
Discussion for EEEMCal and pfRICH and PST mount on GST

Initial concepts and progress

02 March 2026

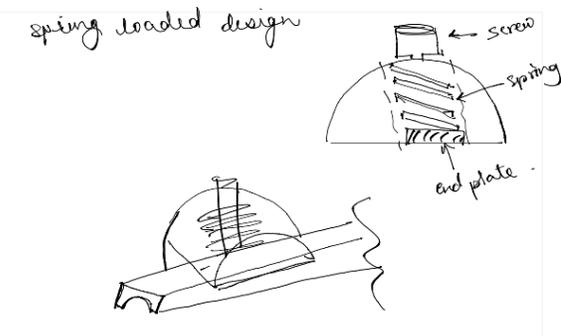
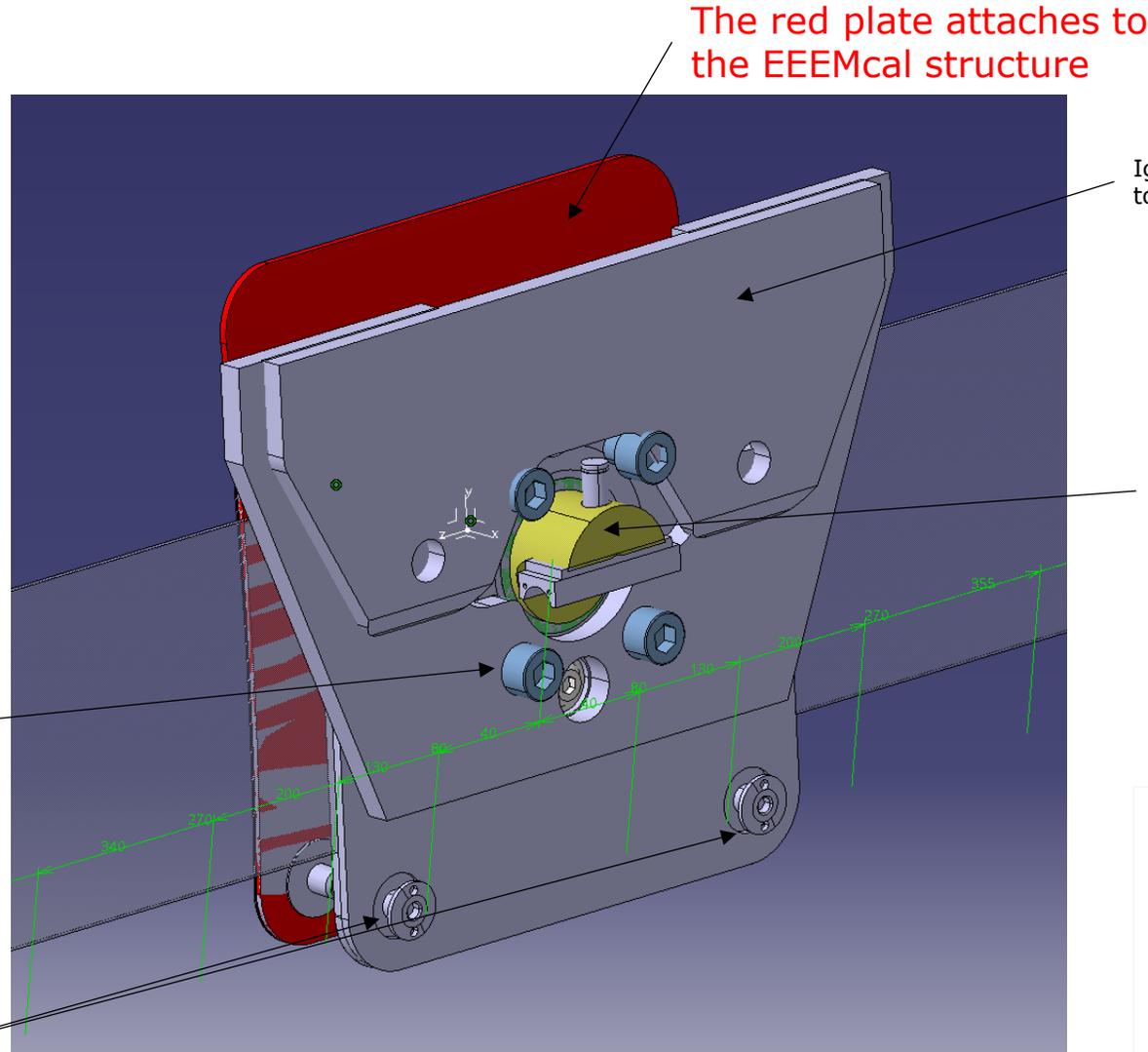
Version 3 of the slider foot concept

