# Stochastic hydrodynamics and long time tails of a nonequilibrium fluid

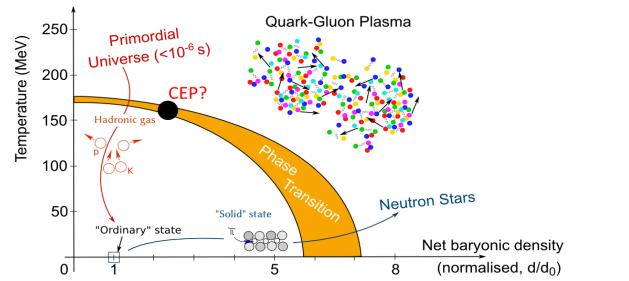
Mauricio Martinez Guerrero Initial Stages 2019 June 24-28, 2019 New York, USA

# Work in collaboration with **T. Schäfer:** PRC 99 (2019) 054902



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### Motivation



- Hydrodynamics has become the 'workhorse' of dynamical modeling of ultra-relativistic heavy-ion collisions
- Multiplicity of particles in HIC  $dN/dy \sim \mathcal{O}(10^{2-4})$

- Large enough for hydrodynamics to be applicable even in farfrom-equilibrium situations

See posters by Martinez et. al., Schlichting et. al.

See talks by Schlichting, Berges, Mazeliauskas, Noronha, Denicol and Heller

- Sufficiently small that one cannot neglect fluctuations Evolution of thermal fluctuations is fundamental for possible signals of QCD critical behavior

# Brownian motion and Einstein relation

The brownian motion of a massive particle

 $\frac{d\vec{p}}{dt} = -\frac{\alpha_D}{\vec{p}} \vec{p} + \vec{s}(t)$ 

Drag coefficient  $\langle s_i(t) s_j(t') \rangle = \kappa \, \delta_{ij} \, \delta(t - t')$ 

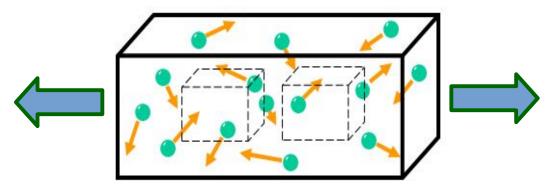
Particle eventually thermalizes  $\langle \mathbf{p}^2 \rangle = 2 \, m \, T$ 

Drag coefficient and noise are **related** via the Einstein relation (**fluctuation-dissipation** theorem)

$$\kappa = k_B T \alpha_D$$

An element missing in hydrodynamical modeling in HIC: The dynamics of hydrodynamic fluctuations

# Challenges with the stochastic hydro approach



In Equilibrium

 Fluctuations of hydro variables are related with thermodynamic properties of the system

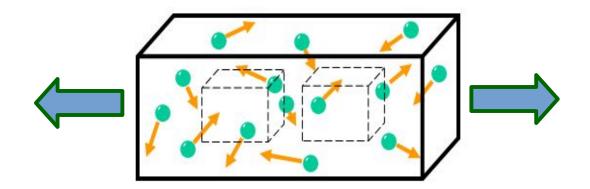
$$\left\langle \frac{\delta p \, \delta p}{c_s^2} \right\rangle \sim T^2 \, c_p$$

