Central Detector Integration software suite (aka EIC Toy Model)

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An attempt to connect some of the dots

Escalate & fun4all; migration process

Tracker, PID & Calorimetry detectors in GEANT

1-st & 2-d IR

EIC detector & greenfield solenoid design

Physics simulations & engineering design

Ideal detectors & services / support

|η|<4.5 & reality

Space available for detectors & IR vacuum chamber

- One can easily identify a number of places with a lack of sync at this early stage
- Some of them can seemingly be addressed in a more or less consistent way

EIC Toy Model: overview

- A tool to model & generate EIC Central Detector "templates" in a way:
 - the new geometries (models) can be generated "quickly" ...
 - ... and represented instantly in a WYSIWYG fashion
 - the sub-detector "container objects" are guaranteed to not overlap either with each other or with the IR vacuum chamber elements
 - technically they can be imported in GEANT frameworks in a consistent way and used as wrappers to the "real" sub-detectors
 - they can be exported in a CAD format to be used in the engineering design of the detector support structures and / or laying out services
- Repository: https://github.com/eic/EicToyModel
 - a README file
 - example ROOT scripts
 - a standalone GEANT example
 - detailed API description
 - Currently neither g4e nor fun4all examples available

Suggested workflow

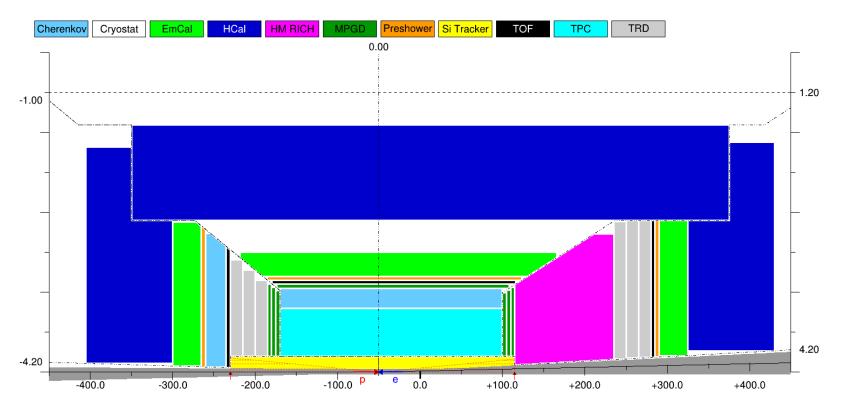
Create a model



Save it as a .root file

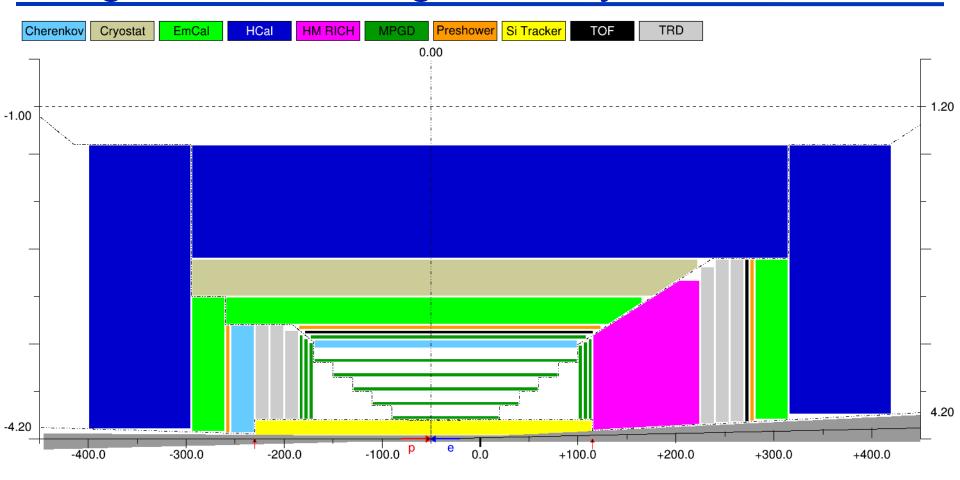


Import in GEANT



- Minimal overhead to create a 2D scheme like this (ROOT scripting)
- Model can be saved, distributed and re-imported as a .root file
- GEANT application: import .root file and create volumes on the fly
 - Alternatively: export and import GDML file(s) (not yet implemented)

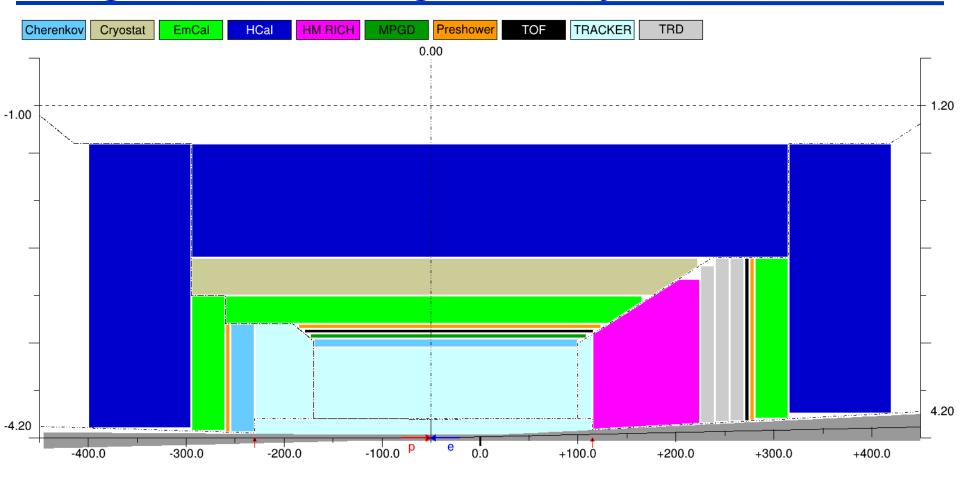
Integration volume granularity: tracker



Detector grouping is certainly possible

- Is it flexible enough?
- As shown here: too detailed at this early stage?
- https://github.com/eic/EicToyModel/blob/master/scripts/tracking.C

Integration volume granularity: tracker



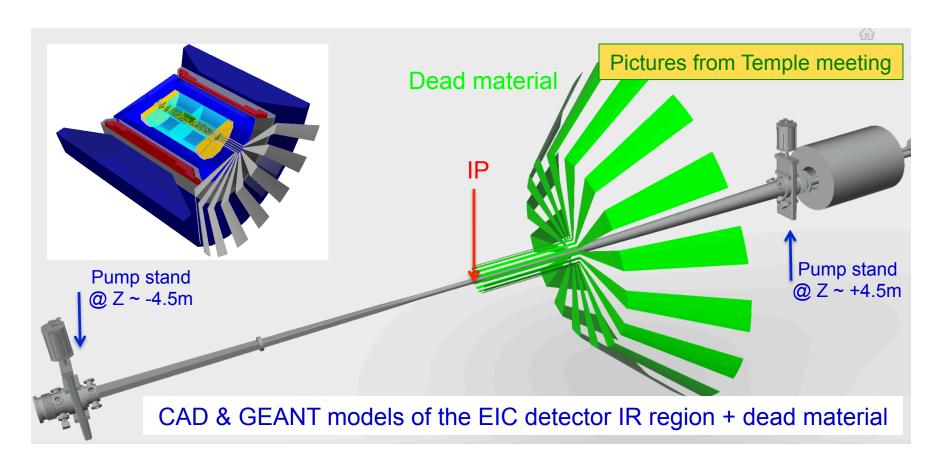
Detector grouping is certainly possible

- Is it flexible enough?
- Allocate larger volumes for PID / Tracking / Calorimetry, to start with?
- https://github.com/eic/EicToyModel/blob/master/scripts/tracking.C

Limitations in the geometry description

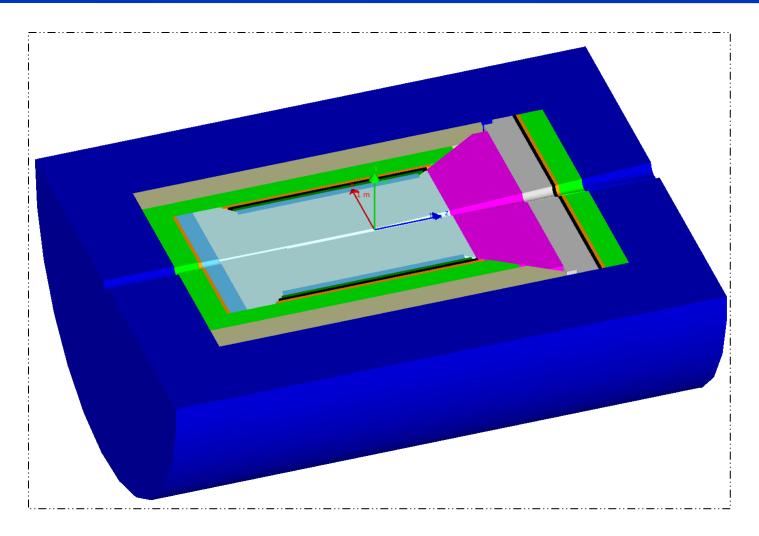
- Four pre-defined detector "stacks": vertex, barrel, and two endcaps ...
- ... in a projective configuration (defined by the η ranges)
- Detector volumes in the endcap stacks are placed as strictly aligned objects with flat front and rear sides, one after the other
 - ... although stack boundaries can be shaped up creatively, if needed
- Detector tags (like "EmCal") and respective colors are hardcoded ...
 - ... though custom ones can be generated dynamically, if really needed
- Exported objects are azimuthally symmetric Polycones, although ...
 - ... with an asymmetric cutaway representing the IR vacuum chamber
- Polyhedra export implemented, but can not be mixed with Polycones
- CAD export: presently Polycones only; no vacuum chamber cutaway

Services



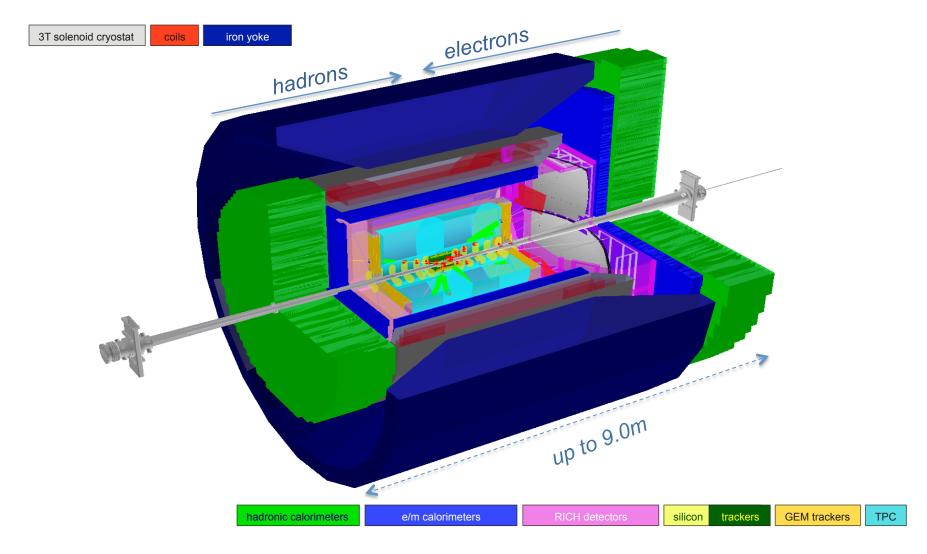
- Barrel-to-endcap cracks (support, services):
 - Obviously affect the available space for the detectors
 - Should be configurable, accumulating services from / to "inner" detectors
 - No progress since Temple; almost the first item on the TODO list

GEANT interface (Qt event display)



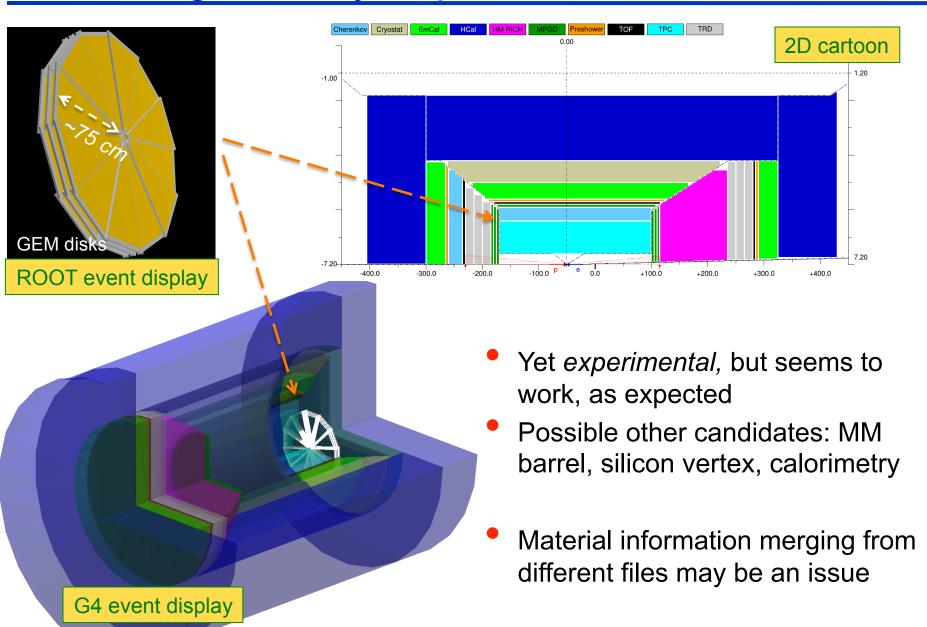
- Volumes are currently generated on the fly (is GDML step really needed?)
- Once imported, the layout will look the same in all G4 applications

Compare: BeAST EicRoot implementation



- Comment#1: some of the volumes here (PID) are also air balloons
- Comment#2: one can seemingly reuse TGeo objects in the new scheme

EicRoot geometry import



Coding overhead in GEANT

Excerpt from a modified working calorimetry code:

```
// Construct the integration volumes geometry, internally;
TFile fin(argv[1]);
dynamic_cast<EicToyModel *>(fin.Get("EicToyModel"));
eic->Construct();
// Populate G4 world by these volumes;
eic->PlaceG4Volumes(expHall_phys);
```

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This part should be taken care of by the framework

```
// Place "MyHCal" tower matrix into the integration volume bubble instead of the world;

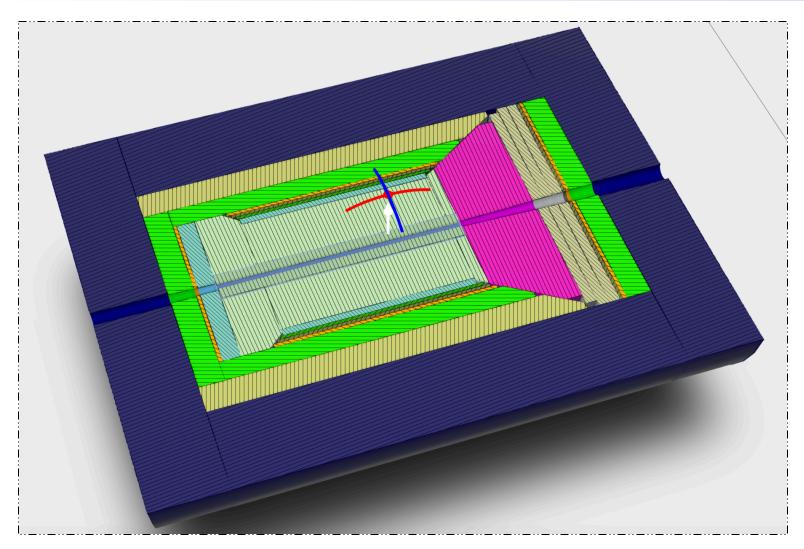
new-G4PVPlacement(0, G4ThreeVector(0, 0, z0ffset),-myhcal_log,-"MyHCal",-expHall_log,---false, 0);

auto hcal_bubble_log = eic->fwd()->get("HCal")->GetG4Volume()->GetLogicalVolume();

new-G4PVPlacement(0, G4ThreeVector(0, 0, 0), myhcal_log, "MyHCal", hcal_bubble_log, false, 0);
```

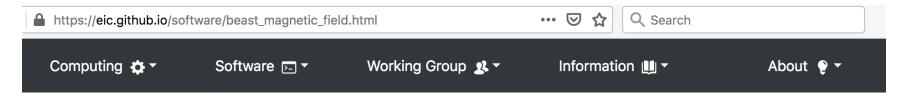
- Immediate migration is not mandatory for everybody
 - Integration bubbles can be imported into a framework one by one
- Bubble size (and location) can be polled (not yet; coming soon)
 - Parametric detectors can be implemented in a proper way
- If the community prefers to use GDML files instead, so be it (consistency?)

CAD interface (3D model in Autodesk viewer)



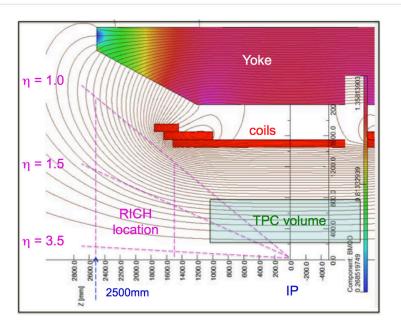
- Obviously looks identical to the GEANT picture
 - Services and support structure engineering design can start off the same configuration as used in GEANT

Magnetic field map interface



BeAST solenoid magnetic field map

The repository contains an ASCII file with the field map, a C++ class to handle it and a GDML model https://github.com/eic/BeastMagneticField



Open solenoid design (no field clamps)

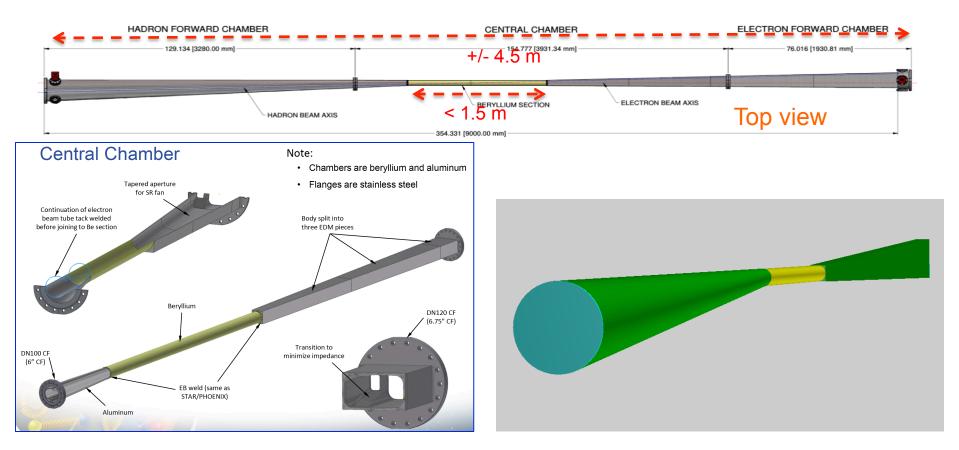
Homogeneous (less than than 4% variation) 3T central field in the TPC volume

Fringe field is tuned in order and minimize charge particle bending in the forward gaseous RICH volume (less than 1mrad RMS for 10 GeV/c particles up to 25 degree polar angles)

Field map originally produced by a collection of Open Source tools (Elmer, Netgen, ROOT)

- Currently only BeAST field map import implemented
- Interface is forward compatible with the greenfield solenoid maps (?)

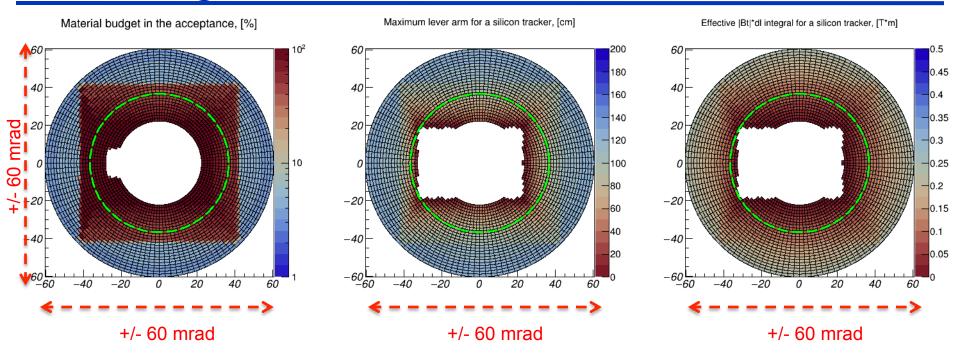
IR vacuum chamber description



CAD drawing and ROOT TGeo implementation

- Coded in TGeo, exportable as GDML
- Kind of parametric (suitable for the 2-d IR description)
- Only the essential part (the outer shell in particular) is implemented

B*dl integral and material scan evaluation



- Material budget: direct use of the vacuum chamber TGeo implementation
- Estimate of the maximum lever arm available for the silicon tracker:
 - Account for the vacuum chamber shape: consider a 3D point where a particle with a given $\{\theta,\phi\}$ would exit the vacuum chamber (starting point) ...
 - ... and account for the configurable markers, indicating at which max distance from the IP the last silicon tracker station can be installed (end point)
- B_T*dl integral estimate: same idea + BeastMagneticField interface
- Primary vertex smearing implemented (this part is trivial of course)

Documentation