Comments received on this version –

1. Need it to be a “rolling” foot instead of a sliding foot
2. The adjustment for EEEMCal is just to get it “in the volume”
3. Adjustment for PST package needs to be more accurate since that has the beam pipe

These 4 bolts allow for movement in the X-axis

These two bolts allow for rotation about **local** the “z” axis



Version 3 of the slider foot concept

⬠ The track groove is changed from a round CFRP tube/rod into conical shape per BNL engineering request

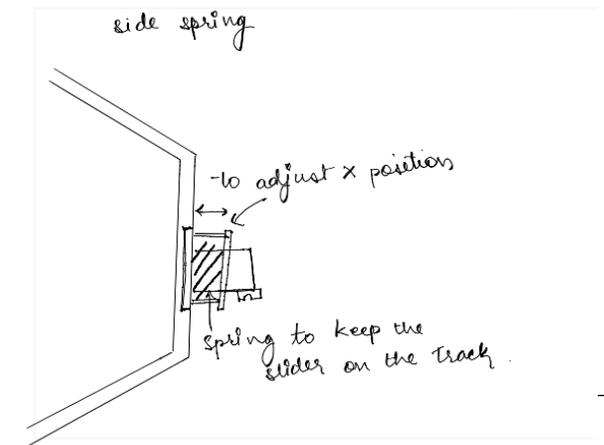
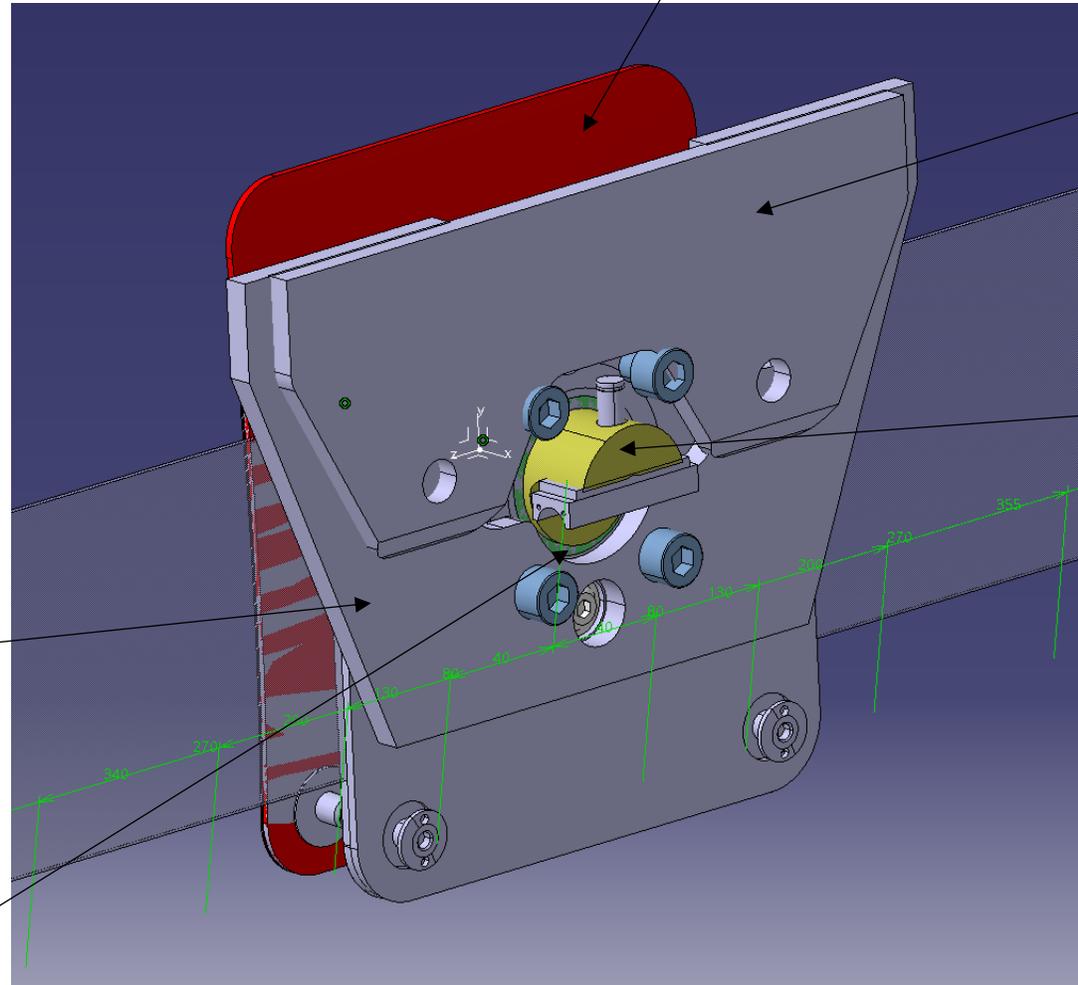
This is pressure plate for spring to restrict and adjust motion in X