Fluctuations of conjugate hydro variables vanish

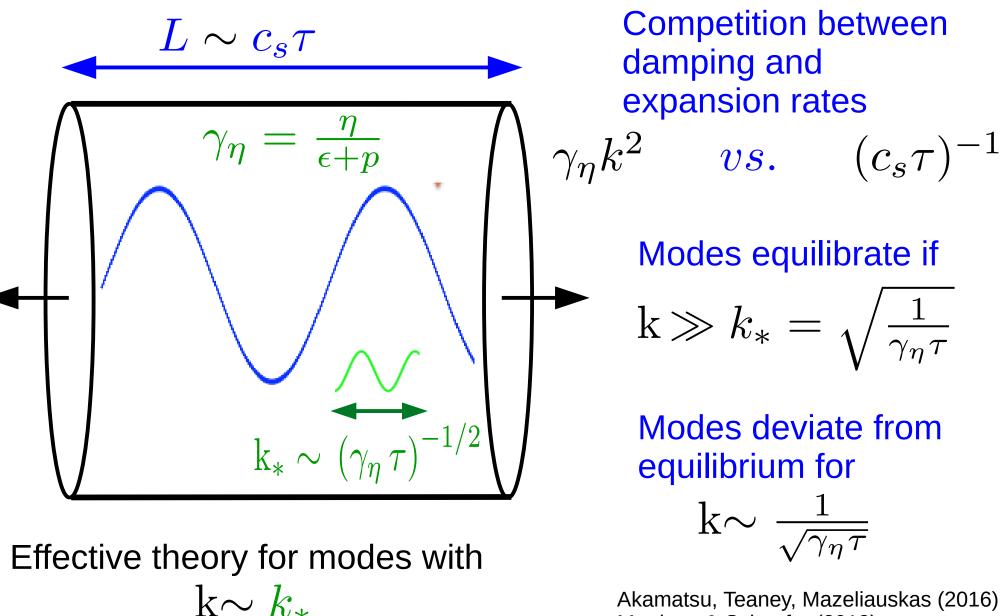
$$\langle \, \delta p \, \delta(s/n) \, \rangle = 0$$
  
 $\langle \, \delta p \, \delta u^i \, \rangle = 0$ 

For rapidly expanding plasmas (out-of-equilibrium) correlations can appear

# Hydrokinetics of a charged expanding fluid



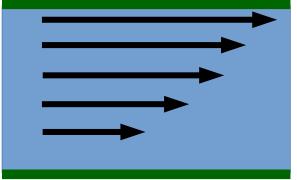
## Hydrokinetics: basic idea



Akamatsu, Teaney, Mazeliauskas (2016) Martinez & Schaefer (2018) X. An, Basar, Stephanov &Yee (2019)

#### **Linearized hydro fluctuations**

$$T^{\mu\nu} = \begin{bmatrix} T^{\mu\nu}_b \\ J^{\mu} \\ J^{\mu} \\ b \end{bmatrix} + \begin{bmatrix} \delta T^{\mu\nu} \\ \delta J^{\mu} \\ \delta J^{\mu} \end{bmatrix} + \begin{bmatrix} S^{\mu\nu} \\ I^{\mu} \\ I^{\mu} \end{bmatrix}$$



Evolving background

$$D_{\mu} T_b^{\mu\nu} = 0$$
$$D_{\mu} J_b^{\mu} = 0$$

White random noise

Fluctuations + noise sources

$$D_{\mu} \left( \delta T^{\mu\nu} (\delta p / v_a, \delta u^i) + S^{\mu\nu} \right) = 0$$
$$D_{\mu} \left( \delta J^{\mu} (\delta q) + I^{\mu} \right) = 0$$

$$S^{\mu\nu} \rangle = 0, \quad \langle I^{\mu} \rangle = 0, \quad \langle S^{\mu\nu} I^{\lambda} \rangle = 0$$
  
$$\langle S^{\mu\nu}(x) S^{\lambda\delta}(x') \rangle = 2T \eta \Delta^{\mu\nu\lambda\delta} \delta^{(4)}(x - x')$$
  
$$\langle I^{\mu}(x) I^{\nu}(x') \rangle = 2T \sigma_0 \Delta^{\mu\nu} \delta^{(4)}(x - x')$$
<sup>7</sup>

# Challenges with the stochastic hydro approach

A naive discretization of the white noise correlators implies

$$\langle SS \rangle \sim \delta(t-t') \,\delta^{(3)} \,(\vec{x}-\vec{x}') \sim (\Delta t \,a^3)^{-1}$$

