

# EIC Crossing Angle: Crab Cavities and FF Detectors

Alex Jentsch

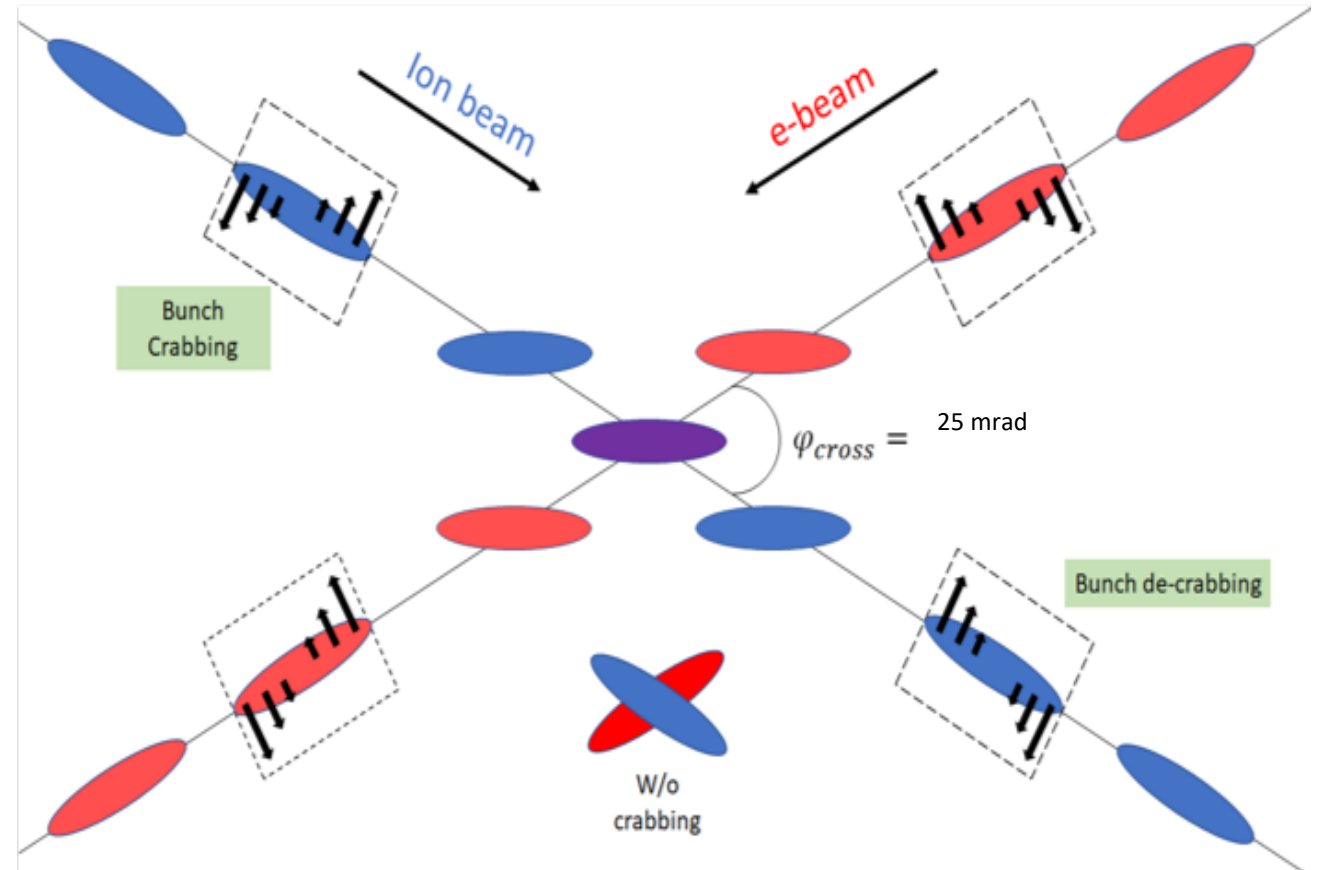
Yellow Report DWG+PWG Joint Meeting

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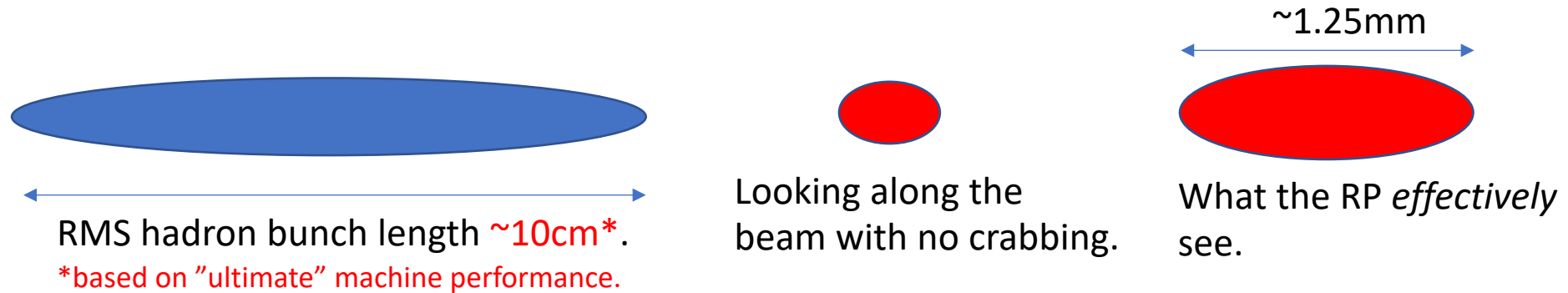
# What do crab cavities do?

