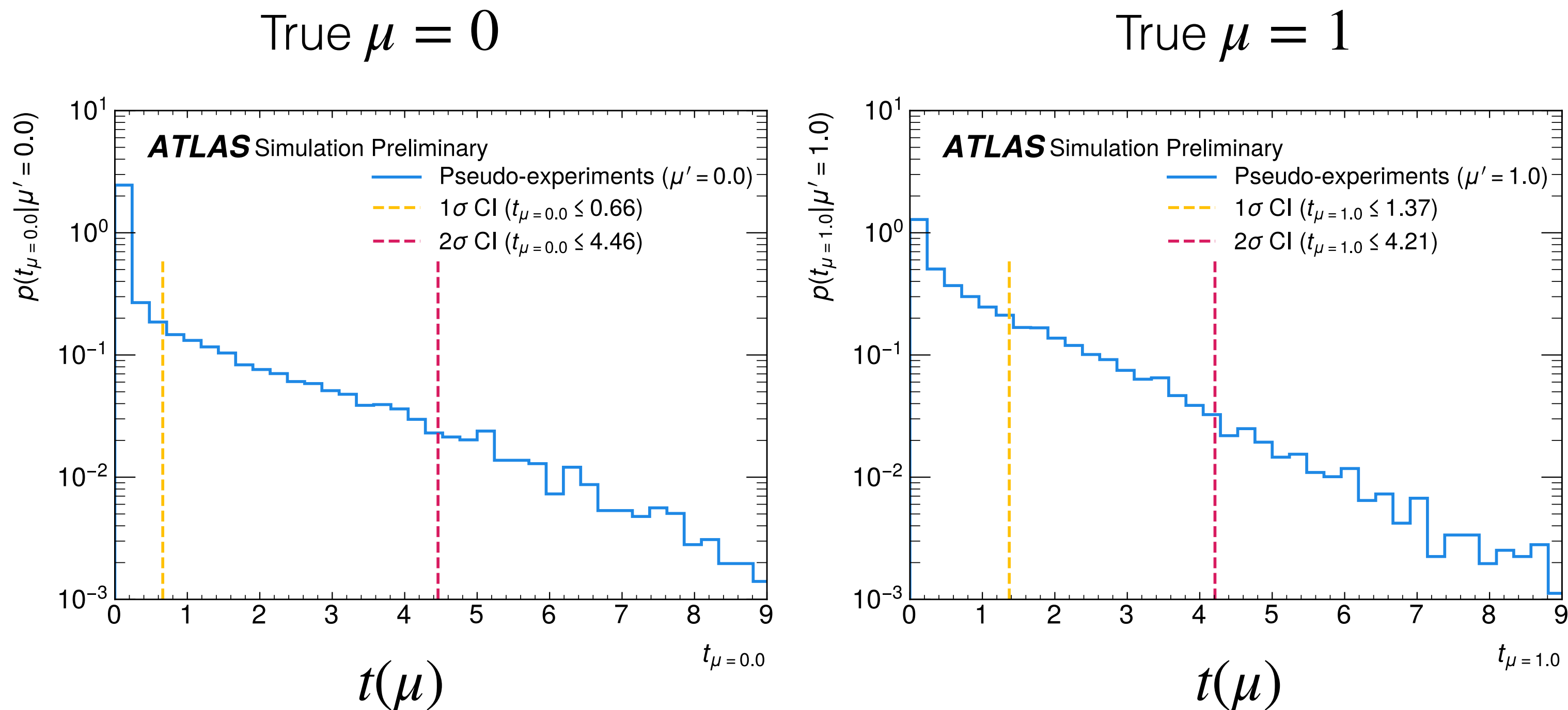
Different NN observables



Neyman construction

Neyman Construction

- To build confidence intervals, we need to ‘invert the hypothesis test’
- Generate pseudo-experiments (‘toys’) and determine 1σ & 2σ CI as a function of parameter of interest



Negative Weighted Events

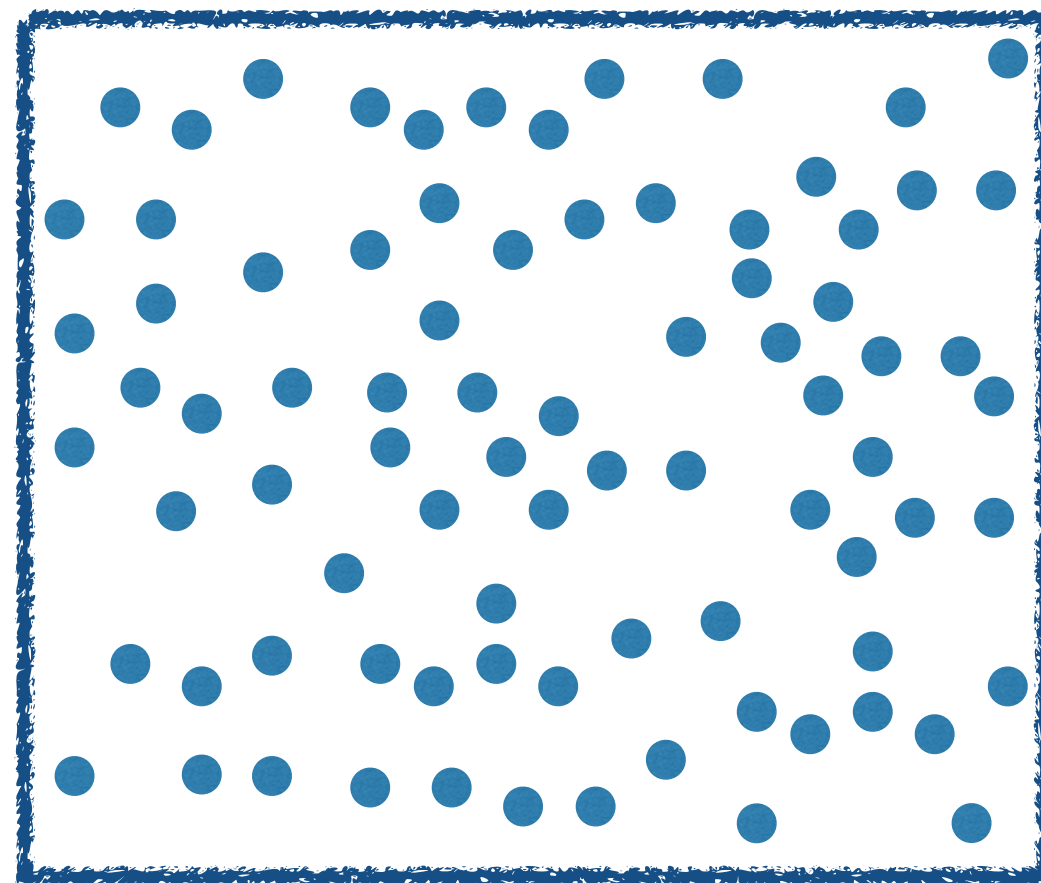
1. Start from a positive weighted reference sample instead
2. Re-weight to intended parameter point
3. Throw toys from this sample

$$w_i^{\text{rwt-ref}} \rightarrow w_i^{\text{Asimov}}(\mu, \alpha) = \frac{v(\mu, \alpha)}{v_{\text{rwt-ref}}} \cdot \frac{p(x_i|\mu, \alpha)}{p_{\text{rwt-ref}}(x_i)} \cdot w_i^{\text{rwt-ref}}$$

Uncertainty from finite training samples

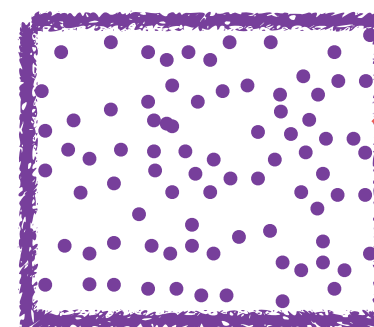
Estimating the variance on mean: Bootstrapping

Want to estimate mean of population

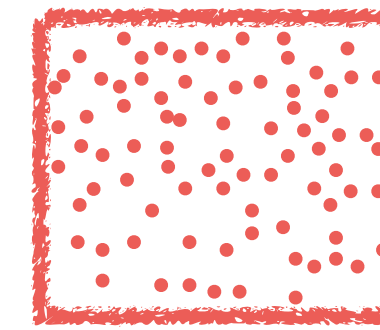


Population

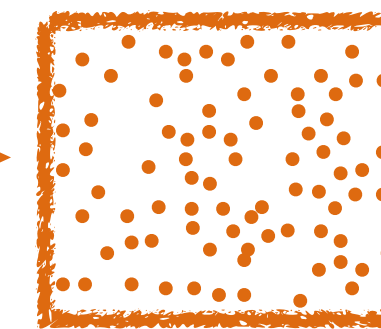
Random Sample



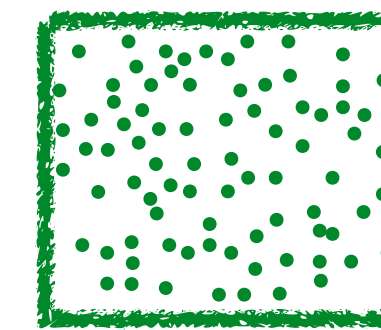
Sample



Sample Mean 1



Sample Mean 2

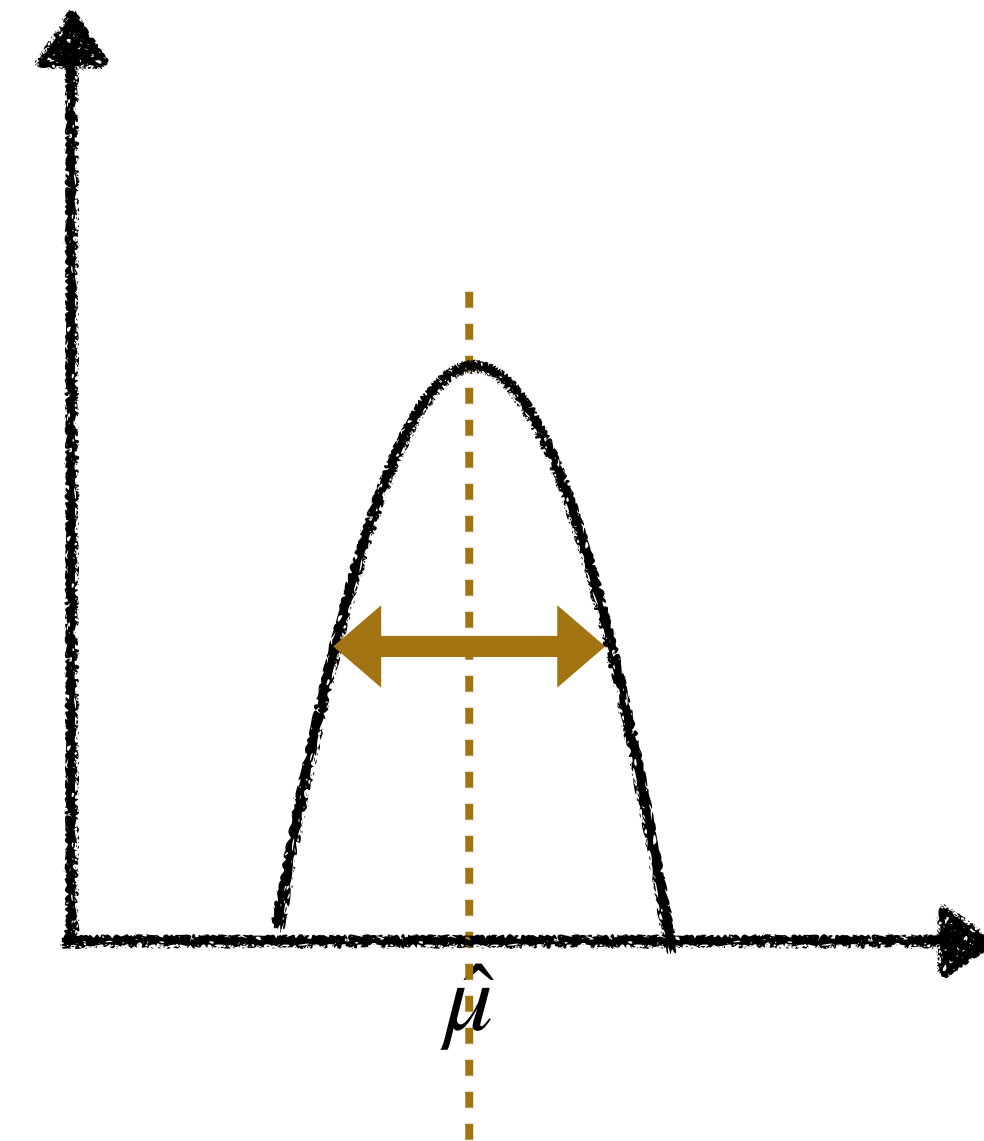


Sample Mean 3

Re-Sample with replacement



Image: [Source](#)