0/0

Lattice size a limits the spatial extent of hydro fluctuating fields

Maximum UV cutoff  $\Lambda$ 

$$|S| \sim (\Delta t \, a^3)^{-1/2} \sim \frac{\Lambda^{3/2}}{\sqrt{\Delta t}}$$

- Noise terms have a large magnitude & numerically difficult to implement
- Instead of solving equations for hydro fluctuating fields one can alternatively solve equations for the correlations themselves (Andreev 70's)

## Hydrokinetics at finite **µ**

Deterministic equation for 2 point matrix correlator

$$C_{AB} = \frac{1}{2} \langle \{ \phi_A(t, \mathbf{k}), \phi_B^{\dagger}(t, \mathbf{k}) \} \rangle \qquad A = \pm, d, \mathbf{T}_{1,2}$$

$$\partial_0 \mathcal{C} + [\mathcal{A}, \mathcal{C}] + \{\mathcal{D}, \mathcal{C}\} = \mathcal{P}\mathcal{C} + \mathcal{C}\mathcal{P}^{\dagger} + \frac{1}{2}(\mathcal{N} + \mathcal{N}^{\dagger})$$

Evolution + reactive + diffusive = sources + noise correlator

$$C_{AB} = \begin{pmatrix} C_{++} & C_{+-} & C_{+T_1} & C_{+T_2} & C_{+d} \\ C_{-+} & C_{--} & C_{-T_1} & C_{-T_2} & C_{-d} \\ C_{T_1+} & C_{T_1-} & C_{T_1T_1} & C_{T_1T_2} & C_{T_1d} \\ C_{T_2+} & C_{T_2-} & C_{T_2T_1} & C_{T_2T_2} & C_{T_2d} \\ C_{d+} & C_{d-} & C_{dT_1} & C_{dT_2} & C_{dd} \end{pmatrix}$$

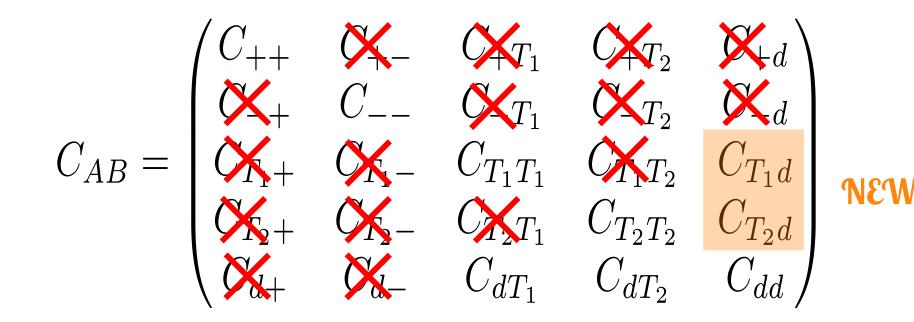
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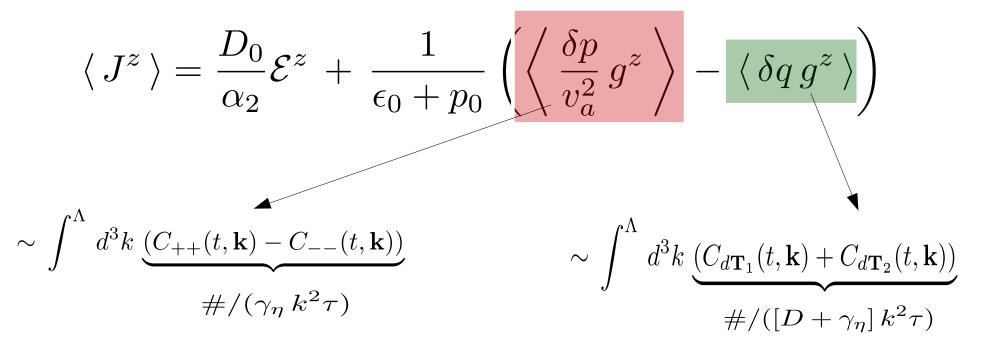
Evolution + reactive + diffusive = sources + noise correlator

Close to equilibrium (asymptotic regime)

$$C_{AA} = C_{eq} \left( 1 + \frac{\#}{D_{AA}k^2\tau} \right)$$
$$C_{d\mathbf{T}_i} = \# \frac{C_{eq}}{(D_0 + \gamma_\eta)k^2\tau}$$

We restrict here to the conformal case.

