



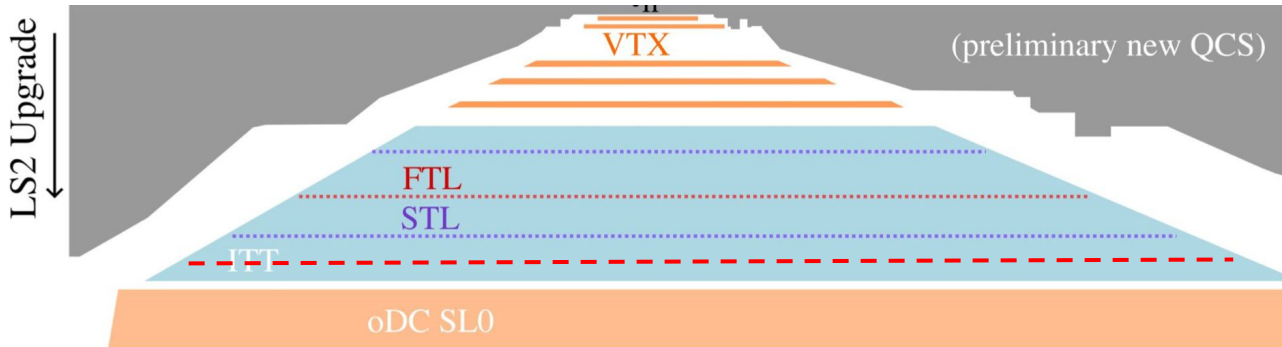
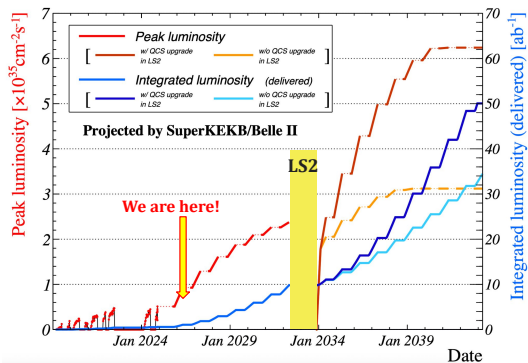
UNIVERSITY
of HAWAII®
MĀNOA

Fast Timing Layer-based EventT0

For Belle II upgrade

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Introduction



- Fast Timing Layer (FTL) in the Belle II upgrade (~2032)
- FTL: excellent PID for low-Pt tracks
 - Further improved by looping tracks
 - Requires a good time reference for the TOF measurement
 - Assumes a close-to-perfect T0 (collision time, $\sigma \approx 25 \text{ ps}$)

Goal: investigate the performance of FTL-based EventT0

- Current b2 EventT0 has several contributions at different stages of reconstruction
- The final value is taken with priority on the CDCchi2 extraction with $\sigma \sim 1 \text{ ns}$

$$\text{CDC}_{\chi^2} > \text{SVD} > \text{CDC}_{\text{hit}}$$

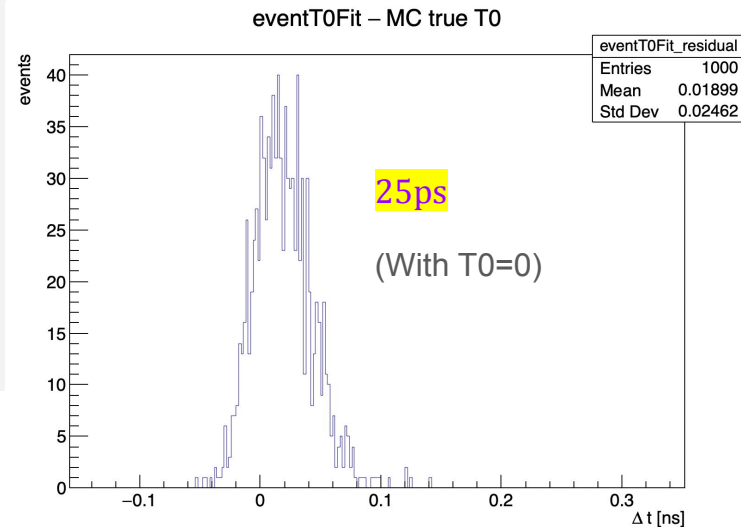
Offline EventT0

- Method to get the $T0_{event}$ giving tracking:
 - For a track with known p:
 - $T_{hit,i} = T0_{event} + T_{TOF, mass}$ (flight length, mc_mass)
 - $R_i = T_{hit,i} - T0_{event} - T_{TOF, mass}$
 - In each event:
 - scan of $T0_{event} = \arg \min \sum (R_i^2 / \sigma_i^2)$ (Remove outliers with pull > 4ns)

