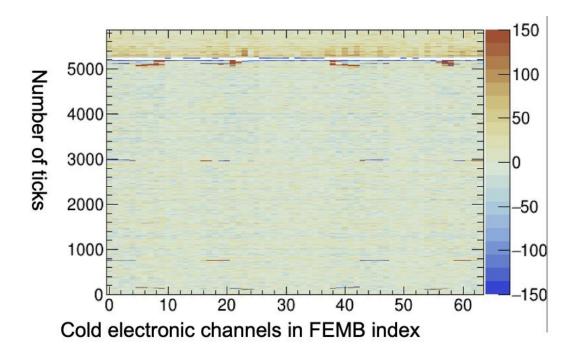
Update for imaging validation

Xuyang Ning

Bad channels

Tags:

- "bad": require input to define, is empty
- "If_noisy": defined by Noise Filter, will generate a lot of bad channels, need check
- "noisy": not put into use previously.
- "femb_noise": haven't included in master.
- In the end all tag will be merged to "bad"



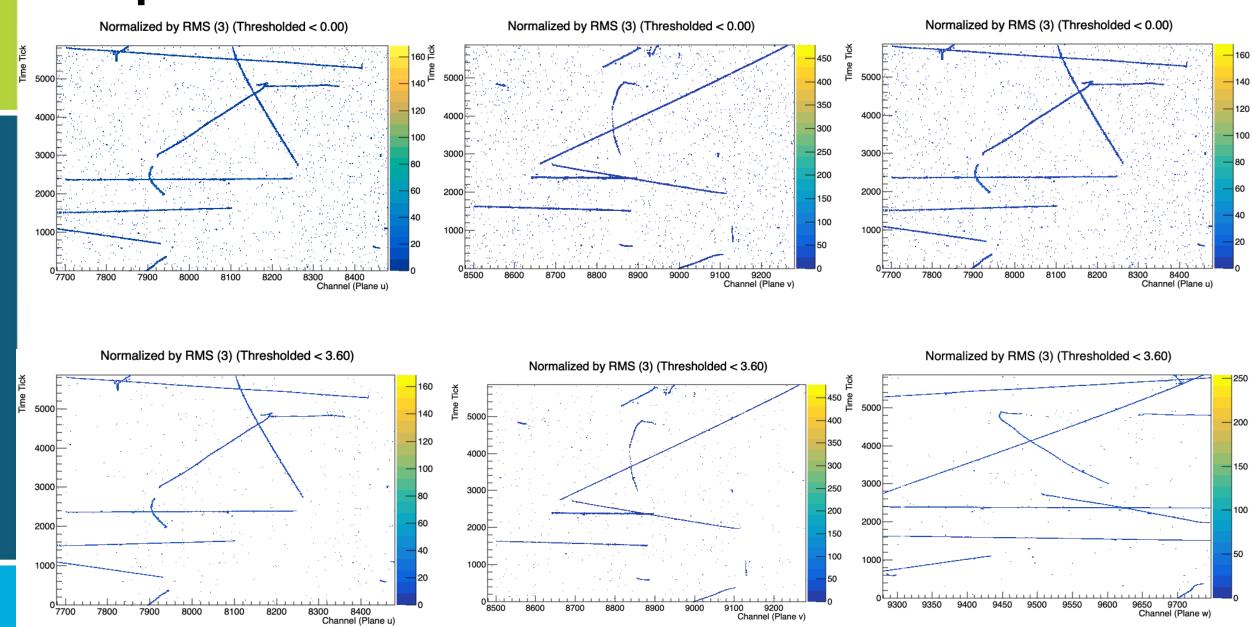
nthreshold

- Threshold: applied on wiener charge, nthreshold*rms
- rms is calculated in signal processing
- Different per channel