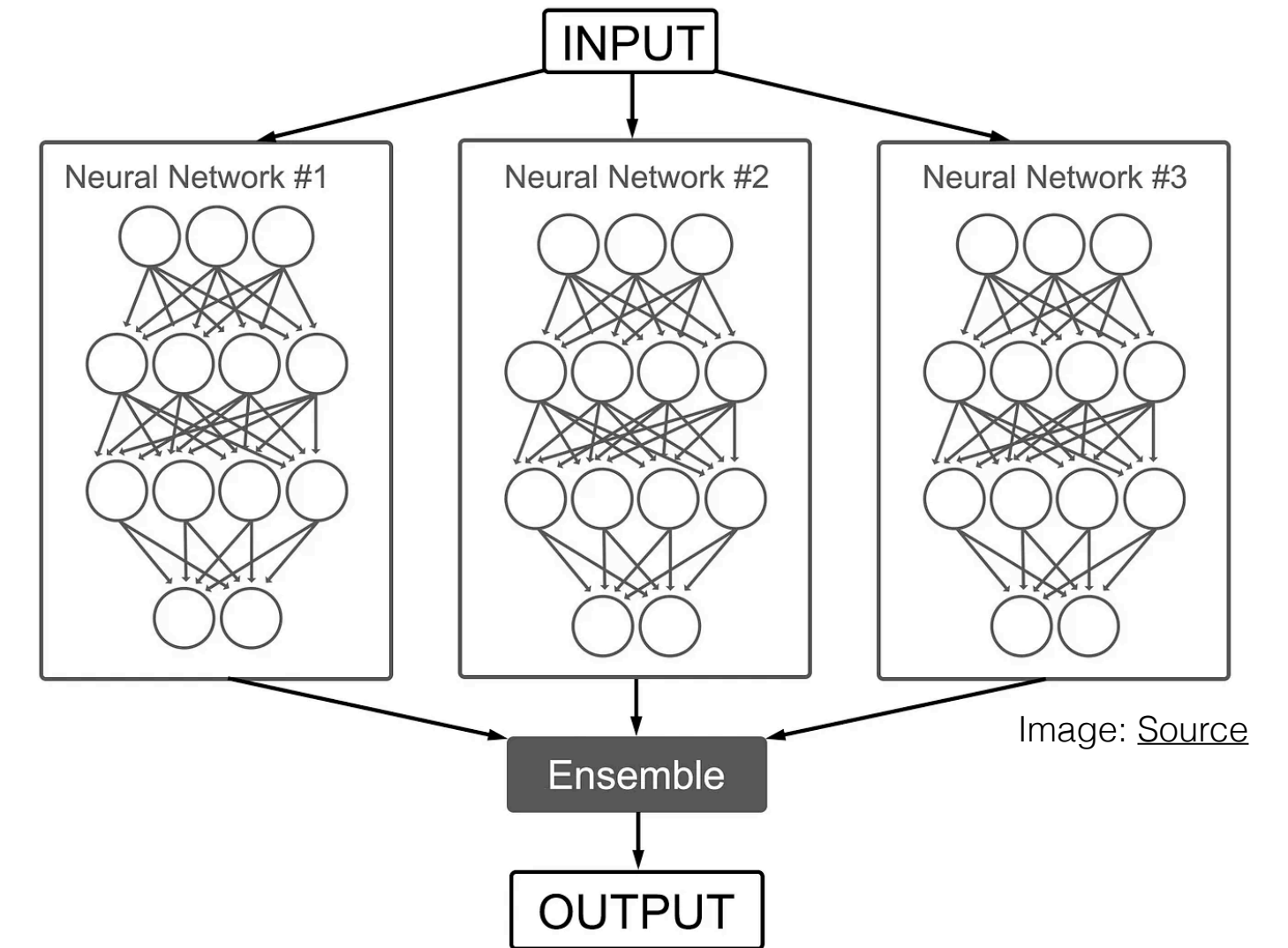


Estimate variance on the mean

Quantifying uncertainty on estimated density ratio

$$w_i \rightarrow w_i \cdot \text{Pois}(1)$$

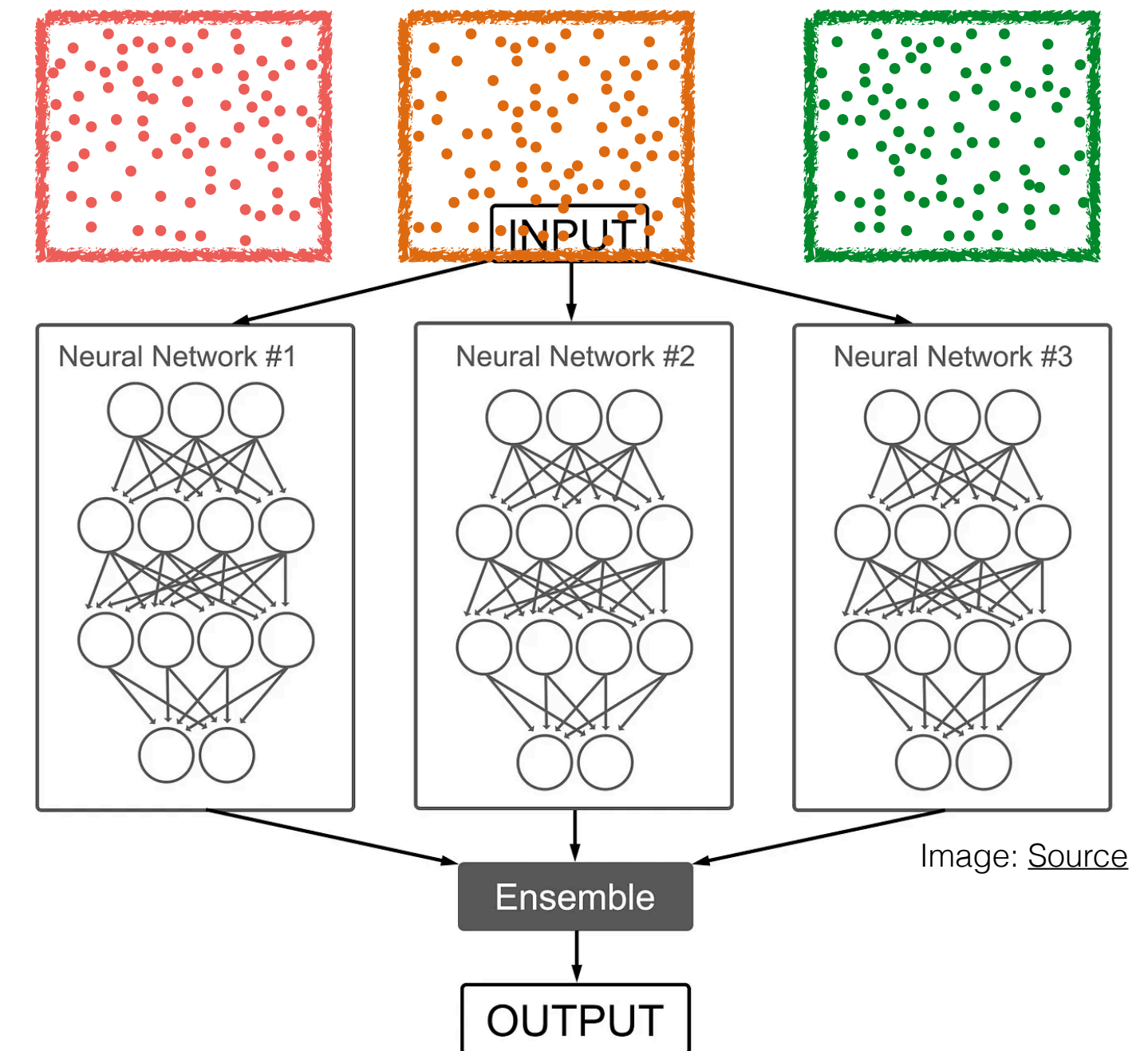
- Train an ensemble of networks, each on a Poisson fluctuated version of the training dataset
- Ensemble average used as final prediction, estimate the variance on mean from bootstrapped ensembles