- **Crab cavity rotation**

- Can perform rotations of the beam bunches in 2D.
- Used to account for the luminosity drop due to the crossing angle – allows for head-on collisions to still take place.
- The rotation induces effective vertex smearing.



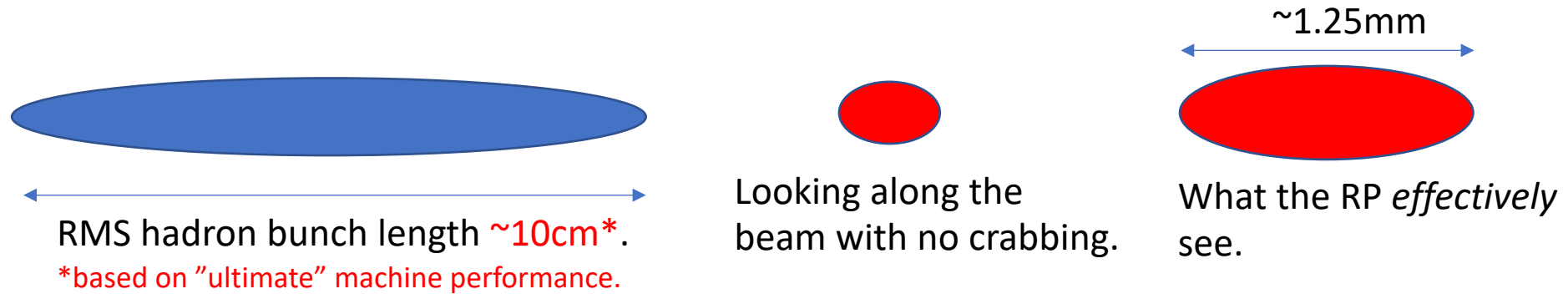
# Crab Cavity Induced Vertex Smearing (25 mrad)



- Because of the rotation, the **Roman Pots+other FF detectors effectively** see the bunch crossing **smearing in x**.
- **Vertex smearing = 12.5mrad (half the crossing angle) \* 10cm = 1.25 mm**
- If the effective vertex smearing was **for a 1cm bunch**, we would have **0.125mm** vertex smearing.

- For a 25mrad crossing angle – the crab smearing is the second largest smearing effect (behind angular divergence).
- The contribution is about half as large compared to angular divergence at top energy.