* mass from mc

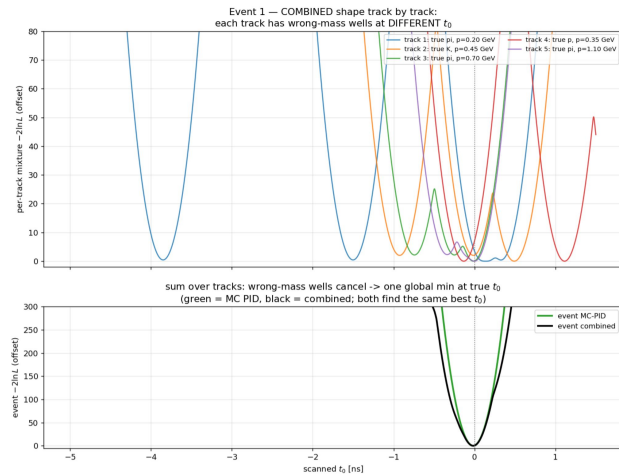
- Inputs from PID would be helpful
- EventT0 and TOF-based PID are interdependent

→ Joint EventT0 and PID determination



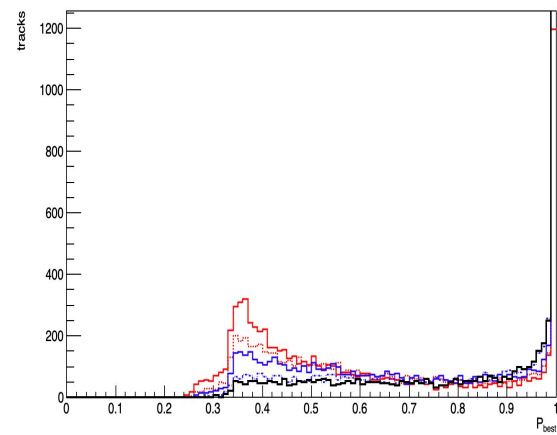
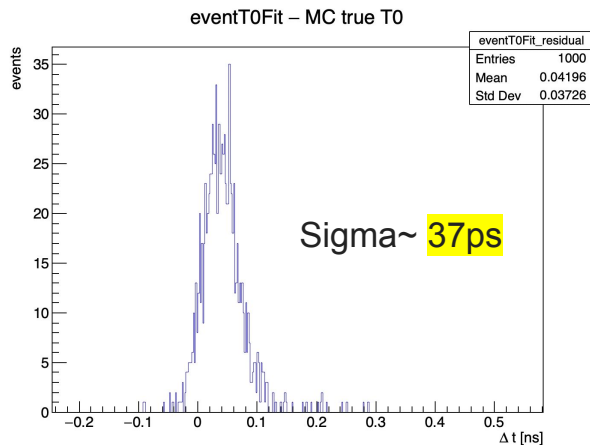
Joint EventT0 and PID determination

- PID Can be marginalized out:
 - Retain all particle hypotheses and estimate the T0 by maximizing the marginal likelihood over the latent PID
 - Preserve the information of the best eventT0
 - Repeat until we have stable PID (this will be improved) and T0(fit once will be fine)
- Allow determination of T0 without knowing PID (more plots in backup)
- Sigma eventT0~ 37ps



