

# Parameter extractions for RHIC BES using Bayesian statistics

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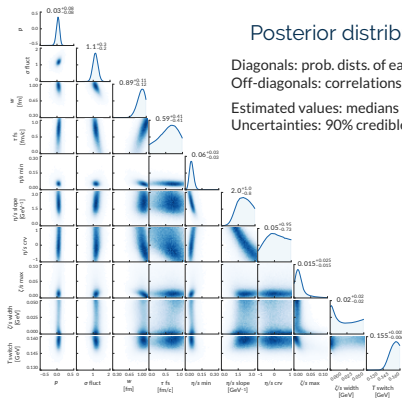
in collaboration with Iu. Karpenko, J. Bernhard and S. A. Bass

CPOD 2017

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# Success of Bayesian approach

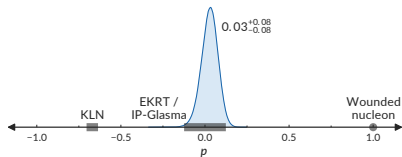


## Posterior distribution

Diagonals: prob. dists. of each param.  
Off-diagonals: correlations b/w pairs

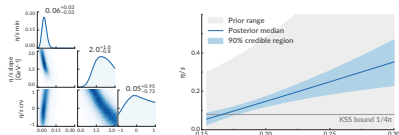
Estimated values: medians  
Uncertainties: 90% credible intervals

## Initial state



## Shear viscosity

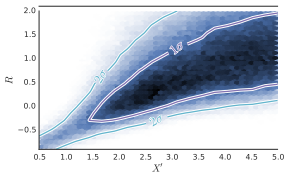
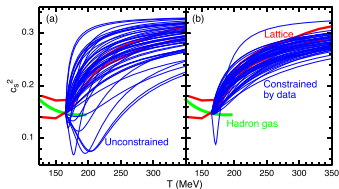
$$(\eta/s)(T) = (\eta/s)_{\min} + (\eta/s)_{\text{slope}}(T - T_C) \times \left(\frac{T}{T_C}\right)^{(\eta/s)_{\text{cv}}}$$



Jonah Bernhard, Quark Matter 2017

# Success of Bayesian approach

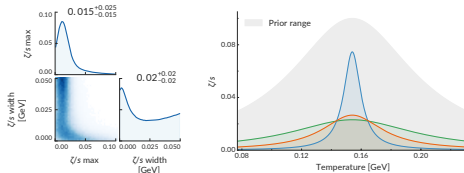
## Equation of state



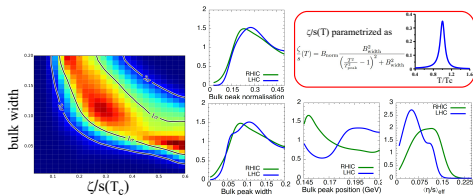
Pratt et al., PRL114, 202301 (2015)

## Bulk viscosity

$$\langle \zeta/s \rangle(T) = \frac{(\zeta/s)_{\max}}{1 + \left( \frac{T - T_c}{(\zeta/s)_{\text{width}}} \right)^2}$$



Jonah Bernhard, QM2017



Gabriel Denicol, QM2017

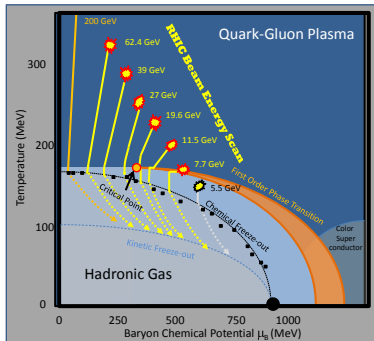
## RHIC beam energy scan

Investigate  $\sqrt{s_{NN}}$ -dependence of  $\eta/s$  using statistical analysis

- Possible indication of  $\mu_B$ -dependence in the transport coefficient
- Statistical analysis  $\Rightarrow$  Get both best-fit values and their uncertainties
- Phase A: Find best-fitting model parameters for multiple collision energies independently
- If energy dependence observed in the best-fit parameters



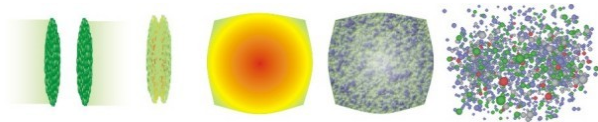
Phase B: parametrize the dependence and find the best fit over all collision energies simultaneously



Picture: G. Odyniec, Acta Phys. Polon. B 43, 627 (2012).