# Crab Cavity Induced Vertex Smearing (25 mrad)

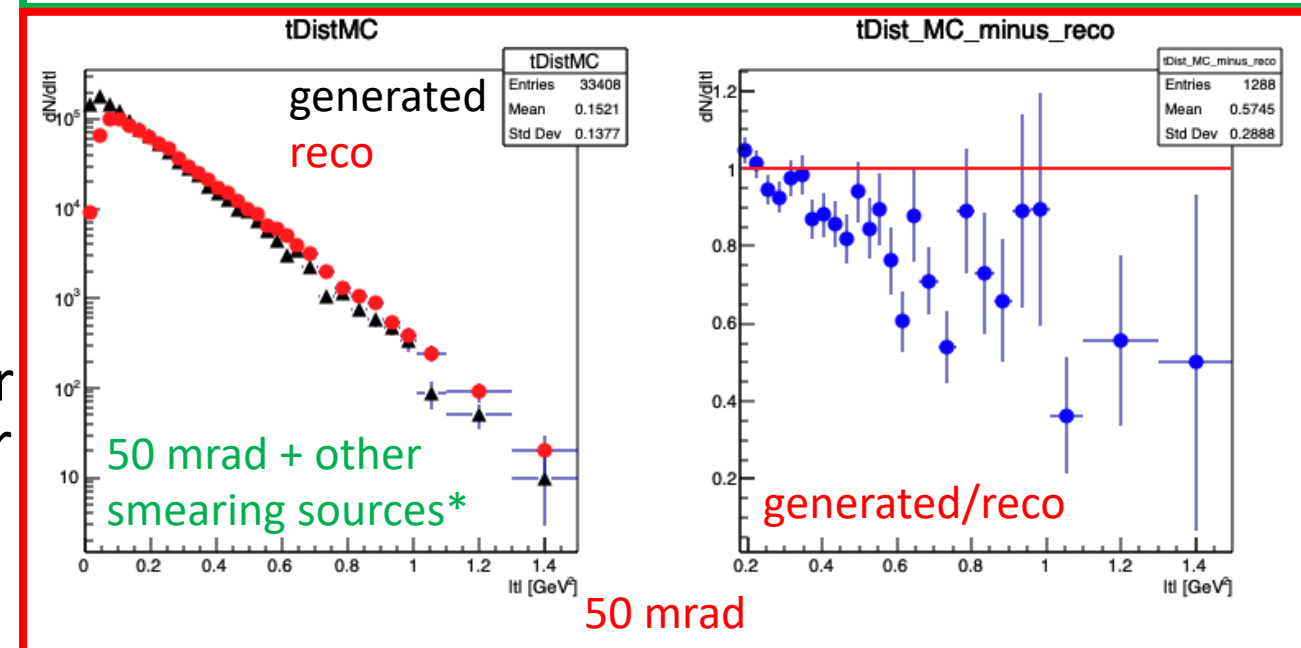
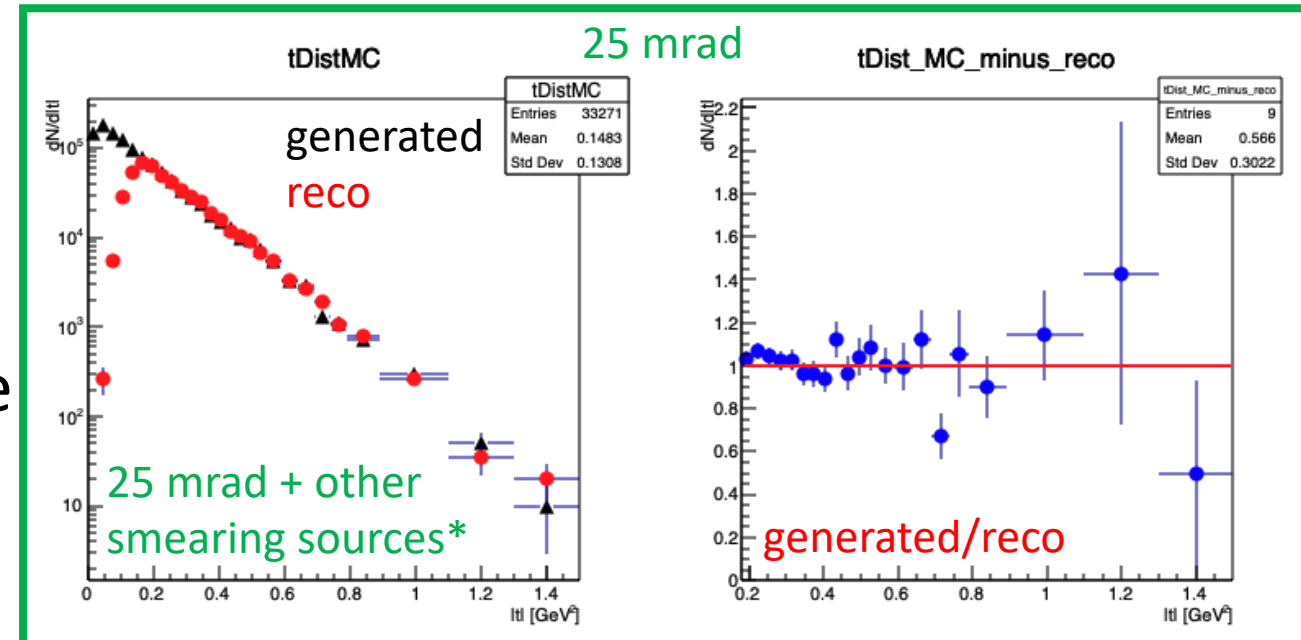


- Because of the rotation, the **Roman Pots+other FF detectors effectively** see the bunch crossing **smearing in x**.
- **Vertex smearing =  $12.5\text{mrad}$  (half the crossing angle) \*  $10\text{cm} = 1.25\text{mm}$**
- If the effective vertex smearing was **for a  $1\text{cm}$  bunch**, we would have  **$0.125\text{mm}$**  vertex smearing.

- Reducing the effective vertex smearing to that of an effective  $1\text{cm}$  bunch length reduces this smearing contribution to a negligible amount.
- This can be achieved with timing of  $\sim 35\text{ps}$  ( $1\text{cm}/\text{speed of light}$ ), with  $70\text{ps}$  still being okay to reduce the effect to much less than the angular divergence contribution.
  - Allows us to pinpoint the Z-coordinate in the bunch coordinate system (i.e. where the collision takes place within the bunch).

# What about 50 mrad?

- A larger crossing angle would increase the needed crab cavity rotation.
- As a result, it also doubles the effective vertex smearing.
- In this case, the crab cavity induced vertex smearing becomes dominant over the angular divergence.
- Without correction, the crab effect for 50mrad becomes the dominate smearing source.
  - Places a tighter constraint on the detector timing (i.e. would need the 35ps timing or better to reduce the smearing below that of the angular divergence).



\*Angular divergence + detector smearing (i.e. pixel size)

# Takeaways

- Crab cavity induced effective vertex smearing is correctable with fast timing.
- With a larger crossing angle, this requirement becomes more strict -> the contribution from the vertex smearing becomes the dominant source of smearing.