

# Controlling correlations and excited states in Lattice QCD analyses - a novel approach

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in collaboration with A.Portelli (University of Edinburgh)

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UNIVERSITY OF  
LIVERPOOL

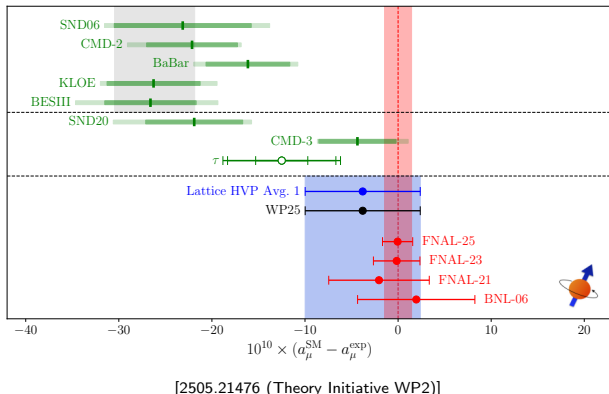
# Outline

- 1 Introduction and motivation
- 2 Laplace filtering
- 3 Application to data
- 4 Annihilating correlation functions
- 5 Excited states
- 6 Conclusions and outlook

## Introduction and motivation

# Testing the Standard Model: Tensions?!

We know the SM is not the end of the story. Look for tensions:

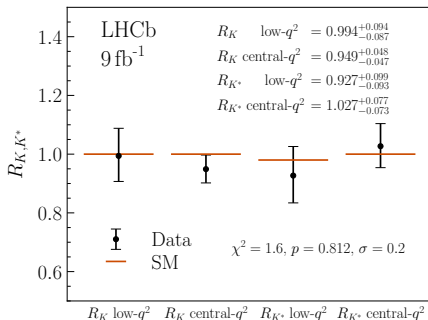


⇒ new results from BMW, Mainz, RBC/UKQCD, Fermilab/MILC/HPQCD, ETMC]

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- ~~$g \times 2$~~
- ~~$R(K), R(K^*)$~~

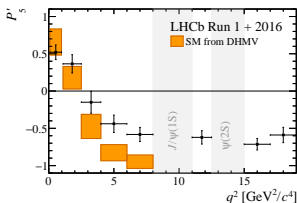
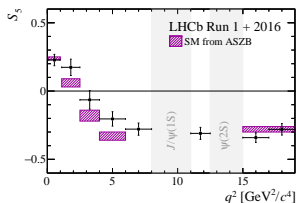
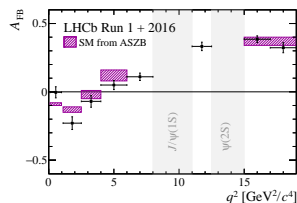
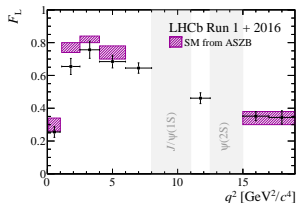


LHCb PRD 108 (2023) 3, 032002

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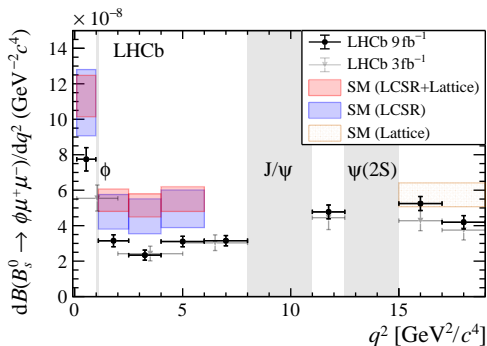


LHCb PRL 125 (2020) 1, 011802

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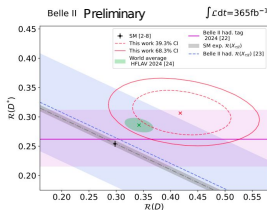
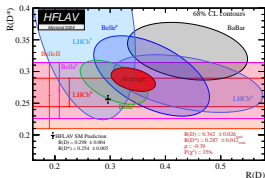


LHCb PRL 127 (2021) 15, 151801

# Testing the Standard Model: Tensions?!

We know the SM is not the end of the story. Look for tensions:

- ~~$g_2$~~
- ~~$R(K)$ ,  $R(K^*)$~~
- $B \rightarrow K^* \ell \ell$
- $B_s \rightarrow \phi \ell \ell$
- $R(D)$ ,  $R(D^*)$



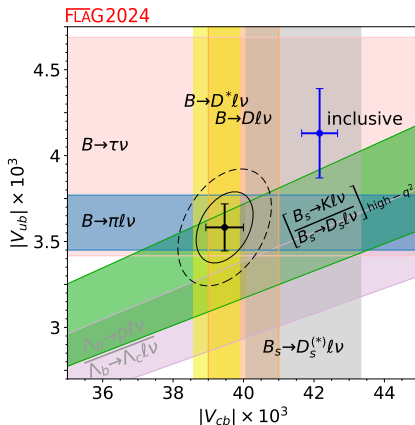
(new result by Belle II presented by Tommy Martinov at EW Moriond)



# Testing the Standard Model: Tensions?!

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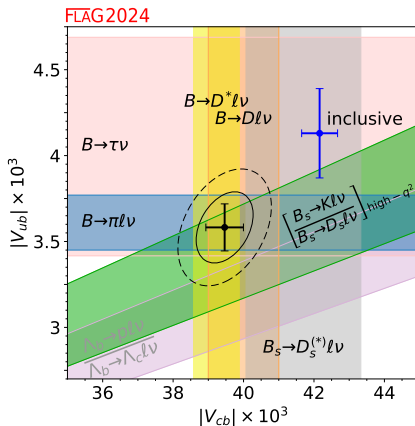
- ~~$g \approx 2$~~
- ~~$R(K), R(K^*)$~~
- $B \rightarrow K^* \ell \ell$
- $B_s \rightarrow \phi \ell \ell$
- $R(D), R(D^*)$
- inclusive vs exclusive
- CKM unitarity?
- ...