# Transport + hydrodynamics hybrid model

Karpenko, Huovinen, Petersen, Bleicher, Phys.Rev.C, 91, 064901 (2015)



- Initial state described by UrQMD<sup>1</sup> hadron transport
- Start the hydrodynamical evolution at time  $\tau_0$  when the two nuclei have passed through each other
- Convert energy, momentum and baryon number of each particle into 3D Gaussian distributions with width parameters  $W_{\text{trans}}$ ,  $W_{\text{long}}$
- (3+1)D **viscous** hydrodynamics with constant ratio of shear viscosity over entropy density  $\eta/s$  (bulk viscosity ignored)
- Transition from hydro back to UrQMD (“particlization”) when energy density  $\epsilon$  is smaller than the switching condition  $\epsilon_{SW}$

“Cornelius” hypersurface finder, P. Huovinen and H. Petersen, EPJ A48 171 (2012)

<sup>1</sup>S. A. Bass *et al.*, Prog. Part. Nucl. Phys. 41, 255 (1998), M. Bleicher *et al.*, J. Phys. G 25, 1859 (1999).

## Bayesian analysis

Model parameters (input):  $\vec{x} = (x_1, \dots, x_n)$

$(\tau_0, W_{\text{trans}}, W_{\text{long}}, \eta/s, \epsilon_{\text{SW}})$



Model output  $\vec{y} = (y_1, \dots, y_m) \Leftrightarrow$  Experimental values  $\vec{y}^{\text{exp}}$

$(N_{\text{ch}}, \langle p_{\text{T}} \rangle, v_2, \dots)$

Bayes' theorem:

Posterior probability  $\propto$  Likelihood  $\cdot$  Prior knowledge

- Prior knowledge: Range of input parameter values to investigate
- Likelihood:  $\mathcal{L}(\vec{x}) \propto \exp\left(-\frac{1}{2}(\vec{y}(\vec{x}) - \vec{y}^{\text{exp}})\Sigma^{-1}(\vec{y}(\vec{x}) - \vec{y}^{\text{exp}})^T\right)$ , where  $\Sigma$  is the covariance matrix

Use Markov chain Monte Carlo to sample the posterior probability

- Random walk in input parameter space, constrained by prior
- Use Gaussian process (GP) emulator to estimate model output for likelihood computations

## Gaussian process

Stochastic process: A parameterized collection of random variables  $\{y_t\}_{t \in \mathcal{T}}$  ( $\mathcal{T}$  possibly infinite).

E.g. random walk over time.

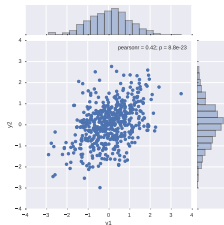
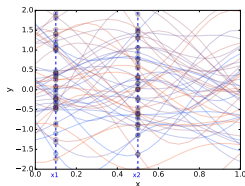
**Gaussian process:** A stochastic process, in which every finite set  $Y = \{y_i\}_{i=1}^N$  is a multivariate Gaussian random variable  $\mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ , where

$$\boldsymbol{\mu} = \mu(X) = \{\mu(x_1), \dots, \mu(x_N)\}$$

is the mean and

$$\boldsymbol{\Sigma} = \sigma(X, X) = \begin{pmatrix} \sigma(\vec{x}_1, \vec{x}_1) & \cdots & \sigma(\vec{x}_1, \vec{x}_N) \\ \vdots & \ddots & \vdots \\ \sigma(\vec{x}_N, \vec{x}_1) & \cdots & \sigma(\vec{x}_N, \vec{x}_N) \end{pmatrix}$$

is the covariance matrix with **covariance function**  $\sigma(\vec{x}, \vec{x}')$ .