Spring and roller system to allow for breathing in X direction

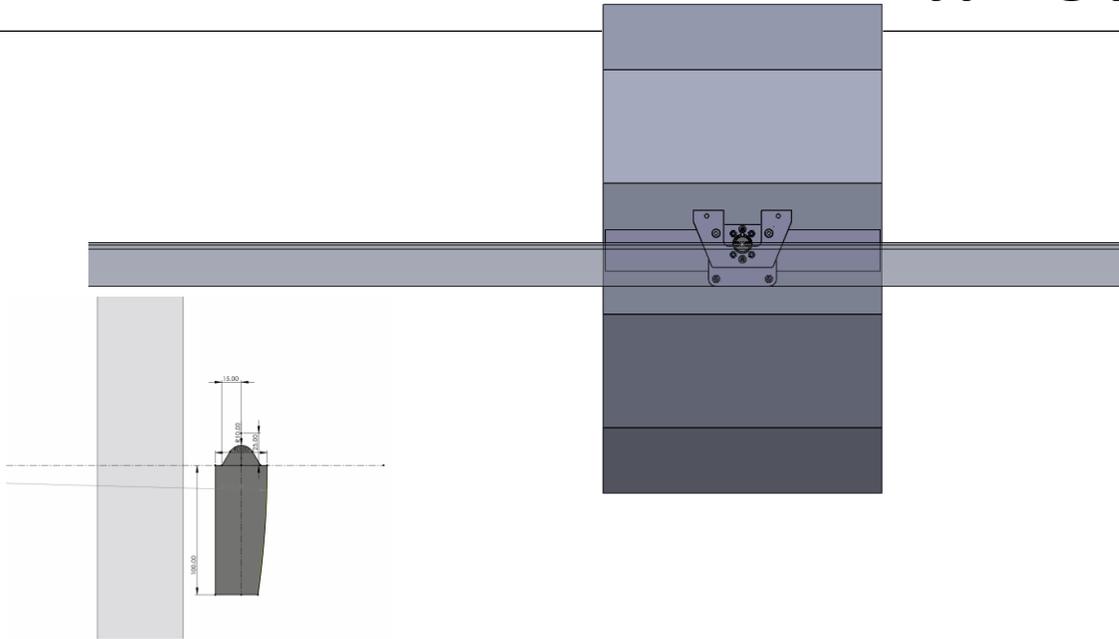
The red plate attaches to the EEEMcal structure