Quantifying uncertainty on estimated density ratio

$$w_i \rightarrow w_i \cdot \text{Pois}(1)$$

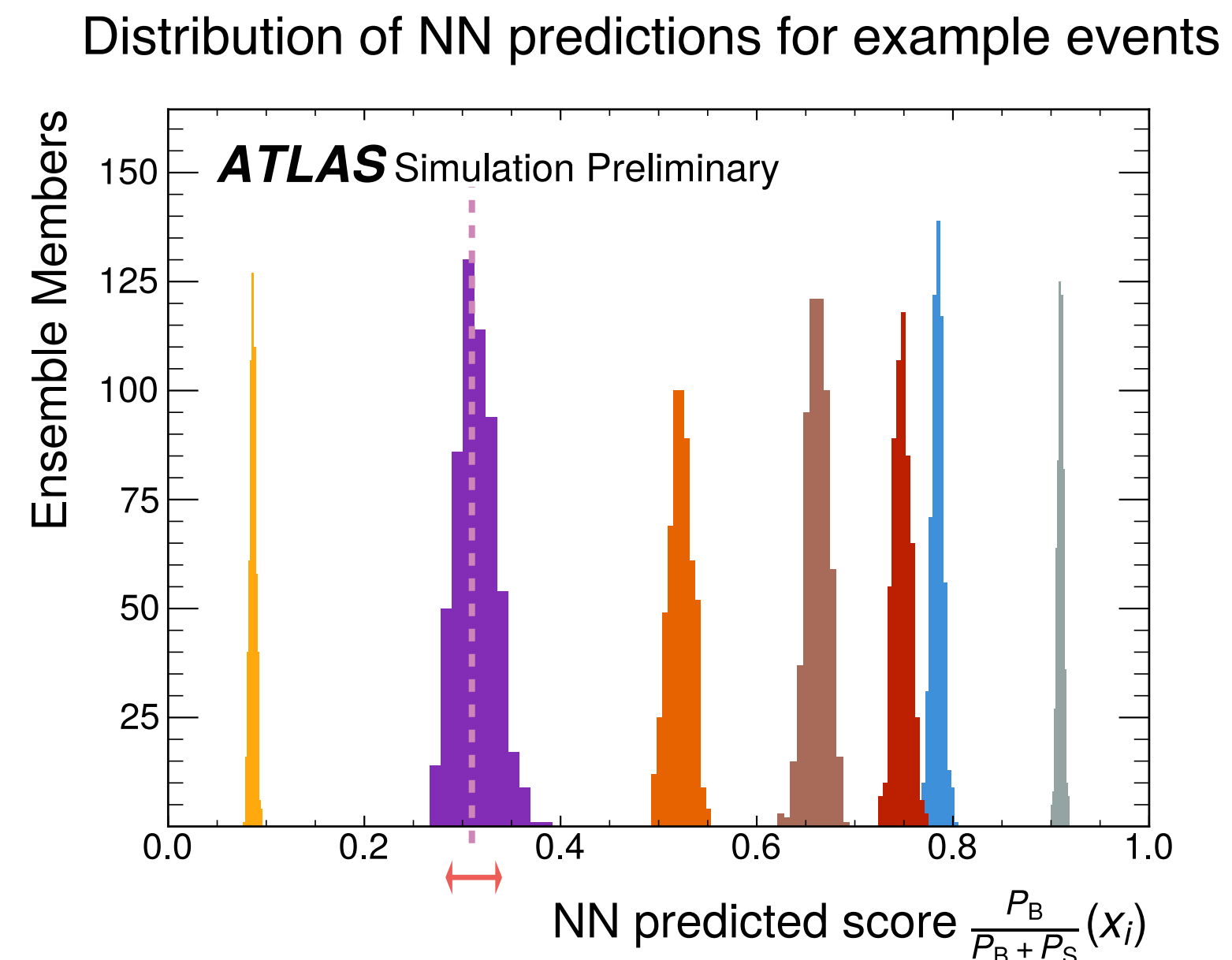
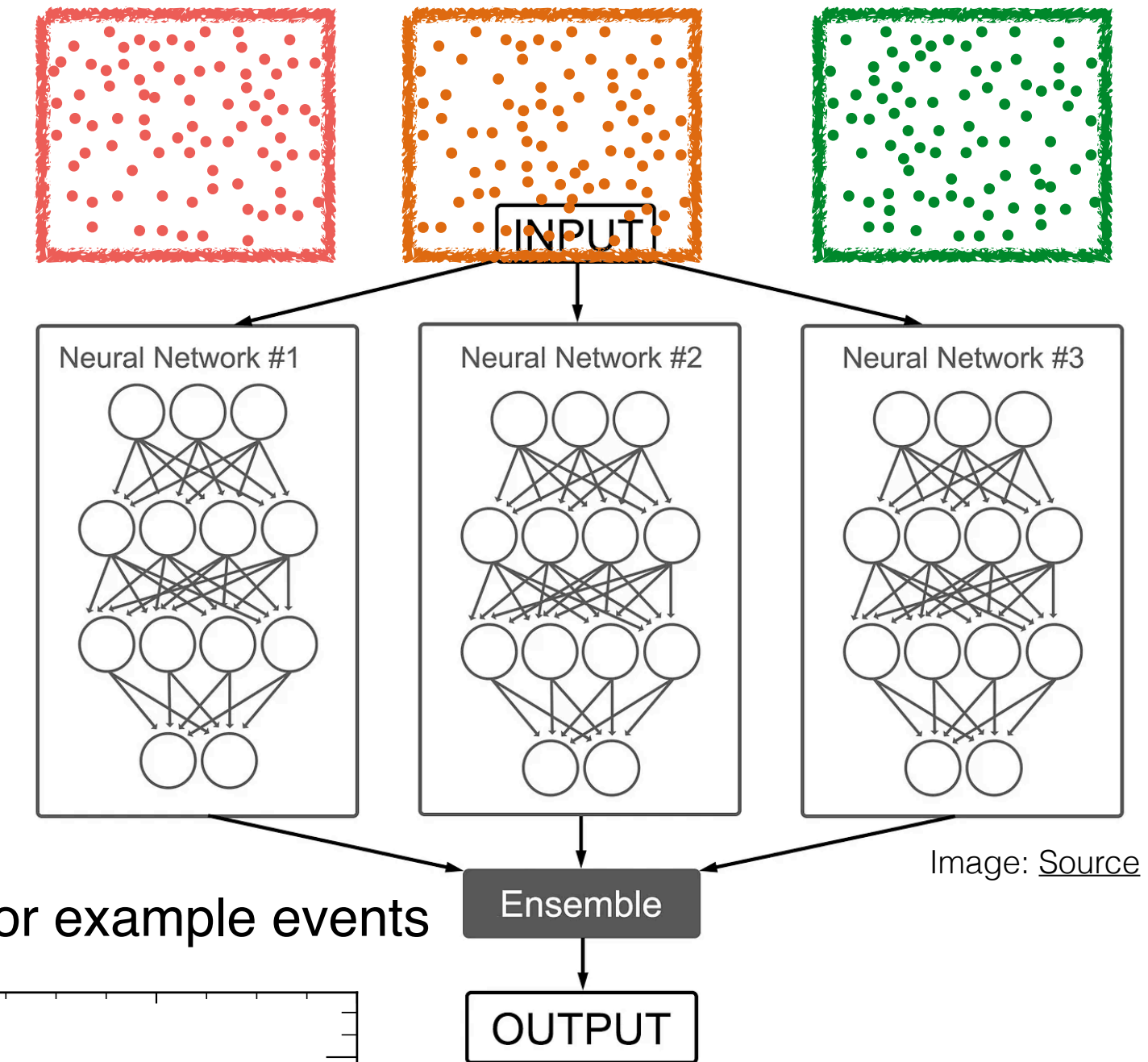
- Train an ensemble of networks, each on a Poisson fluctuated version of the training dataset
- Ensemble average used as final prediction, estimate the variance on mean from bootstrapped ensembles



Quantifying uncertainty on estimated density ratio

$$w_i \rightarrow w_i \cdot \text{Pois}(1)$$

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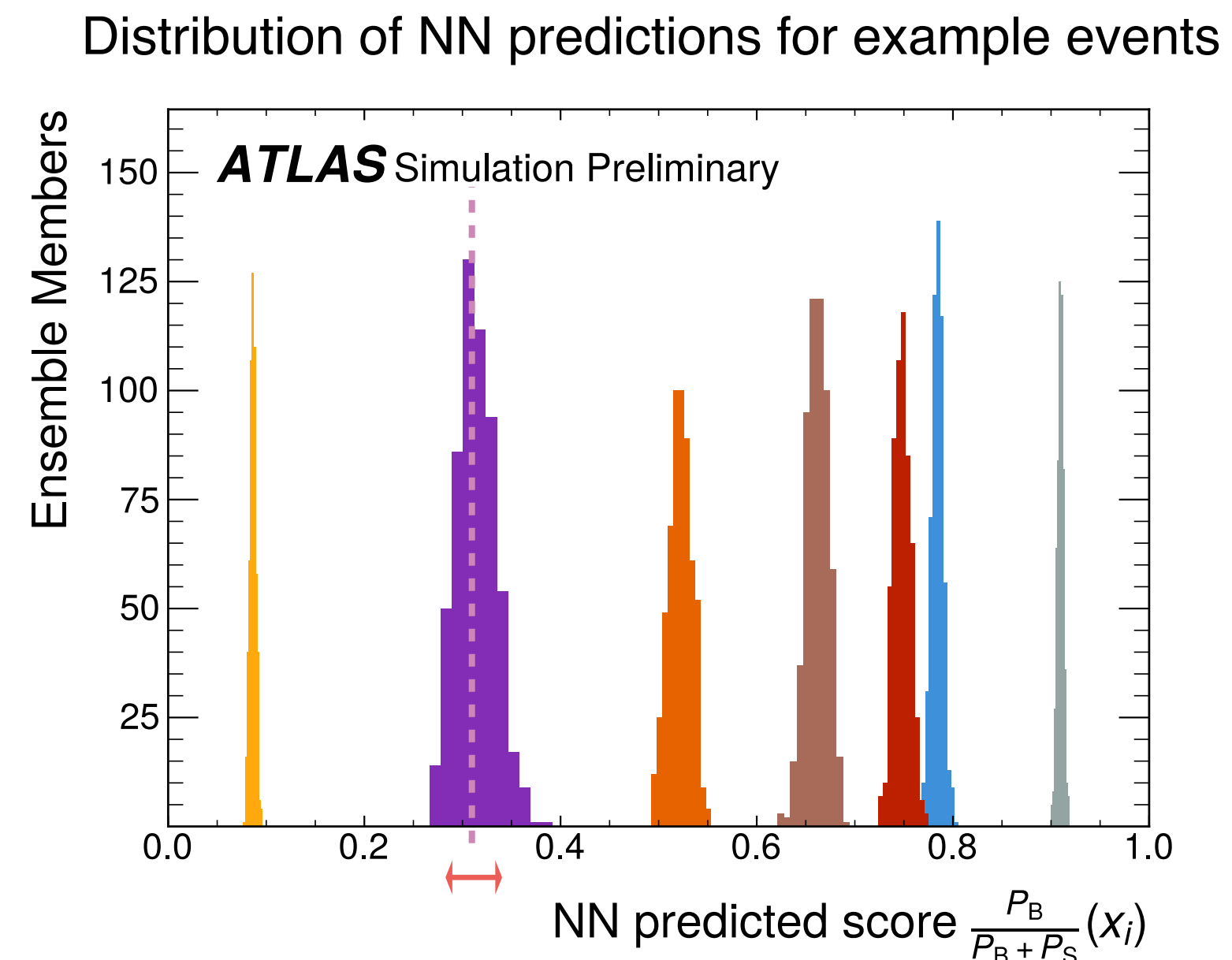
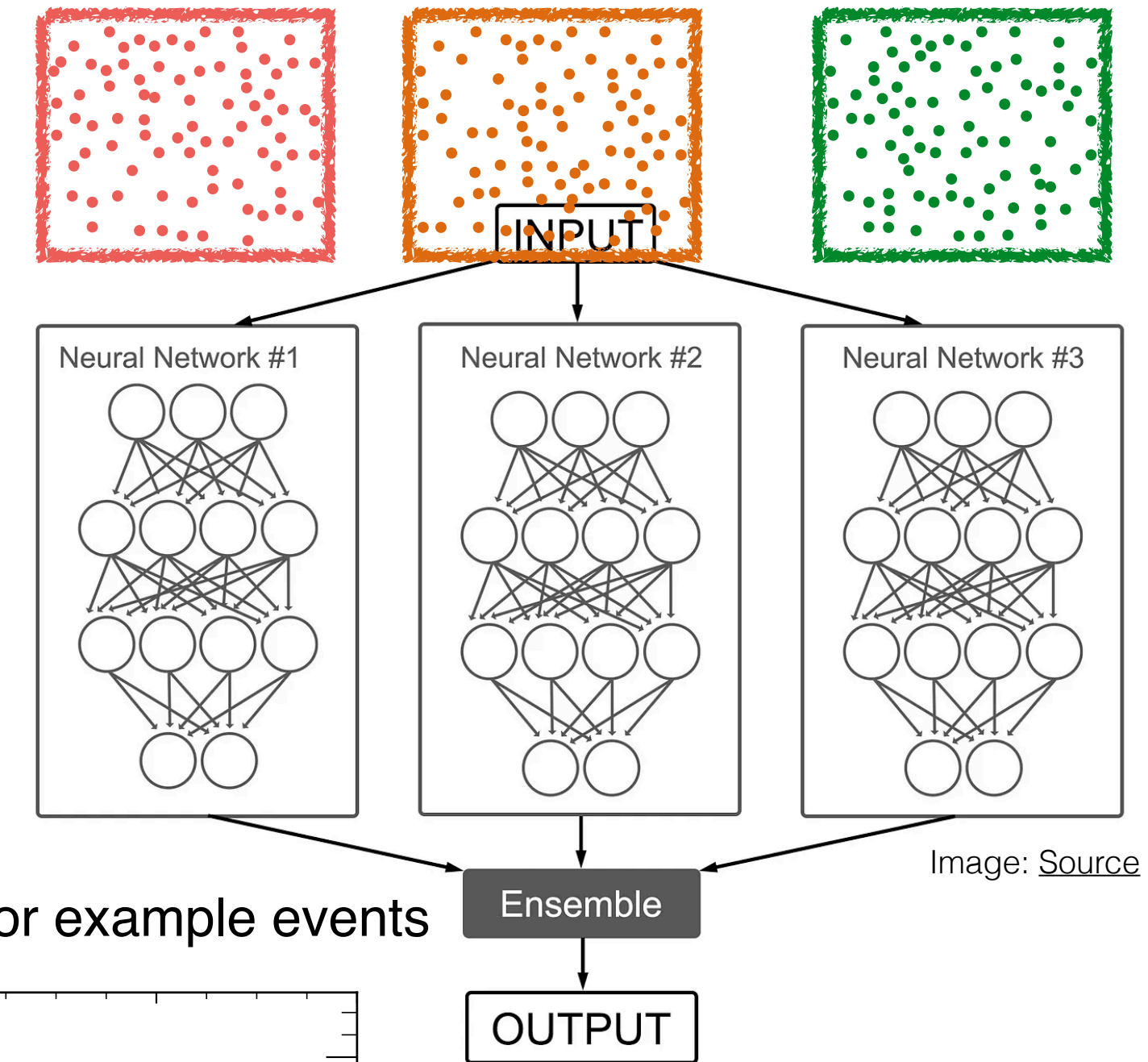
Quantifying uncertainty on estimated density ratio