## Gaussian process

Choice: Squared-exponential covariance function with a noise term

$$\sigma(\vec{x}, \vec{x}') = \theta_0 \exp\left(-\sum_{i=1}^n \frac{(x_i - x'_i)^2}{2\theta_i^2}\right) + \theta_{\text{noise}} \delta_{\vec{x}\vec{x}'}$$

The *hyperparameters*  $\vec{\theta} = (\theta_0, \theta_1, \dots, \theta_n, \theta_{\text{noise}})$  are not known a priori and must be estimated from a set of model outputs ("training points")

⇒ emulator **training**: Maximise the marginal likelihood (aka "evidence")

$$\log P(Y|X, \vec{\theta}) = \underbrace{-\frac{1}{2} Y^T \Sigma^{-1}(X, \vec{\theta}) Y}_{\text{model data fit}} \underbrace{-\frac{1}{2} \log |\Sigma(X, \vec{\theta})|}_{\text{complexity penalty}} \underbrace{-\frac{N}{2} \log(2\pi)}_{\text{normalization}}$$



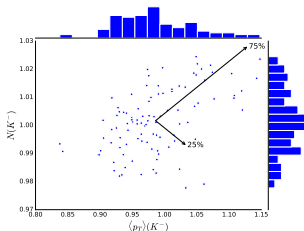
## Principal component analysis

$m$  observables  $\Rightarrow$   $m$  Gaussian processes needed for model emulation

However,  $m$  can be up to  $\mathcal{O}(100)$  at top RHIC energies and at the LHC!  
Number of emulators can be reduced with **principal component analysis**

First principal component represents the direction of largest variance in output space, second PC the direction of second largest variance, etc.

- Fraction of variance explained by principal component  $p_q$ : 
$$\text{Var}(p_q) = \frac{\lambda_q}{\sum_{i=1}^m \lambda_i}$$
- Select the number of principal components which together explain desired fraction of total variance; often only a few PCs are needed to explain 99% of the variance



## Likelihood function

The likelihood function used in MCMC:

$$\frac{1}{|2\pi(\Sigma_{\text{exp}} + \Sigma_{GP})|} \exp\left(-\frac{1}{2}(\vec{z}_{GP}^* - \vec{z}_{\text{exp}})(\Sigma_{\text{exp}} + \Sigma_{GP})^{-1}(\vec{z}_{GP}^* - \vec{z}_{\text{exp}})^T\right)$$

- $\vec{z}_{GP}^*$  is the emulator prediction at the input parameter point  $\vec{x}^*$
- $\vec{z}_{\text{exp}}$  is the experimental data transformed to principal component space
- $\Sigma_{GP}$  is the predictive variance (emulator uncertainty)
- $\Sigma_{\text{exp}}$  is the experimental error squared ( $\sigma_{\text{stat}}^2 + \sigma_{\text{sys}}^2$ ), transformed to PC space

## Analysis procedure

### Produce training data

- run simulations with  $\mathcal{O}(100)$  different parameter combinations

### Preparation for principal component analysis:

1. Scale with experimental values  $\Rightarrow$  Unitless quantities
2. Check that the values are roughly normally distributed; apply a transformation if necessary
3. Center the data; apply possible data weighting

