



## **Neutron Data Standards: Software and Method Developments**

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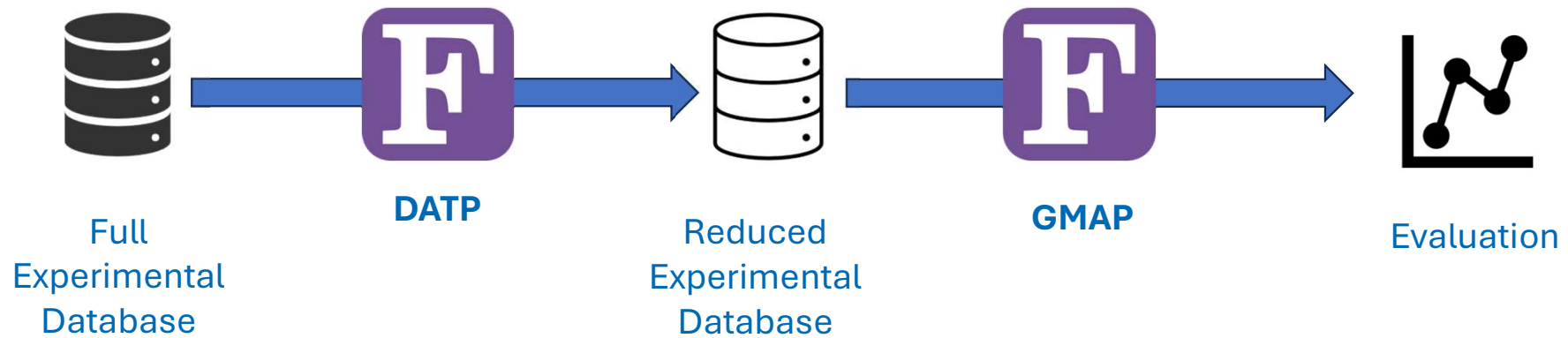
CSEWG Meeting on 8 January 2026



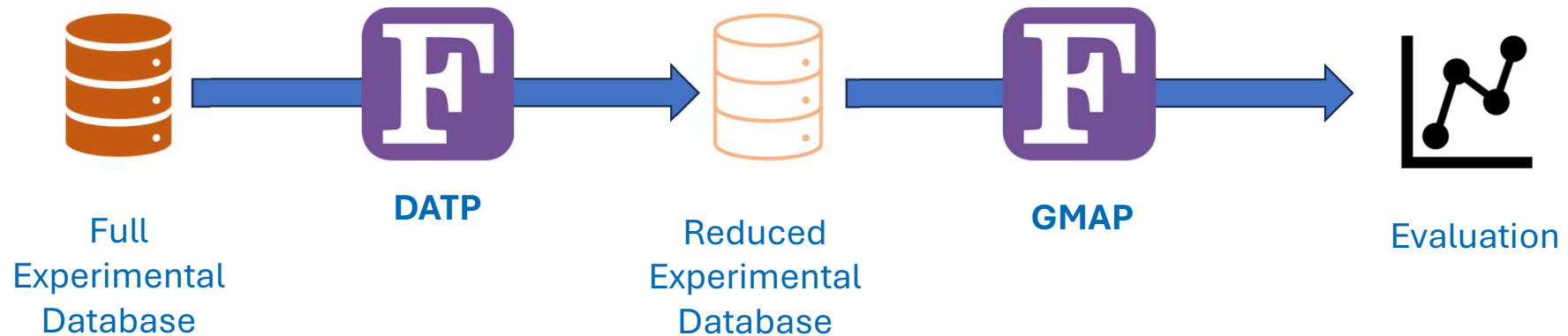
# Outline

- Software modernization
- Method developments
- Brief update on neutron standards developments