$$w_i \rightarrow w_i \cdot \text{Pois}(1)$$

- Train an ensemble of networks, each on a Poisson fluctuated version of the training dataset
- Ensemble average used as final prediction, estimate the variance on mean from bootstrapped ensembles
- Propagate with spurious signal method

$$f_j(\mu) \rightarrow f_j(\mu + \alpha \cdot \Delta \hat{\mu}(\mu))$$

Constraint term: $\text{Gauss}(0,1)$



Combination with histogram analyses

$$\frac{L_{\text{comb}}(\mu, \alpha)}{L_{\text{ref}}} = \frac{L_{\text{full}}(\mu, \alpha)}{L_{\text{ref}}} L_{\text{hist}}(\mu, \alpha)$$

Calculating pulls and impacts in JAX

Hessian:

$$C_{nm} = \left[\frac{1}{2} \frac{\partial^2 \lambda}{\partial \alpha_n \partial \alpha_m} (\hat{\mu}, \hat{\alpha}) \right]^{-1}$$

$$\lambda(\mu, \alpha) = -2 \ln(L_{full}(\mu, \alpha) / L_{ref})$$

Pulls:

$$\frac{\hat{\alpha}_k - \alpha_k^0}{\sqrt{C_{kk}}}$$

Post-fit Impact:

$$\begin{aligned} \Gamma_k &= \frac{\partial \hat{\mu}}{\partial \alpha_k} \times \sqrt{C_{kk}} \\ &= - \left[\frac{\partial^2 \lambda}{\partial^2 \mu} (\hat{\mu}, \hat{\alpha}) \right]^{-1} \frac{\partial^2 \lambda}{\partial \mu \partial \alpha_k} (\hat{\mu}, \hat{\alpha}) \times \sqrt{C_{kk}}, \end{aligned}$$

Vertical interpolation

$$G_j(\alpha_k) = \begin{cases} \left(\frac{v_j(\alpha_k^+)}{v_j(\alpha_k^0)} \right)^{\alpha_k} & \alpha_k > 1 \\ 1 + \sum_{n=1}^6 c_n \alpha_k^n & -1 \leq \alpha_k \leq 1 \\ \left(\frac{v_j(\alpha_k^-)}{v_j(\alpha_k^0)} \right)^{-\alpha_k} & \alpha_k < -1 \end{cases} \quad g_j(x_i, \alpha_k) = \begin{cases} \left(g_j(x_i, \alpha_k^+) \right)^{\alpha_k} & \alpha_k > 1 \\ 1 + \sum_{n=1}^6 c_n \alpha_k^n & -1 \leq \alpha_k \leq 1 \\ \left(g_j(x_i, \alpha_k^-) \right)^{-\alpha_k} & \alpha_k < -1 \end{cases}$$

With some continuity requirements

Physics analysis results

Impact of nuisance parameters

Systematic Uncertainty Fixed	$\mu_{\text{off-shell}}$ Value at which $t_{\mu_{\text{off-shell}}} = 4$	
	NSBI analysis	Histogram-based
All (stat-only)	1.96	2.13
Parton shower uncertainty for $gg \rightarrow ZZ$ (normalization)	2.07	2.26
Parton shower uncertainty for $gg \rightarrow ZZ$ (shape)	2.12	2.29
NLO EW uncertainty for $q\bar{q} \rightarrow ZZ$	2.10	2.27
NLO QCD uncertainty for $gg \rightarrow ZZ$	2.09	2.29
Parton shower uncertainty for $q\bar{q} \rightarrow ZZ$ (shape)	2.12	2.29
Jet energy scale and resolution uncertainty	2.11	2.26
None (full result)	2.12	2.30

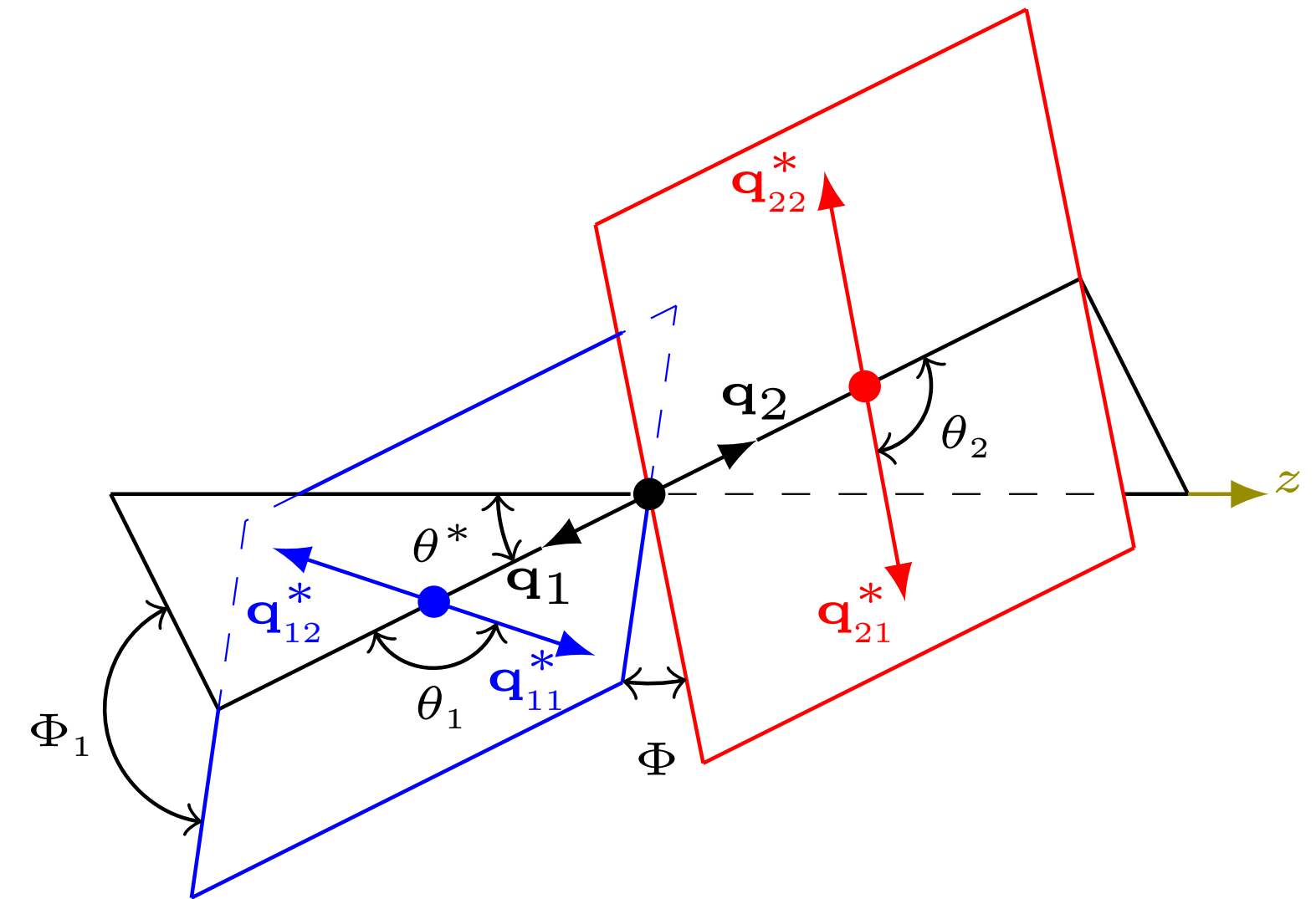
Full probability model, input variables

$$p(x|\mu_{\text{off-shell}}^{\text{ggF}}, \mu_{\text{off-shell}}^{\text{EW}}) = \frac{1}{\nu(\mu_{\text{off-shell}}^{\text{ggF}}, \mu_{\text{off-shell}}^{\text{EW}})} \times$$

$$\left[\mu_{\text{off-shell}}^{\text{ggF}} \nu_{\text{S}}^{\text{ggF}} p_{\text{S}}^{\text{ggF}}(x) + \sqrt{\mu_{\text{off-shell}}^{\text{ggF}}} \nu_{\text{I}}^{\text{ggF}} p_{\text{I}}^{\text{ggF}}(x) + \nu_{\text{B}}^{\text{ggF}} p_{\text{B}}^{\text{ggF}}(x) + \right.$$