# Testing the Standard Model: Tensions?!

We know the SM is not the end of the story. Look for tensions:

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- $B \rightarrow K^* \ell \ell$
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- $R(D), R(D^*)$
- inclusive vs exclusive
- CKM unitarity?
- ...



☹️ Several theory-to-theory tensions ☹️

# Over-constraining the Standard Model: CKM

- Determine individual elements from (many) different decays  $\Rightarrow$  Different determinations compatible?
- SM CKM-matrix is unitary  $\Rightarrow$  Does unitarity hold?

CKM = theory  $\otimes$  experiment

$$\text{experiment} \approx |V_{qq'}|^n \sum_i \text{kinematic} \times \text{non-perturbative}$$

$$\Gamma(B \rightarrow \ell \nu) \approx |V_{ub}|^2 \mathcal{K} f_B$$

$$\frac{d\Gamma(B \rightarrow \pi \ell \nu)}{dq^2} \approx |V_{ub}|^2 \left( \mathcal{K}_1 f_+^{B \rightarrow \pi}(q^2) + \mathcal{K}_2 f_0^{B \rightarrow \pi}(q^2) \right)$$

$$\Delta m_d \approx |V_{tb}^* V_{td}|^2 \mathcal{K} f_{B_d}^2 \hat{B}_{B_d}^{(1)}$$

CKM-precision depends on knowledge of theory AND experiment.

# Lattice QCD: From simulations to physics

Non-perturbative method of choice: **Lattice QCD**

## Schematic lattice workflow

1. (H)MC chain  
⇒ Gauge ensembles
2. measurements  
⇒  $n$ -point correlation functions
3. **correlation function fits**  
⇒ **energies, matrix elements**
4. extrapolations  
⇒  $xx.xxx(yy)_{stat}$
5. estimates of systematics  
⇒  $xx.xxx(yy)_{stat}(zz)_{sys}$

## Data production:

Take as given for this talk

## Data analysis:

## **Topic of this talk.**

In particular

- ⇒ steps that use a data-estimated correlation matrix.
- ⇒ fits to correlation functions.  
[required for all results presented before]

## Some (well-known) nomenclature

Assume raw data on  $N$  samples for  $N_t$  time slices:  $C_i(t)$

- Averaged correlation function

$$\bar{C}(t) = \frac{1}{N} \sum_{i=0}^{N-1} C_i(t)$$

- Covariance matrix

$$\text{cov}(t_1, t_2) = \frac{1}{N-1} \sum_{i=0}^{N-1} [\bar{C} - C_i](t_1) [\bar{C} - C_i](t_2)$$

- Standard deviation

$$\sigma(t_1) = \sqrt{\text{cov}(t_1, t_1)}$$

- Correlation matrix (“normalised covariance matrix”)

$$\text{corr}(t_1, t_2) = \frac{1}{\sigma(t_1)} \text{cov}(t_1, t_2) \frac{1}{\sigma(t_2)}$$

# Where does the correlation matrix enter?

- For a fit function  $f$ , “best” parameters  $\vec{a}$  found by  $\chi^2$ -fitting, i.e. minimise

$$\chi^2 = [f(\vec{a}, t_1) - C(t_1)] \text{cov}(t_1, t_2)^{-1} [f(a, t_2) - C(t_2)]$$

$p(\chi^2, \text{d.o.f.'s})$  used as criterion for which fits “work”

- Many recent works use model averaging procedures (e.g. AIC):
  - $\Rightarrow$  Do many different fits (vary models and included data)
  - $\Rightarrow$  Results get combined weighted by their  $\chi^2$

Note: Inversion of covariance matrix == inversion of correlation matrix

$$\text{cov}^{-1} = \sigma^{-1} \text{corr}^{-1} \sigma^{-1}$$

$\Rightarrow$  From now on we only speak about the correlation matrix!

# Correlation estimation from data

- The correlation matrix is estimated from data.
  - Want  $N_{\text{conf}} \gg N_{\text{obs}}$  for accurate estimates, but often hard in practice.
- ⇒ Non-invertible or poorly conditioned covariance matrix.
- ⇒ Issues amplified since usually we require  $\text{corr}^{-1}$ !
- Several ways to “deal with” the issue [non-exhaustive list]:
    - down-sampling (a.k.a. thinning)
    - uncorrelated fits [Bruno, Sommer; “On fits to correlated and auto-correlated data”, 2209.14188]
    - SVD-cuts
    - “shrinkage” [Ledoit, Wolf, <https://www.zora.uzh.ch/id/eprint/139880/>]
    - source-place treatment [JTT, RBC/UKQCD, “Kaon mixing beyond the standard model with physical masses”, 2404.02297]
    - estimation of  $p$ -values based on bootstrapping [Christ, Ernaki, Kelly; “Bootstrap-determined  $p$  values in lattice QCD”, 2409.11379]
    - Lanczos-methods [Wagman, 2406.20009, 2412.04444, . . . ; Ostmeier, Sen, Urbach, “On the equivalence of Prony and Lanczos methods for Euclidean correlation functions”, 2411.14981]
- ⇒ **All not 100% satisfactory!** Can we do better?

Laplace filtering



# The idea

- Find a transformation of the data to reduce correlations.
  - Transform the model in the same way.
- ⇒ Fit the transformed model to the transformed data.

What transformation to choose?