Determine required number of Gaussian processes with PCA

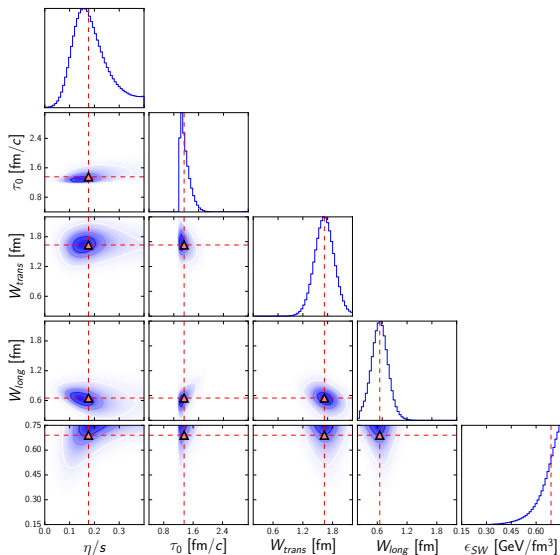


Condition the emulators on training data



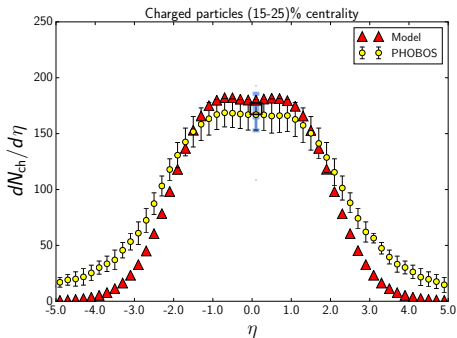
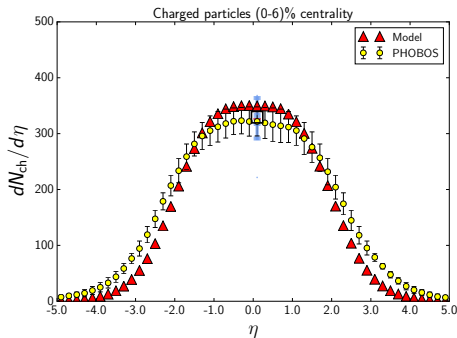
Calibrate on experimental data by running MCMC

# Posterior probabilities at $\sqrt{s_{NN}} = 19.6$ GeV



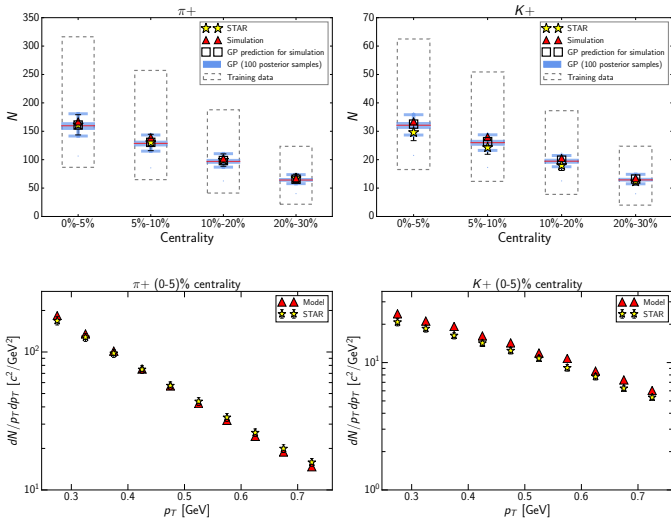
Observables at  $\sqrt{s_{NN}} = 19.6$  GeV

## Charged particle pseudorapidity distribution vs. centrality



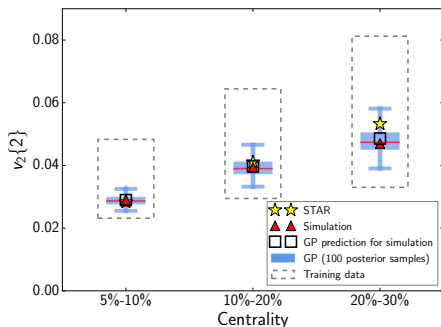
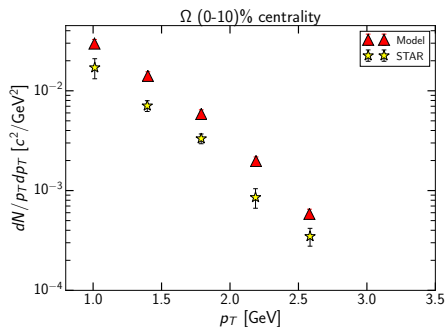
Observables at  $\sqrt{s_{NN}} = 19.6$  GeV