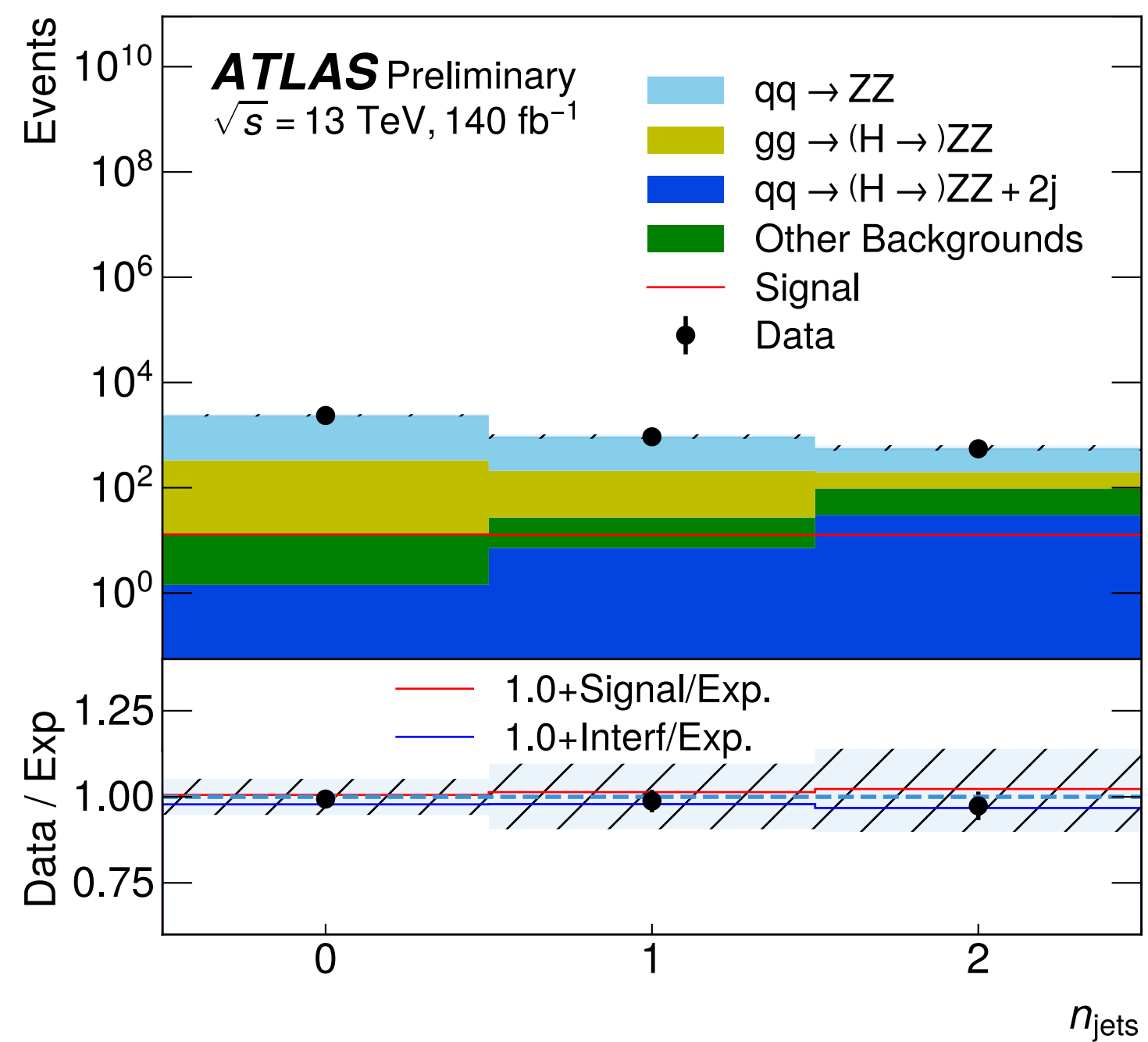
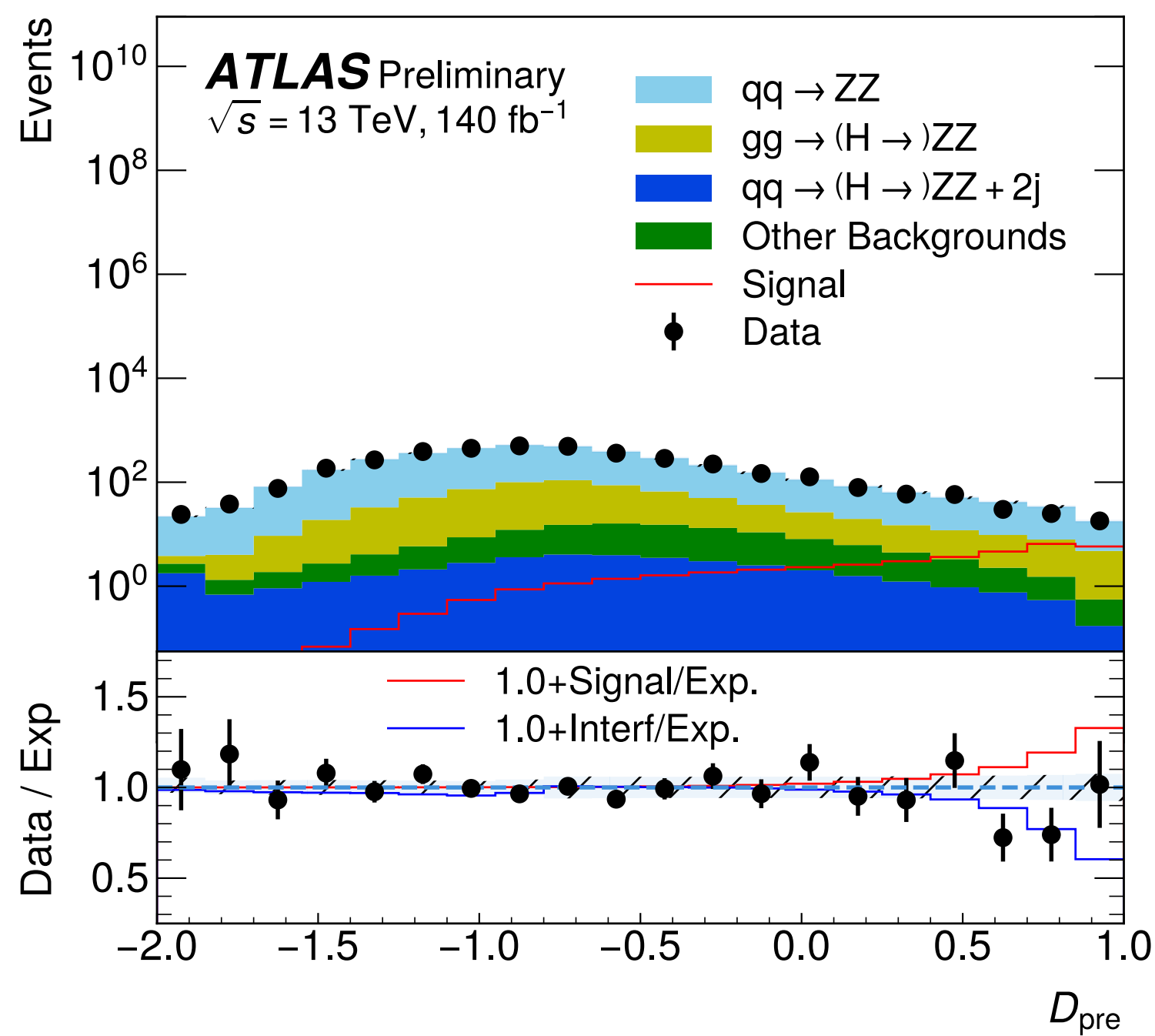
$$\left. \mu_{\text{off-shell}}^{\text{EW}} \nu_{\text{S}}^{\text{EW}} p_{\text{S}}^{\text{EW}}(x) + \sqrt{\mu_{\text{off-shell}}^{\text{EW}}} \nu_{\text{I}}^{\text{EW}} p_{\text{I}}^{\text{EW}}(x) + \nu_{\text{B}}^{\text{EW}} p_{\text{B}}^{\text{EW}}(x) + \nu_{\text{NI}} p_{\text{NI}}(x) \right],$$

Variable	Definition
$m_{4\ell}$	quadruplet mass
m_{Z1}	Z_1 mass
m_{Z2}	Z_2 mass
$\cos \theta^*$	cosine of the Higgs boson decay angle $[\mathbf{q}_1 \cdot \mathbf{n}_z / \mathbf{q}_1]$
$\cos \theta_1$	cosine of the Z_1 decay angle $[-(\mathbf{q}_2) \cdot \mathbf{q}_{11} / (\mathbf{q}_2 \cdot \mathbf{q}_{11})]$
$\cos \theta_2$	cosine of the Z_2 decay angle $[-(\mathbf{q}_1) \cdot \mathbf{q}_{21} / (\mathbf{q}_1 \cdot \mathbf{q}_{21})]$
Φ_1	Z_1 decay plane angle $[\cos^{-1}(\mathbf{n}_1 \cdot \mathbf{n}_{\text{sc}}) (\mathbf{q}_1 \cdot (\mathbf{n}_1 \times \mathbf{n}_{\text{sc}})) / (\mathbf{q}_1 \cdot \mathbf{n}_1 \times \mathbf{n}_{\text{sc}})]$
Φ	angle between Z_1, Z_2 decay planes $[\cos^{-1}(\mathbf{n}_1 \cdot \mathbf{n}_2) (\mathbf{q}_1 \cdot (\mathbf{n}_1 \times \mathbf{n}_2)) / (\mathbf{q}_1 \cdot \mathbf{n}_1 \times \mathbf{n}_2)]$
$p_T^{4\ell}$	quadruplet transverse momentum
$y^{4\ell}$	quadruplet rapidity
n_{jets}	number of jets in the event
m_{jj}	leading dijet system mass
$\Delta\eta_{jj}$	leading dijet system pseudorapidity
$\Delta\phi_{jj}$	leading dijet system azimuthal angle difference



Pre-selection region definition

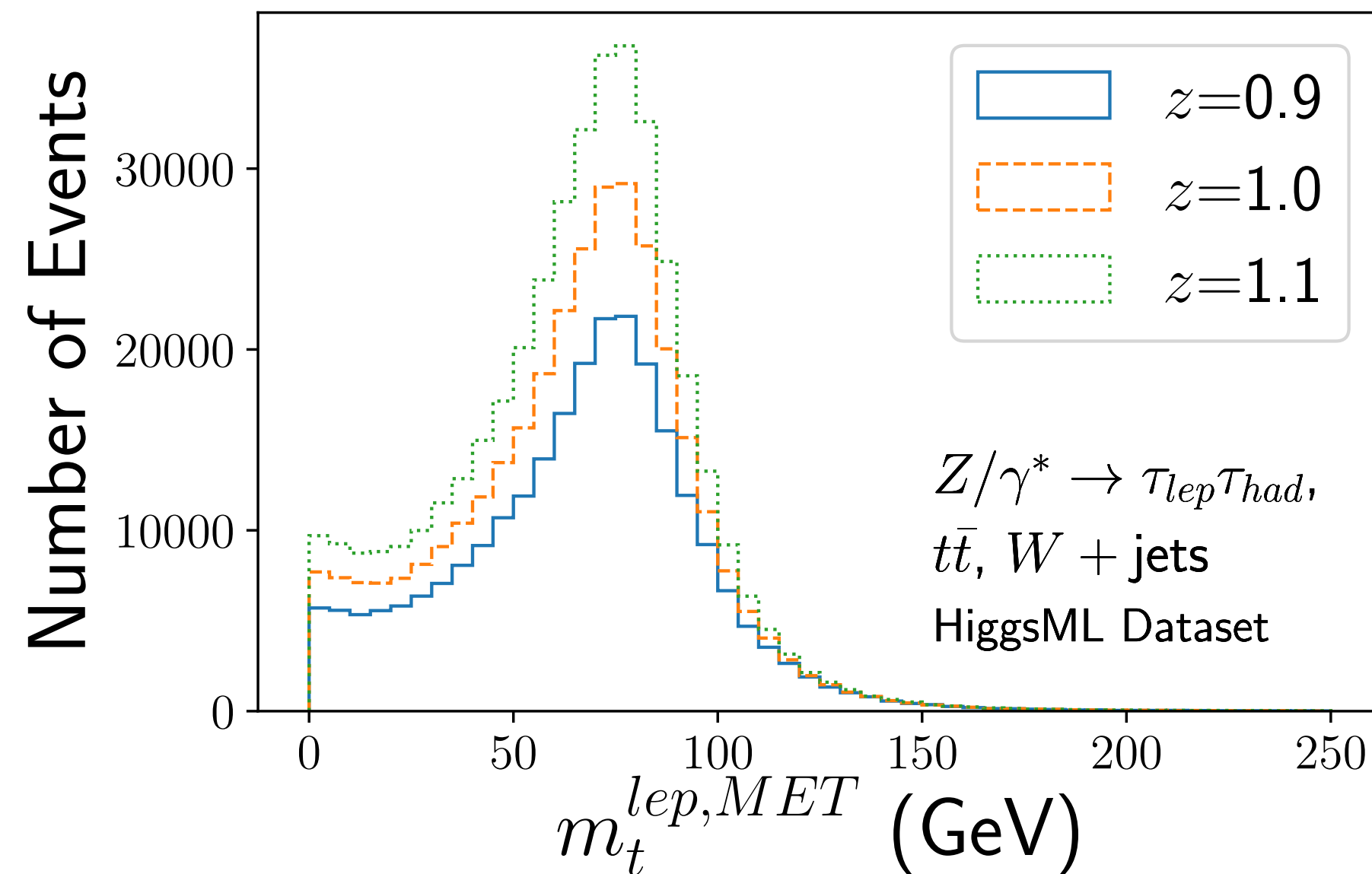
$$D_{\text{pre}}(x) = \log \frac{s_{\text{pre}, S}^{\text{ggF}}(x) + s_{\text{pre}, S}^{\text{EW}}(x)}{s_{\text{pre}, B}^{\text{ggF}}(x) + s_{\text{pre}, B}^{\text{EW}}(x) + s_{\text{pre}, q\bar{q}ZZ}(x)},$$