- Lattice data is highly correlated in time!
- ⇒ Use a time-local transformation

## Laplace filter

$$\Delta C(t) = C(t-1) - 2C(t) + C(t+1)$$

$$D_\lambda C(t) \equiv (-\Delta + \lambda^2)C(t) = -C(t-1) + (2 + \lambda^2)C(t) - C(t+1)$$

# Laplace filtering

$$D_\lambda C(t) = -C(t-1) + (2 + \lambda^2)C(t) - C(t+1)$$

- local subtractions  $\Rightarrow$  reduce local correlations
- tunable parameter  $\lambda$  (assume  $\lambda > 0$  for definiteness)
- preserves original correlations for  $\lambda \rightarrow \infty$
- invertible transformation for  $\lambda > 0$ , but singular as  $\lambda \rightarrow 0^+$ .
- “added bonus”: Preserves exponential form, i.e.

$$D_\lambda \left( A e^{-Et} \right) = A'(\lambda) e^{-Et}$$

## Aside: Measure of the level of correlations: CDR

- Determine eigenvalues of correlation matrix  $\text{corr}$  and define condition number:  $\kappa \equiv \lambda_{\max}/\lambda_{\min}$
- Define Correlation Dynamic Range (CDR):

$$\text{CDR}(\text{corr}) = 10\log_{10}\kappa$$

$\text{CDR}(\text{corr}) = 0 \text{ dB} :$  uncorrelated

$\text{CDR}(\text{corr}) = +\infty \text{ dB} :$  singular

$\text{CDR}(\text{corr}) \gtrsim 156 \text{ dB} :$  double precision numerically singular

Limiting cases of the filtering:

$$\lim_{\lambda \rightarrow \infty} \text{CDR}(\text{corr}(\Delta_{\lambda} C(t))) = \text{CDR}(\text{corr}(C(t)))$$

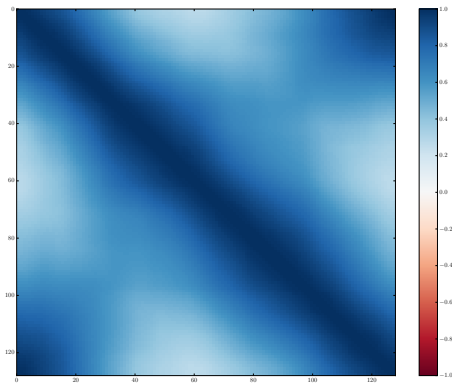
$$\lim_{\lambda \rightarrow 0^+} \text{CDR}(\text{corr}(\Delta_{\lambda} C(t))) = +\infty$$

**Q: Is there a choice of  $\lambda$  that improves (lowers) the CDR?**

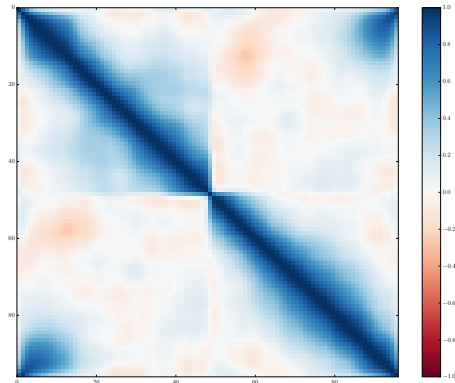
Application to data

# Typical 2-point functions

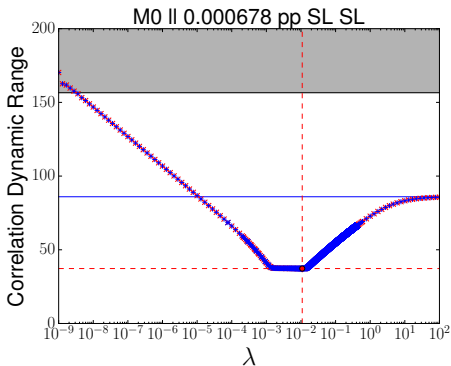
- $m_{\pi}^{\text{phys}}, a^{-1} \sim 2.3 \text{ GeV}$
- pion 2pt function
- Gaussian smeared  $\mathbb{Z}_2$ -sources + point sinks



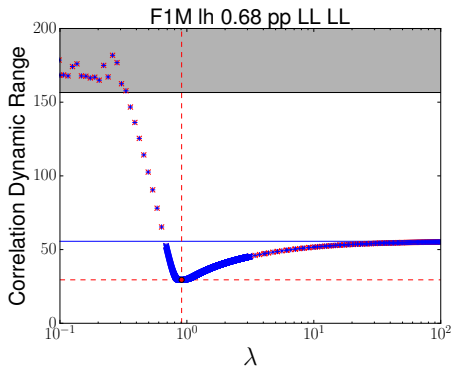
- $m_{\pi} \sim 230 \text{ MeV}, a^{-1} \sim 2.7 \text{ GeV}$
- heavy-light PS meson with  $am_h = 0.68$  ( $m_c < m_h < m_b$ )
- local  $\mathbb{Z}_2$  sources + point sinks



# Exploring $\lambda$ : Correlations



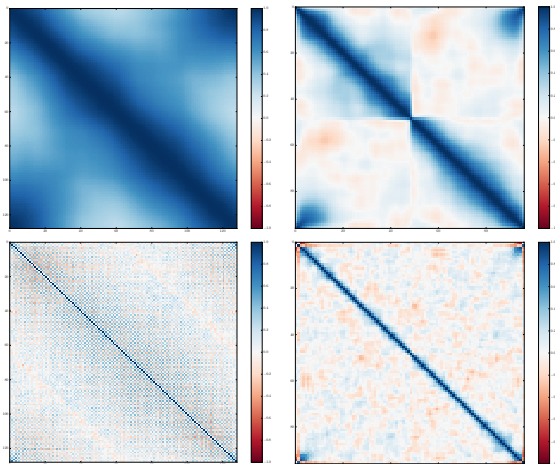
86 dB  $\rightarrow$  37 dB



56 dB  $\rightarrow$  29 dB

- Correct asymp. behaviour as  $\lambda \rightarrow \infty$  and  $\lambda \rightarrow 0^+$ .
- Sizable region with significantly reduced correlations
- Similar gains when restricted to realistic subset of the time-range