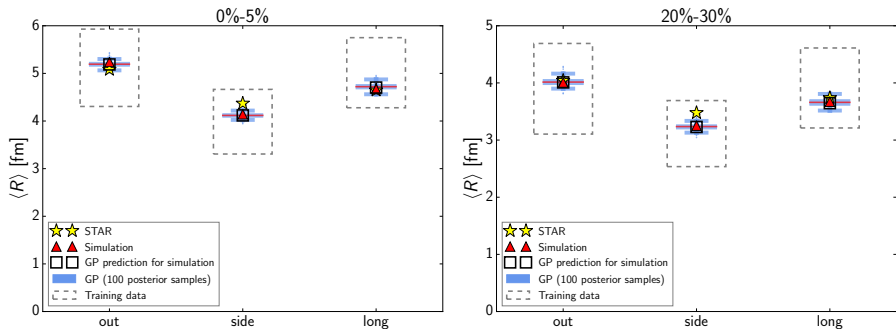
## Pion and kaon multiplicities and transverse momentum spectra



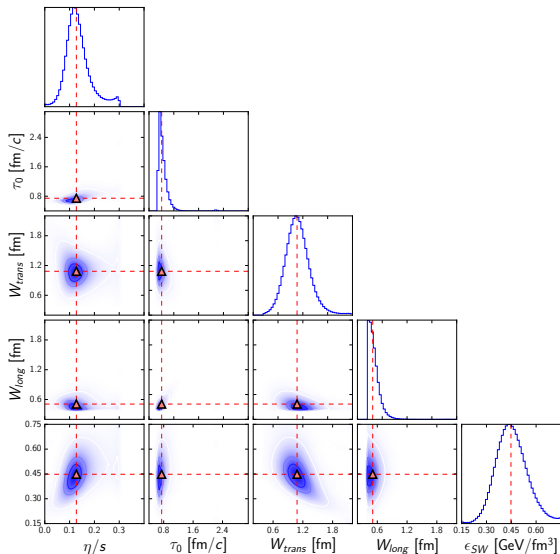
# Observables at $\sqrt{s_{NN}} = 19.6$ GeV

## $\Omega$ $p_T$ spectrum and elliptic flow $v_2\{2\}$



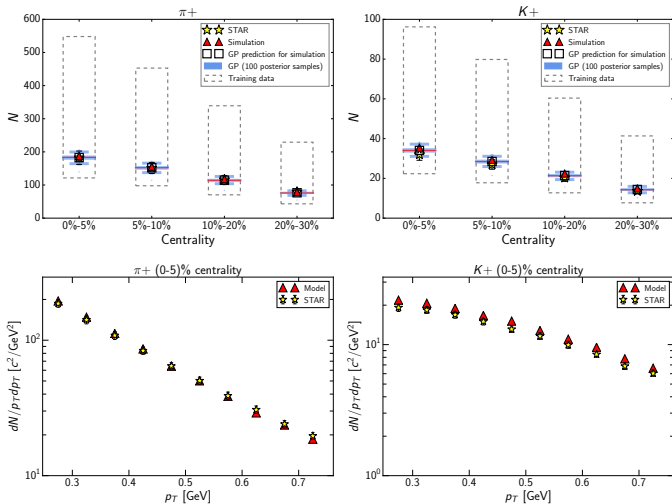
Observables at  $\sqrt{s_{NN}} = 19.6$  GeVHBT radii from two-pion interferometry (averaged over 4  $m_T$  bins)

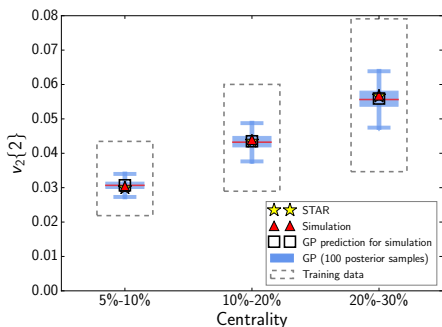
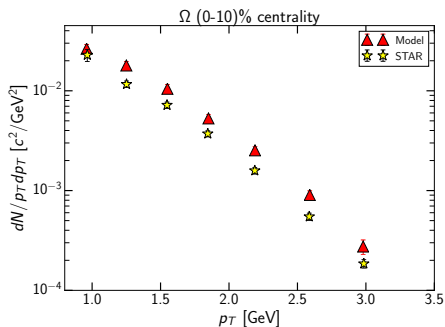