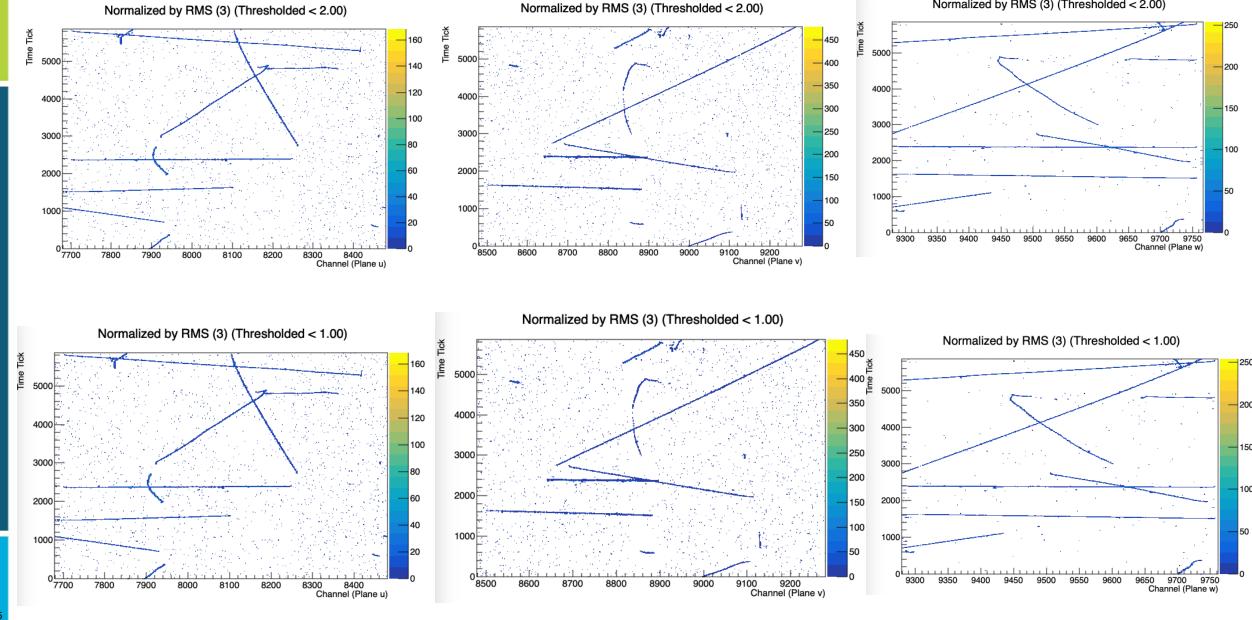
- Extract the rms vs channel
- Draw wiener_charge/rms

```
// A functio that sets up slicing for an APA.
slicing :: function(anode, aname, span=4, active_planes=[0,1,2], n
    ret: g.pnode({
        type: "MaskSlices",
        name: "slicing-"+aname,
        data: {
            tick_span: span,
           wiener_tag: "wiener%d" % anode.data.ident,
           charge_tag: "gauss%d" % anode.data.ident,
           error_tag: "gauss_error%d" % anode.data.ident,
           anode: wc.tn(anode),
            min_tbin: 0,
           max_tbin: 8500,
           active_planes: active_planes,
           masked_planes: masked_planes,
           dummy_planes: dummy_planes,
           nthreshold: [1e-6, 1e-6, 1e-6],
           // nthreshold: [3.6, 3.6, 3.6],
   }, nin=1, nout=1, uses=[anode]),
}.ret,
```

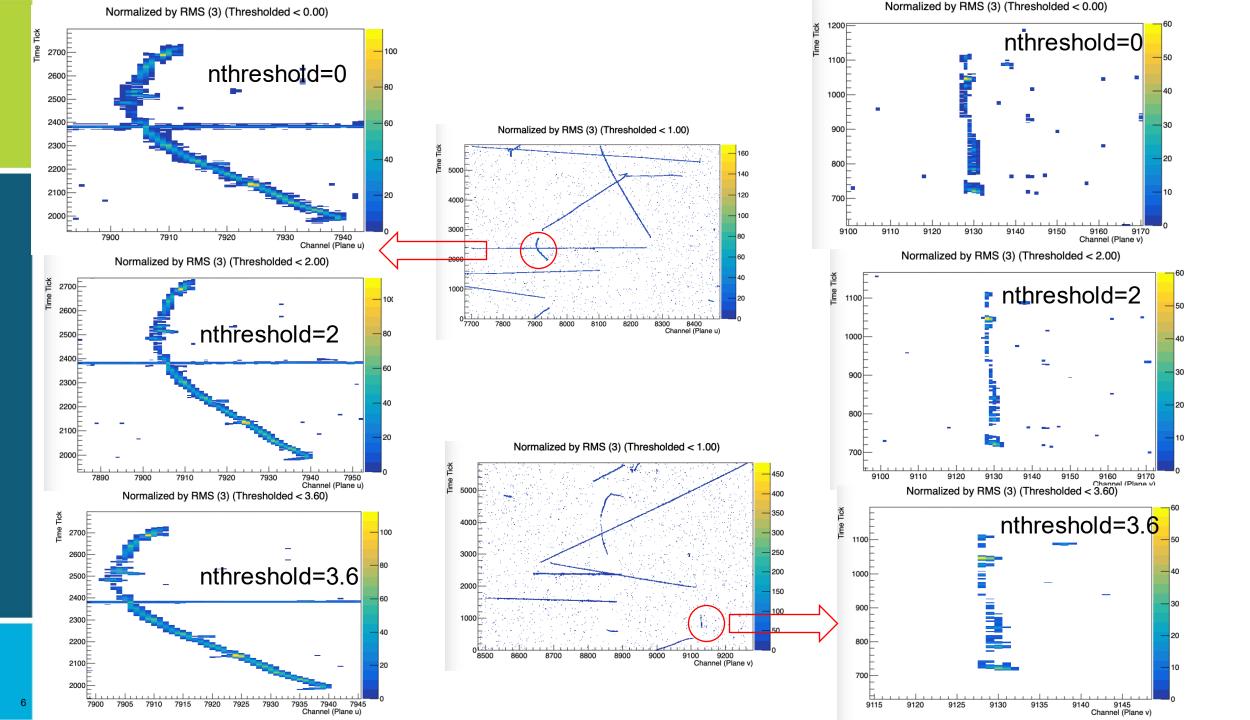
Compare different threshold



Compare different threshold



Normalized by RMS (3) (Thresholded < 2.00)



backup

W plane