• The hydrodynamic fluctuating contributions to the longitudinal component of the particle current is



Linearly divergent integrals which are regularized Martinez and Schaefer (2018)

The hydrodynamic fluctuating contributions to the particle current are

$$\frac{\langle J^{z} \rangle}{\mathcal{E}^{z}} = D_{0} + \alpha_{2} \frac{T}{\bar{w}^{2}} \frac{\Lambda}{\pi^{2}} \left( \frac{1}{8\gamma_{\eta_{0}}} + \frac{T c_{p}}{3\bar{H}(D_{0} + \gamma_{\eta_{0}})} \right)$$
$$- \frac{T\tau}{\bar{w}^{2}} \left( \frac{0.04282}{(\gamma_{\eta_{0}}\tau)^{3/2}} + \frac{T c_{p}}{\bar{H}} \frac{0.008}{[(D_{0} + \gamma_{\eta_{0}})\tau]^{3/2}} \right)$$

- Universal low frequency behaviour, i.e. modes with  $k < \Lambda$ .
- Renormalized diffusion coefficient coincides with the static limit (diagrammatic approach)

- Non-universal high frequency behaviour, i.e. modes with  $k > \Lambda$ .
- Long time tails  $\mathcal{O}(\tau^{-3/2})$

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If one run some numbers one finds that the correction associated to hydrodynamic fluctuations is ~10-15% for small and intermediate values of  $\eta/s \sim (1-2)/4\pi$ 

The hydrodynamic fluctuating contributions to the particle current are

$$\langle J^{\tau} \rangle = \bar{n}(\Lambda) + \frac{1}{4\pi^2} \frac{T}{\bar{w}} \Lambda^3 + \frac{T}{\bar{w}} \frac{0.04808}{(\gamma_{\eta}\tau)^{3/2}}$$

Low frequency behaviour, i.e. modes with  $k < \Lambda$ .

• Renormalized particle density is the same as in the static case

Non-universal high frequency behaviour, i.e. modes with  $k > \Lambda$ .

• Long time tails  $O(\tau^{-3/2})$ 

# Conclusions

- We studied the role of hydrodynamic fluctuations on different energy, momentum and density correlation functions
- Hydrokinetics has been generalized for rapidly expanding fluids at finite chemical potential
- The mix of the mix shear-diffusive mode as well as the sound modes modify the tails of the particle current
- We determine the universal short length behaviour of the hydrodynamic fluctuations which renormalize the particle density and diffussion coefficient.

# Outlook

- Non-conformal fluid at finite chemical potential Martinez and Schaefer 19xx.xxxx
- Enhancement of bulk viscosity for QCD EOS with critical behavior Martinez, Schaefer & Skokov 19xx.xxxx

# **Backup slides**

# Hydrokinetics at finite $\mu$

$$\delta\phi_a = \left(\delta p/c_s, g_i, \delta q\right) \longrightarrow \delta\left(\frac{s}{n}\right)$$

Navier-Stokes-Langevin equations

$$\frac{d}{dt}\delta\phi_a + kA_{ab}\delta\phi_b + k^2 D_{ab}\delta\phi_b = P_{ab}\delta\phi_b + \xi_a$$

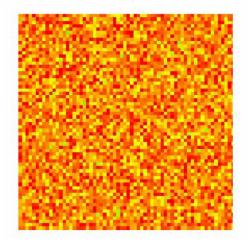
The acoustic matrix A has 5 hydro modes + 5 eigenvalues

Hydrodynamic eigenmode	Eigenvector	Eigenvalue
Sound modes $\phi_{\pm}$	$\frac{1}{\sqrt{2}}\left(1,\pm\hat{\mathbf{k}},0\right)$	$\pm i v_a$
Diffusive mode $\phi_d$	(0, <b>0</b> , 1)	0
Shear modes $\phi_{\mathbf{T}_i}$ $i = 1, 2$	$(0, \hat{e}_{\mathbf{T}_i}, 0)$	0