Ignore this plate... just realized I forgot to hide this when taking a screenshot

Spring loaded mechanism to ensure that the sliding mechanism is always in contact with the Rails and does not "jump" while sliding along Z



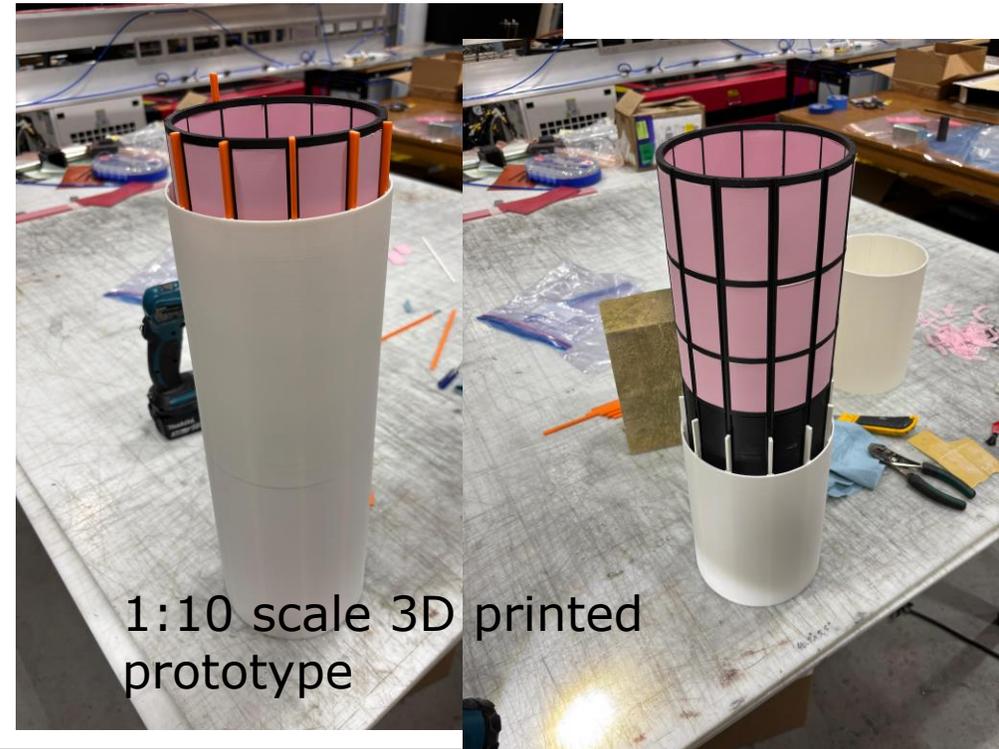
Prototyping progress at Purdue



On-going work –

1. FEA of the new conical rails for GST
2. Prototyping of the mounting mechanism in 1:10 scale including rails and adjustment mechanism of the GST
3. Refinement of the mounting mechanism for the EEEMCal and other inner detectors

- ◊ This is what the design in the EEEMCal geometry looks like.
- ◊ You can have 1 foot per side – or 2 foot per side – being decided by the FEA and prototypes currently in progress at Purdue