# Neutron Standards Pipeline



# Data format modernization



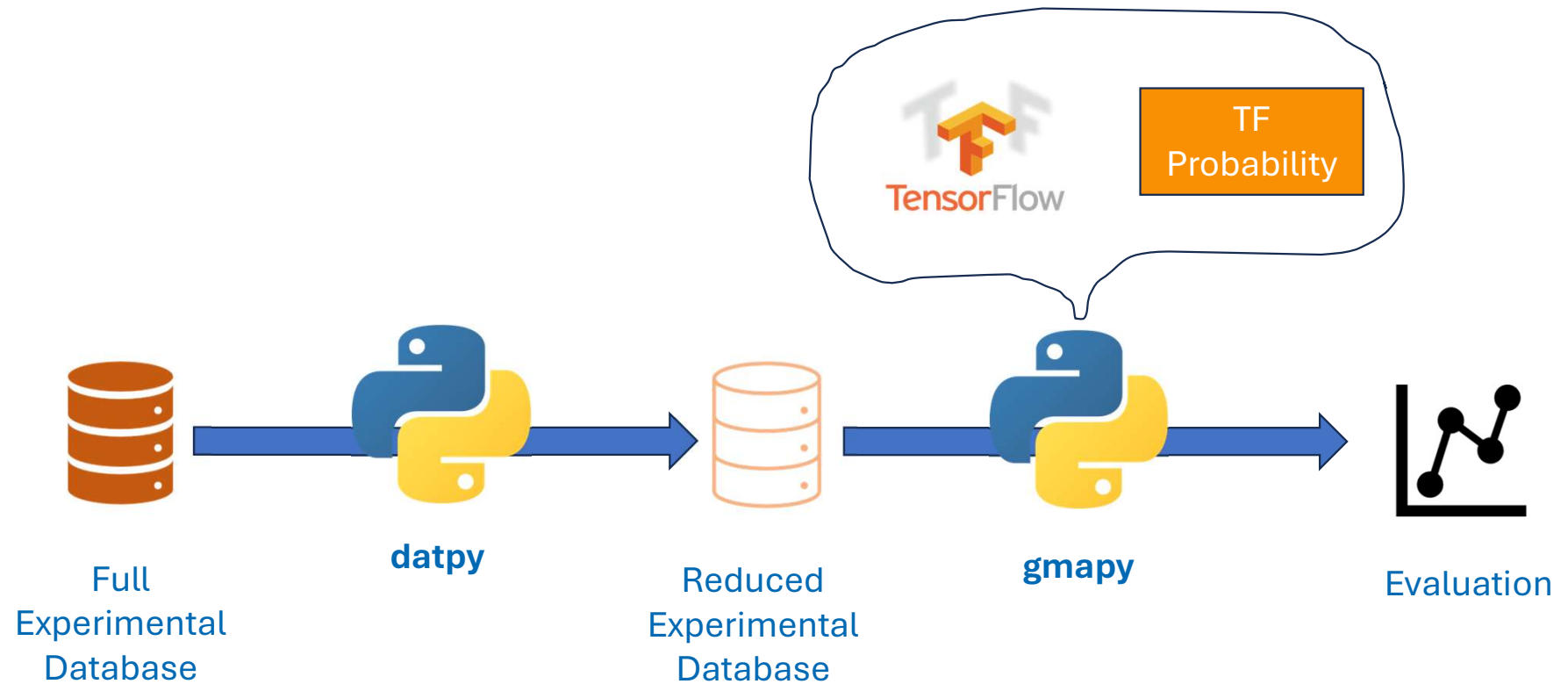
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UNCERTAINTIES
3 STATISTICS
4 BACKGROUND
5 B DET. EFF.
6 FF DET. EFF.
11 MERC TO REDUCE THE DIFFERENCE WITH A POSTERIOR *REV*
.00 .00 .00
.00 .00 .00
.00 .00 .00
.50 .50 .50
.50 .50 .50
.50 .50 .50
.00 .00 .00
.00 .00 .00
.00 .00 .00
.00 .00 .00
.50 .50 .50
0 0 9 2 2 2 0 0 0 0 1
.1500E-03 .3626E+00 .0 33.3 1.0 1.5 .1 .2 .0 .0 .0 .0 3.1 1.8
.2500E-03 .4776E+00 .0 20.0 1.0 1.5 .1 .2 .0 .0 .0 .0 1.7 1.8
.3500E-03 .2598E+00 .0 14.3 1.0 1.5 .1 .2 .0 .0 .0 .0 .0 1.8
```

Legacy format

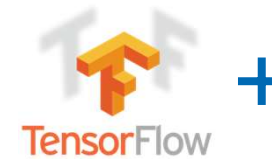
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  ],
}
```