# **Beyond gradient hydro expansion**

Hydrodynamical variables fluctuate (Landau & Lifshitz, 1957)

$$\langle \delta v_i(t, \vec{x}) \, v_j(t, \vec{x'}) \, \rangle = \frac{T}{\rho} \, \delta^{(3)}(\vec{x} - \vec{x'})$$



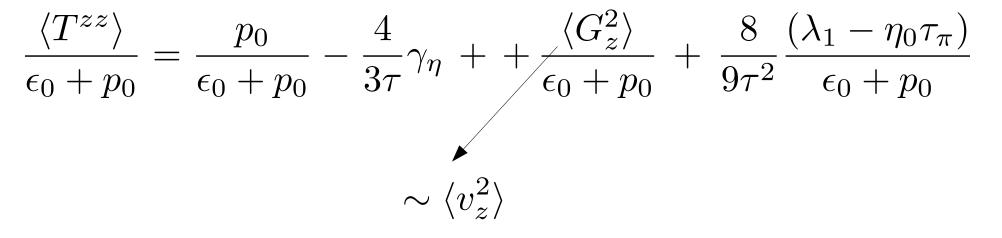
Linearized hydrodynamics propagates fluctuations of different modes, e.g., shear and sound modes

$$\begin{split} \langle \delta v_i^T \delta v_j^T \rangle_{\omega,k} &= \frac{2T}{\rho} (\delta_{ij} - \hat{k}_i \hat{k}_j) \frac{\nu k^2}{\omega^2 + (\nu k^2)^2} \qquad shear \\ \langle \delta v_i^L \delta v_j^L \rangle_{\omega,k} &= \frac{2T}{\rho} \hat{k}_i \hat{k}_j \frac{\omega k^2 \Gamma}{(\omega^2 - c_s^2 k^2)^2 + (\omega k^2 \Gamma)^2} \qquad sound \end{split}$$

$$v = v_T + v_L$$
:  $\nabla \cdot v_T = 0, \nabla \times v_L = 0$   $\nu = \eta/\rho, \quad \Gamma = \frac{4}{3}\nu + \dots$ 

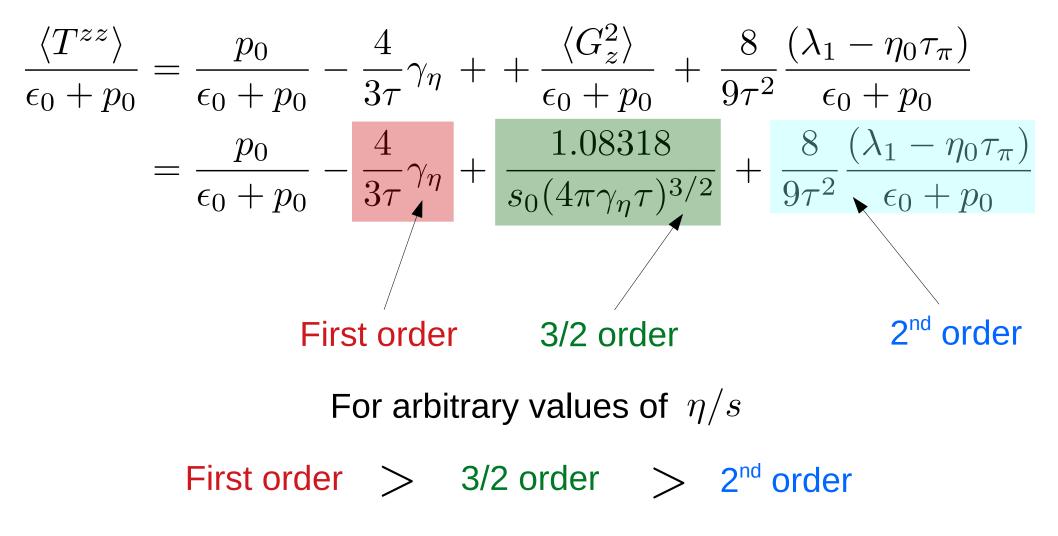
# **Hydrokinetics**

**Akamatsu et. al. (2016) :** non-equilibrium noise contributions to the energy-momentum tensor of a fluid undergoing Bjorken flow