Updated rails to use needle linear bearings

This is the best available for the application

Can take upto 5000 kg

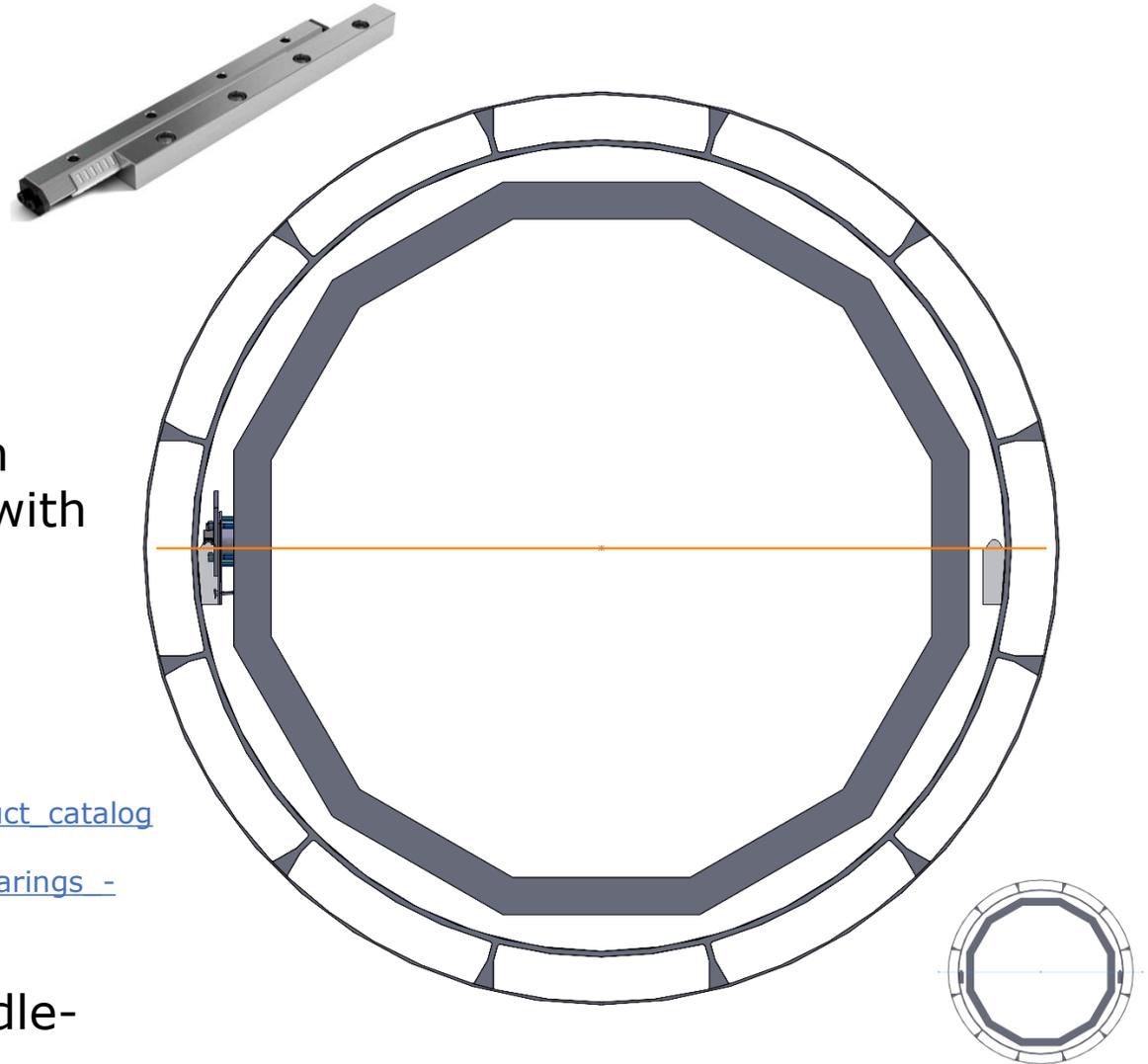
But no off the shelf part available for this

Working with 2 companies for the quotes and possibilities of custom designed linear bearings NRB bearings is willing to come up with custom solutions for GST – trying to set up a meeting with them in early march