# Exploring $\lambda$ : Correlations



- Filtered datapoints carry more independent information
- Still some “redundancy” for neighbouring time-slices  
⇒ can be combined with down-sampling (thinning)

**Q1: Can we quantify the gain?**

**Q2: How do thinning and filtering interfere?**

# Quantifying the gains

- full range ('all  $t$ ') vs representative fit range of  $t \in [1/8T, 3/8T)$
- if thinned: filtering happens first

	<b>M0M-mes-II</b>		<b>F1M-mes-Ih</b>	
	all $t$	$t \in [16, 48)$	all $t$	$t \in [12, 36)$
raw	86 dB	67 dB	56 dB	47 dB
optimised	37 dB	18 dB	36 dB	20 dB
raw thinned	62 dB	52 dB	37 dB	30 dB
optimised thinned	21 dB	11 dB	19 dB	9 dB

- Filtering and thinning interfere constructively!
- Approximately 4 orders of magnitude improvement in all cases!

**Q: How does this translate to precision & stability of correlator fits?**



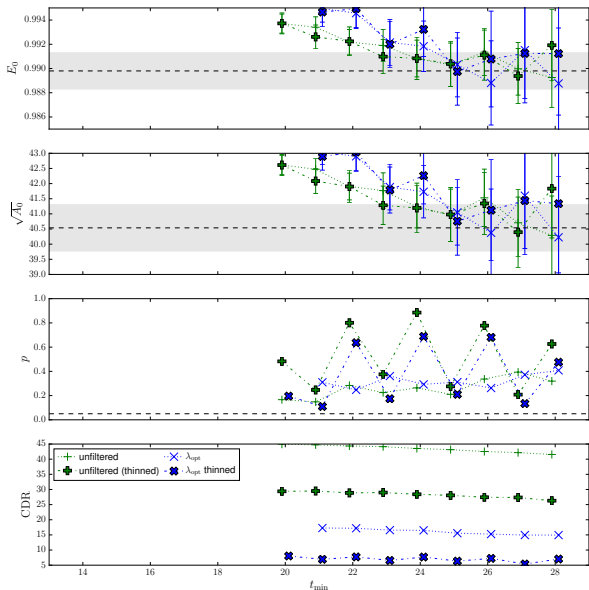
# Application to two-point function fits

**Q: How does this translate to precision & stability of correlator fits?**

Strategy: Determine  $\lambda$  which minimises CDR on a given time-interval, then fit

- Test fits on the heavy-light dataset from before
- Fit to single exponential  $Ae^{-Et}$ .
- Vary  $t_{\min}$ , keep  $t_{\max} = 3/8T = 36$  fixed
- Explore the separate and combined effects of filtering and thinning
- Only keep fits with acceptable  $p$ -value ( $> 5\%$ )
- Known results for  $E_0$  and  $A_0$  from extensive larger scale stability analysis

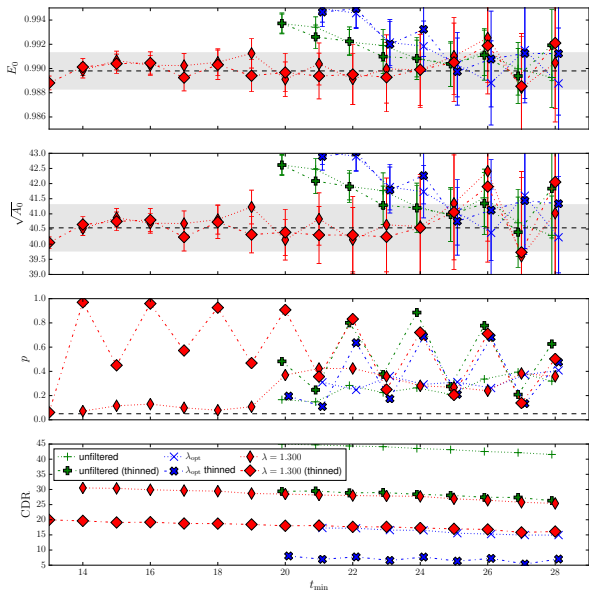
# Minimising correlations



- $t_{\max}$  fixed
- single state fit
- only show fits with  $p \geq 5\%$
- ☺ CDR decreases
- ☹ uncertainties increase

what about  $\lambda \neq \lambda_{\text{opt}}$ ?

# ~~Minimising~~ Reducing correlations



- $t_{\max}$  fixed
- single state fit
- only show fits with  $p \geq 5\%$

😊 CDR decreases  
 ☹️ uncertainties increase

what about  $\lambda \neq \lambda_{\text{opt}}$ ?

😊 CDR decreases  
 😊 largely reduced excited state  
 😊 competitive uncertainties at lower  $t_{\min}$

## Annihilating correlation functions

# Killing exponentials

Recall: Laplace filtering preserves exponentials, specifically

$$D_\lambda \sum_i A_i e^{-m_i t} = \sum_i \left[ \tilde{E}_i^2 - \lambda^2 \right] A_i e^{-m_i t} \equiv \sum_i A'_i(\lambda) e^{-m_i t}$$

with  $\tilde{E}_i^2 = 2(\cosh(m_i) - 1)$

**in idealised world:**

- Exact correlation function  $C(t)$  with exactly 2 states  $E_0$  and  $E_1$
- Choose  $\lambda_0 = \tilde{E}_0$ ,  $\lambda_1 = \tilde{E}_1$
- By definition we must have  $D_{\lambda_1} D_{\lambda_2} C(t) = 0$  [ignore contact term]

**in practice:**

- noisy data  $\Rightarrow$  statistical statements  $\Rightarrow$  hypothesis testing
- $\#$  of states infinite  $\Rightarrow$  “data consistent with description of  $n$ -states”