Posterior probabilities at  $\sqrt{s_{NN}} = 39$  GeV

Observables at  $\sqrt{s_{NN}} = 39$  GeV

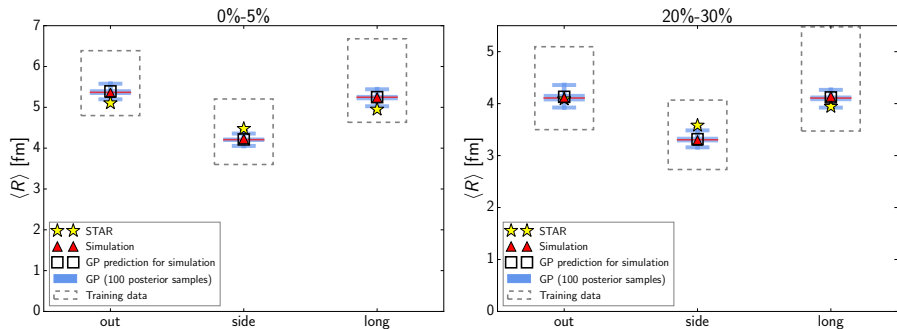
## Pion and kaon yields

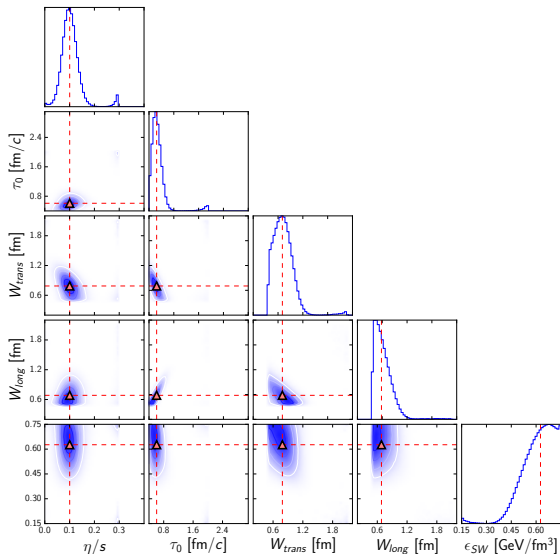


Observables at  $\sqrt{s_{NN}} = 39$  GeV $\Omega$   $p_T$  spectrum and elliptic flow  $v_2\{2\}$ 

# Observables at $\sqrt{s_{NN}} = 39$ GeV

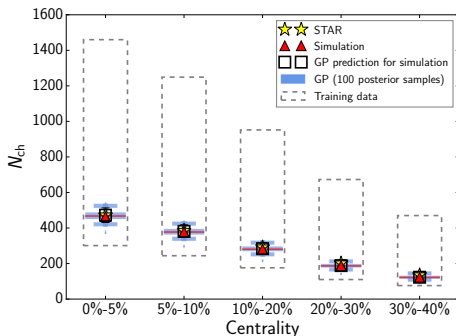
HBT radii (averaged over 4  $m_T$  bins)



Posterior probabilities at  $\sqrt{s_{NN}} = 62.4$  GeV

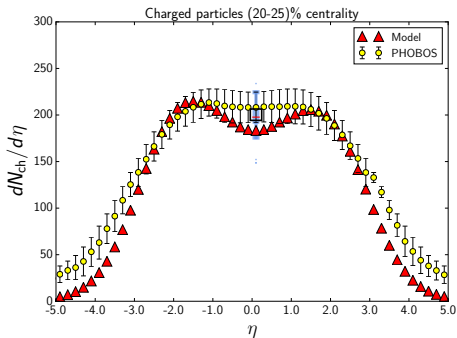
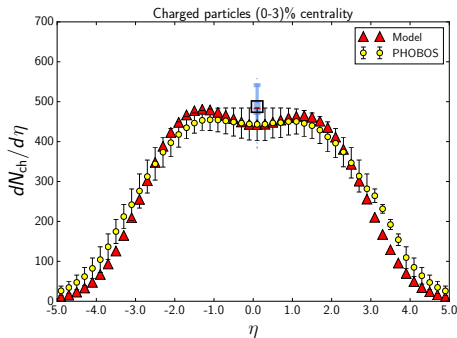
# Observables at $\sqrt{s_{NN}} = 62.4$ GeV