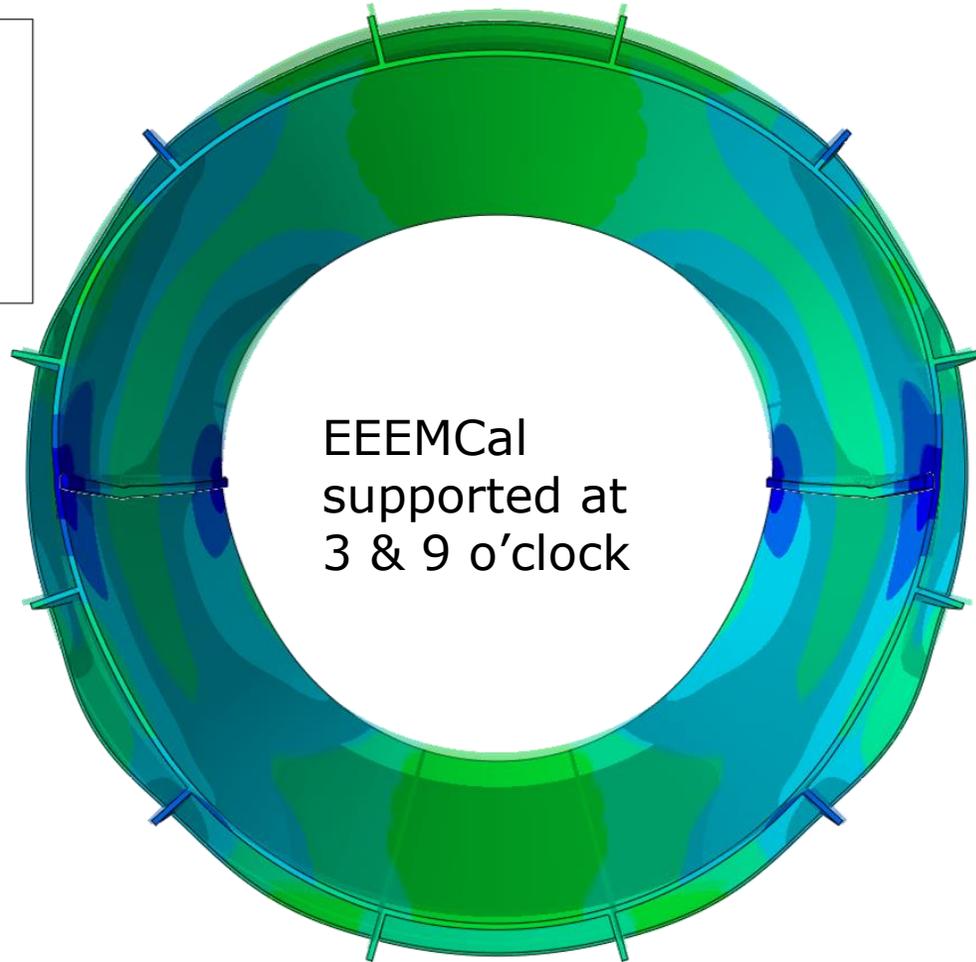
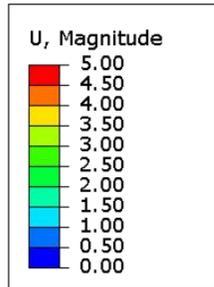
<https://www.nrbbearings.com/index.htm>

https://www.schneeberger.com/fileadmin/documents/downloadcenter/01_product_catalogues_company_brochures/01_Linear_and_profiled_guideways/03_Linear_bearings_and_recirculating_units/Linearbearings_-_Product_catalogue_EN.pdf

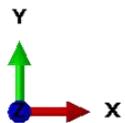
<https://www.linearmotiontips.com/what-are-needle-roller-linear-bearings/>