Traditionally ignoring systematic uncertainties during analysis optimisation

[PRD.104.056026](#): **Aishik Ghosh**, Benjamin Nachman, and Daniel Whiteson

Experimental uncertainties:
Eg. Inaccuracies in the calibration of our detector

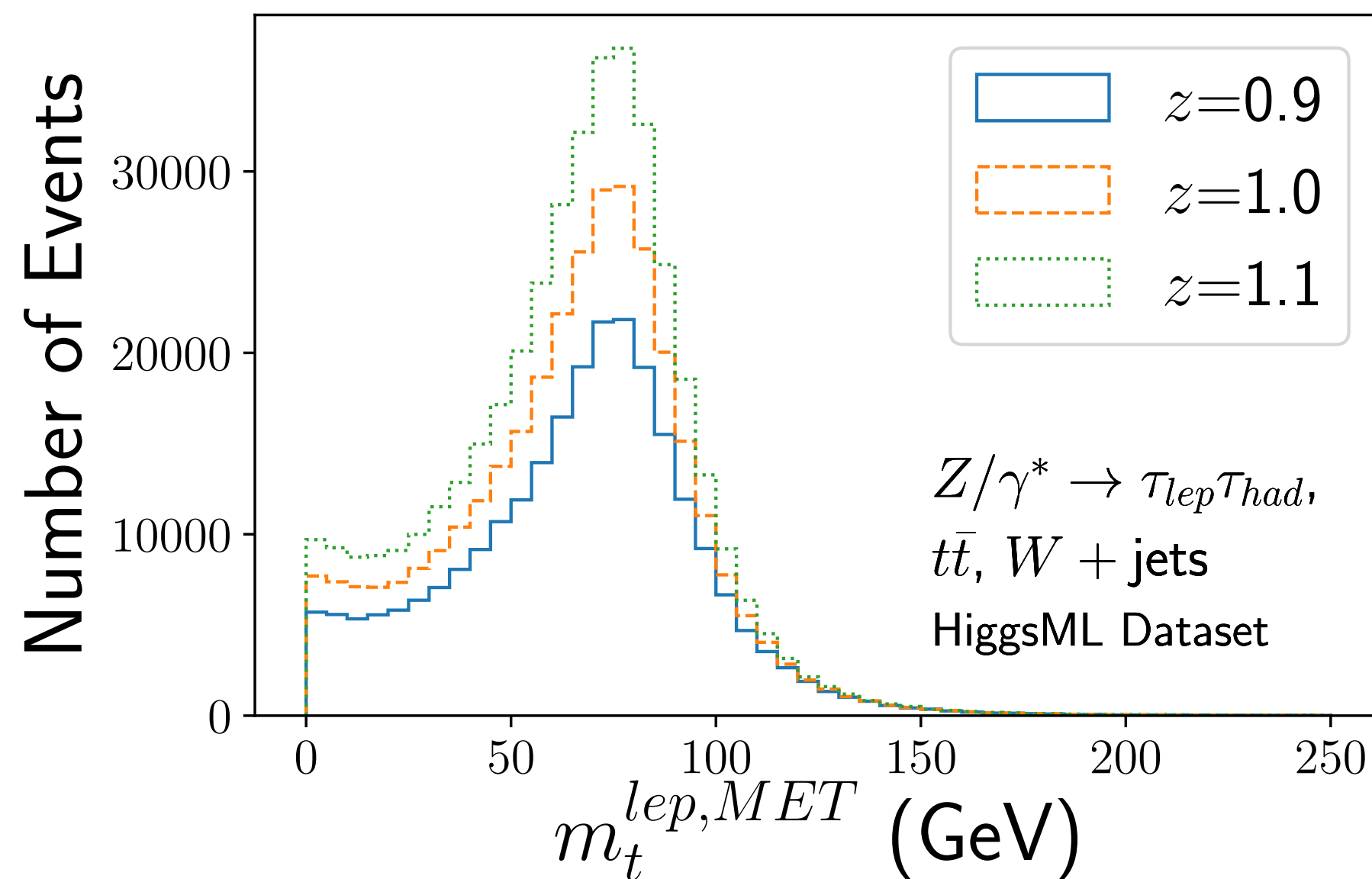


- Current analyses strategies **optimised while ignoring systematic uncertainties**
- Added in post-facto
- Leads to loss in sensitivity compared to uncertainty-aware optimisation (see details)

Traditionally ignoring systematic uncertainties during analysis optimisation

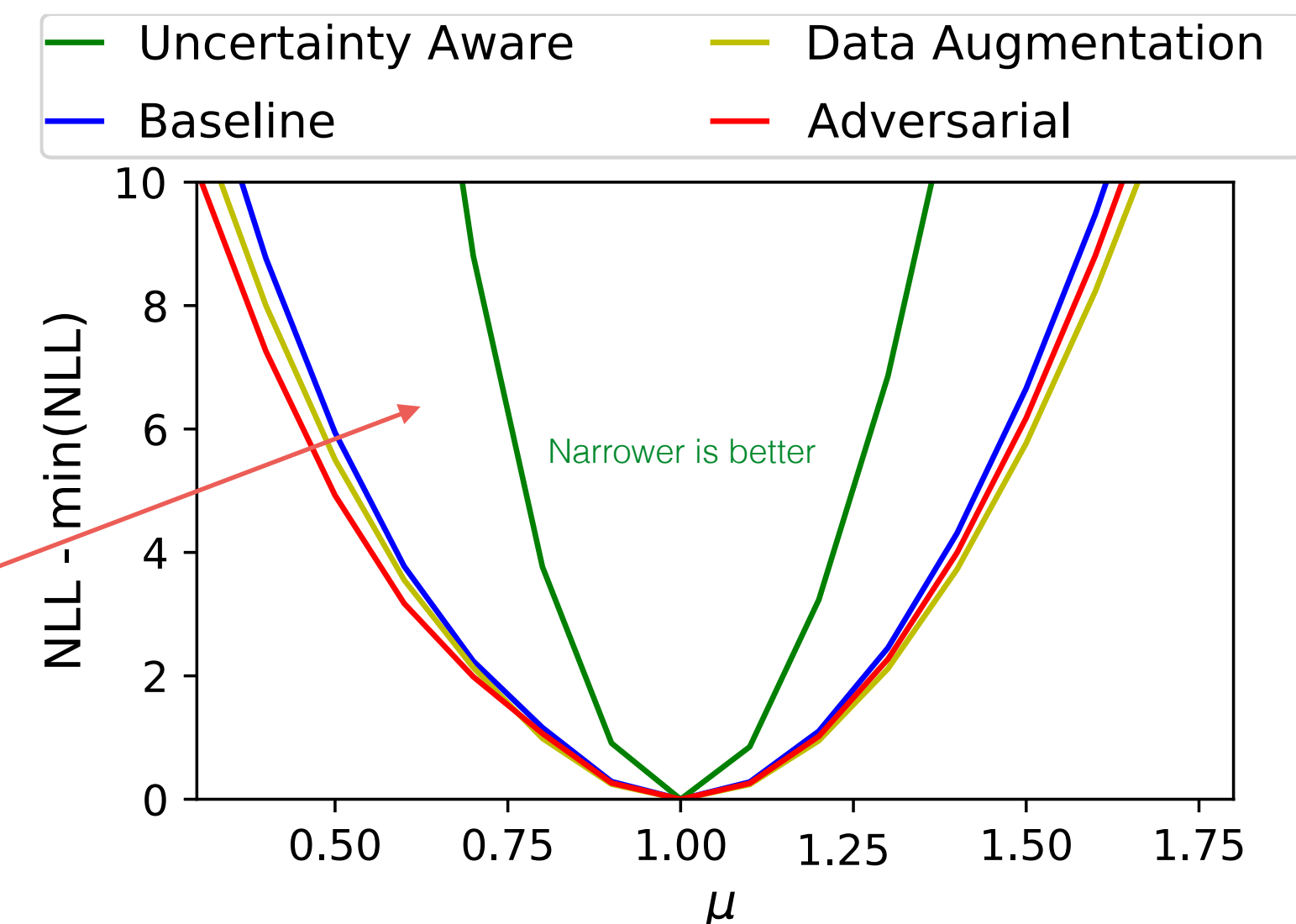
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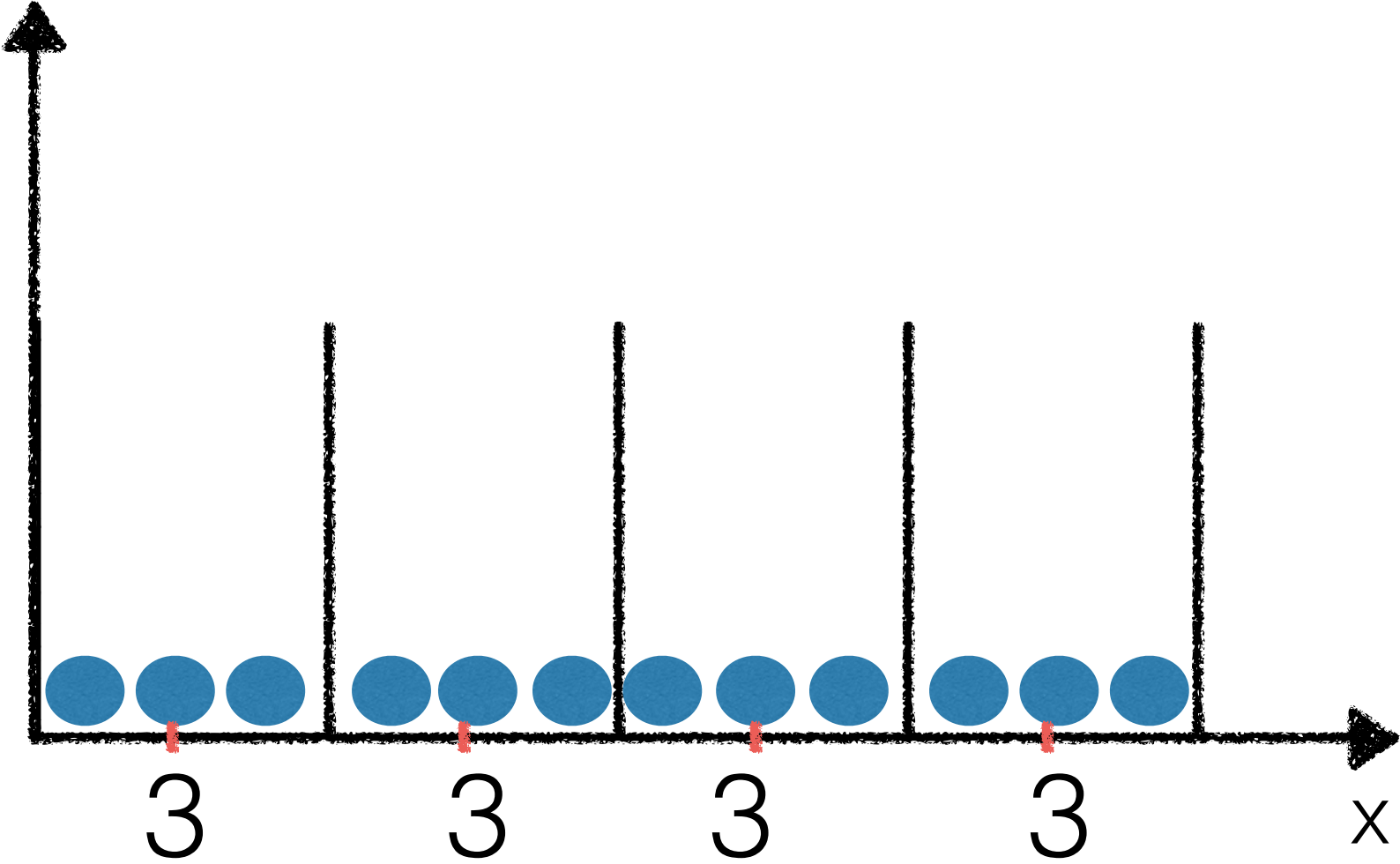
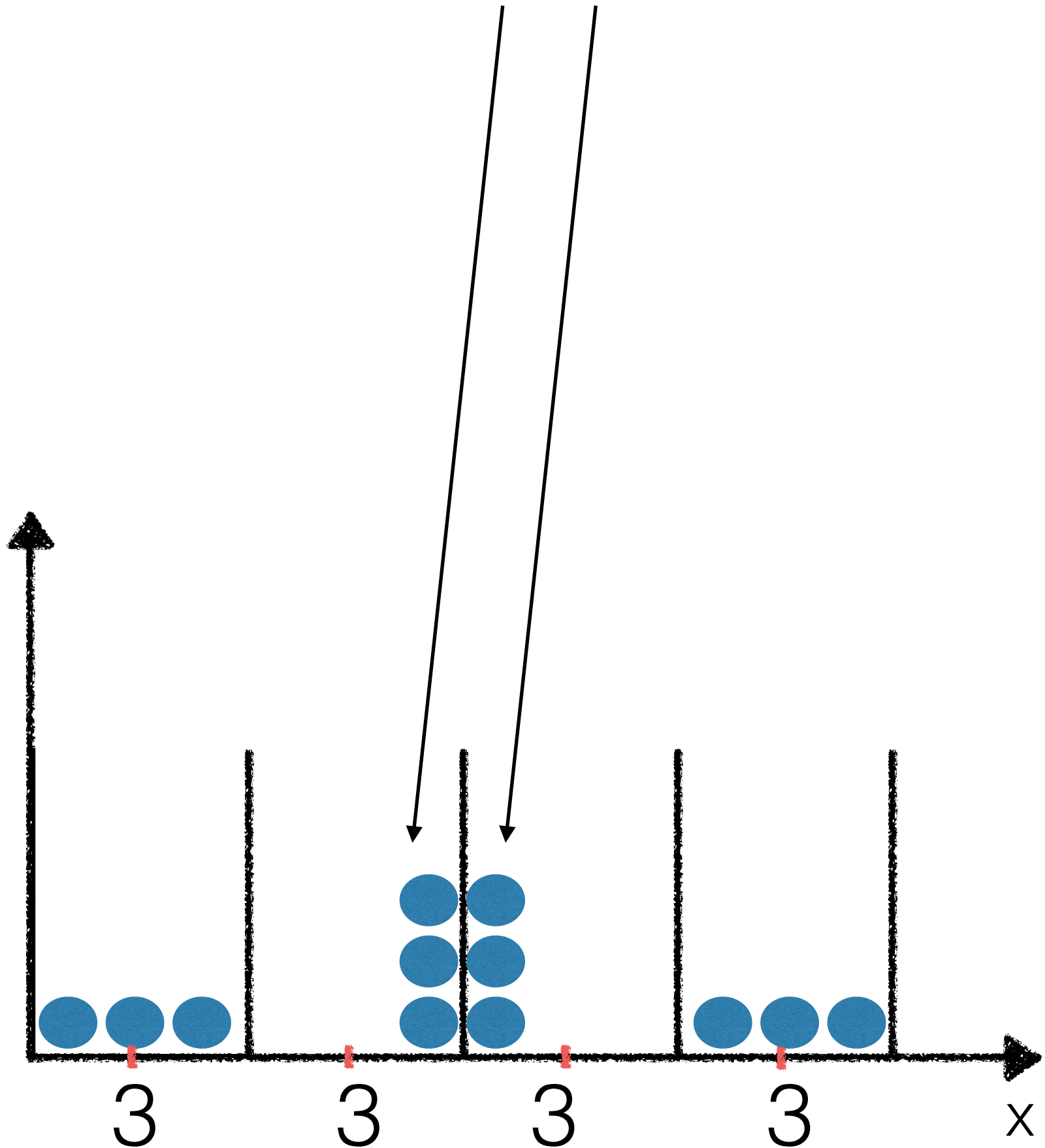
- Current analyses strategies **optimised while ignoring systematic uncertainties**
- Added in post-facto
- Leads to loss in sensitivity compared to uncertainty-aware optimisation (see details)