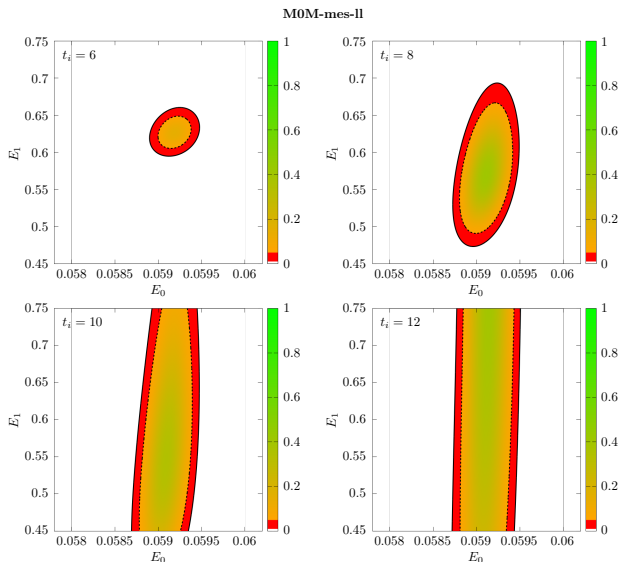
# Multi-state hypothesis testing and the spectrum

- For simplicity test 2 states
- Define  $\Lambda = \{\lambda_0, \lambda_1\}$  and time range  $t \in [t_i, t_f)$  with  $t_i > 2$
- Define the hypothesis  $H_\Lambda$ :

$$C_{\Lambda; t_i, t_f} \equiv D_{\lambda_0} D_{\lambda_1} C(t) = 0$$

- Assume sufficient statistics that correlator is normally distributed in interval.
- $D_\lambda$  is a linear transformation  
 $\Rightarrow C_{\Lambda; t_i, t_f}$  is also normally distributed  
 $\Rightarrow$  use standard  $p$  value and define confidence level  $1 - \alpha$
- Set  $\alpha = 0.05$  and scan the parameter space  $(\lambda_0, \lambda_1)$ .
- Interpret 'solutions' as  $(\tilde{E}_0, \tilde{E}_1)$  and map them to  $(E_0, E_1)$  for convenience.

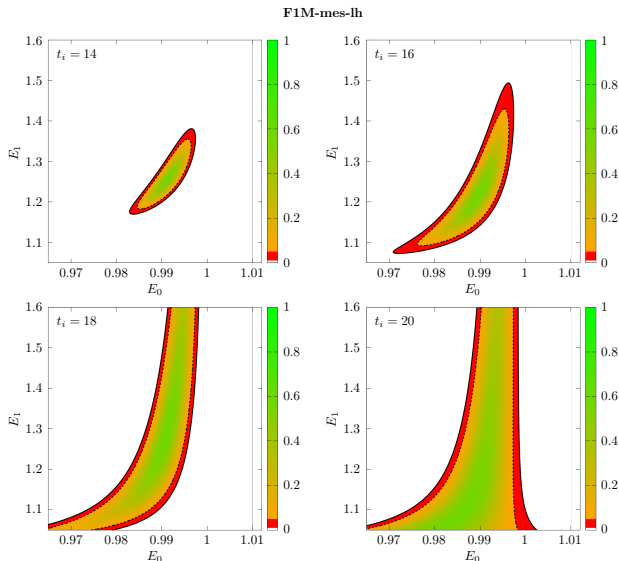
# Multi-state hypothesis testing: physical pion



[Plots by A. Portelli]

- $t_f = 48$
- mapped  $(\tilde{E}_0, \tilde{E}_1)$  back to  $(E_0, E_1)$
- no allowed region if  $t_i$  too small
- decreasing sensitivity to  $E_1$  as  $t_i$  increases
- compare to stability analysis:  
 $E_0 = 0.05908(7)$   
 $E_1 = 0.49(3)$

# Multi-state hypothesis testing: heavy light



- $t_f = 36$
- mapped  $(\tilde{E}_0, \tilde{E}_1)$  back to  $(E_0, E_1)$
- no allowed region if  $t_i$  too small
- decreasing sensitivity to  $E_1$  as  $t_i$  increases
- compare to stability analysis:  
 $E_0 = 0.9898(15)$   
 $E_1 = 1.222(27)$

[Plots by A. Portelli]



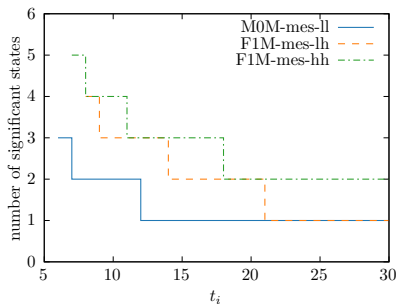
# Determination of number of significant states (sketch)

**Q: For a given time-range, can we determine the number of significant states from this?**

- Define hypothesis  $H_r$ :

$$\exists \Lambda = \{\lambda_1, \dots, \lambda_r\} \text{ s.t. } C_{\Lambda; t_i, t_f} = 0$$

- Compute  $\Delta T^2$  between  $H_{r+1}$  and  $H_r$  and use likelihood ratio test to decide whether  $H_r$  should be rejected in favour of  $H_{r+1}$ . Repeat until no rejection occurs.
- Check that  $H_r$  is not rejected (see previous slides).



[Plot by A. Portelli]

# Possible Applications?

## 1. Use this for existing correlator fit methods:

- Check whether correct number of states are included in the ansatz, i.e.
  - ⇒ are they sufficient to describe the data?
  - ⇒ is the fit actually sensitive to them?