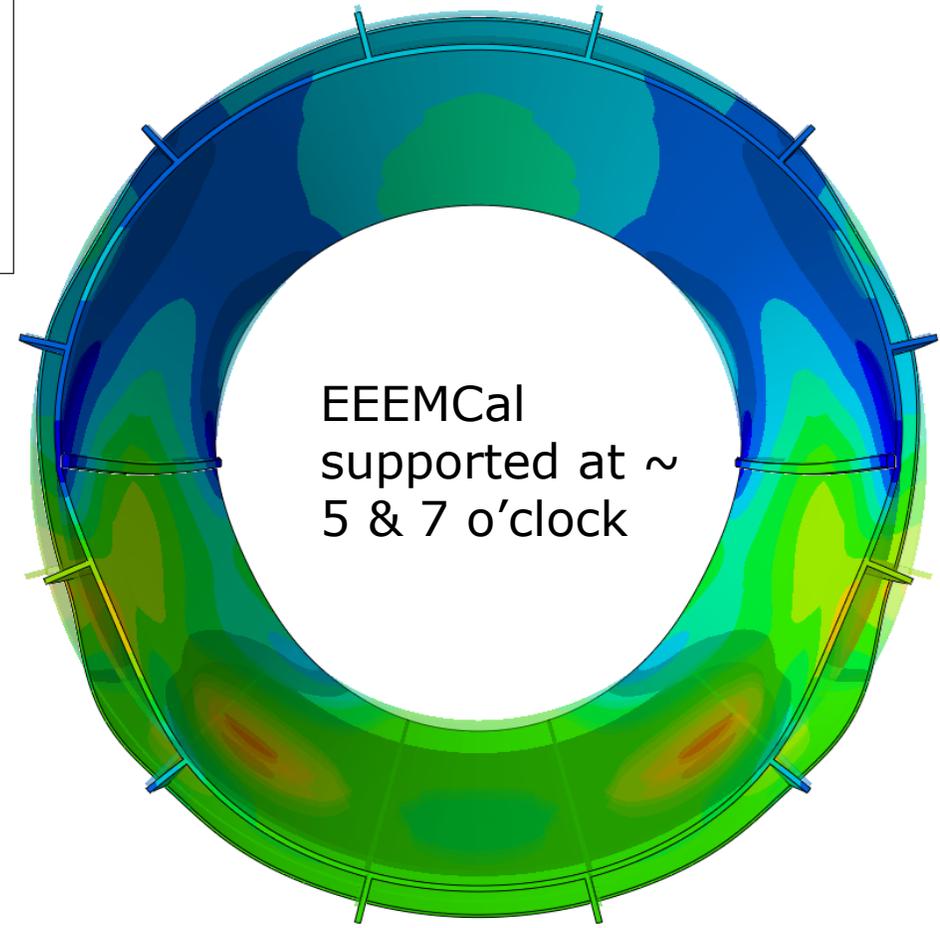
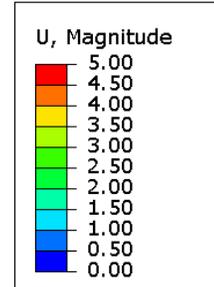
Simulation results for GST



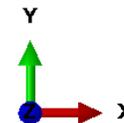
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Step: SelfWeight
Increment 1: Step Time = 1.000
Primary Var: U, Magnitude
Deformed Var: U Deformation Scale Factor: +1.00e+01