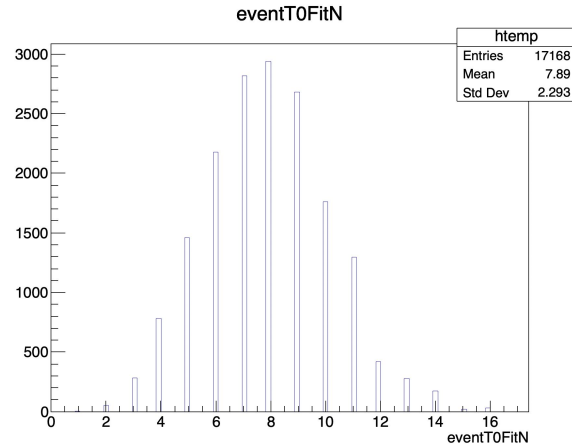
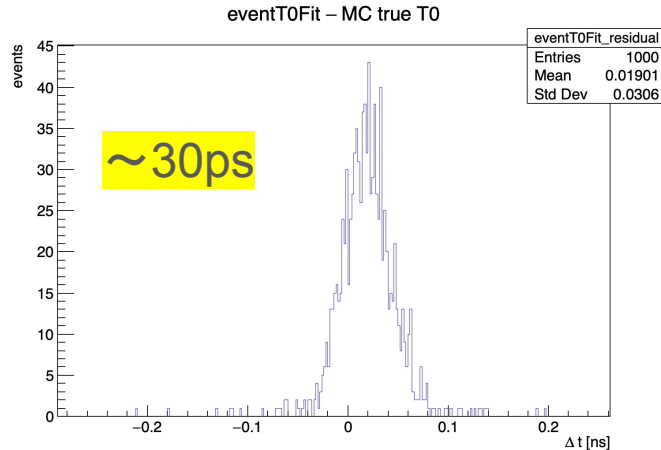
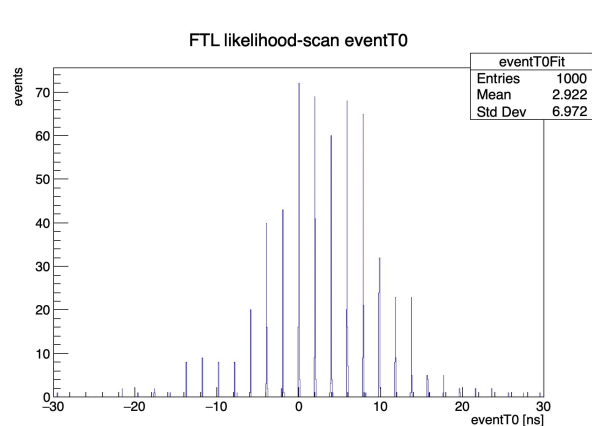
$$L_i(t_0) = \sum_{m=e,\mu,\pi,K} w(m) G(t_i - t_0 - \text{TOF}(m))$$

$$\prod_i L_i(t_0)$$



Joint EvenT0 and PID determination

- Only use higher Pt tracks ($P_t > 0.2$ GeV/c) to determine T0, then update PID for all tracks
- (Or Tracks going through outer detectors with good PID)
- (L1 trigger activated)

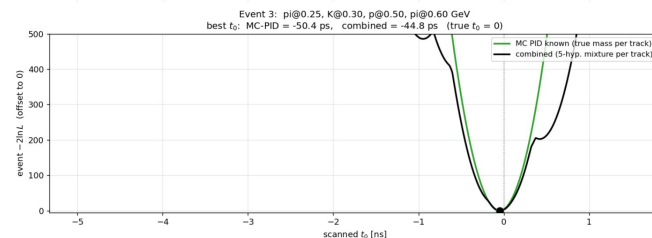
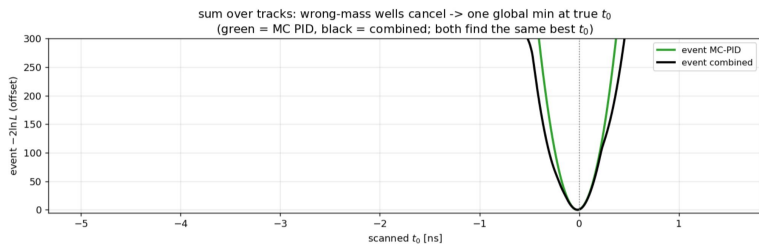
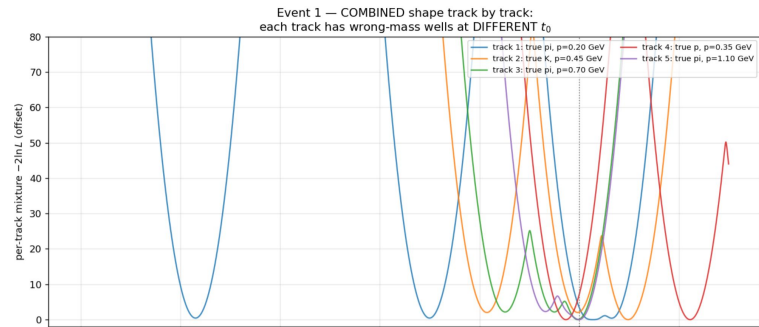
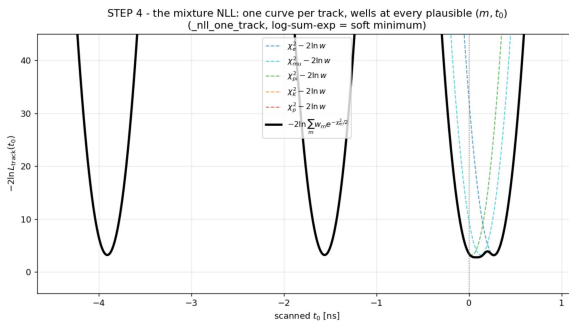
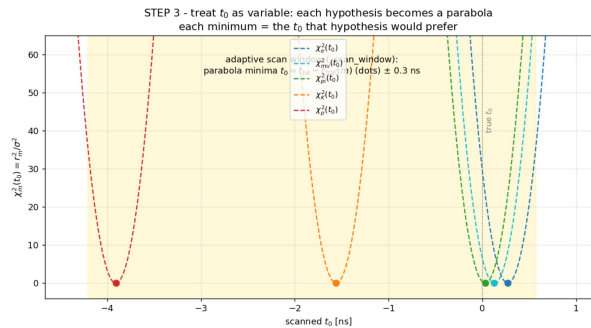