Difference b/w post-facto and uncertainty-aware



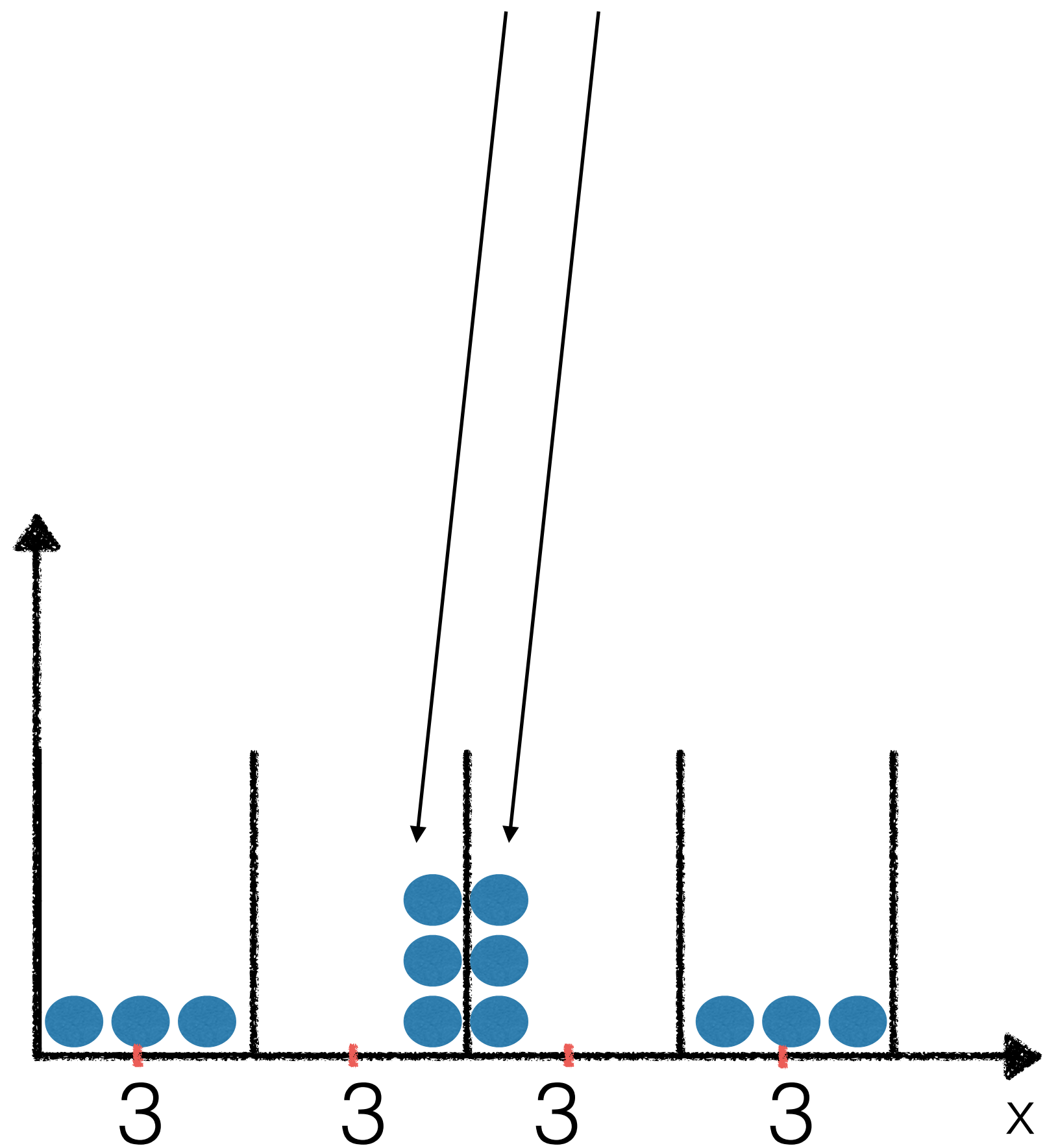
Avoids binning data into histograms, which is another lossy compression

Information on individual events lost!