**Bayes** Relate determinations of  $\tilde{E}_i$  to priors and allowed range to widths

**Frequ** Relate determinations of  $\tilde{E}_i$  to initial parameter guesses

## 2. Turn this into a new way to fit correlators:

- 😊 No non-linear fitting required
- 😊 No need to fit amplitudes (but can be determined)
- ❓ Work in progress: Rigorously assign uncertainties

## 3. Thinking about excited states...

**Q: Rather than killing all the exponentials, can we only remove the unwanted ones?**

Excited states

# Recap: Excited states

- Notorious source of systematic uncertainties in precision predictions
- $N\pi$  states in nucleon form factors [Bär; 1812.09191, 1906.03652, 1912.05873]
- $B\pi$  excited states in semi-leptonic  $B$  decays? [Bär, Broll, Sommer; 2306.02703]
- Fitting excited states
  - need more time slices and more parameters in fit
  - more correlation matrix issues + more involved stability analyses
  - often numerically unstable: need priors and/or sophisticated initial guess determinations
- can be mitigated
  - smearing (additional tuning - hard to get right for many states at once)
  - GEVP [Blossier, Della Morte, von Hippel, Mendes, Sommer; 0902.12675] (additional inversions, more complicated for 3-point functions)

# Killing exponentials - removing excited states

Recall: Laplace filtering preserves exponentials. Specifically:

$$D_\lambda \sum_i A_i e^{-m_i t} = \sum_i \left[ \tilde{E}_i^2 - \lambda^2 \right] A_i e^{-m_i t} \equiv \sum_i A'_i(\lambda) e^{-m_i t}$$

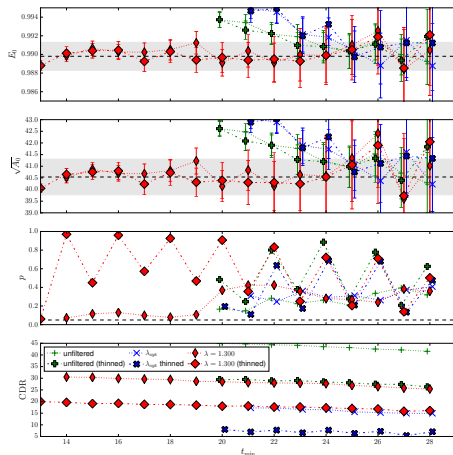
with  $\tilde{E}_i^2 = 2(\cosh(m_i) - 1)$

- $\lambda$  is a free parameter. Can choose it to remove an unwanted exponential, e.g.  $m_1$

$$\lambda = \tilde{E}_1 = \sqrt{2(\cosh(m_1) - 1)}$$

- Known simple relation between  $A_i$  and  $A'_i(\lambda)$
- Can be iterated – multiple applications of Laplace filtering

# Recall from before



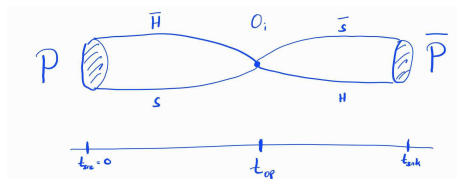
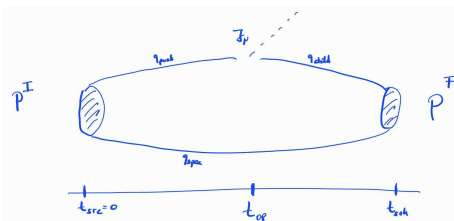
- Choice for the red data points was  $\lambda = 1.3$
- No coincidence: recall result from stability analysis:

$$E_0 = 0.9898(15), \quad E_1 = 1.222(27)$$

$$\Rightarrow \tilde{E}_1 = \sqrt{2[\cosh(E_1) - 1]} \sim 1.29946$$

**Q: What about more complicated correlation functions?**

# Applications beyond 2-point functions



- Three-point functions have two (relative) time scales.  
(w.l.o.g. set  $t_{src} = 0$ )
- Need  $0 \equiv t_{src} \ll t_{op} \ll t_{snk} \ll T$   
 $\Rightarrow$  hard to fit on a typical temporal extent?
- trade-off: excited state contamination vs signal-to-noise properties

**Can Laplace filtering help?**

# Semi-leptonic decays

- neglecting around the world effects (heavy-light)
- two-point functions for initial ( $P^I$ ) and final ( $P^F$ ) states:

$$C_2^X(t) = \sum_i \left( Z_i^X \right)^2 e^{-E_i^X t}$$

- Three-point function for a PS to PS transition:

$$C_{3,\mu}^{I \rightarrow F}(t_{\text{op}}, t_{\text{snk}}) = \sum_{i,j} Z_i^I Z_j^F \left\langle P_j^F \left| V_\mu \right| P_i^I \right\rangle e^{-E_j^F t_{\text{op}} - E_i^I (t_{\text{snk}} - t_{\text{op}})}$$

- Define

$$R_\mu(t_{\text{op}}, t_{\text{snk}}) = \frac{C_{3,\mu}^{I \rightarrow F}(t_{\text{op}}, t_{\text{snk}})}{C_2^F(t_{\text{op}}) C_2^I(t_{\text{snk}} - t_{\text{op}})} \xrightarrow{0 \ll t_{\text{op}}, t_{\text{snk}}} \frac{\langle P_0^F | V_\mu | P_0^I \rangle}{Z_0^I Z_0^F}$$

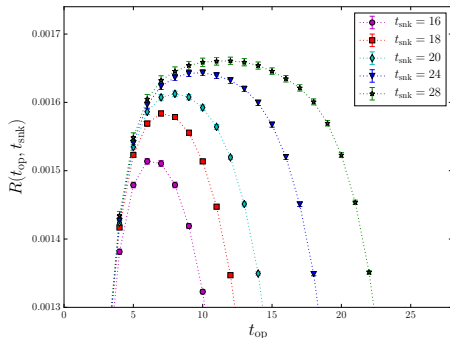
**What choice of  $t_{\text{snk}}$  is large enough?**