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**Akamatsu et. al. (2016) :** non-equilibrium noise contributions to the energy-momentum tensor of a fluid undergoing Bjorken flow



# Hydrokinetics at finite μ: Bjorken flow

• For the Bjorken case the equations of motion of the equal time symmetric correlators are

$$\partial_{0}\mathcal{C} + [\mathcal{A}, \mathcal{C}] + \{\mathcal{D}, \mathcal{C}\} = \mathcal{P}\mathcal{C} + \mathcal{C}\mathcal{P}^{\dagger} + \frac{1}{2}\left(\mathcal{N} + \mathcal{N}^{\dagger}\right)$$

$$\partial_{\tau}\tilde{\mathcal{C}}_{\pm\pm} + \frac{4}{3}\gamma_{\eta_{0}}\mathbf{K}^{2}\tilde{\mathcal{C}}_{\pm\pm} = \tilde{\mathcal{N}}_{\pm\pm} - \frac{\left(2 + v_{a}^{2} + \cos^{2}\theta_{K}\right)}{\tau}\tilde{\mathcal{C}}_{\pm\pm} \mp \frac{\hat{\mathbf{K}}\cdot\mathcal{E}}{\bar{w}}\frac{\left(1 + v_{a}^{2}\right)}{v_{a}}\tilde{\mathcal{C}}_{\pm\pm},$$

$$\partial_{\tau}\tilde{\mathcal{C}}_{T_{1}T_{1}} + 2\gamma_{\eta_{0}}\mathbf{K}^{2}\tilde{\mathcal{C}}_{T_{1}T_{1}} = \tilde{\mathcal{N}}_{T_{1}T_{1}} - \frac{2}{\tau}\tilde{\mathcal{C}}_{T_{1}T_{1}},$$

$$\partial_{\tau}\tilde{\mathcal{C}}_{T_{2}T_{2}} + 2\gamma_{\eta_{0}}\mathbf{K}^{2}\tilde{\mathcal{C}}_{T_{2}T_{2}} = \tilde{\mathcal{N}}_{T_{2}T_{2}} - \frac{2\left(1 + \sin^{2}\theta_{K}\right)}{\tau}\tilde{\mathcal{C}}_{T_{2}T_{2}},$$

$$\partial_{\tau}\tilde{\mathcal{C}}_{dd} + 2D\mathbf{K}^{2}\tilde{\mathcal{C}}_{dd} = \tilde{\mathcal{N}}_{dd} - \frac{2}{\tau}\tilde{\mathcal{C}}_{dd},$$

$$\partial_{\tau}\tilde{\mathcal{C}}_{dT_{1}} + (\gamma_{\eta_{0}} + D)\mathbf{K}^{2}\tilde{\mathcal{C}}_{dT_{1}} = -\frac{2}{\tau}\tilde{\mathcal{C}}_{dT_{1}} + \frac{1}{\bar{w}}\hat{e}_{T_{1}}\cdot\mathcal{E}\left(\tilde{\mathcal{C}}_{dd} - v_{a}\tilde{\mathcal{C}}_{T_{1}T_{1}}\right),$$

$$\partial_{\tau}\tilde{\mathcal{C}}_{dT_{2}} + (\gamma_{\eta_{0}} + D)\mathbf{K}^{2}\tilde{\mathcal{C}}_{dT_{2}} = -\frac{2 + \sin^{2}\theta_{K}}{\tau}\tilde{\mathcal{C}}_{dT_{2}} + \frac{1}{\bar{w}}\hat{e}_{T_{2}}\cdot\mathcal{E}\left(\tilde{\mathcal{C}}_{dd} - v_{a}\tilde{\mathcal{C}}_{T_{1}T_{2}}\right)$$