- So far answers: how well can T0 do *given* tracking?
 - ~30 ps

Number of tracks for fitting

Summary

- We explored the potential improvement of EventT0 with the FTL at Belle II:
 - A joint EventT0 and PID determination could provide a EventT0 with uncertainty $\sim 30\text{ps}$
 - Significantly improved compared with current T0 uncertainty ($\sim 1\text{ns}$)
 - FTL could also work with the current L1-trigger, which has a jitter $\sim 10\text{ns}$
- Implementation of FTL-based EventT0 and PID into basf2 is still on-going
- Exploration of the FTL potential for the trigger



The Belle II TRG system

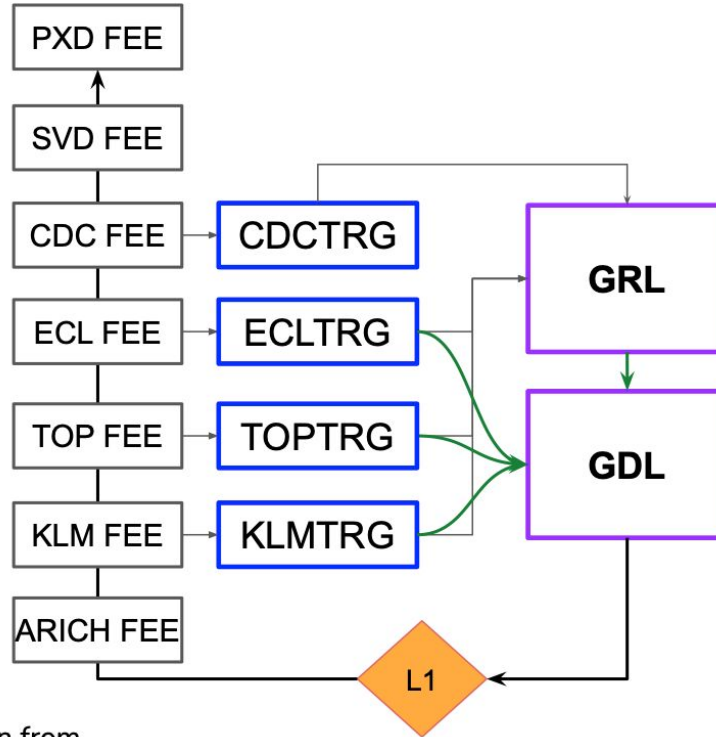
The TRG system is composed of

4 sub-trigger systems:

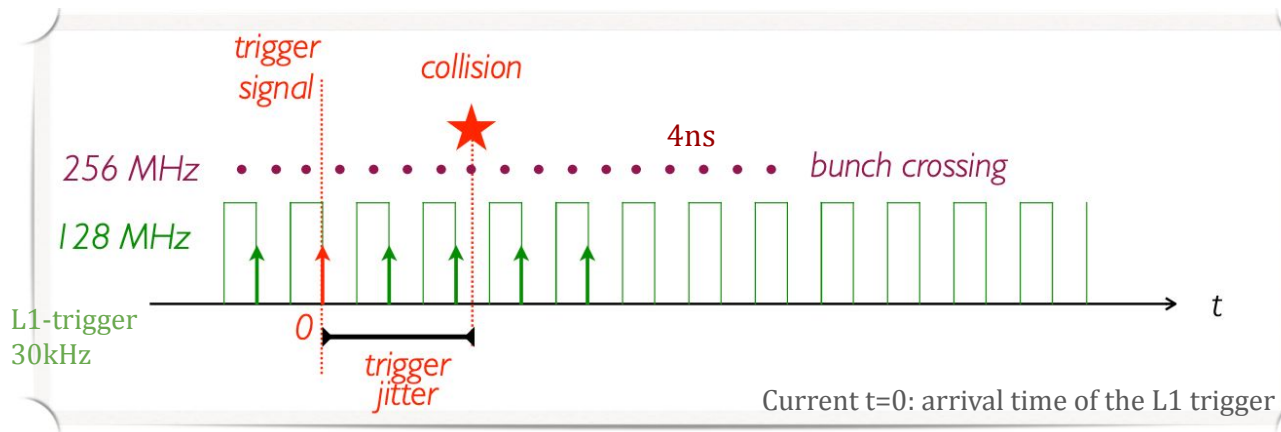
- CDCTRG
 - Charged particle tracks
- ECLTRG
 - Energy deposits and clusters
- KLMTRG
 - Muon-like activity
- TOPTRG
 - Event timing

+ 2 global trigger systems.

- Global Reconstruction Logic
 - Receives data from the 4 subsystems and matches hits among them
- Global Decision Logic:
 - Provides the final L1 decision with information from all subsystems + GRL

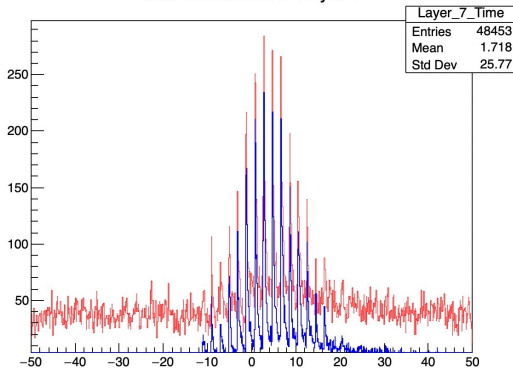


FTL for trigger

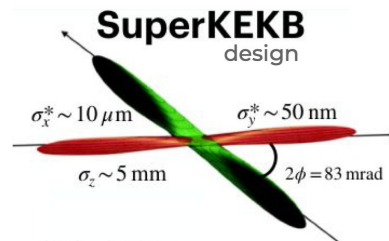
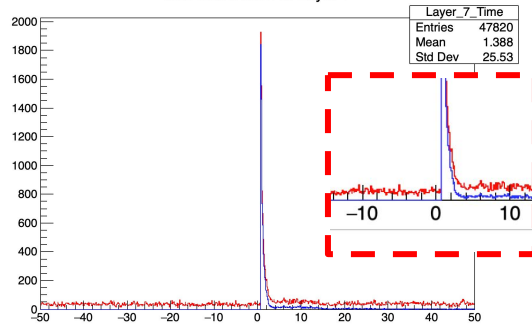


- **RF:** 512 MHz, every 2ns
 - $\sigma_t \sim 25\text{ps}$
- **max(Bunch crossing):** 256 MHz, every 4ns,
 - $\sigma = \sqrt{\sigma_t^2 + \sigma_B^2}$, σ_B is uncertainty of collision within bunch, depending on the beam size ($\sigma_{B2} \sim 12\text{ps}$)
- **L1 trigger:** 128 MHz
 - $\sigma \sim 10\text{ns}$

time distribution of Layer 7



time distribution of Layer 7



T0 resolution vs N_{tracks}
(dashed = theoretical $\sigma_t/\sqrt{N}$ limit)