## Example: $D_s \rightarrow \eta_s$ (raw data)

$$R_\mu(t_{\text{op}}, t_{\text{snk}}) = \frac{C_{3,\mu}^{I \rightarrow F}(t_{\text{op}}, t_{\text{snk}})}{C_2^F(t_{\text{op}})C_2^I(t_{\text{snk}} - t_{\text{op}})}$$

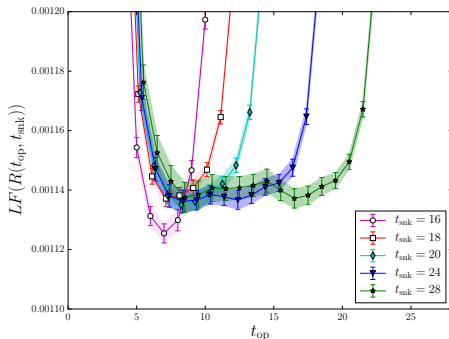
- $a^{-1} \sim 1.7 \text{ GeV}$ ,  $m_\pi \sim 280 \text{ MeV}$ ,  
 $L^3 \times T = 24^3 \times 64$
- everything at rest (i.e.  $q_{\text{max}}^2$ )
- temporal component of vector current
- 5 source-sink separations
- $N_{\text{conf}} = 180$
- 8  $\mathbb{Z}_2$  source-planes/config



**All  $t_{\text{snk}}$  too short to have isolated ground state - are we doomed?**

## Example: $D_s \rightarrow \eta_s$ (Laplace filtered)

$$LF(R_\mu(t_{\text{op}}, t_{\text{snk}})) \equiv \frac{C_3^{I \rightarrow F}(t_{\text{op}}, t_{\text{snk}})}{D_{\lambda_F}[C_2^F](t_{\text{op}}) D_{\lambda_I}[C_2^I](t_{\text{snk}} - t_{\text{op}})}$$

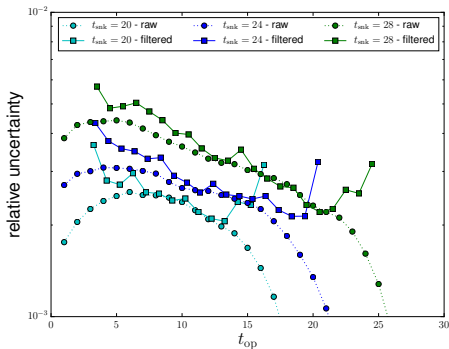
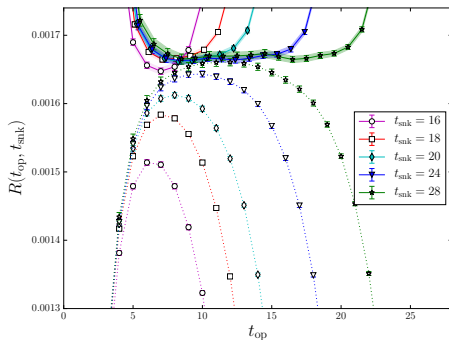


- Same plateau for different  $t_{\text{snk}}$   
 $\Leftrightarrow$  removed excited states
- $t_{\text{snk}} = 20, 24, 28$  compatible
- Several options: Could instead/also apply  $D_{\lambda_3}$  to  $C_3$
- **different asymptotic value**

$$\lim_{0 \ll t_{\text{op}} \ll t_{\text{snk}}} LF(R_\mu(t_{\text{op}}, t_{\text{snk}})) = \frac{\lim_{0 \ll t_{\text{op}} \ll t_{\text{snk}}} R_\mu(t_{\text{op}}, t_{\text{snk}})}{(\lambda_I^2 - \tilde{E}_I^2)(\lambda_F^2 - \tilde{E}_F^2)}$$

## Example: $D_s \rightarrow \eta_s$ (Laplace filtered) cont.

Correct for  $(\lambda_I^2 - \tilde{E}_I^2)(\lambda_F^2 - \tilde{E}_F^2)$  by 'reading off'  $E_0^I$  and  $E_0^F$  from effective mass



- $t_{\text{snk}} = 28$  raw within less than  $2\sigma$  of filtered results
- multiple  $t_{\text{snk}}$  at same plateau value
- extended plateaus!
- similar statistical precision for filtered and unfiltered!

# Neutral meson mixing

- Same initial and final state: “Same spectrum on both sides”
- For  $0 < t_{\text{op}} < t_{\text{snk}}$  we have

$$C_3^{O_k}(t_{\text{op}}, t_{\text{snk}}) = \sum_{i,j} Z_i Z_j \langle P_j | O_k | P_i \rangle e^{-E_j t_{\text{op}} - E_i (t_{\text{snk}} - t_{\text{op}})}$$

(safely neglecting around the world effects since  $E_0 \sim 0.94$ )

- at fixed  $t_{\text{snk}}$ :  $t_{\text{op}}$  dependence cancels if single-state dominated
- historical normalisation: “bag parameters”, e.g. for Standard Model bag parameter (VV+AA)

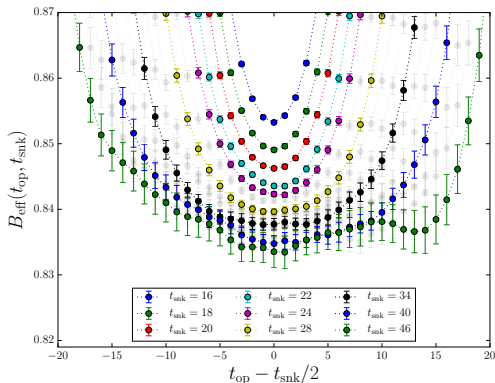
$$B_{\text{eff}}(t_{\text{op}}, t_{\text{snk}}) = \frac{C_3^{O_1}(t_{\text{op}}, t_{\text{snk}})}{8/3 C_2^{PA}(0) C_2^{AP}(t_{\text{snk}})}$$