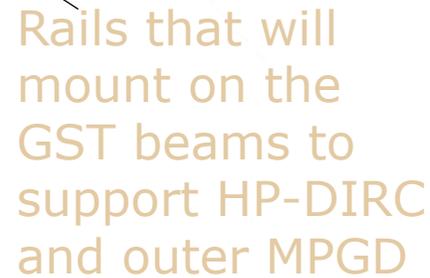
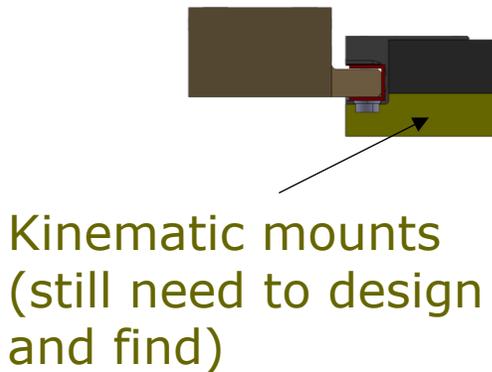
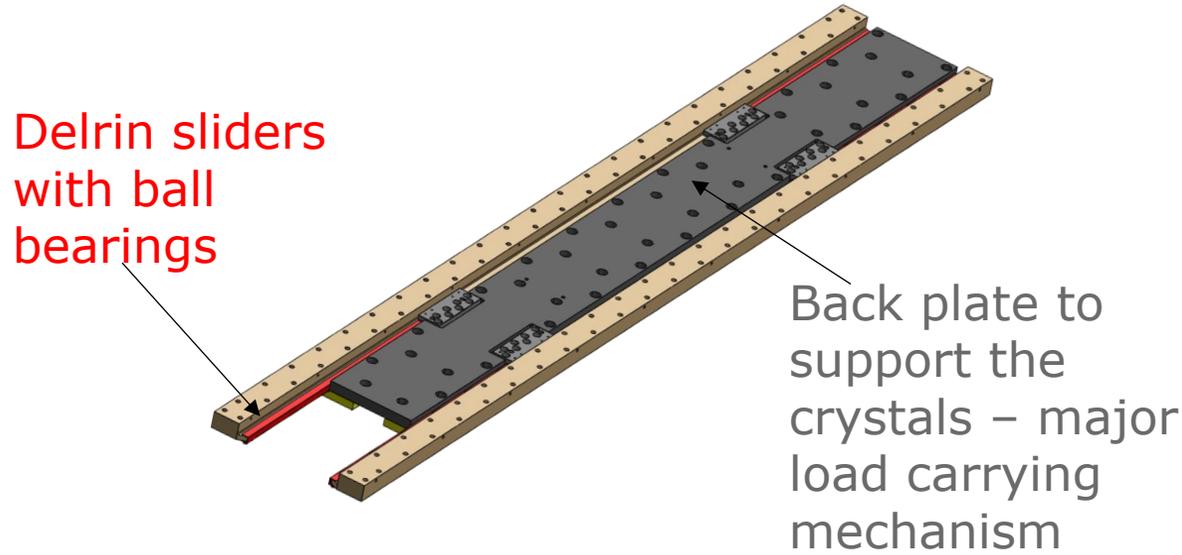


ODB: GST_BaseDesign_CFRP_57rails.odb Abaqus/Standard 2024 Tue Jan 27 20:25:28



Step: SelfWeight
Increment 1: Step Time = 1.000
Primary Var: U, Magnitude
Deformed Var: U Deformation Scale Factor: +1.00e+01

Mounting mechanism design – preliminary for quartz HPDIRC crystals into GST

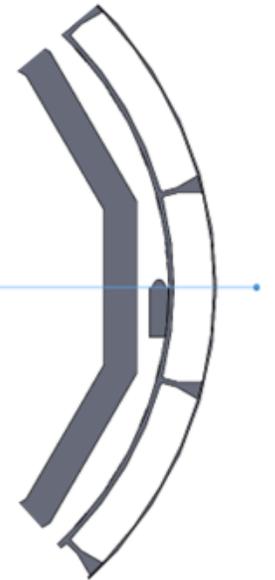


- Very preliminary adaptation from the HGICAL mounting mechanism for CMS.
- Still working out the details – stress analysis for crystals

Coming up next work –

- Full scale 3 drawer prototype of GST with rails and inserts for HP-DIRC
(well I guess not the EEEMCal part of this picture)

- Current team working on GST
 - Andy Jung
 - Sushrut Karmarkar (Engineer)
 - Anish Tilak (PhD student)
 - David Vasilev (UG intern)
 - Gavin Forrest (UG intern)



Simulation results for GST