Modern format (JSON)

# Code modernization



# Flexibility in method choice



TF  
Probability

$$\log p(\vec{x} \mid \vec{d}) = -\frac{1}{2} \left( n \log(2\pi) + \log \det \Sigma + \chi^2(\vec{x}) \right)$$

$$\chi^2(\vec{x}) = \left( \vec{d} - f(\vec{x}) \right)^T \Sigma^{-1} \left( \vec{d} - f(\vec{x}) \right)$$

$$\Sigma = \left[ \left( f(\vec{x})^T f(x) \right) \right] \odot \Sigma_{\text{rel}}$$

**Maximum Likelihood / Maximum A-Posteriori:** Find  $x$  to maximize  $\log p(x|d)$

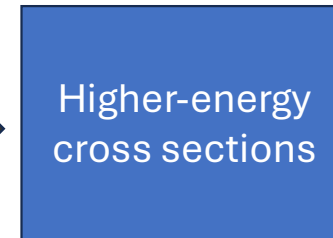
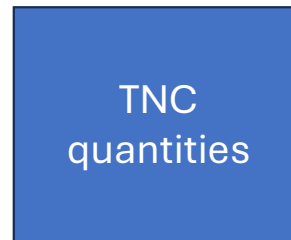
**ChiSquare minimization:** Find  $x$  to minimize  $\chi^2$

**Generalized Least Squares:** Apply iteratively GLS equation (Fortran GMAP approach)

**Bayesian inference:** Sample from posterior distribution by MCMC (e.g. Hamiltonian Monte Carlo)

# Support for statistical model extensions

Cut posteriors  
(cut-Bayes)



Bayesian hierarchical modeling  
“Uncertain Uncertainties”

$$\rho(\vec{\sigma}_{\text{true}}, \Sigma'_{\text{exp}} \mid \vec{\sigma}_{\text{exp}}) \propto \rho(\vec{\sigma}_{\text{exp}} \mid \vec{\sigma}_{\text{true}}, \Sigma'_{\text{exp}}) \rho(\vec{\sigma}_{\text{true}}) \rho(\Sigma'_{\text{exp}})$$



# Summary

- Significant code modernization (with extensive validation)
- Traceability and reproducibility significantly enhanced (JSON database, modular code structure)
- New ML backend (TensorFlow) allows choice of statistical method (and makes extensions possible)
- Decision on which method to use not yet taken
- Within Standards committee: Progress in dataset preparation, R-matrix, TNC and Cf-252(s.f.) PFNS evaluation
- Next IAEA technical meeting on Neutron Data Standards: 26-30 January 2026



# GitHub repositories

- <https://github.com/iaea-nds/gmapy>
- <https://github.com/IAEA-NDS/datp-python>
- <https://github.com/IAEA-NDS/gmap-fortran>
- <https://github.com/IAEA-NDS/datp-fortran>
- <https://github.com/IAEA-NDS/neutron-standards-evaluation>
- <https://github.com/IAEA-NDS/neutron-standards-pipeline>
- <https://github.com/IAEA-NDS/neutron-standards-database>

## Important Disclaimers:

- All of these repos are work in progress (especially on dev and feature branches)
- Most documentation non-existent (but will be created eventually)
- Therefore, at present repos mostly relevant for standard contributors (not the general public)