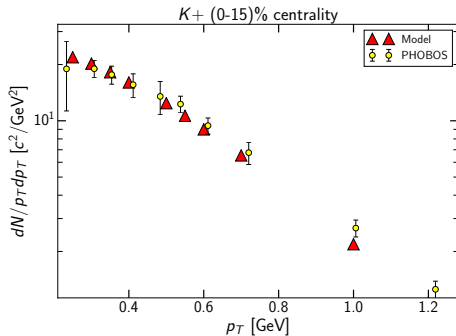
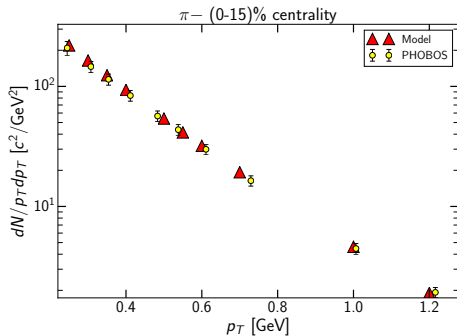
## Charged particle yield vs. centrality



Observables at  $\sqrt{s_{NN}} = 62.4$  GeV

## Pseudorapidity distribution vs. centrality

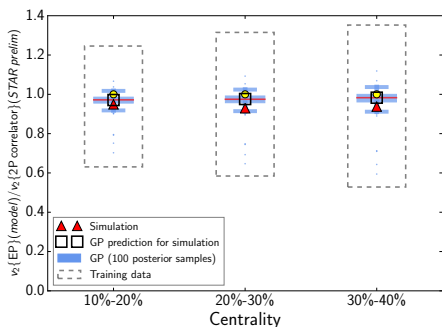
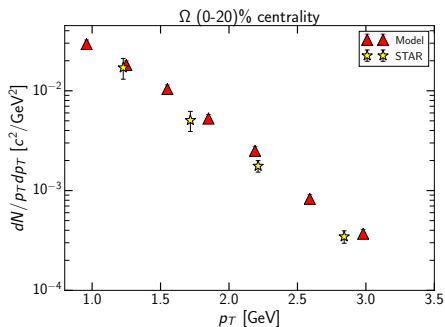


Observables at  $\sqrt{s_{NN}} = 62.4$  GeVPion and kaon  $p_T$  spectra



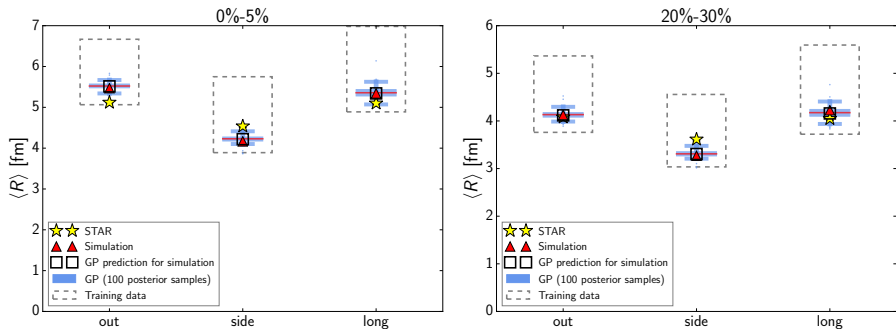
# Observables at $\sqrt{s_{NN}} = 62.4$ GeV

## $\Omega$ $p_T$ spectrum and elliptic flow $v_2$ {EP}

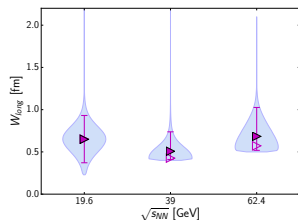
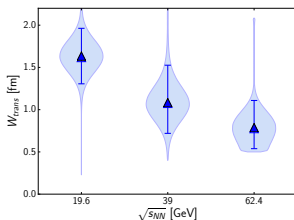
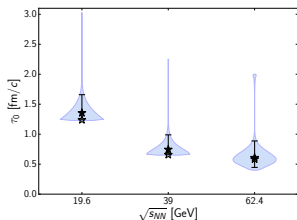
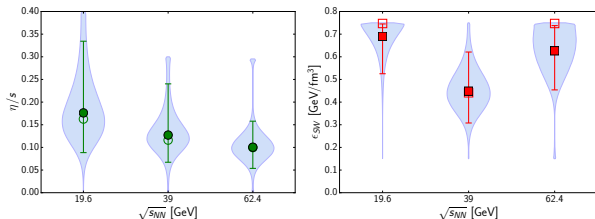