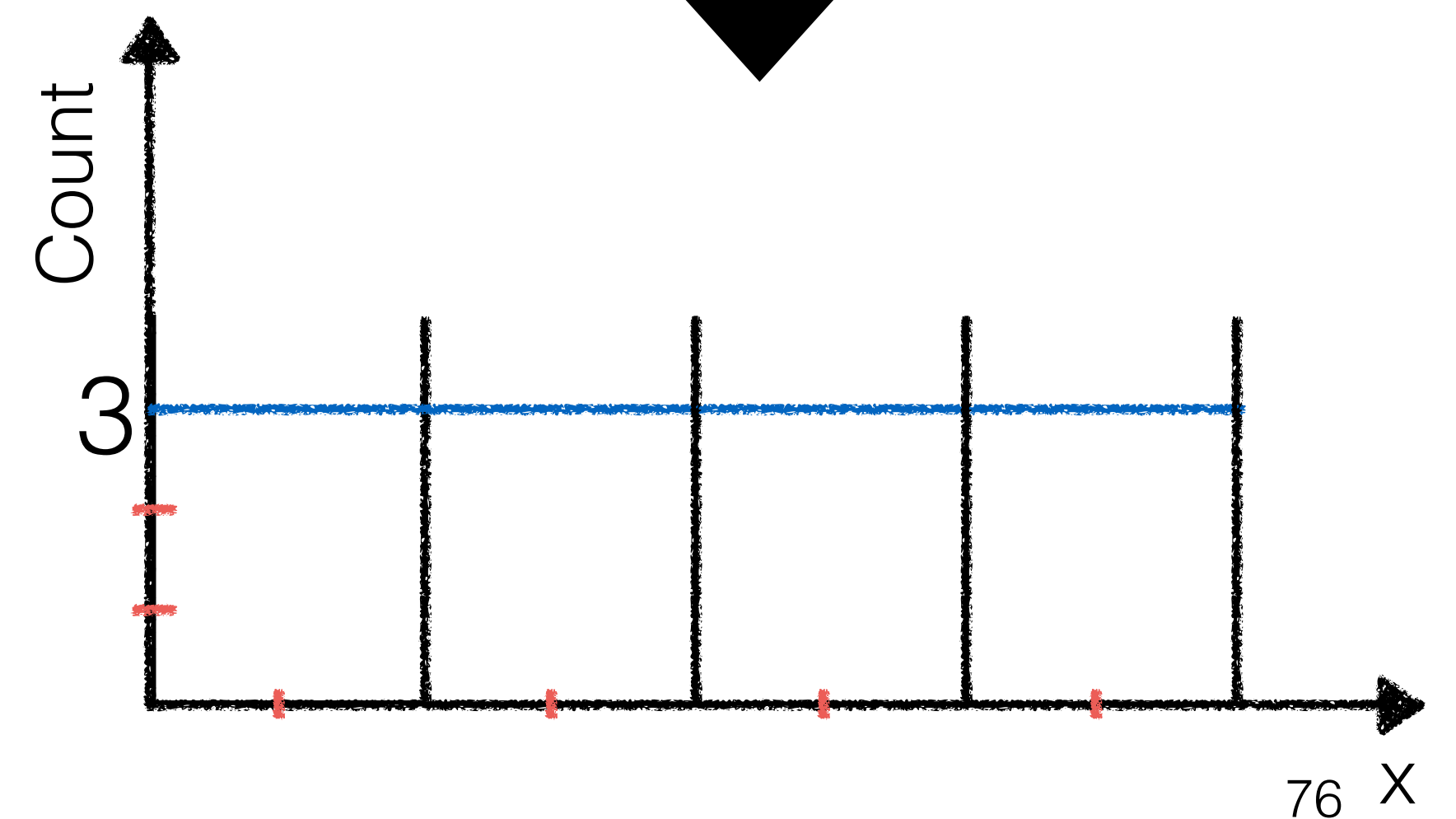
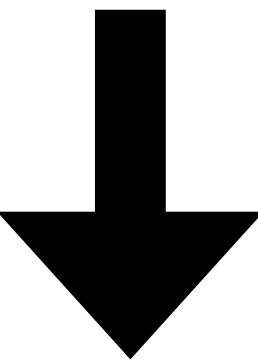
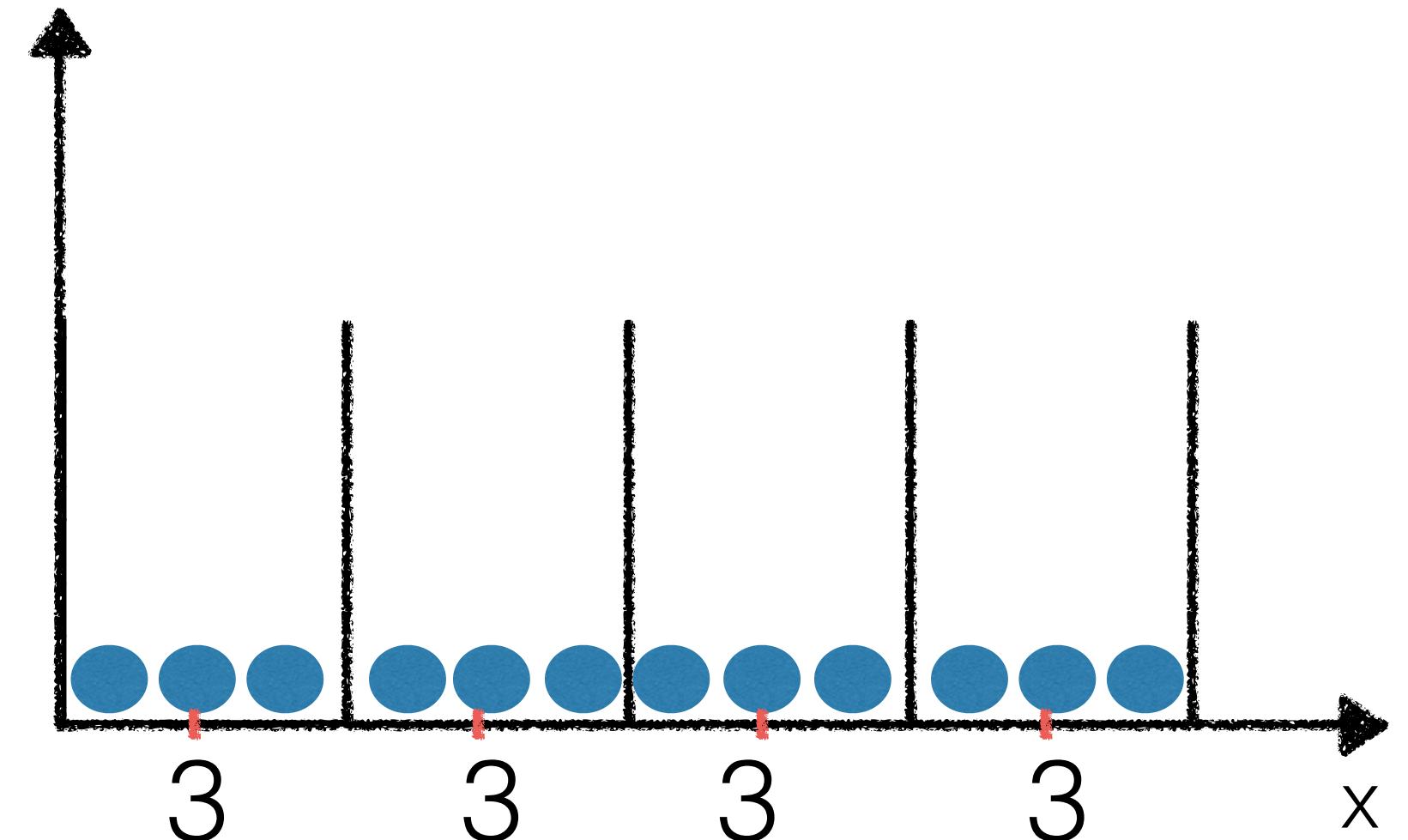


Avoids binning data into histograms, which is another lossy compression

Information on individual events lost!



Same representation in histogram



$$p(\text{theory} \mid \text{data}) = \frac{p(\text{data} \mid \text{theory})p(\text{theory})}{p(\text{data})}$$

What we all
want
(Posterior)

$$p(\text{theory} \mid \text{data}) = \frac{p(\text{data} \mid \text{theory})p(\text{theory})}{p(\text{data})}$$

What we all
want
(Posterior)

Likelihood

$$p(\text{theory} \mid \text{data}) = \frac{p(\text{data} \mid \text{theory})p(\text{theory})}{p(\text{data})}$$

What we all want
(Posterior)

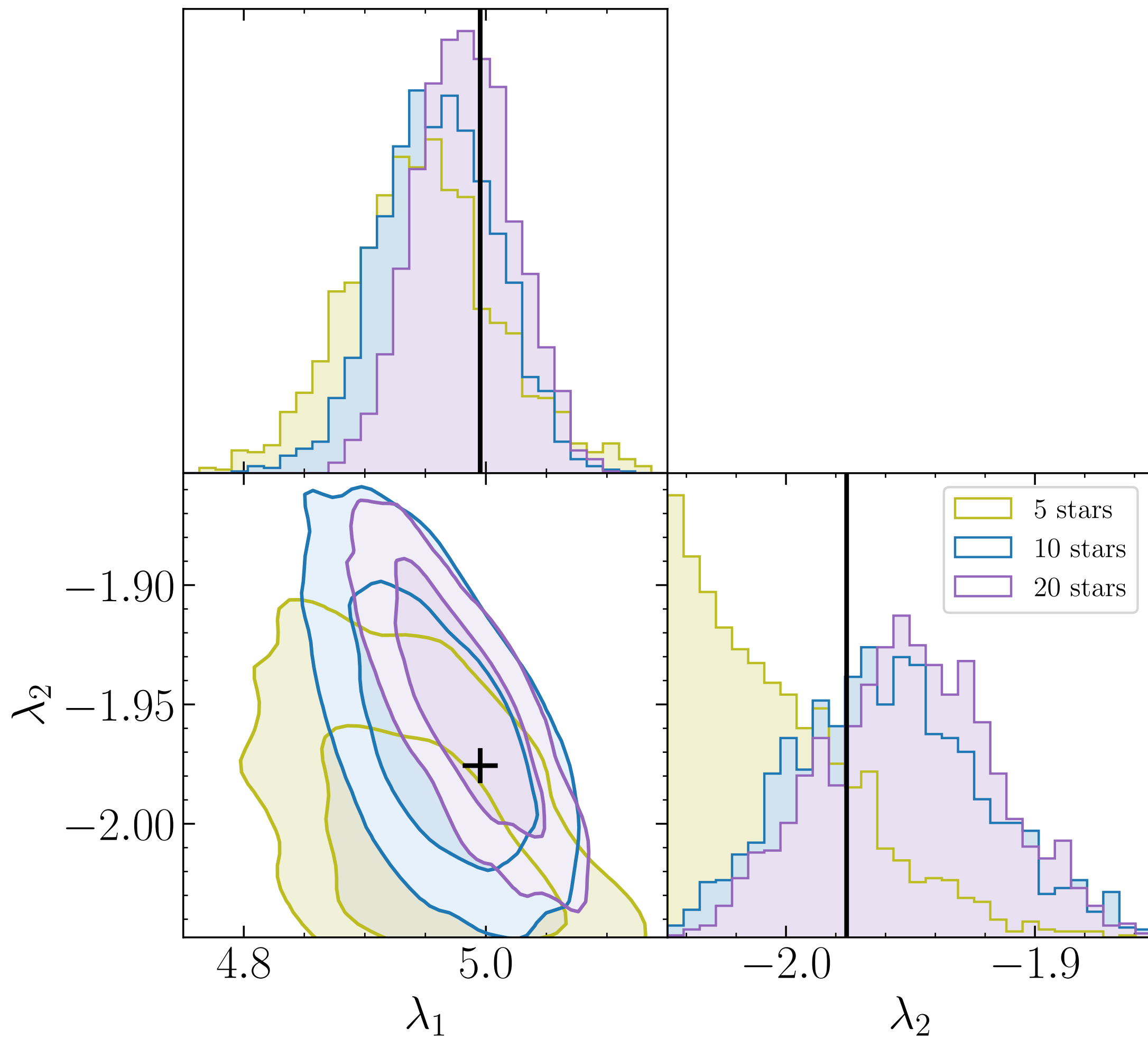
Likelihood

Prior

$$p(\text{theory} \mid \text{data}) = \frac{p(\text{data} \mid \text{theory})p(\text{theory})}{p(\text{data})}$$

Evidence

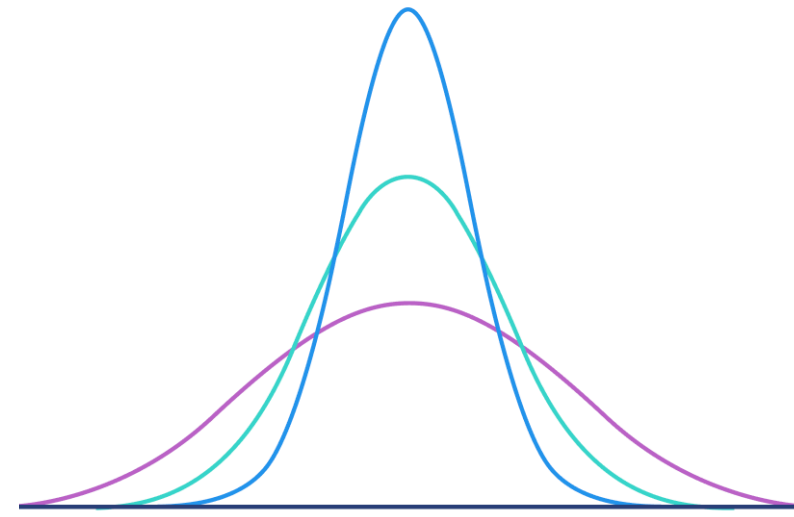
Which neutron stars should we measure next ?



Test potential improvement in sensitivity coming from new measurements

Could inform decisions on which stars to measure next!

Most sensitive method for EoS inference to date!



NP priors

NP priors		$\lambda_{1,\text{pred}} - \lambda_{1,\text{truth}}$		$\lambda_{2,\text{pred}} - \lambda_{2,\text{truth}}$		Combined
$p(\nu)$	Method	μ	σ	μ	σ	σ_{tot}
true	ML-Likelihood _{EOS}	-0.02	0.066	0.01	0.070	0.096
	NN(Spectra)	-0.02	0.066	0.01	0.075	0.099
	NN(M, R via XSPEC)	-0.03	0.065	0.01	0.055	0.085
	NLE	0.00	0.056	-0.01	0.070	0.090
tight	ML-Likelihood _{EOS}	-0.02	0.078	0.03	0.081	0.112
	NN(Spectra)	0.02	0.085	-0.02	0.077	0.115
	NN(M, R via XSPEC)	-0.03	0.081	0.01	0.056	0.098
	NLE	0.00	0.066	-0.02	0.071	0.097
loose	ML-Likelihood _{EOS}	-0.04	0.089	0.03	0.081	0.120
	NN(Spectra)	-0.03	0.131	-0.01	0.078	0.152
	NN(M, R via XSPEC)	-0.03	0.123	0.01	0.058	0.136
	NLE	0.00	0.085	-0.01	0.074	0.113

Pretend that nuisance parameters known exactly



Realistic scenarios:

