



# sPHENIX INTT

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Rachid Nouicer (BNL)



# The arrival of chips

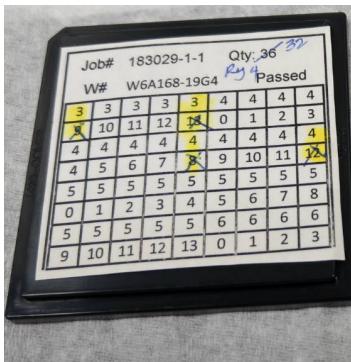


2020/05/11

Good : 1534 pcs

Bad : 135 pcs

All the chips are in NTU





# Previous sensor assembly testing

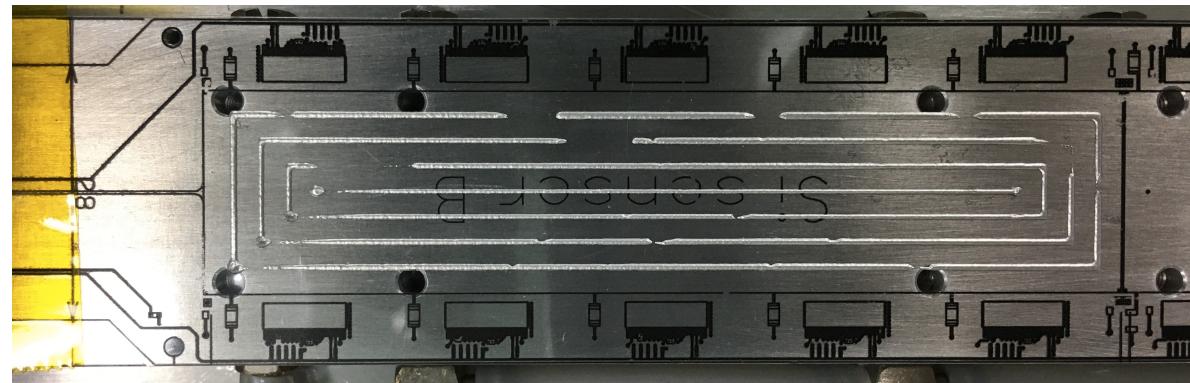
\*2020/5/5

SPHENIX

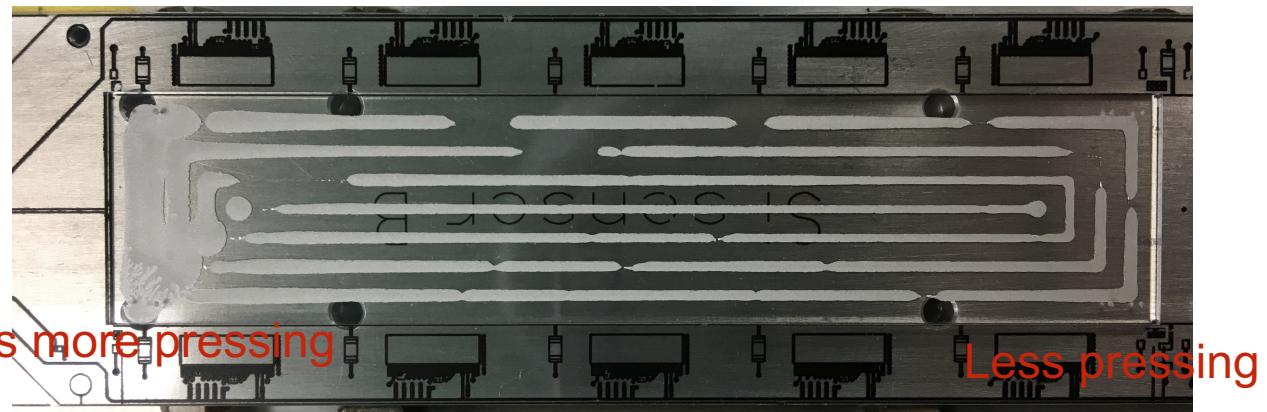
Test area : type B (acrylic sensor (1.5mm) and HDI film were used)

Test Chips : 3 (chips from first test were used)

The glue pattern of type B area



Acrylic dummy sensor assembly

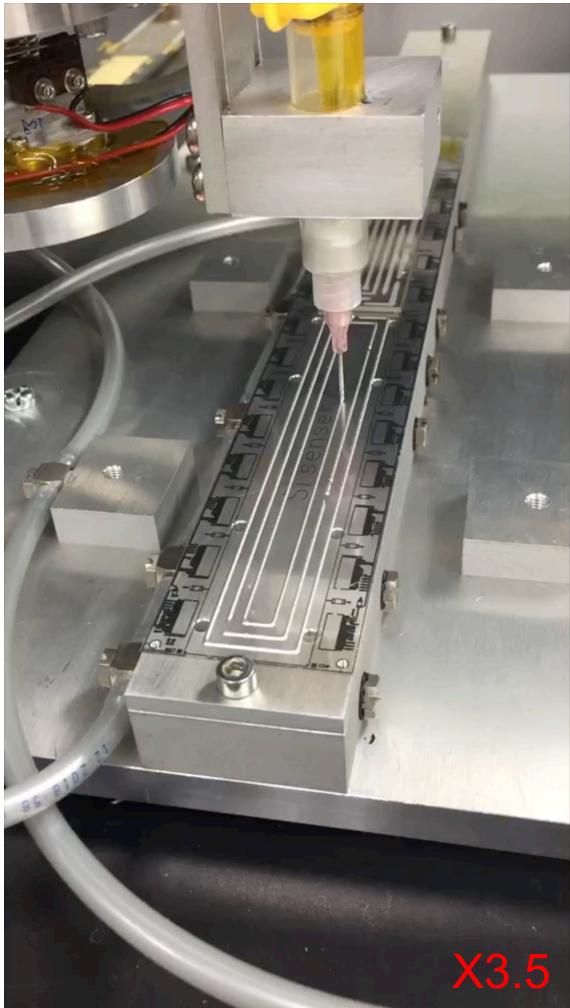




# Video : deposit glue, sensor pick and place



Glue deposit



Sensor pick and place



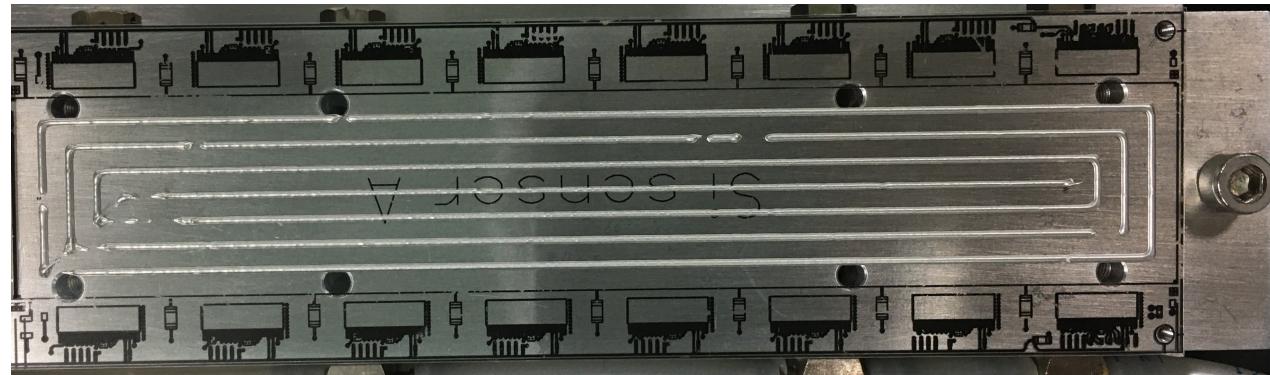


# Type A sensor assembly testing

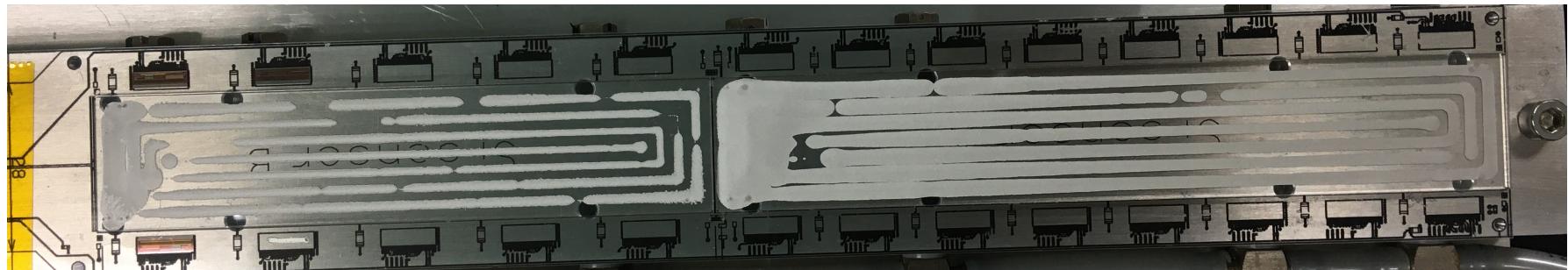


Test area : type A (acrylic sensor (1.5mm) and HDI film were used)

The glue pattern of type A area



After the assembly of acrylic sensor

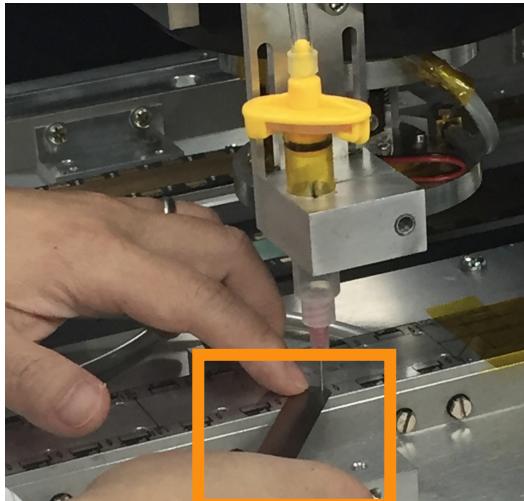




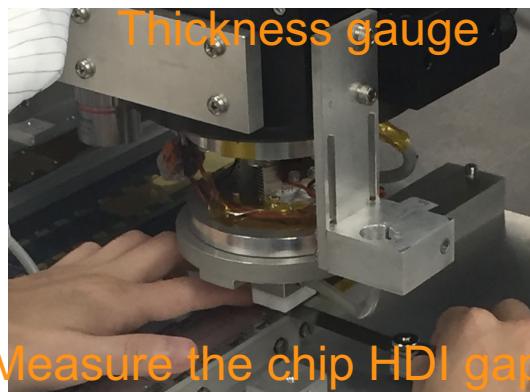
# The chip assembly test



Use the thickness gauge, the gap : 140 um  
Waiting cure time : 20 min



Thickness gauge



Measure the chip HDI gap



There is no leakage

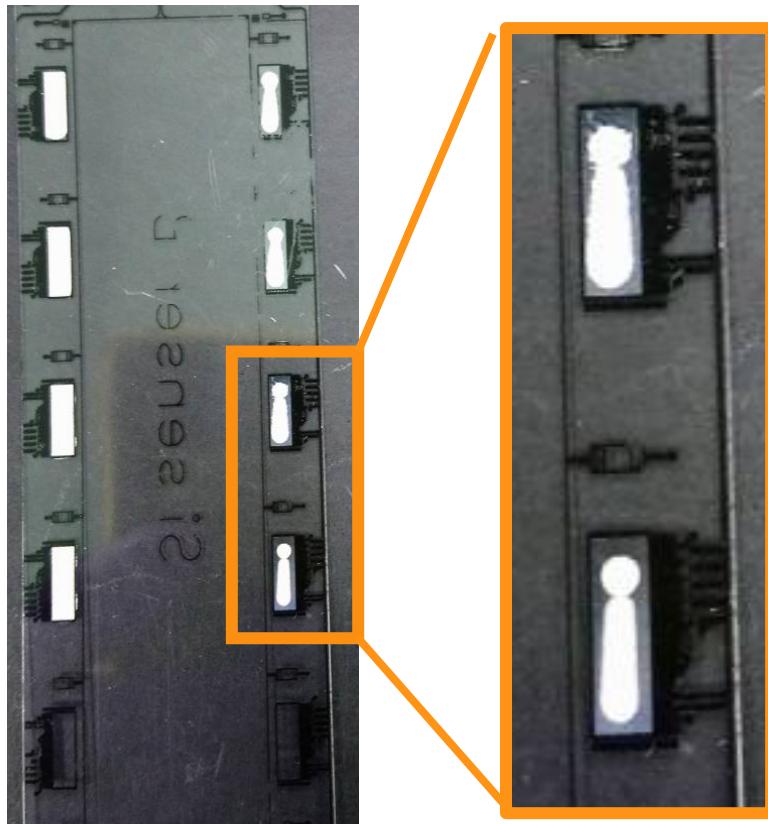




# Properties measurements of chip + glue



The back side of the HDI film



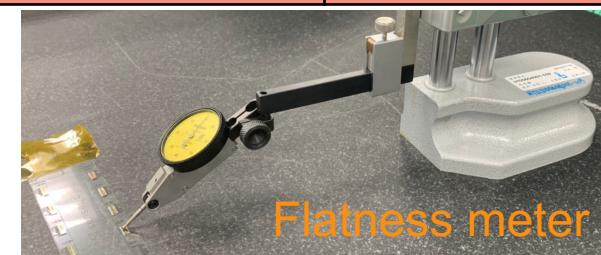
No glue spread

Measured by OGP

Chip number	Rotate angle
U14	$0.0823^0$
U15	$0.0313^0$
U16	$0.0094^0$
U17	$0.025^0$

Measured by flatness meter

Chip number	Glue layer
U14	$30 \mu m$
U15	$50 \mu m$
U16	$40 \mu m$
U17	$55 \mu m$



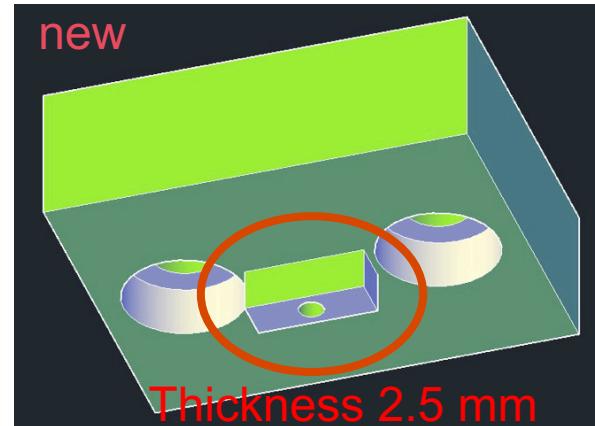
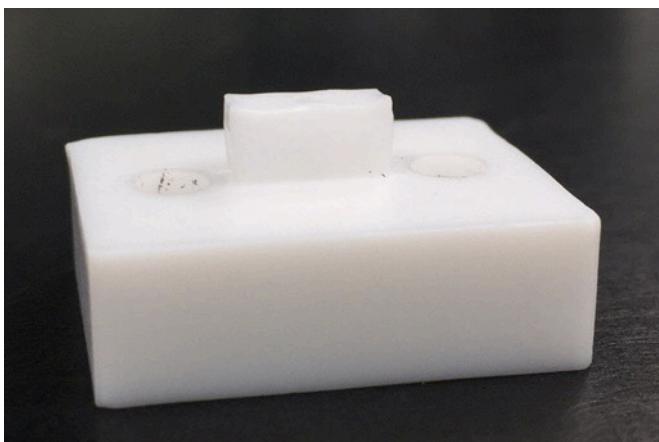
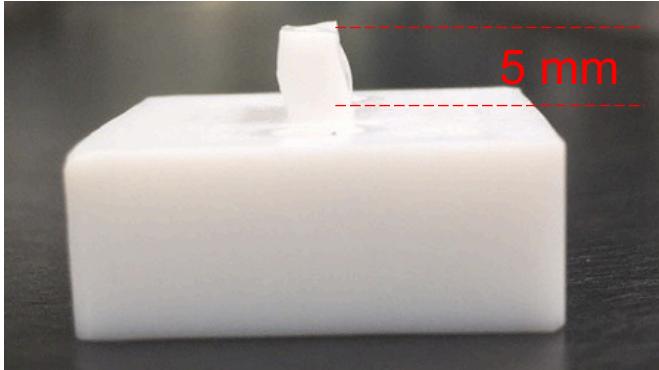
Flatness meter



# The problem of the chip pick up head - teflon

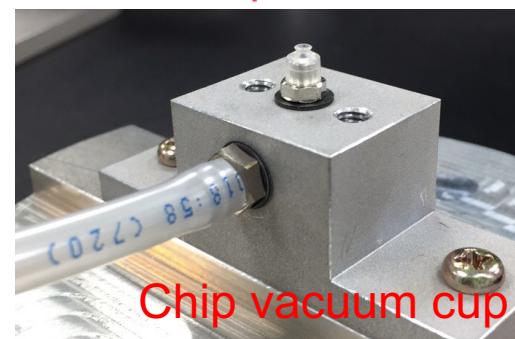


The durability of Teflon is not good....



Decrease the thickness of the attached pad

Current plan : use the vacuum cup, 4 new teflon heads are in production.





# Fourth assembly test



Test area : type A (acrylic sensor (1.5mm) and HDI film were used)

Test Chips : 4 (new chips)

Sensor assembly :

Needle height : 190  $\mu\text{m}$

Sensor – HDI gap : 60  $\mu\text{m}$

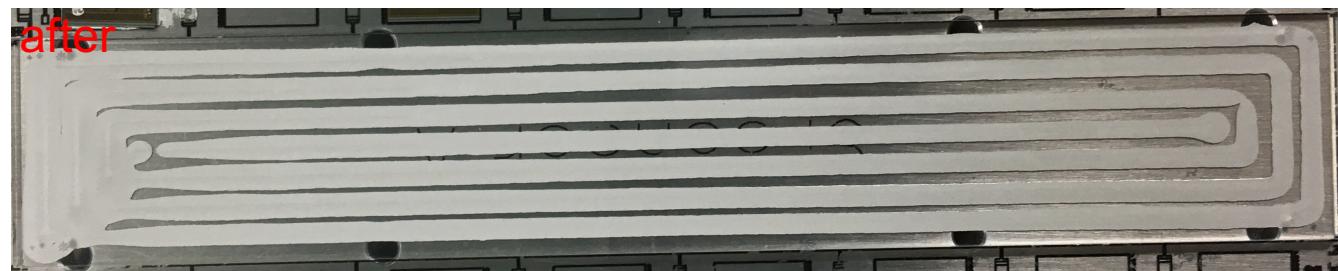
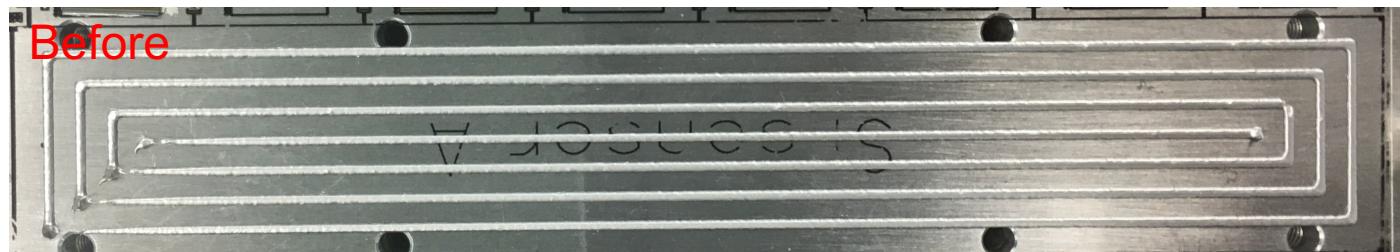
Chips assembly :

Needle height : 140  $\mu\text{m}$

Chips - HDI gap : 70  $\mu\text{m}$

Sensor A position	Height (mm)
Up point	1.55
midpoint	1.53
Down point	1.53

Thickness of acrylic sensor 1.40 ~ 1.49 mm





# Fourth assembly test



Test area : type A (acrylic sensor (1.5mm) and HDI film were used)

Test Chips : 4 (new chips)

Sensor assembly :

Needle height : 190  $\mu\text{m}$

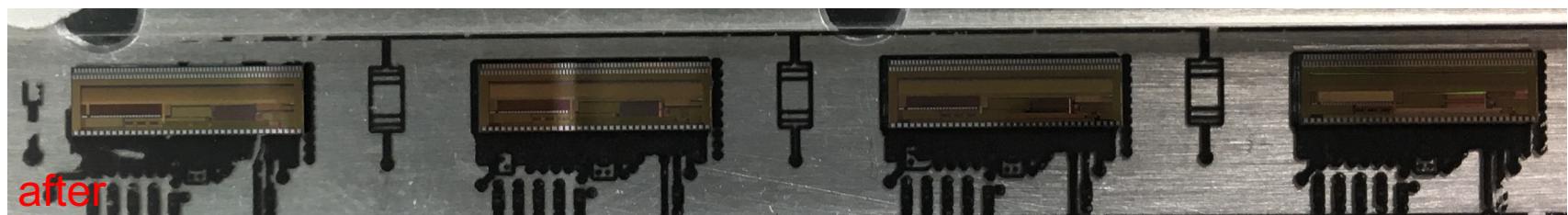
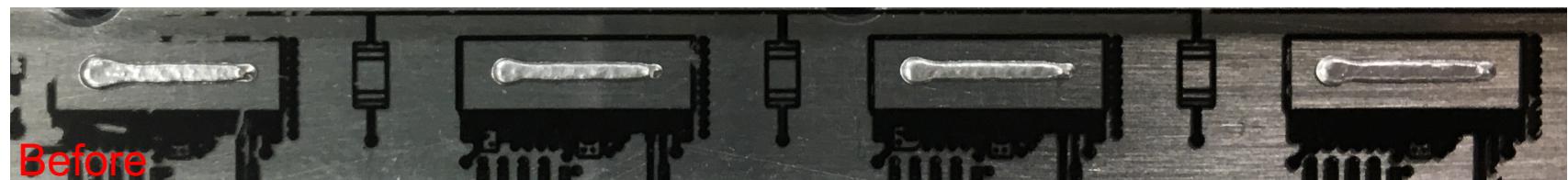
Sensor – HDI gap : 60  $\mu\text{m}$

Chips assembly :

Needle height : 140  $\mu\text{m}$

Chips - HDI gap : 60  $\mu\text{m}$

Chip number	Glue layer
U19	35 $\mu\text{m}$
U20	25 $\mu\text{m}$
U21	25 $\mu\text{m}$
U22	35 $\mu\text{m}$





# Assembly test with rejected HDI



Test area : type A (dummy sensor (320 $\mu$ m), rejected HDI were used)

Test Chips : 6 (new chips)

Sensor assembly :

Needle height : 190  $\mu$ m

Sensor – HDI gap : 60  $\mu$ m

Chips assembly :

Needle height : 140  $\mu$ m

Chips - HDI gap : 60  $\mu$ m



To do list : assemble dummy sensor type B, measure the placing error by OGP



# Assembly test with rejected HDI



Test area : type A (dummy sensor (320 $\mu$ m), rejected HDI were used)

Test Chips : 6 (new chips)

Sensor assembly :

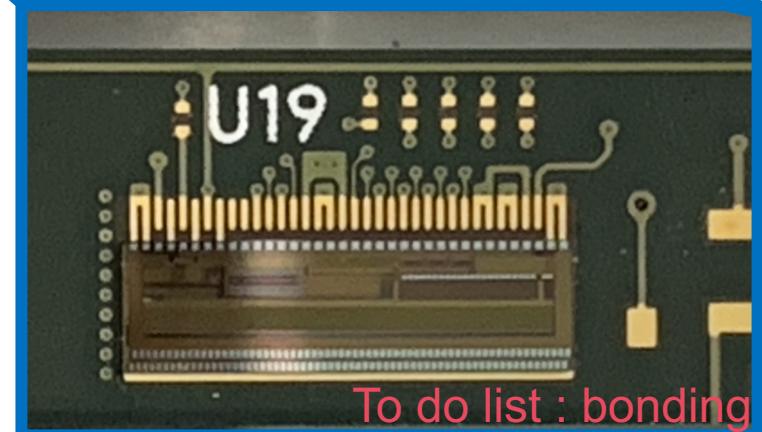
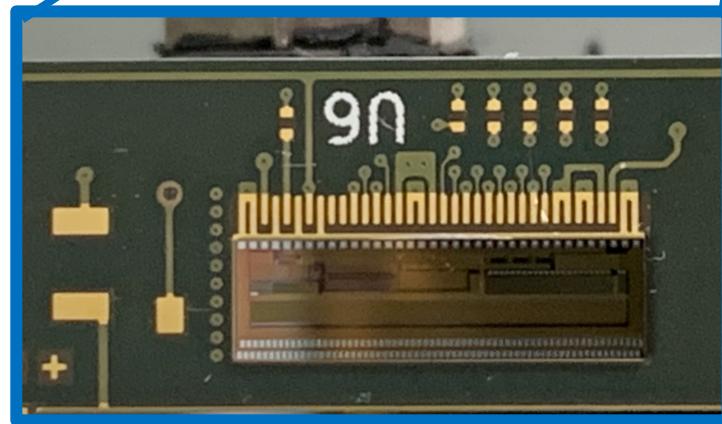
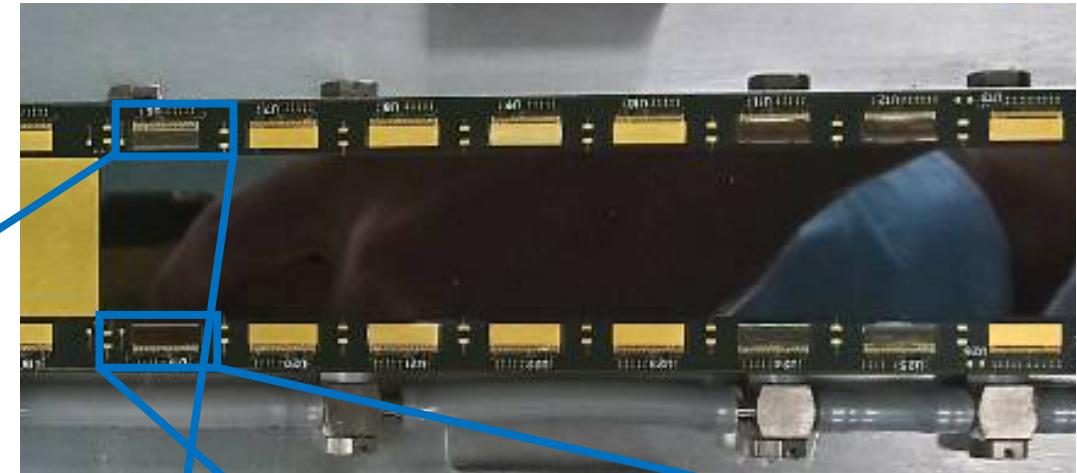
Needle height : 190  $\mu$ m

Sensor – HDI gap : 60  $\mu$ m

Chips assembly :

Needle height : 140  $\mu$ m

Chips - HDI gap : 60  $\mu$ m





# To do list



- ~~Test the glue applying parameters with the acrylic sensors.~~

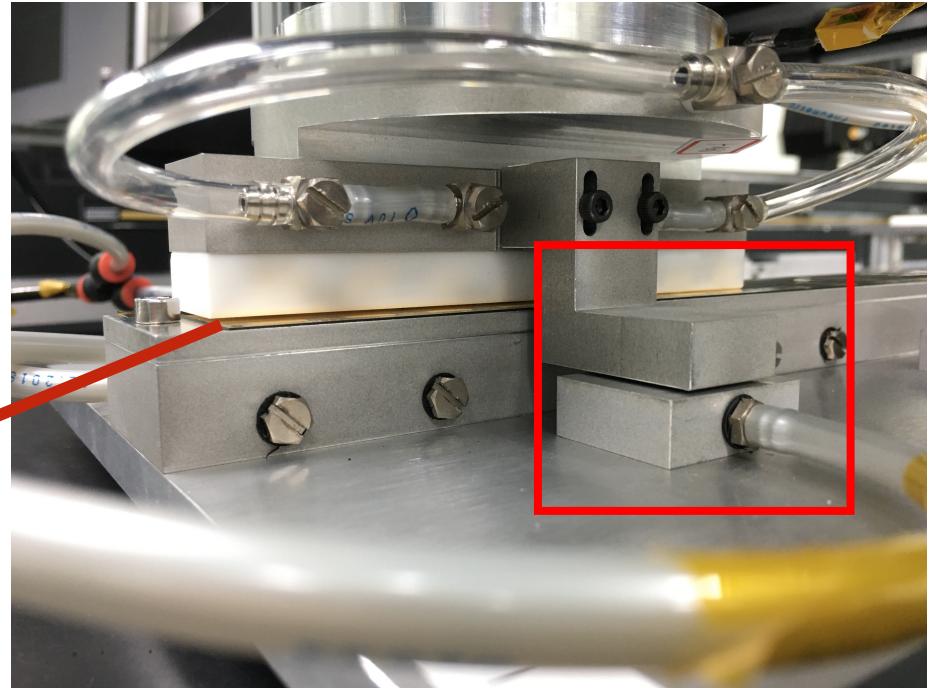
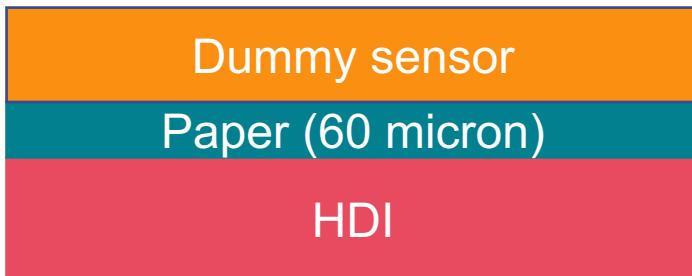
~~Assemble real chips again after making sure the proper glue applying parameters.~~

- ~~Assemble the dummy sensor and check the position error by using OGP~~
- Produce two real modules before 5/29

# Back up



# Maintain the sensor – HDI gap



Legs were used for alignment