**normalisation does not influence  $t_{\text{op}}$ -dependence.**

## Example: $\overline{B}_s - B_s$ mixing (raw data)

$$B_{\text{eff}}(t_{\text{op}}, t_{\text{snk}}) = \frac{C_3^{O_1}(t_{\text{op}}, t_{\text{snk}})}{8/3 C_2^{PA}(-t_{\text{snk}}/2) C_2^{AP}(t_{\text{snk}}/2)}$$

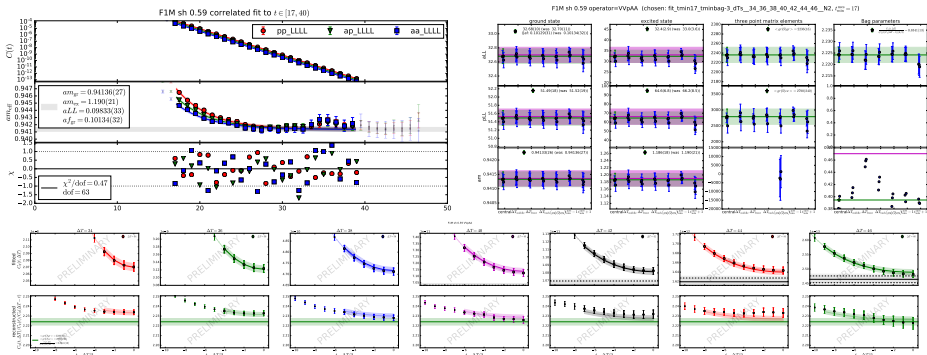
- $a^{-1} \sim 2.7 \text{ GeV}$ ,  
 $m_\pi \sim 230 \text{ MeV}$ ,  
 $L^3 \times T = 48^3 \times 96$
- $am_s \sim am_s^{\text{phys}}$ ,  $am_h = 0.59$   
 $\Rightarrow M_{D_s} < M_{H_s} < M_{B_s}$
- $N_{\text{conf}} = 72$
- 48  $\mathbb{Z}_2$  source-planes/config
- 16 different  $t_{\text{snk}}$  values (only plotting some of them for readability!)



# Example: $\bar{B}_s - B_s$ mixing ("traditional" analysis)

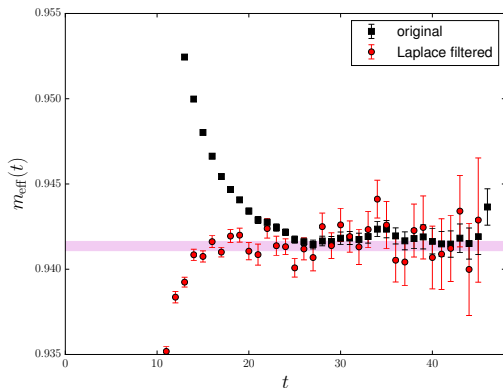
Results "known" from extensive stability analysis:

- 2-exponential frequentist fit
- simultaneously fit in both time coordinates  $C_2(t_{\text{op}})$  and  $C_3(t_{\text{op}}, t_{\text{snk}})$  for many  $t_{\text{snk}} \in [34, 46]$
- source-place treatment [JTT, RBC/UKQCD, 2404.02297]



## Example: $\overline{B}_s - B_s$ mixing (Laplace filtered - mesons)

$$C_2(t) \sim \sum_i A_i e^{-E_i t}$$



“Known”  $E_i$ : Use  $\lambda = \tilde{E}_1$

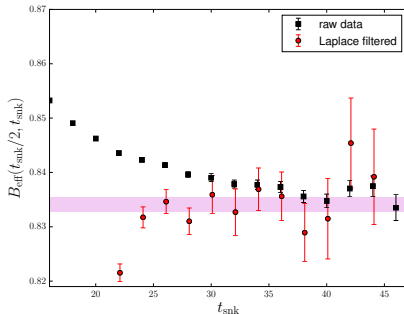
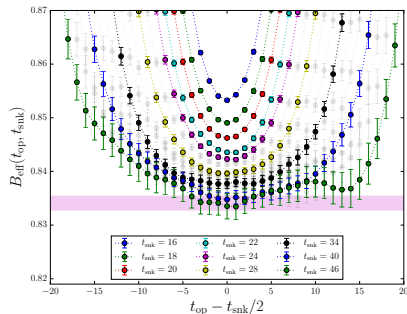
- Individual errors grow, but more independent information
- Reducing correlations between neighbouring time-slices  
 $\Rightarrow$  noisier effective mass data.
- plateau starts  $\sim 10$  time-slices earlier

# Example: $\overline{B}_s - B_s$ mixing (Laplace filtered - bags)

Recall

$$C_3(0, t_{\text{snk}}) \sim \sum_{i,j} Z_{ij} e^{-(E_i + E_j) \frac{t_{\text{snk}}}{2}}$$

Use “known” energies in LF: Use  $\lambda = \tilde{E}'$  where  $E' = (E_1 + E_2)/2$  restrict to  $t_{\text{op}} = t_{\text{snk}}/2$  (i.e. midpoint) for  $C_3$



- Sometimes (other ensembles/operators) even maximal  $t_{\text{snk}}$  too small.
- Individual errors grow, but more independent information



## Conclusions and outlook

# Summary

## Numerical estimation of correlation matrices

- significant improvement without any ad-hoc assumptions
- simple analysis: transformed data can be fitted to transformed model
- tunable parameter to reduce correlations...

## Contamination by excited states

- ... and use tunable parameter to remove excited states  
⇒ gain control over ground state parameters
- no additional data generation + can be applied post-data production
- demonstrated applications for two-point and three-point functions

## Alternatives and improvements to non-linear fitting

- get spectrum without needing multi-exponential fits
- determination of number of statistically significant states
- data driven priors & widths (Bayes)/initial guesses (Freq.)

⇒ **Draft in preparation (arXiv:2508.xxxxx)** 😊