# Observables at $\sqrt{s_{NN}} = 62.4$ GeV

HBT radii (averaged over 4  $m_T$  bins)



# Parameter dependence on collision energy



Filled symbols: Median values

Open symbols: Peak values

Error bars: 90% confidence range

## Summary

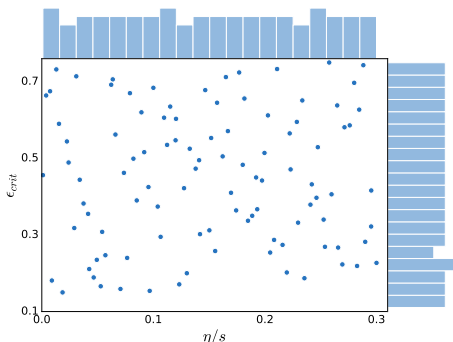
- Bayesian analysis provides a rigorous method for simultaneous estimation of both the best-fit values and the associated uncertainties for the parameters of heavy ion collision models
- Pion  $p_T$  spectra and charged particle elliptic flow  $v_2$  well reproduced using median values from the posterior probability distributions
- Charged particle pseudorapidity distribution and  $R_{\text{side}}$  have systematic deviations from measured values; excess of strange particles at lower beam energies
- Transport-to-hydro switching time  $\tau_0$  and longitudinal smoothing  $W_{\text{long}}$  well constrained by data, while transverse smoothing  $W_{\text{trans}}$ , hydro-to-transport switching density  $\epsilon_{\text{SW}}$  and shear viscosity  $\eta/s$  have larger uncertainties
- While the most probable value of  $\eta/s$  is higher at lower energies, a constant value of 0.10 – 0.15 cannot be currently excluded

# Extra slides

## Investigated parameter ranges

Sample points evenly over whole parameter space using Latin hypercube method

- Shear viscosity over entropy density  $\eta/s$ : 0.001 - 0.4
- Transport-to-hydro transition time  $\tau_0$ : 0.4 - 3.1 fm
- Transverse Gaussian smearing of particles  $W_{\text{trans}}$ : 0.2 - 2.2 fm
- Longitudinal Gaussian smearing of particles  $W_{\text{long}}$ : 0.2 - 2.2 fm
- Hydro-to-transport transition energy density  $\epsilon_{SW}$ : 0.15 - 0.75 GeV/fm<sup>3</sup>



## Gaussian process prediction

To predict the model output  $y_0$  in an arbitrary point  $\vec{x}_0$ , we write the joint distribution

$$\begin{pmatrix} y_0 \\ Y \end{pmatrix} = \mathcal{N} \left( \begin{pmatrix} \mu(\vec{x}_0) \\ \mu(X) \end{pmatrix}, \begin{pmatrix} \Sigma_{0,0} & \Sigma_{0,X} \\ \Sigma_{X,0} & \Sigma_{X,X} \end{pmatrix} \right)$$

and calculate the conditional predictive mean

$$\bar{\mu}(\vec{x}_0) = \mu(\vec{x}_0) + \Sigma_{0,X} \Sigma_{X,X}^{-1} (Y - \mu(X)).$$

Typically we define the mean function  $\mu(\vec{x}) \equiv 0$  and the prediction is simply

$$\bar{\mu}(\vec{x}_0) = \Sigma_{0,X} \Sigma_{X,X}^{-1} Y$$

with the associated predictive (co)variance

$$\bar{\Sigma} = \Sigma_{0,0} - \Sigma_{0,X} \Sigma_{X,X}^{-1} \Sigma_{X,0}.$$